

Introducing CHESTER Platform for Industrial IoT

Applications

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How CHESTER started

- ❑ A few years back:
One of our customers needs an NB-IoT thermometer
in the forests to correlate the bark beetle occurrence...

- ❑ Where we are today:
An open and multi-purpose IoT hardware platform with
businesses relying on it around the world...

- ❑ Target audience:
 - ❑ Connected hardware enthusiasts
 - ❑ Embedded software craftsmen
 - ❑ Anybody who likes to see things in action

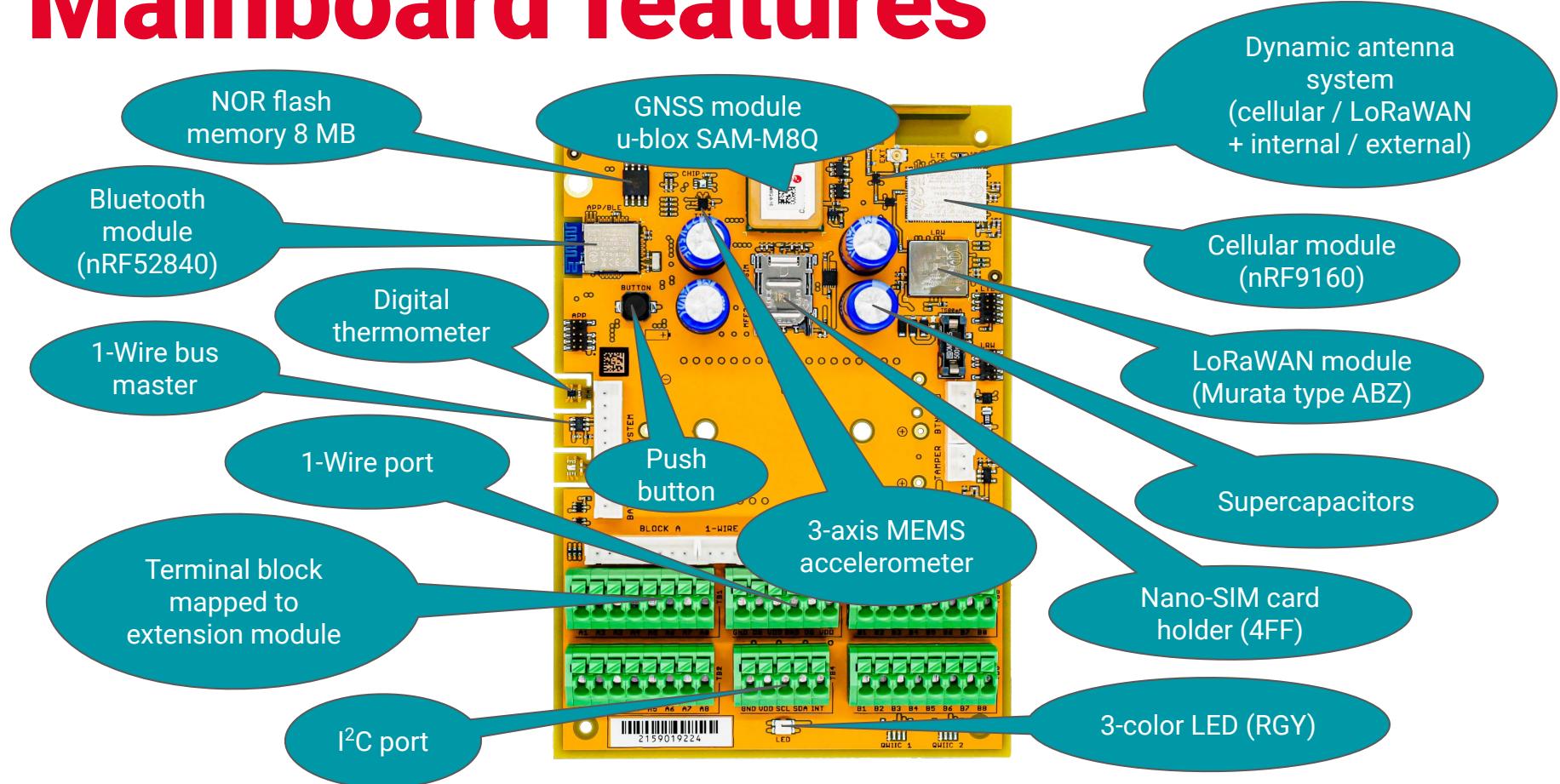


CHESTER introduction

- ❑ Configurable IoT hardware endpoint with open Zephyr-based SDK
- ❑ Open platform for HARDARIO partners with possibility for full OEM customization
- ❑ Applications: Industrial IoT plus every thing that should be connected



Mainboard features



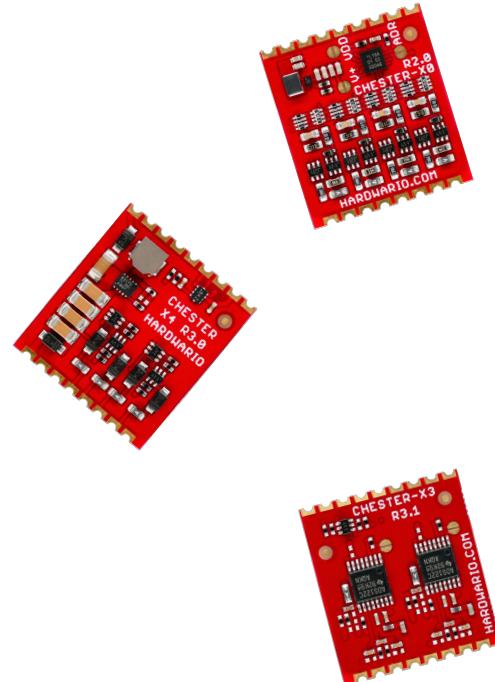
Rich connectivity

- ❑ Short range: **Bluetooth Low Energy**
- ❑ Cellular: **NB-IoT** (SIM card needed)
- ❑ Cellular: **LTE-M** (SIM card needed)
- ❑ ISM radio: **LoRaWAN**
- ❑ Satellite: **Astrocast** (top cover module with L-Band communication)
- ❑ Positioning: **GNSS** (GPS / Galileo / GLONASS / Beidou)

- ❑ All of these combined or targeted **mainboard variants**

Hardware extensibility

- ❑ Three types:
 - ❑ Backside modules
 - ❑ Top cover modules
 - ❑ Carrier boards



(Low-)Power flexibility

- ❑ Primary Lithium 3.6 V cells (LiSoCl₂) - typically 7.700 mAh
- ❑ Integrated supercapacitors (energy bank for high current demand)
- ❑ Rechargeable Li-Ion battery (extension module CHESTER-Z)
- ❑ Solar photovoltaic panels (in connection with rechargeable cells)
- ❑ Idle current (incl. BLE) ~230 uA
- ❑ Battery lifespan incl. NB-IoT communication (in ECL 0) ~3 years
- ❑ Multiple power sources can be combined together
(batteries have lower "hardware priority")



If just one is not enough...



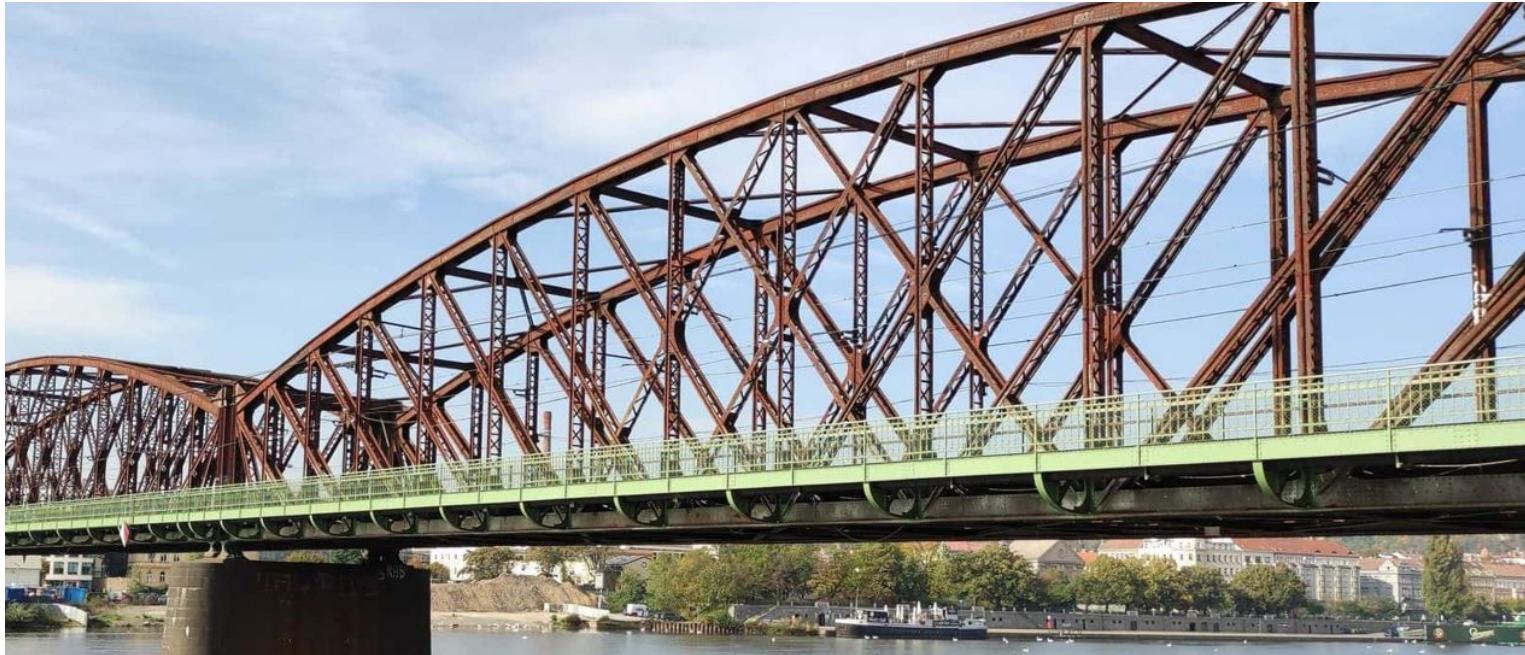
Real applications

Environmental monitoring in the UK forests



Real applications

Bridge inclination monitoring



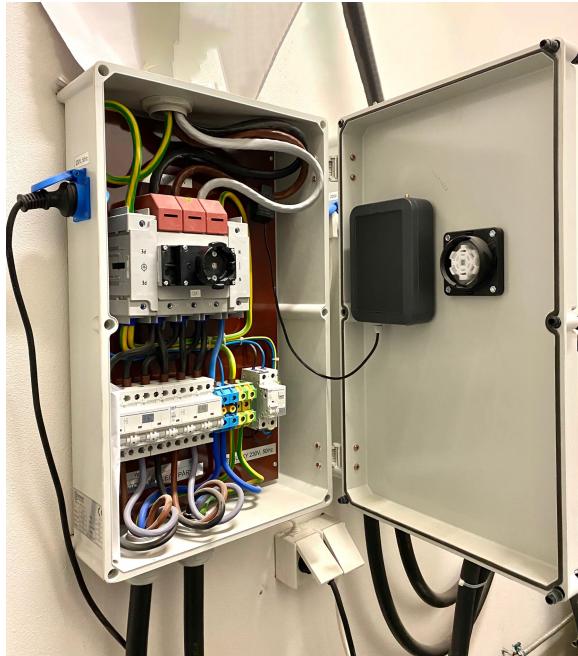
Real applications

Retail digitization



Real applications

Utility - cathodic protection monitoring + rack cabinets



Catalog applications

- ❑ Ready-to-go products:
 - ❑ CHESTER **Push** - Rugged button notification system
 - ❑ CHESTER **Clime** - Environmental monitoring
 - ❑ CHESTER **Current** - Current measurement for OEE / predictive maintenance
 - ❑ CHESTER **Input** - Configurable analog/digital generic sensor telemetry unit
 - ❑ CHESTER **Meteo** - Outdoor weather and soil moisture monitoring
 - ❑ CHESTER **Modbus** - Rugged button notification system
 - ❑ CHESTER **Scale** - Precise weight scale measurement
 - ❑ CHESTER **Range** - Distance measurement using ultrasonic ranger
 - ❑ CHESTER **Control** (**COMING SOON**) - Remote appliance control and input scanning
- ❑ ...they are all open-source

Living ecosystem



NORDIC®
SEMICONDUCTOR

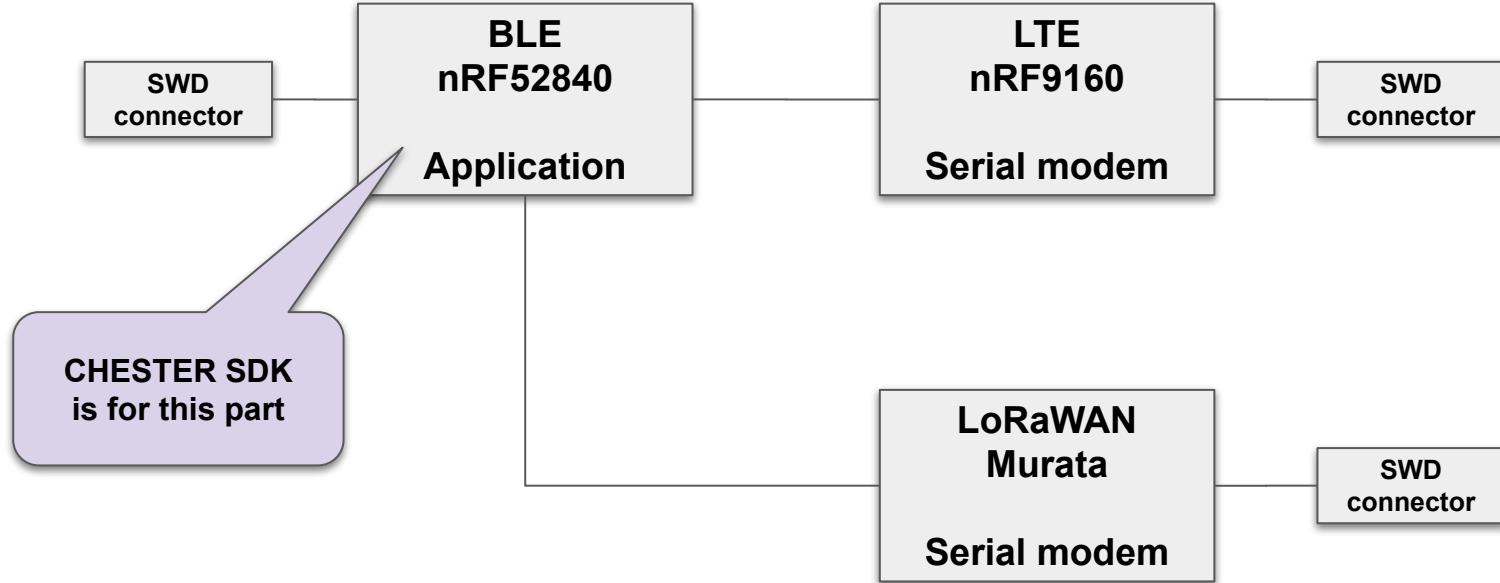


CHESTER + Zephyr

- ❑ Scalable, **secure & safe**
- ❑ Friendly for low-power applications
- ❑ Designed with **IoT projects** in mind
 - ❑ Vast range of connectivity options
 - ❑ Integrates with **MCUboot** bootloader
- ❑ Encourages portability & code re-usability
- ❑ Protects investments to your code by imposing low-maintenance requirements
- ❑ But there is a learning curve...

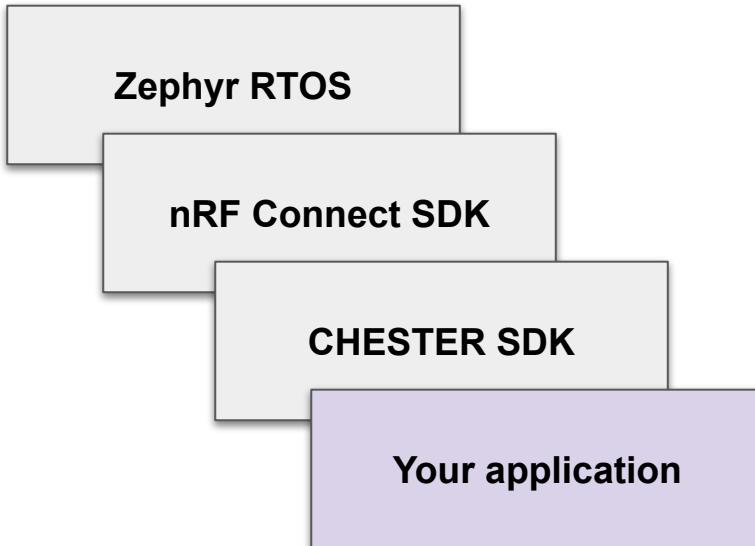


Firmware landscape



Software stack

Zephyr's West tool makes structuring Git repositories convenient...



File: `west.yml`

```
manifest:  
  version: "0.12"  
  remotes:  
    - name: hardware  
      url-base: https://github.com/hardwario  
  projects:  
    - name: nrf  
      remote: hardware  
      repo-path: ncs.git  
      revision: v2.2-chester-branch  
      import: true  
  self:  
    path: chester  
    west-commands: scripts/west-commands.yml
```

Hardware abstraction

Exercise:

Let's move an LED indication from CHESTER mainboard to a carrier board where LED is driven by an I²C expander.

```
led_rgy {  
    compatible = "gpio-leds";  
  
    led_r: led_r {  
        gpios = <&gpio1 13 GPIO_ACTIVE_HIGH>;  
    };  
  
    led_g: led_g {  
        gpios = <&gpio1 11 GPIO_ACTIVE_HIGH>;  
    };  
  
    led_y: led_y {  
        gpios = <&gpio1 12 GPIO_ACTIVE_HIGH>;  
    };  
};
```



```
led_rgy {  
    compatible = "gpio-leds";  
  
    led_r: led_r {  
        gpios = <&ctr_b1_tca9534a 5 GPIO_ACTIVE_LOW>;  
    };  
  
    led_g: led_g {  
        gpios = <&ctr_b1_tca9534a 6 GPIO_ACTIVE_LOW>;  
    };  
  
    led_y: led_y {  
        gpios = <&ctr_b1_tca9534a 7 GPIO_ACTIVE_LOW>;  
    };  
};
```

Modularity

- ❑ Goal: Keep independents block truly independent (avoid cross-dependency whenever possible)
- ❑ Symbol definition via Kconfig (enable/disable modules being built)
`add_subdirectory_ifdef(CONFIG_SERIAL serial)`
- ❑ Zephyr modules (add sources w/o altering CMake)

File: Kconfig

```
menu "Application"

config APP_REPORT_JITTER
    bool "Add random time jitter to report transfers"
    default y
    select ENTROPY_GENERATOR

endmenu

menu "Zephyr Kernel"
source "Kconfig.zephyr"
endmenu
```

File: prj.conf

```
CONFIG_APP_REPORT_JITTER=n
CONFIG_ADC_NRFX_SAADC=n
CONFIG_ADC_SHELL=n
CONFIG_CTR_ACCEL=y
CONFIG_CTR_BATT=y
CONFIG_CTR_BLE=y
CONFIG_CTR_BUF=y
CONFIG_CTR_DEFAULTS=y
CONFIG_CTR_INFO=y
CONFIG_CTR_LED=y
CONFIG_CTR_LOG=y
CONFIG_CTR_LTE_CLKSYNC=y
CONFIG_CTR_RTC=y
```

Coherence

- ❑ Goal: Keep the related functionalities together
- ❑ Zephyr facilitates this:
 - ❑ Initialization
 - ❑ Logging
 - ❑ Shell
 - ❑ Settings
- ❑ Avoid cross-dependencies:
 - ❑ `init1(); init2(); ...`

The diagram illustrates the Zephyr initialization process. Four blue callouts point to specific parts of the code:

- Logging module name: Points to the macro `LOG_MODULE_REGISTER(ctr_config, CONFIG_CTR_CONFIG_LOG_LEVEL);`
- Minimum module log level: Points to the macro `CONFIG_CTR_CONFIG_LOG_LEVEL` in the callout for the logging module name.
- Boot priority: Points to the macro `CONFIG_CTR_CONFIG_INIT_PRIORITY` in the callout for the boot stage.
- Boot stage: Points to the macro `APPLICATION` in the callout for the boot priority.

```
#include <zephyr/init.h>
#include <zephyr/logging/log.h>
#include <zephyr/settings/settings.h>

LOG_MODULE_REGISTER(ctr_config, CONFIG_CTR_CONFIG_LOG_LEVEL);

static int init(void)
{
    int ret;

    LOG_INF("System initialization");

    ret = settings_subsys_init();
    if (ret) {
        LOG_ERR("Call `settings_subsys_init` failed: %d", ret);
        return ret;
    }

    return 0;
}

SYS_INIT(init, APPLICATION, CONFIG_CTR_CONFIG_INIT_PRIORITY);
```

TIME TO DEMO

Windows

An error has occurred. To continue:

Press Enter to return to Windows, or

Press CTRL+ALT+DEL to restart your computer. If you do this,
you will lose any unsaved information in all open applications.

Error: 0E : 016F : BFF9B3D4

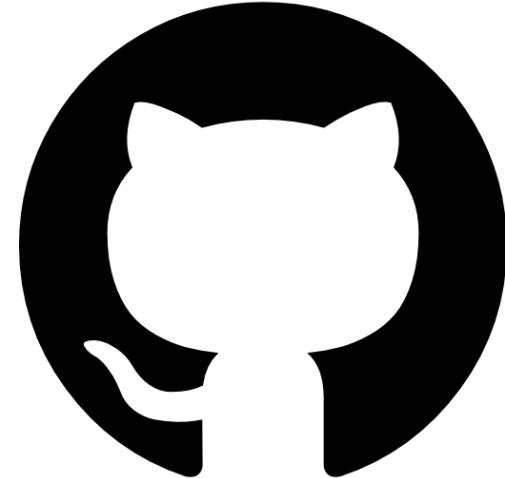
Press any key to continue _

Past & Future

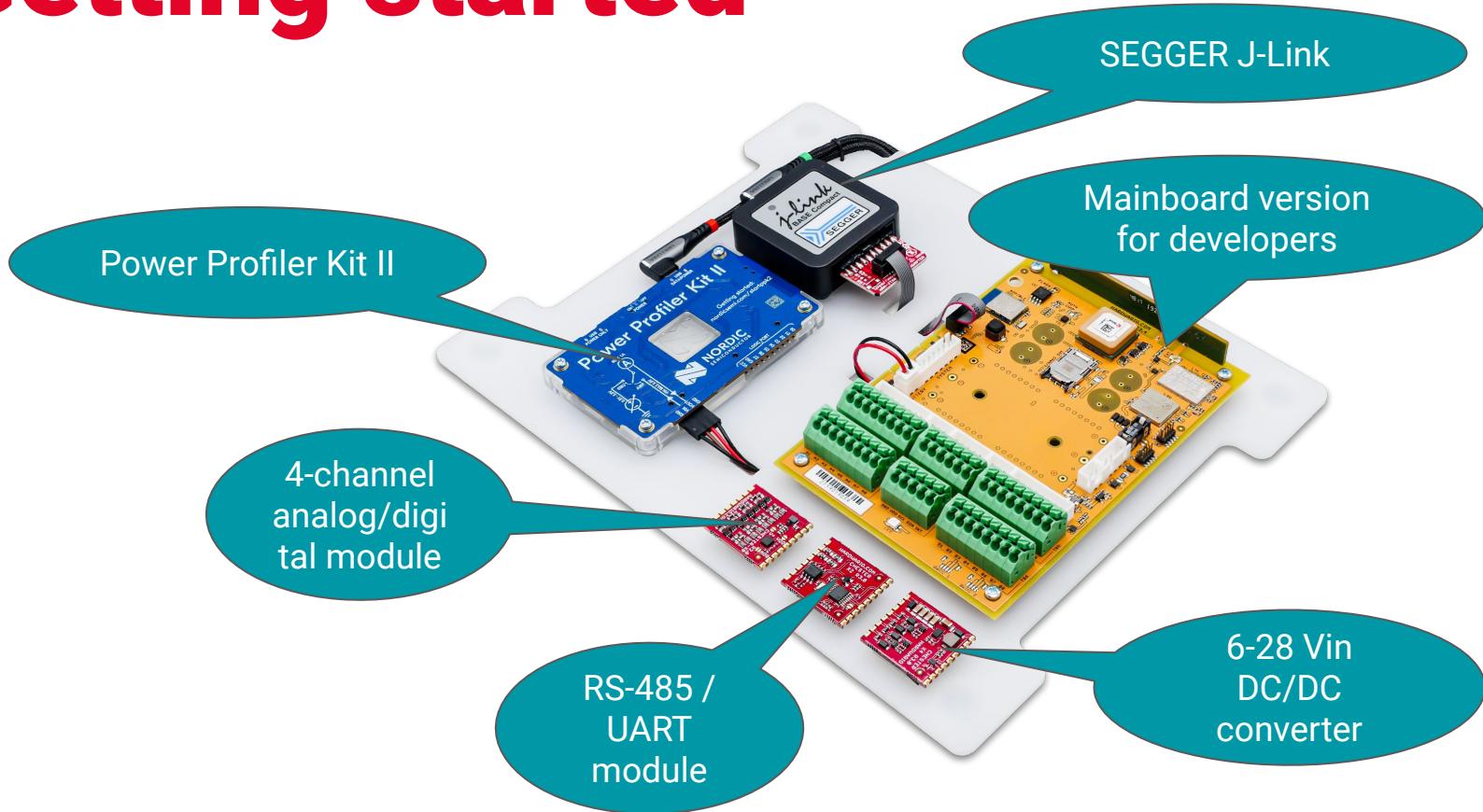
- ❑ Contributions:
 - ❑ Testing and improvements to 1-Wire subsystem:
 - ❑ Thomas Stranger (1-Wire subsystem)
 - ❑ Caspar Friedrich (Drivers for 1-Wire bus masters)
 - ❑ Several minor enhancements (also to nRF Connect SDK)
- ❑ Next development:
 - ❑ Consider replacing Zephyr shields with Zephyr snippets
 - ❑ Adopt Zephyr zbus pub/sub messaging

Now open-source

- ❑ Published on June 26, 2023
- ❑ 5-clause open-source license
(inheritance from Nordic Semiconductor)
- ❑ CHESTER SDK:
<https://github.com/hardwario/chester-sdk>
- ❑ CHESTER Skeleton application:
<https://github.com/hardwario/chester-skeleton>
- ❑ CHESTER documentation:
<https://docs.hardwario.com/chester/>



Getting started



GRACIAS

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Welcome to our booth number 33