

Release Notes for Noble NB4+ Transmitter Firmware/Noble NB4+ 软件版本更新记录

新增功能: 无

修改功能: 优化调节亮度时屏幕偶尔出现的轻微闪烁问题。

• 优化其他与用户体验相关的问题。

▶ 特殊变化: • 无

注意事项

• 更新完成后模型数据可能会被复位,建议提前通过遥控管家进行数据备份,然后导入该版本使用。

• 发射机和接收机更新完成后需要重新对码。

New functions: • None

Modified functions:
Optimized the occasional slight flickering of the screen when adjusting the brightness of the transmitter.

Optimized other user experience related issues.

Special changes: • None

Notes

- After the transmitter firmware update is finished, the model data may will be reset. It is recommended to back up data through the FlySkyAssistant, and then import the data after the update is finished.
- The transmitter and the receiver need to be rebound after the update is finished.



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Software version 软件版本	1.0.7		Date 日期	05/2024
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新增功能: 新增支持好盈 i-BUS2 R3 电调及相关功能。

修改功能: 优化失控保护机制,提升远距离延时体验。

• 优化其他与用户体验相关的问题。

▶ 特殊变化: • 无

注意事项

• 发射机固件更新完成后,模型数据会被复位。在固件更新之前,可通过遥控管家进行数据备份,然后导入该版本使用。

• 发射机和接收机更新完成后需要重新对码。

New functions:
Added support for HobbyWing i-BUS2 R3 ESC and related functions.

• Optimized the failsafe algorithm so as for better latency experience to

Optimized other issues related to user experience.

Special changes: • None

Notes

- After the transmitter firmware update is finished, the model data will be reset. It is recommended to back up data through the FlySkyAssistant, and then import the data after the update is finished.
- The transmitter and the receiver need to be rebound after the update is finished.



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新增功能: 无

修改功能: • 优化屏幕触摸灵敏度。

• 修复使用发射机更新 INr4-GYB 接收机后,无法校准陀螺仪的问题。

• 优化其他与用户体验相关的问题。

▶ 特殊变化: • 无

注意事项

• 更新完成后模型数据可能会被复位,建议提前通过遥控管家进行数据备份,然后导入该版本使用。

• 发射机和接收机更新完成后需要重新对码。

New functions: • None

Modified functions:
Optimized screen touch sensitivity.

• Fixed the issue that the gyroscope cannot be calibrated after updating the firmware of INr4-GYB receiver via the transmitter.

• Optimized other user experience related issues.

Special changes: • None

Notes

- After the transmitter firmware update is finished, the model data may will be reset. It is recommended to back up data through the FlySkyAssistant, and then import the data after the update is finished.
- The transmitter and the receiver need to be rebound after the update is finished.