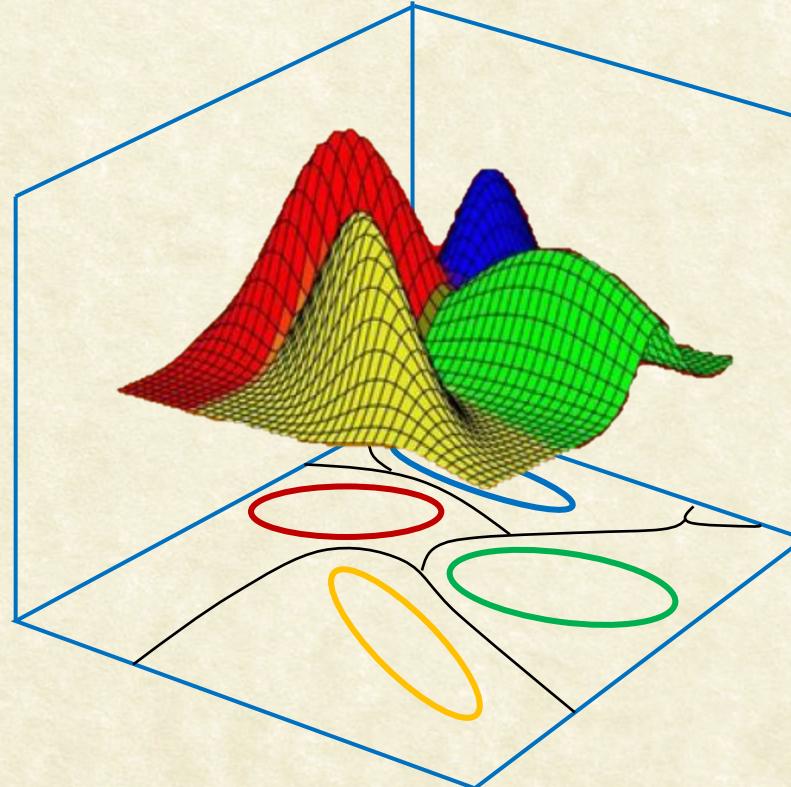




CS7.404: Digital Image Processing

Monsoon 2023: Sampling and Quantization

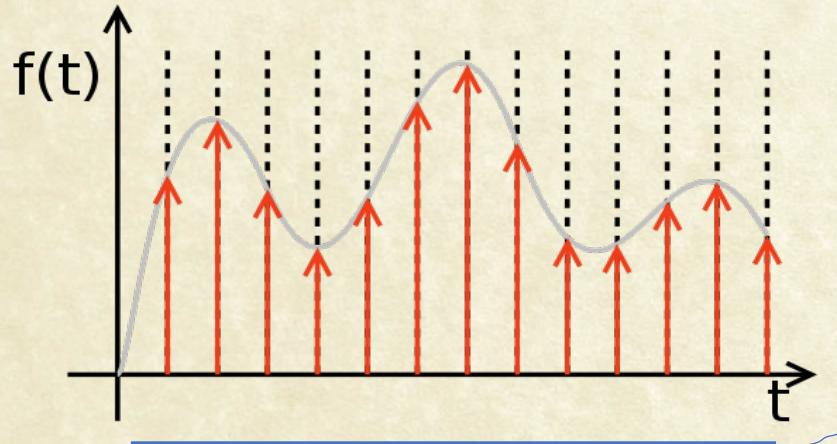


Anoop M. Namboodiri

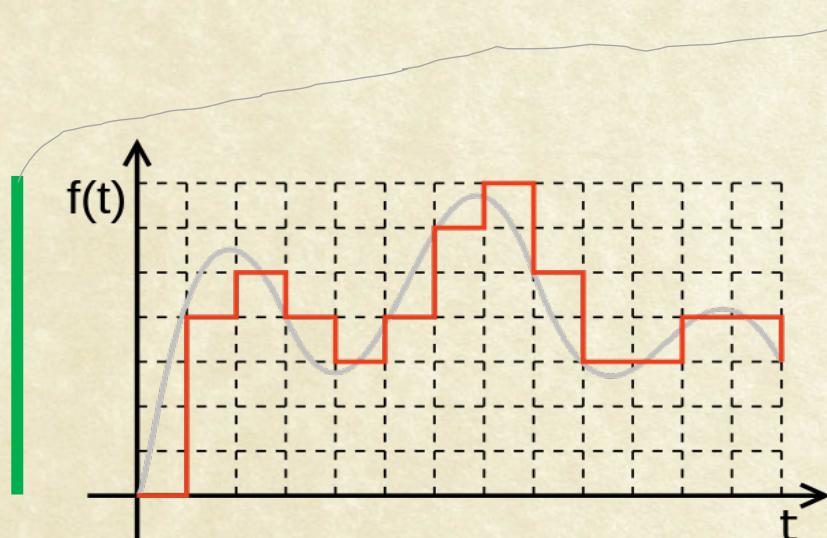
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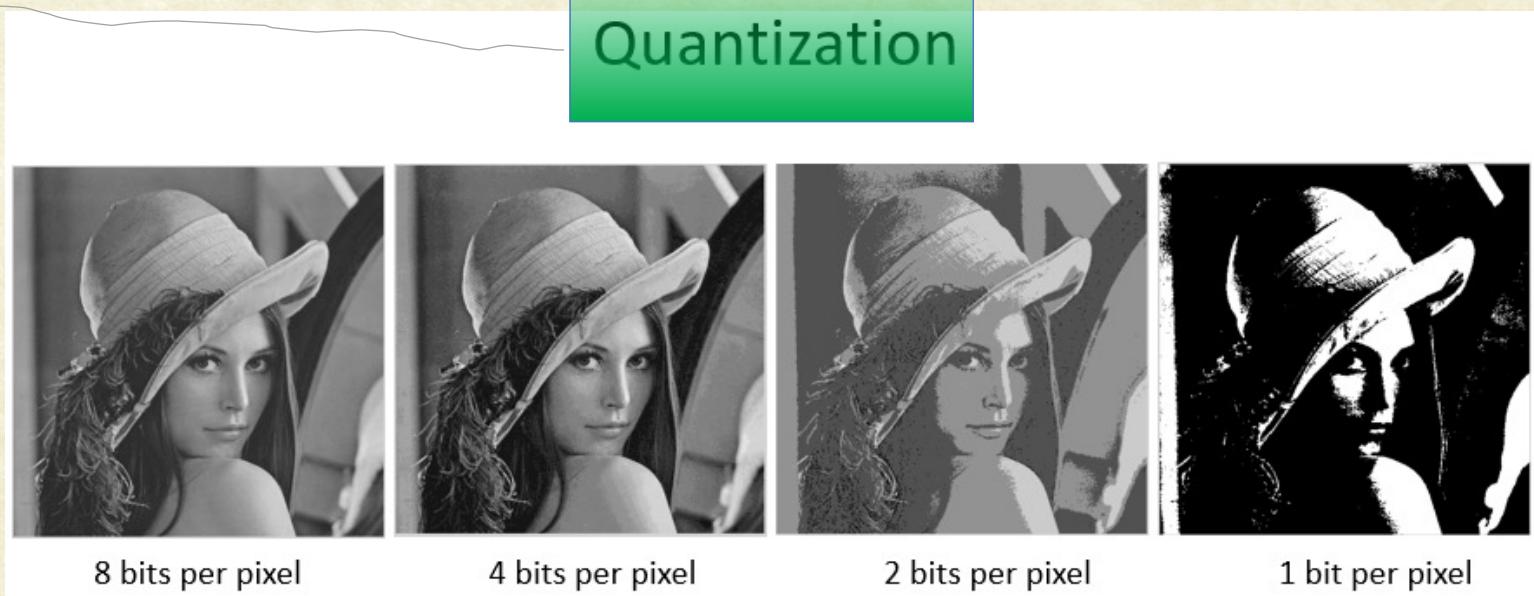
Summary

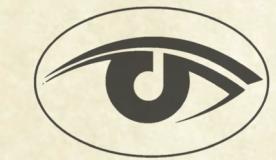


Sampling



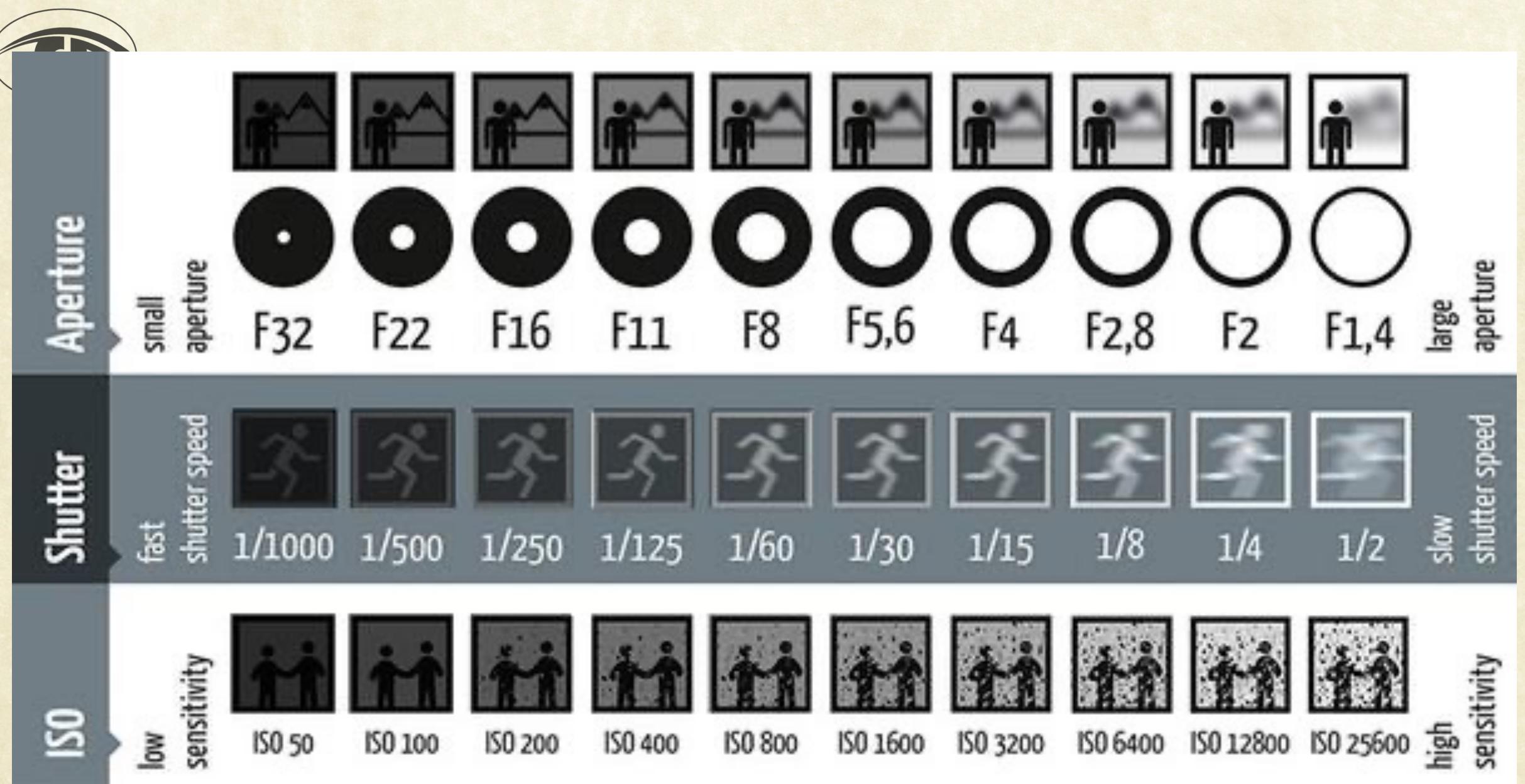
Quantization





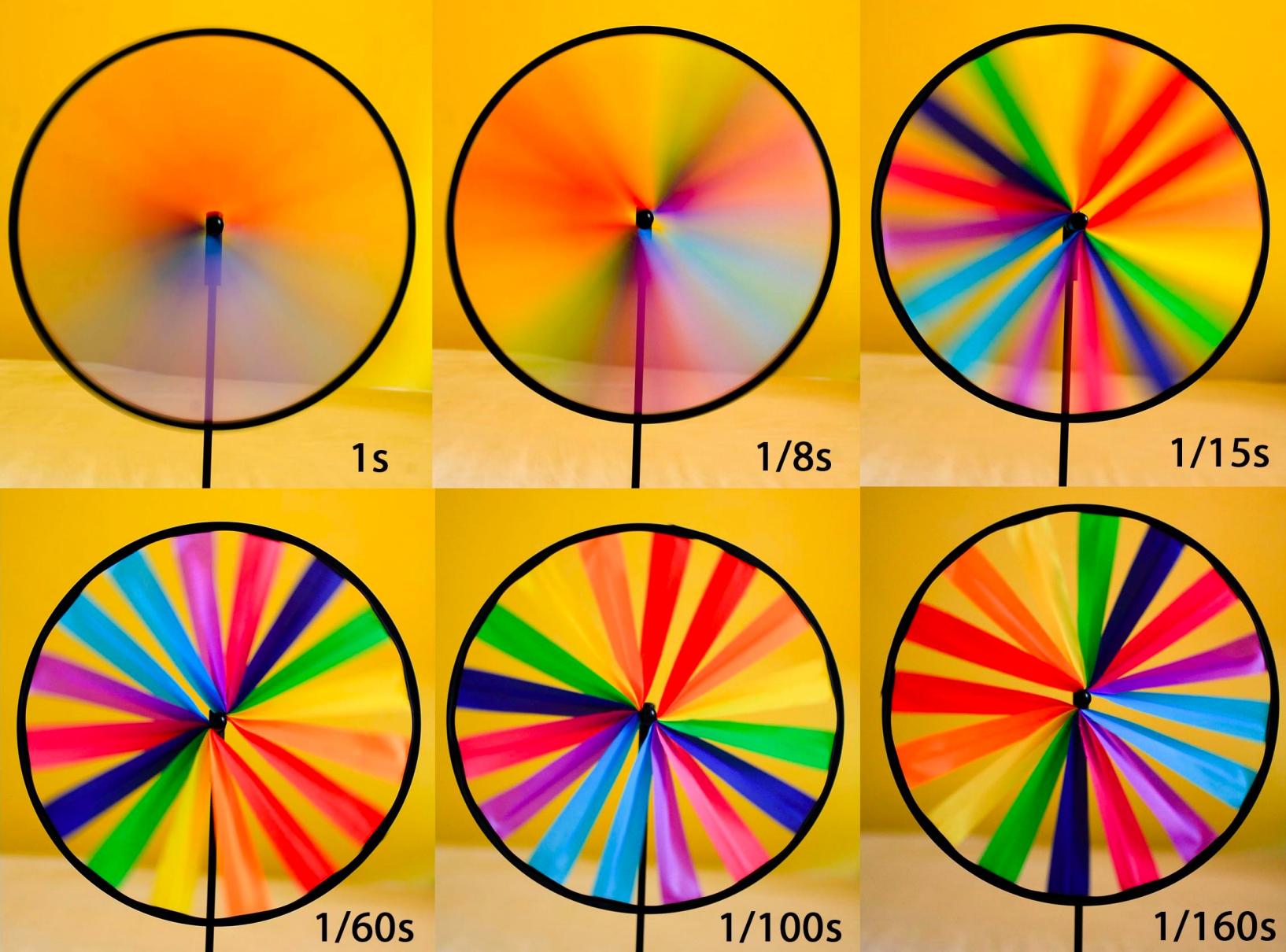
Temporal Sampling







Temporal Sampling





Temporal Sampling





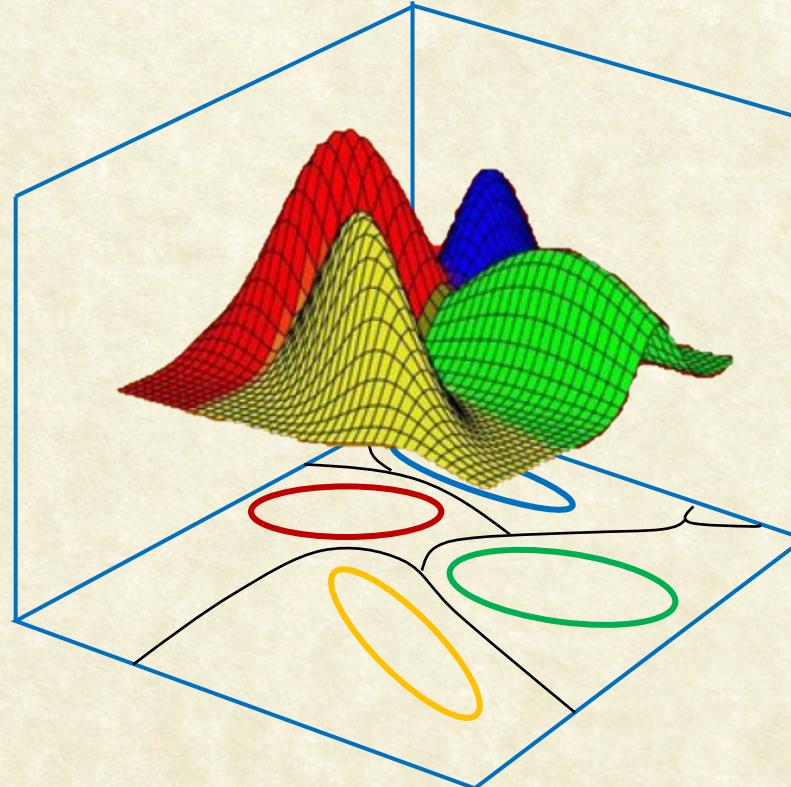
References

- Gonzalez and Woods (2.1,2.3-2.4)
 - Problems : 2.1 – 2.10
- Optional Reading
 - <https://www.edmundoptics.com/resources/application-notes/imaging/camera-resolution-for-improved-imaging-system-performance/>
 - <http://www.andor.com/learning-academy/ccd-spatial-resolution-understanding-spatial-resolution>
 - <http://av.jpn.support.panasonic.com/support/global/cs/dsc/knowhow/knowhow26.html>
 - <http://www.vision-doctor.com/en/camera-technology-basics/sensor-and-pixel-sizes.html>
 - <https://nostalgicmedia.com/pages/resolution-scanning-dpi-ppi>
 - <http://www.ubergizmo.com/what-is/ppi-pixels-per-inch/>



CS7.404: Digital Image Processing

Monsoon 2023: Pixel Processing



Anoop M. Namboodiri

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Two Paradigms of Image Processing

Directly in Spatial Domain

- Manipulating Pixels
 - Easier to Understand
 - Easier to Implement
 - Local Changes
 - Not so efficient

Processing in Transform Domain

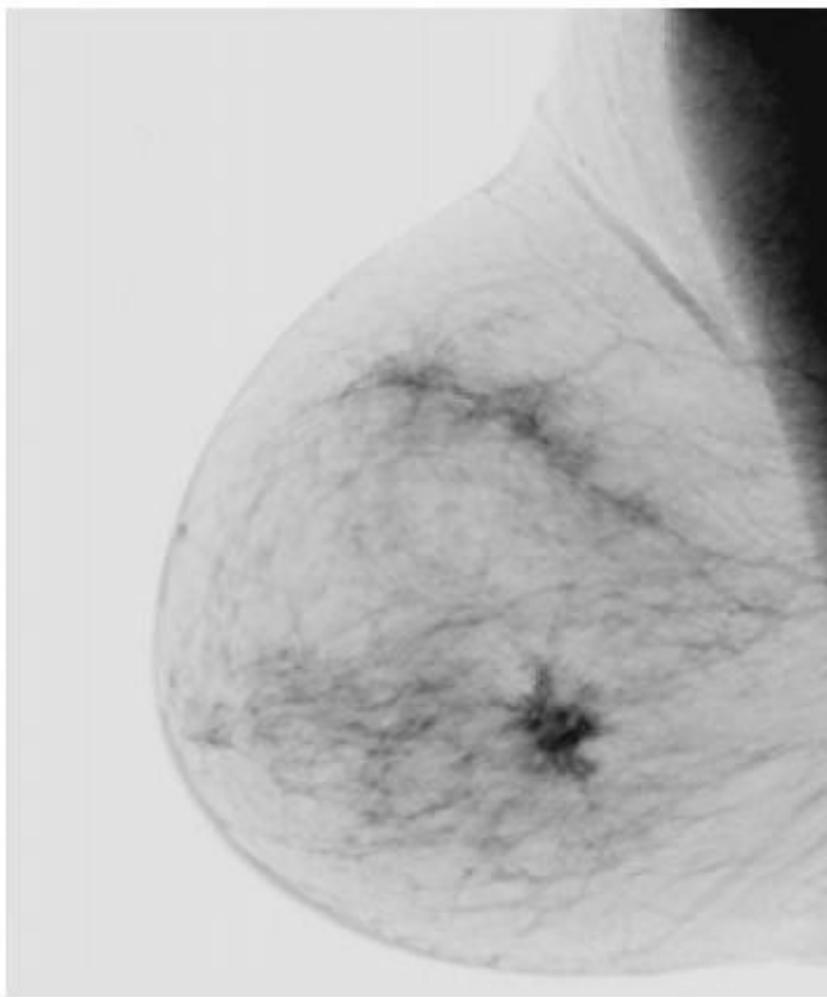
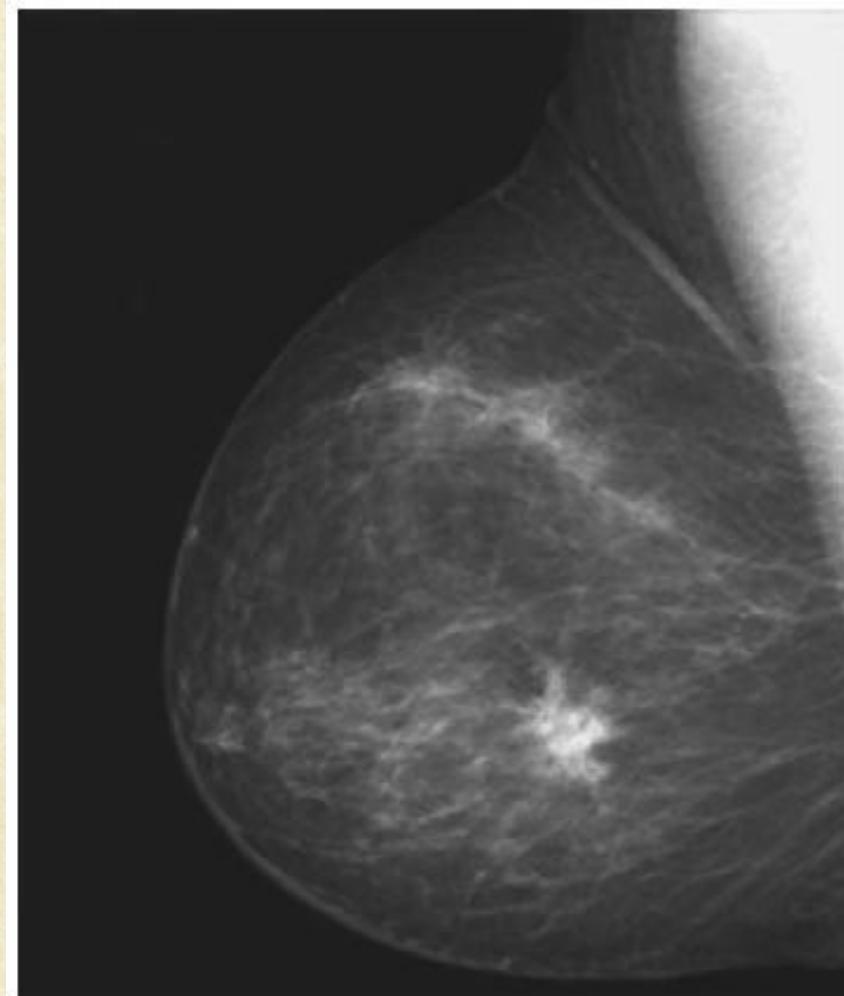
- Manipulating JPG coefficients
 - Complex to visualize
 - Tricky to implement
 - Changes can be global
 - Can be very efficient, effective,

...



Intensity Transformations: Point-to-Point

- $b(x,y) = T(a(x,y))$; $T(z) = K - z$



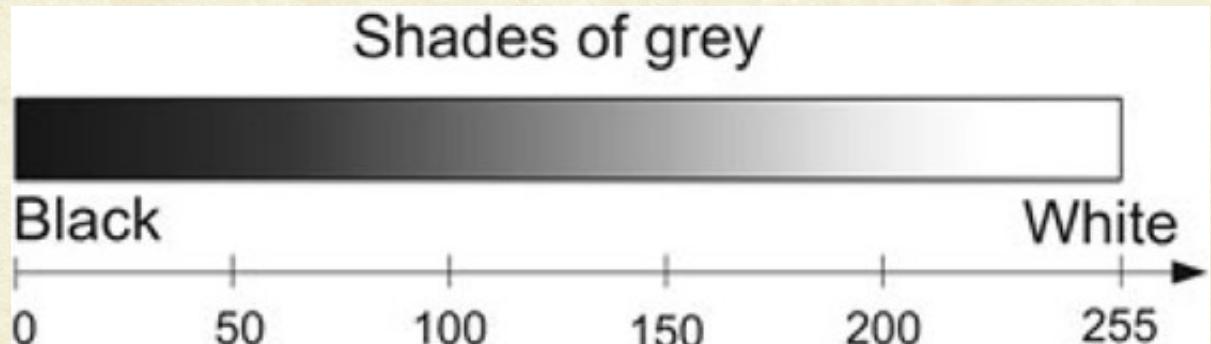
a b

FIGURE 3.4
(a) Original digital mammogram.
(b) Negative image obtained using the negative transformation in Eq. (3.2-1).
(Courtesy of G.E. Medical Systems.)



Linear Intensity Transforms

- $T(z) = z + K$
 - $T(z) = z - K$
 - $T(z) = Kz$
 - $T(z) = K_1 z + K_2$



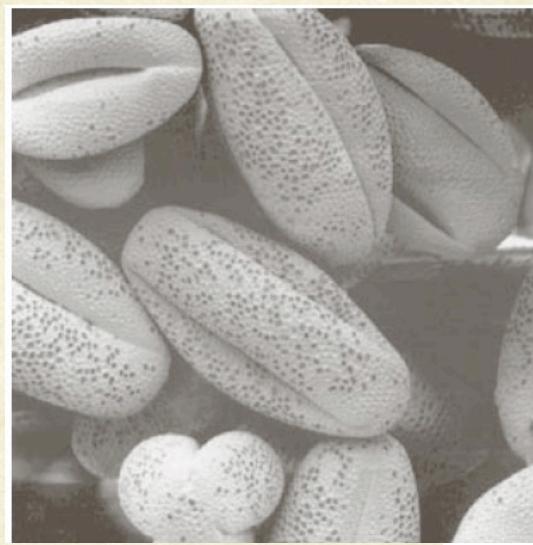
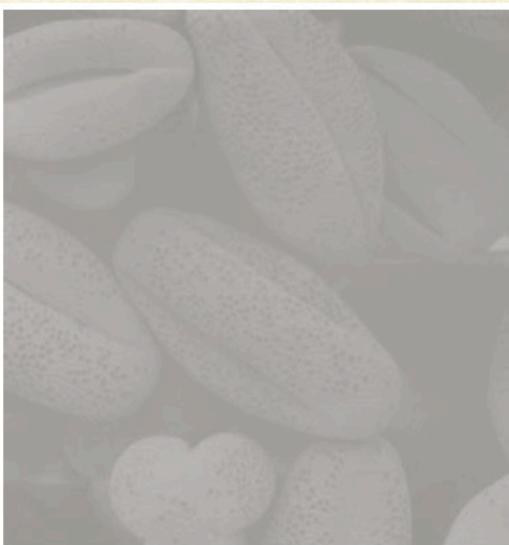
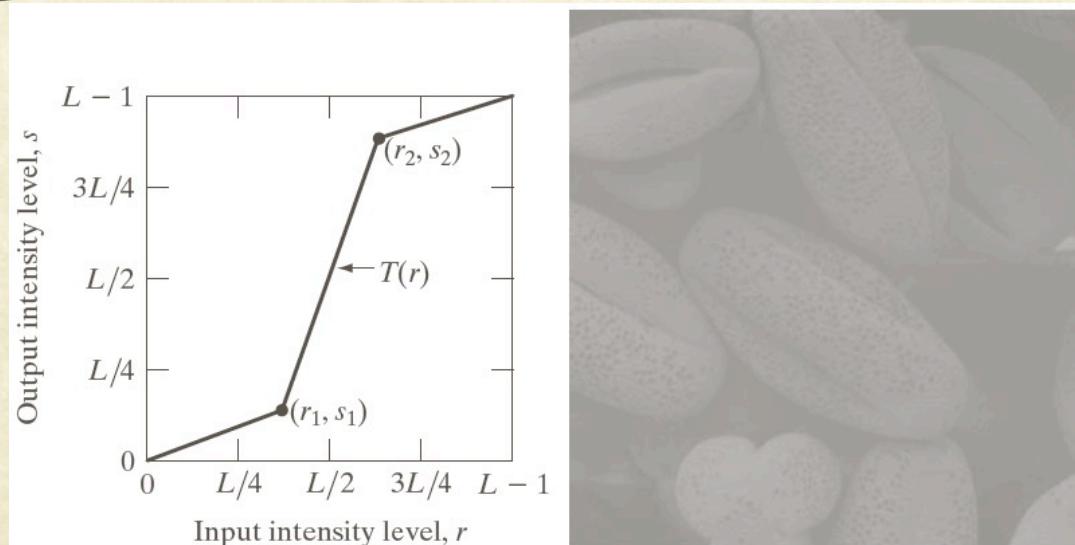
e.g.,

- Image Negative
 - Data Visualization:
 - Map to display range

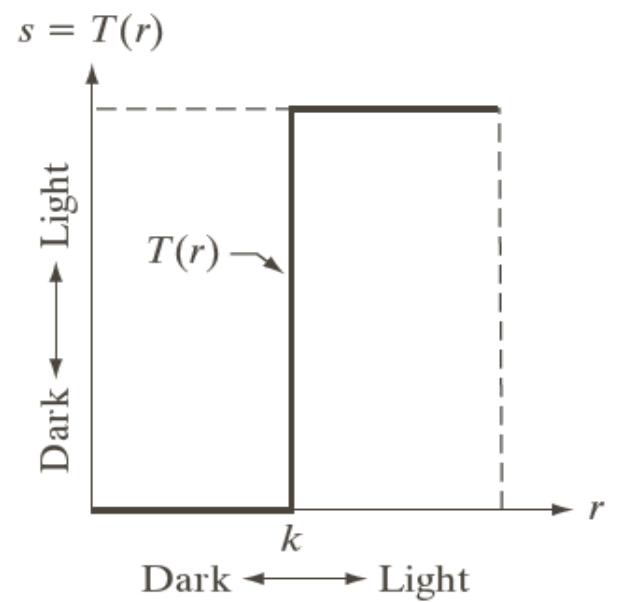
$$J = \text{round} \left(255 * \frac{I - \min(I)}{\max(I) - \min(I)} \right)$$



Piece-wise Linear Transformations



- Can be arbitrarily complex
- Finer control over transformation
- Thresholding
- Contrast Stretching
 - Expand intensity range to **full intensity range**
 - What are the constraints on (r_1, s_1) and (r_2, s_2) ?



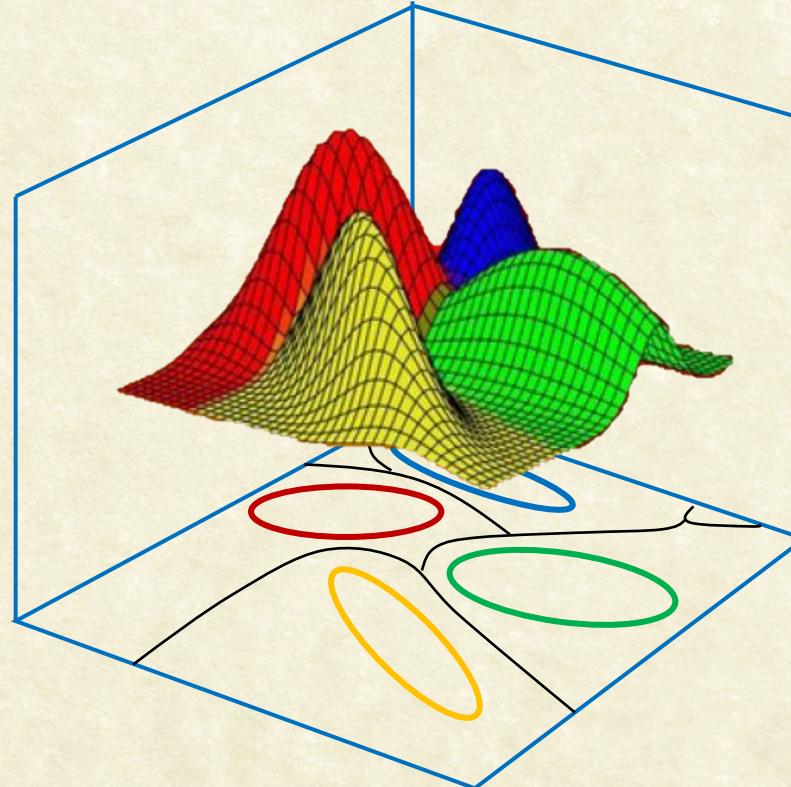


Questions?



CS7.404: Digital Image Processing

Monsoon 2023: Non-Linear Transformations



Anoop M. Namboodiri

Biometrics and Secure ID Lab, CVIT,
IIIT Hyderabad

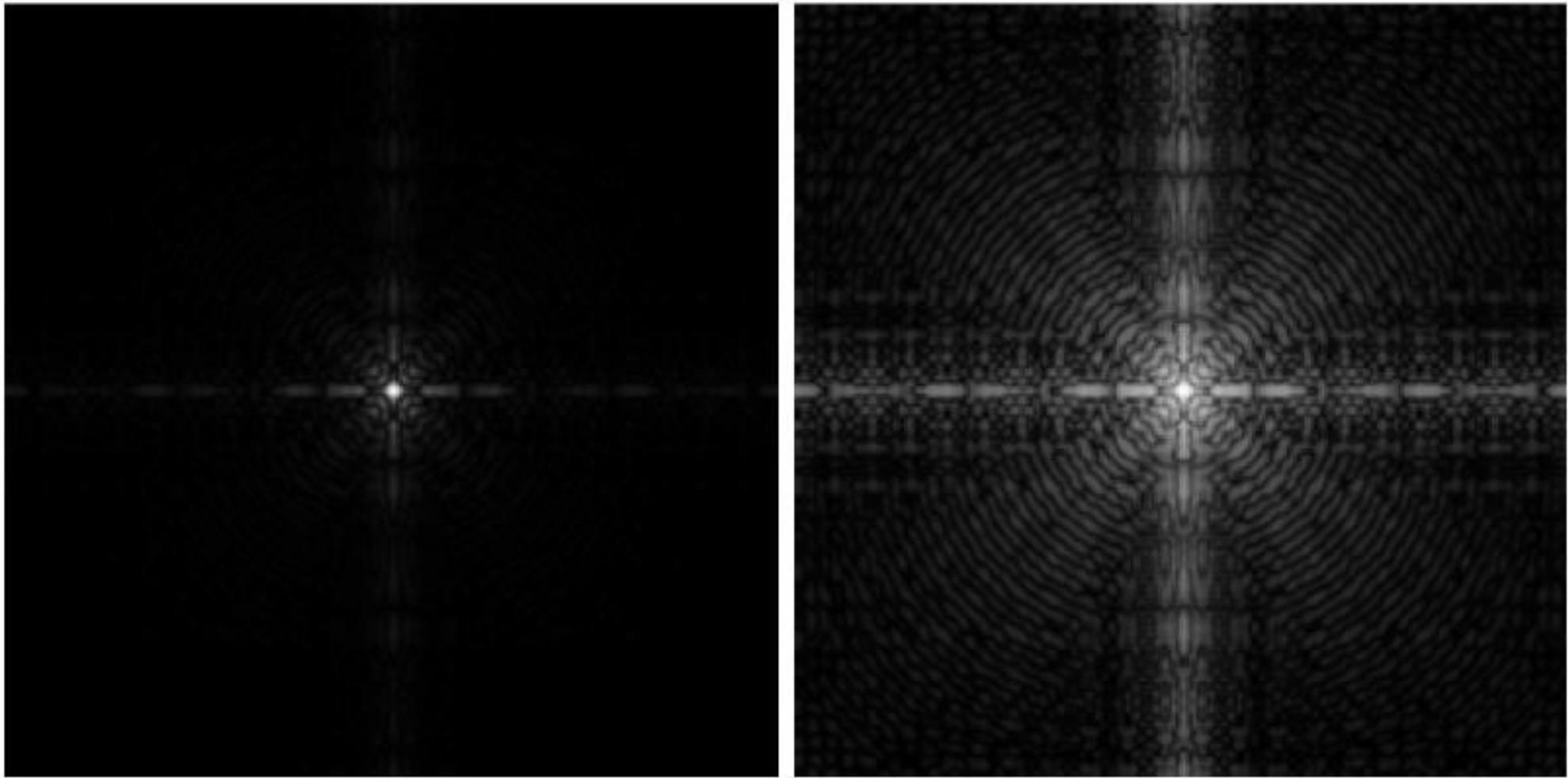


Log Transformations

a b

FIGURE 3.5

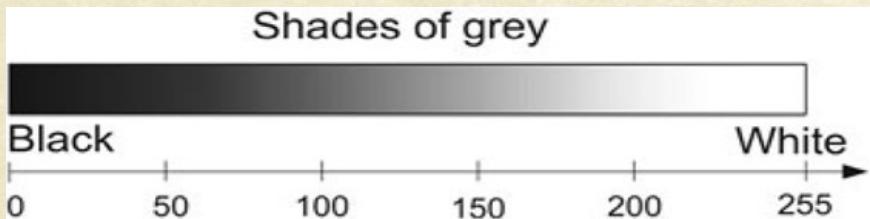
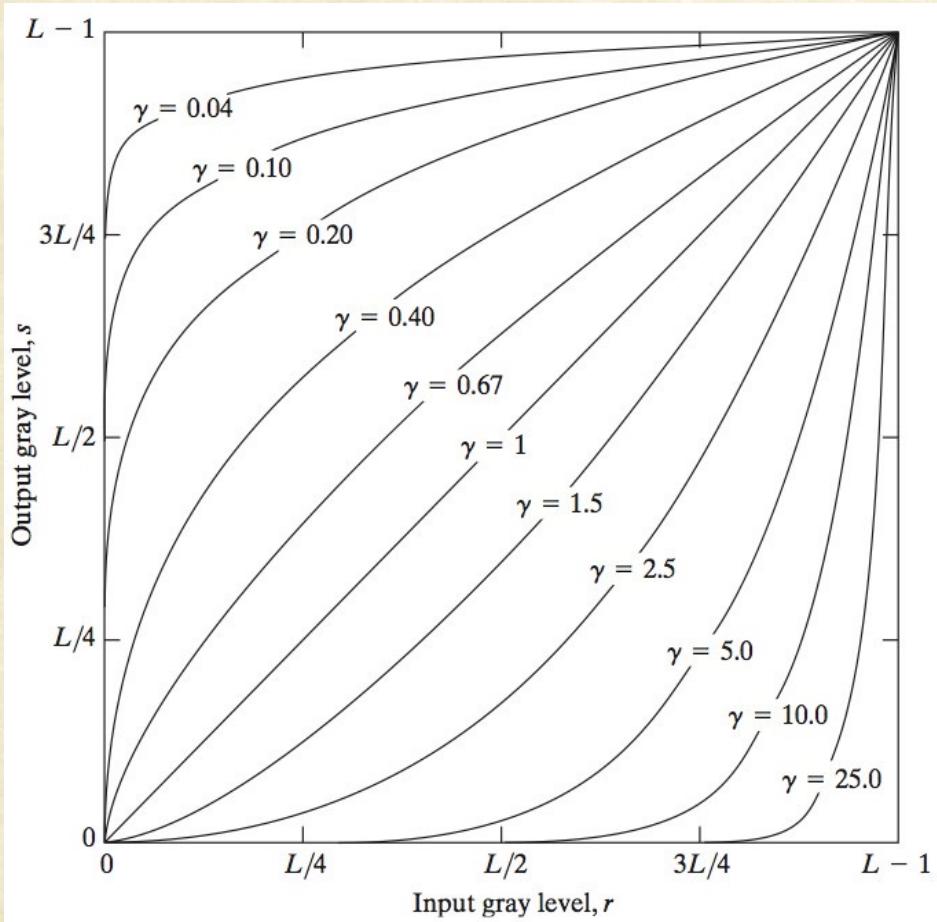
(a) Fourier spectrum.
(b) Result of applying the log transformation given in Eq. (3.2-2) with $c = 1$.



$$s = T(r) = c \log(1 + r)$$



Power-Law Transformations

$$s = cr^\gamma$$


a
b
c
d

FIGURE 3.9
(a) Aerial image.
(b)–(d) Results of applying the transformation in Eq. (3.2-3) with $c = 1$ and $\gamma = 3.0, 4.0$, and 5.0 , respectively. (Original image for this example courtesy of NASA.)



Demo:

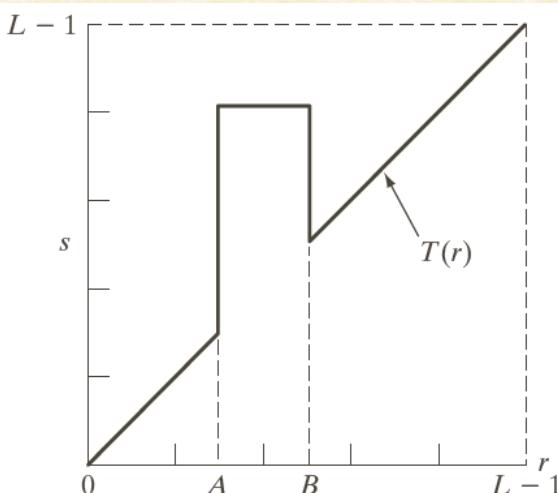
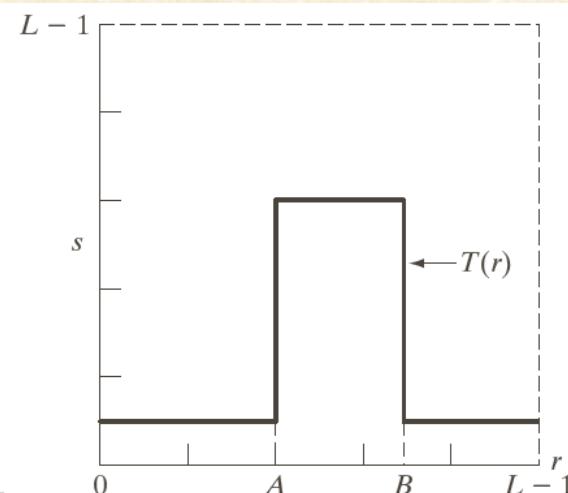
<https://colab.research.google.com/drive/11qlOVKleZnONtPuxAryAf9WkUC7kEMI#scrollTo=aU5WQaqOpSCr&line=12&uniquifier=1>



Intensity Slicing

a b

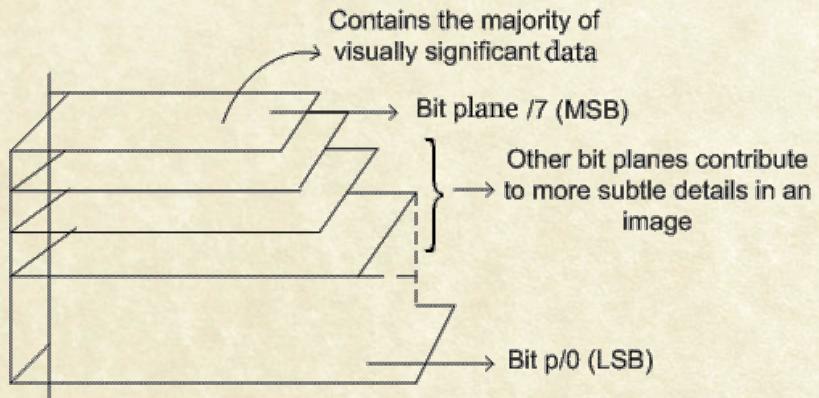
FIGURE 3.11 (a) This transformation highlights intensity range $[A, B]$ and reduces all other intensities to a lower level. (b) This transformation highlights range $[A, B]$ and preserves all other intensity levels.



a b c



Bit plane slicing



a	b	c
d	e	f
g	h	i

FIGURE 3.14 (a) An 8-bit gray-scale image of size 500×1192 pixels. (b) through (i) Bit planes 1 through 8, with bit plane 1 corresponding to the least significant bit. Each bit plane is a binary image.



Bit plane slicing



a b c

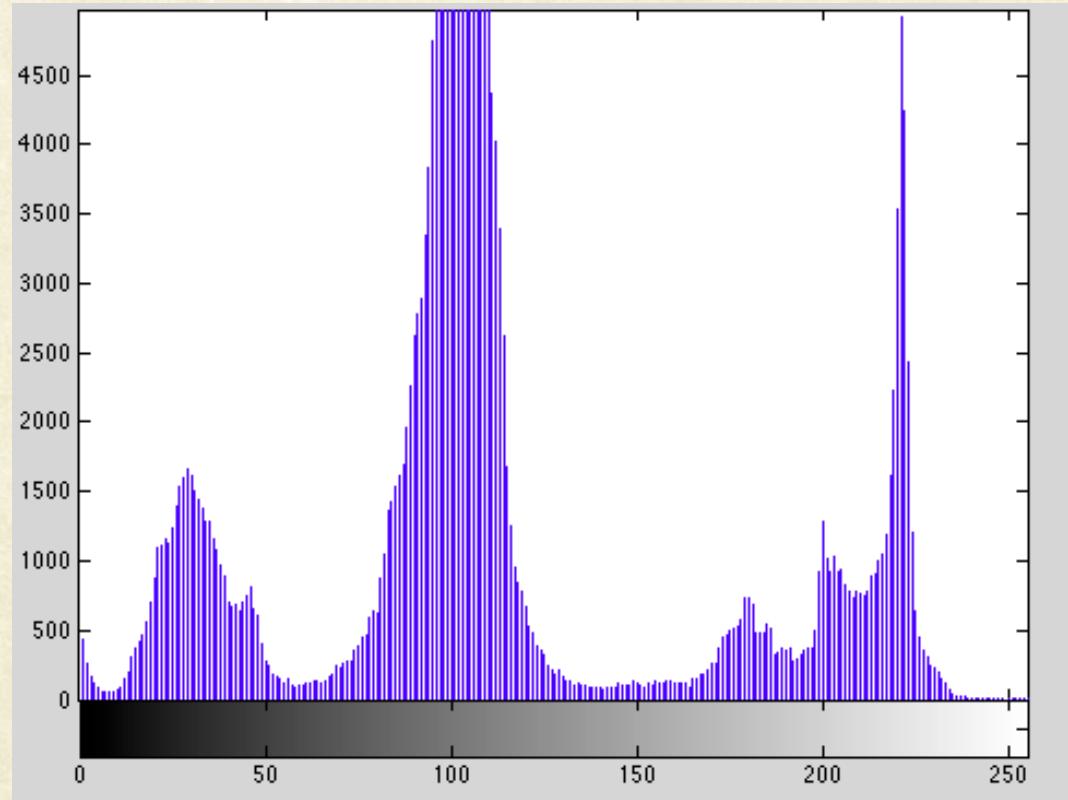
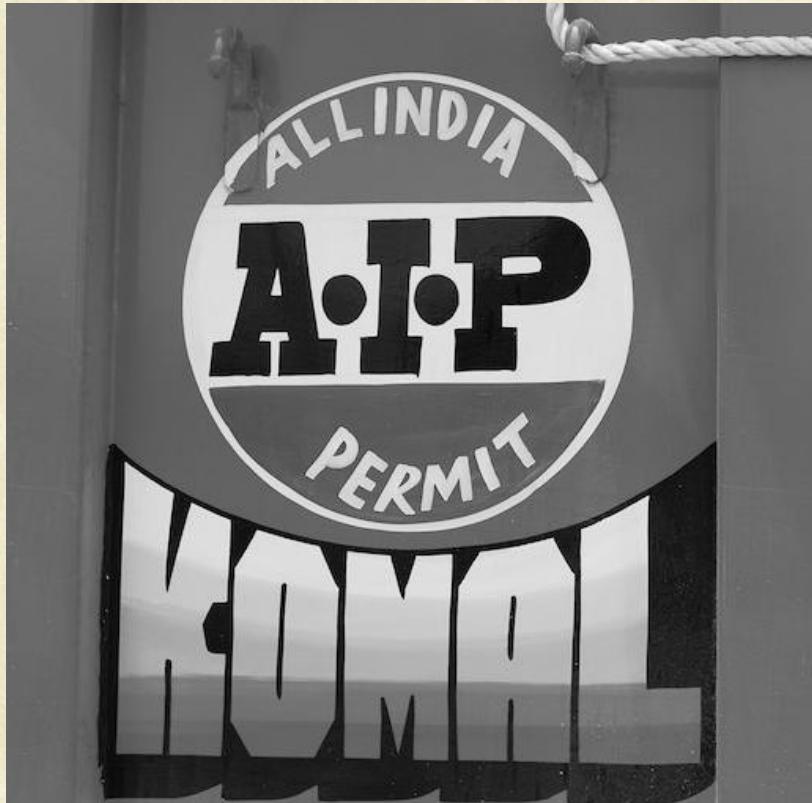
FIGURE 3.15 Images reconstructed using (a) bit planes 8 and 7; (b) bit planes 8, 7, and 6; and (c) bit planes 8, 7, 6, and 5. Compare (c) with Fig. 3.14(a).



Histogram

$$h_r(i) = n_i$$

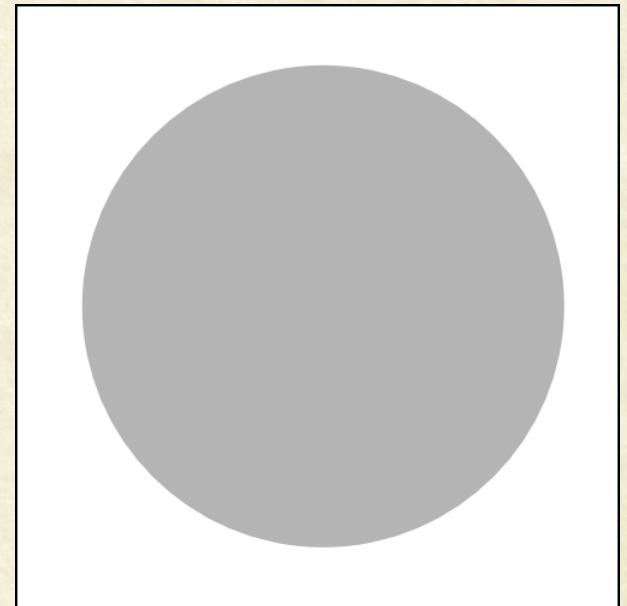
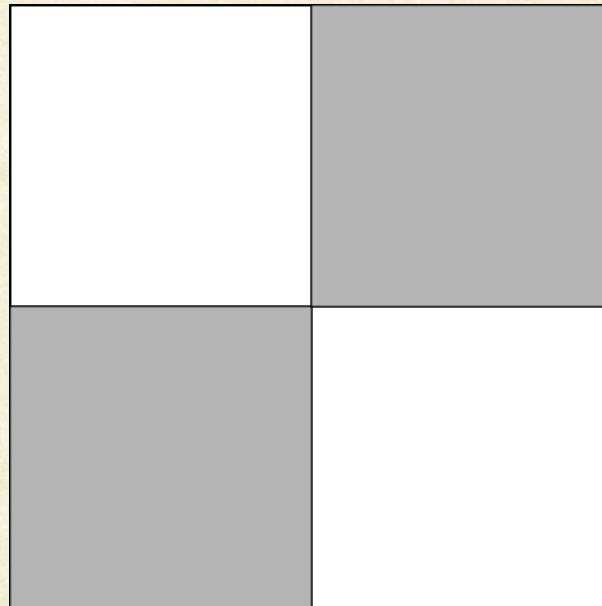
$i \rightarrow$ intensity value, range $[0, L-1]$
 $n_i \rightarrow$ number of pixels with intensity i



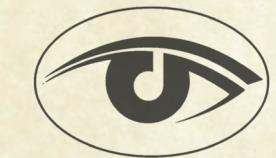


Histograms

- ▶ Different images can have same histogram



- ▶ No information about spatial distribution of intensity values



Histograms

- ▶ What can we infer from histograms?

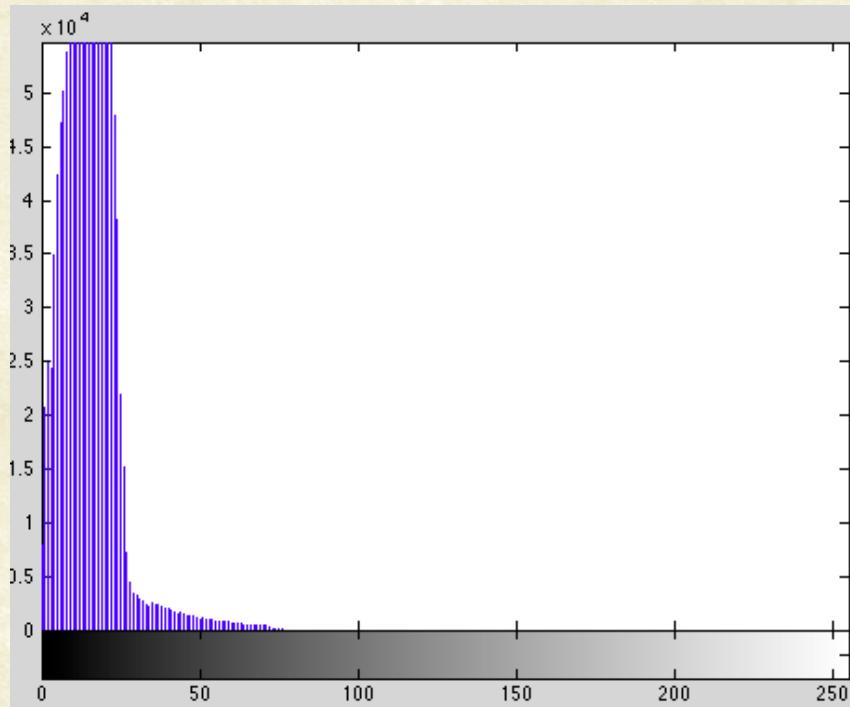


Histogram viewing standard in most DSLR cameras



Histograms

▶ Histograms and brightness

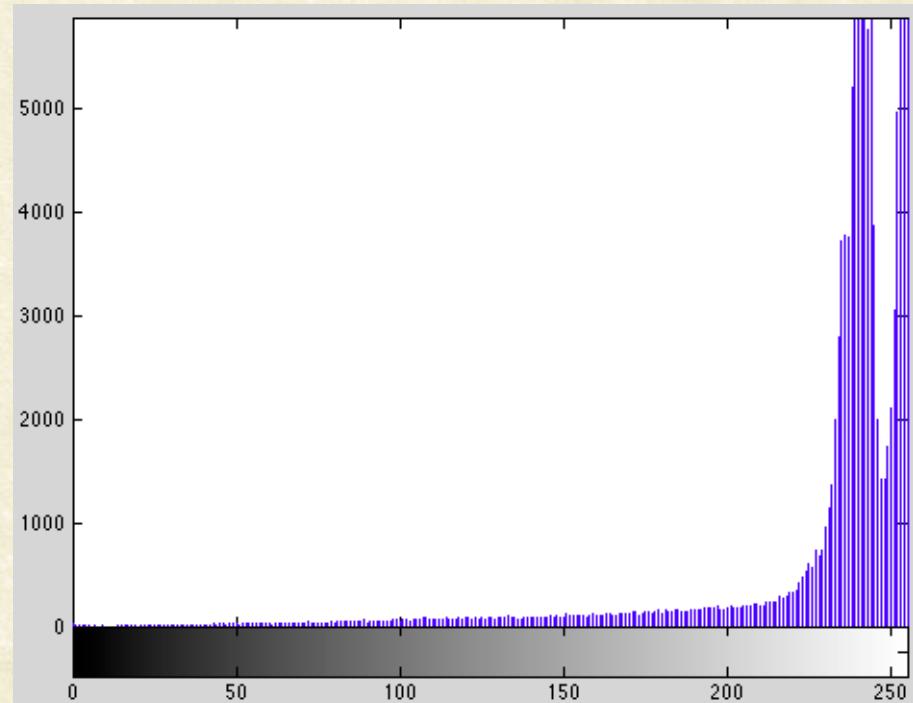


Under exposure



Histograms

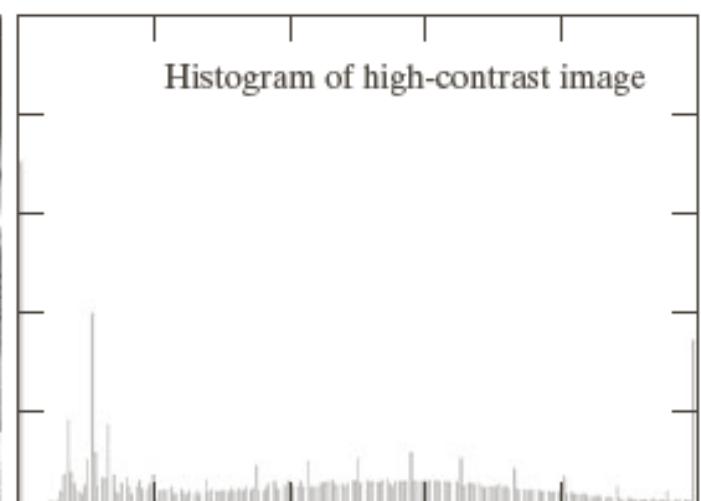
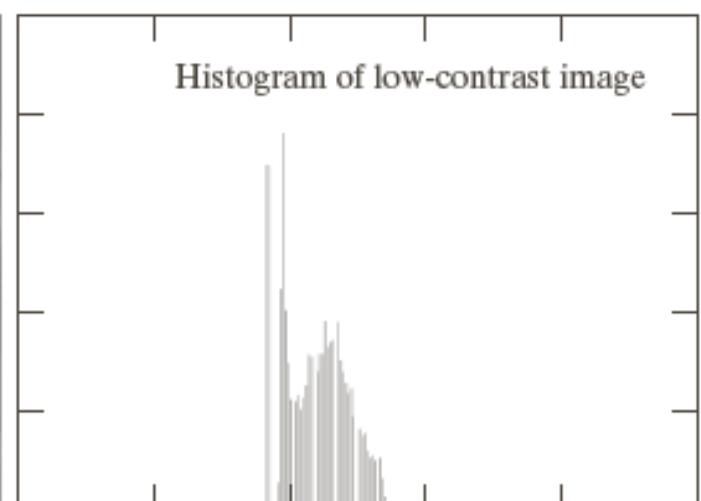
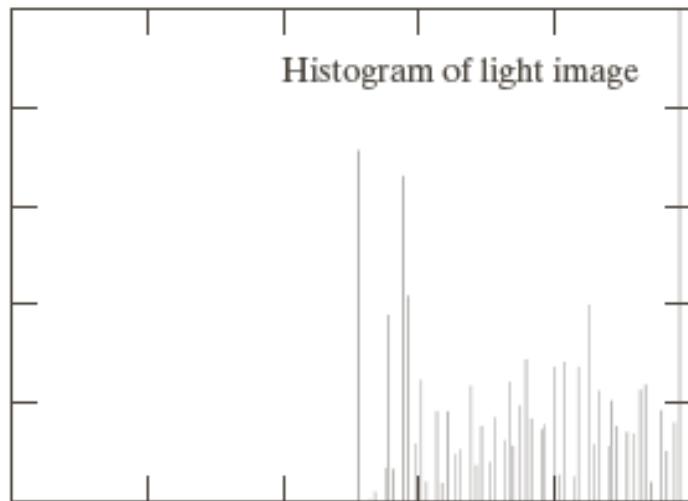
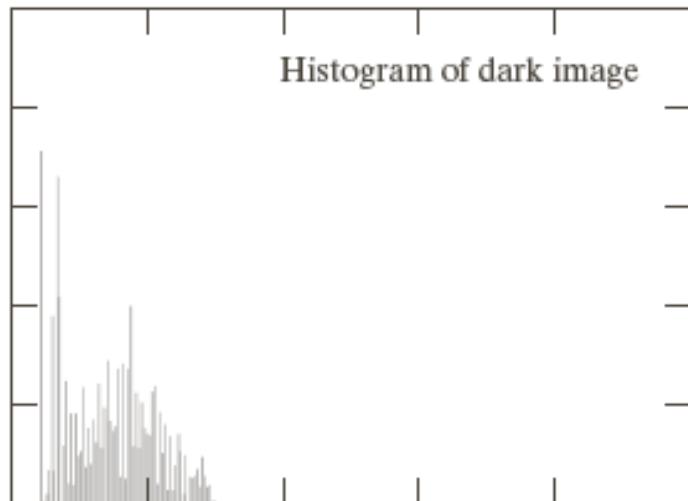
▶ Histograms and brightness



Over exposure

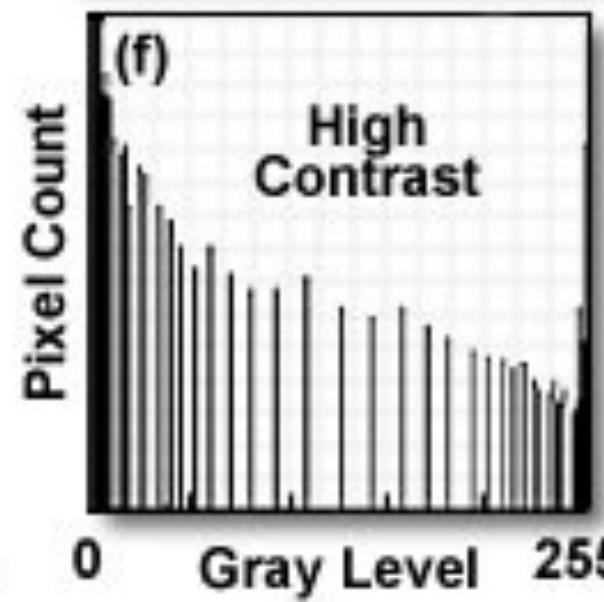
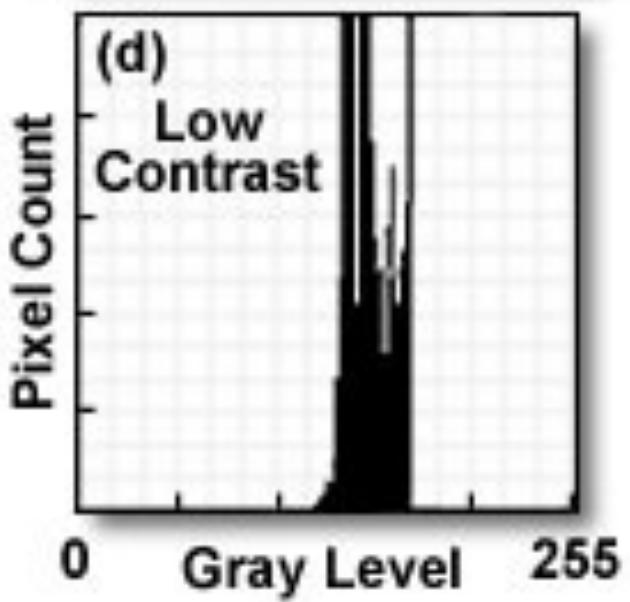
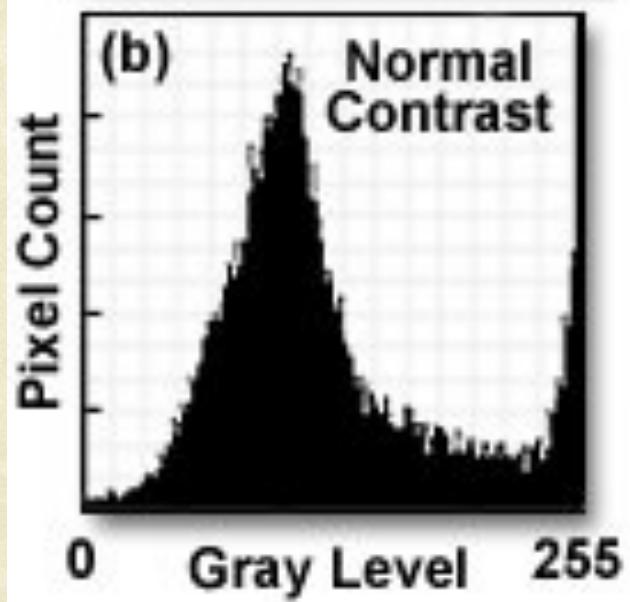
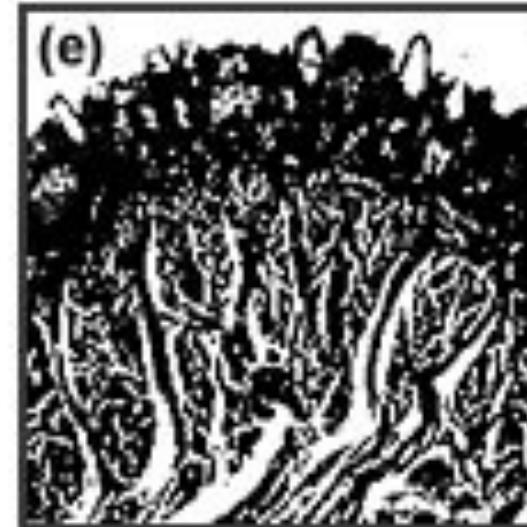
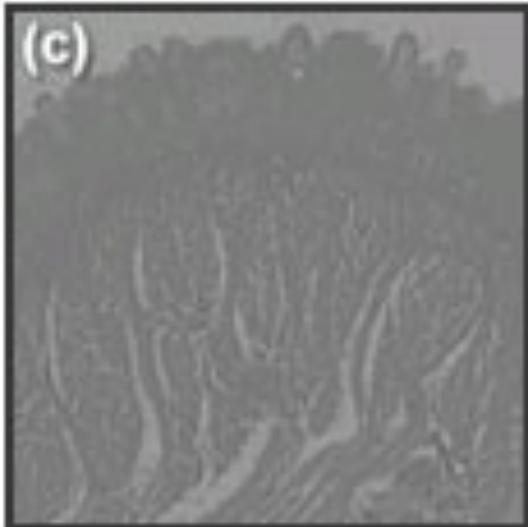
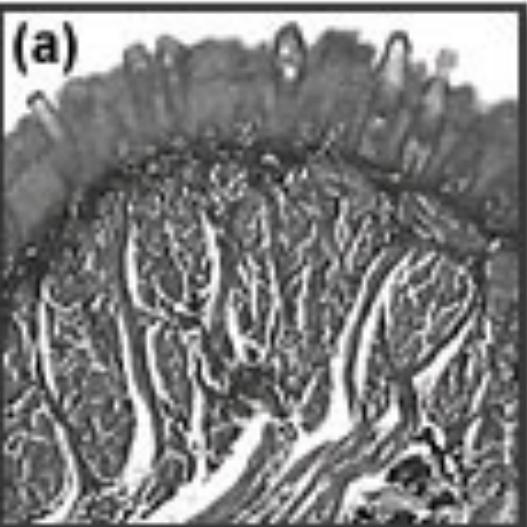


Histogram and Contrast





Grayscale Histograms and Contrast Levels in Digital Images

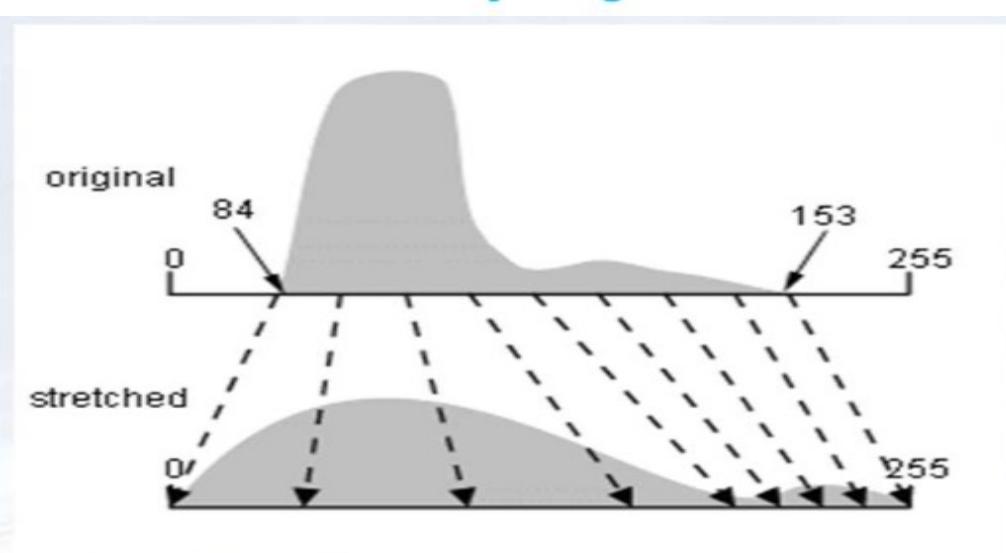


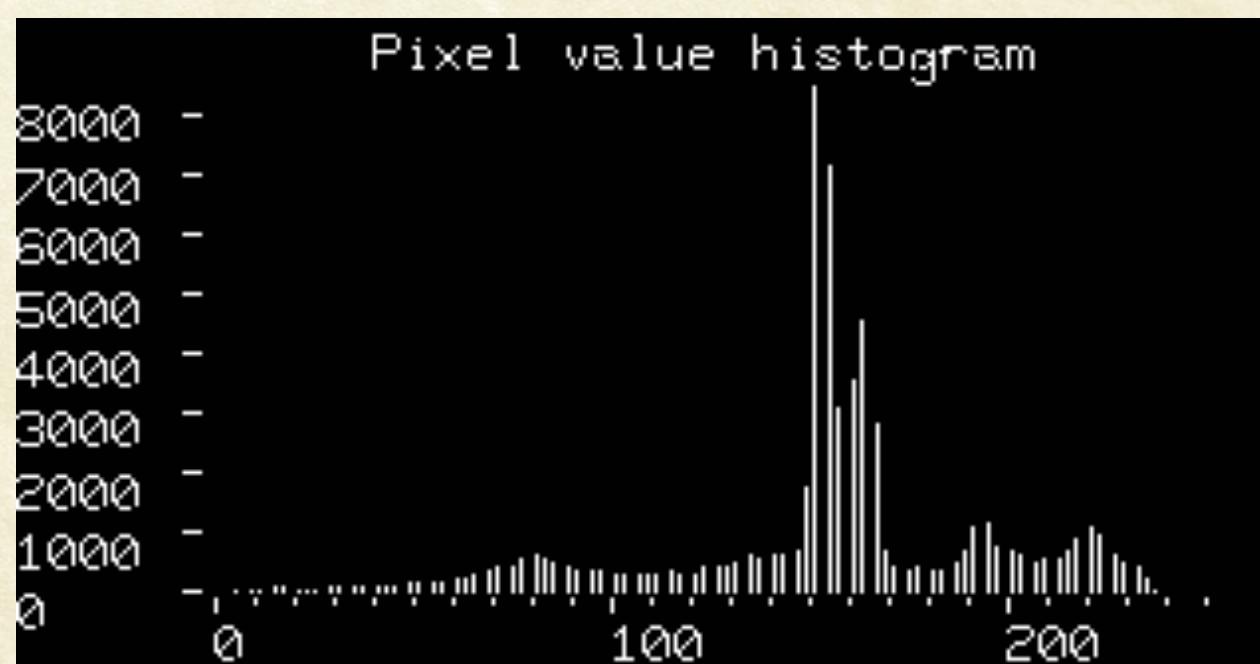
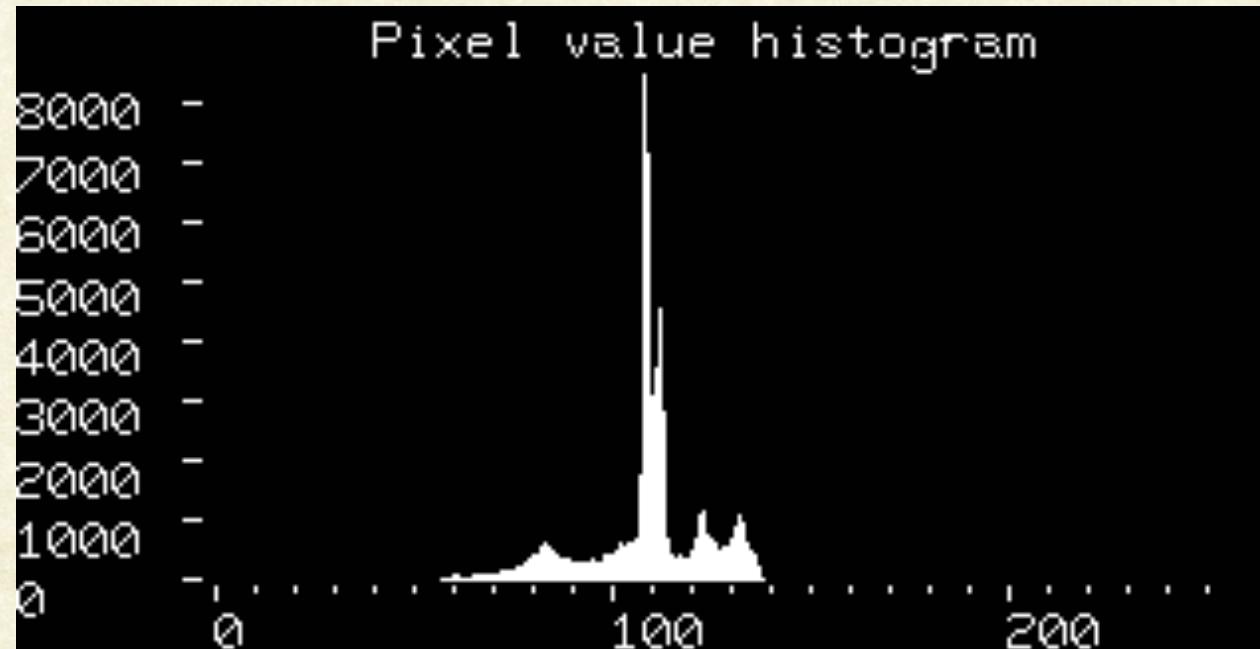


Contrast Stretching



$$f_{\text{ac}}(a) = a_{\text{min}} + (a - a_{\text{low}}) \cdot \frac{a_{\text{max}} - a_{\text{min}}}{a_{\text{high}} - a_{\text{low}}}$$







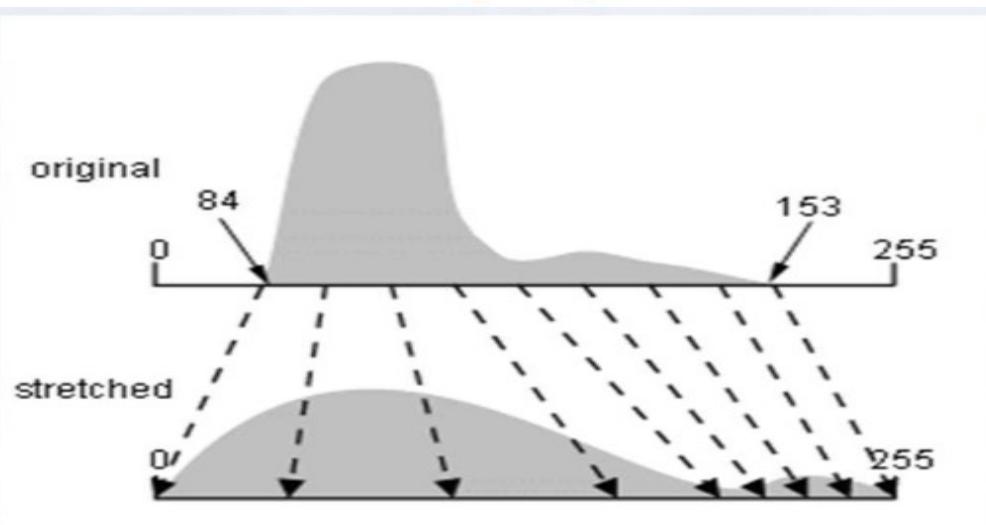
Contrast Stretching



$$f_{ac}(a) = a_{min} + (a - a_{low}) \cdot \frac{a_{max} - a_{min}}{a_{high} - a_{low}}$$

If $a_{min} = 0$ and $a_{max} = 255$

$$f_{ac}(a) = (a - a_{low}) \cdot \frac{255}{a_{high} - a_{low}}$$

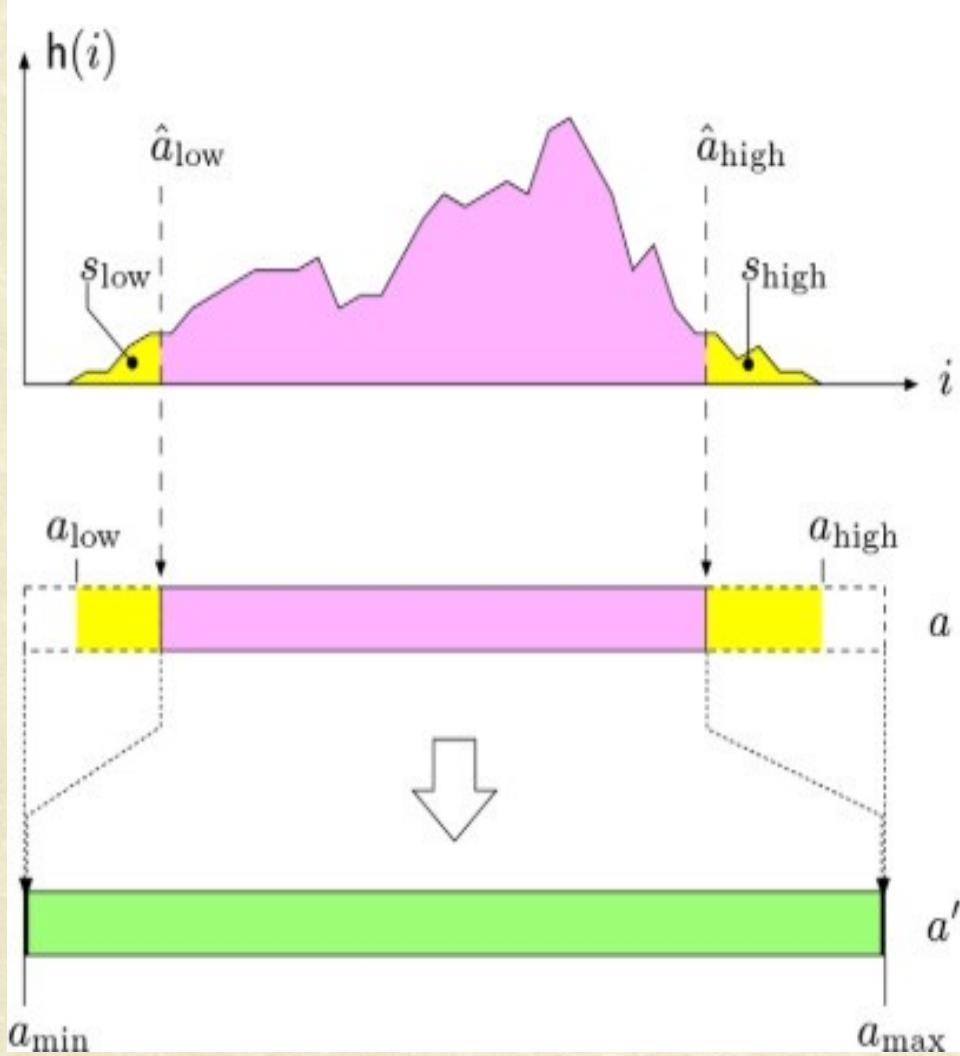


What happens if we have a single pixel with intensity 255 in the original intensity range?

What happens if we have a single pixel with intensity 0 in the original intensity range?



Contrast Stretching ver. 2



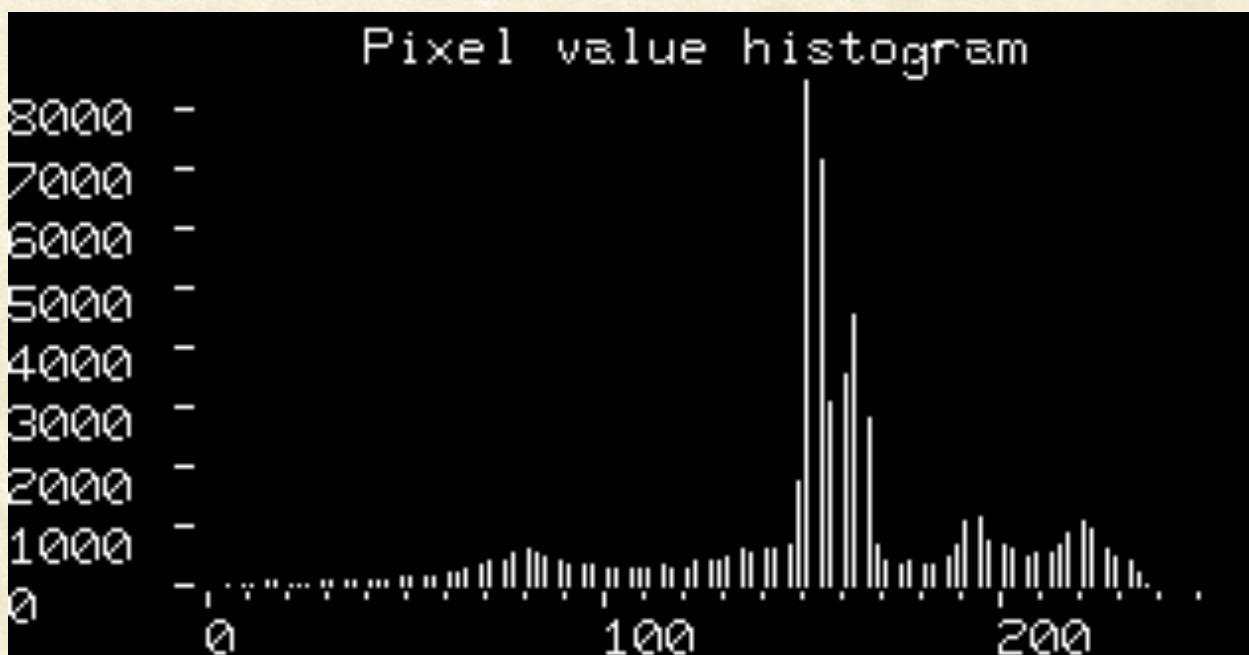
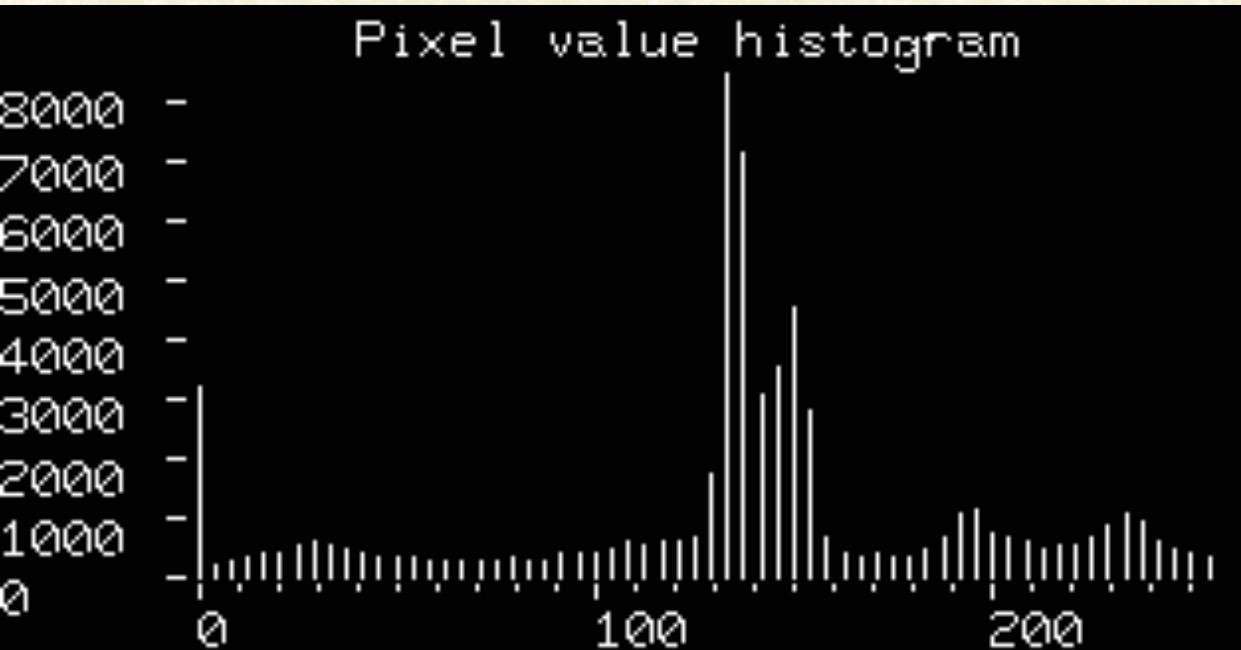
$$\hat{a}_{\text{low}} = \min\{ i \mid H(i) \geq M \cdot N \cdot s_{\text{low}} \}$$

$$\hat{a}_{\text{high}} = \max\{ i \mid H(i) \leq M \cdot N \cdot (1 - s_{\text{high}}) \}$$

$$f_{\text{mac}}(a) = \begin{cases} a_{\text{min}} & \text{for } a \leq \hat{a}_{\text{low}} \\ a_{\text{min}} + (a - \hat{a}_{\text{low}}) \cdot \frac{a_{\text{max}} - a_{\text{min}}}{\hat{a}_{\text{high}} - \hat{a}_{\text{low}}} & \text{for } \hat{a}_{\text{low}} < a < \hat{a}_{\text{high}} \\ a_{\text{max}} & \text{for } a \geq \hat{a}_{\text{high}} \end{cases}$$

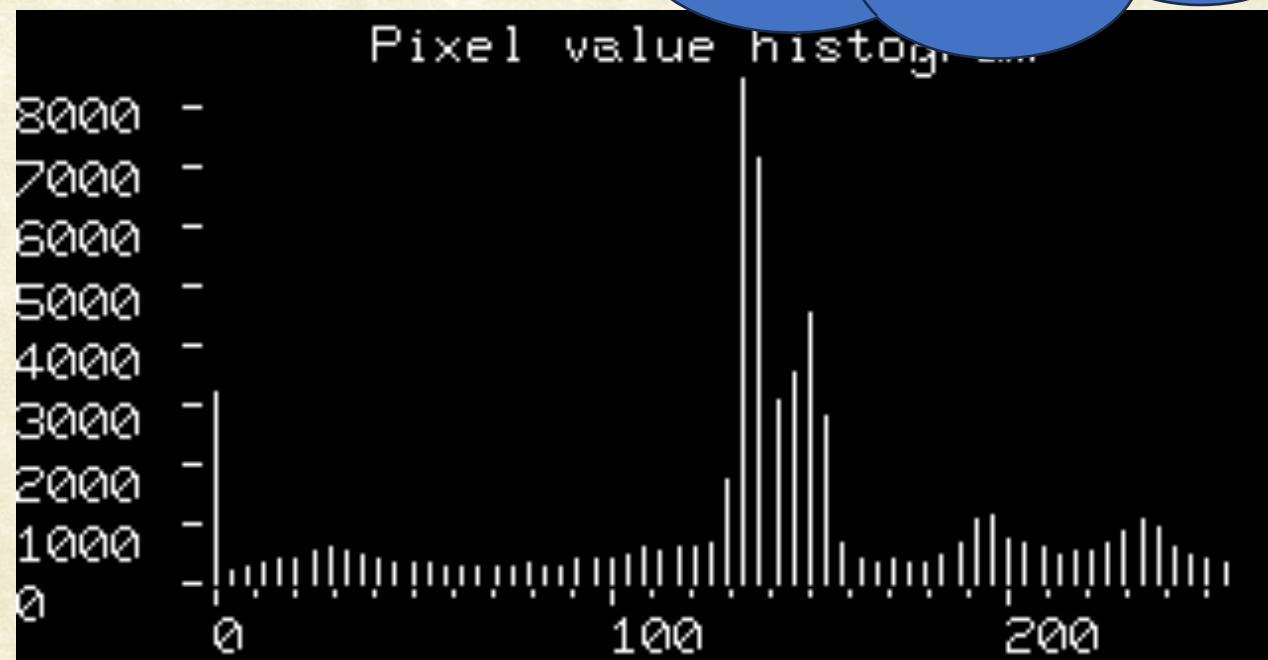


Ver. 2





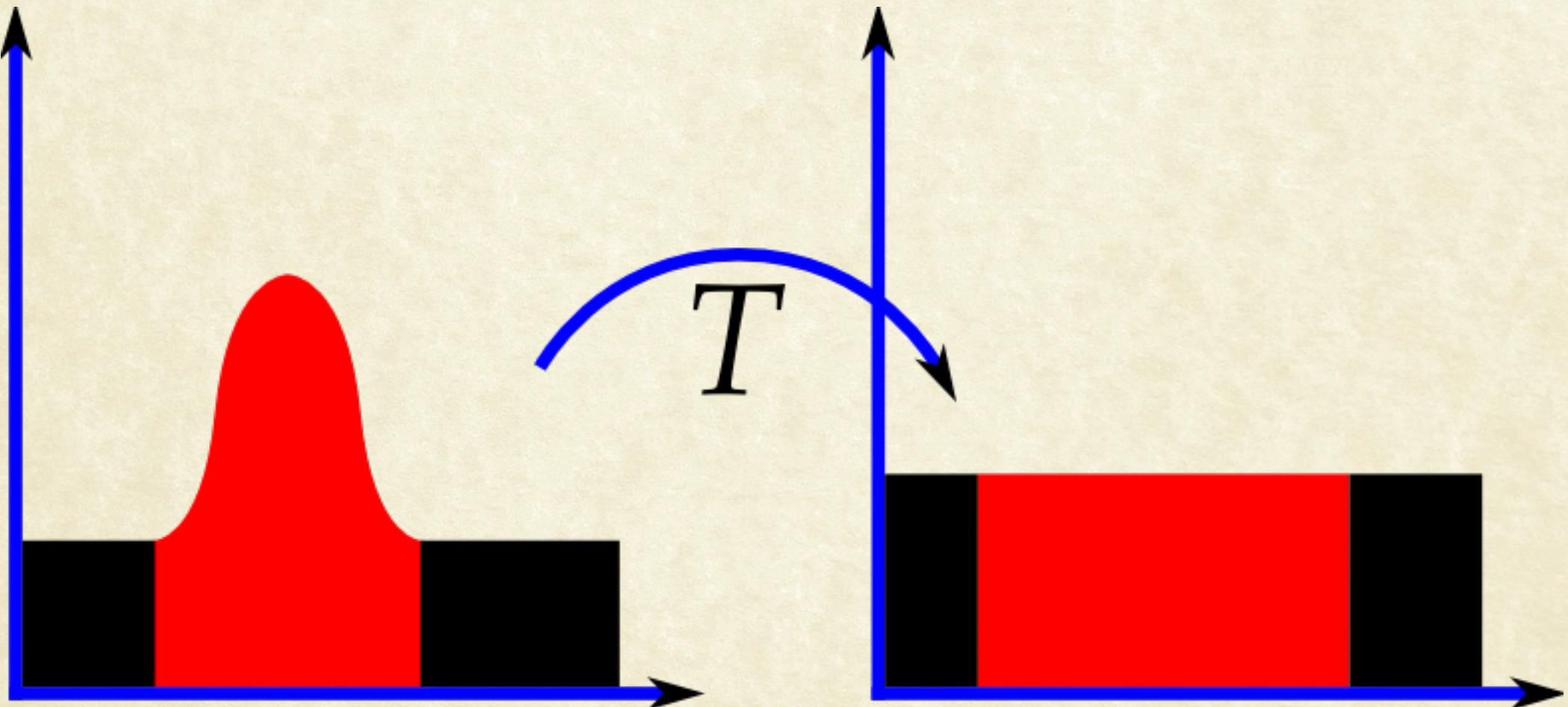
Are all intensities well represented ?

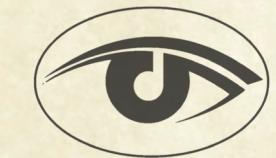


All Intensities
Matter

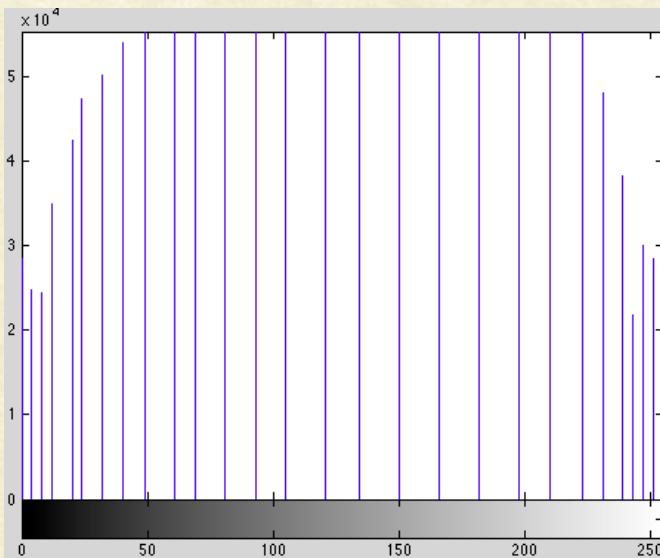
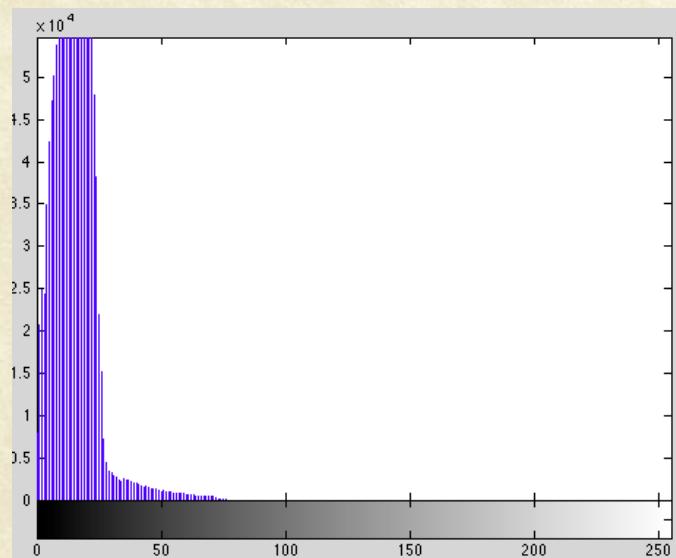
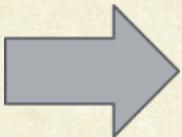


Histogram Equalization





Histogram Equalization





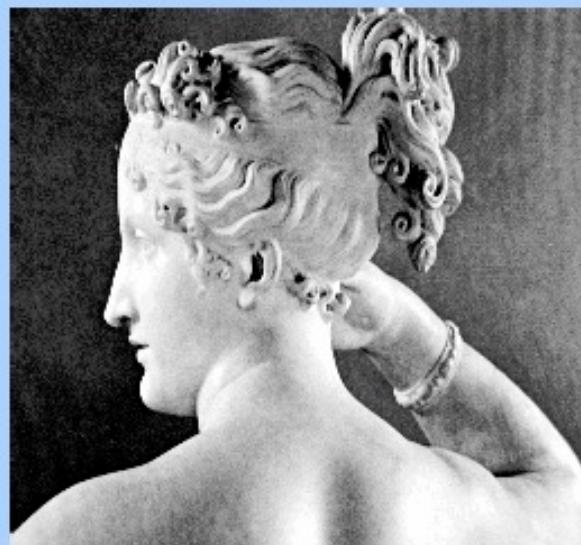
Histogram Equalization



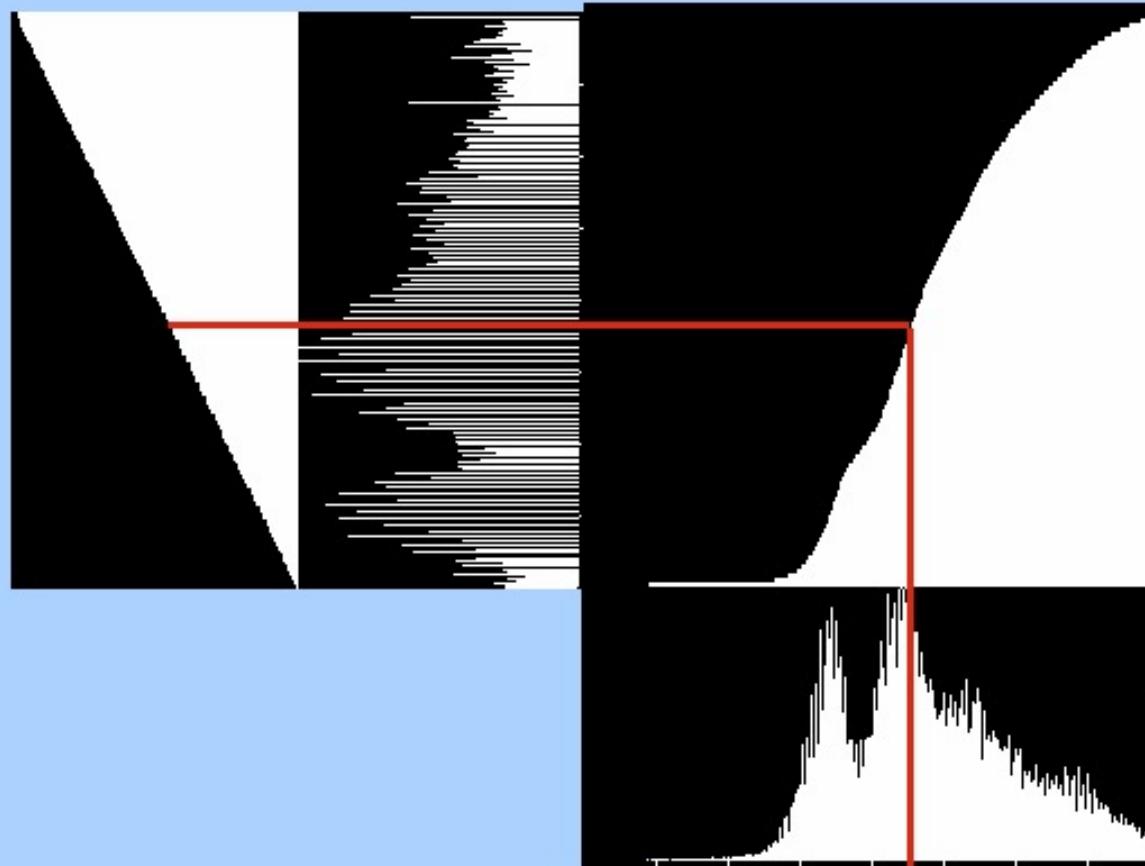
Contrast
Stretching



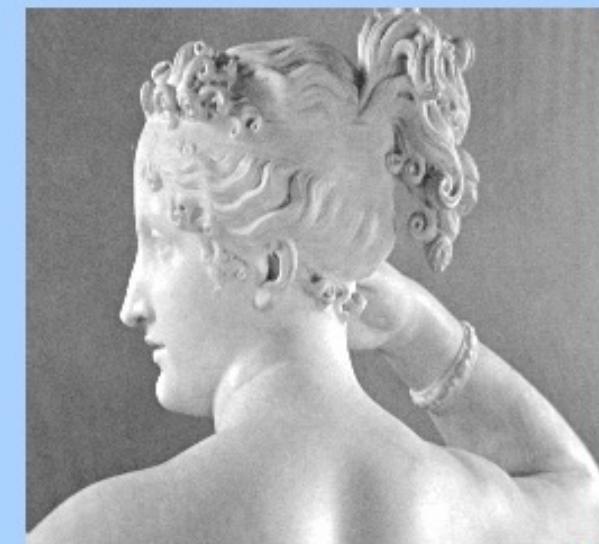
Histogram
Equalization



Equalized histogram



Histogram of riginal image



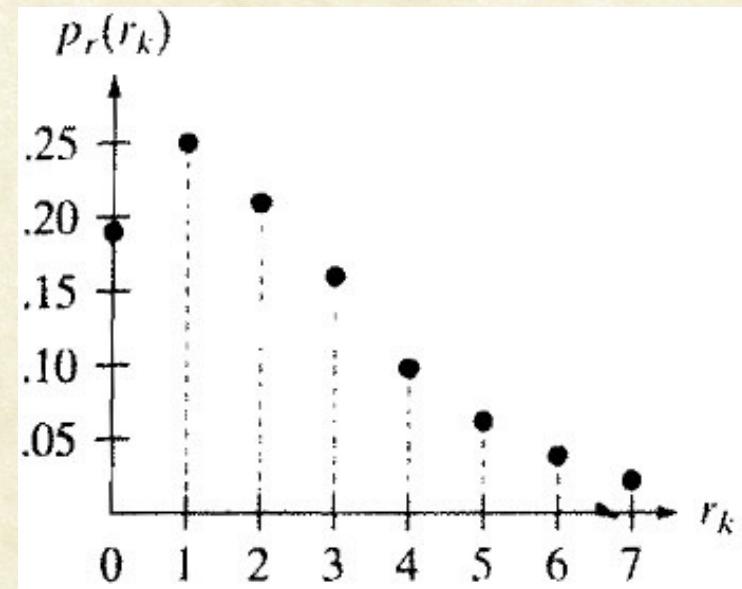


Histogram Equalization - Example

64 × 64 image

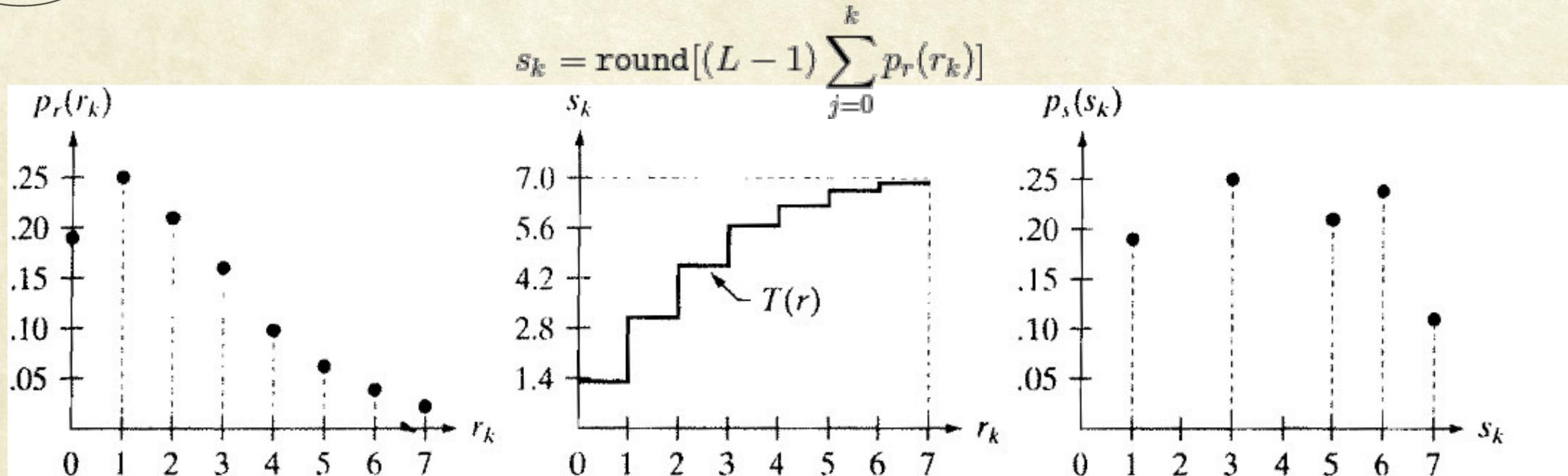
3-bits / pixel

r_k	n_k	$p_r(r_k) = n_k/MN$
$r_0 = 0$	790	0.19
$r_1 = 1$	1023	0.25
$r_2 = 2$	850	0.21
$r_3 = 3$	656	0.16
$r_4 = 4$	329	0.08
$r_5 = 5$	245	0.06
$r_6 = 6$	122	0.03
$r_7 = 7$	81	0.02





Histogram Equalization - Example



a b c

FIGURE 3.19 Illustration of histogram equalization of a 3-bit (8 intensity levels) image. (a) Original histogram. (b) Transformation function. (c) Equalized histogram.



Histogram Equalization

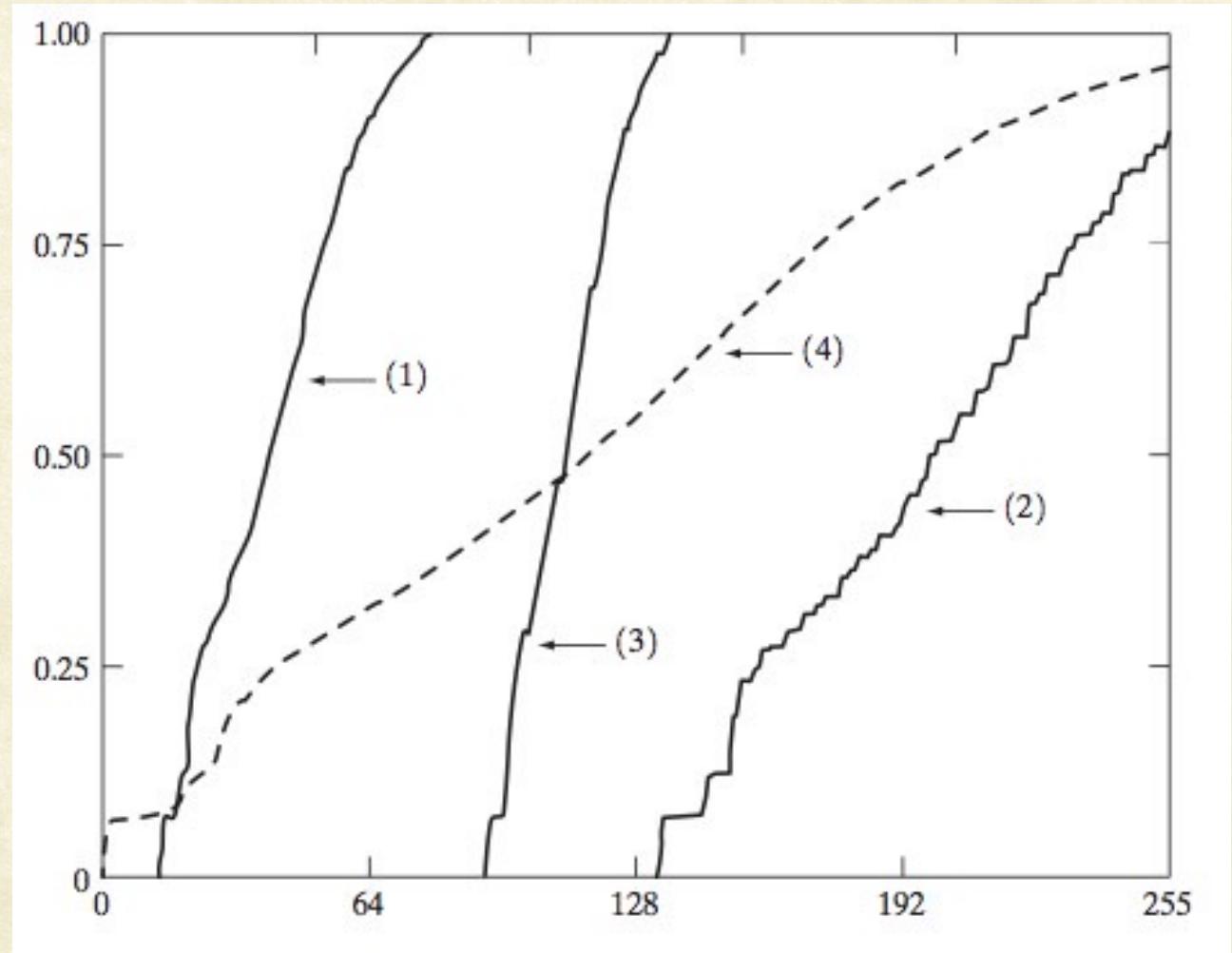
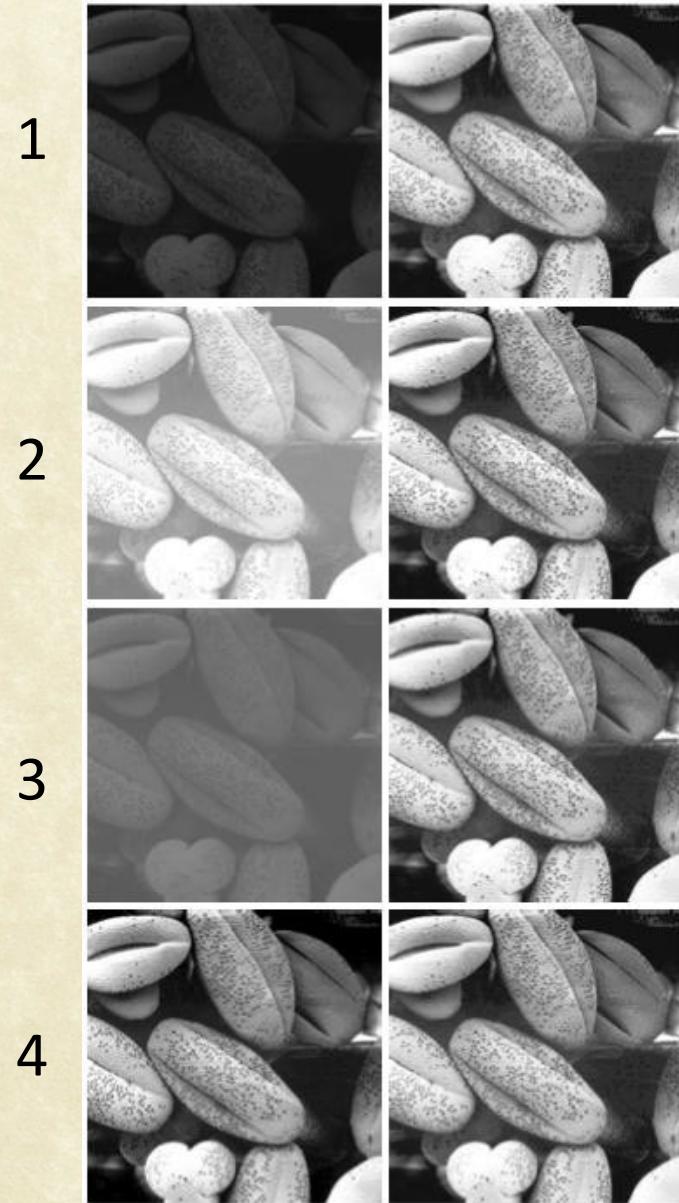


Image Courtesy: Gonzalez and Woods



Histogram Equalization v/s Contrast Enhancement



Contrast Enhancement



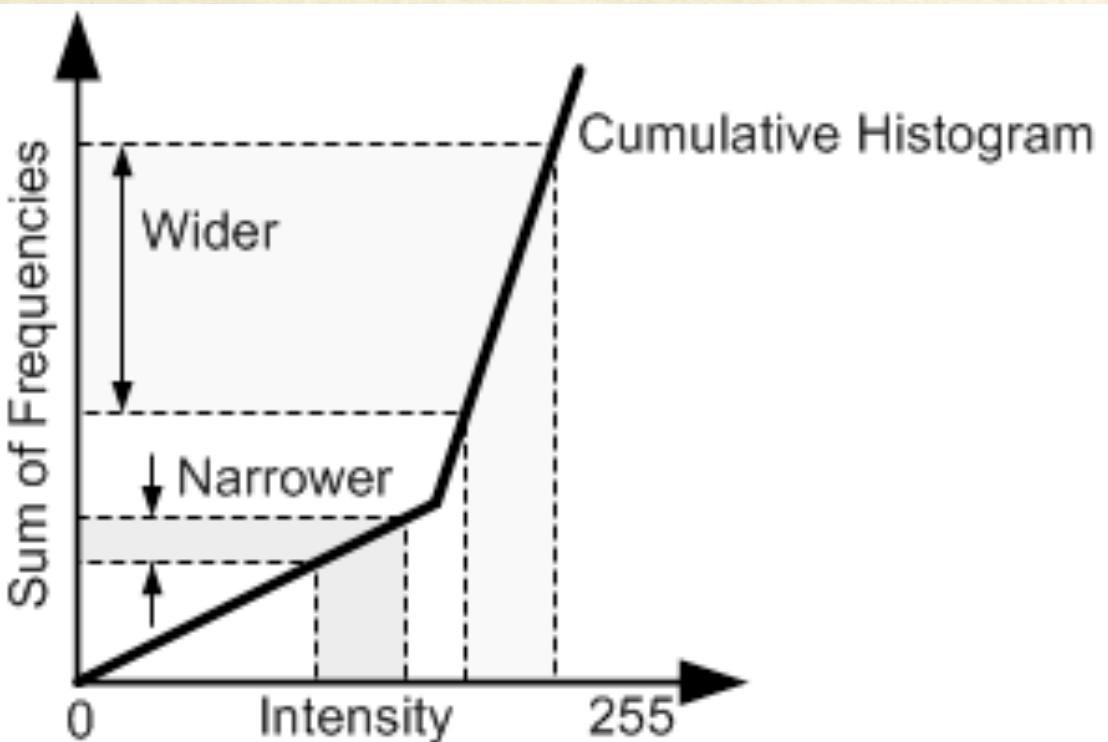
Histogram equalization



Histogram Equalization: A Visual Explanation

$$h[i] = \text{constant}, \quad 0 \leq i \leq L - 1$$

$$s = T(r) = (L - 1) \int_0^r p_r(w) dw$$



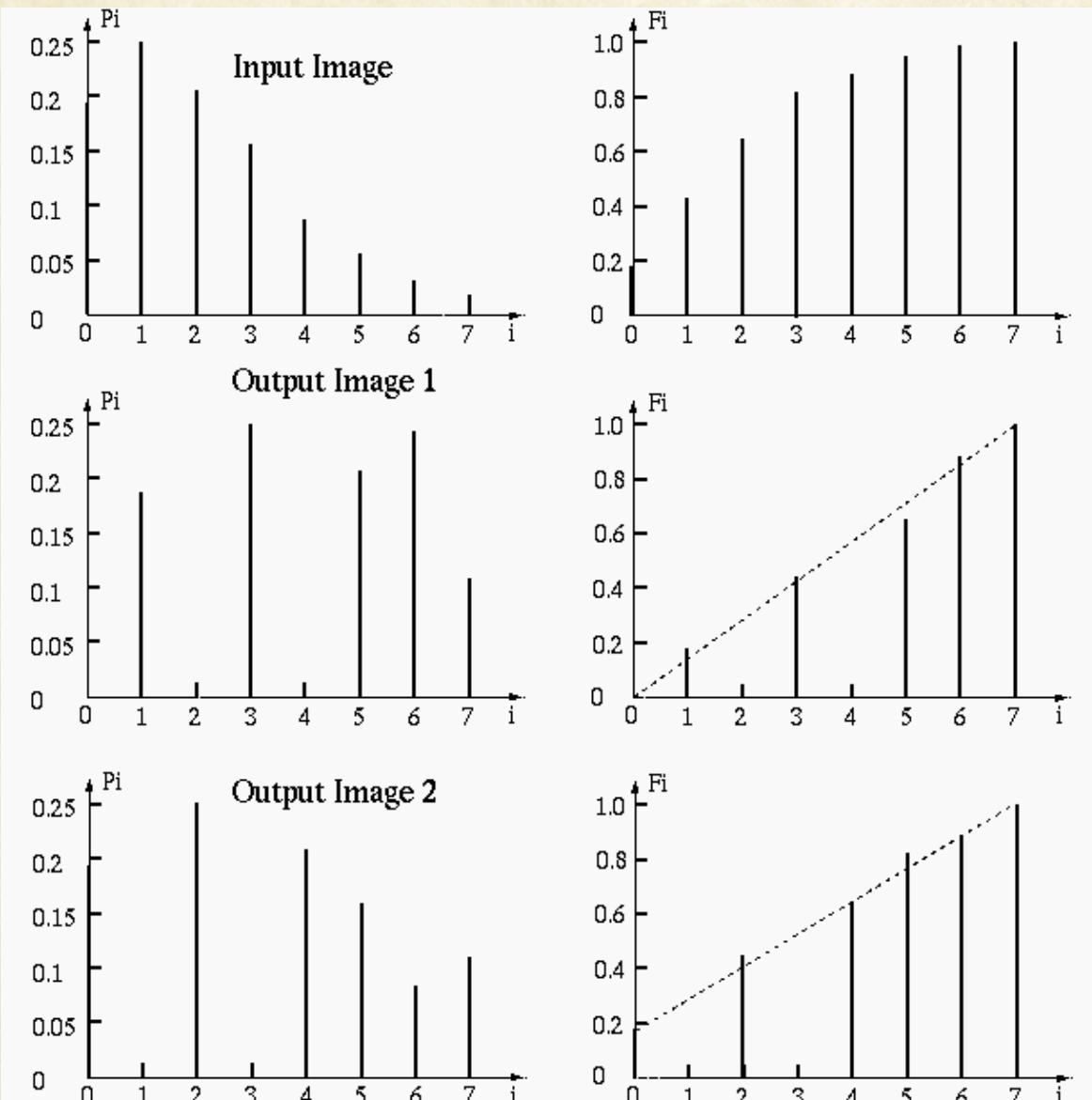
$$s_k = T(r_k) = \text{round} \left((L - 1) \sum_{j=0}^k p_r(r_j) \right)$$

$$s_k = T(r_k) = \text{round} \left((L - 1) \frac{cdf(r_k) - cdf_{min}}{1 - cdf_{min}} \right)$$

$$cdf_{min} = p_r(r_a) \text{ where } r_a = \min\{r_t | p_r(r_t) > 0\}; 0 \leq r_t \leq (L - 1)$$



Histogram Equalization (Default v/s Ver. 2)



$$s_k = T(r_k) = \text{round} \left((L - 1) \sum_{j=0}^k p_r(r_j) \right)$$

Ver. 2

$$s_k = T(r_k) = \text{round} \left((L - 1) \frac{cdf(r_k) - cdf_{min}}{1 - cdf_{min}} \right)$$



Histogram Equalization

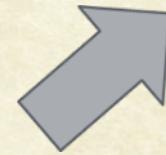
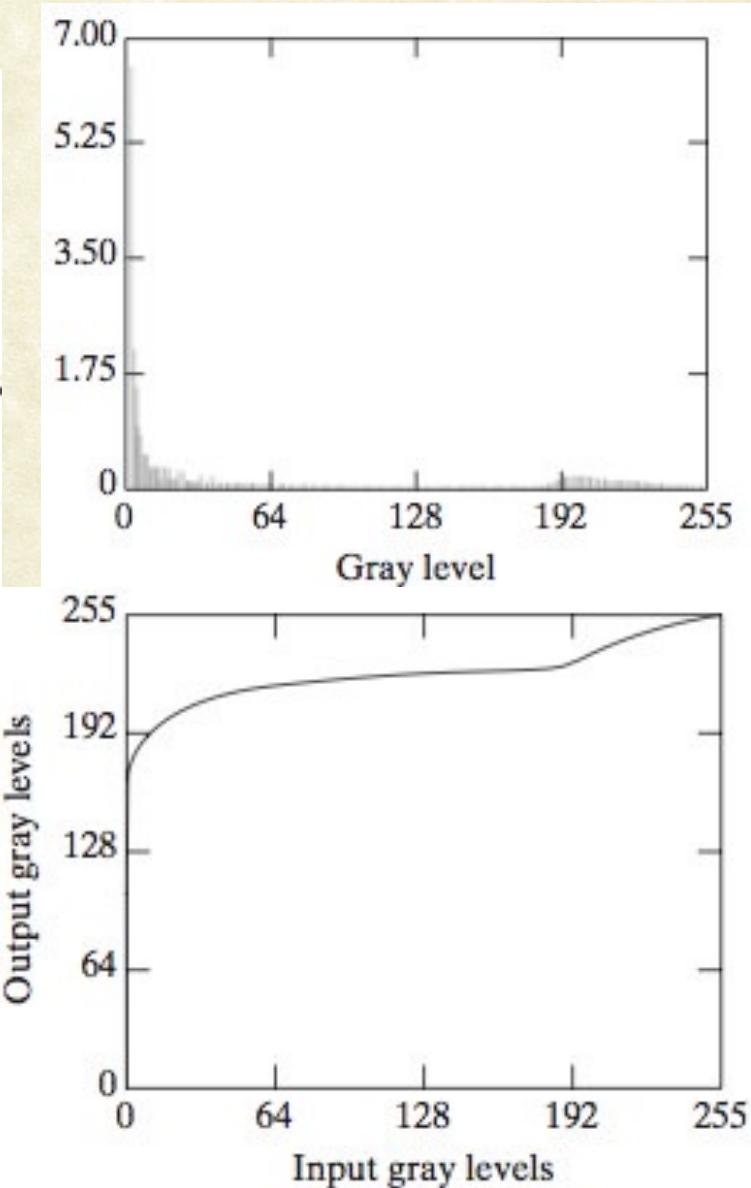
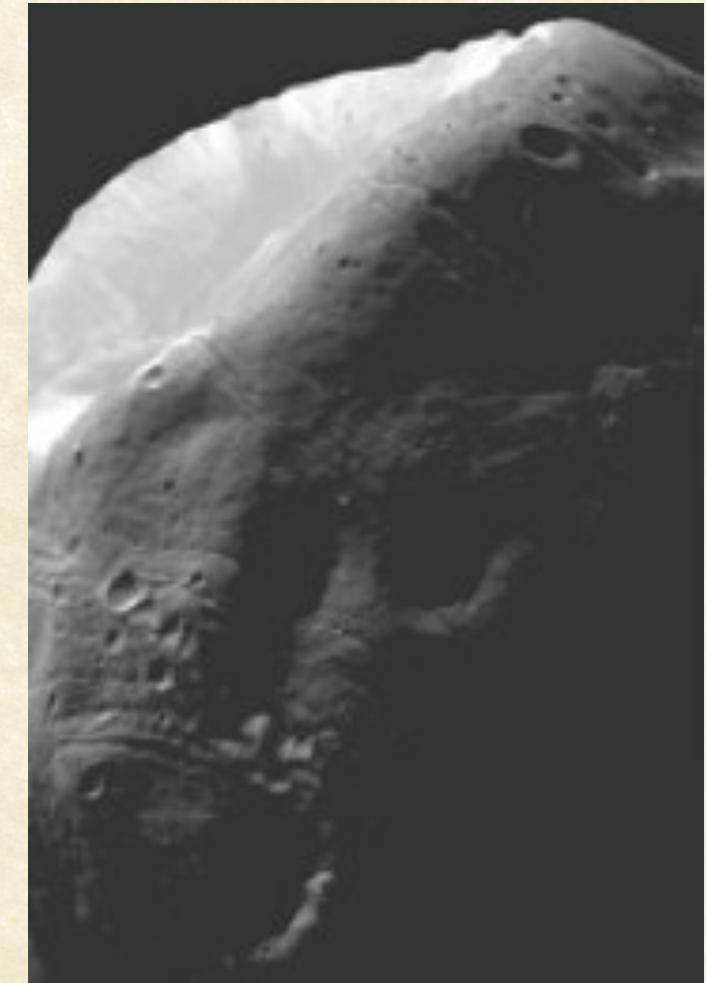
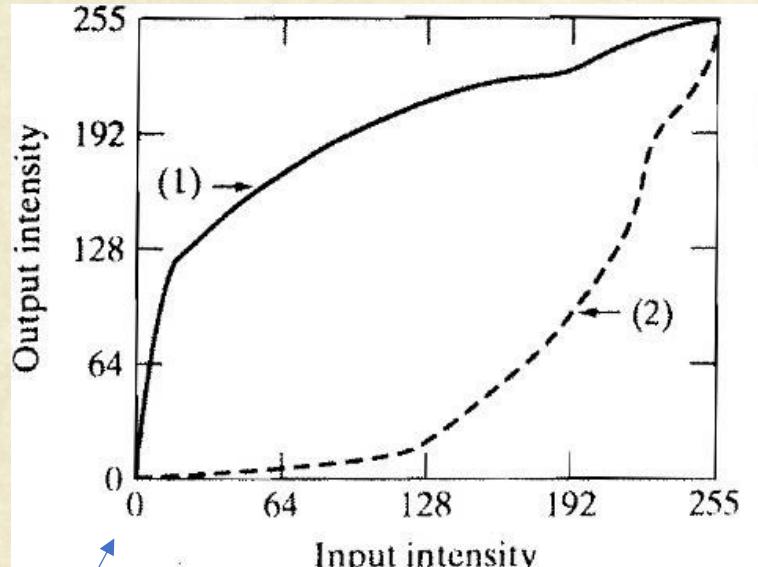


Image Courtesy: Gonzalez and Woods



Histogram Specification / Matching [Section 3.3.2]

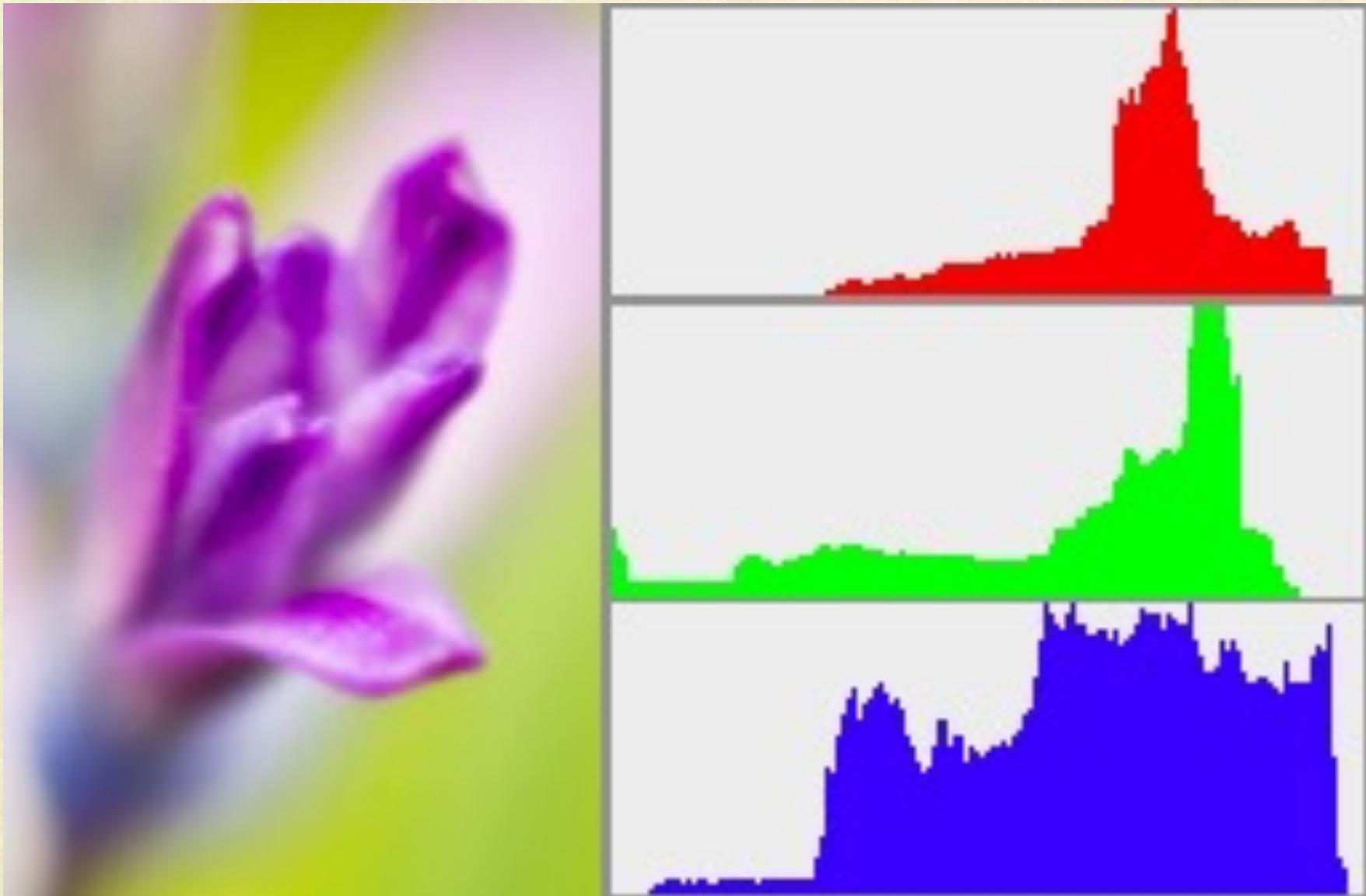


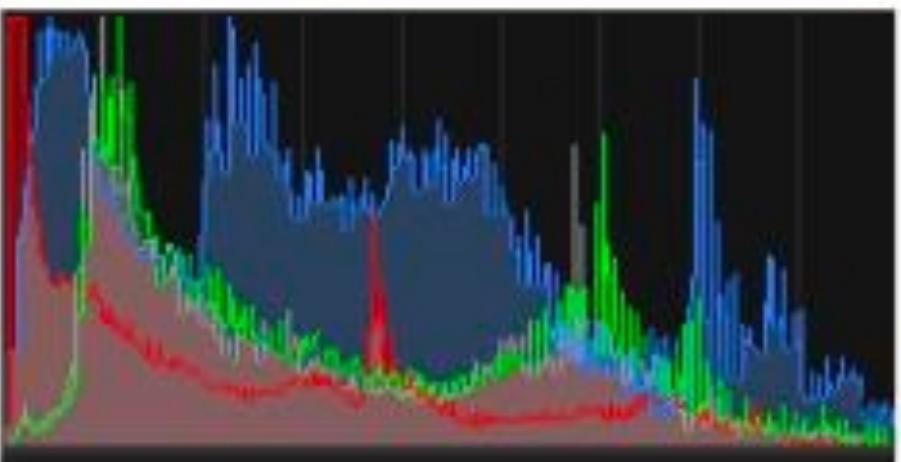
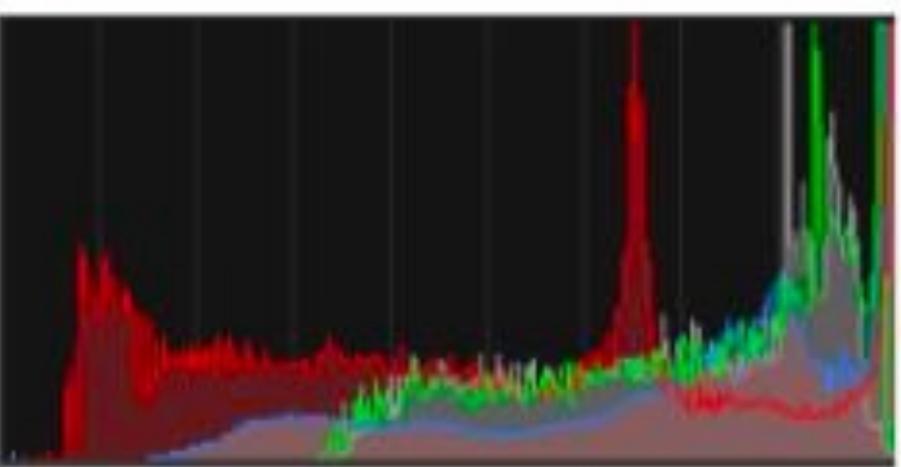
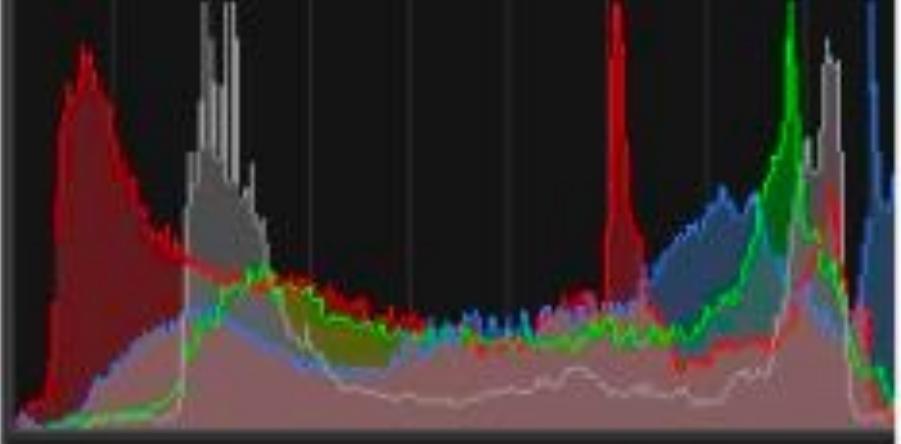
Compare with the curves we saw for contrast enhancement. What's the difference?

Image Courtesy: Gonzalez and Woods



Histograms for RGB images

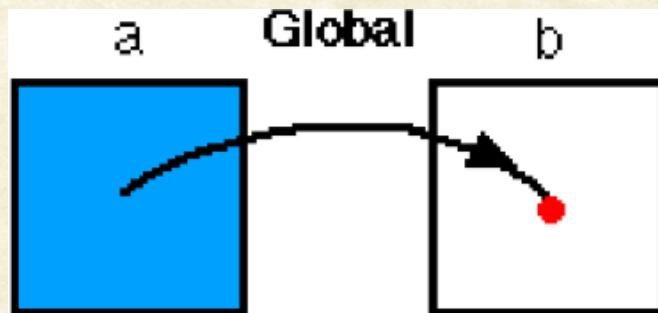






Histogram Processing

▶ Global to Point





Histogram : Discussion

- A visualization
- A useful statistical representation of image intensities
 - Not dependent on image size
- Drawbacks
 - No spatial information
 - Intensity-centric
 - Raw (unnormalized form): Image-size dependent
- Equalization:
 - An image ‘normalization’ approach
 - Improves global contrast, but can also boost noise



References

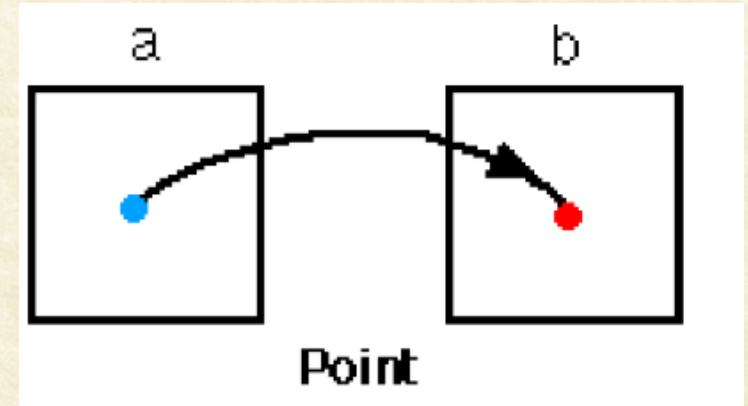
- ▶ GW Chapter – 3.3.1 to 3.3.3
- **Transformations of Random Variables**
 - <http://www.randomservices.org/random/dist/Transformations.html>
 - Section 1 of <http://www.cs.cmu.edu/~minx/transform.pdf>
 - Leibnitz Integration Rule :
https://en.wikipedia.org/wiki/Leibniz_integral_rule#Alternative_derivation
 - [Univariate transformation of a random variable](#)



Summary

- ▶ Manipulating Pixels Directly in Spatial Domain
- ▶ 3 approaches
- ▶ 1. Point to Point

- Linear Intensity Transforms
 - e.g., Negative
- Non-linear Transforms
 - e.g., Logarithm
- Histogram

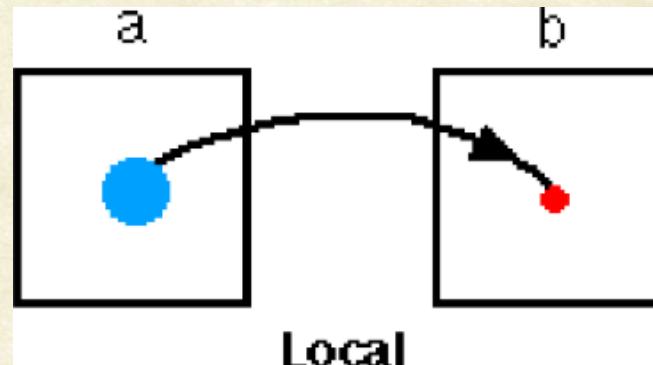




Spatial Domain Processing

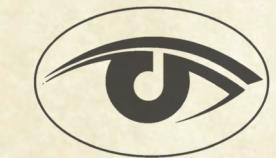
- ▶ Manipulating Pixels Directly in Spatial Domain
- ▶ 3 approaches
- ▶ 2. Neighborhood to Point

48	219	168	145	244	188	120	58
49	218	87	94	133	35	17	148
174	151	74	179	224	3	252	194
77	127	87	139	44	228	149	135
138	229	136	113	250	51	108	163
38	210	185	177	69	76	131	53
178	164	79	158	64	169	85	97
96	209	214	203	223	73	110	200



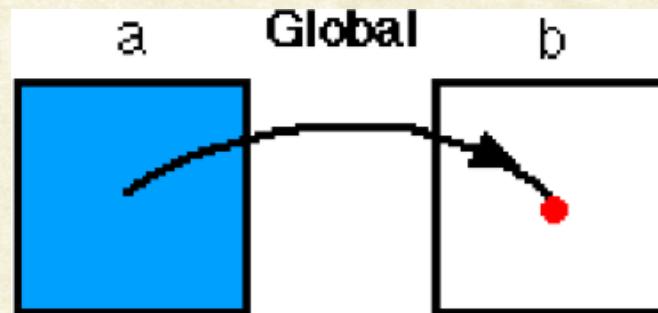
Current pixel

3 × 5 neighbourhood



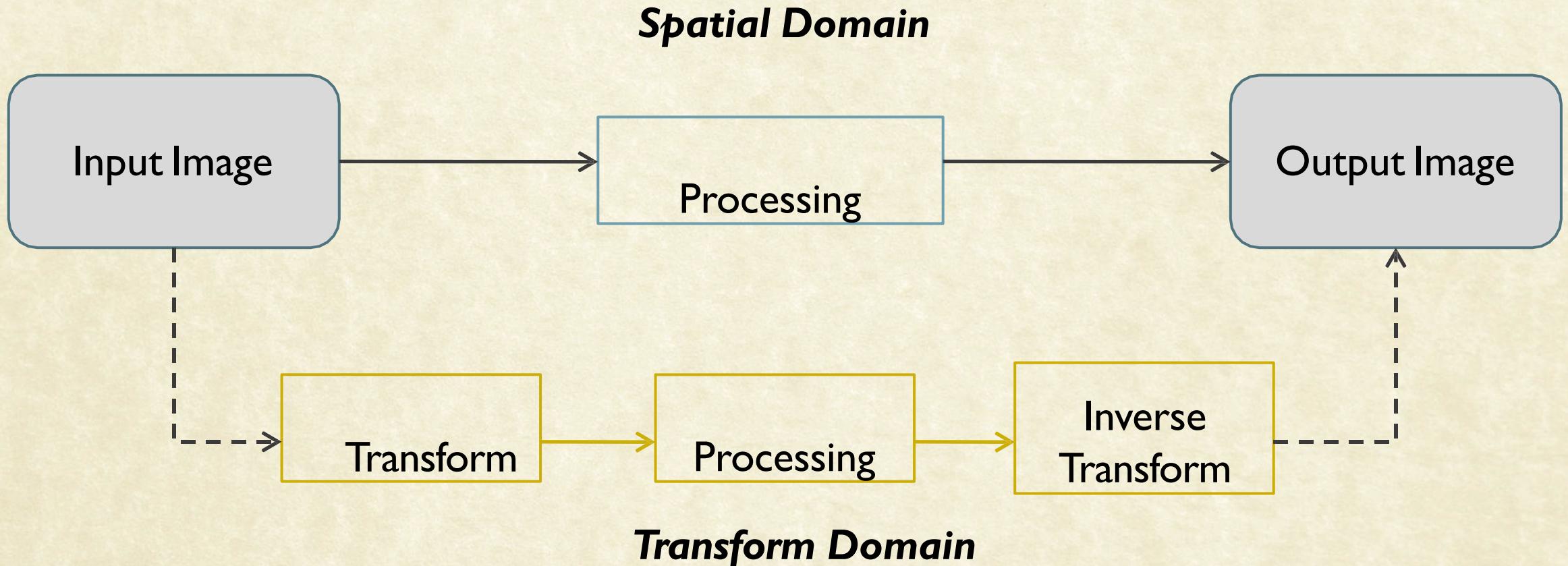
Spatial Domain Processing

- ▶ Manipulating Pixels Directly in Spatial Domain
- ▶ 3 approaches
- ▶ 3. Global to Point





Spatial vs. Transform Domain Processing





Spatial vs. Transform Domain Processing



Bandhani / Bandhej



Tie & Dye



Spatial vs. Transform Domain Processing

Transform (Tie)



Process (Dye)



Inverse Transform (Untie)