

# **ONOE INSTRUCTION BOOKLET**

**v1.2.0**

## PARTS

~3D Printed~



MAIN MOLD A



MAIN MOLD B



PLATFORM



TOP CAP



PLUG



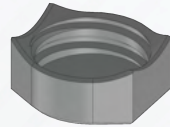
BOTTOM CAP



TIP MOLD A



TIP MOLD B



TIP MOLD CAP



LOWER GUARD



UPPER GUARD



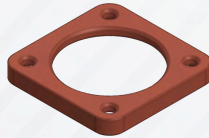
HALF SPOOL **x8**



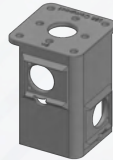
SPRING PLATE



AXLE **x2**



BRACKET



SERVO MODULE A



SERVO MODULE B

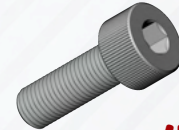


SPACER **x2**

~Hardware~



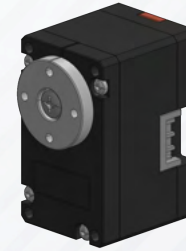
**x4**  
M2 x 6 mm



**x4**  
M4 x 12 mm



**x4**  
M2 x 8 mm



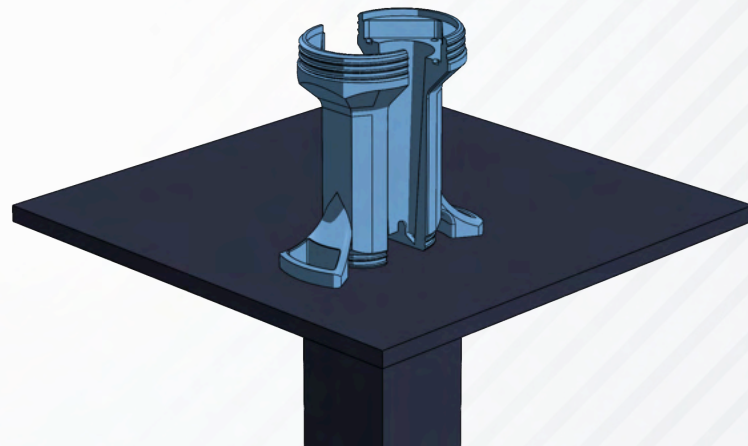
**x2**  
DYNAMIXEL  
XC-330



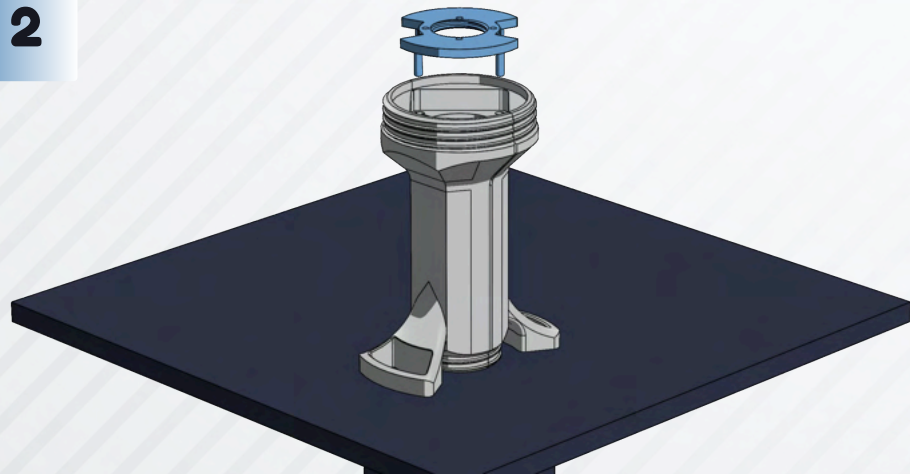
**x4**  
2 mm  
Aluminum Rod

## PART 1: MOLDING

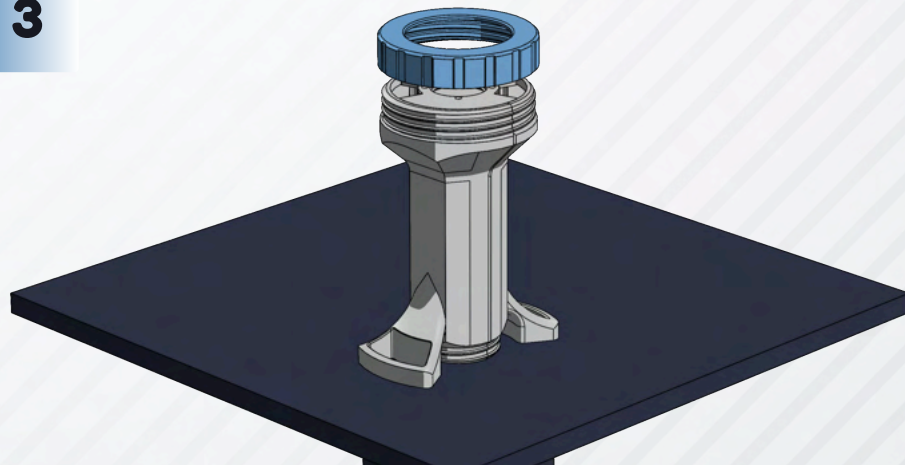
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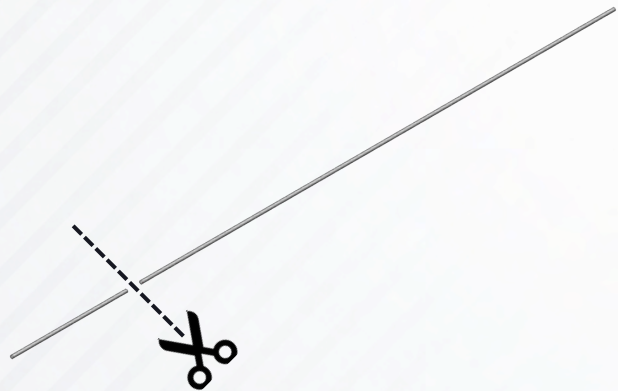
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3



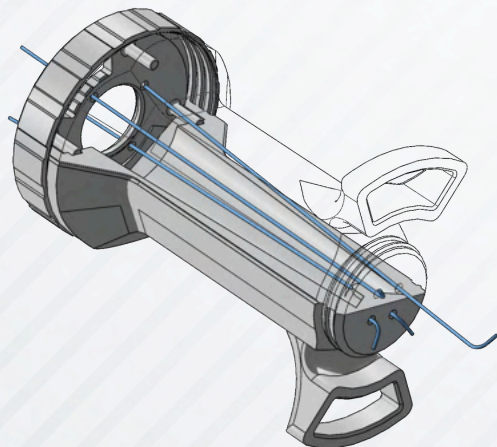
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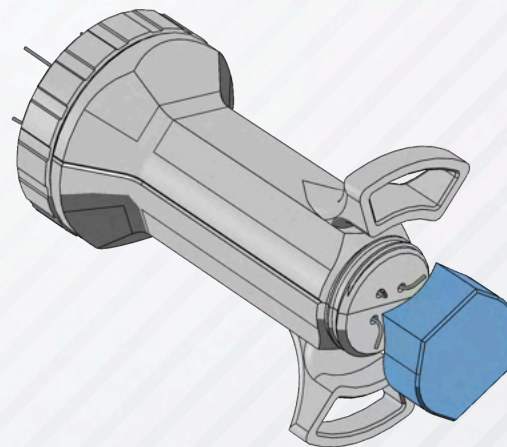
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6



7

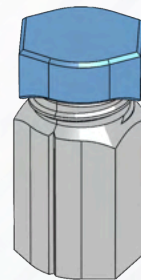




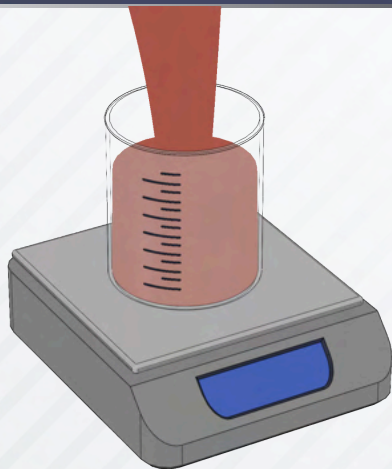
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9



10



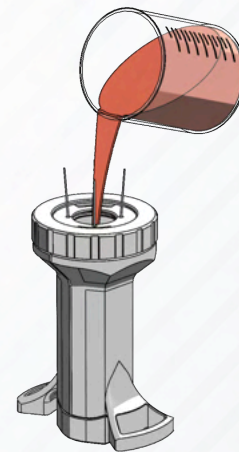
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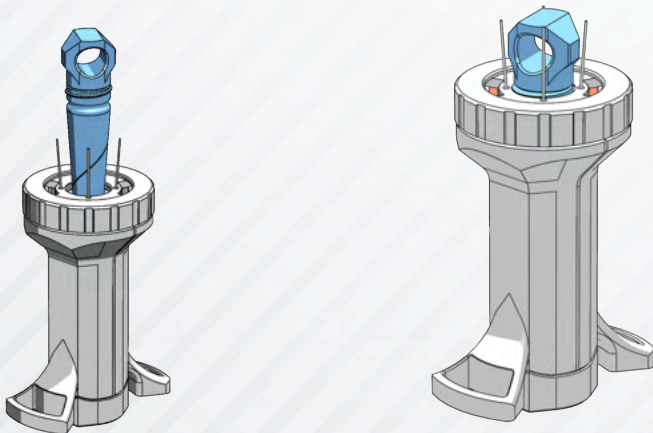
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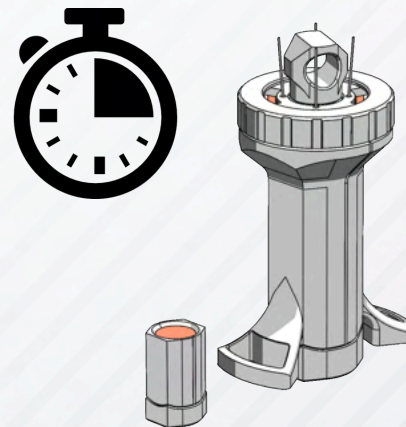
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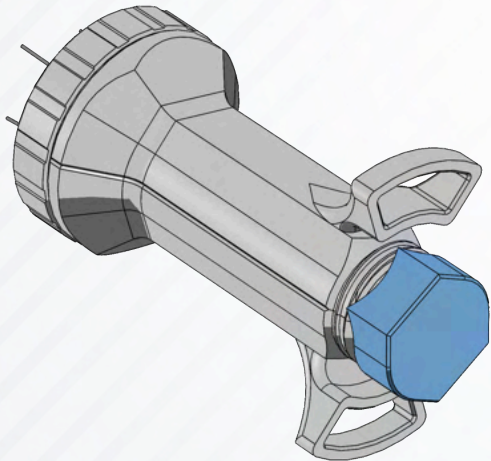
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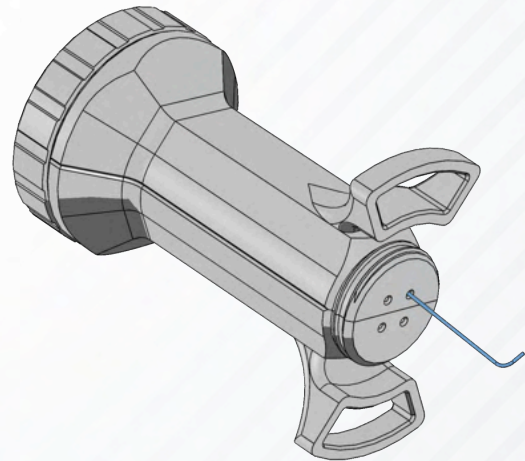
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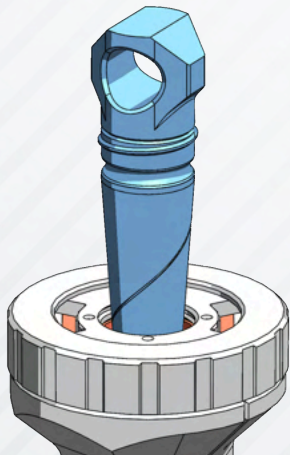
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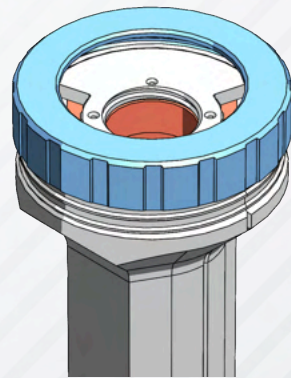
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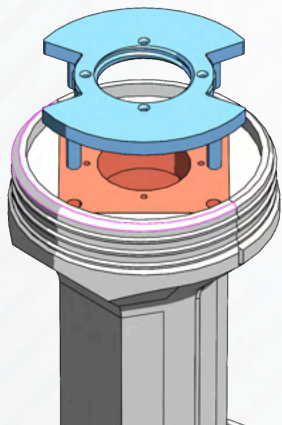


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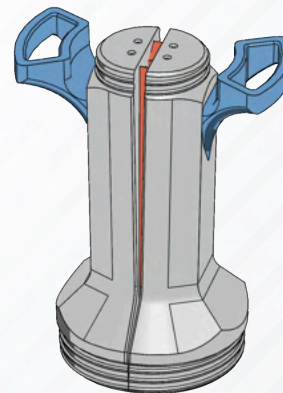




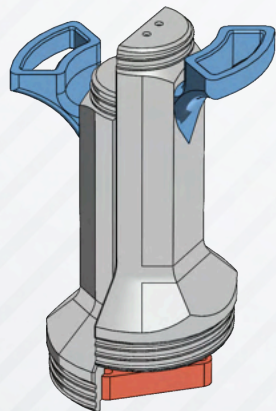
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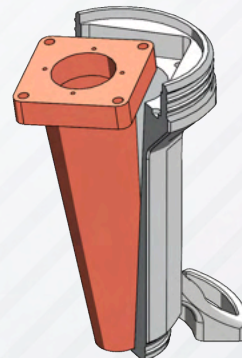
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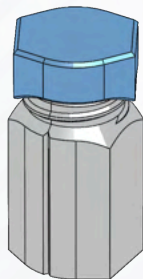


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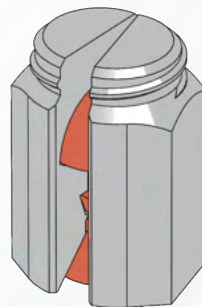




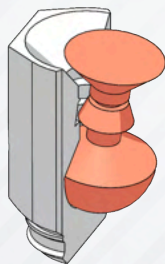
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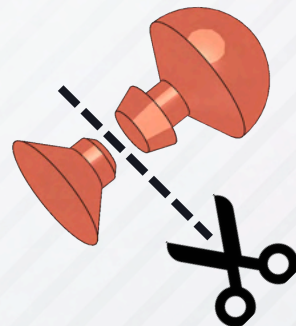
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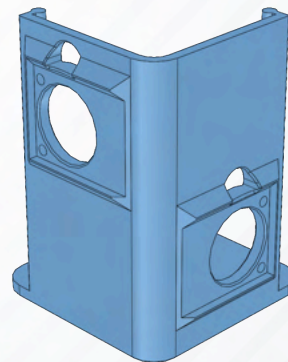


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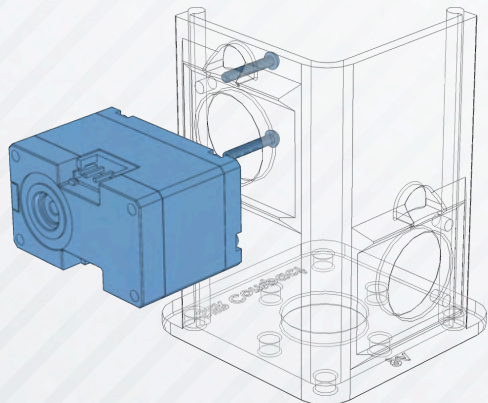


## PART 2: SERVO MODULE

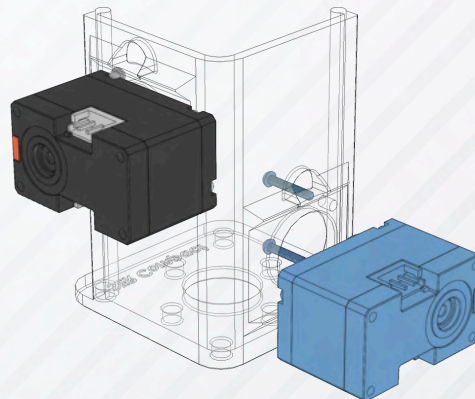
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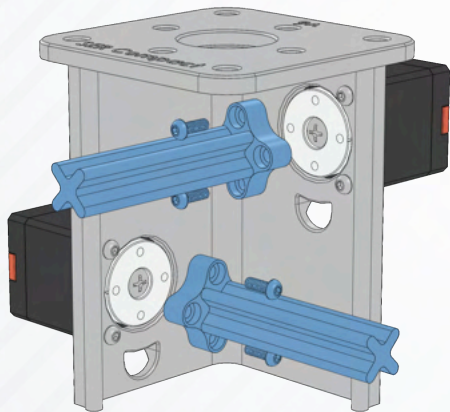
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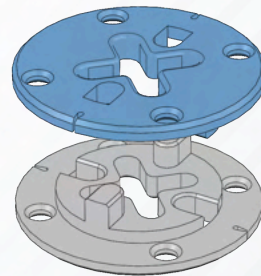
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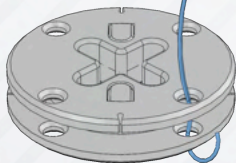
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5



6

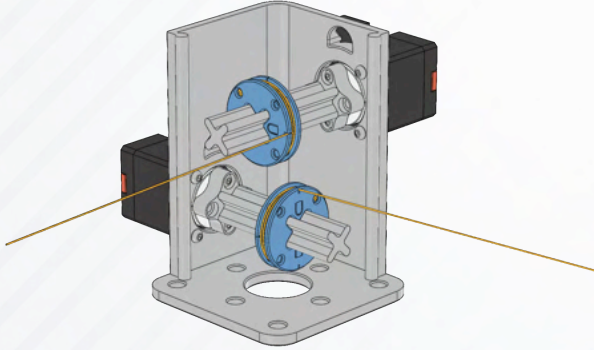


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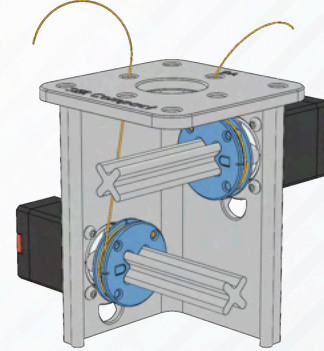




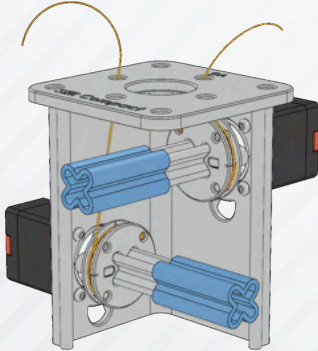
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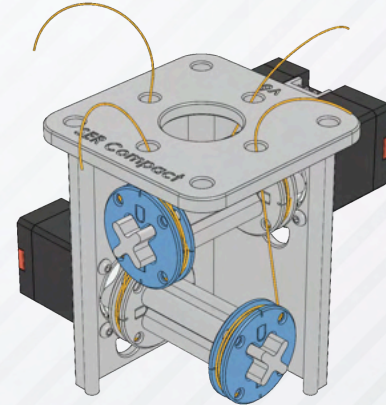
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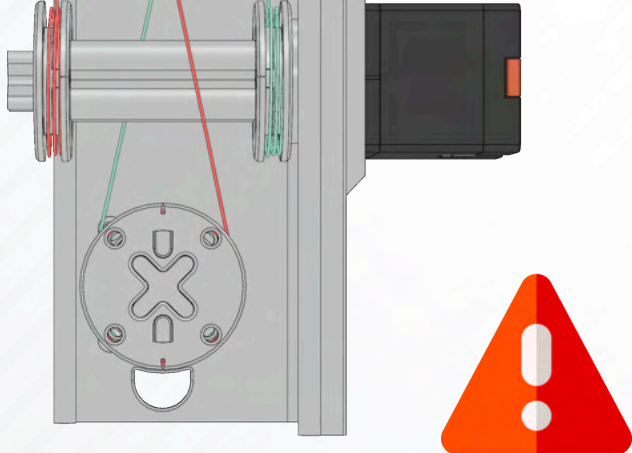


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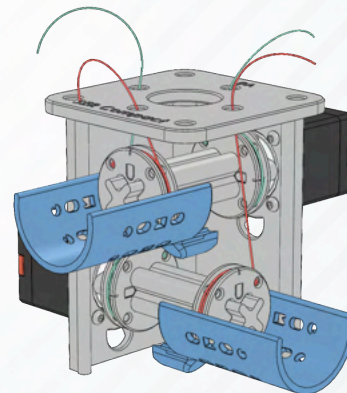




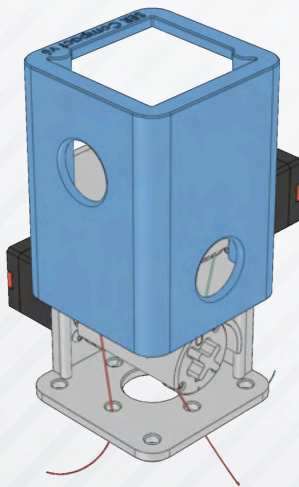
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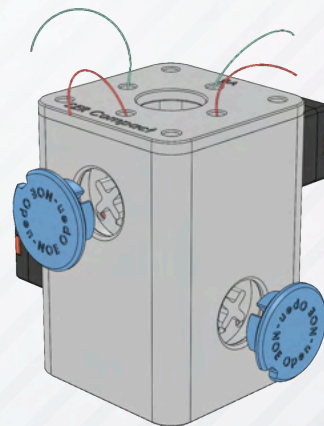
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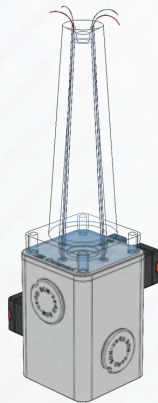
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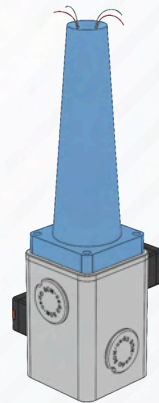
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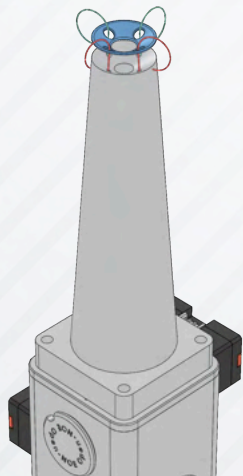
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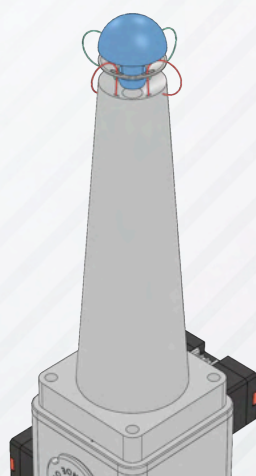
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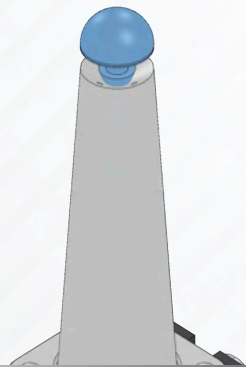
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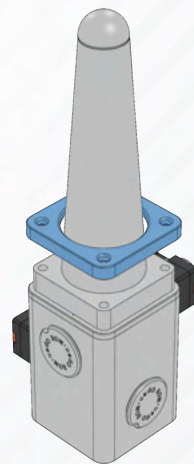
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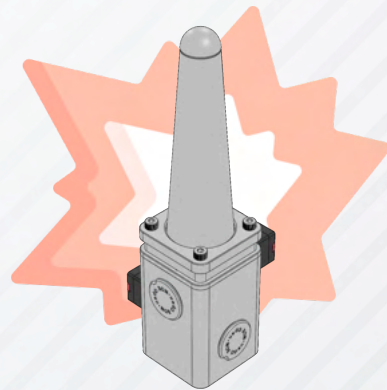
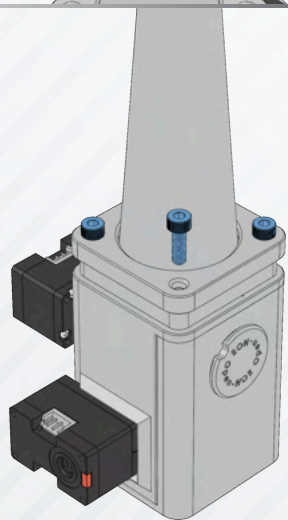
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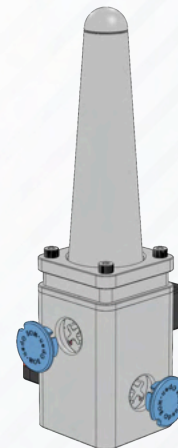


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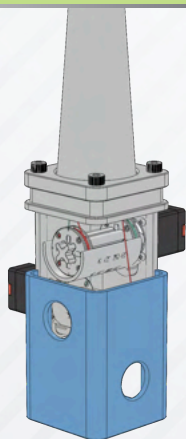


## PART 3: TENSIONING

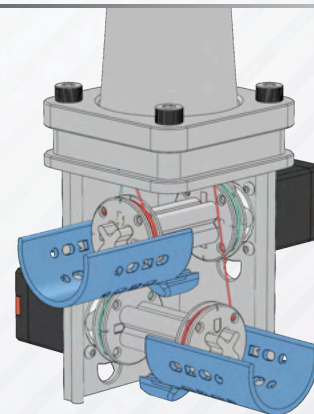
1



2

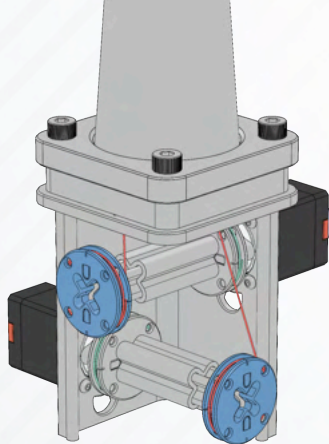


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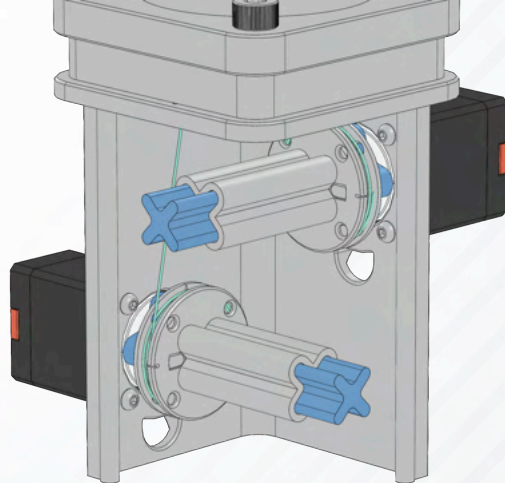




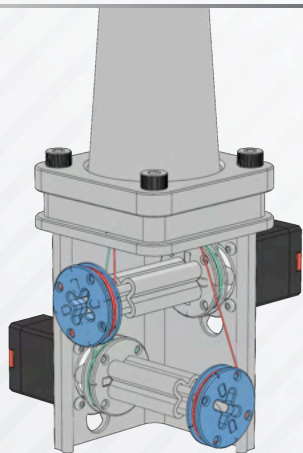
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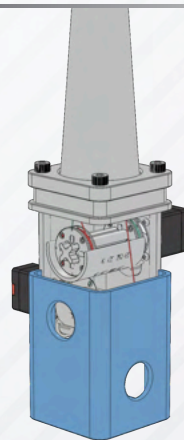
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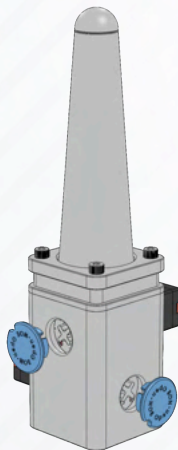


6



7



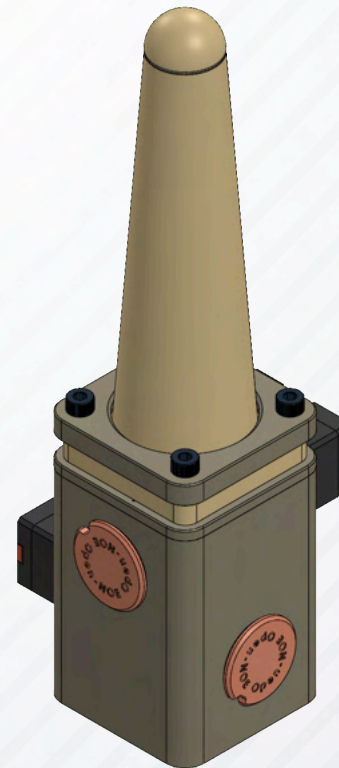


**Finger Module Version:** 1.0.0

**Instruction Booklet Version:** 1.1.0

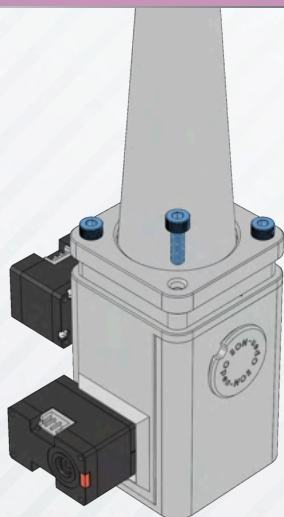
**Update Notes:** - Added parts list

*Designed by Momentum Lab at Carnegie Mellon Robotics Institute*

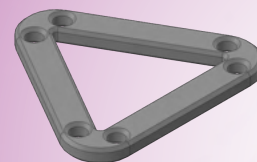
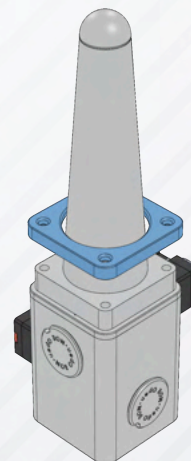


## PART 4: JOINING MULTIPLE FINGERS

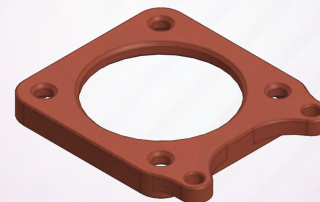
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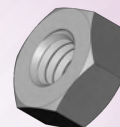
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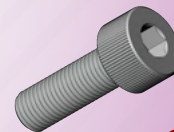
TRIANGLE  
CONNECTOR



BRACKET WITH TABS

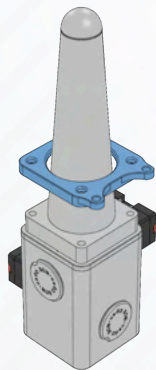


M4  
**x6**

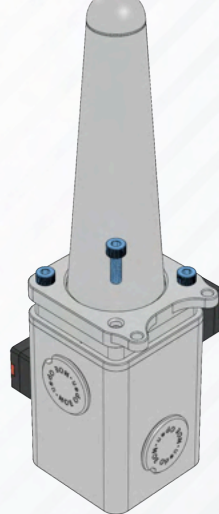


**x6**  
M4 x 12 mm

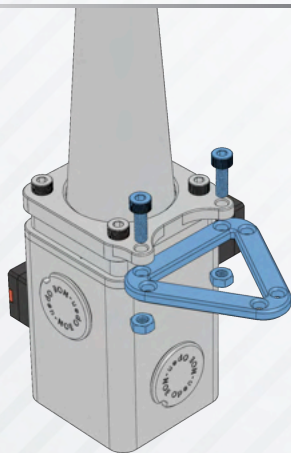
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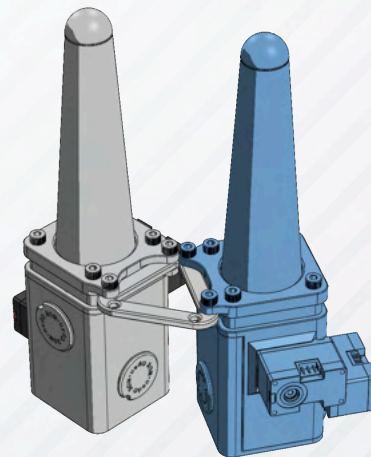
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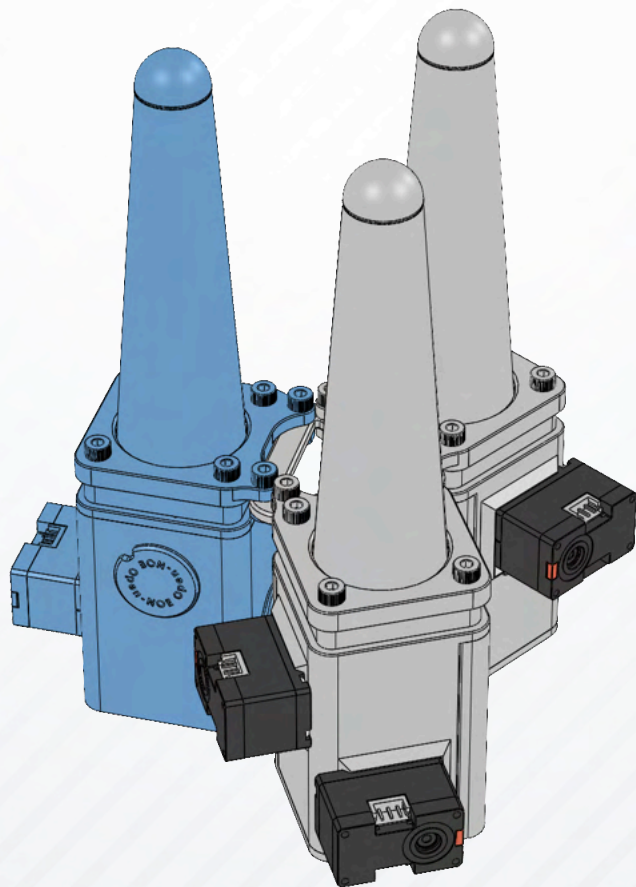
5



6







**Finger Module Version: 1.0.0**

**Instruction Booklet Version: 1.2.0**

**Update Notes:**

- Added section for joining multiple finger modules
- Added page numbers

*Designed by Momentum Lab at Carnegie Mellon Robotics Institute*

