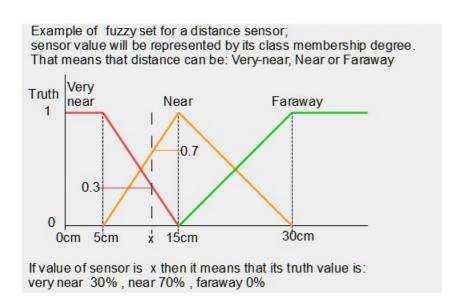
NNFuzzy Library

NNFuzzyLib implements a specific Neural Network that uses a kind of RBF (Radial Basis Function) to realize a Fuzzy System.

A Fuzzy System traslates input values into classes (Fuzzy Sets) then uses a list of rules "if...then..." that describes the functional link between input and output. Output values are expressed in terms of output classes (Mamdani system inference) or in terms of singletons (Sugeno system inference). In this case we use Sugeno version.



Rules example:

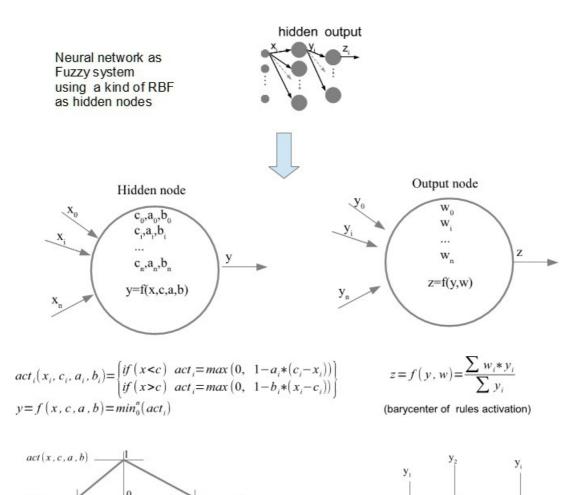
If sensor-1 is Near and sensor-2 is Faraway then motor-1 has to be Medium and motor-2 has to be Low If sensor-1 is Faraway and sensor-2 is Faraway then motor-1 has to be High and motor-2 too .

Where motor Low, Medium and High means for example power percent 0.3, 0.6 and 1.0 (Singletons)

Each rule result: minimum truth value of antecedents (fuzzy logic AND = minimum truth value); this result is applied to consequents as weight for motor power fraction.

Inference result (following Sugeno singletons method):
For each motor the total result is the weighted sum of each rule result (barycenter)

The Neural Network that implements this engine uses a specific local activation system for hidden nodes and a weighted sum as output nodes. The local activation system is made by a specific RBF node as represented below.



Anyway this library can be used in the same way as NNet library. In a word, the library function are the same. As the NNet library, NNFuzzy on Arduino or on PC. Some features (as save on file or load from file) are available only if you comment this define:

#define ARDUINONNFuzzy

A utility C program is provided, to trasform a Fuzzy description of a problem to the exact equivalent NNFuzzy network. The utility is provided as source and as Windows (V10) executable:

- FuzzyDefine.cpp
- FuzzyDefine.exe (Windows 10)

Format: FuzzyDefine.exe filename-fuzzy-definition.txt

Where the fuzzy definition file is a file where are used this keywords: nput,output,inpfuzzyset,outclass,if,and,then.

Example: (/* are comments)

Ardusumo rover Fuzzy model	
input 2 output 2 /* sensor 0 and 1 classes */	// input (sensors) number //output (motors) number
inpfuzzyset 0 L=0.000 V=0.400 VV=0.800	// L:faraway, V:near, VV:very near

```
inpfuzzyset 1 L=0.000 V=0.400 VV=0.800
                                                            // L:faraway, V:near, VV:very near
/* output classes (singletons)*/
outclass BD -0.200 -0.800
                                                            //back and right rotate
outclass RD 0.400 -0.400
                                                            // right rotate
outclass RS -0.400 0.400
                                                            // left rotate
                                                            // go medium speed
outclass AM 0.600 0.600
outclass AS 1.000 0.600
                                                            // go and left rotate
outclass AD 0.600 1.000
                                                            // go and right rotate
outclass AV 1.000 1.000
                                                            // go fast
/* Rules */
if 0=VV and 1=VV then BD
if 0=VV and 1=V then RD
if 0=V and 1=VV then RS
if 0=V and 1=V then AM
if 0=V and 1=L then AS
if 0=L and 1=V then AD
if 0=L and 1=L then AV
```

FuzzyDefine.exe tranform it into:

```
Fuzzy Neural Network definition
char* netdef=
"L0 2 "
"L1 7 NodeFuzzy"
"FCT0 0.8 0.8 "
"FCT1 0.8 0.4 "
"FCT2 0.4 0.8 "
"FCT3 0.4 0.4 "
"FCT4 0.4 0.0 "
"FCT5 0.0 0.4 "
"FCT6 0.0 0.0 "
"FWA0 2.5 2.5 "
"FWA1 2.5 2.5 "
"FWA2 2.5 2.5 "
"FWA3 2.5 2.5 "
"FWA4 2.5 0.1 "
"FWA5 0.1 2.5 "
"FWA6 0.1 0.1 "
"FWB0 0.1 0.1 "
"FWB1 0.1 2.5 "
"FWB2 2.5 0.1 "
"FWB3 2.5 2.5 "
"FWB4 2.5 2.5 "
"FWB5 2.5 2.5 "
"FWB6 2.5 2.5 "
"L2 2 NodeDFTnh "
"OLW0 -0.2 0.4 -0.4 0.6 1.0 0.6 1.0 "
"OLW1 -0.8 -0.4 0.4 0.6 0.6 1.0 1.0 "
```

And now you have just to instanziate Neural Network: NNfuzzy net(netdef). And use it.