

C code Optimization

<Training Topic /Lesson Name>



Lesson Objectives

- *Code optimization overview*
- *Classification of optimization types*
- *Optimization methods and terms*
- *Document analysis tools*
- *Common algorithms*

Section 1

Overview

Overview Agenda

- *Code optimization overview*
- *Classification of code optimization*

- *Code optimization involves the application of rules and algorithms to program code with the goal of making it faster, smaller, more efficient, and so on*
- *Often these types of optimizations conflict with each other: for instance, faster code usually ends up larger, not smaller*
- *Optimizations can be performed at several levels (e.g. source code, intermediate representations), and by various parties, such as the developer or the compiler/optimizer*

- **Local optimizations** - *Performed in a part of one procedure.*
 - ✓ *Common sub-expression elimination (e.g. those occurring when translating array indices to memory addresses.*
 - ✓ *Using registers for temporary results, and if possible for variables.*
 - ✓ *Replacing multiplication and division by shift and add operations.*
- **Global optimizations** - *Performed with the help of data flow analysis (see below) and split-lifetime analysis.*
 - ✓ *Code motion (hoisting) outside of loops*
 - ✓ *Value propagation*
 - ✓ *Strength reductions*
- **Inter-procedural optimizations**
 - ✓ *Global optimization allows the compiler/optimizer to look at the overall program and determine how best to apply the desired optimization level. Peep-hole provides local optimizations, which do not account for patterns or conditions in the program as a whole. Local optimizations may include instruction substitutions.*

Section 2

Optimization methods

- *Common sub-expression elimination*
- *Constant propagation*
- *Copy propagation*
- *Dead code elimination*
- *Global register allocation*
- *Inline calls*
- *Instruction scheduling*
- *Lifetime analysis*
- ...

- If the value resulting from the calculation of a sub-expression is used multiple times, perform the calculation once and substitute the result for each individual calculation***

Normal	Optimization
<pre>float x = a*min/max + sx; float y = a*min/max + sy;</pre>	<pre>float temp = a*min/max; float x = temp + sx; float y = temp + sy;</pre>

- ***Replace variables that rely on an unchanging value with the value itself***

Normal	Optimization
<pre>x2 = 5; x3 = x1 + x2;</pre>	<pre>x3 = x1 + 5;</pre>

- ***Replace multiple variables that use the same calculated value with one variable***

Normal	Optimization
$x2 = x1;$	$x3 = x1 + x1;$
$x3 = x1 + x2;$	$x2 = 3;$
$x2 = 3;$	

- **Dead code elimination**

- ✓ *Code that never gets executed can be removed from the object file to reduce stored size and runtime footprint*

- **Global register allocation**

- ✓ *Variables that do not overlap in scope may be placed in registers, rather than remaining in RAM. Accessing values stored in registers is faster than accessing values in RAM*

- **Inline calls**

- ✓ *A function that is fairly small can have its machine instructions substituted at the point of each call to the function, instead of generating an actual call. This trades space (the size of the function code) for speed (no function call overhead).*

- **Instructions for a specific processor may be generated, resulting in more efficient code for that processor but possible compatibility or efficiency problems on other processors. This optimization may be better applied to embedded systems, where the CPU type is known at build time**

- **A register can be reused for multiple variables, as long as those variables do not overlap in scope**

- **Values that do not change during execution of a loop can be moved out of the loop, speeding up loop execution.**

Normal	Optimization
<pre>for (int i = 0; i < length; i++) x[i] += pi + cos(y);</pre>	<pre>double temp = pi + cos(y); for (int i = 0; i < length; i ++) x[i] += temp;</pre>

- **Statements within a loop that rely on sequential indices or accesses can be repeated more than once in the body of the loop. This results in checking the loop conditional less often.**

Normal	Optimization
<pre>double temp = pi + cos(y); for (int i = 0; i < length; i++) x[i] *= temp;</pre>	<pre>double temp = pi + cos(y); for (int i = 0; i < length; i += 2) { x[i] *= temp; x[i+1] *= temp;} }</pre>

- **Certain operations and their corresponding machine code instructions require more time to execute than simpler, possibly less efficient counterparts.**

Normal	Optimization
$x/4$	$x \gg 2$
$x*2$	$x \ll 1$

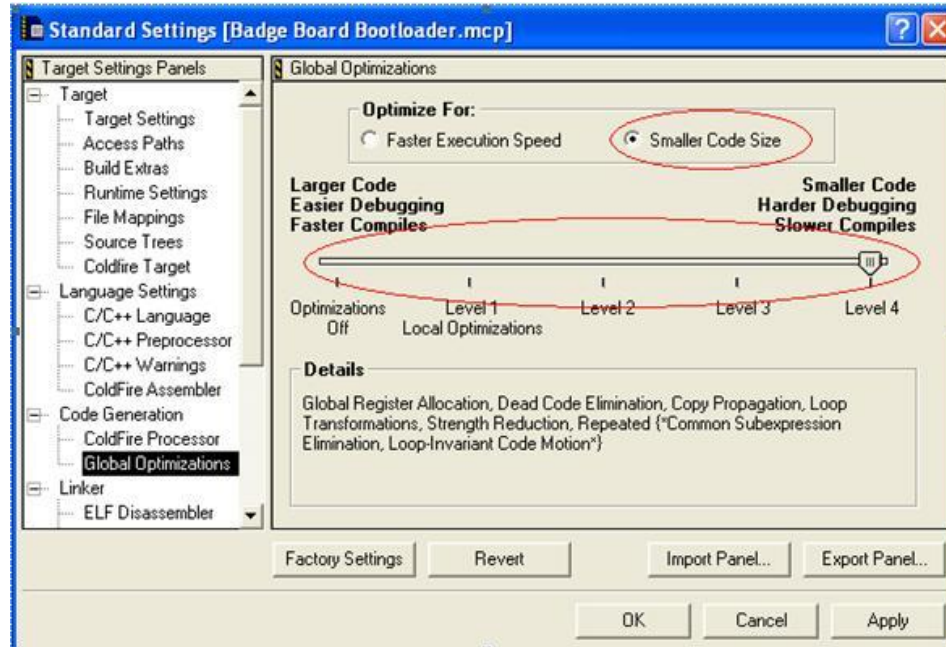
Section 3

Code size optimization and Speed optimization

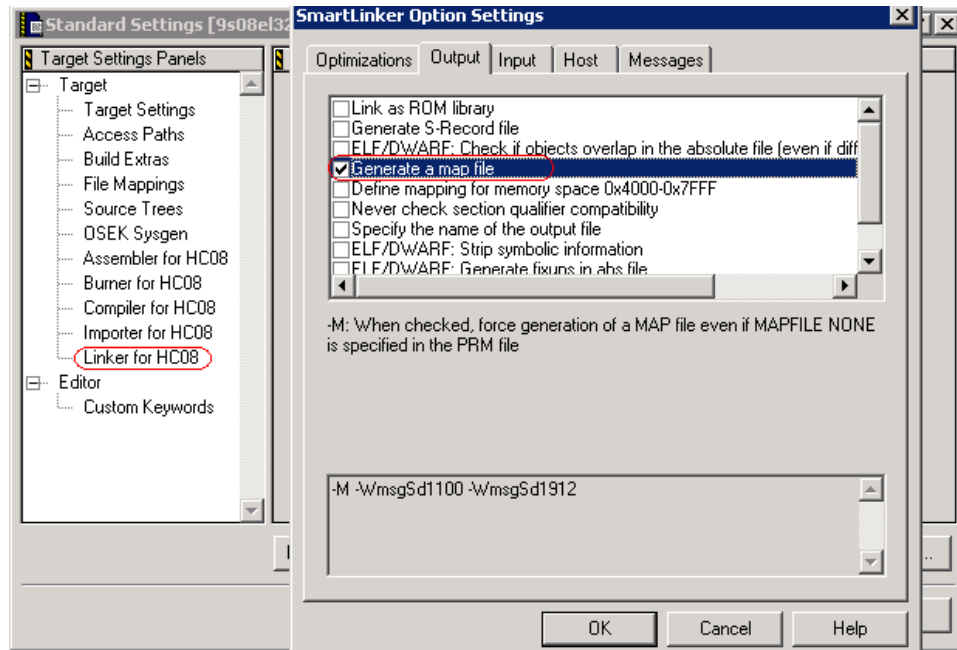
■ Step 1. Manual optimization

- ✓ **Dead code elimination;**
- ✓ **Lifetime analysis: A register can be reused for multiple variables, as long as those variables do not overlap in scope;**
- ✓ **Constant propagation: Replace variables that rely on an unchanging value with the value itself;**
- ✓ **Copy propagation: Replace multiple variables that use the same calculated value with one variable;**
- ✓ **Not use inline calls.**

■ Step 2. Using compiler options (tools)



- **Step 1. Analyze code distribution in memory using Linker MAP file**



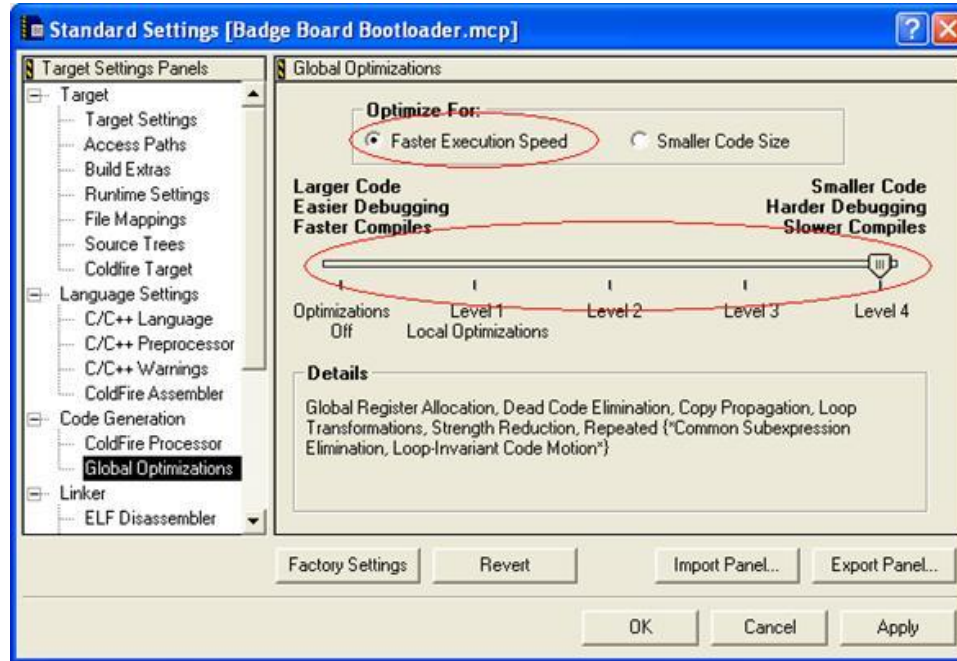
- **Step 2. Analyze the linker MAP file and identify the objects most memory consuming**

```
*****1
MODULE STATISTIC
Name                               Data    Code   Const
-----
Start08.c.o                        0        7        0
main.c.o                           5       113        0
mc9s08el32.c.o                     128        0        0
RTSHC08.C.o (ansiis.lib)           0       206        0
lin_cfg.c.o                        164        0       273
lin_common_api.c.o                 0       864        0
lin_common_proto.c.o               0      3405        0
lin_j2602_proto.c.o                0       438        0
lin_lin21_proto.c.o                0       639        0
lin_commonctl_api.c.o              0       624        0
lin.c.o                            0       279        0
lin_lld_slic.c.o                   4       124        0
slic_isr.c.o                       2       333        2
other                              64        16        8
```

▪ Step 1. Manual optimization

- ✓ Dead code elimination;
- ✓ Common sub-expression elimination;
- ✓ Constant propagation;
- ✓ Copy propagation: Replace multiple variables that use the same calculated value with one variable;
- ✓ Global register allocation;
- ✓ Inline calls;
- ✓ Instruction scheduling;
- ✓ Loop invariant expressions (code motion);
- ✓ Loop transformations;
- ✓ Loop unrolling;
- ✓ Strength reduction;
- ✓ Using a fast algorithm;
- ✓ Writing in assembly language

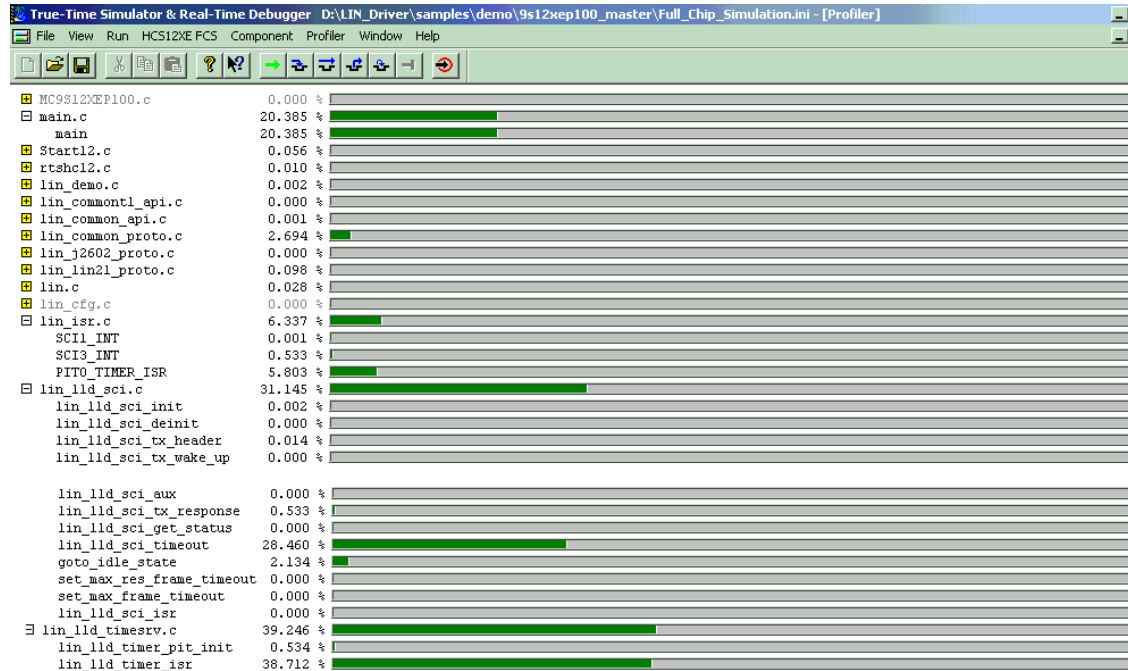
■ Step 2. Using compiler options (tools)



■ Step 1. Profile the code

- ✓ Profiling is the process of analyzing software to determine how much time, on average, an executable spends on a particular amount of code.
- ✓ While profiling can reveal a lot of useful information about your code. Profiling identifies bottlenecks -- areas of code that hold back the entire performance of the system. Optimization attempts to make those bottleneck faster.
- ✓ Most code loosely follows an 80/20 pattern of execution -- 80% of execution time is spent executing 20% of the code

■ Step 1. Profile the code (cont)



- **Searching and sorting**
 - ✓ **Binary search**
 - ✓ **Bubble sort**
 - ✓ **Selection sort**
 - ✓ **Insertion sort**
- **Strings**
 - ✓ **Brute-force algorithm**

Thank you

