

# **ONOE INSTRUCTION BOOKLET**

**v1.2.0**

# PARTS

~3D Printed~



MAIN MOLD A



MAIN MOLD B



PLATFORM



TOP CAP



PLUG



BOTTOM CAP



TIP MOLD A



TIP MOLD B



TIP MOLD CAP



LOWER GUARD



UPPER GUARD



HALF SPOOL

x8



SPRING PLATE



AXLE



BRACKET



SERVO MODULE A



SERVO MODULE B



SPACER



DYNAMIXEL  
XC-330

x2

2 mm  
Aluminum Rod

2

~Hardware~



x4



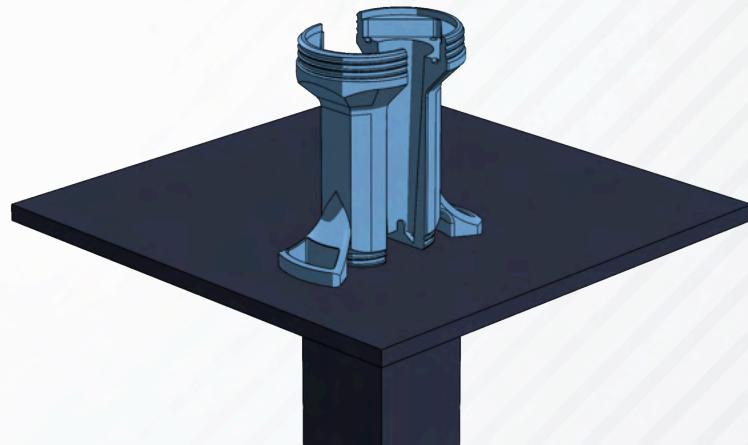
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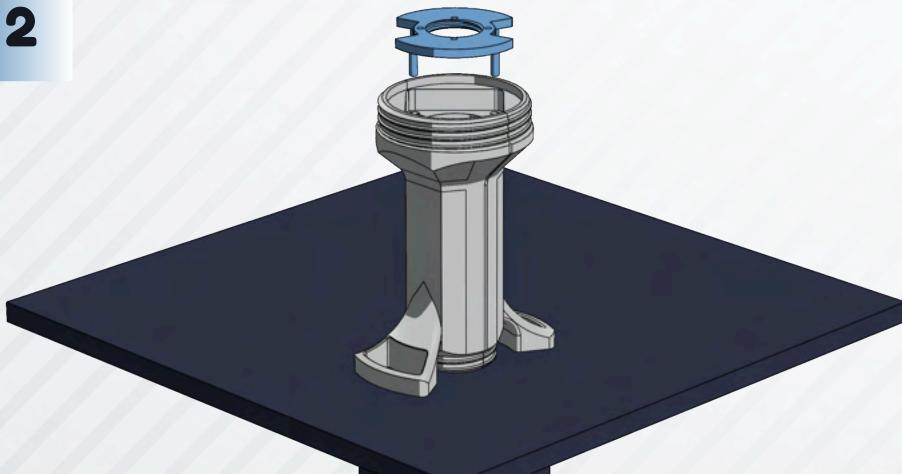
x4

# PART 1: MOLDING

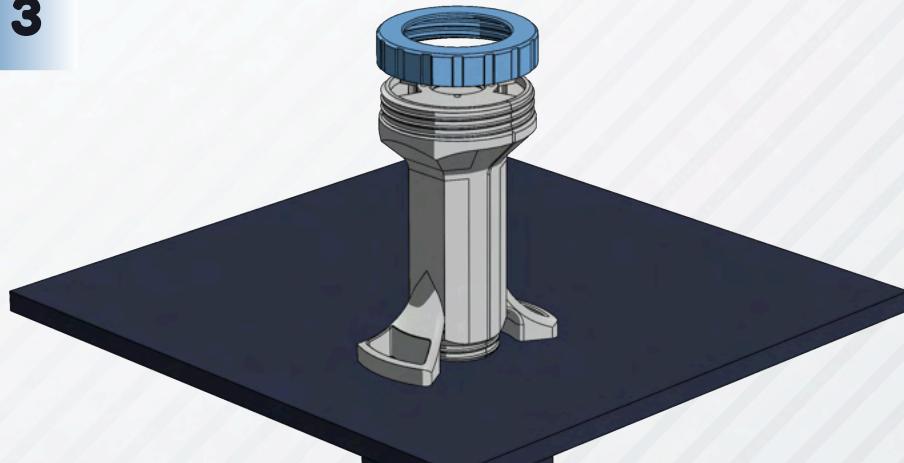
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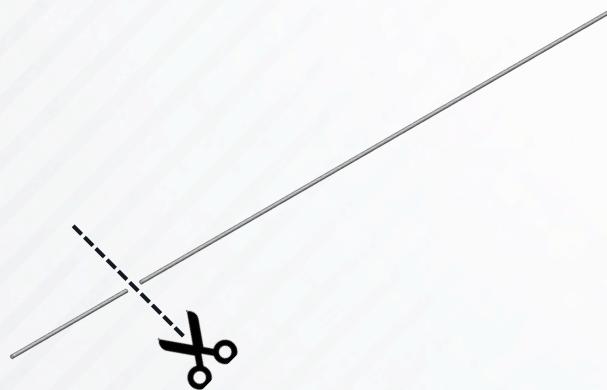


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3

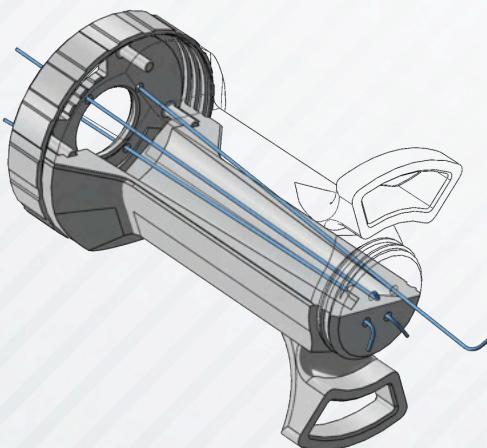
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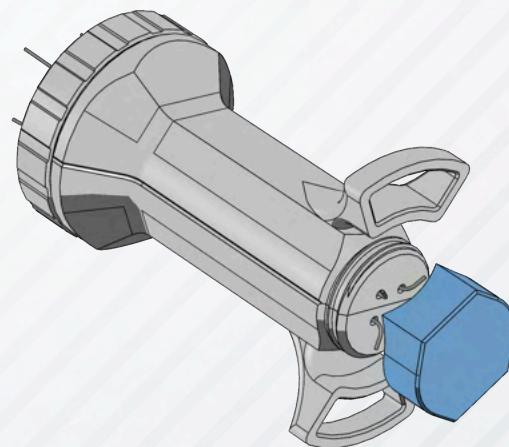
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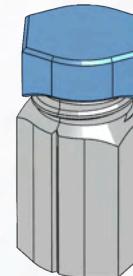
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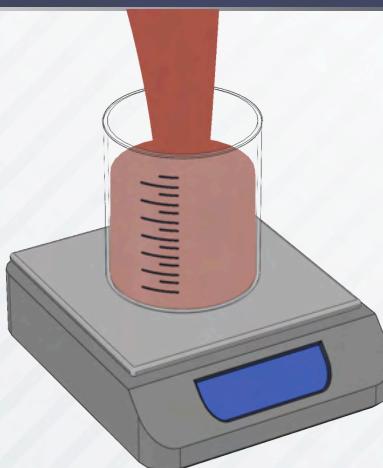
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9



10



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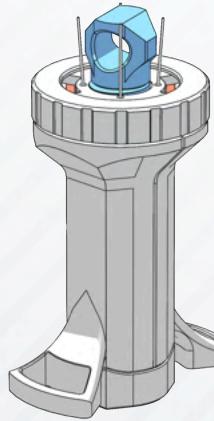
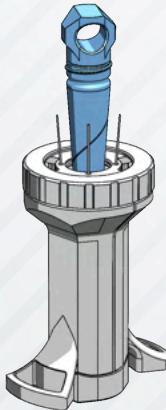
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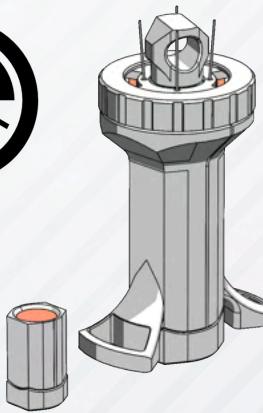
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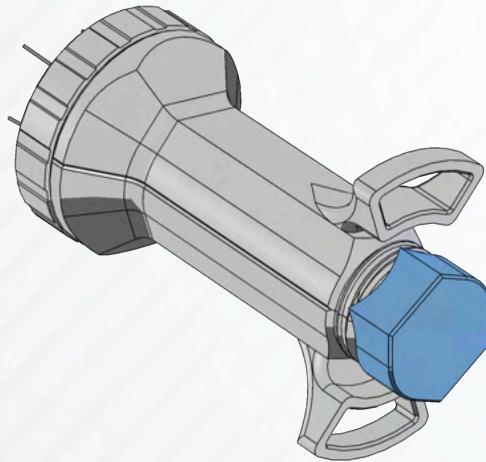
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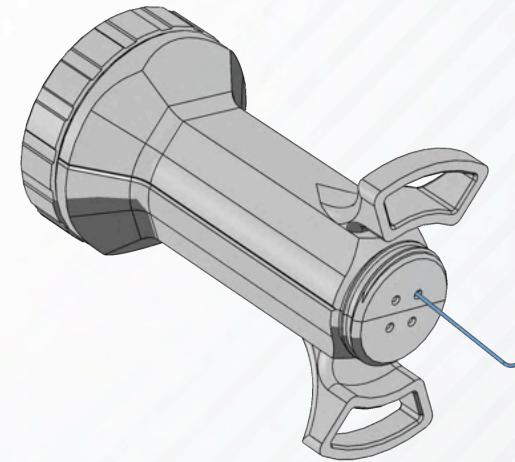
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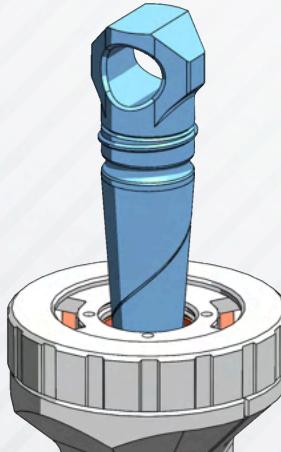
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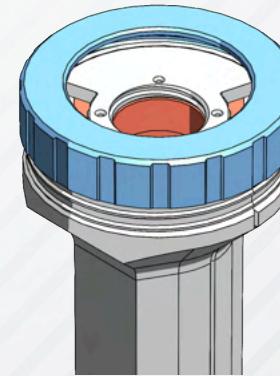
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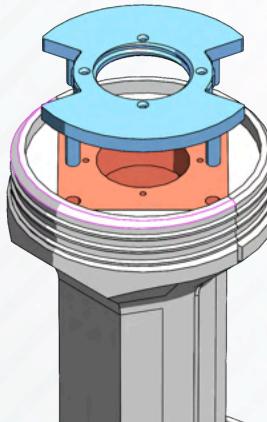
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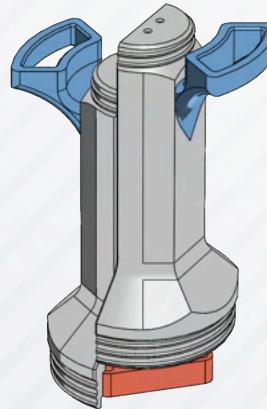
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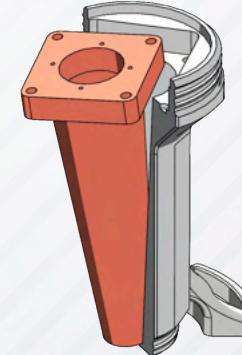
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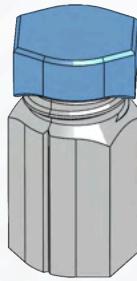
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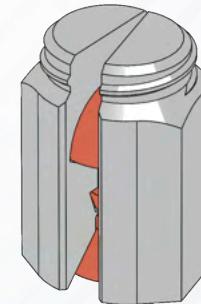
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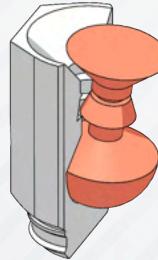
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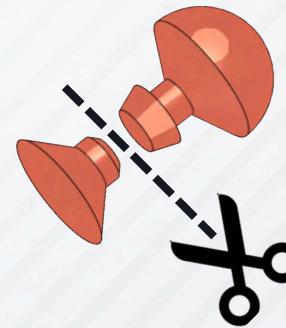
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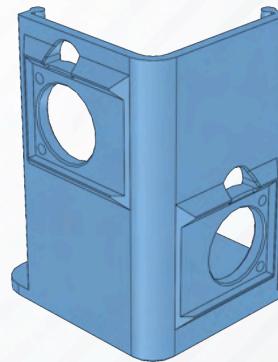


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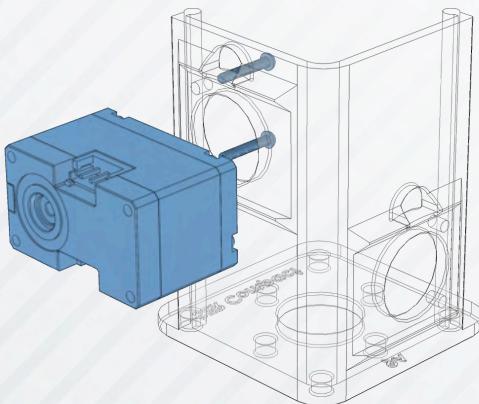


## PART 2: SERVO MODULE

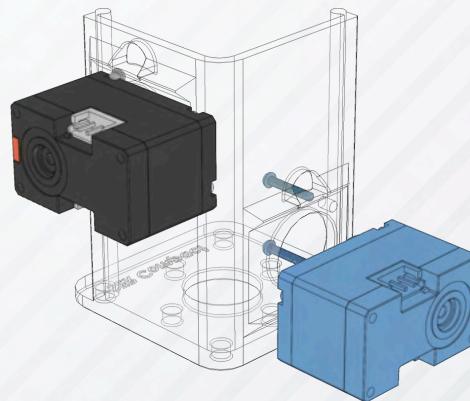
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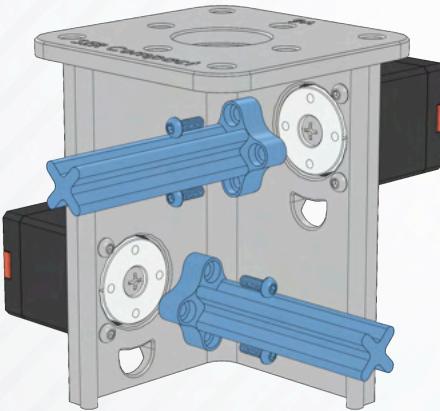
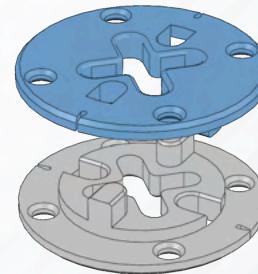
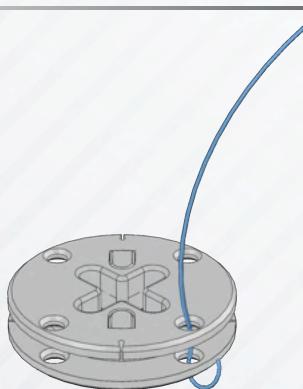


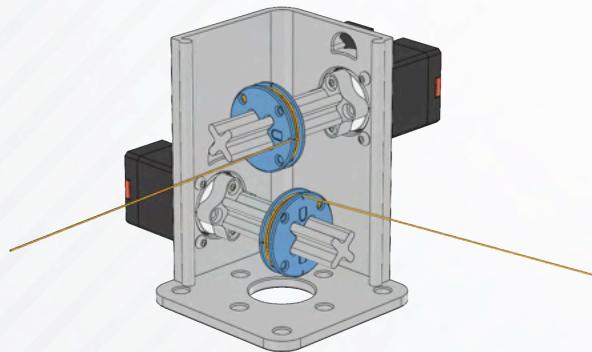
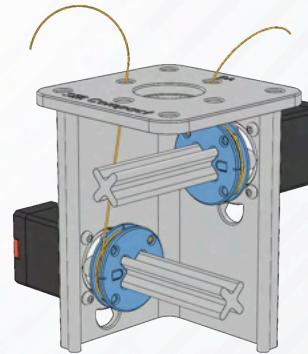
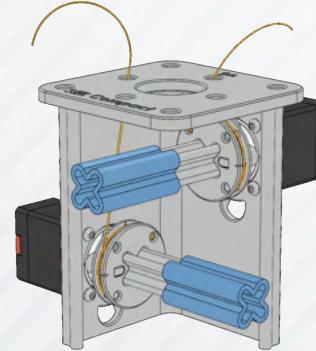
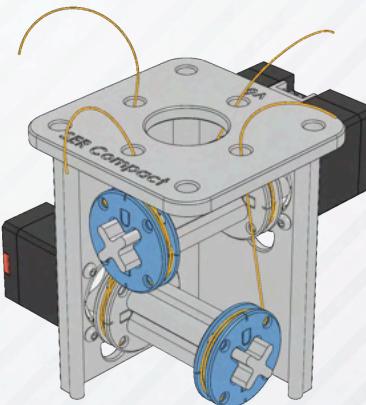
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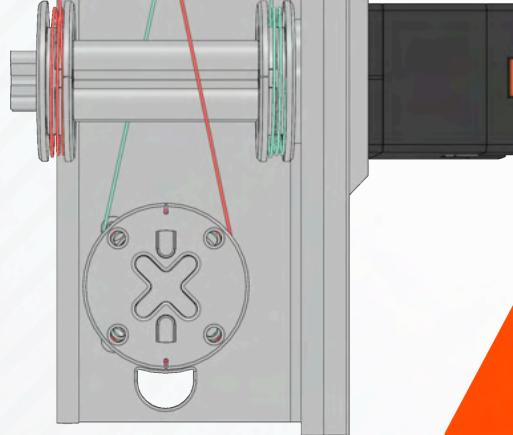
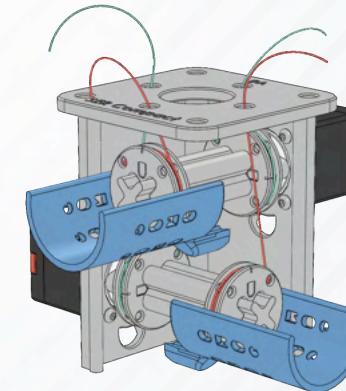
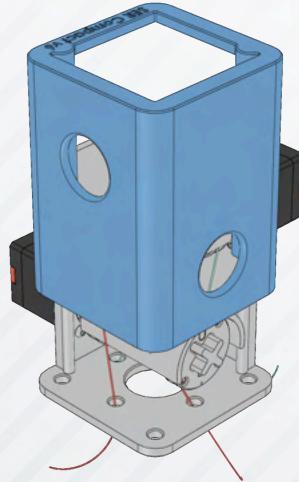
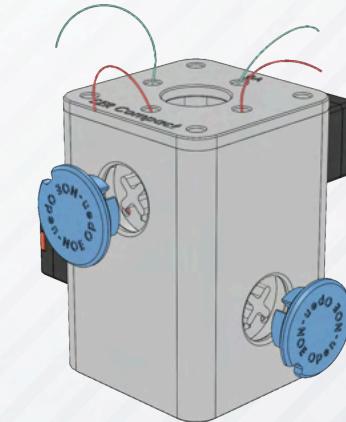


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**8****9****10****11****12**

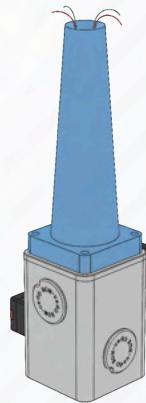
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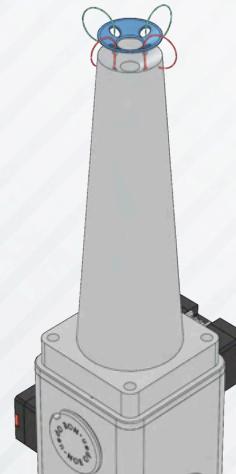
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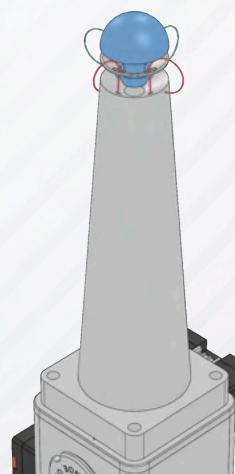
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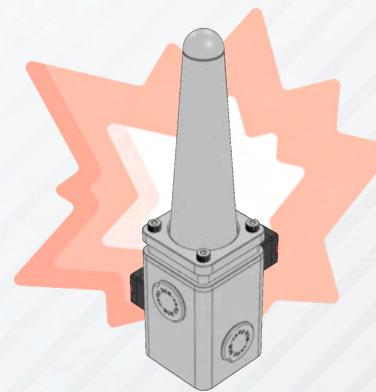
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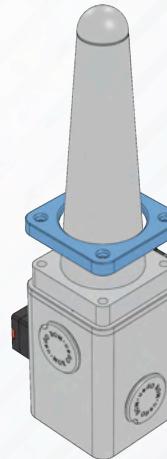
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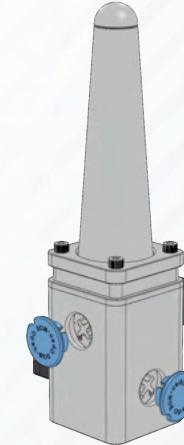
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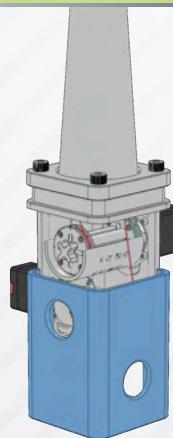
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## PART 3: TENSIONING

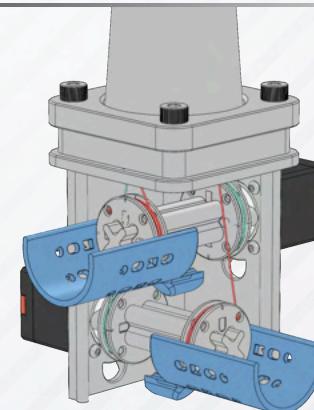
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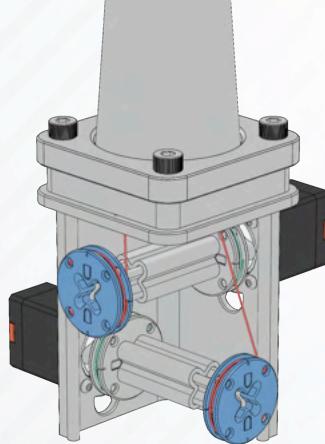
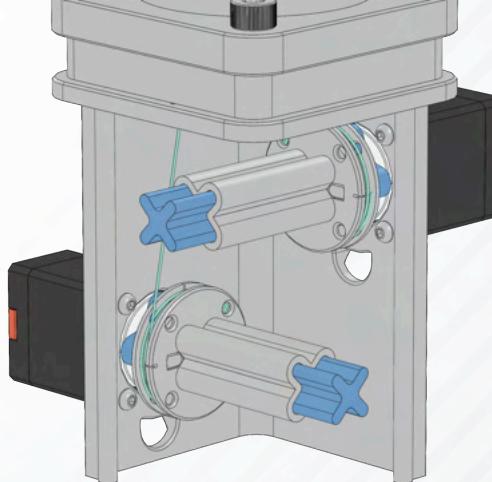
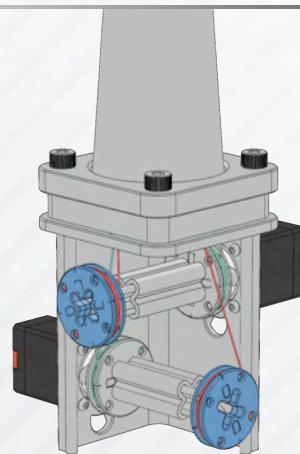
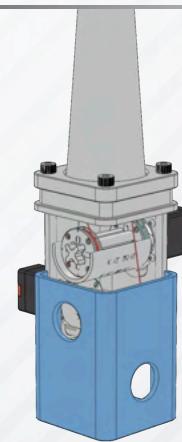


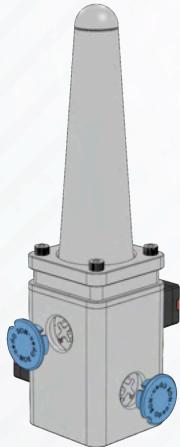
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3



**4****5****6****7**

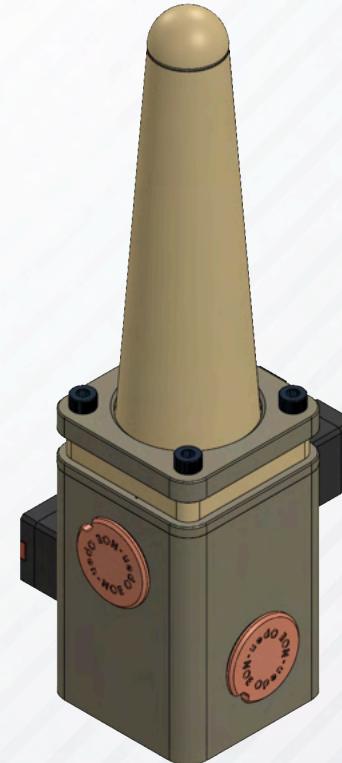


**Finger Module Version:** 1.0.0

**Instruction Booklet Version:** 1.1.0

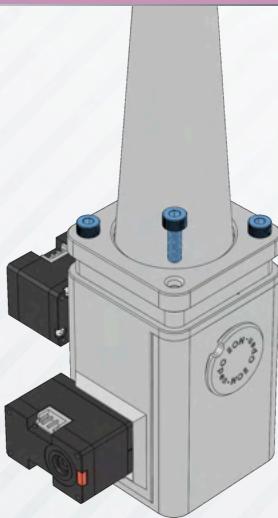
**Update Notes:** - Added parts list

*Designed by Momentum Lab at Carnegie Mellon Robotics Institute*

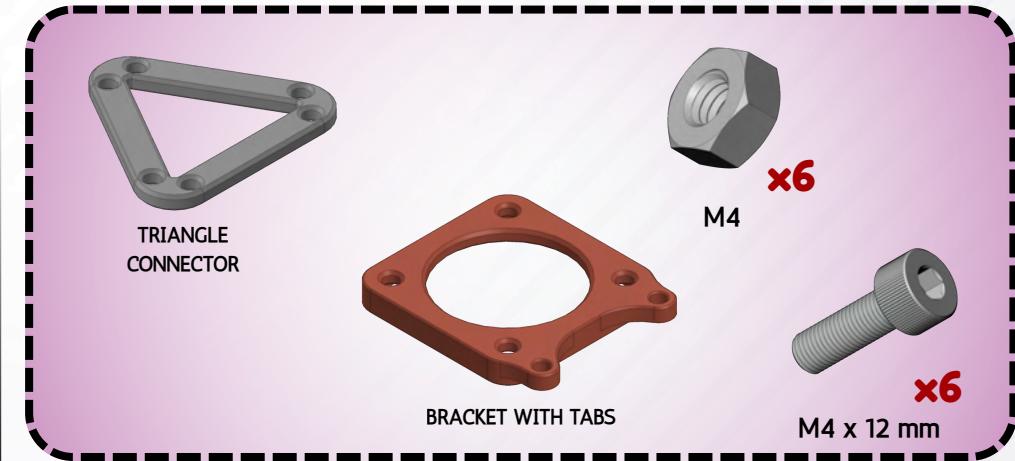
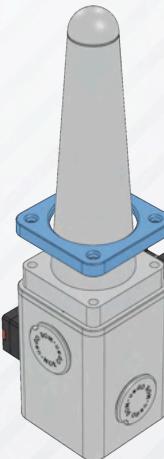


## PART 4: JOINING MULTIPLE FINGERS

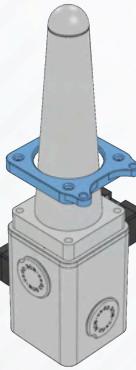
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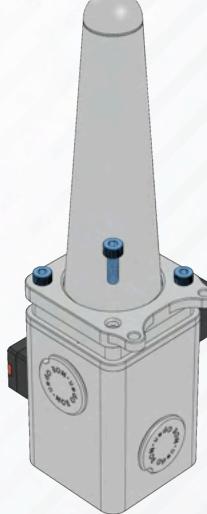
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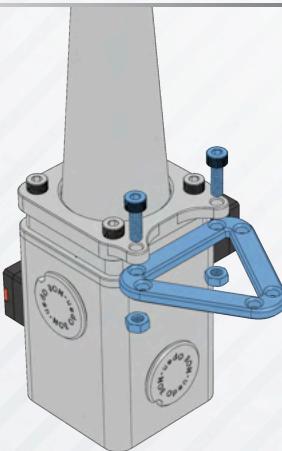
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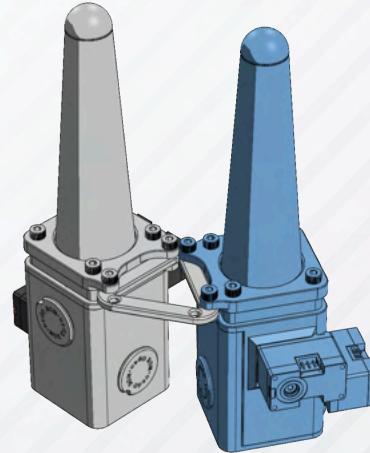
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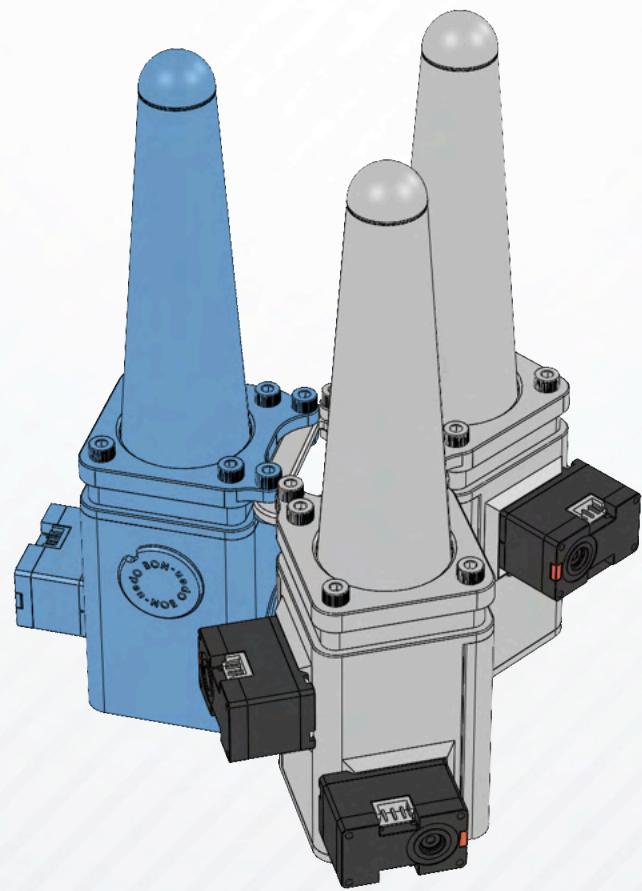


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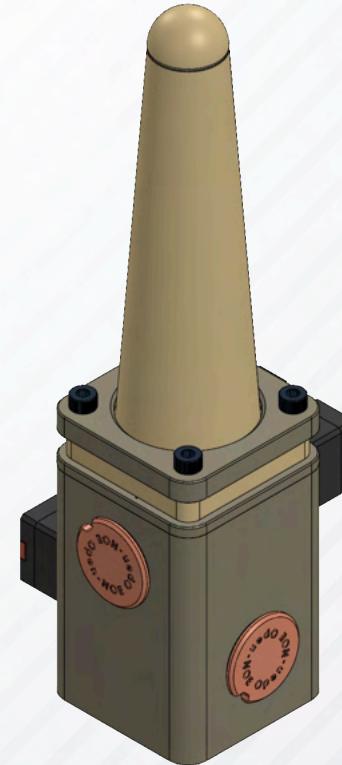


**Finger Module Version:** 1.0.0

**Instruction Booklet Version:** 1.2.0

**Update Notes:**

- Added section for joining multiple finger modules
- Added page numbers



*Designed by Momentum Lab at Carnegie Mellon Robotics Institute*