

# Microservices for Microcontrollers

Composable Software Architecture  
for Embedded Systems



# Um, Aren't Microservices a Cloud Thing?



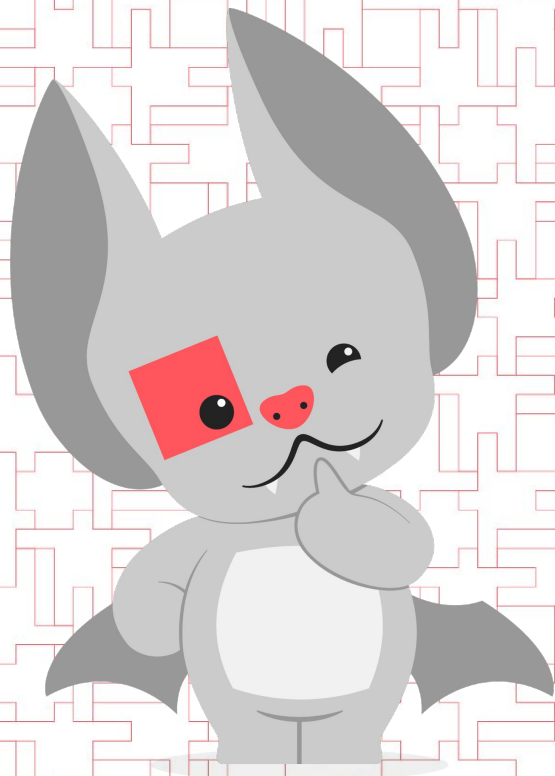
# What is a Microservice?

## **Modular Software**

- Fine-grained, loosely coupled, independently deployable software components

## **Built for Speed**

- Organized around business functions. Many teams in a large organization can push updates faster and without fear of breaking everything.



# Okay but Firmware?

## **Modular Software**

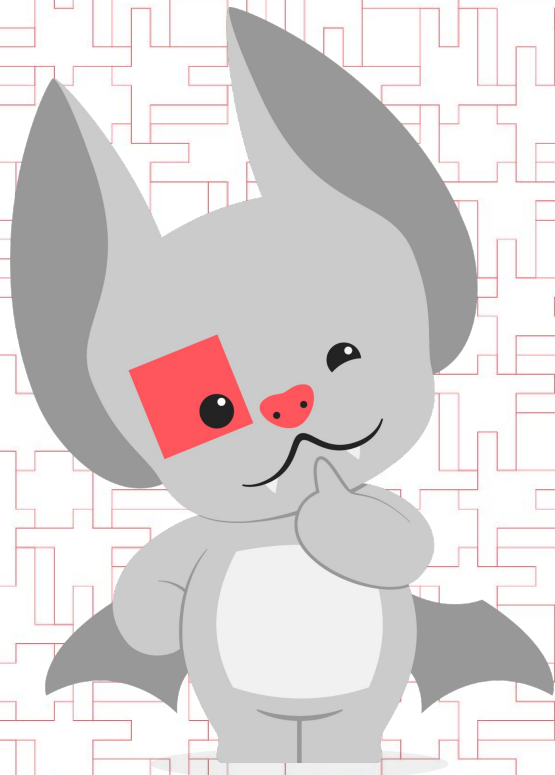
- Independent, loosely coupled, fine-grained tasks communicating through well-defined IPC mechanisms

## **Improved Encapsulation**

- Better code organization makes firmware easier to read, maintain, and test.

## **Composability**

- Smaller pieces are more reusable



# What is Composability?

## A Lego Set of Components

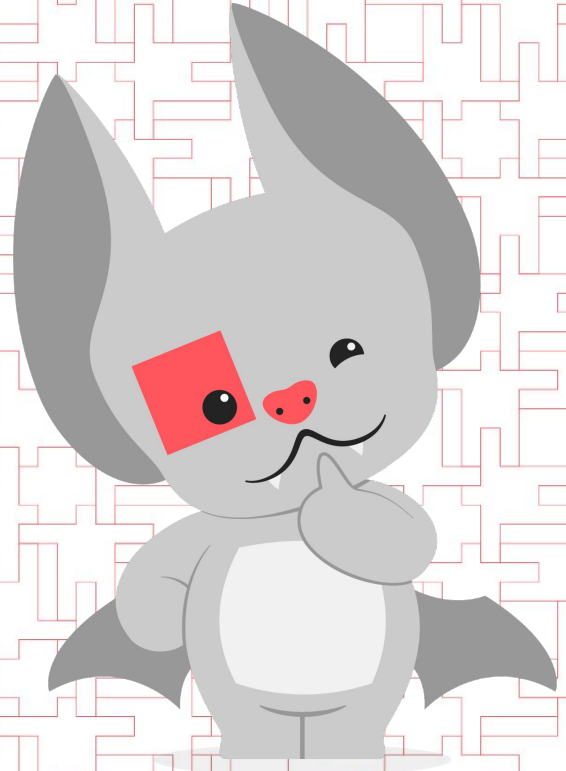
- Small building blocks of functionality that are combined into a larger application

## Infinite combinations

- Components can be added, removed, or swapped out to change the functionality of the application, without requiring source code changes

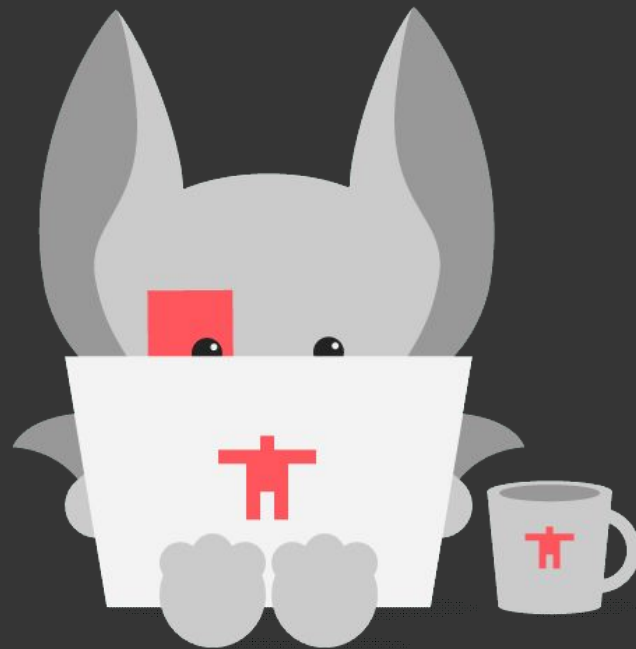
## Support Them All

- Create bespoke firmware for each revision of a product by selecting the required components



# In Practice

- Tasks
- IPC
- Event Tasks



# Tasks

## Fine Grained

- Many small tasks
- Each concerned with one (1) business function

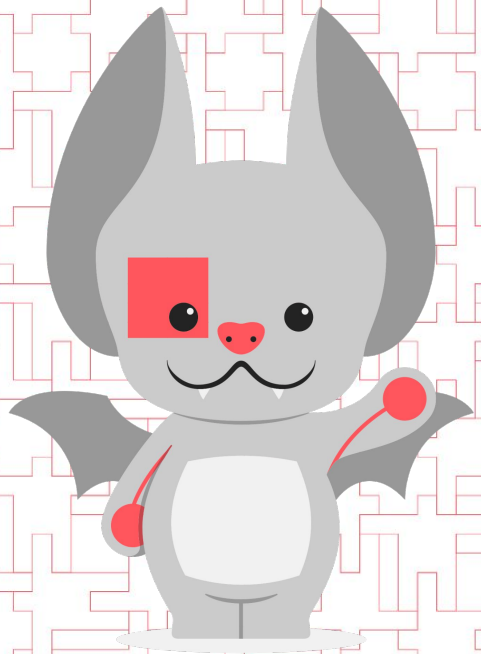
## Loosely Coupled

- No public interface
- All communication through indirect IPC

## A Collection of Equals

- No main()
- No library/driver initialization

**All Threads are Tasks, but Not All Tasks are Threads (more later)**



# IPC: PubSub

## Data-Oriented Architecture

- Focus is on the form and flow of data, not on connections between modules
- Modules communicate without knowing about the other party

## Removes inter-task dependencies

- Tasks communicate with Pubsub, not (directly) with each other

## Removes development dependencies too

- Publishers and Subscribers easily mocked and tested





# Tasks Redux: Events

## Threadless Functions™

- Multiple tasks executing on one thread, running to completion in response to events

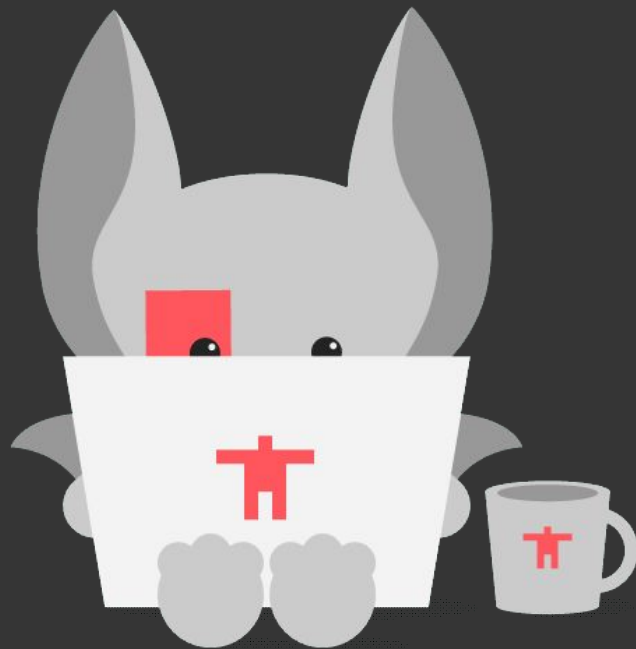
## Tread Lightly

- Need to ensure that the event thread isn't blocked



# Building it in Zephyr

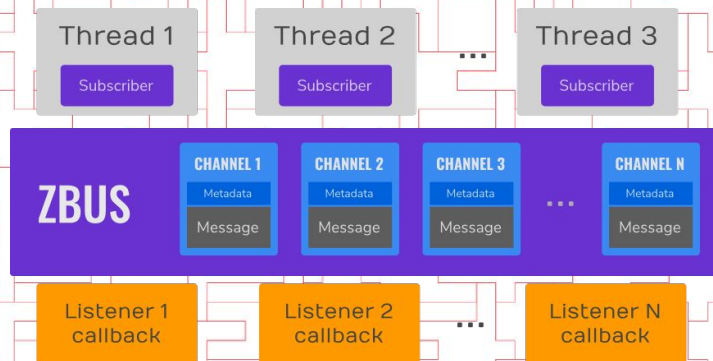
- zbus
- Iterable Sections
- System Initialization



# zbus

- Zephyr's [native pubsub bus](#)
- Also implements event tasks (listeners)

See the [Zephyr Tech Talk](#) on zbus!



# Iterable Sections

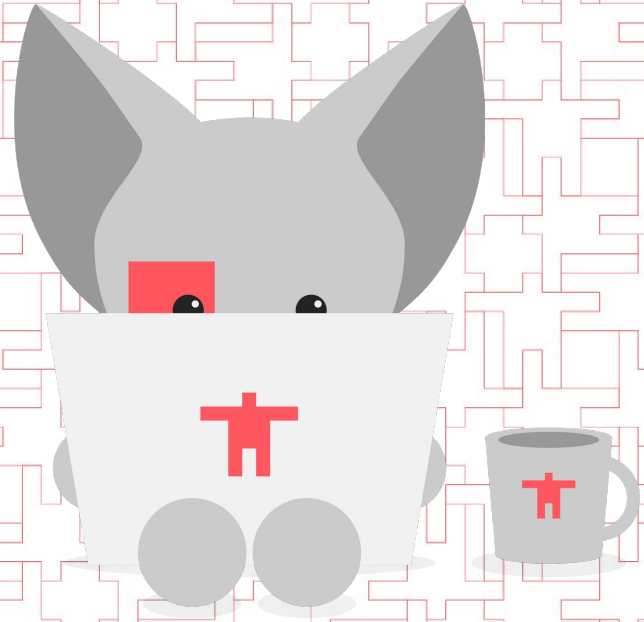
## Leverage the Linker

- Allow modules to register themselves.  
No API call at bootup, no central registry.

## Build Time Configuration

- Compiling a file integrates that module into the system.

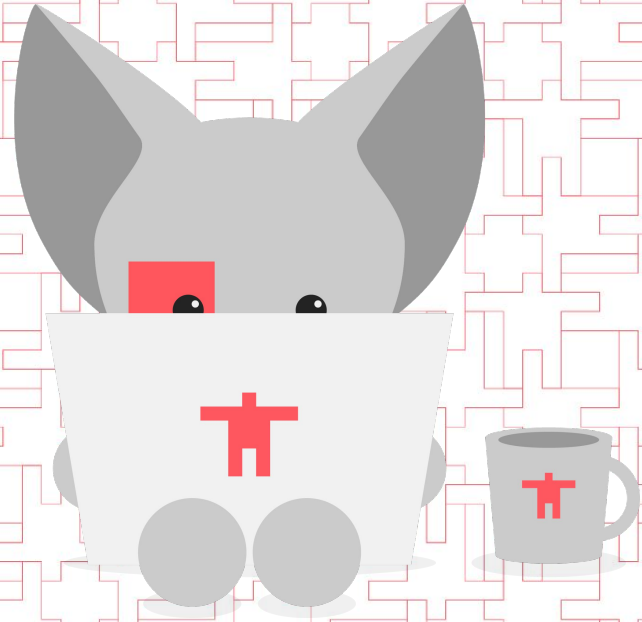
\* Remember: no main(), no public APIs!



# System Initialization

**Tasks come and go but initialization is forever**

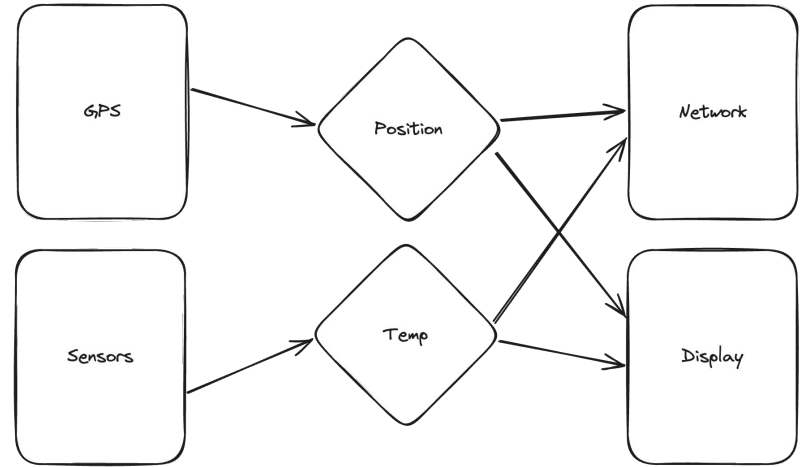
- Zephyr's system initialization system allows us to decouple initialization of libraries, subsystems and drivers from which tasks are included.



# Real World Example



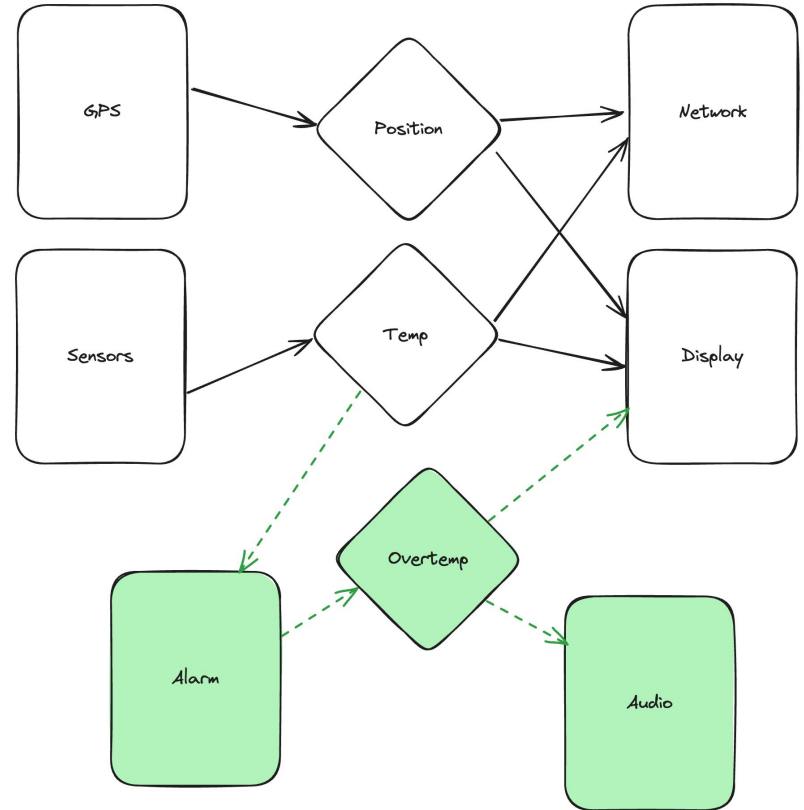
# Cold Chain Asset Tracker



# New Feature! (temperature alarm)

Customer requests local alerting

- Alarm Event Task listens to temperature topic, publishes to overtemp topic
- New Audio Thread Task plays tones
- Display Task adds an alert screen

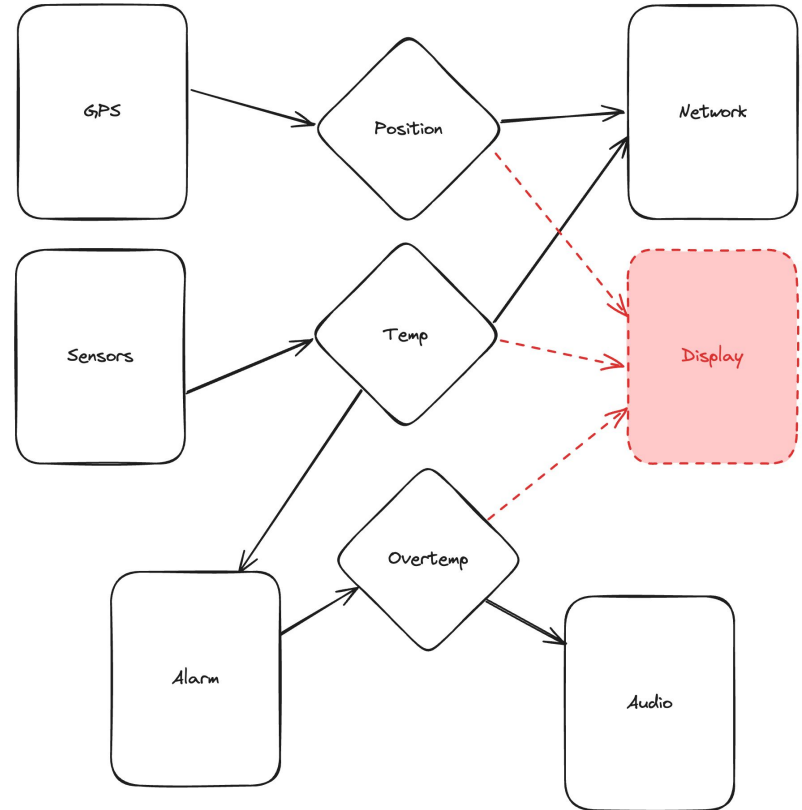




# Cost Down (Remove Display)

Display is too expensive, let's remove it!

- Don't compile the Display task





# Questions?

