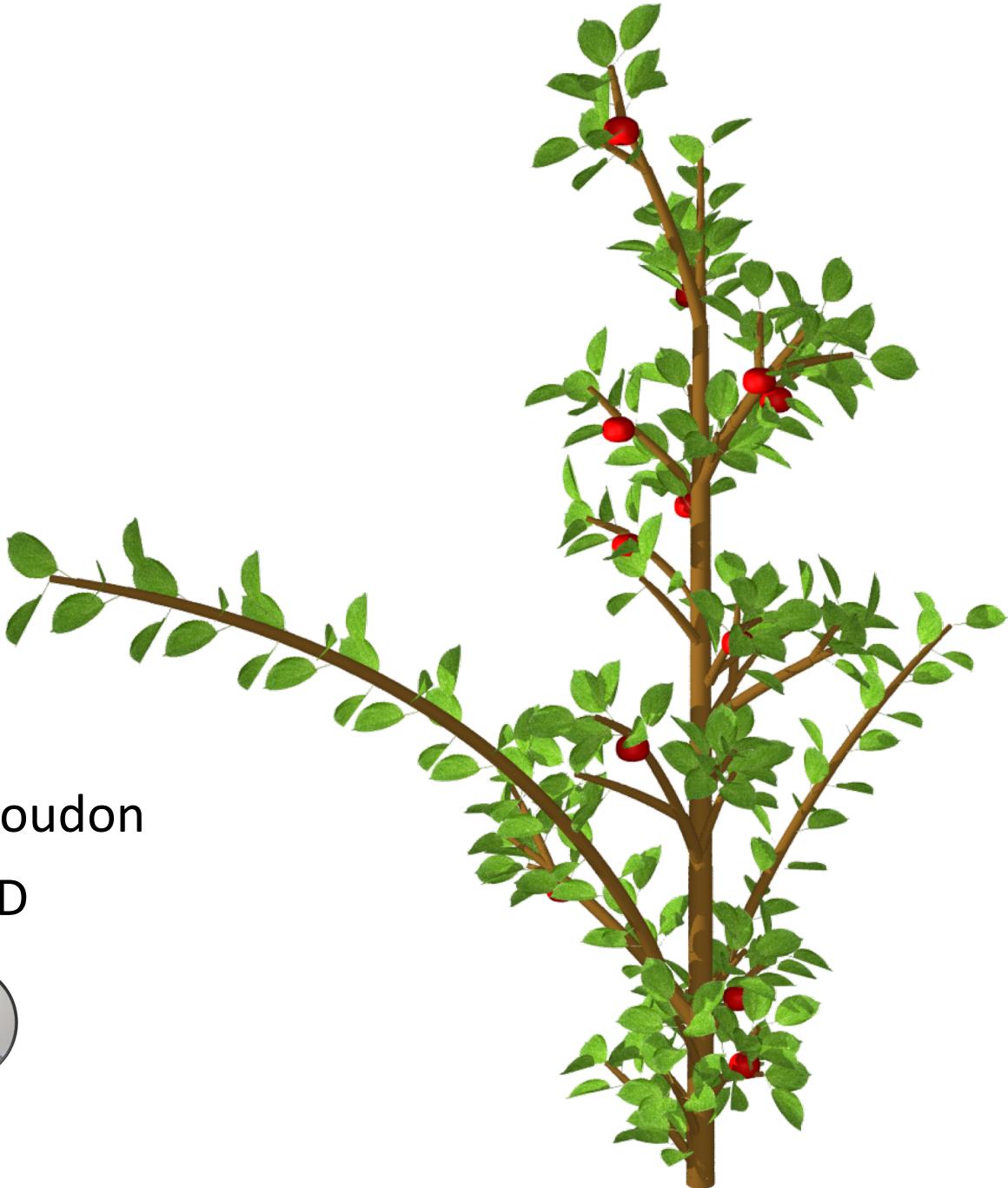


# L-systems

Application to plant modelling

Frédéric Boudon

CIRAD



# Prerequisite

- Use of the L-Py modelling framework

- Installation instructions :
  - [https://github.com/openalea-training/hbma312\\_training](https://github.com/openalea-training/hbma312_training)
  - Training material in folder lsystem
- Launching lpy in the conda console

```
conda activate training  
lpy
```

- Exercises in the notebook: L-systems.ipynb  
[https://github.com/openalea-training/hbma312\\_training/blob/master/lSystem/L-systems.ipynb](https://github.com/openalea-training/hbma312_training/blob/master/lSystem/L-systems.ipynb)

```
conda activate training  
jupyter notebook L-systems.ipynb
```

# Modeling dynamical systems

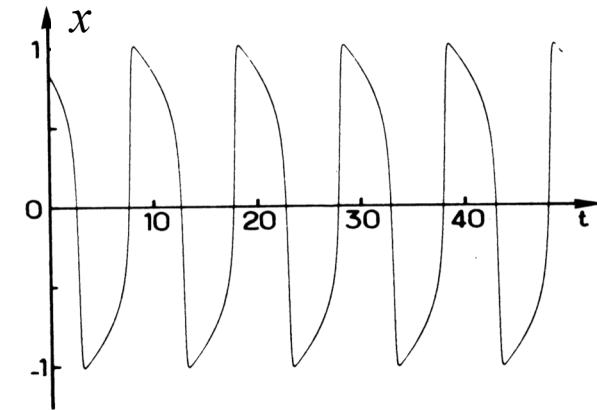
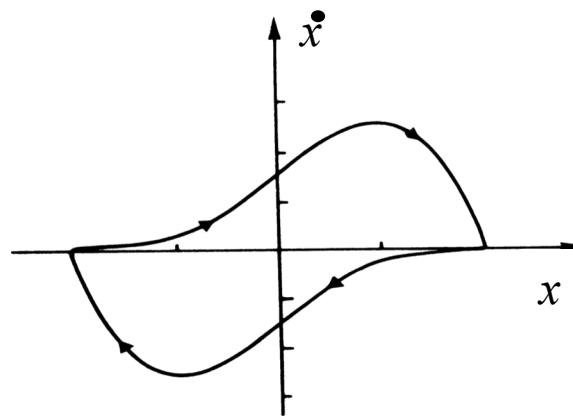
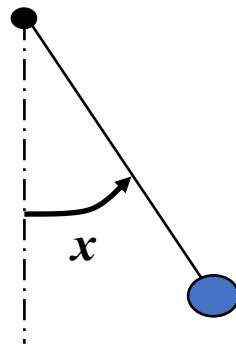
- Classical approach

$$f(x, \dot{x}, t) = 0$$

$$x \in \mathbf{R}^n$$

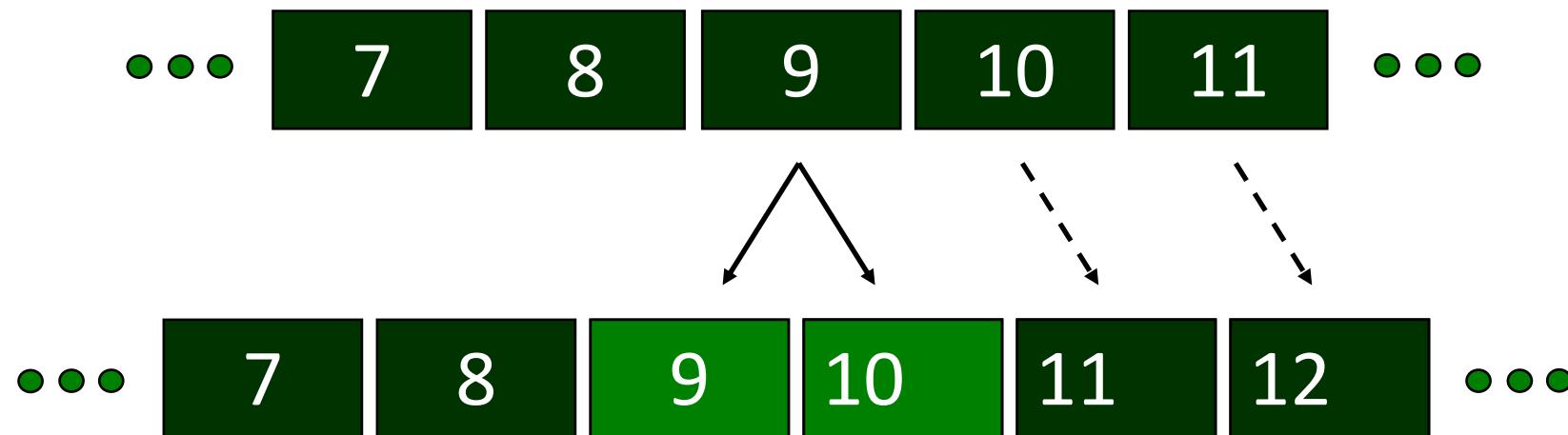
*n* fixed

Example:  
trajectories



# Problem of dynamical systems with dynamical structures

- Number of variables changing over simulation
- Existing formalism are not adapted to manage dynamical structures
- Problem of indexing



Managing indices quickly becomes a headache

➤ Use of a language to avoid indices

# Procedural modelling

- A set of generative rules to build 3D models or textures.
- Modelling of Textures, Plants, Lands, City, Building



[Muller et al., 2006]



[Oppenheimer, 1986]

[Parish et al., 2001]

# Procedural modelling

- Require development of specific formalism
- A classification [Hendrikx et al., 2011]
  - Pseudo-Random Number Generator (Perlin noise)
  - Generative Grammar (L-systems, Shape Grammar)
  - Image Filtering (Morphology, Convolution, ...)
  - Spatial Algorithm (Fractals, ...)
  - Artificial Intelligence (Neural Network, Genetic algorithms, ...)
  - Simulation of Complex Systems (Cellular Automata, ...)



[Muller et al., 2006]



# Applications

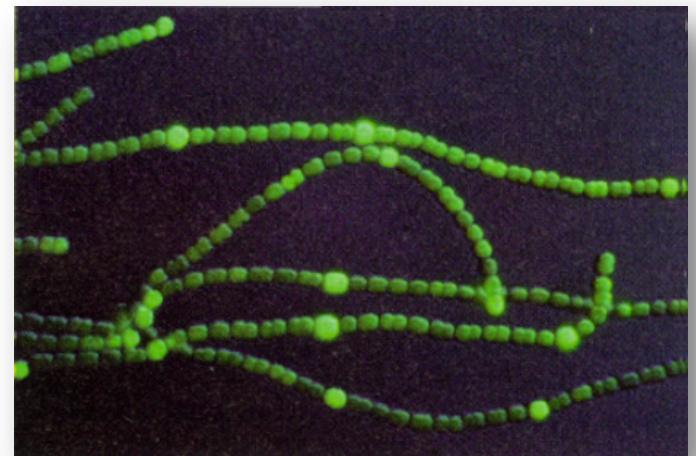
- Scientific modelling : integrative models of growing structures



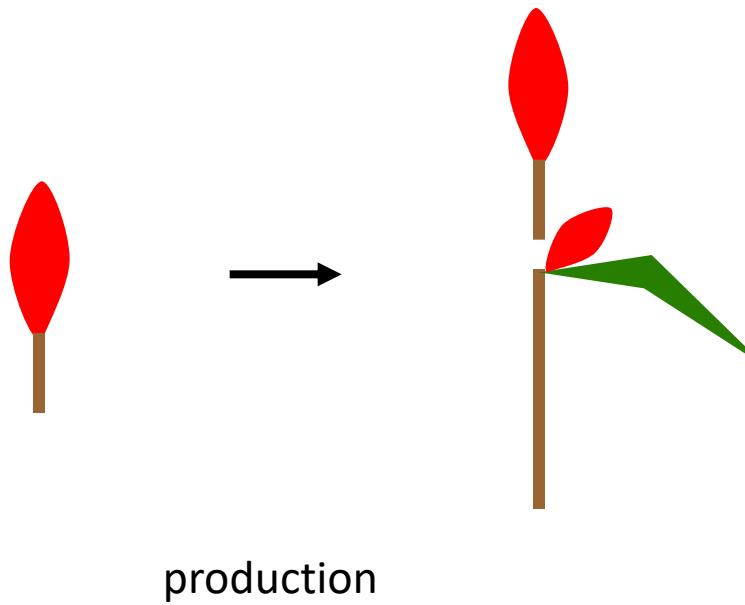
[Boudon et al., 2020]

# L-systems

- Introduced by A. Lindenmayer in 1968
  - Simulation of multi-cellular organisms (Anabaena)
- **Dynamic Systems with Dynamic Structures**  
(Giavitto, 01)
- Well adapted for modeling **plant growth**. Widely used for FSPM.
- Important contribution from computer graphics  
(Prusinkiewicz et al.).
- Different implementations : VLab (Prusinkiewicz, Lindenmayer, 90), Grolmp/XL (Kurth, 2008), L-Py (Boudon et al., 2008)



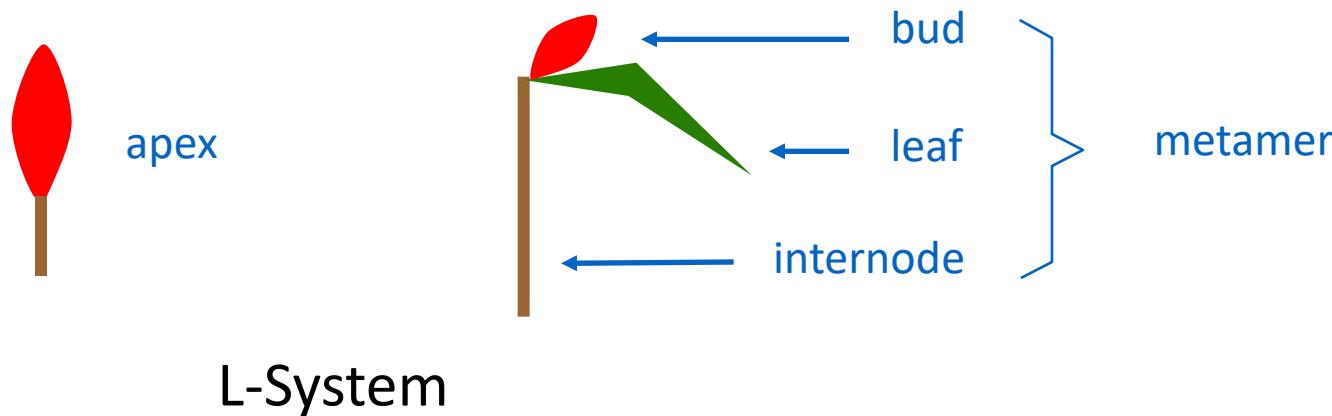
# Development as a rewriting process



production

Development can be thought of as a re-writing process  
Apex is replaced by an internode, leaf, bud, and another apex

# Development as a rewriting process



Alphabet: (A, M)

Axiom: A

Production:  $A \rightarrow MA$

# Development as a rewriting process

L-System

Alphabet: (A, M)

Axiom: A

Production:  $A \rightarrow MA$



A

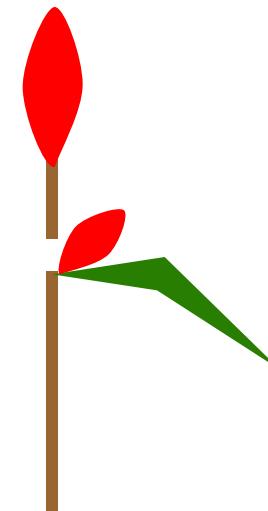
# Development as a rewriting process

L-System

Alphabet:  $(A, M)$

Axiom: A

Production:  $A \rightarrow MA$



MA

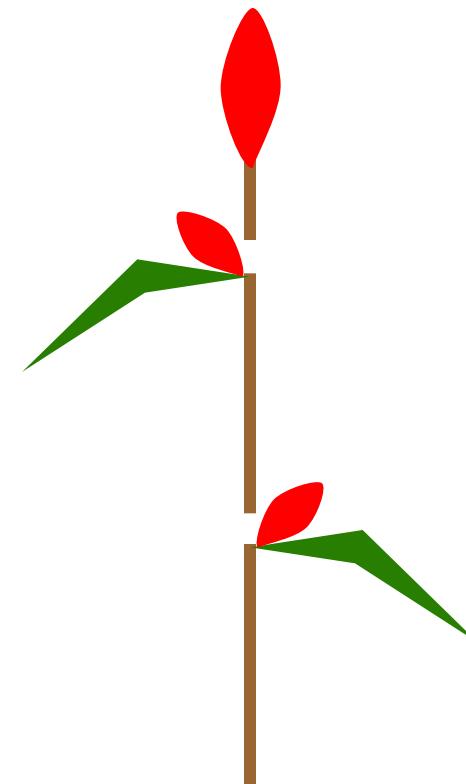
# Development as a rewriting process

L-System

Alphabet:  $(A, M)$

Axiom: A

Production:  $A \rightarrow MA$



MMA

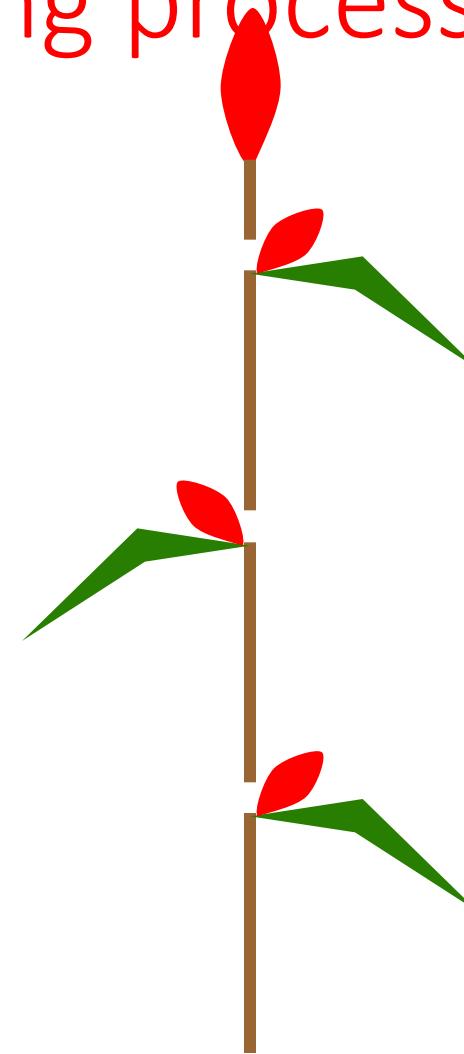
# Development as a rewriting process

L-System

Alphabet:  $(A, M)$

Axiom: A

Production:  $A \rightarrow MA$



MMMA

HFS 52.00

# L-systems

- L-systems consist of an alphabet  $V$ , an axiom  $w$  and a set of productions  $P$ .

$$G = \langle V, w, P \rangle$$

- **Alphabet:** Finite set of symbols

$$V = \{A, E, +, \#, m\}$$

- **String:** any word made of letters from  $V$

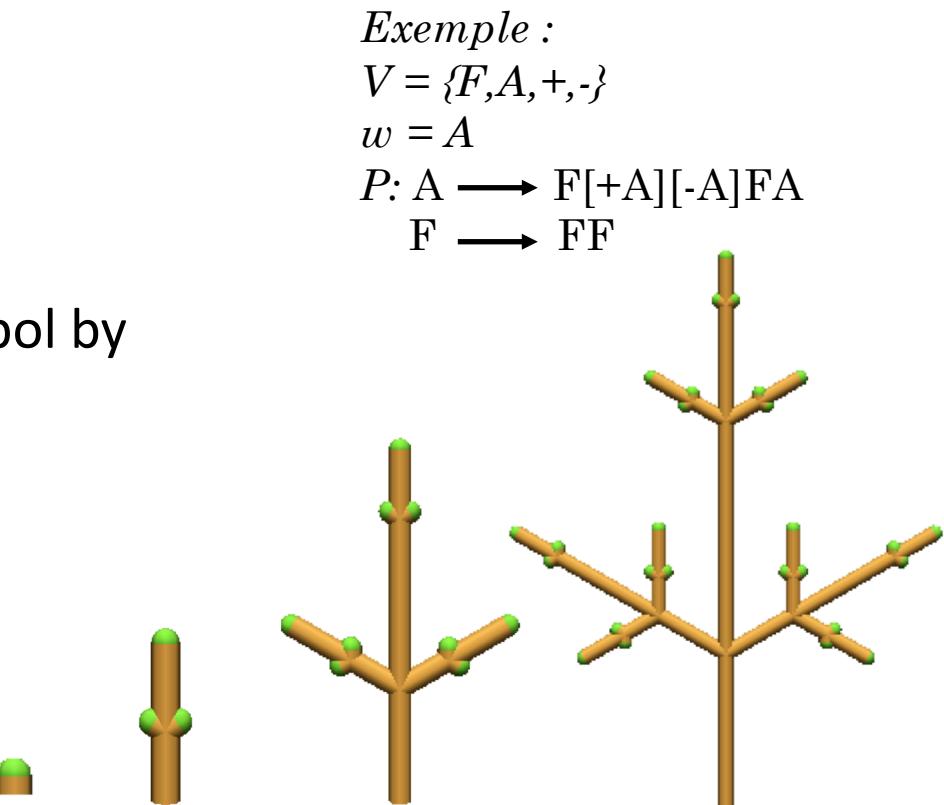
$$AmEAA\#A++\#mmmm$$

- **Production rule:** rule that specifies how to replace a symbol by a string of symbols in a given string

$$\# \longrightarrow A\#AE$$

- **L-System :** grammar for which rules are applied in parallel to all the symbols of an input string (axiom)

*Example :* AmEAA#A++#mmmm  $\Rightarrow$  AmEAAA#AEA++A#AEmmmm



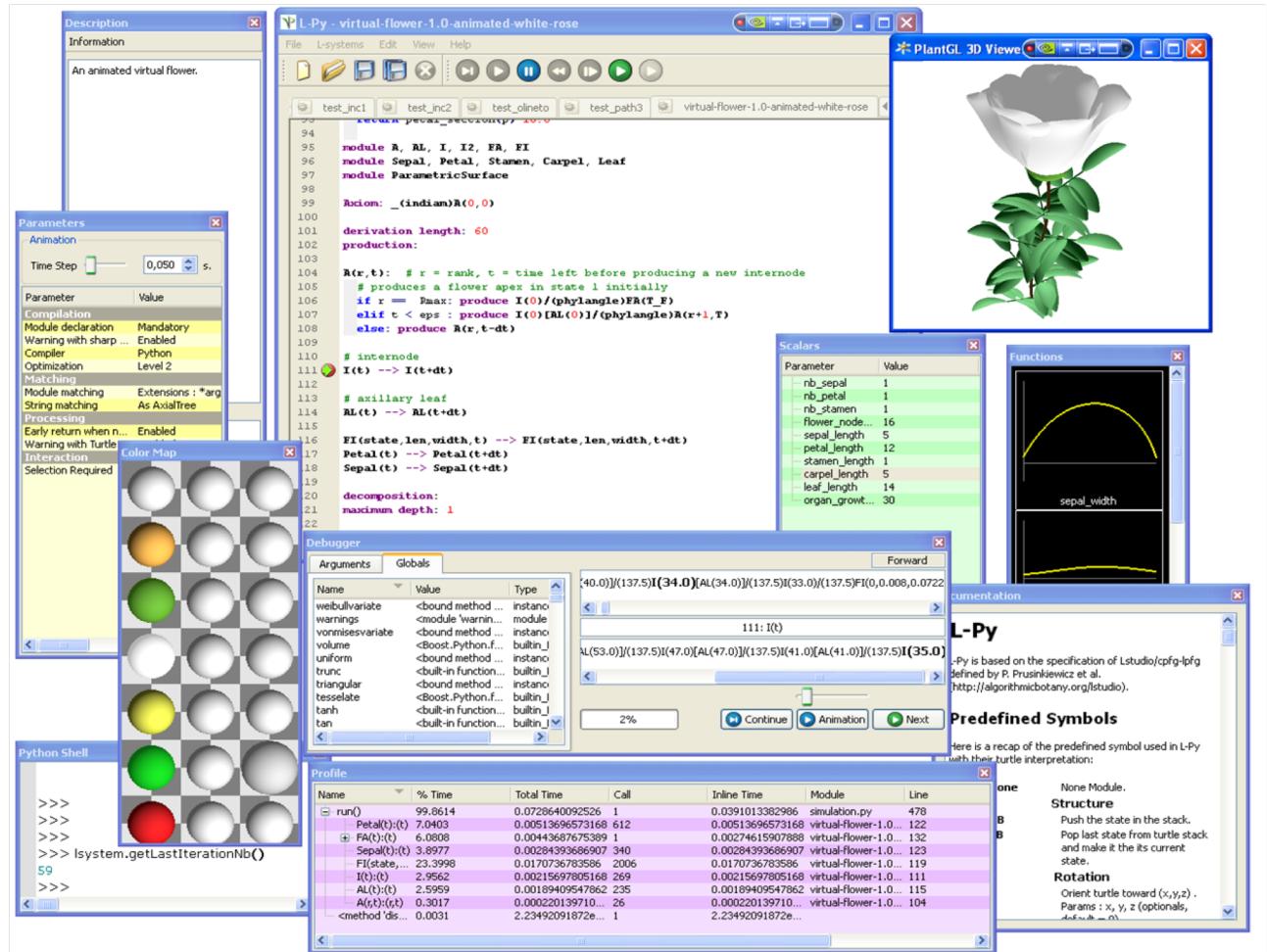
*Exemple :*

$$V = \{F, A, +, -\}$$

$$w = A$$

$$P: A \longrightarrow F[+A][-A]FA$$
$$F \longrightarrow FF$$

# L-Py



<https://github.com/fredboudon/lpy>

frontiers in  
PLANT SCIENCE

METHODS ARTICLE

published: 30 May 2012  
doi: 10.3389/pls.2012.00076

## L-Py: an L-system simulation framework for modeling plant architecture development based on a dynamic language

Frédéric Boudon<sup>1\*</sup>, Christophe Pradal<sup>1</sup>, Thomas Cokelaer<sup>2</sup>, Przemysław Prusinkiewicz<sup>3</sup> and Christophe Godin<sup>2\*</sup>

<sup>1</sup> CIRAD, Virtual Plants INRIA Team, Montpellier, France

<sup>2</sup> INRIA, Virtual Plants INRIA Team, Montpellier, France

<sup>3</sup> Department of Computer Science, University of Calgary, Calgary, AB, Canada

**Edited by:**  
Basil Nikolau, Iowa State University, USA

**Reviewed by:**  
Roeland Merks, Centrum Wiskunde & Informatica, Netherlands  
Haizhou Li, National University of Singapore, Singapore

**\*Correspondence:**  
Frédéric Boudon and Christophe Godin, INRIA Team Virtual Plants, UMR AGAP TA A-108/02, Avenue Agropolis, 34398 Montpellier Cedex 5, France.  
e-mail: frederic.boudon@cirad.fr; christophe.godin@inria.fr

The study of plant development requires increasingly powerful modeling tools to help understand and simulate the growth and functioning of plants. In the last decade, the formalism of L-systems has emerged as a major paradigm for modeling plant development. Previous implementations of this formalism were made based on static languages, i.e., languages that require explicit definition of variable types before using them. These languages are often efficient but involve quite a lot of syntactic overhead, thus restricting the flexibility of use for modelers. In this work, we present an adaptation of Lsystems to the Python language, a popular and powerful open-license dynamic language. We show that the use of dynamic language properties makes it possible to enhance the development of plant growth models: (i) by keeping a simple syntax while allowing for high-level programming constructs, (ii) by making code execution easy and avoiding compilation overhead, (iii) by allowing a high-level of model reusability and the building of complex modular models, and (iv) by providing powerful solutions to integrate MTG data-structures (that are a common way to represent plants at several scales) into Lsystems and thus enabling to use a wide spectrum of computer tools based on MTGs developed for plant architecture. We then illustrate the use of L-Py in real applications to build complex models or to teach plant modeling in the classroom.

**Keywords:** L-system, Python language, plant modeling, MTG, development, environment, FSPM

## INTRODUCTION

new components to the structure. Brackets are used to delimit

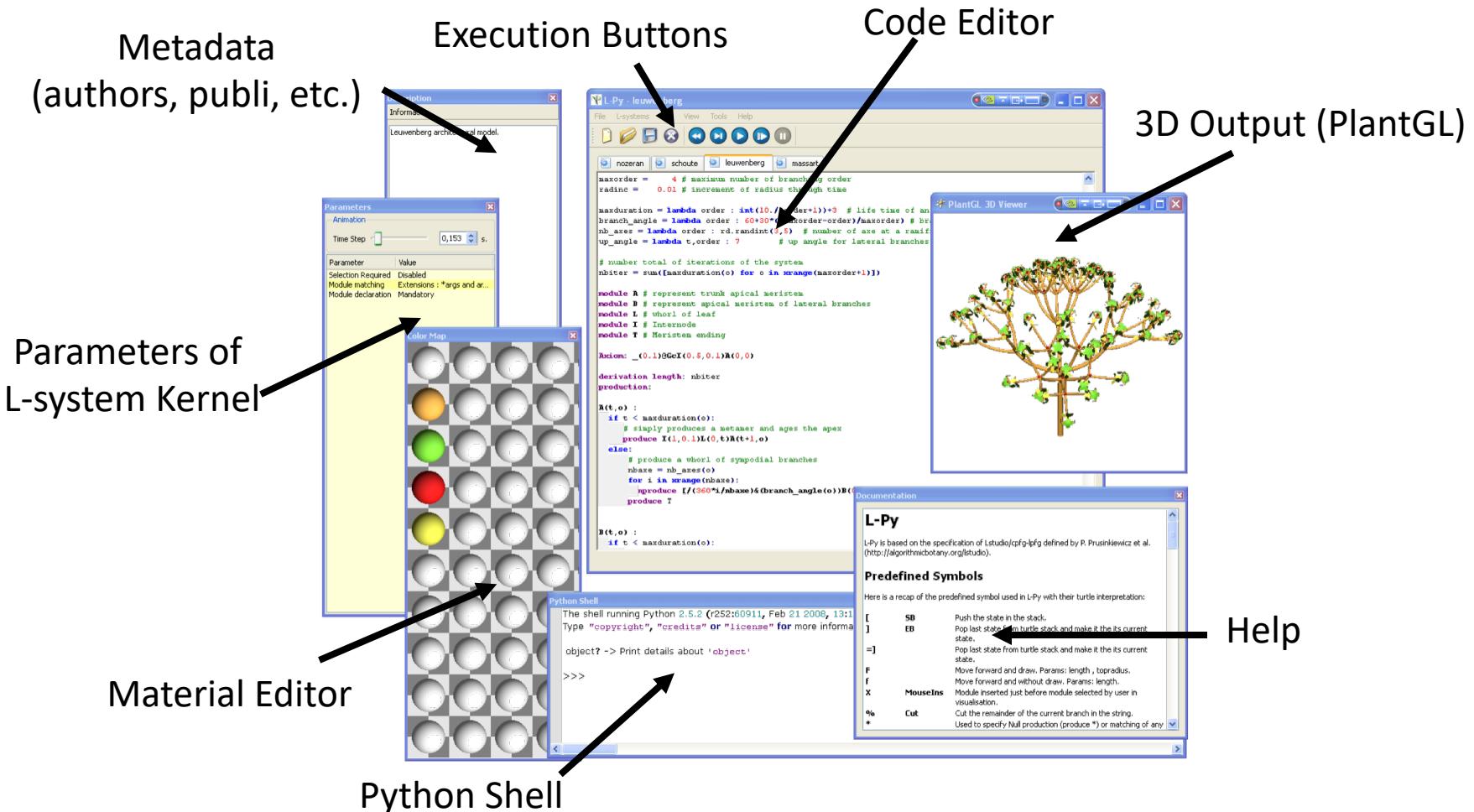
# L-Py Syntax

- Combining L-systems and python

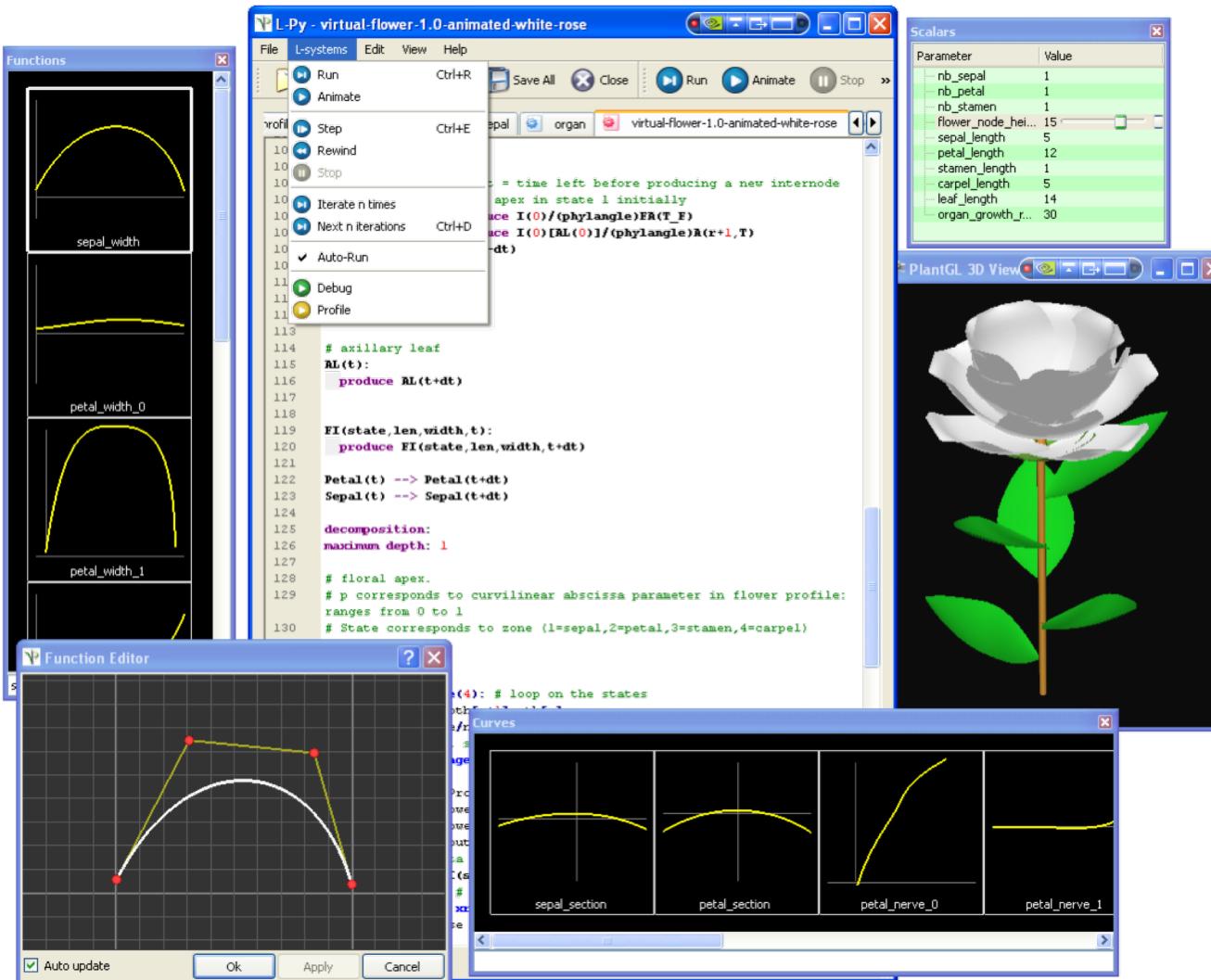
```
from random import random
MAX_AGE, dr = 10, 0.03 # constants
module Apex(age), Internode(length, radius)
Axiom: Apex(0)
derivation length: 5
production:
Apex(age) :
    if age < MAX_AGE:
        produce Internode(1+ random(), 0.3)
            / (137) [+ (30) Apex(age+1)] Apex(age+1)

Internode(l,r) --> Internode(l,r+dr)
interpretation:
Internode(l,r) --> _(r) F(l)
endsystem
```

# Graphical editors



# Scalars, Functions and Curves



- Direct use of objects into the code
- Continuous modeling

# The notebook environment



Cell of lsystem code

```
%%lpy -w size -a True  
# lsystem code  
Axiom: A
```

render nbviewer

launch binder

Jupyter L-systems Last Checkpoint: 11/28/2019 (unsaved changes) Se déconnecter

Fichier Édition Affichage Insérer Cellule Noyau Widgets Aide Trusted | Python 3

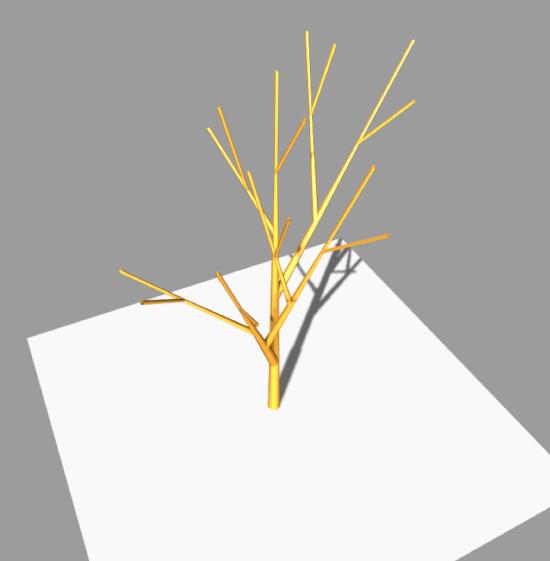
## L-systems

In [2]: `from pgljupyter import *`

### L-Py syntax

Here comes a simple example of L-systems

```
In [10]: %%lpy -w 10 -a True  
from random import random  
MAX_AGE, dr = 10, 0.03 # constants  
module Apex(age), Internode(length,radius)  
Axiom: @Gc Apex(0)  
derivation length: 5  
production:  
Apex(age) :  
    if age < MAX_AGE:  
        produce Internode(1+ random(), 0.03) / (137)[+(30)Apex(age+1)]Apex(age+1)  
  
Internode(l,r) --> Internode(l,r+dr)  
interpretation:  
Internode(l,r) --> _ (r) F(l)  
endsystem
```



First draft of graphical parameter edition

# Fundamental concepts

- Axial tree; string of characters

*Structure*

- 3D Representation; LOGO Turtle

*Geometry*

- Rewriting rules

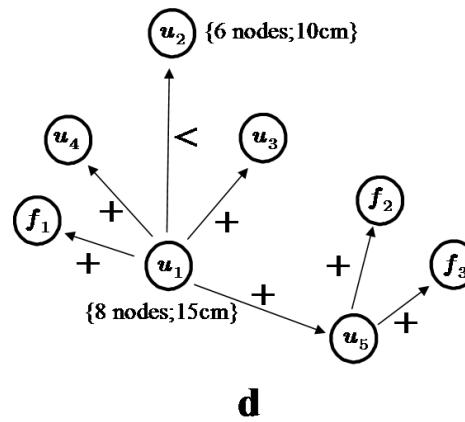
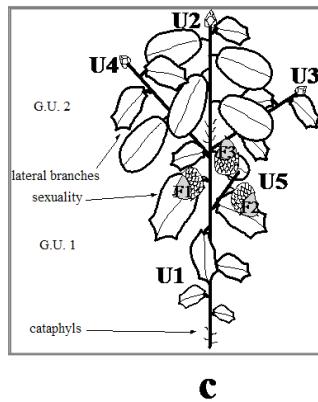
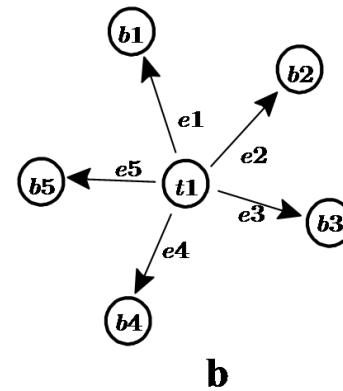
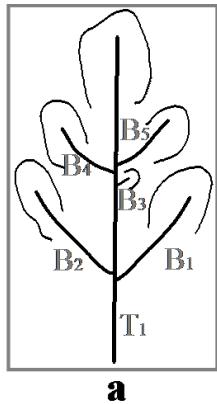
*Dynamic*

# Tree structure representation

Describing trees with strings

# Axial tree

- Representation of plant structure



# Axial tree

- Bracketed string notation

Alphabet

$V$

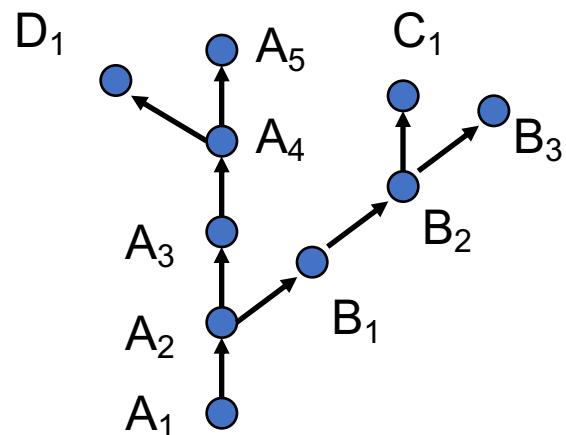
$V_E = V \cup \{[, ]\}$

String

$m = x_1[\alpha_1]x_2[\alpha_2]\dots x_n[\alpha_n]x_{n+1}$

$x_1, x_2, \dots, x_{n+1} \in V^*$        $\alpha_1, \alpha_2, \dots, \alpha_n \in V_E^*$

- Example



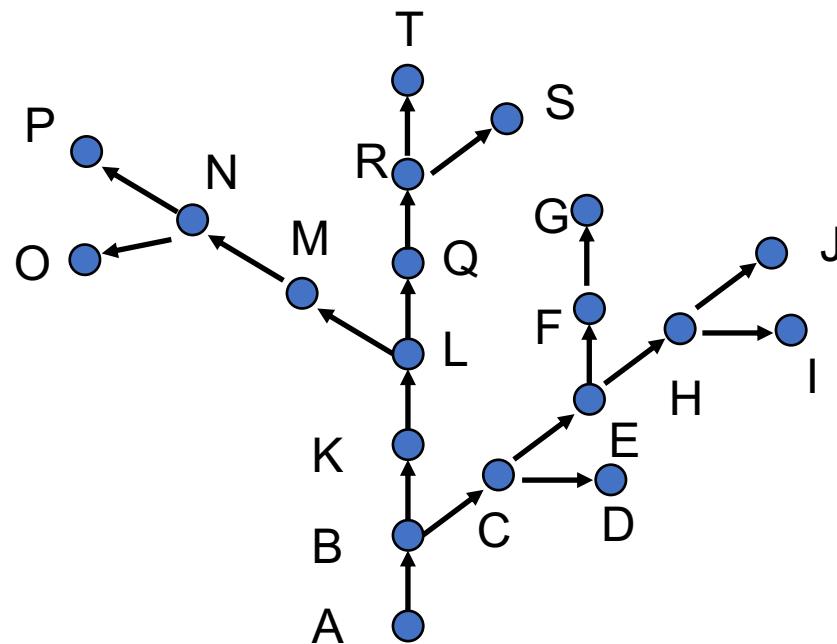
$A_1A_2 [ B_1B_2 [ C_1 ] B_3 ] A_3A_4 [ D_1 ] A_5$

# Parameters

- Use of parameters to characterise modules of plants
  - Parametric letters (or modules)
    - Parametric strings
- Example:  
 $I(5, 6) I(4, 5.8) I(3, 5.8) I(1, 3) B('F')$
- Useful for geometric interpretation

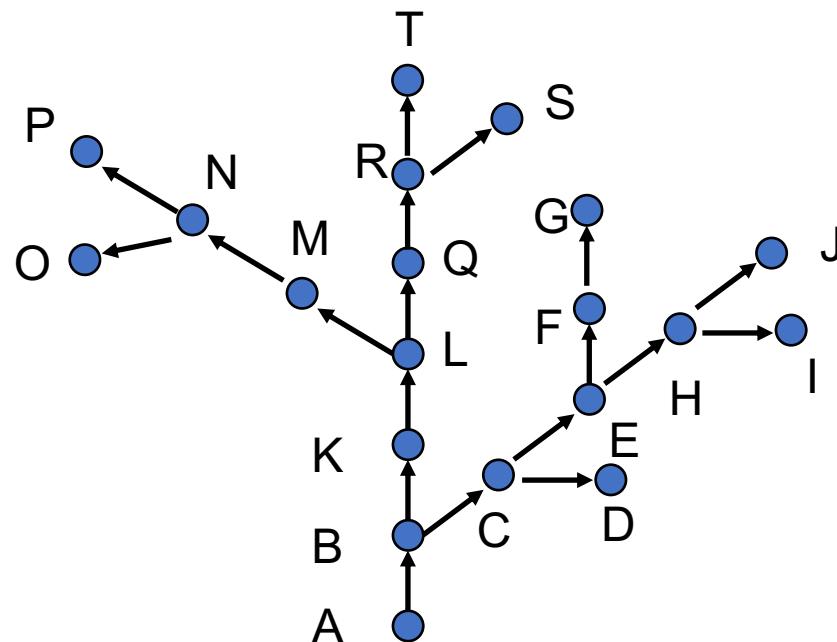
# Exercice

- Give the string representing the following structure



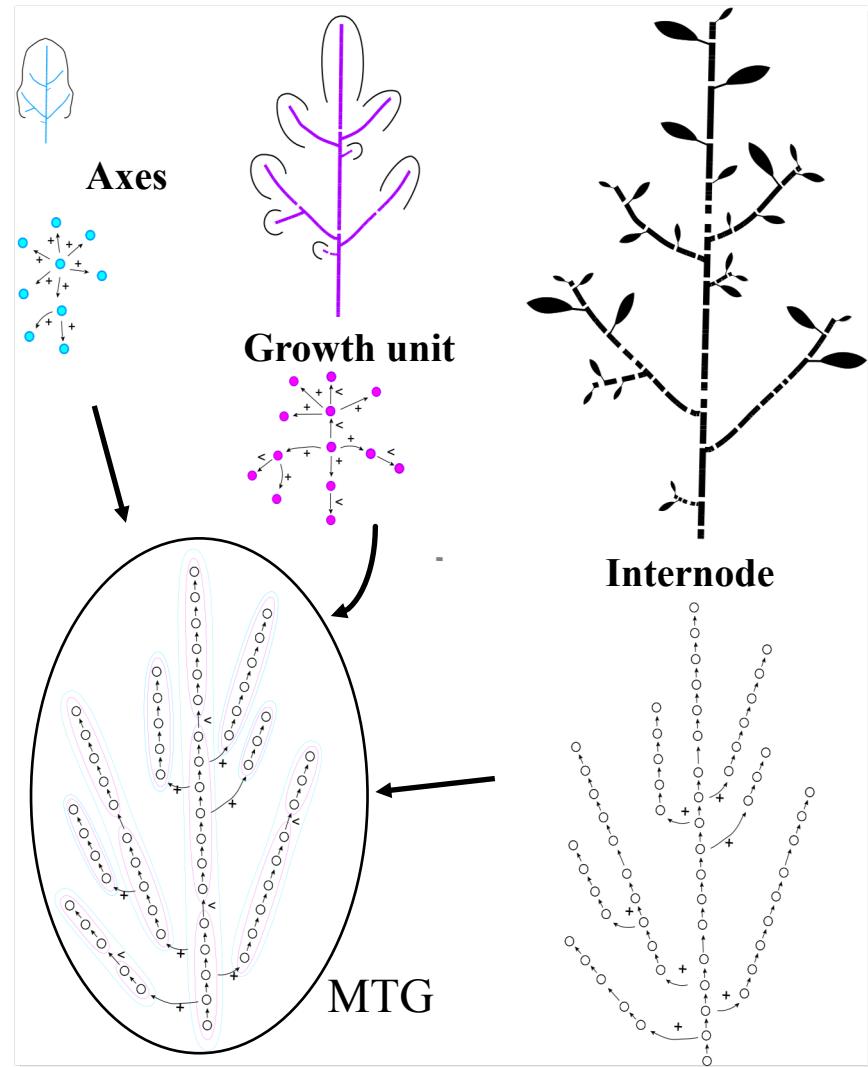
# Exercice

- Give the string representing the following structure

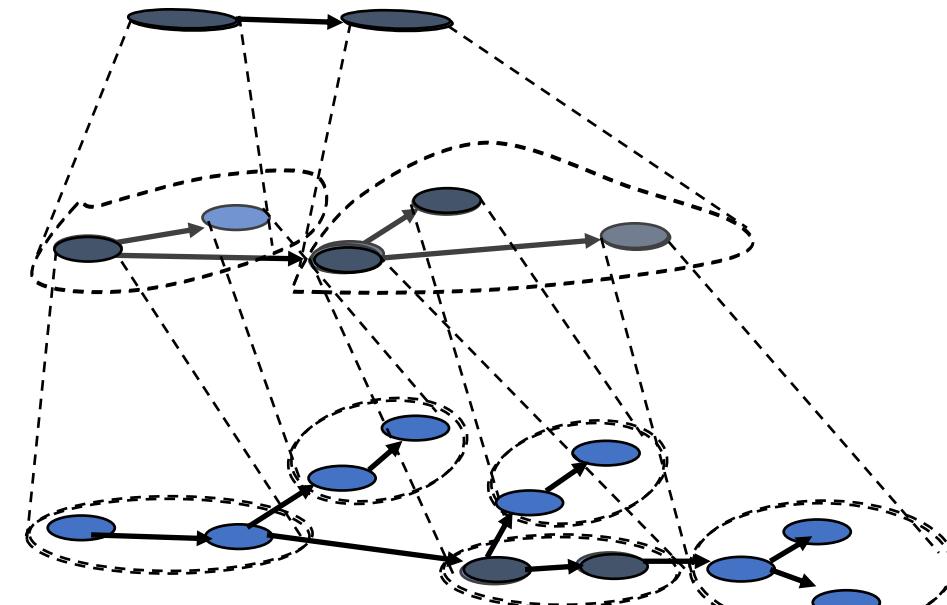


AB[C[D]E[FG]H[I]J]KL[MN[O]P]QR[S]T

# Multiscale topological representation of plants

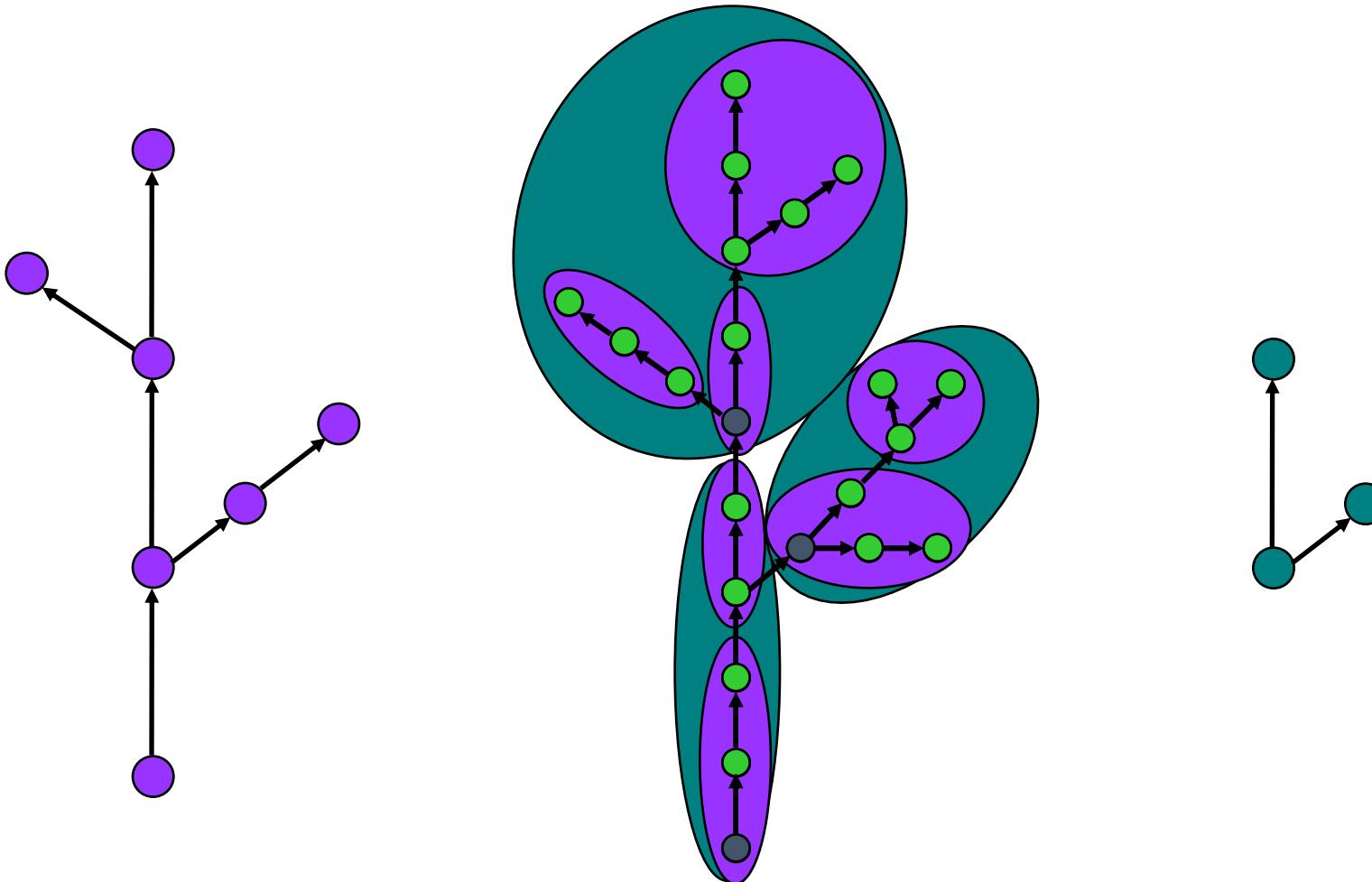


Multiscale Tree Graph (MTG)



(Godin, Caraglio 98)

# Specification of macroscopic scale



NNNN[N[NN]NN[N]N]NN[NNN]NN[NN]NN  
BNNNBN[BN[NN]NB[N]N]NB[N]NN[BNNN]NB[N]NN  
SBNNNBN[SBN[NN]NB[N]N]NSBN[BNNN]NB[N]NN

# Multi-scale extension

- Extend modules with scale tags

module P : scale 1

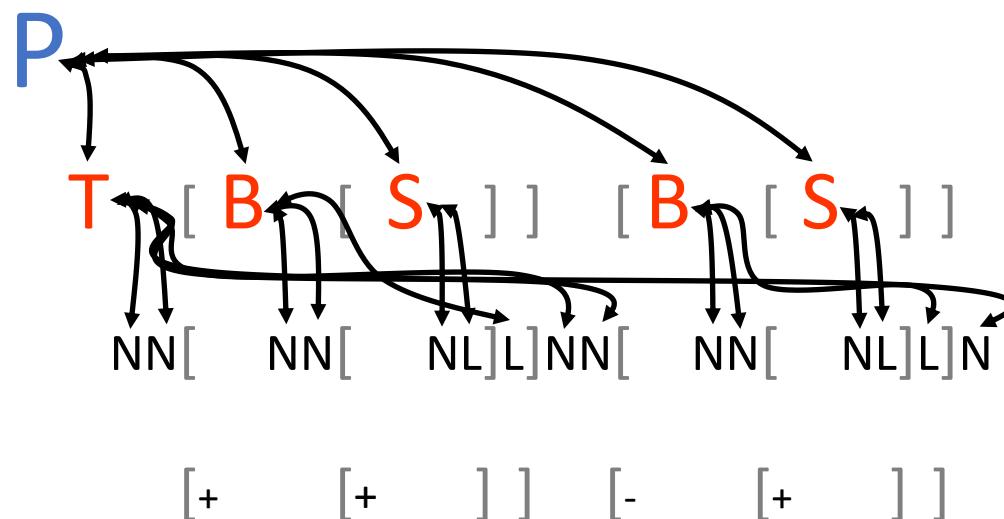
PTNN[+BNN[+SNL]L]NN[-BNN[+SNL]L]N

module T,B, S : scale 2

P<sub>T</sub>NN[+B<sub>NN</sub>[+S<sub>NL</sub>]L]NN[-B<sub>NN</sub>[+S<sub>NL</sub>]L]N

module N,L : scale 3

- Add some between scale relations



# Multi-scale extension

- Extend modules with scale tags

module P : scale 1

PTNN[+BNN[+SNL]L]NN[-BNN[+SNL]L]N

module T,B, S : scale 2

P<sub>T</sub>NN[+B<sub>NN</sub>[+S<sub>NL</sub>]L]NN[-B<sub>NN</sub>[+S<sub>NL</sub>]L]N

module N,L : scale 3

- Add some within scale relations



NN ← NN ← NL ] L ] NN ← NN ← NL ] L ] N

[ +      [ +      ] ]      [ -      [ +      ] ]

# Multi-scale extension

- Extend modules with scale tags

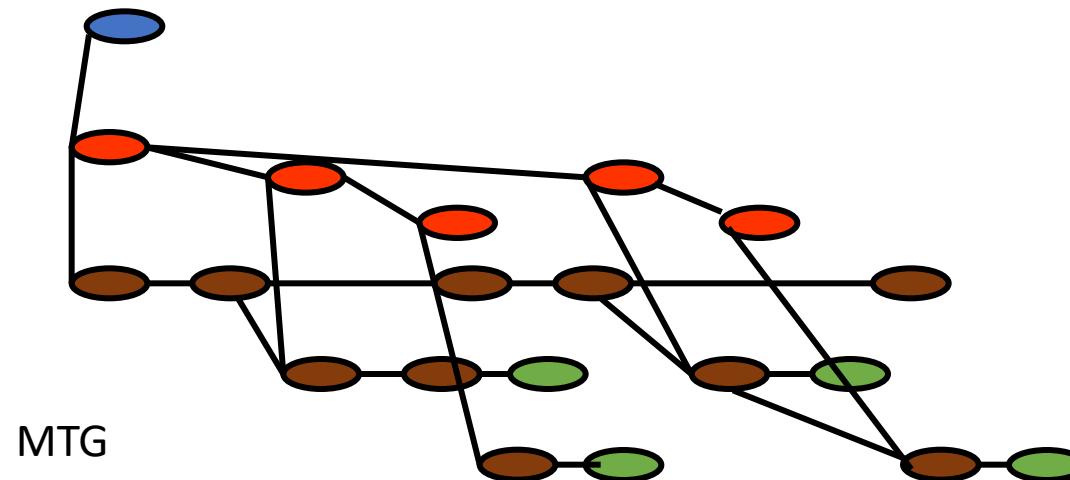
module P : scale 1

PTNN[+BNN[+SNL]L]NN[-BNN[+SNL]L]N

module T,B, S : scale 2

P<sub>T</sub>NN[+B<sub>NN</sub>[+S<sub>NL</sub>]L]NN[-B<sub>NN</sub>[+S<sub>NL</sub>]L]N

module N,L : scale 3



# Exercise

- Let the following multiscale structure

module S : scale = 1

module B : scale = 2

module N : scale = 3

$S_1 B_1 N_0 N_1 [S_2 B_2 N_2 [N_3] B_3 N_4 [N_5 N_6] N_7 [N_8] N_9] N_{10} B_4 N_{11} [S_3 B_5 N_{12} N_{13} [N_{14}] N_{15}] N_{16} N_{17} [N_{18}] N_{19}$

- Draw a geometrical interpretation

# Exercise

- Let the following multiscale structure

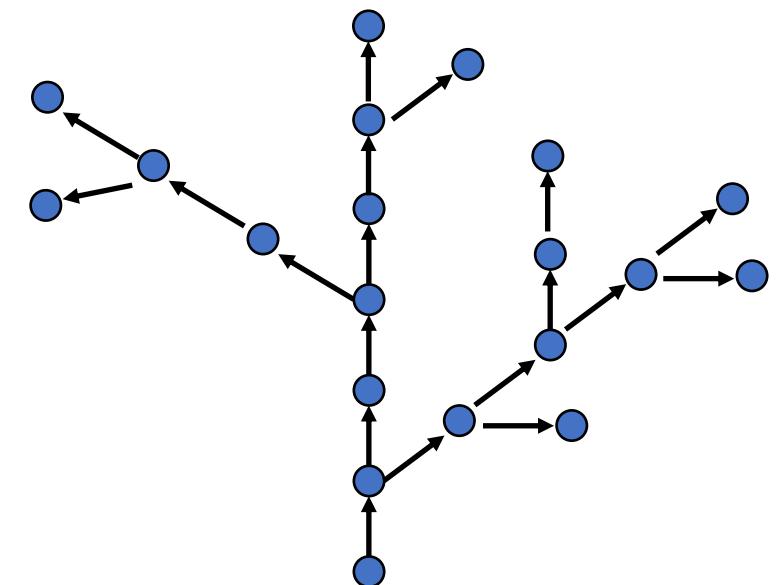
module S : scale = 1

module B : scale = 2

module N : scale = 3

$S_1 B_1 N_0 N_1 [S_2 B_2 N_2 [N_3] B_3 N_4 [N_5 N_6] N_7 [N_8] N_9] N_{10} B_4 N_{11} [S_3 B_5 N_{12} N_{13} [N_{14}] N_{15}] N_{16} N_{17} [N_{18}] N_{19}$

- Draw a geometrical interpretation



# Exercise

- Let the following multiscale structure

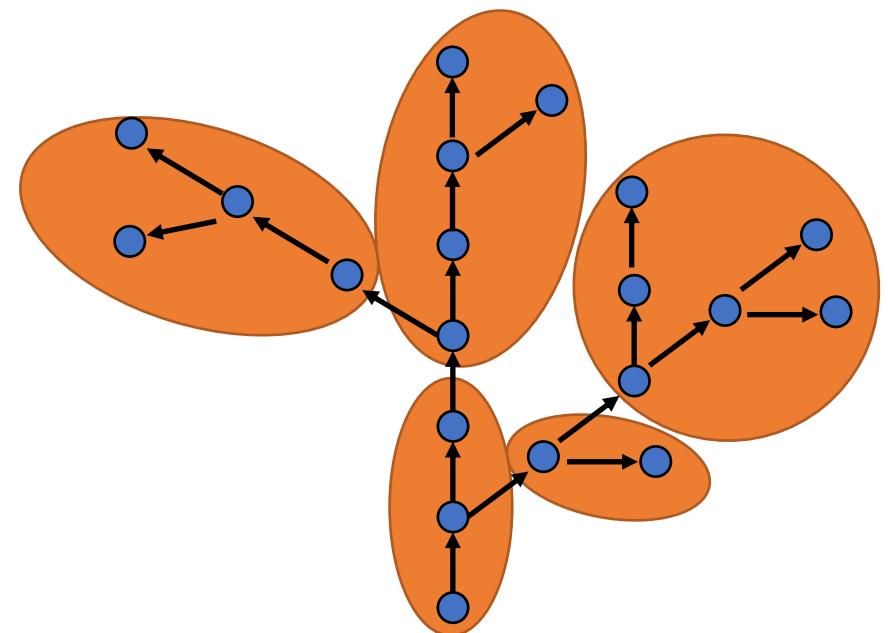
module S : scale = 1

module B : scale = 2

module N : scale = 3

$S_1 B_1 N_0 N_1 [S_2 B_2 N_2 [N_3] B_3 N_4 [N_5 N_6] N_7 [N_8] N_9] N_{10} B_4 N_{11} [S_3 B_5 N_{12} N_{13} [N_{14}] N_{15}] N_{16} N_{17} [N_{18}] N_{19}$

- Draw a geometrical interpretation



# Exercise

- Let the following multiscale structure

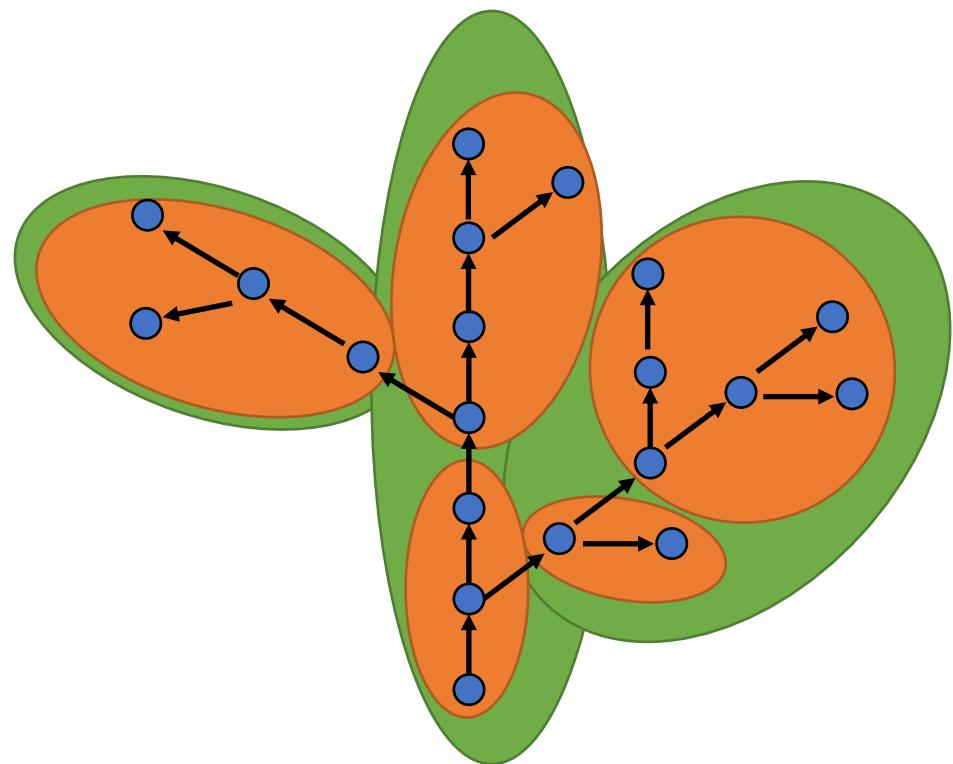
module S : scale = 1

module B : scale = 2

module N : scale = 3

$S_1 B_1 N_0 N_1 [S_2 B_2 N_2 [N_3] B_3 N_4 [N_5 N_6] N_7 [N_8] N_9] N_{10} B_4 N_{11} [S_3 B_5 N_{12} N_{13} [N_{14}] N_{15}] N_{16} N_{17} [N_{18}] N_{19}$

- Draw a geometrical interpretation



# Exercise

- Let the following multiscale structure

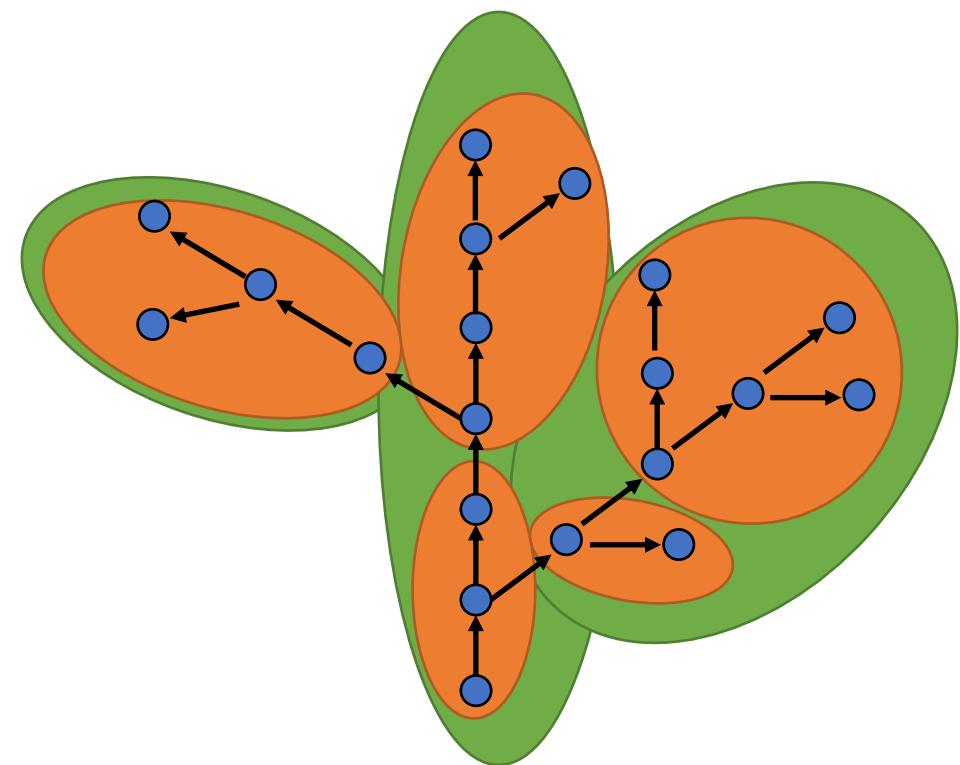
module S : scale = 1

module B : scale = 2

module N : scale = 3

$S_1 B_1 N_0 N_1 [S_2 B_2 N_2 [N_3] B_3 N_4 [N_5 N_6] N_7 [N_8] N_9] N_{10} B_4 N_{11} [S_3 B_5 N_{12} N_{13} [N_{14}] N_{15}] N_{16} N_{17} [N_{18}] N_{19}$

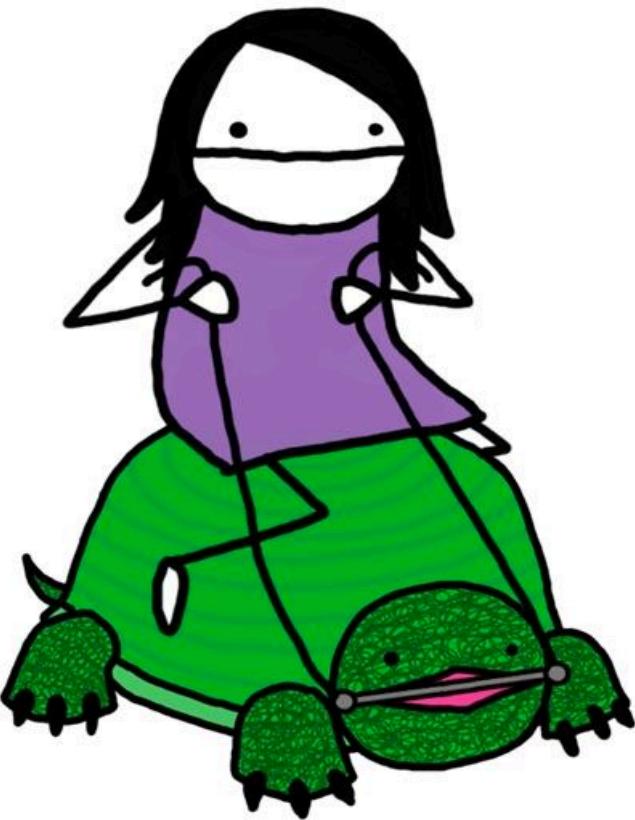
- Draw a geometrical interpretation
- Complexes at scale 2 of  $N_3$  ?  $B_2$
- Complexes at scale 1 of  $B_3$  ?  $S_2$
- Components at scale 3 of  $B_3$  ?  $N_4 N_5 N_6 N_7 N_8 N_9 N_{10}$
- Parents at scale 2 of  $B_3$  ?  $B_2$
- Parents at scale 3 of  $N_{12}$  ?  $N_{11}$
- What are the children at scale 3 of  $N_4$  ?  $N_5$  and  $N_7$ ,



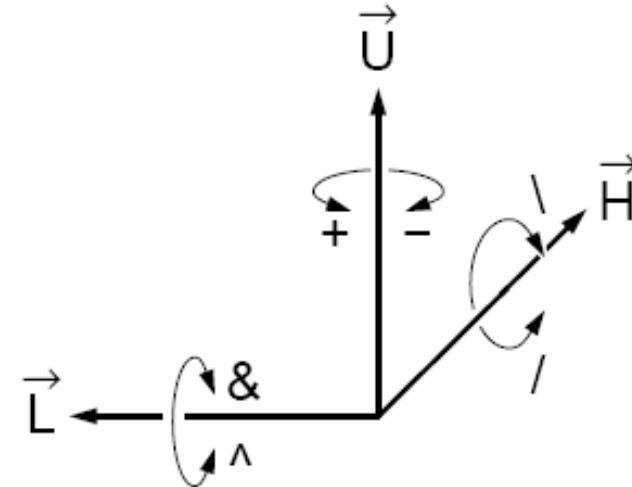
# Geometrical Interpretation

Riding the turtle

# Geometric Interpretation

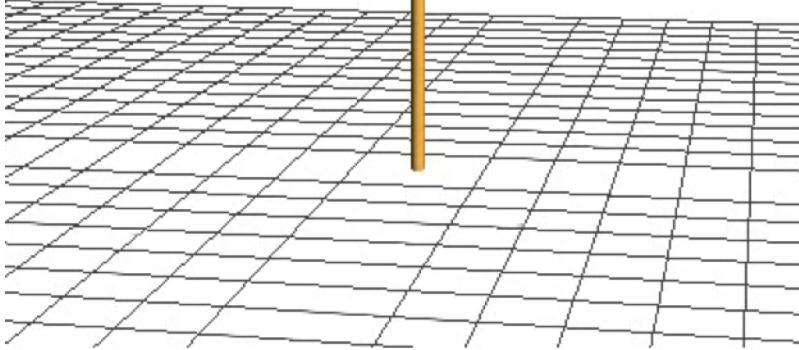
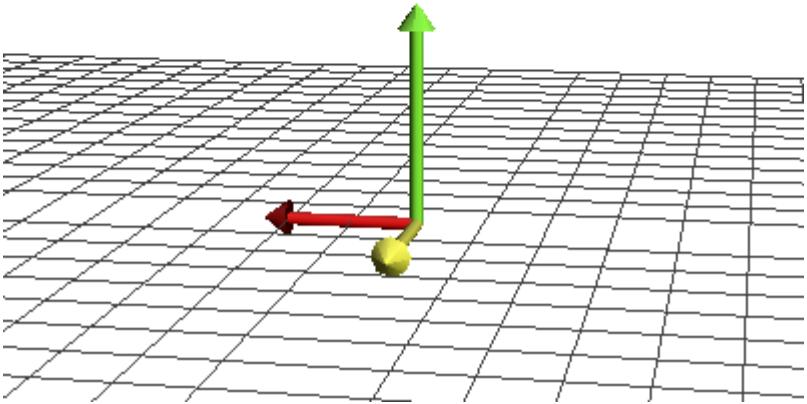


- LOGO Turtle :

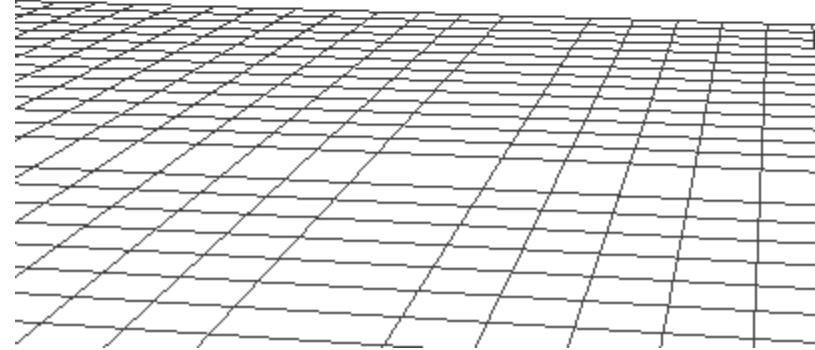


- Symbols interpreted as commands for the turtle

# Geometric Interpretation

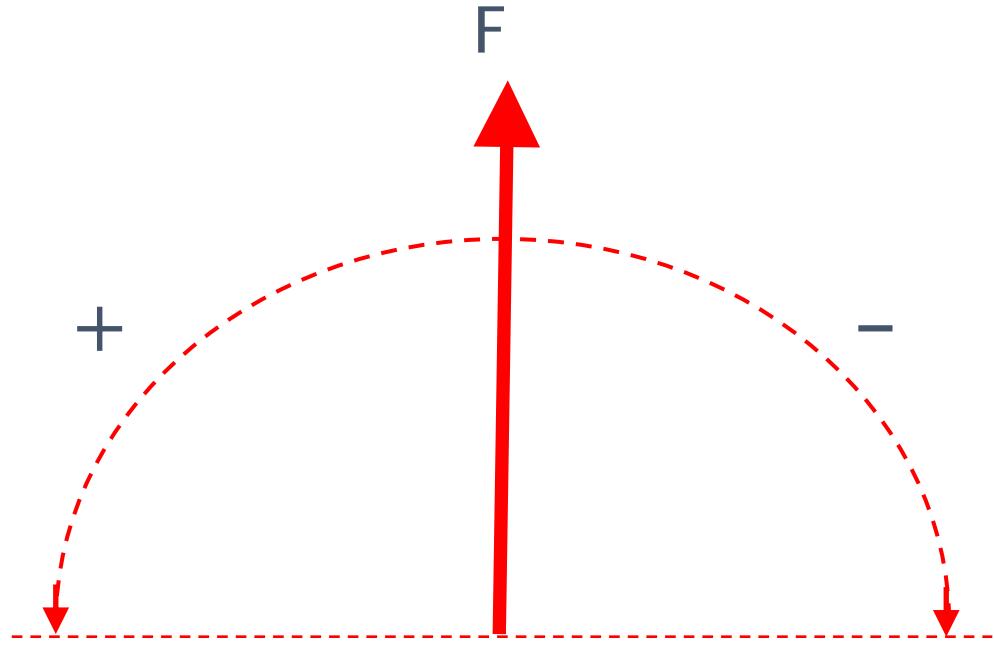


$F(x)$



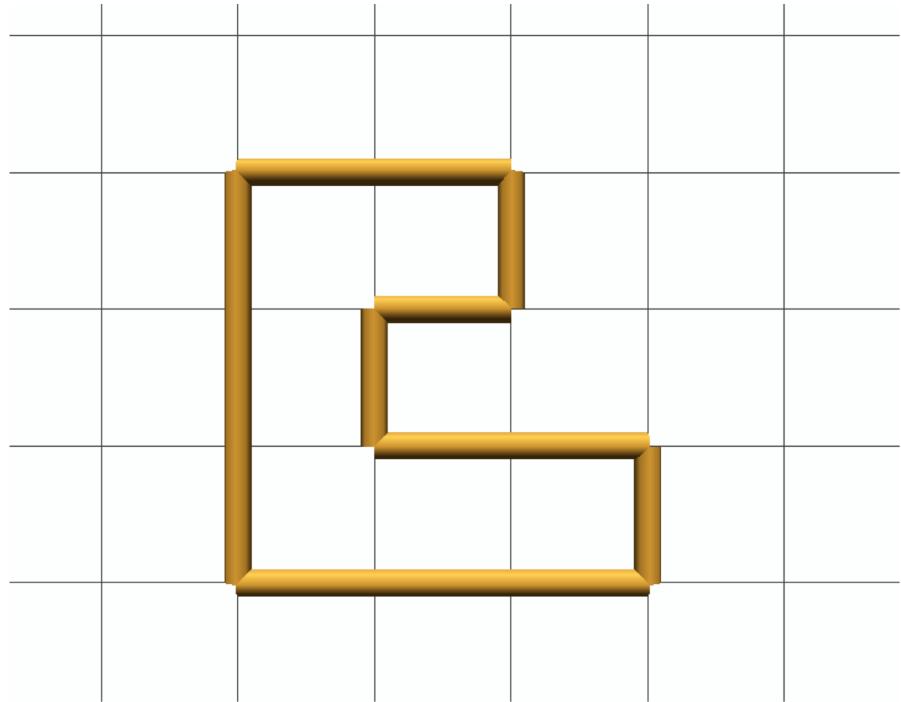
$f(x)$

# Geometric Interpretation



Logo style turtle interpretation

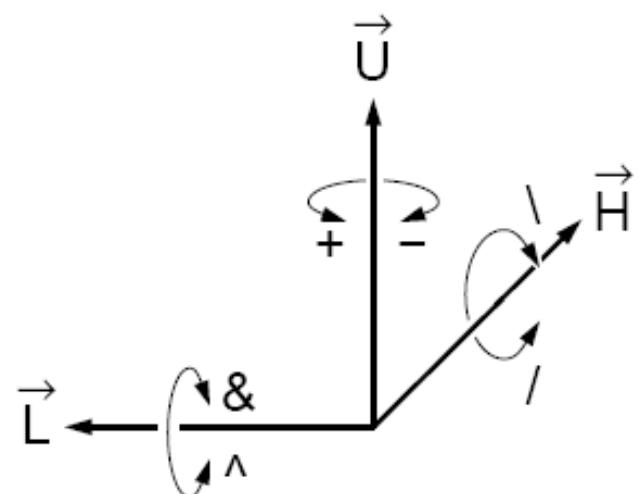
- F Move forward, drawing a line
- +
- Turn right 90 degrees



Axiom: FFF-FF-F-F+F+FF-F-FFF

# Geometric Interpretation

- Left:  $- (\alpha)$  Right:  $+ (\alpha)$
- Down:  $\& (\alpha)$  Up:  $\wedge (\alpha)$
- RollL:  $/ (\alpha)$  RollR:  $\backslash (\alpha)$
- TurnAround:  $|$



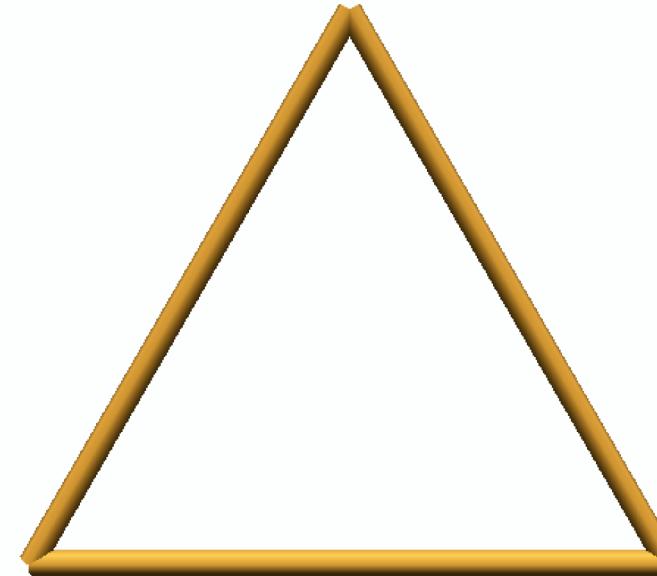
$$R_U(\alpha) = \begin{bmatrix} \cos \alpha & \sin \alpha & 0 \\ -\sin \alpha & \cos \alpha & 0 \\ 0 & 0 & 1 \end{bmatrix},$$

$$R_L(\alpha) = \begin{bmatrix} \cos \alpha & 0 & -\sin \alpha \\ 0 & 1 & 0 \\ \sin \alpha & 0 & \cos \alpha \end{bmatrix},$$

$$R_H(\alpha) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \alpha & -\sin \alpha \\ 0 & \sin \alpha & \cos \alpha \end{bmatrix}$$

# First geometric figures with L-Py

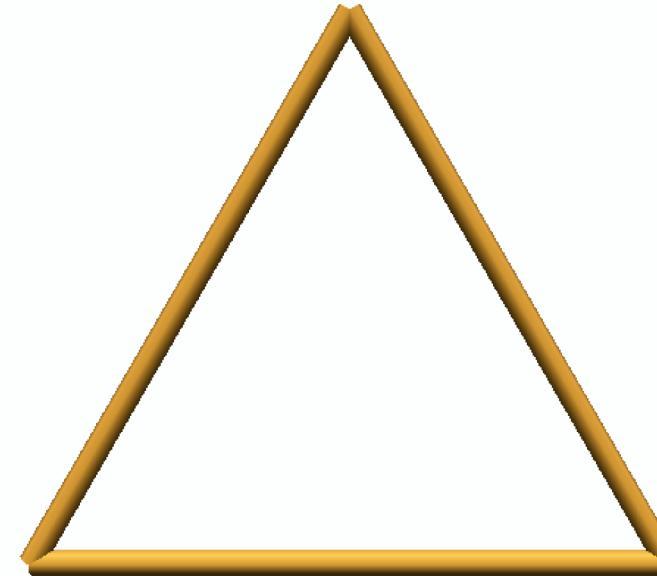
- Drawing an equilateral triangle



**Axiom:** -(90) F(5) ...

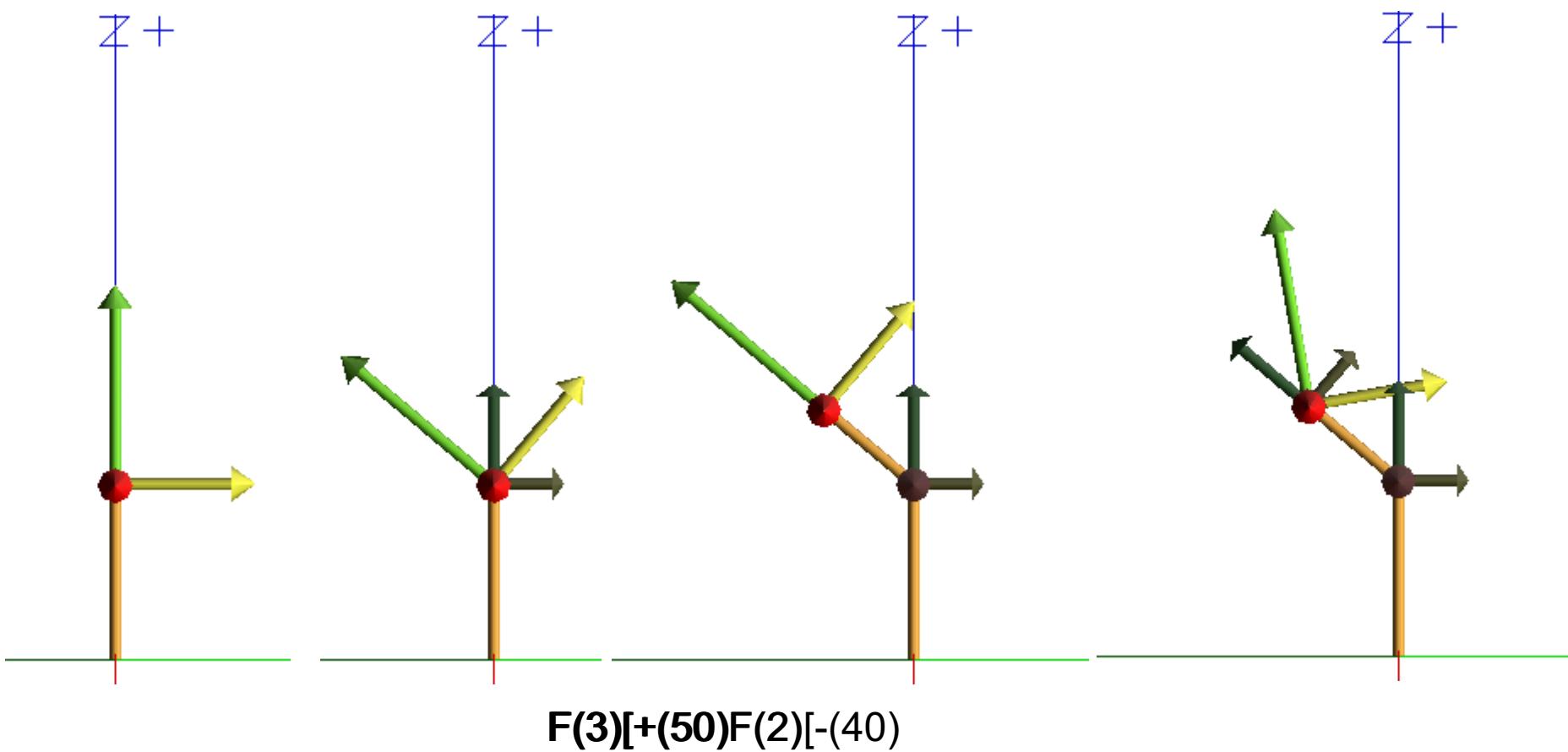
# First geometric figures with L-Py

- Drawing an equilateral triangle

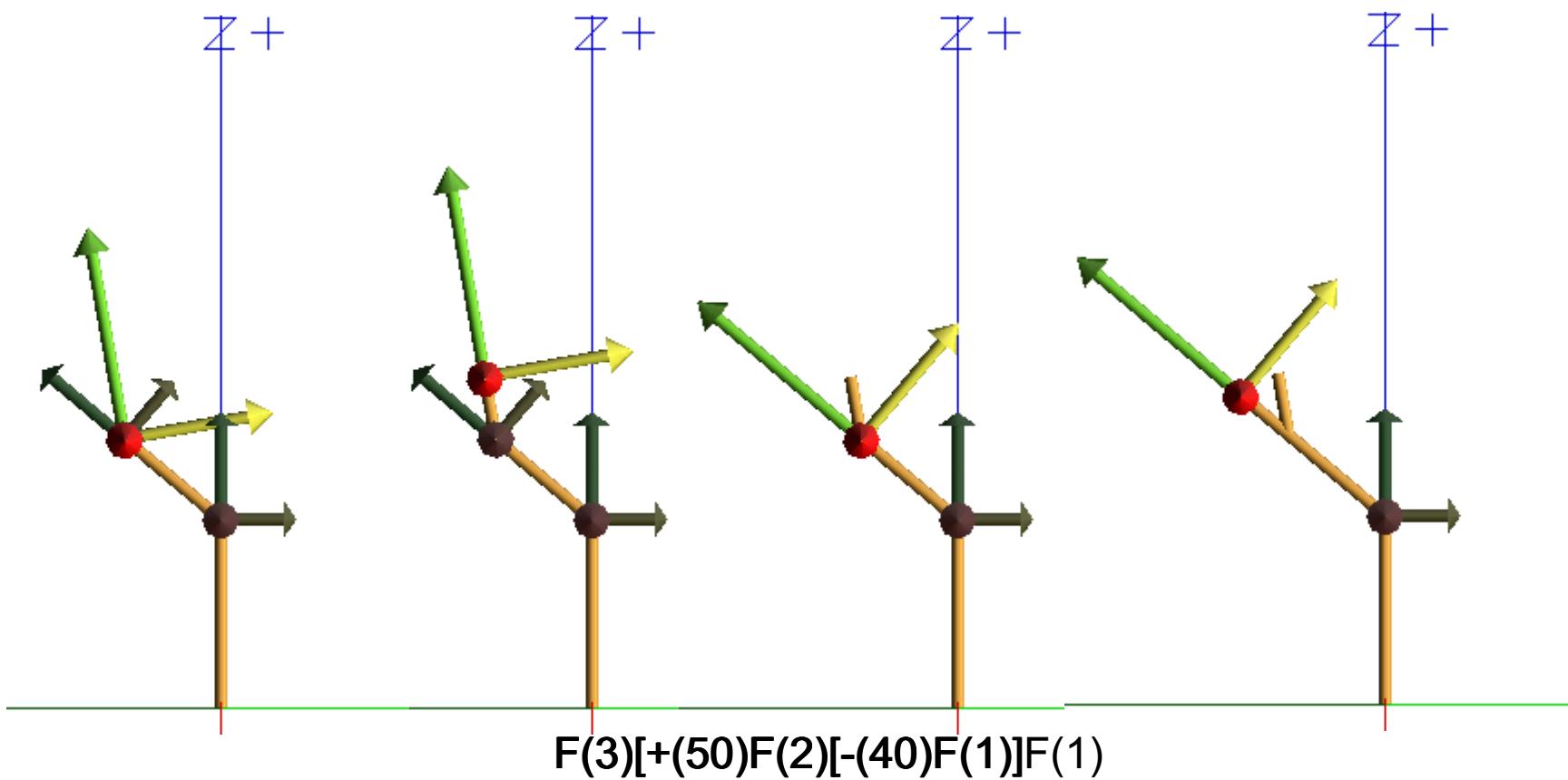


**Axiom:** -(90) F(5) +(120) F(5) +(120) F(5)

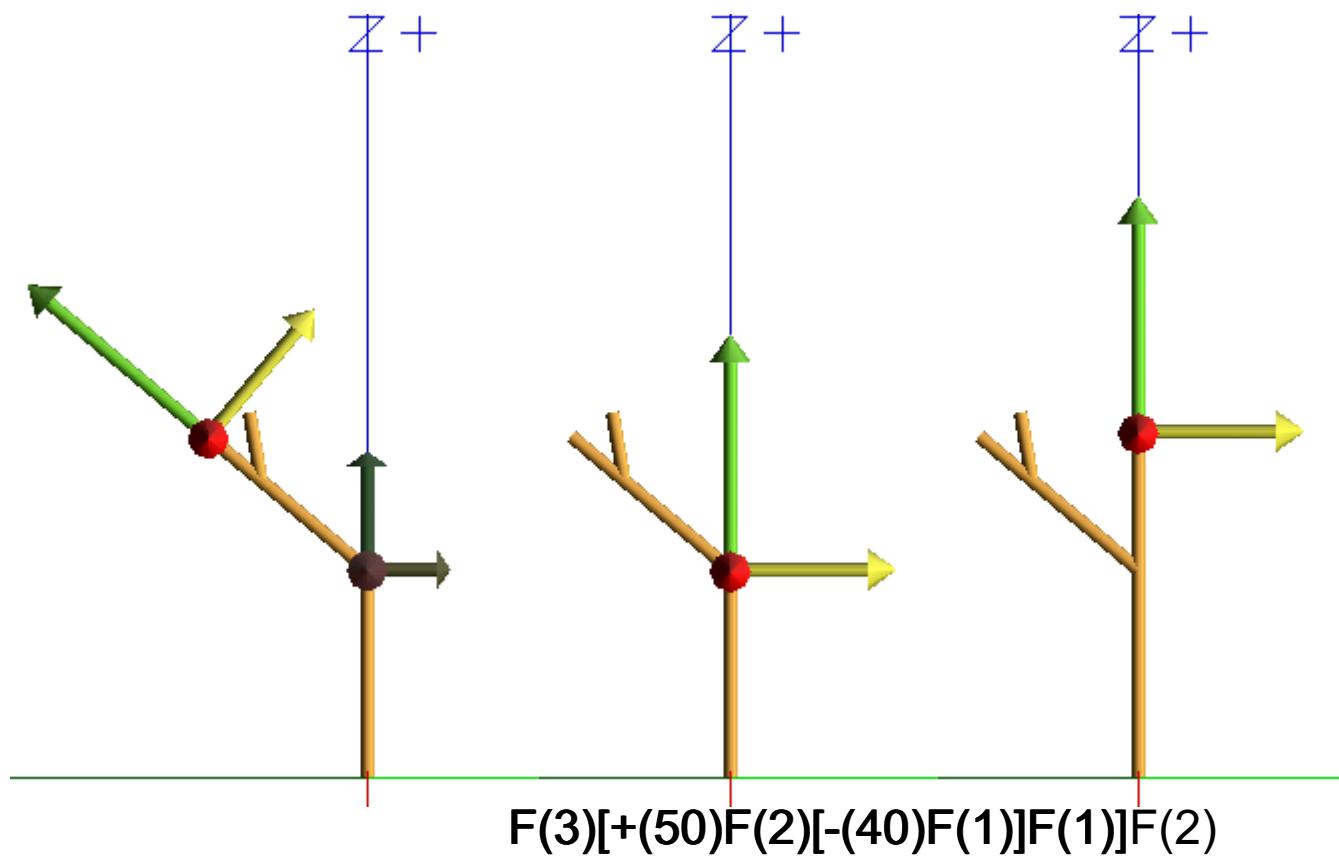
# Geometric interpretation of bracketed strings [...]



Use of a stack to manage bifurcation points [...]



Use of a stack to manage bifurcation points [...]



# Geometric Interpretation

- Moving to a precise location :

- $@M(x, y, z)$

- Locating Turtle

- Frame ()

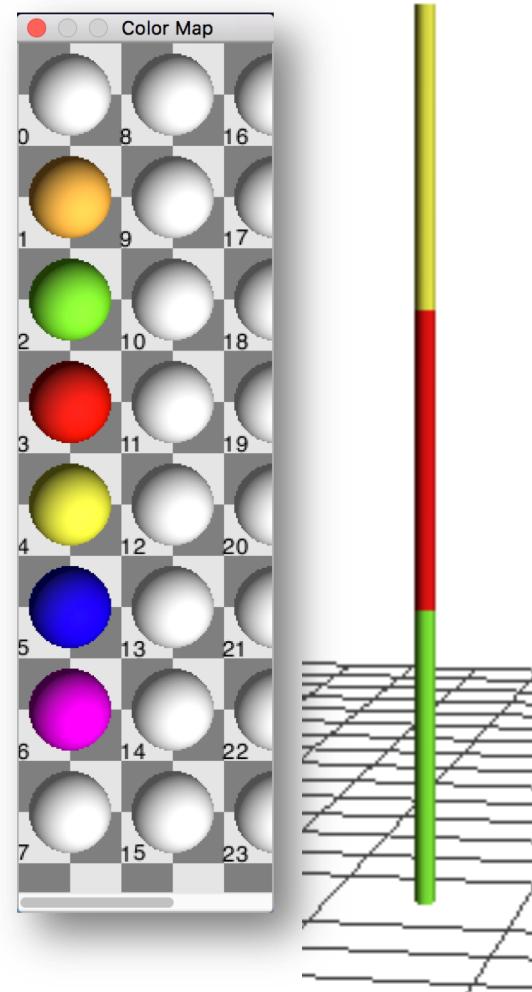
- Parameter of the plot:

- Width :  $\underline{w}$

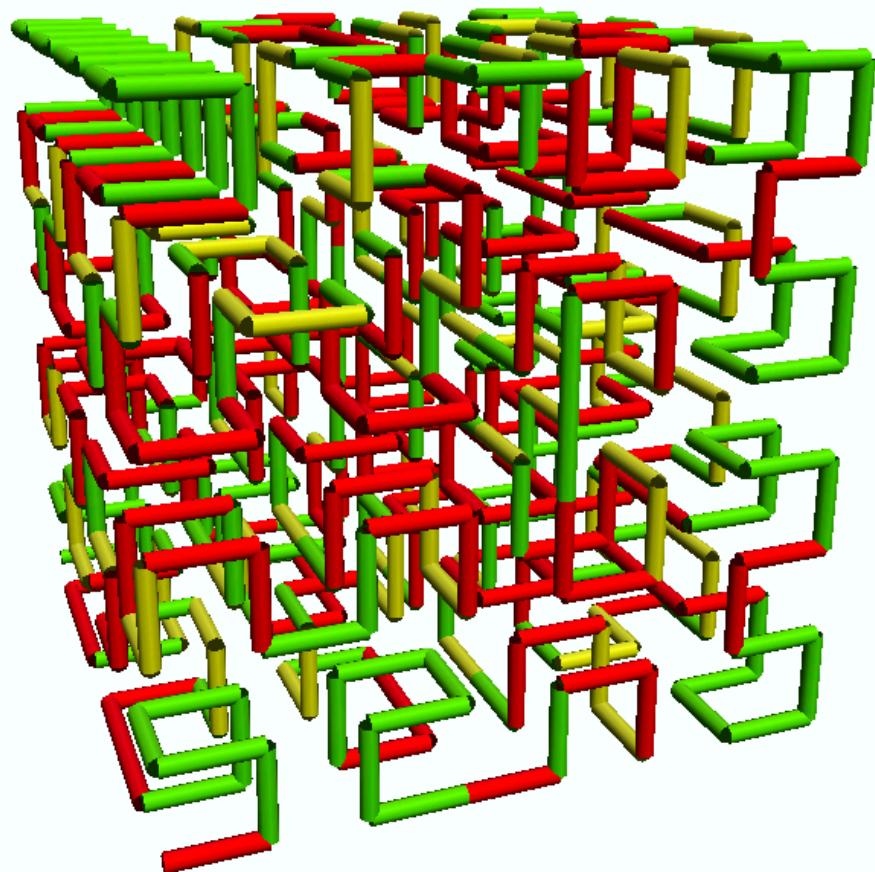
- Color :  $, \underline{c}$

- Section of the plot

- SetContour



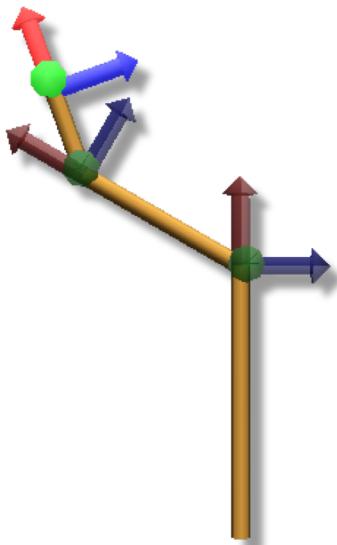
# Turtle Interpretation



Axiom : A

A --> B-F+CFC+F-D&F^D-F+&&CFC+F+B//  
B --> A&F^CFB^F^D^^-F-D^|F^B|FC^F^A//  
C --> |D^|F^B-F+C^F^A&&FA&F^C+F+B^F^D//  
D --> |CFB-F+B|FA&F^A&&FB-F+B|FC//

# Lpy help



F (3) [+ (60) F (2) [-(40) F (1) ] ]

Documentation

## L-Py

L-Py is based on the specification of Lstudio/cpfg-lpfg defined by P. Prusinkiewicz et al. (<http://algorithmicbotany.org/lstudio>).

### Predefined Symbols

Here is a recap of the predefined symbol used in L-Py with their turtle interpretation:

	<b>None</b>	<b>Structure</b>
[	<b>SB</b>	Push the state in the stack.
]	<b>EB</b>	Pop last state from turtle stack and make it its current state.
<b>Rotation</b>		
<b>Pinpoint</b>		Orient turtle toward (x,y,z). Params : x, y, z (optionals, default = 0).
<b>PinpointRel</b>		Orient turtle toward pos+(x,y,z). Params : x, y, z (optionals, default = 0).
<b>@R</b>	<b>SetHead</b>	Set the turtle Heading and Up vector. Params : hx, hy, hz, ux, uy, uz (optionals, default=0,0,1, 1,0,0).
+	<b>Left</b>	Turn left around Up vector. Params : angle (optional, in degrees).
-	<b>Right</b>	Turn right around Up vector. Params : angle (optional, in degrees).
^	<b>Up</b>	Pitch up around Left vector. Params : angle (optional, in degrees).
&	<b>Down</b>	Pitch down around Left vector. Params : angle (optional, in degrees).
/	<b>RollL</b>	Roll left around Heading vector. Params : angle (optional, in degrees).
\	<b>RollR</b>	Roll right around Heading vector. Params : angle (optional, in degrees).
<b>iRollL</b>		Roll left intrinsically around Heading vector. Params : angle (optional, in degrees).
<b>iRollR</b>		Roll right intrinsically around Heading vector. Params : angle (optional, in degrees).
	<b>TurnAround</b>	Turn around 180deg the Up vector.
@v	<b>RollToVert</b>	Roll to Vertical : Roll the turtle around the H axis so that H and U lie in a common vertical plane with U closest to up
<b>Position</b>		
<b>@M</b>	<b>MoveTo</b>	Set the turtle position. Params : x, y, z (optionals, default = 0).
<b>MoveRel</b>		Move relatively from current the turtle position. Params : x, y, z (optionals, default = 0).
<b>@Dd</b>	<b>DivScale</b>	Divides the current turtle scale by a scale factor, Params : scale factor (optional, default = 1.0).
<b>@Di</b>	<b>MultScale</b>	Multiplies the current turtle scale by a scale factor, Params : scale factor (optional, default = 1.0).
<b>@D</b>	<b>SetScale</b>	Set the current turtle scale, Params : scale (optional, default = 1.0).
<b>Scale</b>		
<b>F</b>		Move forward and draw. Params: length , toradius.
f		Move forward and without draw. Params: length.
<b>@Gc</b>	<b>StartGC</b>	Start a new generalized cylinder.
<b>@Ge</b>	<b>EndGC</b>	Pop generalized cylinder from the stack and render it.
{	<b>BP</b>	Start a new polygon.
}	<b>EP</b>	Pop a polygon from the stack and render it.
<b>LineTo</b>		Trace line to (x,y,z) without changing the orientation. Params : x, y, z (optionals, default = 0).
<b>OLineTo</b>		Trace line toward (x,y,z) and change the orientation. Params : x, y, z (optionals, default = 0).

# The rewriting system



# Rule application

- Parametric rules

$A(x) \rightarrow B(2*x)$

apply to  $A(3)$  but not  $B(5)$  and not  $A(3, 5)$ .

$A(x) :$

*if*  $x < 3:$

**produce**  $B(2*x)$

apply to  $A(2)$  but not  $A(3)$ .

- Possibility to make production in multiple steps

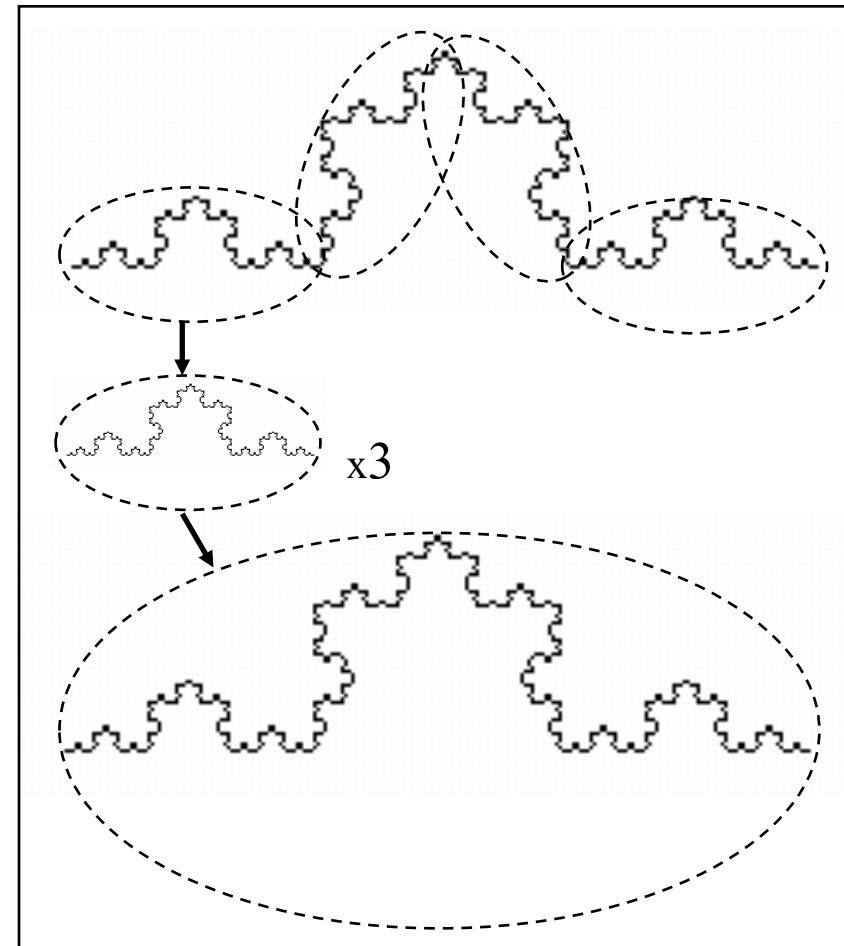
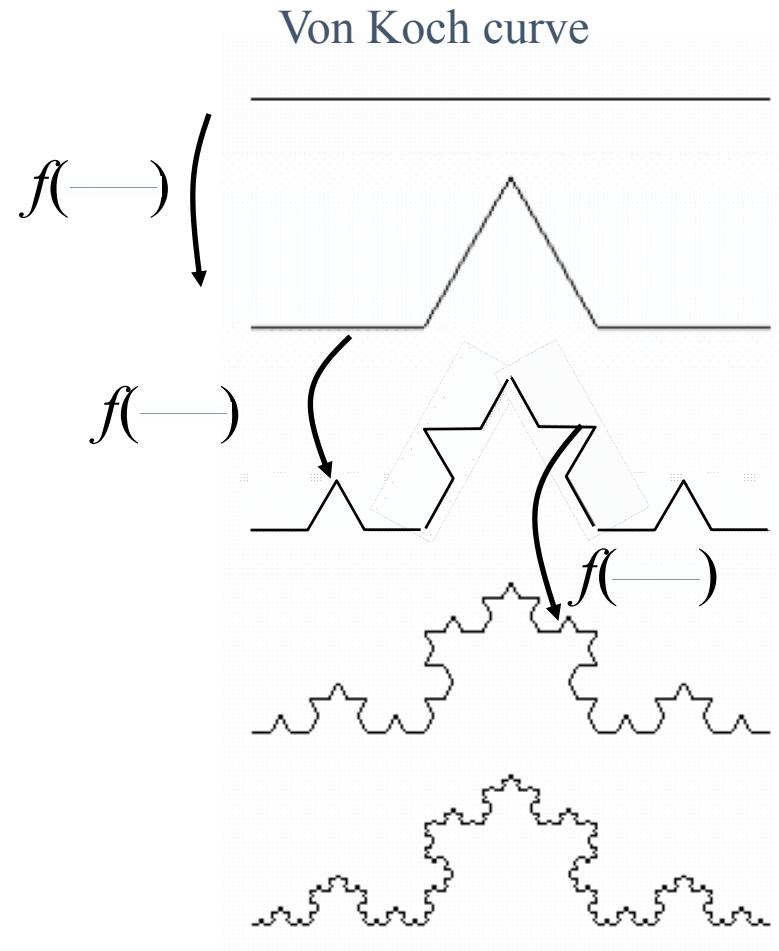
$B(x) :$

*for*  $i$  *in*  $range(x):$

**nproduce**  $F + (5)$

# Application to fractals

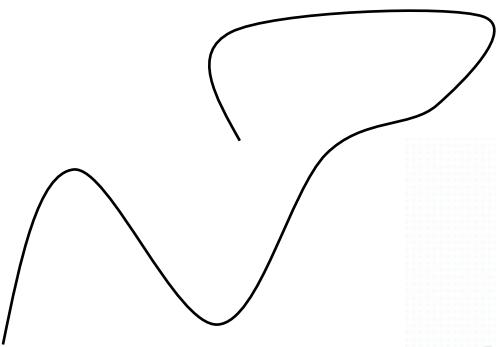
Mathematical object whose structure is invariant by scale change: Mandelbrot, B.B. (1983), W.N. Freeman



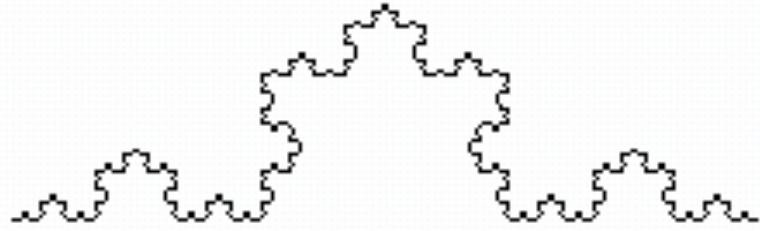
autosimilarité !

# Fractal dimension

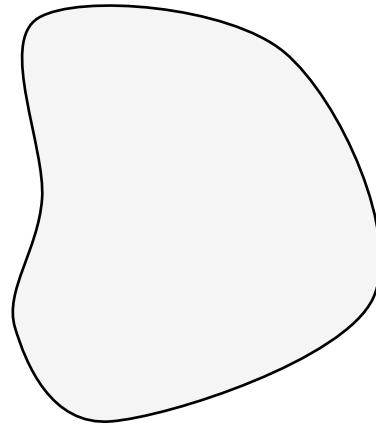
The fractal dimension of an irregular object can be not an integer. It quantifies complexity of fractals as a ratio of change in details to the change of scale.



$$D = 1$$



$$D = 1.262$$

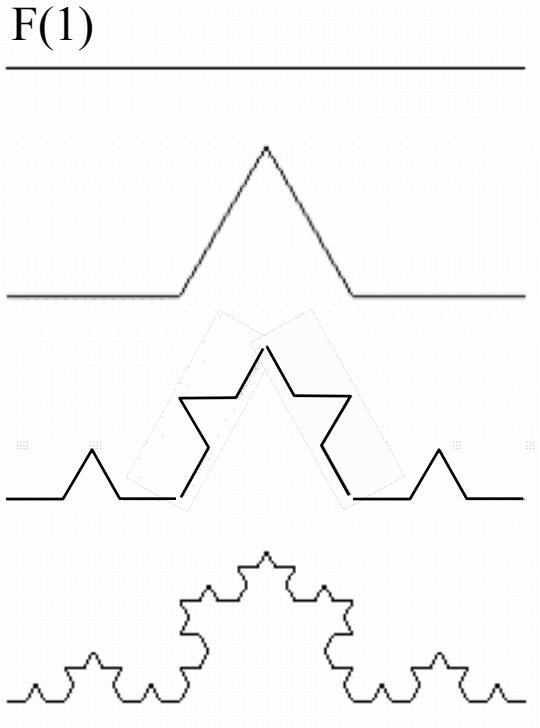


$$D = 2$$

When the scale of measured is divided by 3, its length is multiply by 4.

$$D = \log 4 / \log 3$$

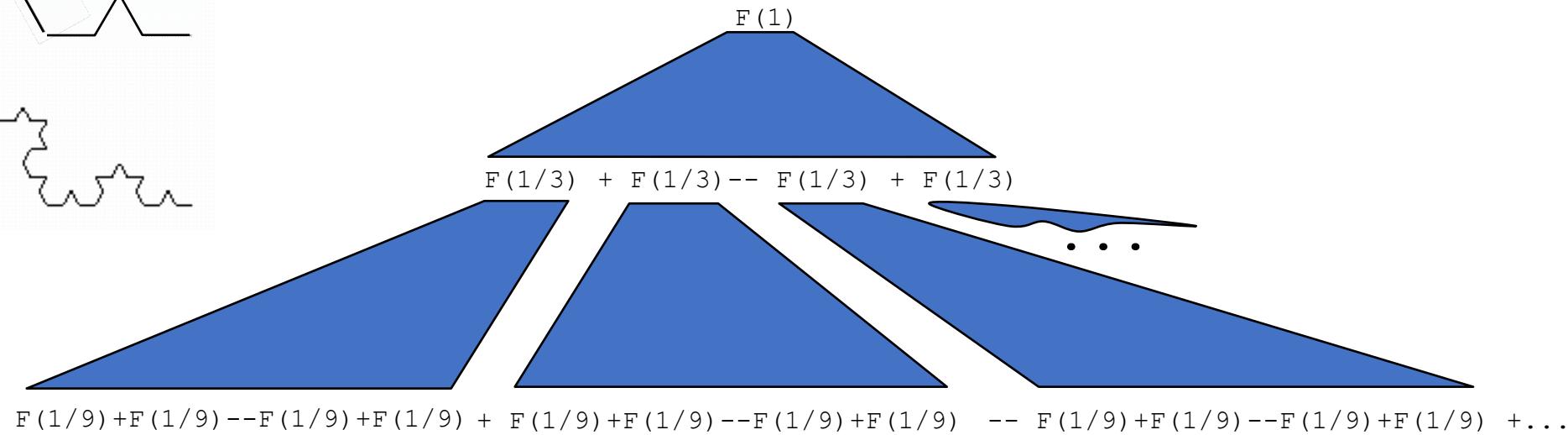
# L-Systems for simple fractals



$$G = (\{F, +, -\}, \{F(1)\}, P)$$

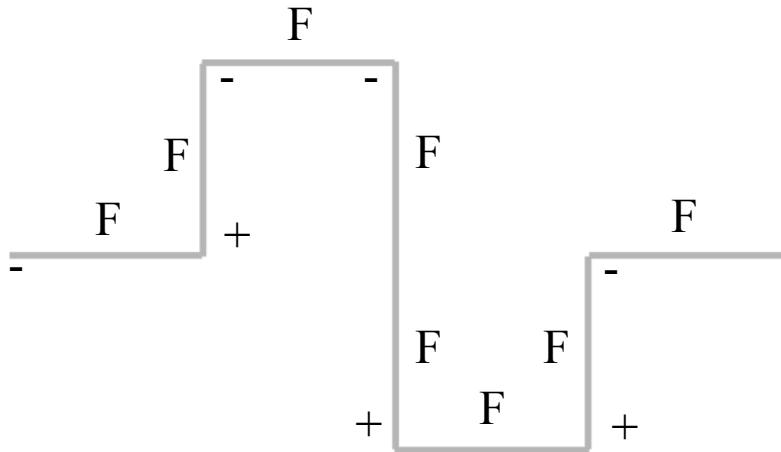
Parametric rule de P:

$$F(x) \rightarrow F(x/3) + F(x/3) -- F(x/3) + F(x/3)$$



# Minkowski curve

*a.k.a the Minkowski sausage*



The Axiom:

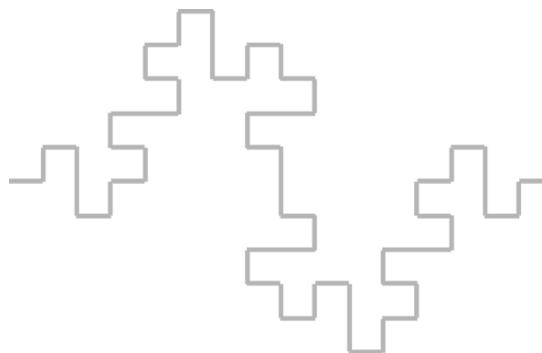
-F

Production, or re-writing rule:

$F \rightarrow F+F-F-FF+F+F-F$

After one step:

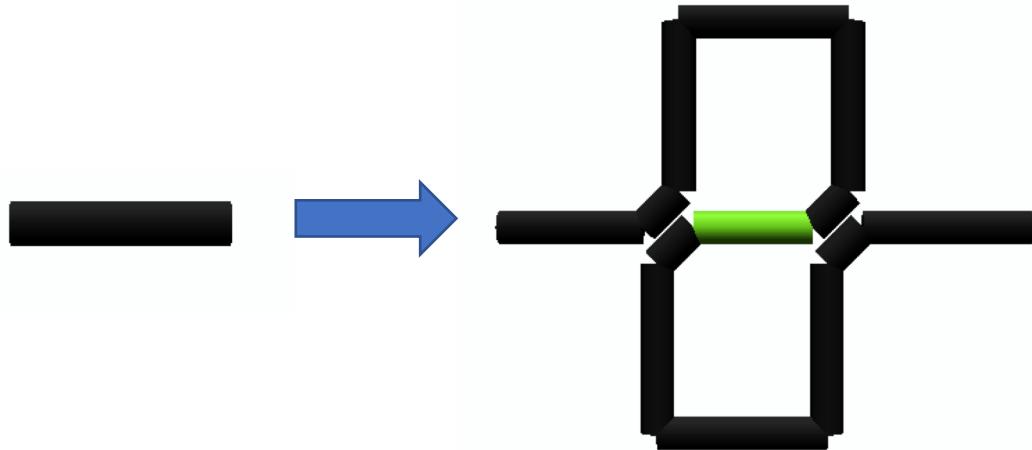
$-F+F-F-FF+F+F-F$



After two steps:

$$\begin{aligned} & - F+F-F-FF+F+F-F + F+F-F-FF+F+F-F - F+F-F-FF+F+F-F \\ & - F+F-F-FF+F+F-F F+F-F-FF+F+F-F + F+F-F-FF+F+F-F \\ & + F+F-F-FF+F+F-F - F+F-F-FF+F+F-F \end{aligned}$$

# Exercises



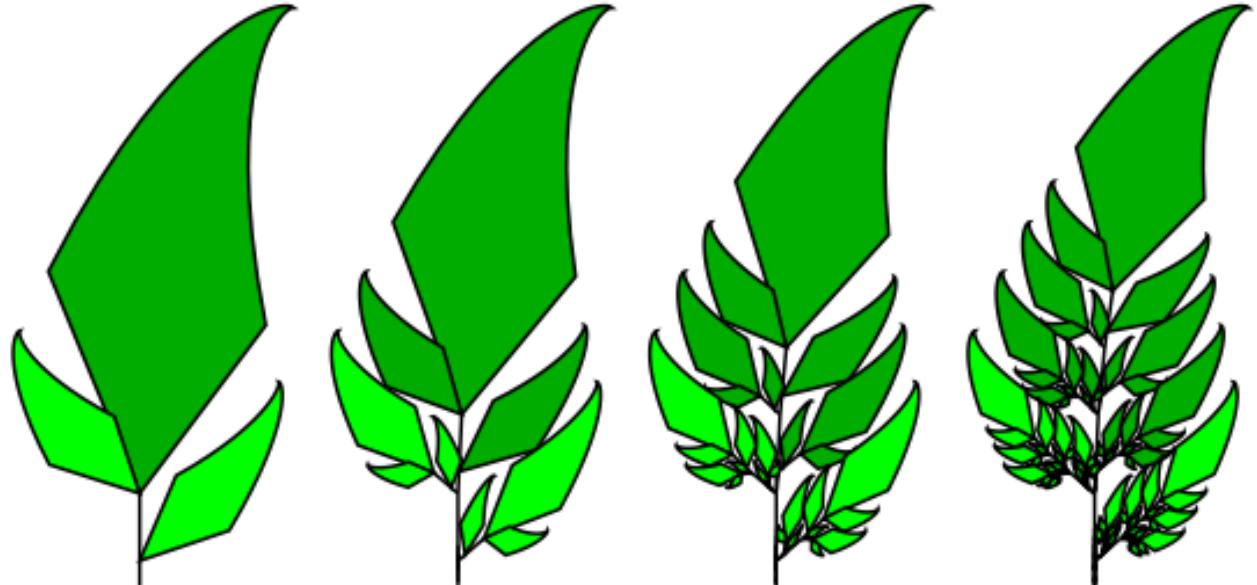
The peano curve



The cantor dust

# Exercise : Barnley fern

Recursive fractal construction



# Exercise : Barnley fern

Recursive fractal construction



R = 1.5

**Axiom:** \_ (0.01) , (2) A(1)

**derivation length:** 16

A(s) --> F(s) - (5) [+B(s/R)] F(s) - (5) [/ (180) +B(s/R)] F(s) A(s/R)

B(s) --> A(s/R)



# Interpretation

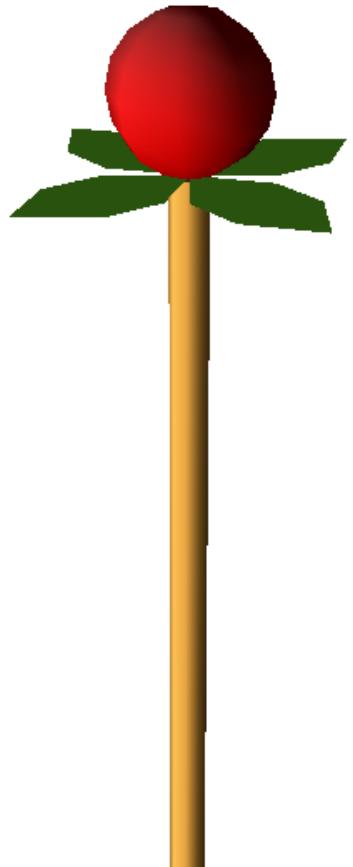
- Interpretation rule of module into geometrical symbol. Can be recursive.

**interpretation:**

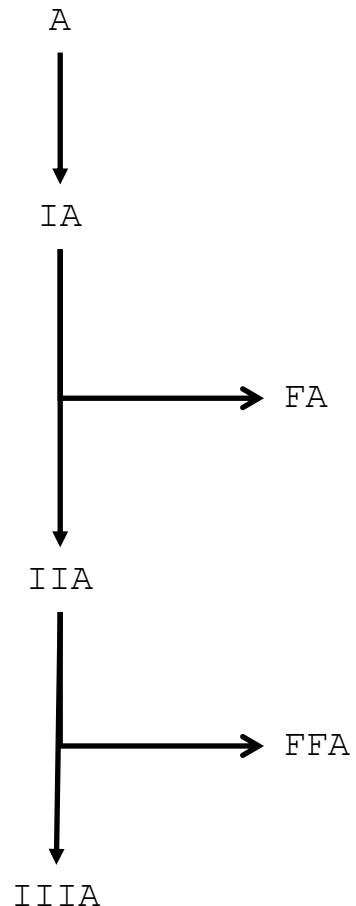
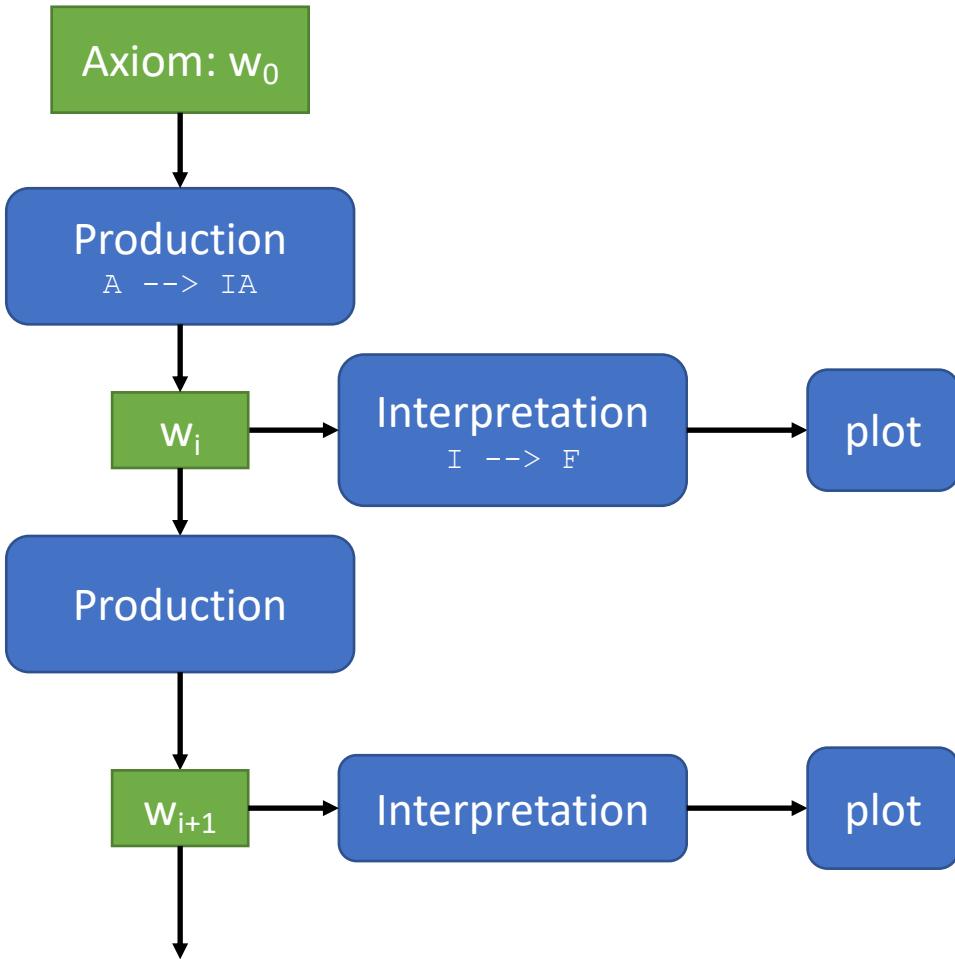
**maximum depth:** 2

**A(x) --> F(5) [, (2)/(90)L/(90)L/(90)L/(90)L, (3)f(0.4)@O(0.4)]**

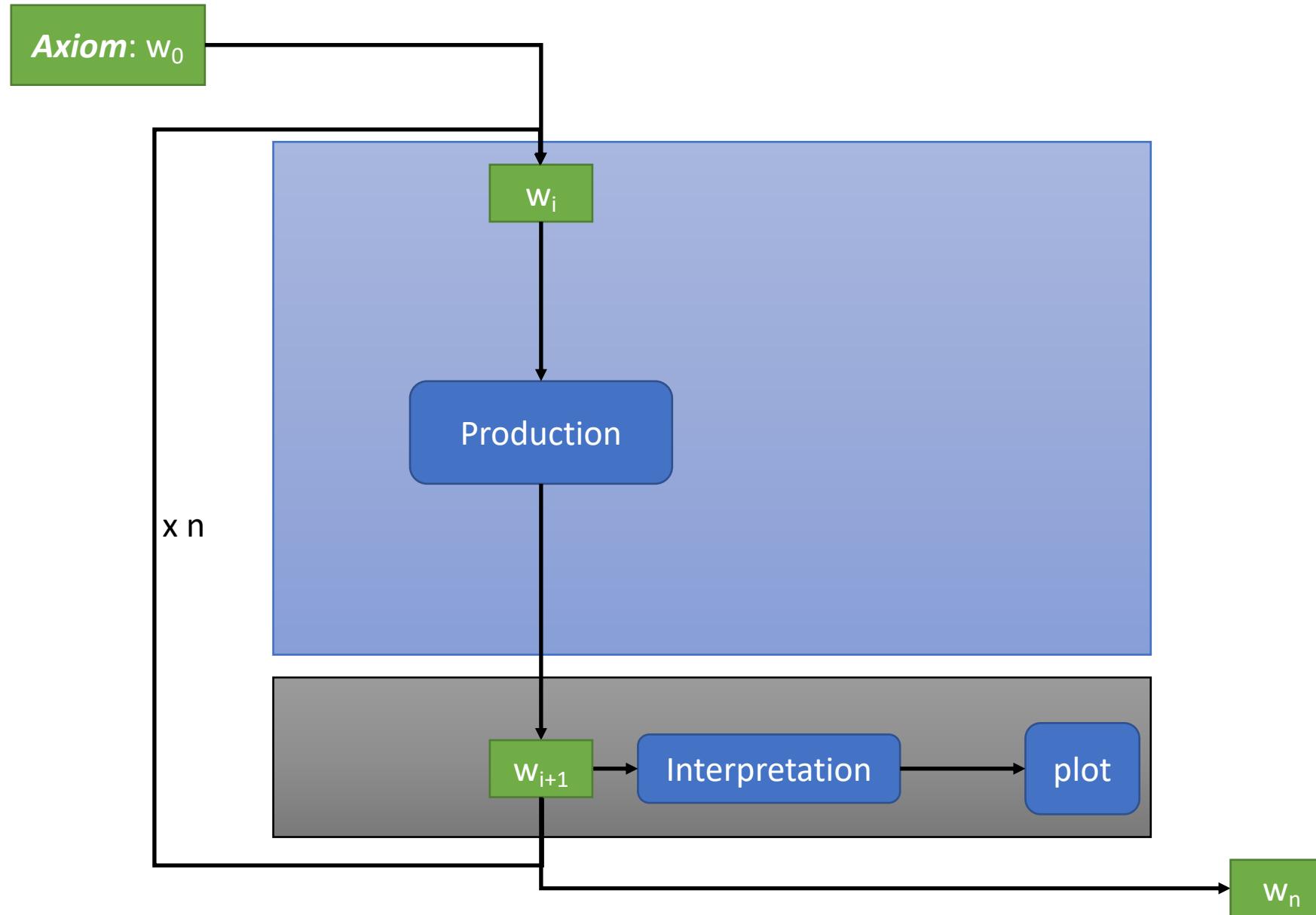
**L --> [+ (90)/(90)~1]**



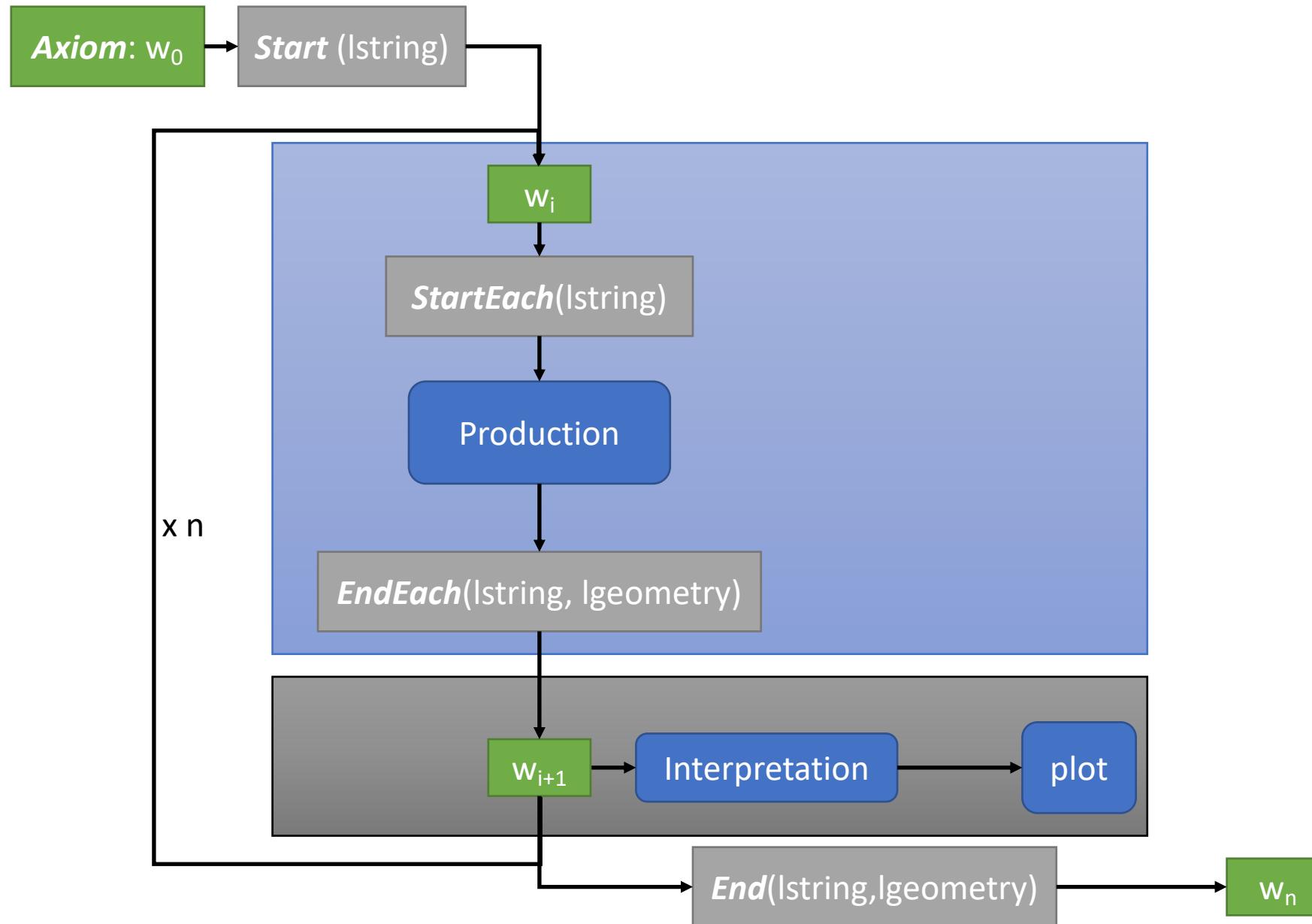
# Simulation Pipeline



# Simulation Pipeline (more details)



# Simulation Pipeline (more details)



# Controlling Simulation

```
def Start(lstring):  
    pass  
def End([lstring[, scene]]):  
    pass  
def StartEach(lstring):  
    pass  
def EndEach([lstring[, scene]]):  
    pass
```

```
def StartEach():  
    if isForward(): backward()  
    else: forward()
```

```
def StartEach():  
    if getIterationNb() % 2: useGroup(3)  
    else: useGroup(2)
```

production:

A --> BA

**Group** 2:

B --> C

**Group** 3:

B --> D

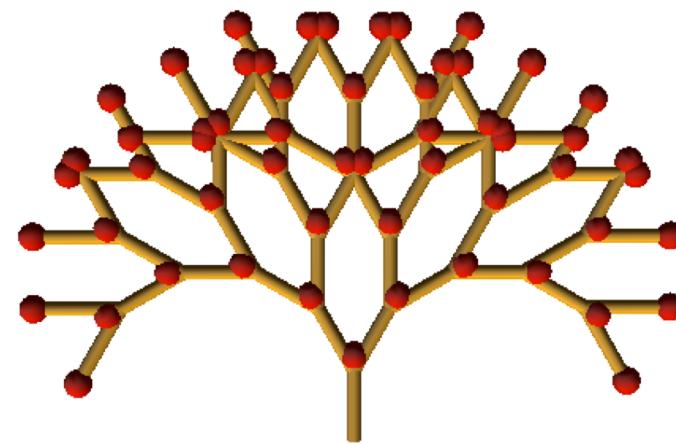
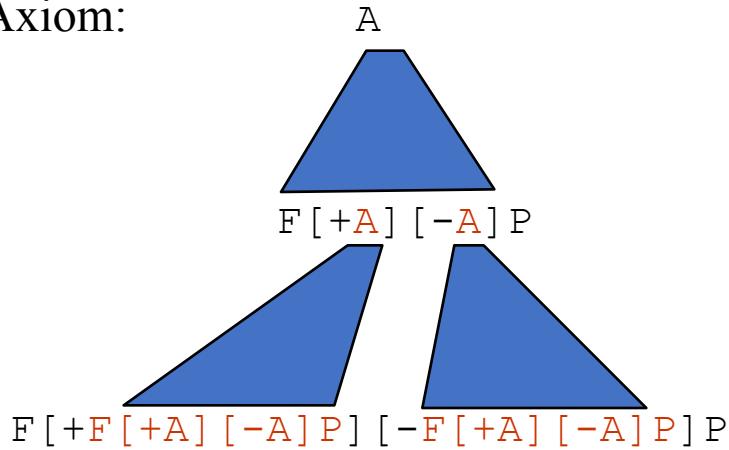
**EndGroup**

# Rewriting trees

Rules:

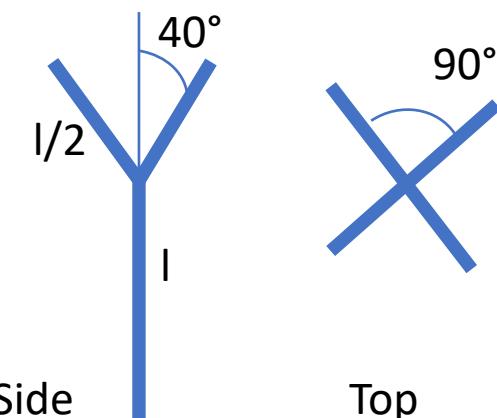
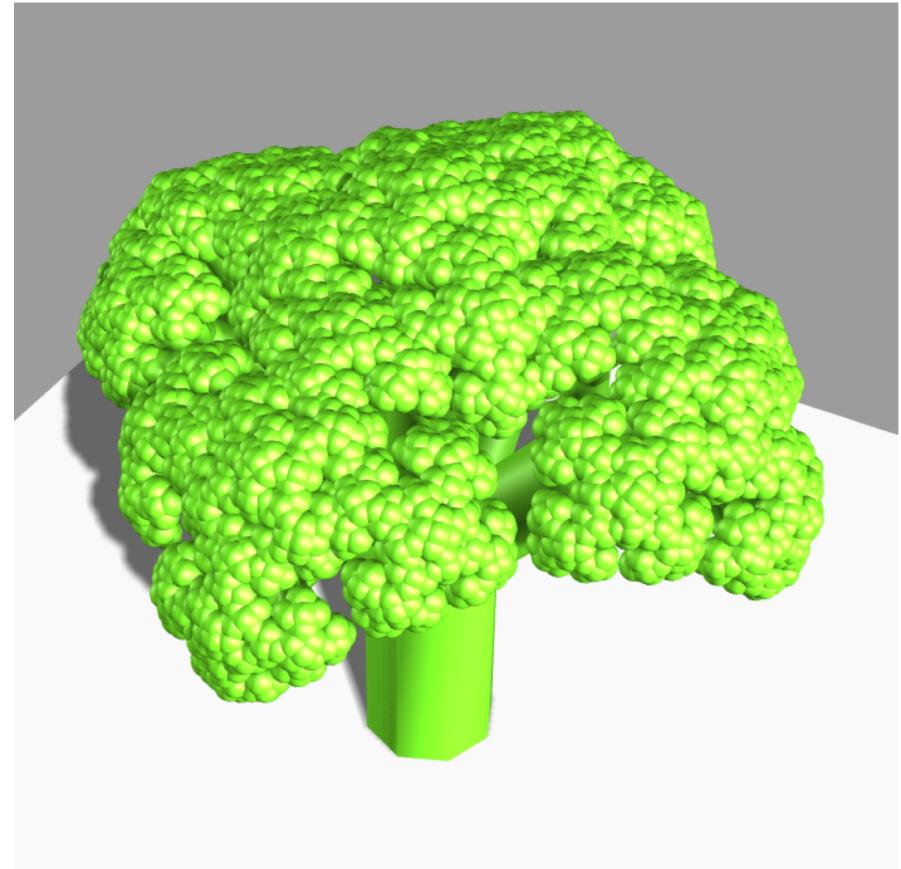
$$A \dashrightarrow F [+A] [-A] P$$

Axiom:



# Exercise

- Generate a broccoli
  - Tree structure with 4 children internode at each node
    - Insertion angle: 40
    - 90 degree between each children
    - Width that depend on the order of ramification
      - Scaling factor of 0.5 between each order
    - Finish structure with sphere with size double from terminal internode



# Stochastic L-systems

- Insertion of stochastic productions

```
from random import *
```

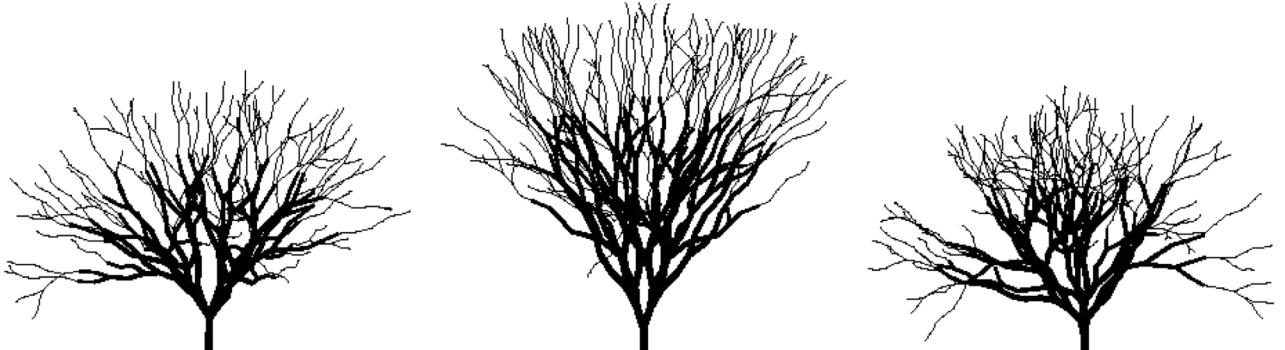
Axiom: A

production:

A :

```
    if random() < 0.5: produce B
```

```
    else produce C
```

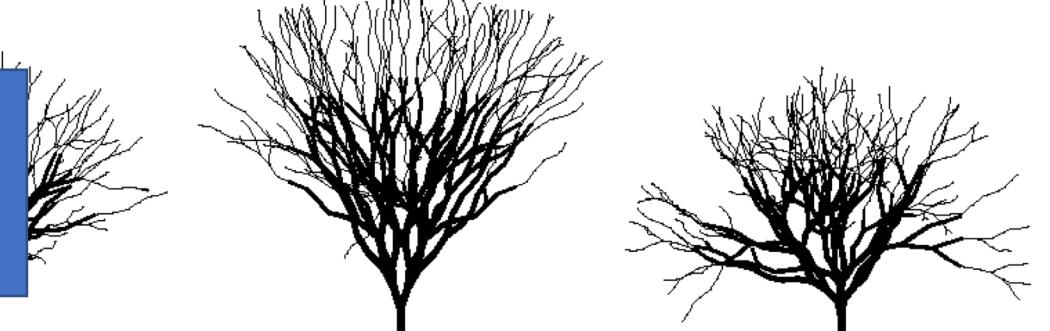


# Stochastic L-systems

- Insertion of stochastic production

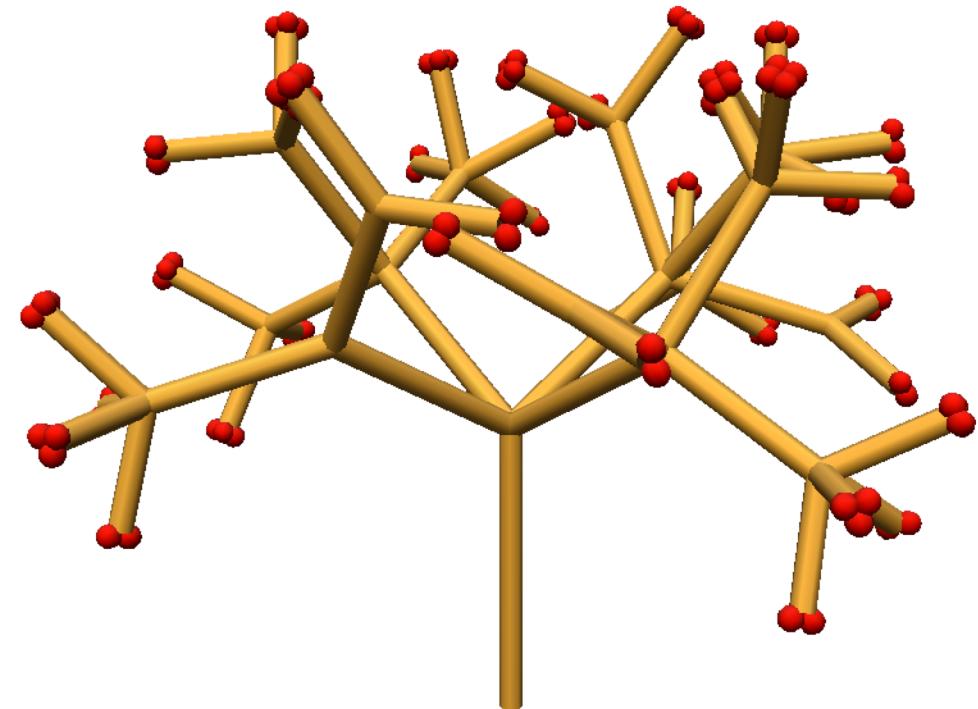
```
from random import *
seed(50)
Axiom: A
production:
A :
    if random() < 0.5: produce B
    else produce C
```

Control of the random seed



# Random trees

- Generate a tree such as at the end of each segment, a random number of lateral segment children (between 2 and 4) are generated.
  - Insertion angle: 60
  - Divergence angle between segments at the same node: proportional to number of segments i.e.  $360/nb$



# Simulations of continuous development

- Use infinitesimal increments  $dt$  or  $dx$

```
phyllochrone = 1  
maxgrowthtime =1  
dt = 0.1
```

*Axiom:* **A(0)**

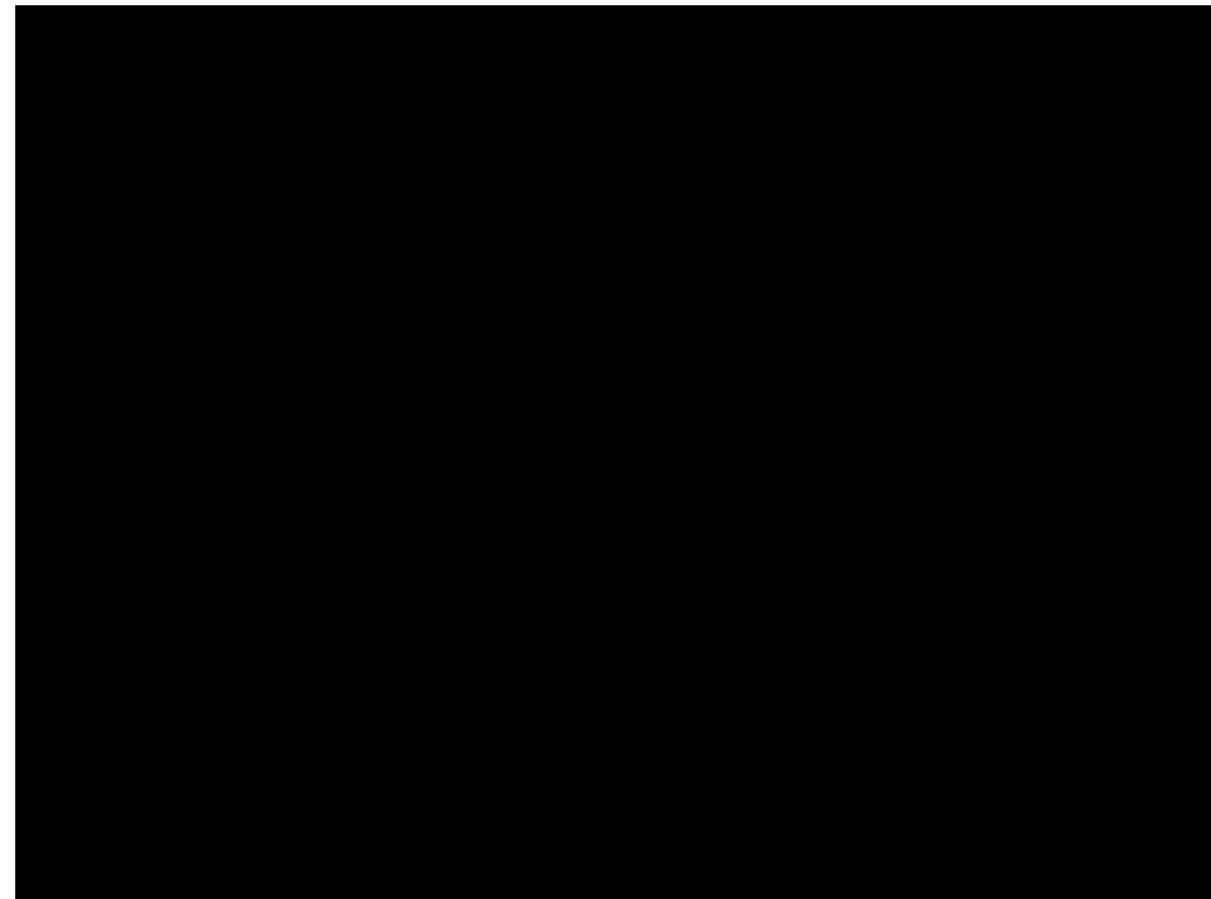
**A(t) :**

```
if t <= 0 : produce I(0)/(137.5) L(0) A(0)  
else: produce A(t+dt)
```

```
I(t) --> I(min(maxgrowthtime,t+dt))  
L(t) --> L(min(maxgrowthtime,t+dt))
```

**interpretation:**

```
I(t) --> F(t * Li)  
L(t) --> [&(90*t), (2) ~l(t*Lf)]
```



# Pruning

# Information transfer and signal



# Contextual L-systems

- Left and Right Contexts

$$A < S > B \rightarrow C$$

apply on  $^A S B$

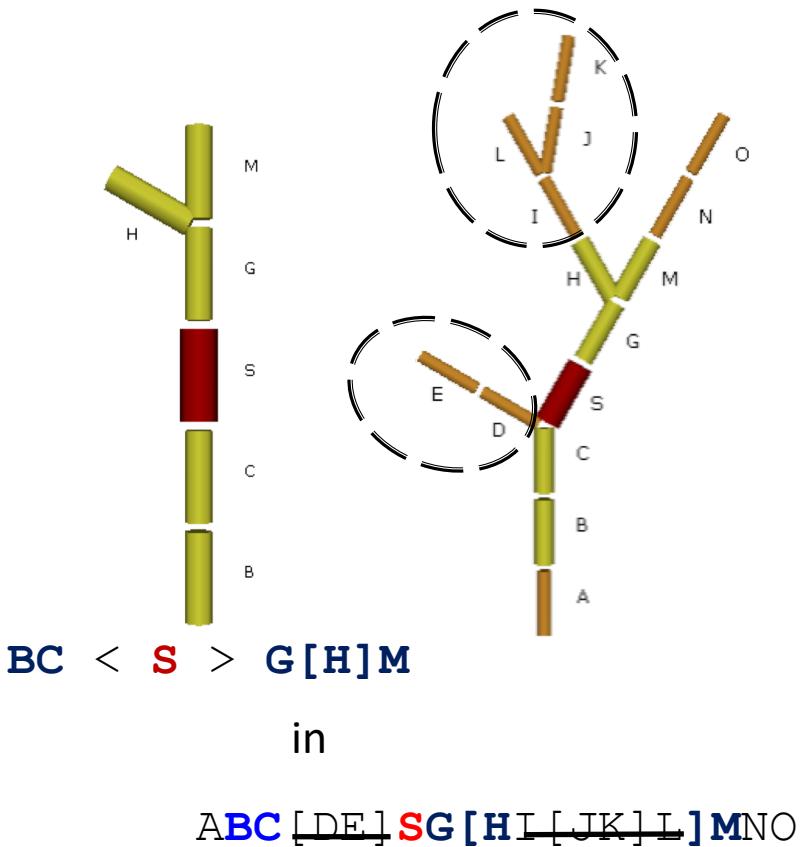
- Parametric contexts to retrieve information

$$S(x) < S(y) \rightarrow S(f(x, y))$$

- Possibility to ignore some symbols (for instance geometrical ones)

ignore: + - / \

# Context application within trees



# Information transfer

Contextual rules:

$$B < A \quad \dashrightarrow \quad B$$

$$B[A]A[A]A[A]A$$

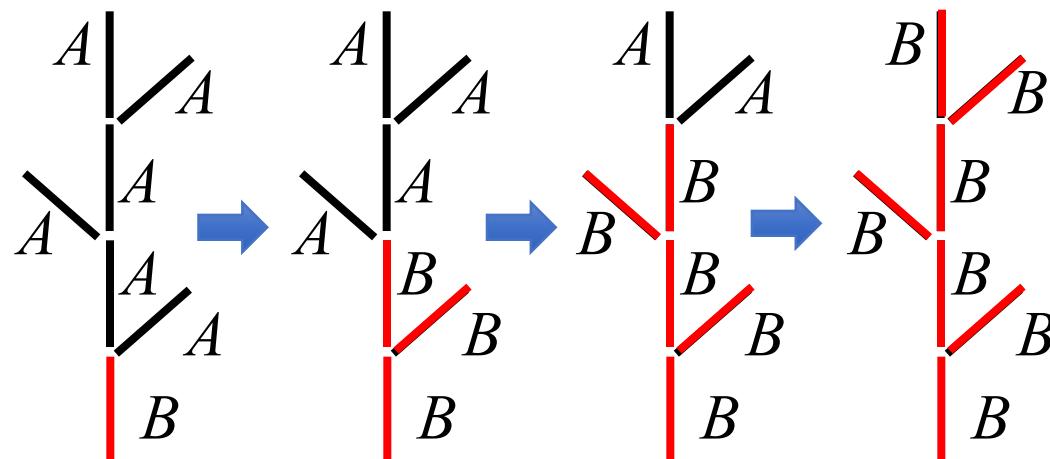
$$B[B]B[A]A[A]A$$

$$B[B]B[B]B[A]A$$

$$B[B]B[B]B[B]B$$

Axiom:

$$B[A]A[A]A[A]A$$



Requires n iterations

# Information transfer

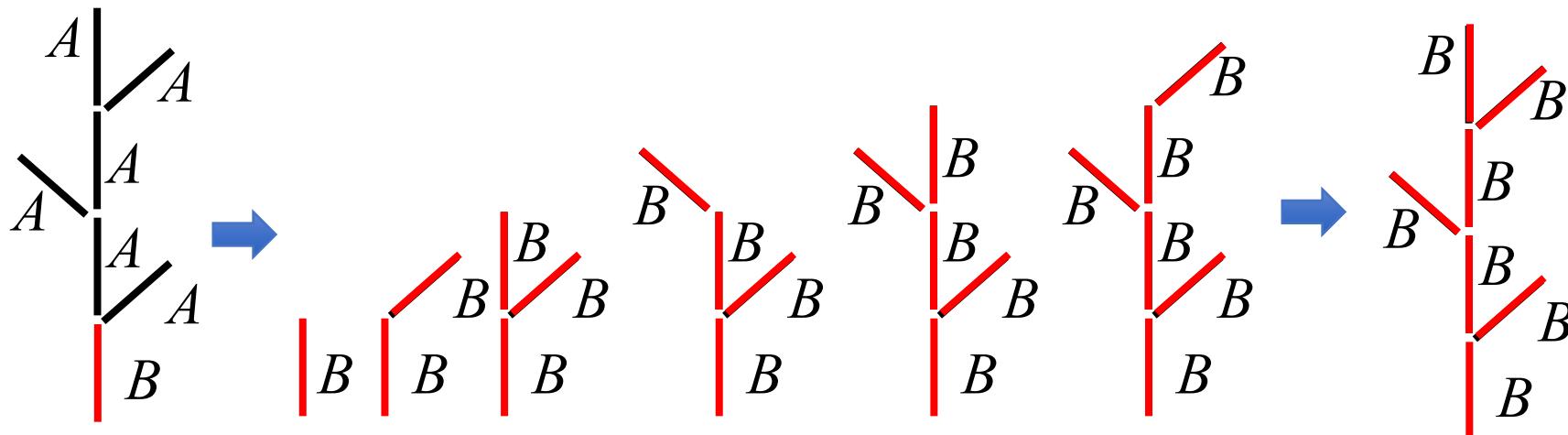
Contextual rules:

$$B \ll A \quad \dashrightarrow \quad B$$

Axiom:

$$B[A]A[A]A[A]A$$

$$\begin{aligned} & B \\ & B[ \\ & B[B] \\ & B[B]B \\ & \dots \\ & B[B]B[B]B[B]B \end{aligned}$$



Requires 1 iterations

# Information transfer

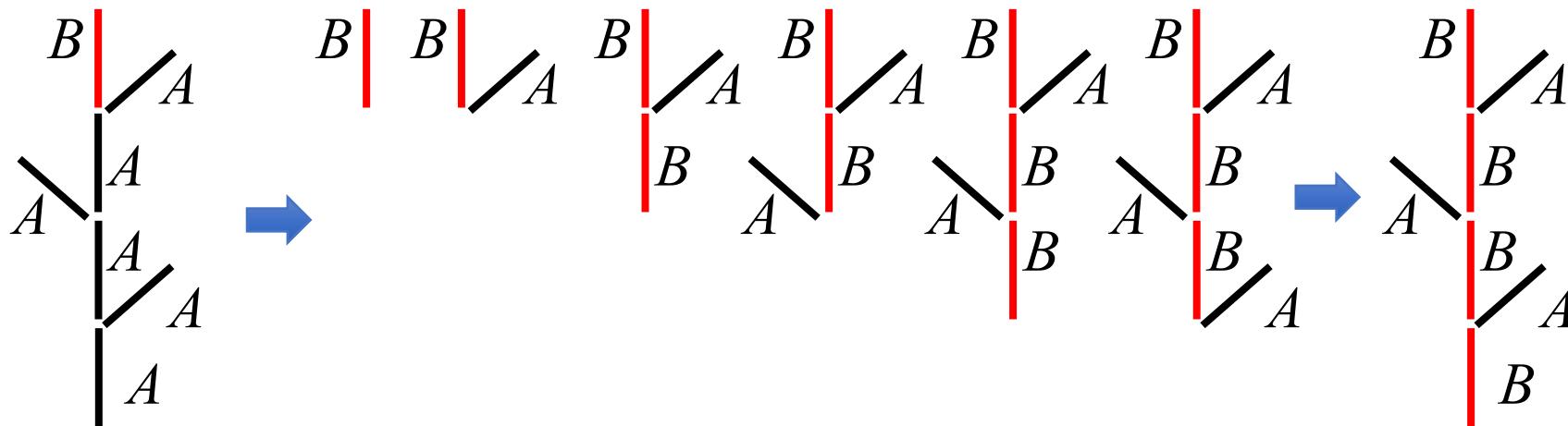
Contextual rules:

$$A \gg B \quad \dashrightarrow \quad B$$

$$\begin{array}{c} B \\ ] B \\ [ B ] B \\ B [ B ] B \end{array}$$

Axiom:  $A[A]A[A]A[A]B$

$$\dots \\ B[B]B[B]B[B]B$$

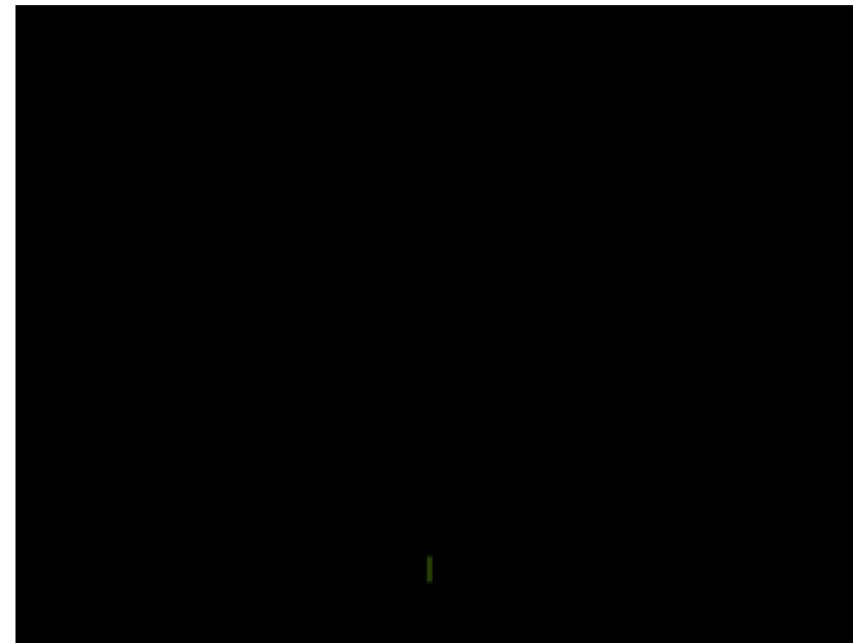


- Backward rewriting mode : from leaf to root
- Not symmetrical

# Signal et Flowering



# Signal et Flowering



*Mycelis muralis*

- Complete the following L-systems to simulate signal propagation

## Exercise

Delay, LDelay = 5, 10

T = 120

**Axiom:** R(T) I(0) A(Delay, 0)

$$R(t) \rightarrow R(t-1)$$

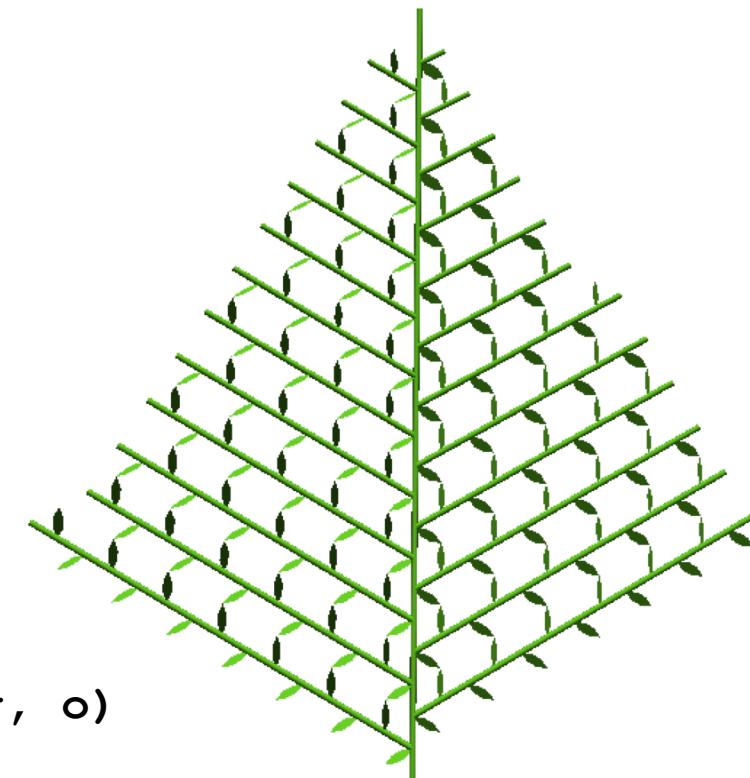
**derivation length:** 150

**production:**

**consider:** R I A B

I(x) < A(d,o) :

```
# produce flower
if x == 1 : produce W
# continue to growth
elif d > 0: produce A(d-1, o)
else:
    # produce lateral apex or leaf
    if o == 0: nproduce [ +(60) A(0,o+1) ]
    else : nproduce [ +(60) / (60) ,(2) ~1
produce I(0) / (180) A(Delay if o == 0 else LDelay, o)
```



- Complete the following Lsystems to simulate signal propagation

Delay, LDelay = 5, 10

T = 120

**Axiom:** R(T) I(0) A(Delay, 0)

**derivation length:** 150

**production:**

**consider:** R I A B

I(x) < A(d,o) :

# produce flower

if x == 1 : **produce** W

# continue to growth

elif d > 0: **produce** A(d-1, o)

else:

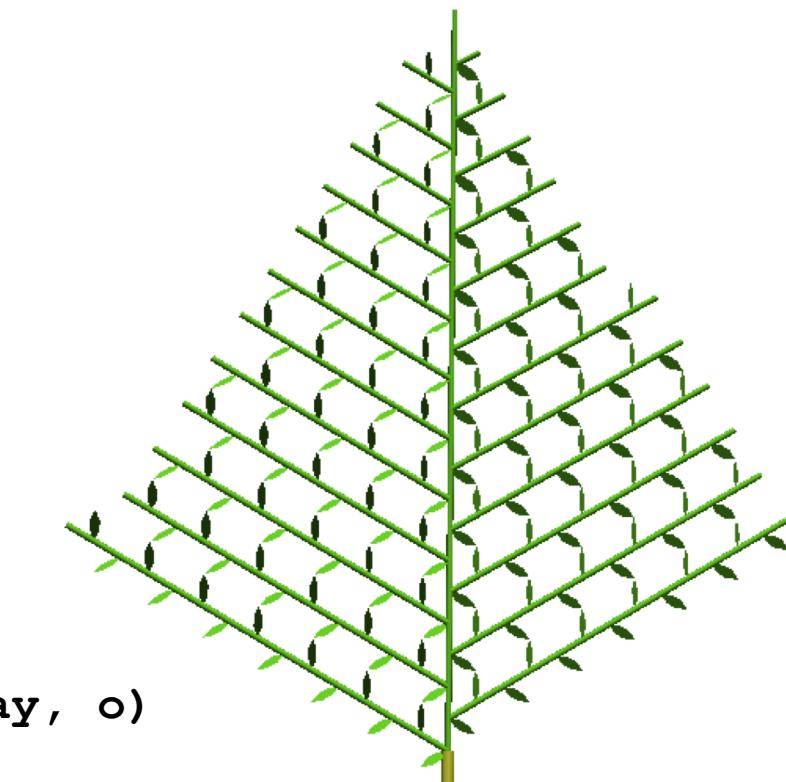
# produce lateral apex or leaf

if o == 0: **nproduce** [ +(60) A(0,o+1) ]

else : **nproduce** [ +(60) / (60) ,(2) ~1

**produce** I(0) / (180) A(Delay if o == 0 else LDelay, o)

## Exercise



- Complete the following Lsystems to simulate signal propagation

Delay, LDelay = 5, 10

T = 120

**Axiom:** R(T) I(0) A(Delay, 0)

**derivation length:** 150

**production:**

**consider:** R I A B

I(x) < A(d,o) :

# produce flower

if x == 1 : **produce** W

# continue to growth

elif d > 0: **produce** A(d-1, o)

else:

# produce lateral apex or leaf

if o == 0: **nproduce** [ +(60) A(0,o+1) ]

else : **nproduce** [ +(60) / (60) ,(2) ~1

**produce** I(0) / (180) A(Delay if o == 0 else LDelay, o)

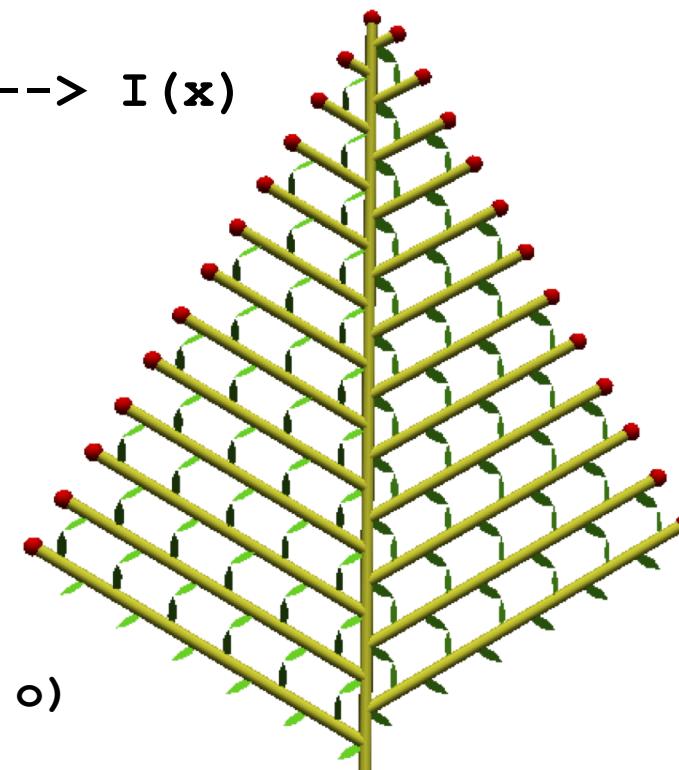
R(t) --> R(t-1)

R(t) < I(x) :

# Wait for the root to propagate

if t < 0: **produce** I(1)

I(x) < I(s) --> I(x)



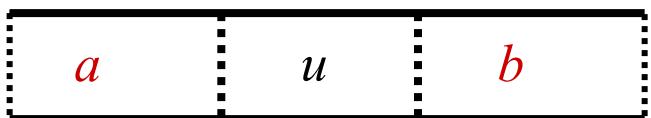
## Exercise

# Hormone diffusion

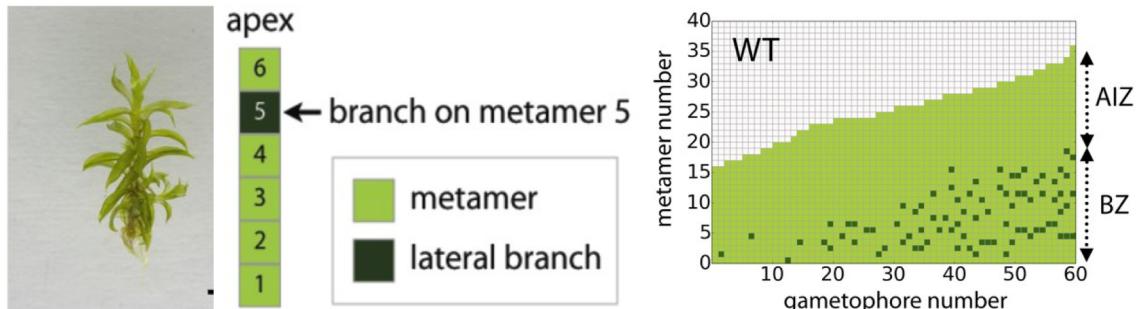
Diffusion of hormones using conservation

law:

$$\frac{\partial u}{\partial t} = \alpha \Delta u + \beta - \gamma u$$



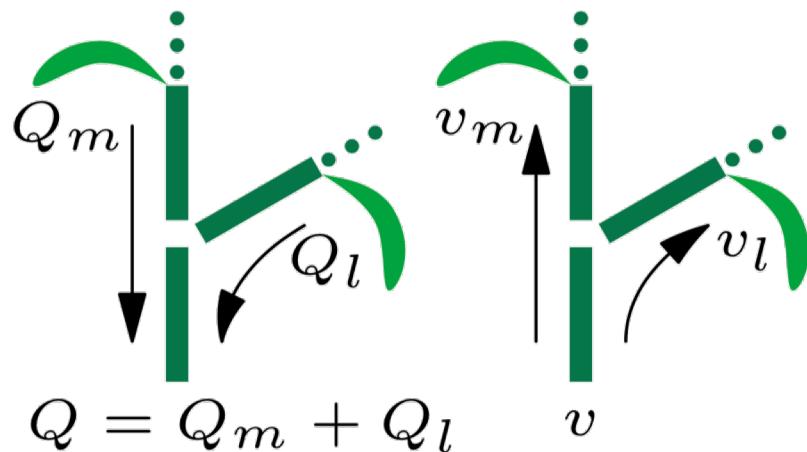
```
I(a) < I(u) > I(b) :  
produce I(u + (a+b-2*u)*alpha +beta - u*gamma)
```



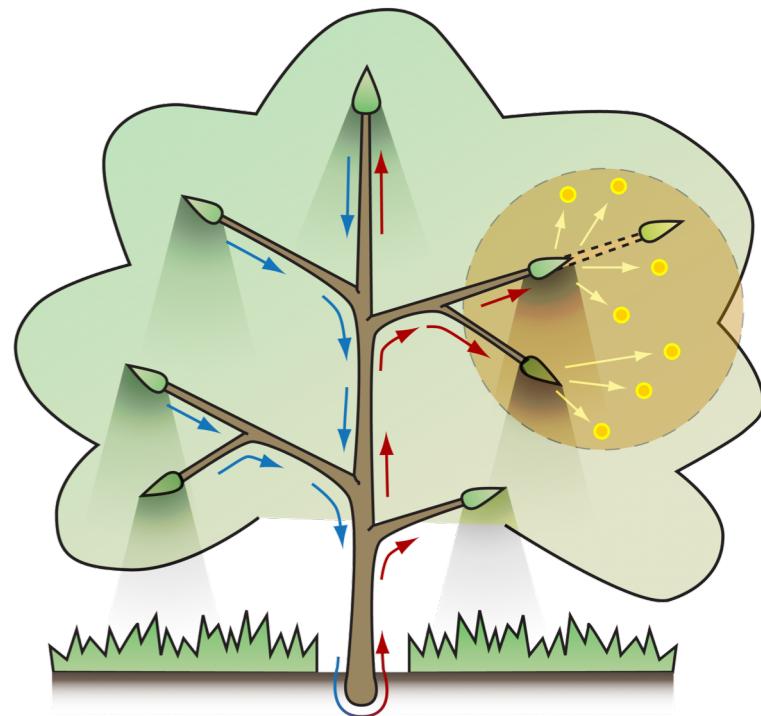
(Coudert et al., eLife, 2015)

# Transport of nutrients

- Model of Borchert-Honda, 84:
  - Simulating flows of resources (photosynthates or water and mineral)
  - Apical control is determined with a parameter in resources redistribution.



$$v_m = v \frac{\lambda Q_m}{\lambda Q_m + (1 - \lambda) Q_l}$$

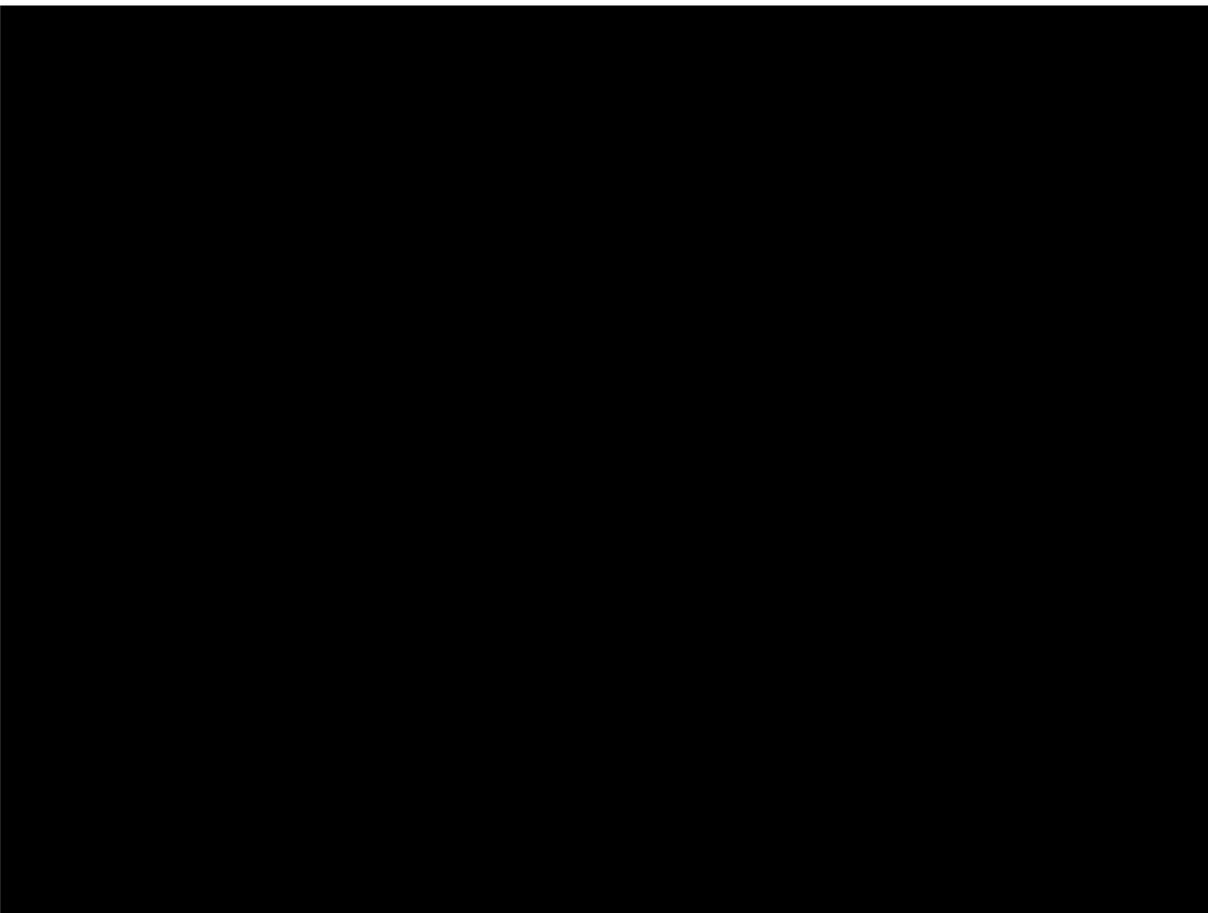


```
I(t, v, Q) >> [I(tl, vl, Ql)]I(tm, vm, Qm) :  
produce I(t, v, Qm+Ql)
```

```
I(tp, vp, Qs) << I(t, v, Q) :  
Qs = Qp - Q  
l = lambda if t == Apical else (1-lambda)  
vm = vp * (l*Q) / (l*Q + (1-l)*Qs)  
produce I(t, vm, Q)
```

# Transport of water and carbon

- Coupling of models of aerial and root part of a tree structure
  - Flow of photosynthate control root dev and mineral uptake control aerial dev.



†

‡

# Environment

# Environmentally sensitive L-systems

- Request symbols

?P(v) ?H(v)  
?U(v) ?L(v)  
?F(p, h, u, l)

- Example

Axiom: A

production:

A --> [+ (60)B] [-(60)B] F ?P A

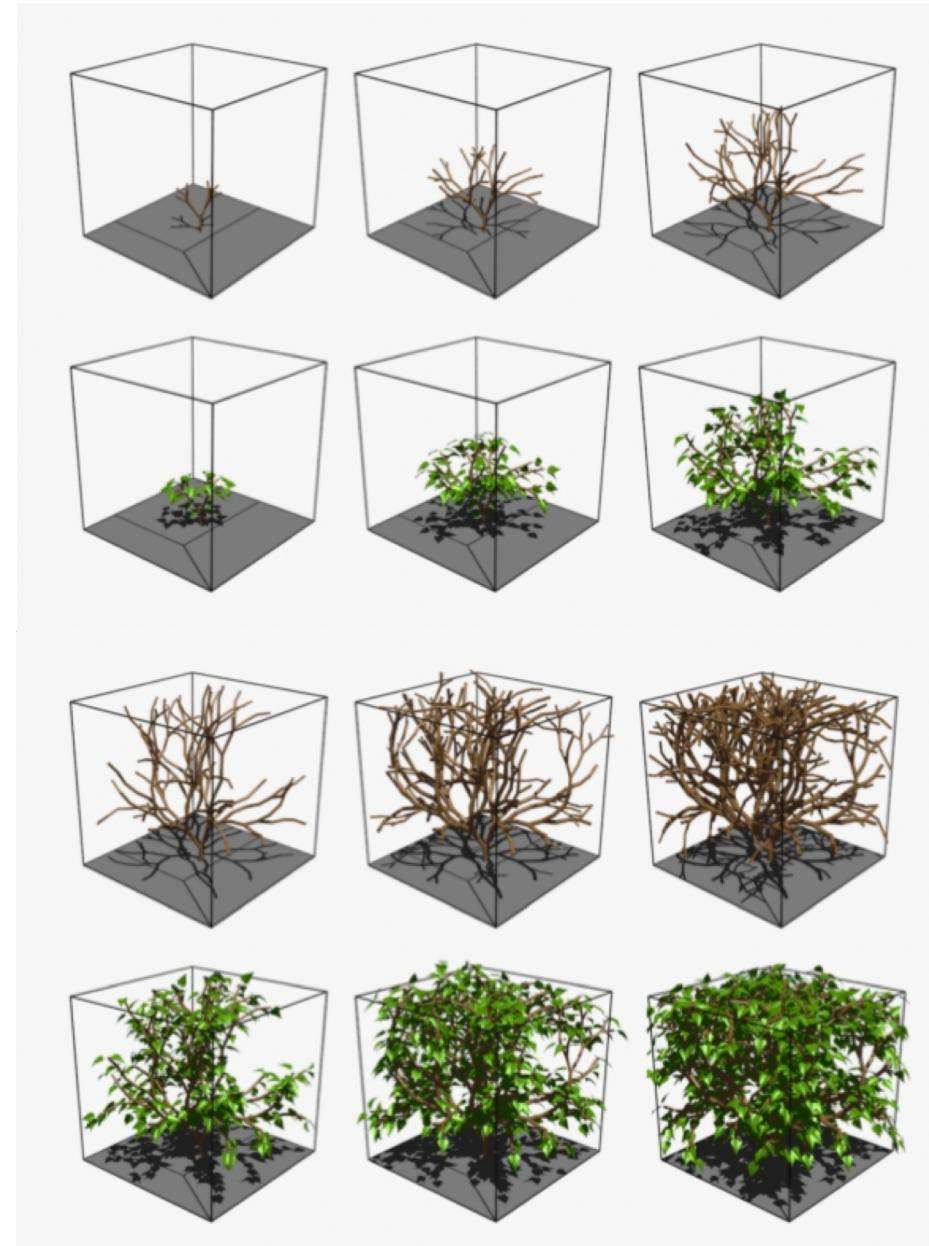
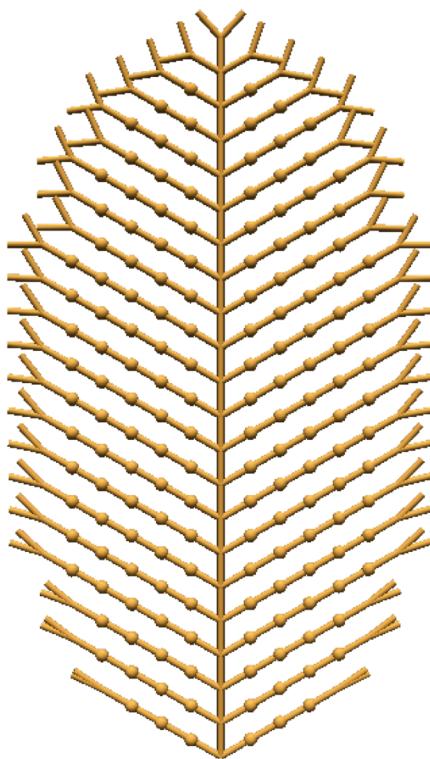
B --> F ?P @O(0.2)B

?P(p) :

if  $4 * p.y * p.y + (p.z - 10) ^ 2 > 100$ :

produce [+ (2 \* p.z) F] [-(2 \* p.z) F] %

else: produce \*



(Prusinkiewicz et al., 1994)

# Local interaction with environment

- Use of a structure to represent space

```
class Grid:  
    def __init__(self, size = (10,10,10))  
        self.values = numpy.random.random(size))  
    def getvalue(self, pos3d): ...  
    def setvalue(self, pos3d, value):...
```

```
grid = Grid()
```

Axiom:  $A(0) ?P$

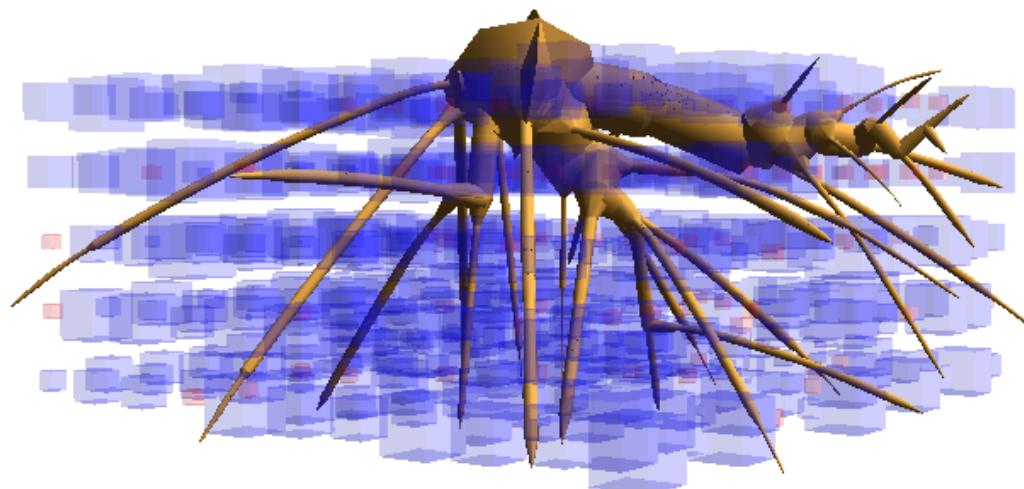
Request position in environment

$A(x) ?P(v)$ :

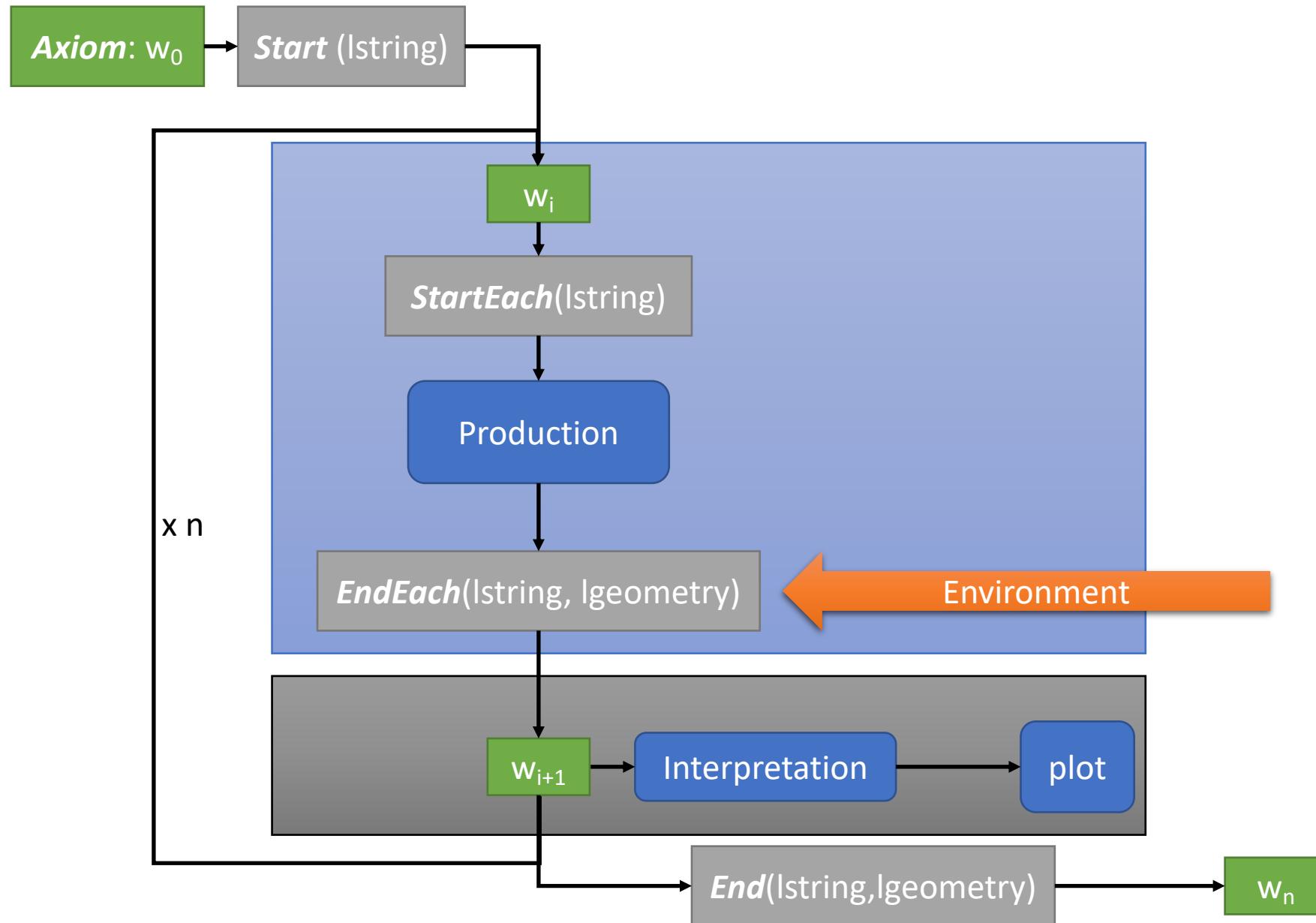
```
water = grid.getValue(v)  
water -= dw  
x += dw  
grid.setValue(v, water)
```

Change value in environment

Global structure to represent environment



# Simulation Pipeline



# Global interaction with environment

- Light Interaction. Depend on the entire geometry of the plant

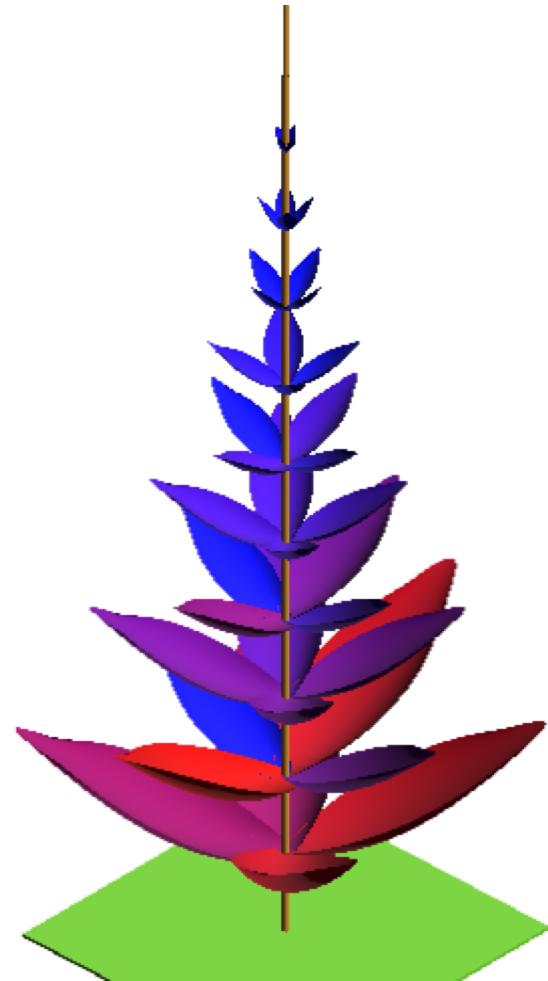
```
from openalea.fractalanalysis.light.directLight import diffuseInterception
module Leaf(t, carbon, light)
def EndEach(lstring, lscene):
    lightvalues = diffuseInterception(lscene)
    for modid, light in lightvalues.items():
        if lstring[modid].name == 'Leaf':
            lstring[modid].light = light
return lstring
```

Compute intercepted light

Report light value in the string

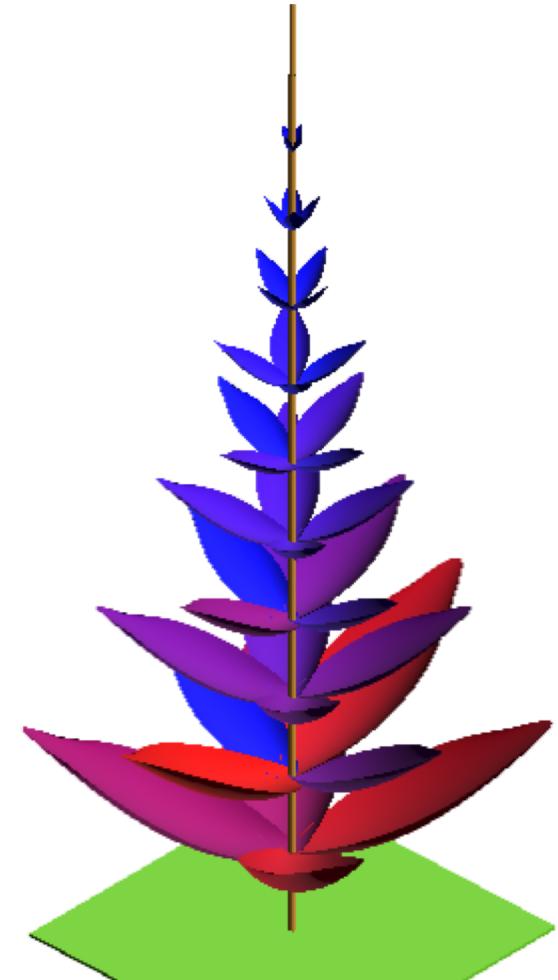
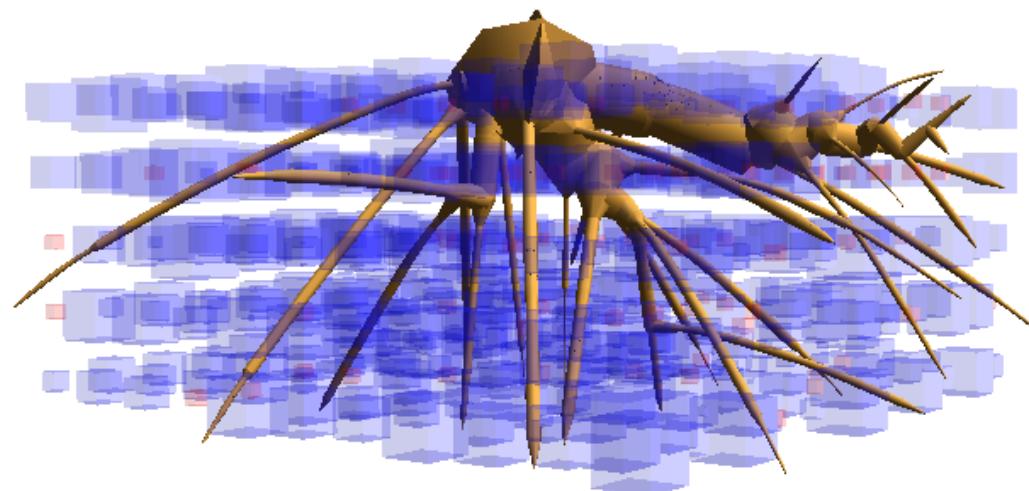
For module `modid`, set its `light` parameter to the `light` value.

- `diffuseInterception` return of dictionary of id and cumulated value of intercepted light.
- `directInterception` is doing the same with a given set of light directions.

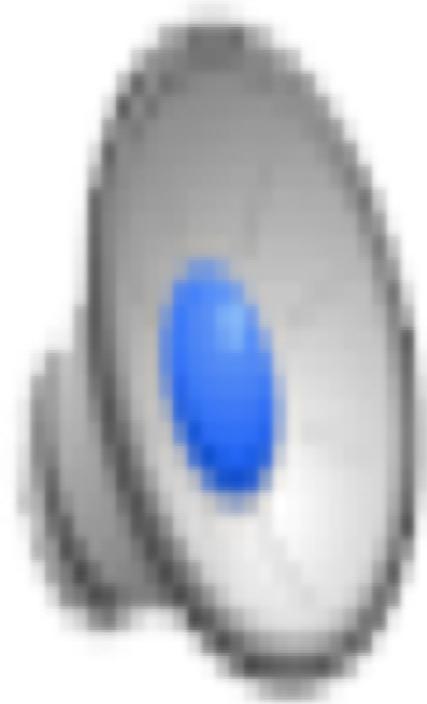


# Exercise

- Test the two environmental models



Interactive  
edition based  
on space  
colonization



Thanks for you attention

