



## Application Development with TDD

**Getting Started** 

Luis Ubieda Lead FW Engineer











## Agenda

- Intro
- Basics of Test-Driven Development (TDD)
- TDD in Zephyr
- Faking dependencies (Device-Tree Nodes and Subsystems)
- Live Demo
- Q&A





## Intro





#### **About Me**

#### Luis Ubieda

- Electrical Engineer
- Lead Firmware Engineer @ Croxel
- 7 Years developing Firmware
- Based in Melbourne, FL (Space Coast)
- Passion for Technology, Electronics and IoT
- First Zephyr Contribution on 2021
- Free-Time: Fitness and Sports
- Blogger: <a href="https://embeddedtales.blog">https://embeddedtales.blog</a>
- First Time Speaker at EOSS





Rocket Launch every other week at the Space Coast. Image Source: visitspacecoast.com



### **About Croxel**

- Deep Zephyr RTOS expertise for tailored, technically sound solutions.
- End-to-end product development capabilities aligned with your goals.
- Rapid prototyping and low-power optimization for faster time-to-market.
- Seamless integration with your teams across all areas of development.
- Active contributions to the Zephyr Project and continuous community involvement.











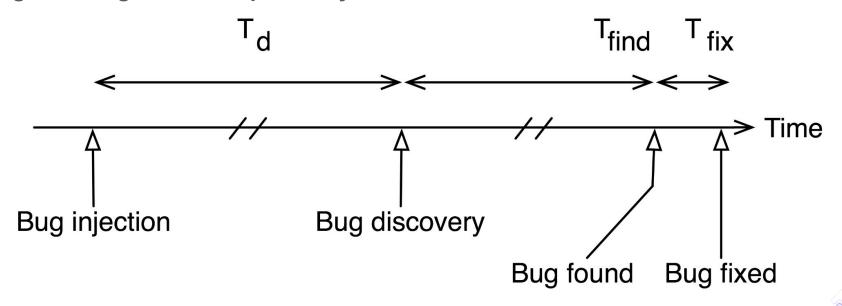
#### **Fundamentals**

- Comes from Extreme Programming (XP).
- Opposite to typical Waterfall-type development (develop first, test later).
- Focuses on incremental development.
- Embraces the fact that bugs are inevitable.
- Relies on capturing and passing **Unit Tests** as means to develop the application.





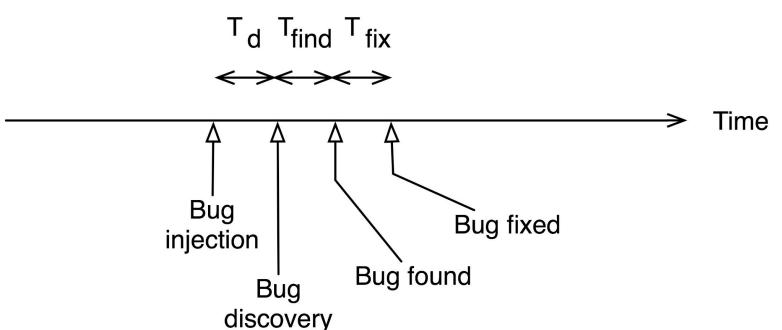
#### **Bugs in a Regular Development Cycle**







#### **Bugs in a TDD Development Cycle**



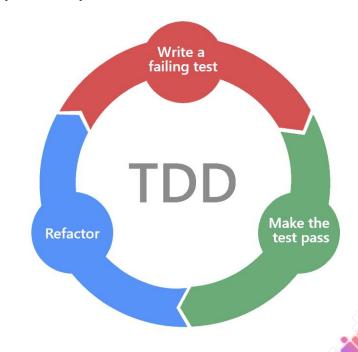


Source: Test-Driven Development for Embedded C, James Grenning



#### **Steps to Progress on TDD**

- Start with a List of Requirements.
- From requirements to a List of Tests.
- One test at a time.
- Iteration Cycle: Fail -> Pass -> Refactor.
- Capture new test-cases while iterating.







#### **Example Requirements - Motion Detection Engine**

- 1. The Possible Motion states are: Movement, Idle or Unknown.
- 2. Upon initialization the motion state is Unknown.
- 3. Idle means no motion has occurred in the last 5 seconds.
- 4. Movement means detecting at least 2 m/s<sup>2</sup> acceleration on any axis for at least 1 second.
- 5. A Motion State change triggers an event to users.







#### **Example List of Tests (Initial) - Motion Detection Engine**

- 1. Initializing the Module starts the Motion Detection Engine.
- 2. Initial State is Unknown.
- 3. Callback is triggered on a state change.
- 4. Transition to Idle state if no motion in 5 seconds.
- 5. Transition to Movement state if Motion is sustained for 1 second
- 6. Once entered, stay in Movement state for 5 seconds.
- 7. Sustained motion while in Movement extends the motion state.







#### **Faking Dependencies**

- Unit Under Test (UUT) relies on dependencies.
- Faking a dependency means replacing it by a
  Test Double, abstracted to the UUT.
- Test Double sets and manages expectations and returning parameters.
- Types of Test Doubles: Dummy, Stub, Mock.
- It may be done manually or by using Frameworks (e.g. CMock, CppUTest, FFF).









#### **Benefits of TDD**

- Software Development without needing Hardware.
- Catch bugs easier and faster.
- Definition of Done is clear.
- Improve Predictability of Development Cycle.
- Code-base feels less "fragile".
- Overall Improvement of Code Quality.





## TDD in Zephyr







### TDD in Zephyr

#### **Testing Frameworks Available**

- ZTest, Zephyr Test Framework.
- FFF, Mocking.
- Twister, Test Runner.
- BabbleSim, Radio Simulator (e.g. Bluetooth).
- Pytest, Integration tests.







## TDD in Zephyr

#### **Pros**

- Extensive Boards support.
- Inherent Abstractions and Generalized APIs
- Testing Frameworks Available.

#### Complexities

- Dealing with Device-Tree
- Dealing with Subsystems (Kconfig dependencies).





## Faking Dependencies







## Faking Dependencies in Zephyr - Subsystems

#### **Alternatives**

- Use an existing Zephyr emulator.
- Implement a Test-Double.

#### Implementing a Test-Double

- Approach: Link-Time Substitution.
- Disable Module using Kconfigs.
- Add minimal Test-Double, implementing the used APIs.









## Faking Dependencies in Zephyr - Device-Tree

#### **Alternatives**

- Use an existing Zephyr emulator.
- Develop a Device-Tree Node Test-Double.

#### Implementing a DT-Node Test-Double

- Link Device-tree devices using Node-labels.
- Create a DT-Node Test-Double using the same APIs your dependency implements.
- Use the DT-Node Test-Double to emulate the expected behavior (set/check expectations, provide return parameters, etc).







## Live Demo





## Q&A

