

# Open3DBench: 3D-IC Backend Implementation Flow

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github:



arXiv:



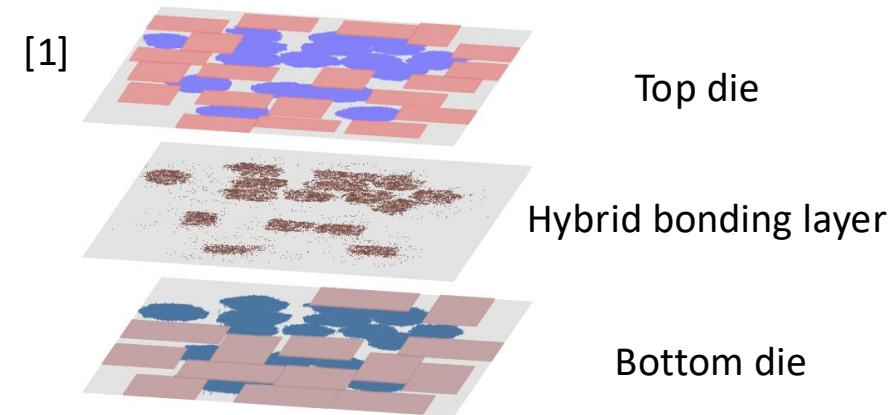
# Why Open3DBench?

- 3D-IC physical design research has attracted tremendous attention these years.
- We want to test our 3D algorithms in a standardized and reliable way.

Taking 3D placement as an example:

## Contest benchmarks:

- 3D Placement with D2D Vertical Connections @ ICCAD'22 Contest
- 3D Placement with Macros @ ICCAD'23 Contest



- Such contest benchmarks provide standardized comparison. But the host did not provide any implementation details (including valid PDK or design RTLs), narrowing the use of test cases.

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## **Workaround by 2D backend flow:**

- Macro-3D [1], Pin-3D [2], 3D Net-to-Pad Assignment [3] use Innovus to perform 3D backend flow.
- TA-3D [4] builds a 3D timing model using 2D tool OpenSTA.

- Commercial tools and commercial PDKs prevent replicable comparisons due to license issue.
- Building our own workaround flow may be time consuming and sometimes not reliable enough.

[1] Bamberg, Lennart, et al. "Macro-3D: A physical design methodology for face-to-face-stacked heterogeneous 3D ICs." DATE 2020.

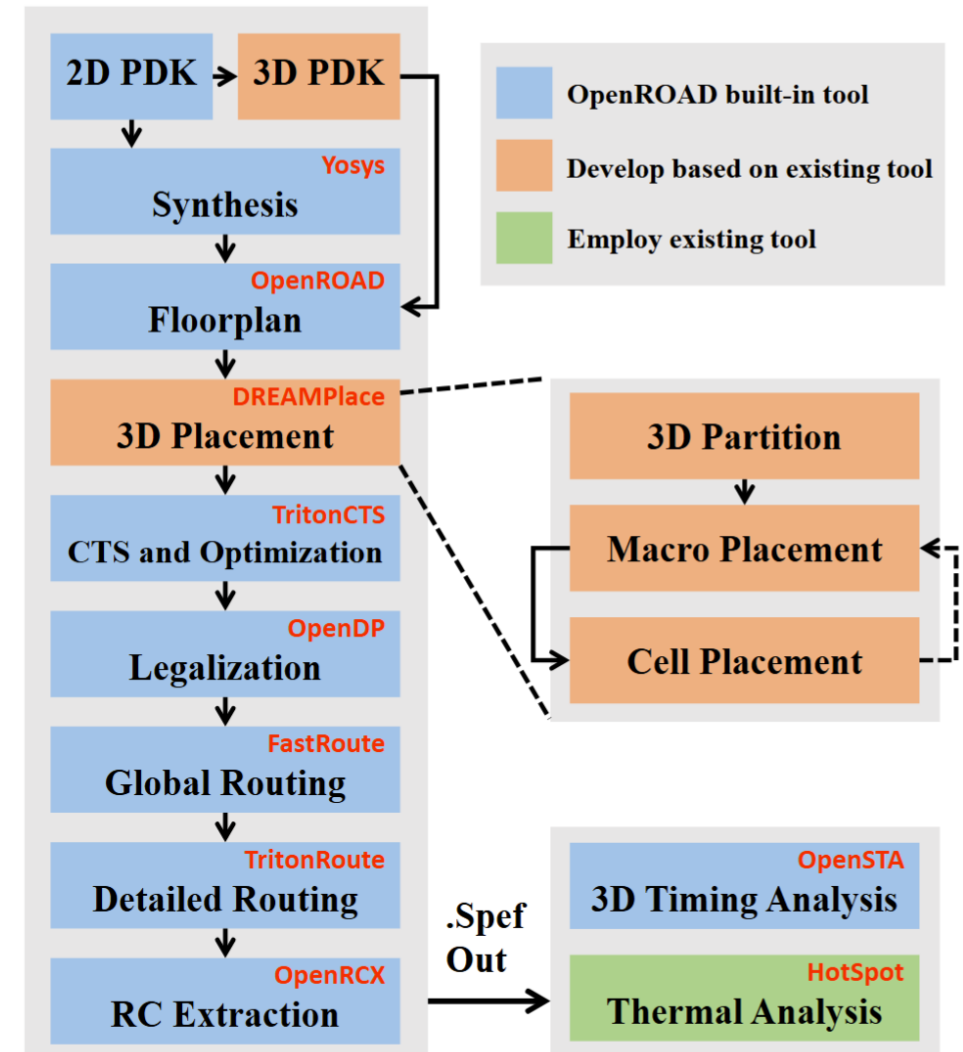
[2] Pentapati, Sai Surya Kiran, et al. "Pin-3D: A physical synthesis and post-layout optimization flow for heterogeneous monolithic 3D ICs." ICCAD 2020.

[3] Vanna-iampikul, Pruek, et al. "Placement-Aware 3D Net-to-Pad Assignment for Array-Style Hybrid Bonding 3D ICs. " ISPD 2025.

[4] Kim, Donggyu, et al. "TA3D: Timing-Aware 3D IC Partitioning and Placement by Optimizing the Critical Path." MLCAD 2024

# What is Open3DBench?

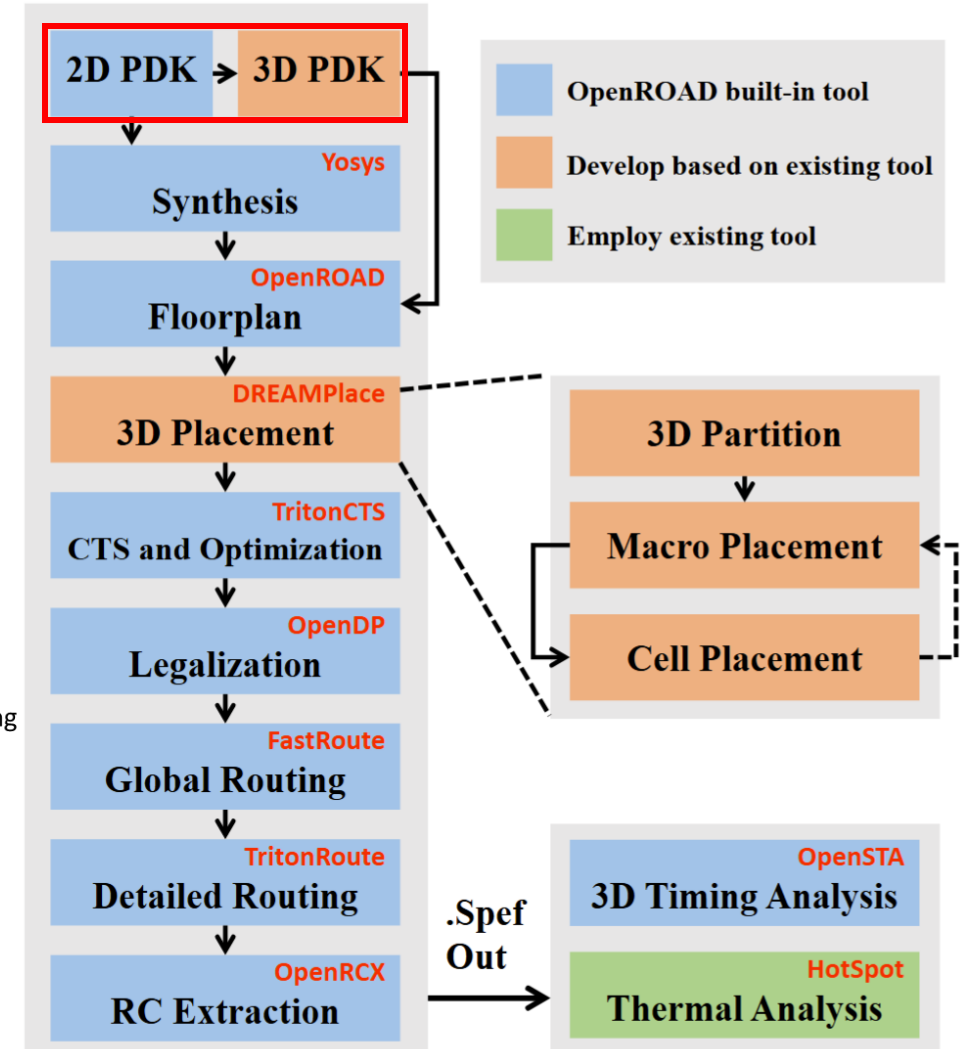
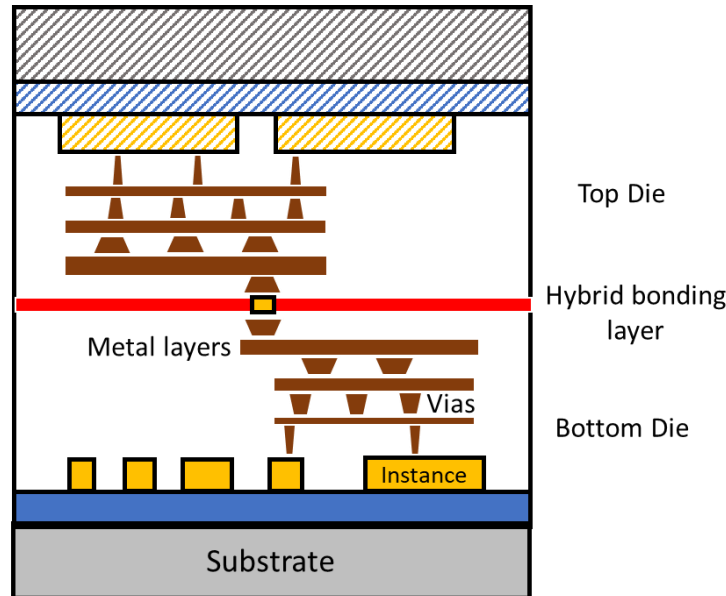
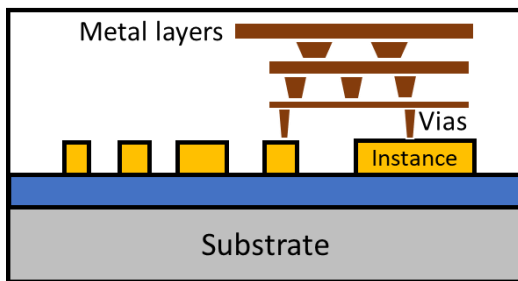
- **Main purpose:**  
Benchmarking everything in 3D backend flow



# What is Open3DBench?

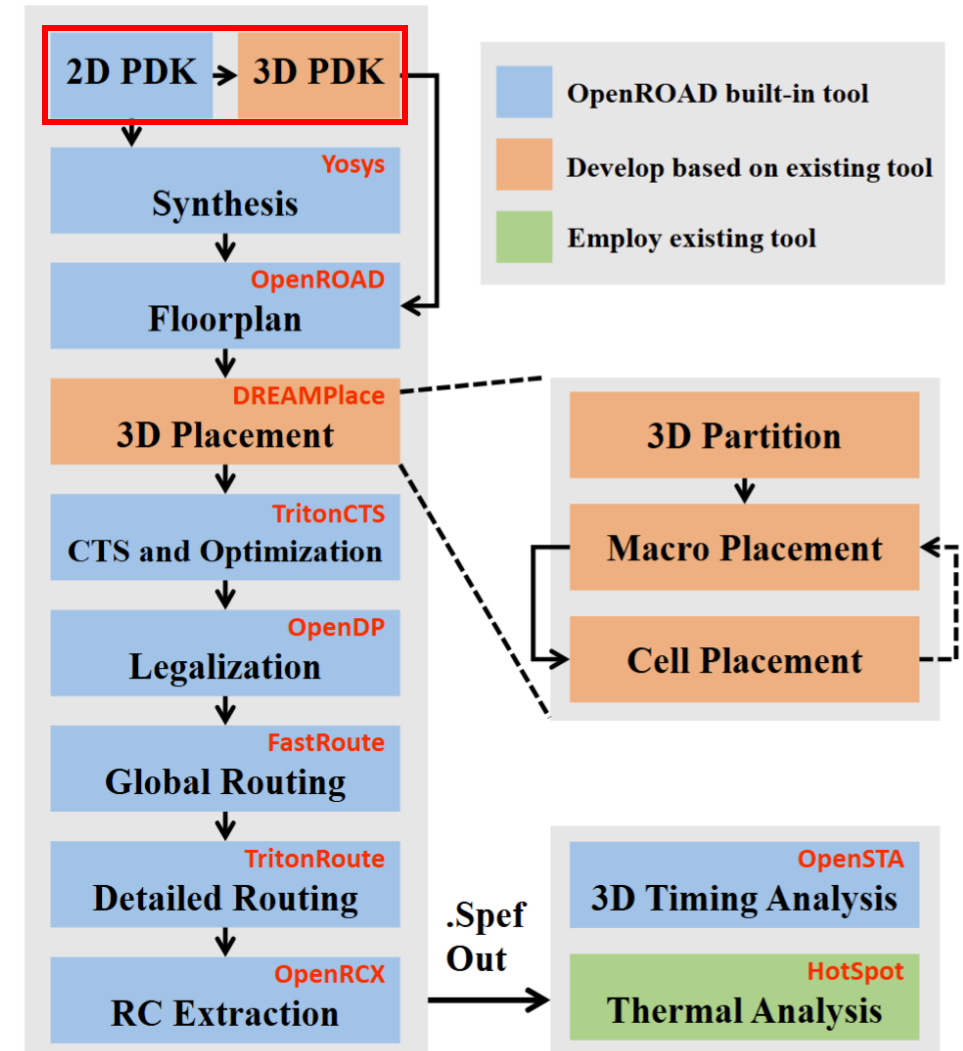
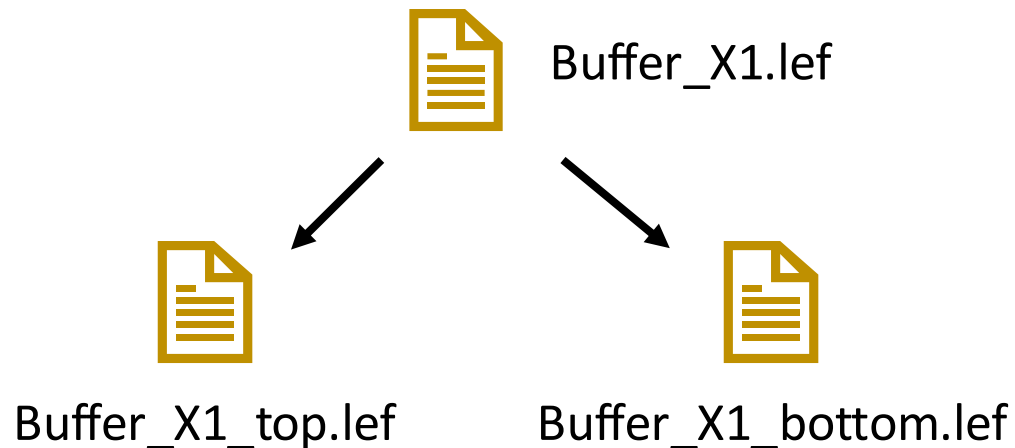
- **Key idea:**

Double the original 2D metal layers and implement the 3D design on one die (like Macro-3D [1]).



# What is Open3DBench?

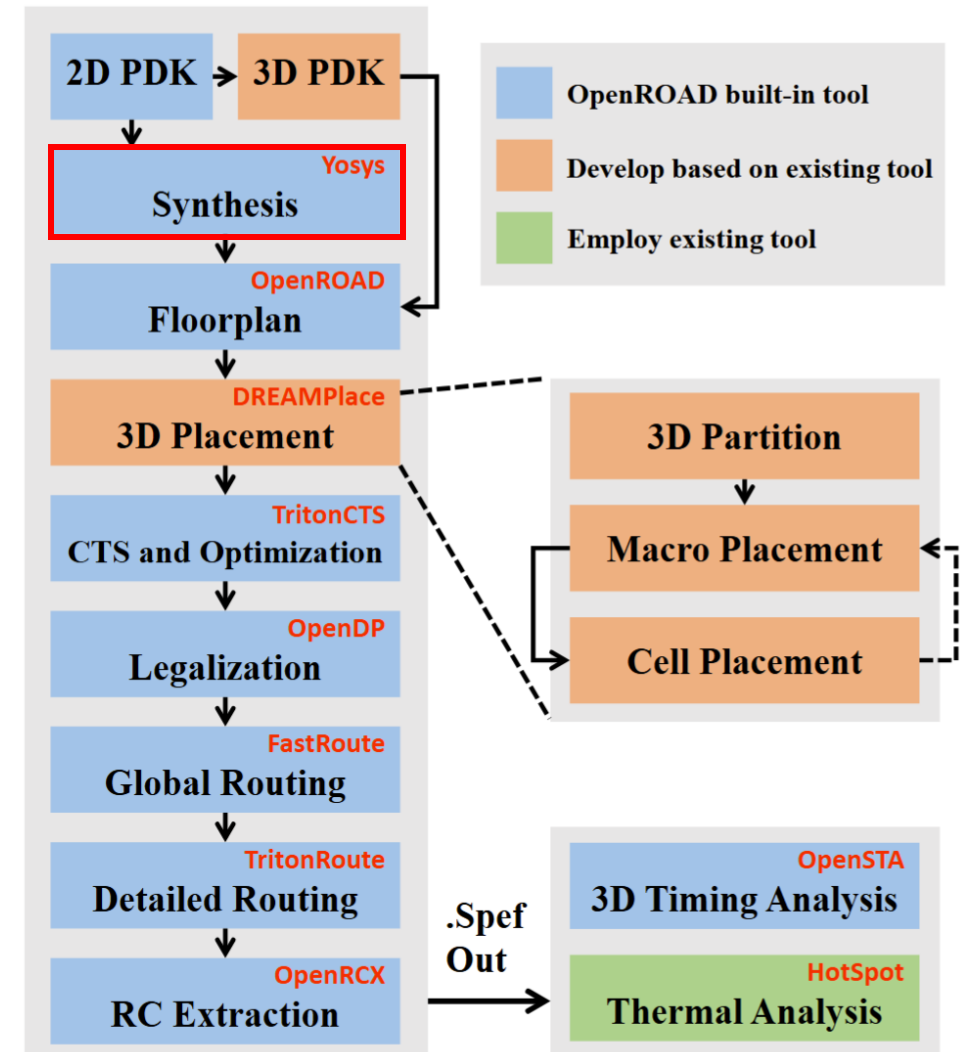
- **PDK preparation:** Modify NG45 to NG45\_3D
  - Duplicate the metal layer in *techlef*
  - Duplicate the instance *lef* and *lib* to distinguish top and bottom die



# What is Open3DBench?

- **Design preparation:**

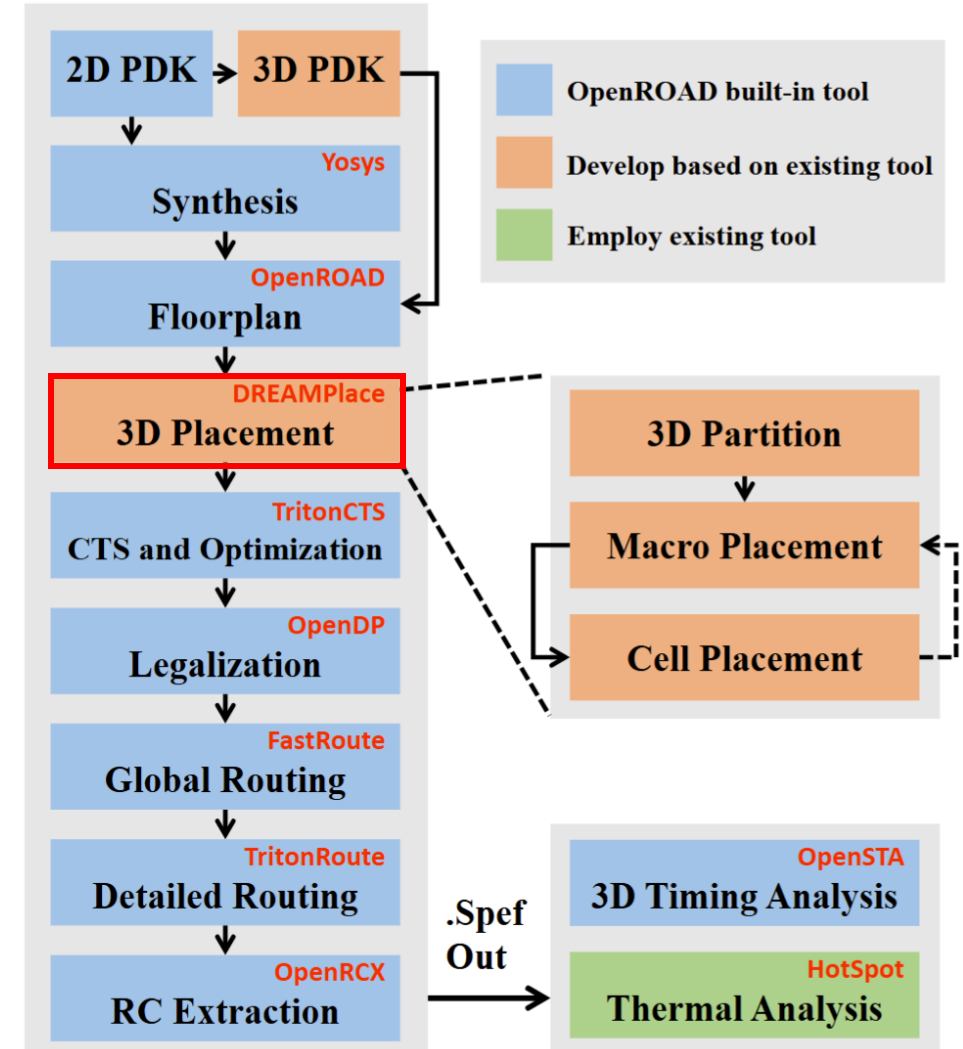
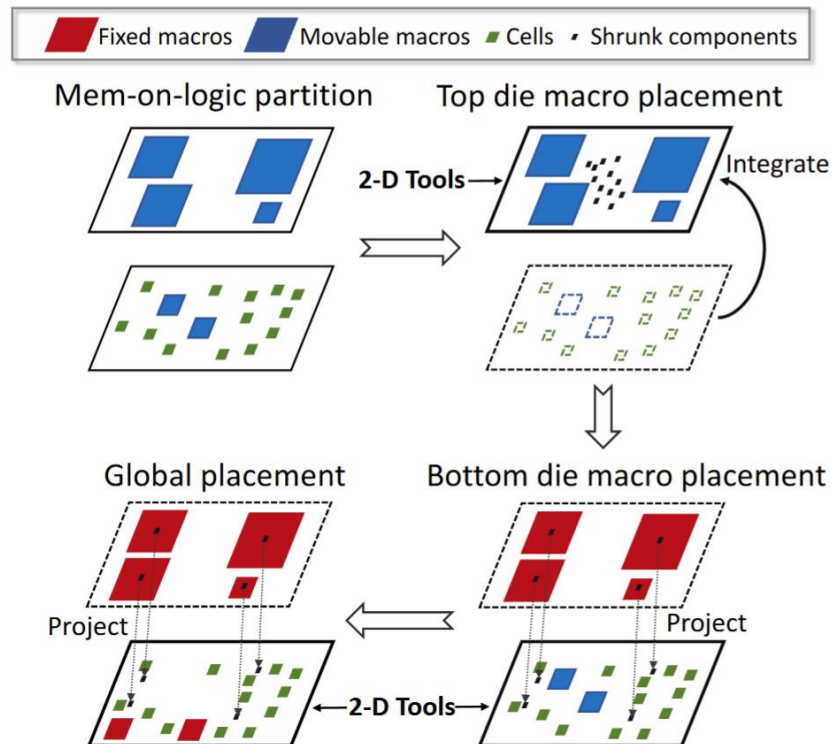
Any 2D design (RTL / netlist) supported by  
OpenROAD-flow-scripts



# What is Open3DBench?

- **3D Placement:**

Adopt 2D DREAMPlace [1] for workaround

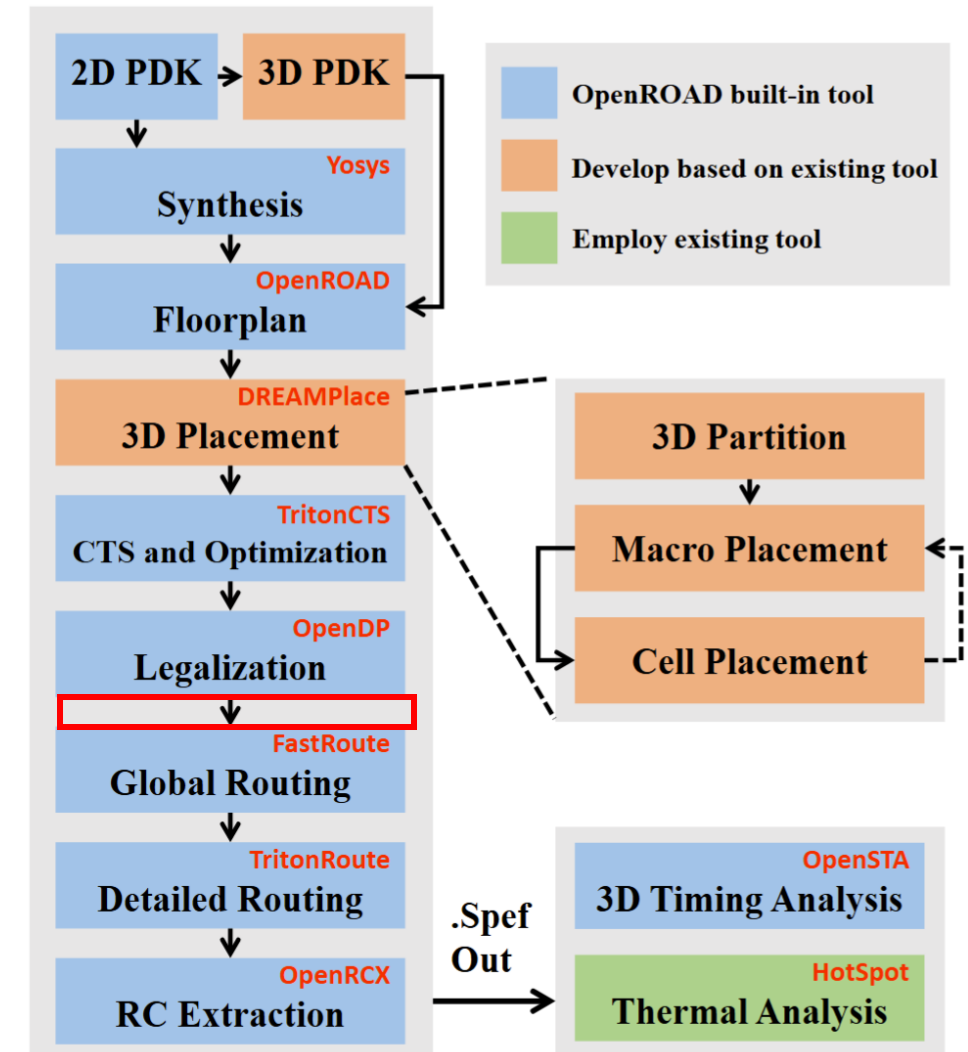
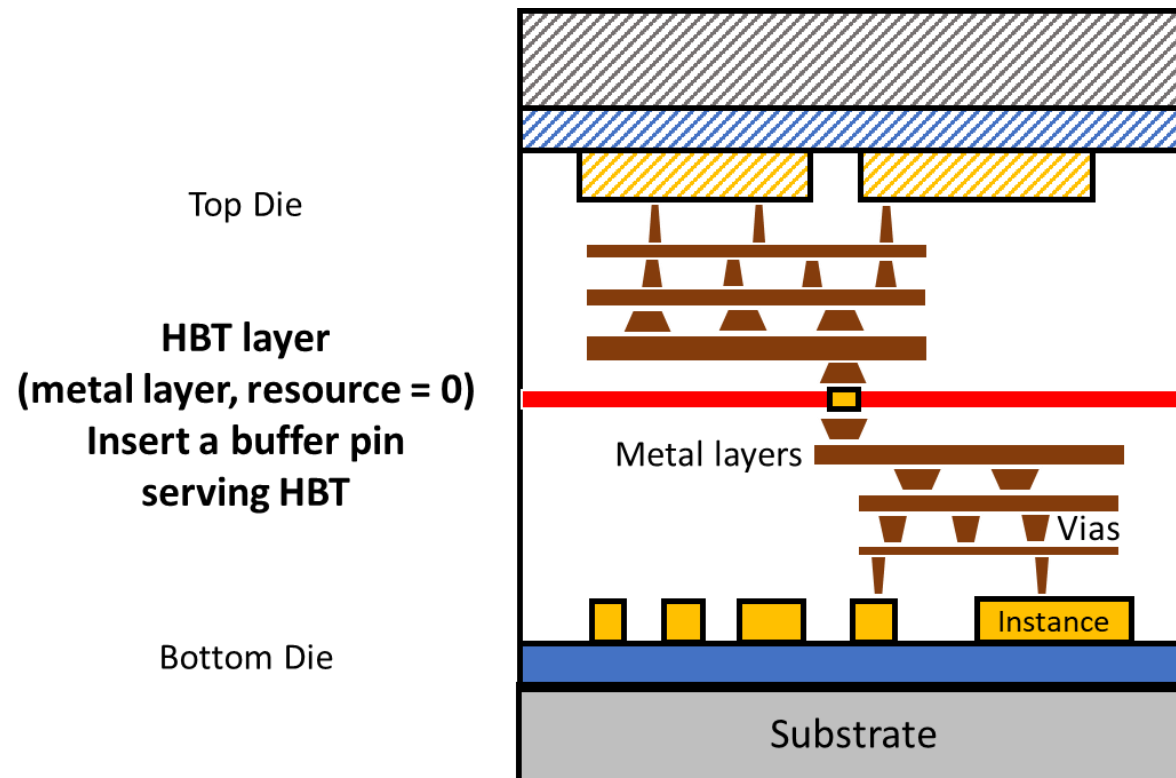


[1] Lin, Yibo, et al. "DREAMPlace: Deep learning toolkit-enabled GPU acceleration for modern VLSI placement." DAC 2019.



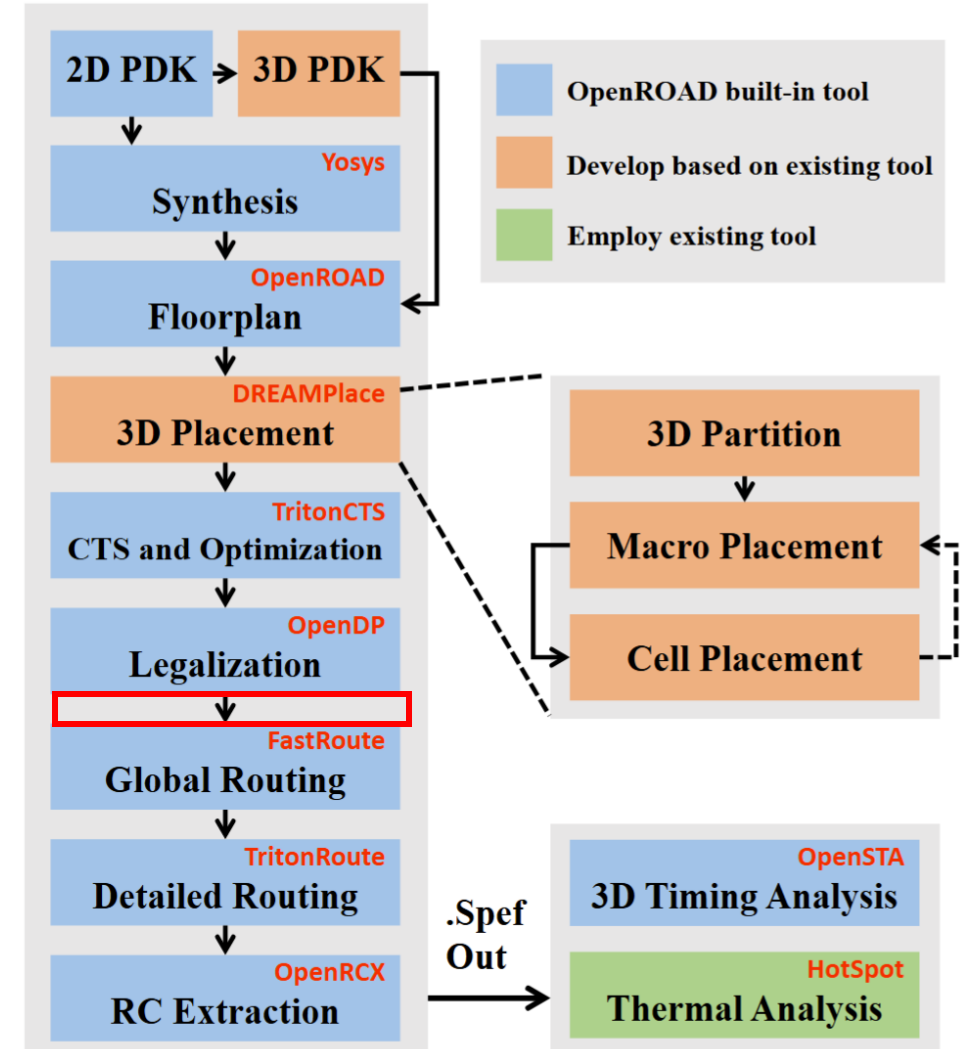
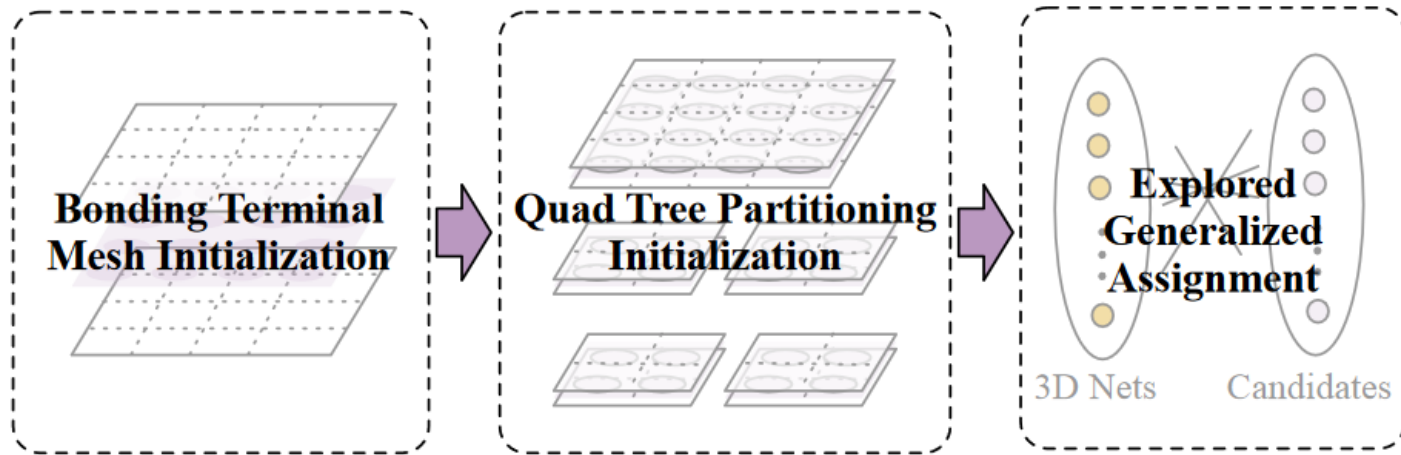
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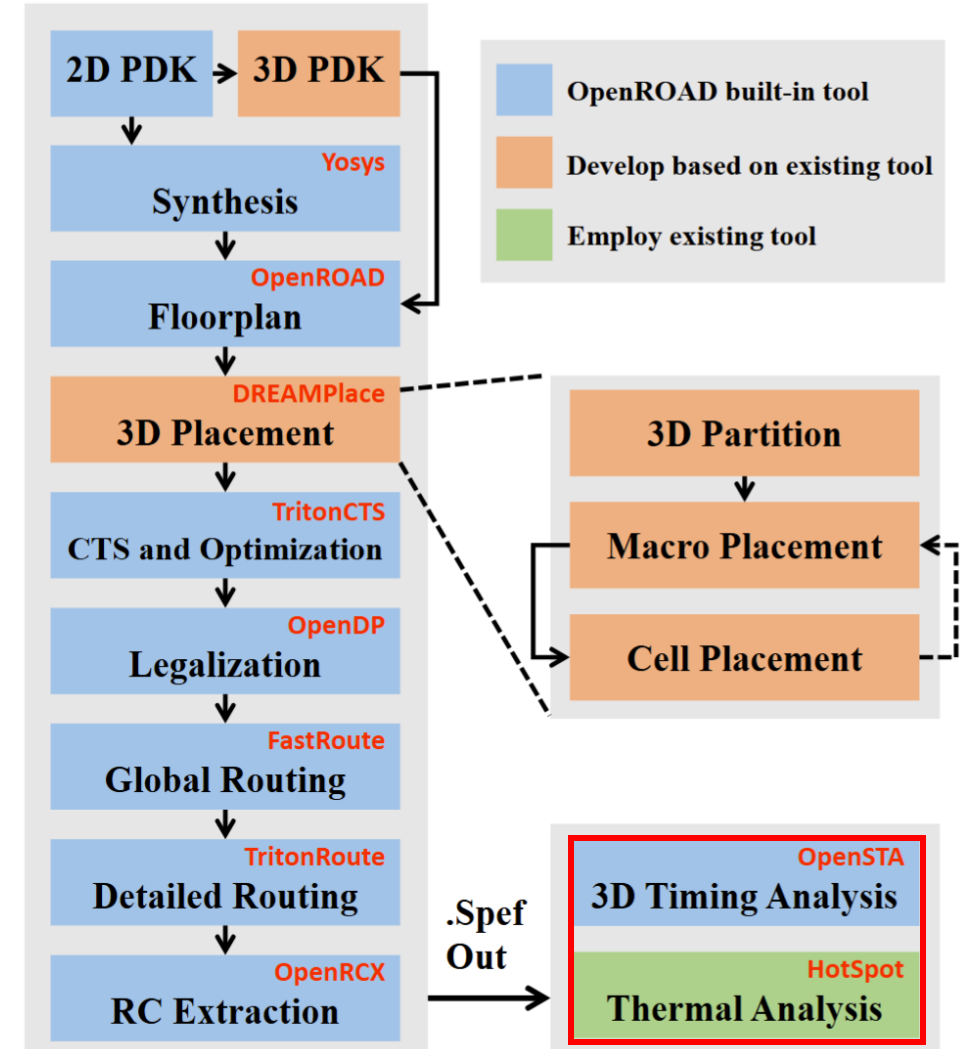


# What is Open3DBench?

- **PPA evaluation**

Since we establish the whole design on a 2D vision, and have defined the 3D connections properly, the original 2D OpenSTA [1] can serve 3D timing analysis.

HotSpot [2] supports 3D inherently.

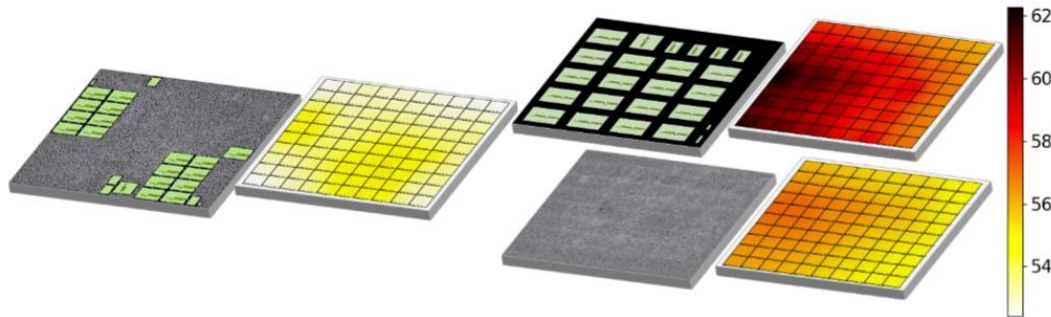


[1] <https://github.com/The-OpenROAD-Project/OpenSTA>

[2] <https://github.com/uvahotspot/HotSpot>

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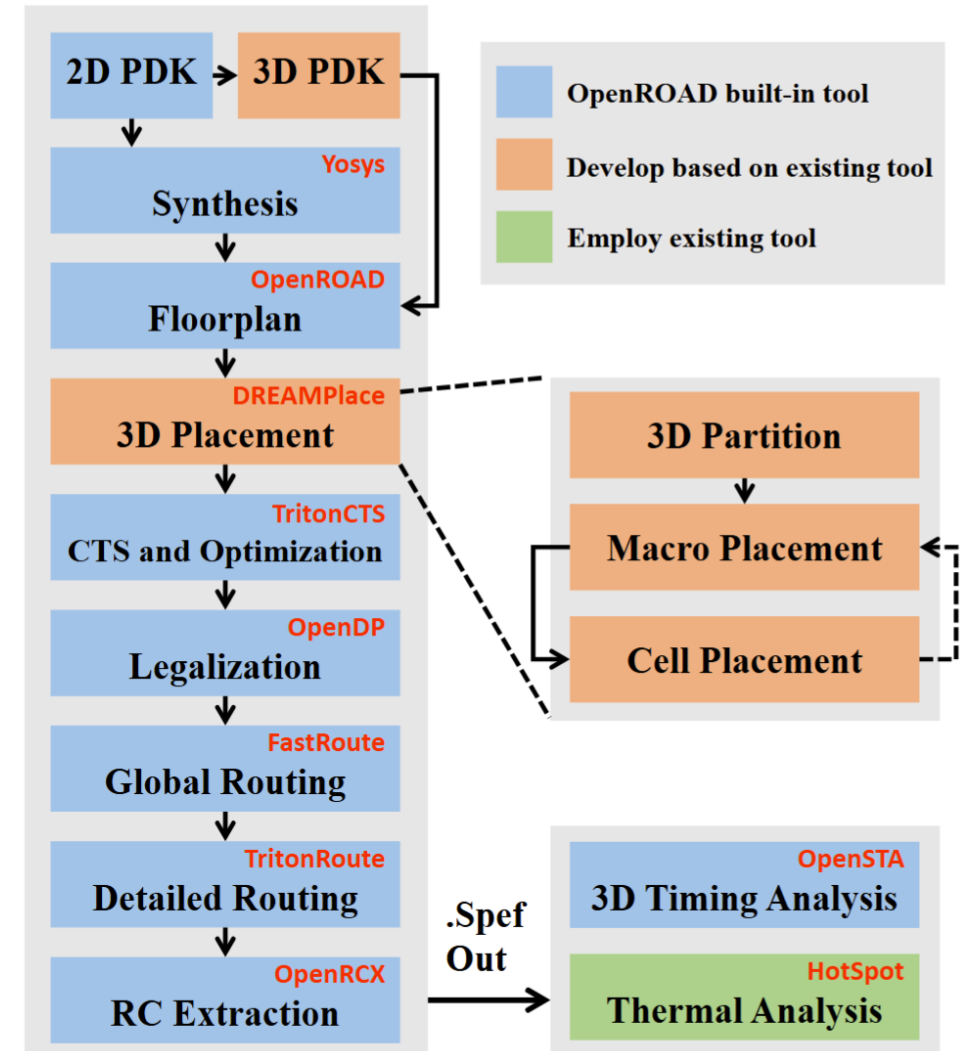
- Some evaluations



Designs	Methods	Area (mm <sup>2</sup> )	rWL (m)	Overflow (#)	WNS (ns)	TNS (ns)	Power (W)	$T_{max}$ (°C)	Runtime (s)
arianel33	Hier-RTLMP-2D	2.25	8.20	132	-2.18	-5766.41	0.393	58.84	3667
	DREAMPlace-2D	2.25	7.18	112	-1.69	-4098.04	0.389	58.69	1556
	Open3D-Tiling	1.00	6.21	0	-1.40	-3049.41	<b>0.360</b>	58.35	1743
	Open3D-DMP	1.00	<b>5.59</b>	0	<b>-1.34</b>	<b>-2648.76</b>	<b>0.360</b>	58.21	1739
arianel36	Hier-RTLMP-2D	2.25	8.63	127	-2.51	-7072.67	0.514	63.40	1779
	DREAMPlace-2D	2.25	7.80	148	-2.71	-7561.23	0.508	61.14	1720
	Open3D-Tiling	1.00	6.32	0	<b>-2.38</b>	<b>-6125.24</b>	<b>0.471</b>	60.93	1791
	Open3D-DMP	1.00	<b>6.05</b>	0	-2.45	-6603.91	<b>0.471</b>	62.27	1870
black_parrot	Hier-RTLMP-2D	1.76	12.41	68	-6.96	-6289.17	0.398	55.14	1819
	DREAMPlace-2D	1.76	12.23	334	-6.57	-5268.85	0.399	55.26	1728
	Open3D-Tiling	0.81	8.08	0	-5.76	<b>-2251.30</b>	0.376	62.29	1895
	Open3D-DMP	0.81	<b>7.79</b>	0	<b>-5.67</b>	-4067.11	<b>0.374</b>	60.97	1920
bp_be	Hier-RTLMP-2D	0.56	3.00	30	-1.88	-523.27	0.152	52.63	1063
	DREAMPlace-2D	0.56	2.89	36	-1.30	-246.99	0.153	53.08	916
	Open3D-Tiling	0.30	<b>2.40</b>	0	-1.21	-188.86	<b>0.144</b>	61.17	998
	Open3D-DMP	0.30	2.42	0	<b>-0.89</b>	<b>-108.89</b>	<b>0.144</b>	59.11	1053
bp_fe	Hier-RTLMP-2D	0.48	1.81	6	-1.40	-942.36	0.302	64.09	449
	DREAMPlace-2D	0.48	1.73	30	-1.51	-978.59	0.305	63.62	239
	Open3D-Tiling	0.24	1.38	0	-1.53	<b>-729.42</b>	0.284	87.33	398
	Open3D-DMP	0.24	<b>1.30</b>	0	<b>-1.37</b>	-814.64	<b>0.283</b>	82.32	388
bp_multi	Hier-RTLMP-2D	1.21	6.20	36	-7.97	-12072.10	1.143	86.18	868
	DREAMPlace-2D	1.21	5.63	9	-8.30	-10946.20	1.126	85.50	760
	Open3D-Tiling	0.64	4.06	0	<b>-7.01</b>	<b>-9246.70</b>	1.062	112.09	883
	Open3D-DMP	0.64	<b>4.03</b>	0	-8.03	-9812.57	<b>1.050</b>	98.09	935
bp_quad	Hier-RTLMP-2D	12.96	46.63	3429	-3.66	-39020.00	<b>1.822</b>	66.05	8010
	DREAMPlace-2D	12.96	41.99	3968	-2.05	-31231.90	1.848	68.17	6336
	Open3D-Tiling	6.25	50.19	0	-2.62	-31124.70	1.840	69.78	7973
	Open3D-DMP	6.25	<b>40.39</b>	0	<b>-1.83</b>	<b>-26966.20</b>	1.832	66.96	7981
swerv_wrapper	Hier-RTLMP-2D	1.10	5.62	14428	-2.14	-1975.79	0.250	54.86	1175
	DREAMPlace-2D	1.10	5.54	9540	-1.86	-1429.90	0.254	53.48	1092
	Open3D-Tiling	0.56	3.63	0	-1.26	-972.80	<b>0.232</b>	62.17	2085
	Open3D-DMP	0.56	<b>3.46</b>	0	<b>-1.23</b>	<b>-958.01</b>	0.234	60.49	1744
3D improvements over 2D†		51.19%↑	24.06%↑	100%↑	16.24%↑	30.84%↑	5.72%↑	-10.04%↓	-24.82%↓
3D-DMP improvements over 3D-Tiling		Equal	5.96%↑	Equal	7.22%↑	-4.49%↓	1.98%↑	3.56%↑	0.23%↑

# Limitations

- Heterogeneous
- TSV consideration
- 3D power distribution network
- 3D buffering & sizing
- ...



# Thank you!

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github:



arXiv:

