

STARTR ROBOTICS

WEEK 5:

INPUTS AND OUTPUTS

FOR MORE ACTIVITIES, DOWNLOAD THE OFFICIAL "ROBOT IN A CAN GUIDEBOOK" AT ROBOTINACAN.COM/SUPPORT (CLICK ON THE "GUIDEBOOK" BUTTON)

WHAT DO WE CALL IT WHEN A ROBOT SENDS
AND RECEIVES INFORMATION?

AND

WHAT CAN A ROBOT USE TO PERCEIVE THE
WORLD AROUND IT?

Lesson by Lindsey Renault
Learn more at STARTR.CA



WHAT CAN A ROBOT USE TO INTERACT WITH THE
WORLD AROUND IT? (HINT: IF YOU DON'T KNOW
WHAT ONE OF THESE WORDS MEANS, TRY
GOOGLING IT ;D)

- A) STEPPERS
- B) SERVOS
- C) LIGHTS
- D) ACTUATORS
- E) HYDRAULICS
- F) THRUSTERS
- G) ALL OF THE ABOVE
- H) NONE OF THE ABOVE

FUN FACT!

The word "Robot" was
coined by Karel Capek in
1921. It was used for his
play titled "Rossum's
Universal Robots".

IF YOU DON'T WANT TO PRINT THIS SHEET OUT,
YOU CAN DRAW ON A SEPERATE PIECE OF PAPER.

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