## Summary - Complex Mixer

Name	complex_mixer
Latest Version	1.5 (4/2019)
Worker Type	Application
Component Library	ocpi.training.components
Workers	complex_mixer.hdl complex_mixer.rcc
Tested Platforms	c7-x86_64, linux-x13_3-arm, linux-x13_4-arm, xsim,
	Matchstiq-Z1(PL)(Vivado 2017.1), Ettus E310(PL)

#### Revision History

Revision	Description of Change	Date
v1.2		8/2017
v1.3		2/2018
v1.4		10/2018
v1.5	Convert Worker to Version 2 HDL API	4/2019

## **Functionality**

The Complex Mixer consists of a Numerically Controlled Oscillator (NCO) and a complex multiplier. Complex IQ data is received on the input port and is multiplied with the output of the NCO and put on the output port.

### Worker Implementation Details

#### complex\_mixer.hdl

Figure 1 diagrams the complex mixer.

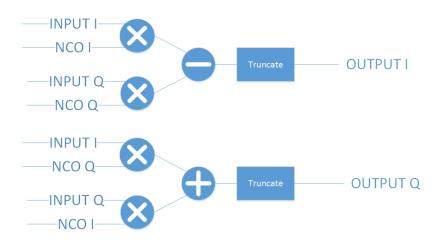


Figure 1: Complex Mixer Functional Diagram

The control properties for all implementations provide the ability to enable (or bypass) the worker and set the tune frequency via  $phs\_inc$ .

The HDL worker leverages Xilinx Vivado cores to implement the NCO (DDS Compiler v6.0.13) and complex multiply (Complex Multiplier v6.0.12) functions. The Vivado IP Catalog tool was used to generate both cores. For both cores, their respective default configuration settings were chosen with the following exceptions:

• DDS Compiler 6.0.13 (dds\_compiler.xci)

Parameter Selection = Hardware Parameters

Output Width = 16

Phase Increment Programmability = Streaming

Optional Pins: Has Phase Out is unchecked and ARESETn checked

• Complex Multiplier v6.0.12 (complex\_multiplier.xci)

Control Signals: ACLKEN and ARESETn checked

The dds\_compliler v6.0.13 implements a phase generator and  $\sin/\cos$  look-up tables (LUT), and has a latency of 7. The complex\_multiplier v6.0.12 uses 3 DSP48E1s and has a latency of 6.

In conjunction with the enable (or bypass) control property, the HDL worker provides the ability to select different ( $data\_select$ ) data to output in bypass mode: input or output of the NCO.

#### complex\_mixer.rcc

The RCC worker leverages liquid-dsp v1.2 and its *nco* class to generate the internal NCO used in the algorithm. More information on this liquid-dsp module can be seen in the online documentation: liquid-dsp. In the RCC version of this component the samples are converted from fixed point to floating point numbers in order to do that math on a GPP. This conversion introduces a small amount of error in the output data and should be accounted for when it is used in an application. The conversion equations are as follows:

$$iq\_float = \frac{iq\_fixed}{2^{15} - 1} \tag{1}$$

$$iq_{-}fixed = iq_{-}float * (2^{15} - 1)$$
 (2)

In the RCC worker a conversion needs to be done for the phase increment to adhere to the way the HDL phase increment is implemented. The conversion was done in the RCC version of this component because the division operation is very resource intensive in HDL. The conversion from the component property to the liquid-dsp interface input property is as follows:

$$liquid\_phs\_inc = phs\_inc * \frac{2\pi}{0x7FFF * 2}$$
(3)

## Theory

The Complex Mixer worker inputs complex signed samples and performs a complex multiply with a digital sine wave produced by an numerically controlled oscillator (NCO). The resulting output data is a frequency shifted version of the input data.

The magnitude of the frequency shift is determined by the output frequency of the NCO, which can be calculated with the following equation:

$$nco\_output\_freq = sample\_freq * \frac{phs\_inc}{2^{phs\_acc\_width}}$$
 (4)

In this component, phs\_inc is runtime configurable and has a data type of 16 bit signed short. phs\_acc\_width is fixed at 16. The input clock frequency is the sample rate of the samples. The amplitude of the NCO's sine wave is fixed at the full range of a signed 16 bit value.

# **Block Diagrams**

# Top level

enable, phs\_inc

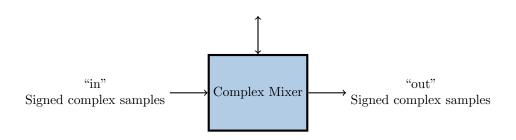


Figure 2: Complex Mixer Top Level Block Diagram

## Source Dependencies

#### complex\_mixer.rcc

• Liquid DSP (provided with opencpi RPMs)

#### complex\_mixer.hdl

- training\_project/components/complex\_mixer.hdl/vivado\_ip/complex\_multiplier\_stub.vhd
- training\_project/components/complex\_mixer.hdl/vivado\_ip/complex\_multiplier\_sim\_net.vhd
- training\_project/components/complex\_mixer.hdl/vivado\_ip/complex\_multiplier.vho
- training\_project/components/complex\_mixer.hdl/vivado\_ip/complex\_multiplier.xci
- training\_project/components/complex\_mixer.hdl/vivado\_ip/complex\_multiplier.edf
- $\bullet \ training\_project/components/complex\_mixer.hdl/vivado\_ip/dds\_compiler\_stub.vhd\\$
- training\_project/components/complex\_mixer.hdl/vivado\_ip/dds\_compiler\_sim\_net.vhd
- $\bullet \ training\_project/components/complex\_mixer.hdl/vivado\_ip/dds\_compiler.vho$
- $\bullet \ training\_project/components/complex\_mixer.hdl/vivado\_ip/dds\_compiler.xci$
- $\bullet \ training\_project/components/complex\_mixer.hdl/vivado\_ip/dds\_compiler.edf$

# ANGRYVIPER Team

# Component Properties

Name	Type	SequenceLength	ArrayDimensions	Accessibility	Valid Range	Default	Description
enable	Bool	-	-	Writable	Standard	0	Enable(true) or Bypass(false) mixer
phs_inc	Short	ī	ī	Writable	Standard	0	Phase increment of NCO

# Worker Properties

 $complex\_mixer.hdl$ 

Name	Type	SequenceLength	ArrayDimensions	Accessibility	Valid Range	Default	Description
data_select	bool	-	-	Writable	Standard	0	In Bypass Mode: selects data to
							output: 0=input data, 1=output of
							NCO

# **Component Ports**

Name	Producer	Protocol	Optional
in	false	iqstream_protocol.xml	false
out	true	iqstream_protocol.xml	false

## Worker Interfaces

 $complex\_mixer.hdl$ 

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Type	Name	DataWidth
StreamInterface	in	32
StreamInterface	out	32

## Control Timing and Signals

The Complex Mixer HDL worker uses the clock from the Control Plane and standard Control Plane signals.

There is a startup delay for this worker. Once the input is ready and valid and the output is ready, there is a 6 clock cycle start delay (pipeline delay of complex multiplier). After this startup delay, valid output data is given 6 clock cycles after input data is taken.

Latency
6 clock cycles

#### Performance and Resource Utilization

#### complex\_mixer.hdl

Table 6: Resource Utilization Table for worker "complex\_mixer"

Configuration	OCPI Target	Tool	Version	Device	Registers (Typ)	LUTs (Typ)	Fmax (MHz) (Typ)	Memory/Special Functions
0	$_{ m zynq}$	Vivado	2017.1	xc7z020clg400-3	558	379	N/A	RAMB36E1: 7 DSP48E1: 3 BUFG: 2 RAMB18E1: 1 BUFGCTRL: 2

#### Test and Verification

Test cases are derived from the number of properties, and their respective values, as listed in the complex\_mixer-test.xml. Specifically, the complex\_mixer.rcc and complex\_mixer.hdl implementations tested, as follows:

- 1) Bypass (RCC & HDL): The input data is forwarded to the output port. For verification of this case, the output file is byte-wise compared to the input file.
- 2) Normal mode (RCC & HDL): The NCO is configured to tune the input signal to baseband. For verification, an FFT of the output data is performed and the max value of the FFT is checked to be at DC (0 Hz).

For all cases, the input file contains a tone of 12.5 Hz sampled at 100 Hz and an amplitude of 32767.