



GEOSPARQL 3D WHITE PAPER

TECHNICAL PAPER

DRAFT

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KEYWORDS

The following are keywords to be used by search engines and document catalogues.

OGC, GeoSPARQL, 3D

To come...

SECURITY CONSIDERATIONS

The following security considerations apply...

IV

SUBMITTING ORGANIZATIONS

The following organizations submitted this Document to the Open Geospatial Consortium (OGC):

- Organization one
- Organization two
- Organization three

V

SUBMITTERS

NAME	AFFILIATION	OGC MEMBER
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1

SCOPE

1

SCOPE

2

CONFORMANCE

3

NORMATIVE REFERENCES

NORMATIVE REFERENCES

There are no normative references in this document.

4

TERMS AND DEFINITIONS

TERMS AND DEFINITIONS

No terms and definitions are listed in this document.

5

ABSTRACT

ABSTRACT

To come...

6

KEYWORDS

To come...

7

CONVENTIONS

8

MOTIVATION

8.1. Why do we want 3D semantic modeling?

The white paper: "OGC Benefits of Representing Spatial Data Using Semantic and Graph Technologies" describes the beneficiaries and benefits of representing data, including geospatial data, using semantic and graph technologies Abhayaratna2020wp. This section describes the motivation of adding 3D functionality to the GeoSPARQL standard.

While humans can often resolve 3D spatial questions such as "Is cube A inside cylinder B?" — even when the underlying data comes from different systems like GIS and BIM — this typically relies on implicit understanding, conventions, or direct communication between the data creators. For datasets to be meaningfully aligned, the people who created them often need to clarify assumptions, data structures, coordinate systems, or modeling intentions. Without such human-to-human explanation, machines struggle to interpret spatial relationships across heterogeneous sources. A conversion process is required, in which data is made homogeneous for analysis through extraction, transformation, and loading. Based on a homogeneous dataset, conclusions can then be drawn. Performing conversions may result in geometric simplifications, which can limit or even eliminate the functionality of spatial queries Biljecki2019. If one desires digital, automated processing or analysis of 3D spatial questions without requiring conversion, spatial information must be structured in an explicitly machine-readable format. When this is done, initiatives based on federated systems with heterogeneous datasets can obtain computer-generated answers to spatial 3D queries. This requires semantic alignment and standardized geometry processing in machine-driven analysis. In other words, a common vocabulary is needed to semantically define the 3D objects and its 3D spatial function.

Imagine a constructor who wants to use real-time sensor data at a construction site in combination with modelled 3D data and 3D base registration data. By combining this the person wants to visualize the site, perform accurate spatial checks and calculations, and automatically update machine instructions for safe, efficient and autonomous execution"

The system uses 3D GeoSPARQL to integrate the data of the 3D design model, the 3D base registration model and 3D real-time sensor data to:

- Spatially associate sensor data with objects in the design and registration model
- Calculate the permissible tolerances
- Detect the deviations
- Dynamic adjust the design model
- Instruct the machine with the changes
- Visualize the new situation

For both humans and machines, it must be unambiguous what is meant by the queries that are needed to do the job and the resulting answers. It should not matter whether the data is provided in a 3D-GIS, 3D-BIM or 3D-CG standard vocabulary.

8.1.1. A geo-spatial 3D specification would support data consumers by:

- access and understanding of 3D-geometry and 3D-topology from multiple sources;
- the integration of 3D-data geospatial and non-geospatial;
- data quality evaluation of the given 3D-data;
- Geometric and topological description in natural language.

8.1.2. A geo-spatial 3D specification would support data providers by:

- Maximizing the use of 3D-geometry and 3D-topology data;
- Defining multiple 3D topology or geometries;
- Assuring the quality of 3D geospatial data.

9

RELATED WORK

RELATED WORK

This is still just a dump of resources. To be transformed into actual text.

9.1. CityGML

CityGML [koble2005citygml] is an open standardized data model for the exchange of 3D models of cities and landscapes. Since its standardization by OGC, CityGML has seen a wide variety of proposed extensions and alignments to other data standards.

9.1.1. CityJSON and CityRDF

[27] proposed the extension of the CityGML and its accompanying serialization CityJSON as an ontology model. Currently, the CityRDF standardization group works towards the standardization of this CityGML data model in RDF.

The proposed CityRDF model, even though focused on CityGML and 3D building contents, contains valuable data descriptions which could be generalized in a GeoSPARQL 3D approach. One such element is the description of the appearance of a 3D-modeled building using colors or textures, so-called surface materials. In addition, CityGML includes relations of 3D primitives between each other, which could serve as an inspiration for similarly-named functions or properties in the GeoSPARQL 3D ontology model.

[27] describes the CityGML Ontology, which is an ontology model to formalize the CityGML standard towards a representation in OWL. It shows a workflow of identification, classification and selection of the relevant data points needed to describe 3D city models in OWL as derived from building and city models. In addition, it introduces the concept of Level of Information Need, defining the granularity of the information on the various levels of the building and the types of information retrieval – direct/indirect, i.e. information which is commonly obtained directly from a dataset or using a calculation or reasoning approach. The paper exemplifies the concept in a study case for property unit cost and indoor daylight. The contribution outlined here became the basis of the CityGML ontology which can serve as one broad application area for GeoSPARQL 3D.

Following on this publication [22] presents a system architecture and a set of interfaces that can represent city modeling approaches using dynamic geospatial knowledge graphs. The paper proves the viability of a transition between a SQL based system for 3D building management to a SPARQL based system using a SQL2SPARQL Transformer component. It therefore proves the feasibility of employing linked open data technologies for 3D building data and in particular the CityGML model in practice.

[30] introduces CityGML 3.0 with a newly added Core module including a new space concept and Level Of Detail concept. The given publication sets the standard especially for Level of Detail in 3D buildings, which may be considered for adoption as GeoSPARQL 3D concepts too.

In addition, CityGML 3.0 proposes the addition of 3D point clouds for the representation of 3D geometries of physical spaces and space boundaries. A mapping from IFC to CityGML 3.0 is also proposed by these authors.

CityGML 3.0 therefore represents many of the elements that a GeoSPARQL 3D ontology would need to implement on a more abstract level and can give ideas about future query functions to be implemented in the GeoSPARQL query language.

In addition, a master thesis hansson2024citygml proved the feasibility of not only converting CityGML to a knowledge graph representation, but also its application in triple stores such as Ontop or 3DCityDB. The mapping of CityGML to the knowledge graph was tested using a set of SPARQL queries retrieving different components of building parts. While the thesis could construct a knowledge graph representation from CityGML, it points out that the incorporation of spatial operations is left to future work and could provide a possible field for GeoSPARQL 3D adoption.

Finally, [21] proposed OntoCityGML, an extension to the CityGML ontology <https://www.sciencedirect.com/science/article/pii/S2666546821000574?via%3Dihub> Semantic 3D City Database – An enabler for a dynamic geospatial knowledge graph

Other details and history of Onto CityGML.

CityRDF working group <https://github.com/ogcincubator/cityrdf>

9.2. Medicine & Chemistry

The medicine and chemistry domains contain a variety of usecases for 3D applications.

In particular, 3D metadata of microscopy is a common application field, which yielded for instance the [3D Microscopy Metadata Standards \(3D-MMS\)](#) [32] developed by the BRAIN 3D Microscopy Working Group. This standard helps ensuring that a 3D microscopy dataset is sufficiently described to support its re-use by other scientists not involved in data creation. Its adoption will therefore enable investigators willing to share their data to evaluate and decide which data can be combined.

<https://onlinelibrary.wiley.com/doi/abs/10.1111/cgf.13083> Ontology-Based Representation and Modelling of Synthetic 3D Content: A State-of-the-Art Review

[24]

A range of approaches have been proposed to permit semantic representation and modelling of synthetic 3D content. These approaches differ in the methodologies and technologies used as well as their scope and application domains. This paper provides a review of the current state of the art in representation and modelling of 3D content based on semantic web ontologies, together with a classification, characterization and discussion of the particular approaches.

<https://www.inderscienceonline.com/doi/abs/10.1504/IJMSO.2017.087702> A novel ontology for 3D semantics: ontology-based 3D model indexing and content-based video retrieval applied to the medical domain

[25]

This paper presents the most comprehensive formally grounded 3D ontology to date that maps the entire XSD-based vocabulary of the industry standard X3D (ISO/IEC 19775-19777) to OWL 2, complemented by fundamental concepts and roles of the 3D modelling industry not covered by X3D.

9.3. 3D data formats and ontologies

A new GeoSPARQL standard should be compatible with existing approaches to encode 3D data. Semantic technologies should enable users to encode important metadata in the knowledge graph, while retaining the possibility to use already well-known 3D geometry formats either as String literals or file references. bonduel2019including shows how common widespread geometry formats could be included into knowledge graphs, which could be one starting point to investigate the integration within GeoSPARQL.

9.3.1. STereoLithography (STL)

STL files describe only the surface geometry of a three-dimensional object without any representation of color, texture or other common CAD model attributes. The STL format specifies both ASCII and binary representations and was invented by the Albert Consulting Group for 3D Systems in 1987. Nowadays it is mainly used for 3D printing purposes, which makes it a plausible candidate for support in GeoSPARQL 3D settings of movable objects such as in cultural heritage. Since the STL format does not contain a geospatial reference, the reference needs to be provided externally if STL files were to be used in a geospatial context. However, STL objects could be used in local CRS contexts as well.

9.3.2. Wavefront OBJ Format (OBJ)

The OBJ format is a file format developed by Wavefront Technologies for the Advanced 3D Visualizer animation package. Its roots therefore lie in the world of 3D animation. The format represents vertex coordinates, texture coordinates, as well as vertex normals, parameter space vertices and faces of a 3D model. These are all elements which would need to be considered and supported in an upcoming GeoSPARQL 3D release.

9.3.3. Polygon File Format (PLY)

The Polygon File Format is a format which was designed to store 3D data from 3D scanning environments, which makes it especially widespread in the Cultural Heritage application area. The format consists of a vertex list and a faces list with optional parameters per vertex. Like the

OBJ format, supporting PLY would imply including support for vertices and faces of a 3D model and their relationships in a knowledge graph.

9.3.4. CARARE Metadata Schema

The CARARE metadata schema d2013carare is a harvesting schema intended for delivering metadata about an organisation's online collections, heritage assets and their digital resources. The strength of the schema lies with its ability to support the full range of descriptive information about monuments, building, landscape areas and their representations. The CARARE metadata schema builds on existing standards and best practice from a number of different countries in Europe and the rest of the world.

9.3.5. IIIF 3D

The International Image Interoperability Framework (IIIF) standard snydman2015international is currently developing a [specification](#) for the standardization of 3D viewers. The viewer specification includes the visualization of 3D models including lighting positions, a scene graph and annotations in the form of additional 3D objects added to a 3D scene. A GeoSPARQL 3D standard might need to be compatible with, or include a compatibility statement of, converting 3D objects encoded in GeoSPARQL to the IIIF viewer specification. A prototype implementation might be necessary to comply with this specification.

9.3.6. X3D and X3D Ontology

The X3D format feichtenhofer2020x3d, brutzman2010x3d, X3DOM behr2009x3dom and its Ontology version brutzman2020x3d provide a data format and a blueprint for how 3D data is handled in computer vision approaches. X3D is an interesting format to investigate for 3D components which need to be modeled within a GeoSPARQL 3D specification. It is a likely candidate for a literal format and might be integrated using interlinking approaches to the already existing X3D vocabulary. However, since X3D was invented with computer vision approaches in mind it does not define any geospatial aspects that could be considered by a GeoSPARQL 3D implementation.

9.3.7. Geometry Metadata Ontology (GOM)

The [Geometry Metadata Ontology \(GOM\)](#) introduces classes for surfaces which are common in the 3D world, but uncommon for 3D geometries, for instance Meshes or NURBS surfaces. The ontology can serve as an inspiration for extensions in GeoSPARQL 3D and may or may not be fully or partly adopted in the process of standardization.

9.3.8. Ontology for Managing Geometry (OMG)

The [Ontology for Managing Geometry \(OMG\)](#) describes states and derivation of geometries which may be useful to the description of data in GeoSPARQL 3D. For example, an extrusion in

3D from a 2D geometry template would have a derivation relation from the 2D geometry which one might want to see modeled in GeoSPARQL 3D.

9.3.9. File Ontology for Geometry Formats (FOG)

The [File Ontology for Geometry Formats \(FOG\)](#) provides a bridge between ontology descriptions of geometries and data file descriptions of 3D contents. Since many 3D datasets are of considerable size, their inclusion into the knowledge graph as String literals might hinder the query performance of said knowledge graph. It therefore stands to reason whether to adopt the same or a similar method of geometry access that FOG provides for GeoSPARQL 3D.

9.4. To consider

<https://link.springer.com/article/10.1007/s10845-023-02246-6> Ontology of 3D virtual modeling in digital twin: a review, analysis and thinking

[33]

To help novice engineers understand and scheme 3D virtual modeling in digital twin for future research and applications, this paper reviews 106 digital twin 3D modeling cases with their characteristics, including deployment targets, purposes & roles, collaborative models, data flows, the autonomy of 3D modeling, fidelity, twinning rates, enabling technologies, and enabling tools.

Open standard for particle-mesh data (openPMD)

The [openPMD standard](#), short for open standard for particle-mesh data files is not a file format per se. It provides guidance for meta-data and naming schemes. openPMD provides naming and attribute conventions that allow the exchange of particle and mesh based data from scientific simulations and experiments. Its primary goal is to define a minimal set/kernel of meta information that allows to share and exchange data to achieve portability between various applications and different algorithms, a unified open-access description for scientific data (publishing and archiving), and a unified description for post-processing, visualization and analysis. If outputs from programs, devices (such as cameras), simulations or post-processed data-sets, contain a minimal set of meta information as provided by openPMD, data can be exchanged between those with minimal effort, with the same tools used for visualization.

[19]

9.5. Cultural Heritage

In the research domain of cultural heritage, 3D models of either cultural heritage artifacts (possibly georeferenced), 3D models of archaeological sites or simply 3D models of ancient buildings are becoming increasingly common.

9.5.1. Use Cases

Use Cases in the Cultural Heritage domain include, but are not limited to, the following main interests:

Visualization: The visualization of 3D models for the presentation of such 3D models, for example in the context of a museum. 3D models may be styled with a particular set of textures or modeled with a specific set of colours to highlight certain relevant aspects. The visualization of 3D models is currently standardized by the IIIF 3D working group [29], which aims to create viewing parameter descriptions that 3D viewers may implement, similar to the specifications of IIIF 2D for images.

Object Annotation: 3D models are seen as the subject of a research question in absence of the original artifact for political, practical or other restrictive reasons. Out of all known methods of the representation of cultural heritage artifacts, 3D models provide the most detail when being delivered as a digital artifact and are therefore very often preferred in a research context. Researchers mark noteworthy aspects of the cultural artifact as 3D annotations [28] which may include surface descriptions, volumes of the 3D model or 3D models which are created and placed adjacent to the to-be-annotated 3D model [20].

Relation of Objects: Objects of a specific collections always exist in a spatio-temporal context. It is important to relate these representations via meaningful relations, so that relevant objects of a collection can be retrieved more easily

AI Applications in Cultural Heritage: Usage for annotated areas on 3D models or their derivations for machine learning classifications Stotzner_2023_ICCV 10.2312/gch.20231157

Knowledge Graphs as Metadata descriptions: With the advent of more 3D models being published, the relevance of their creation parameters [31], their contents and their object metadata increases for the usecases of filtering them and also for the possibly automated selection of suitable cultural heritage metadata for e.g. machine learning classifications. Currently, many metadata standards fulfil parts of the description chain and a unified vocabulary to described data types seems to be missing.

9.5.2. Research applications making use of 3D models in Cultural Heritage

This section discusses research projects with 3D contents based on the technologies they use as elaborated in the previous section.

9.5.2.1. 3D models of cuneiform tablets

Cuneiform tablets from ancient Iran provide an interesting research area, since they combine a 3D artifact with textual imprints that are of interest to a variety of research communities including Assyriologists, Digital Humanists, Computational Linguists and last but not least Computer Scientists. The creation of 3D models of cuneiform tablets provides the best accessibility to the specificities of the original artifact in its absence and 3D scans have been used by computer scientists as the basis for certain machine learning application tasks, even

though to this day only as a provision for 2D renderings of their surfaces. Interests of the research community include the description of interesting features such as cuneiform signs on cuneiform tablet surfaces and their connection to other text contents or other cuneiform artifacts. Knowledge graphs provide machine learning approaches Stotzner_2023_ICCV stotzner2023r with unique opportunities to connect different kinds of data using a unified data format.

To describe 3D meshes, several vocabularies have been developed in the context of the cuneiform studies project:

- [MeshSPARQL](#): A vocabulary to describe essential mesh elements
- [Gigamesh Metadata Vocabulary](#): A vocabulary which describes metadata of a 3D model. The metadata can be generated using the Gigamesh Software Framework
- [3DCAP Vocabularies](#): An ontology model to describe the creation of a 3D model. It has been applied to different scanning softwares

9.6. IFC and BIM

9.6.1. Industry Foundation Classes (IFC) and BIM

BIM is a paradigm in which object-model definitions – with machine-interpretable semantics – are exchanged, rather than relying on CAD drawings that convey only graphical semantics. The predominant open exchange standard is Industry Foundation Classes (IFC).

9.6.1.1. Product model

In IFC, a construction work is decomposed into a set of products. These products can have **multiple representations**. For example, a wall can be described as a solid body as well as a two-dimensional axis. These representations facilitate different views on the same data: an editable line segment or an easily visualized volume. The Object-relational nature of the IFC EXPRESS schema allows intricate relationships such as a representation context that communicates additional intent for the representation or presentation styles that can be granularly assigned to individual faces.

At the same time, such a product separates the **placement** (an hierarchical transformation) from the actual geometry definition. The consequence of this is that in spite of its object-relational nature, IFC product representations cannot be used for building-level topological relationships between solids, because even if two solids are touching in 3D, the fact the the placement is externalized out of the geometry definition (or the fact that faces are constructed procedurally and do not exist explicitly), means that the two faces cannot be opposite oriented twins. As such, relational geometric constructs such as space boundaries are provided as additional supplementary geometries.

In principle, the IFC schema has been designed in a modular fashion with independent modules for, for example, geometry, materials and meta-data. However in other cases, **semantics and geometry are intertwined** such as tapered extrusions (*lofts*) where the begin and end profile of a duct carry important semantics.

IFC also allows for **decomposition**, where a whole is aggregated into multiple parts for richer semantics. This allows for example to connect materials and meta-data to the frame and the glazing separately, while still being able to identify the aggregate as a single window. This is not used as frequently, partially due to inability to efficiently instantiate such aggregates as geometry instances.

9.6.1.2. Evolving views on geometry

IFC is heavily influenced by the ISO 10303 (STEP) family of standards, but over time adopted its own geometric paradigms:

- Procedural geometry and boolean operations became less prominent with the adoption of ReferenceView in IFC4. Tessellated geometry definitions were added for more compact exchange.
- **Infrastructure definitions** were added with precise mathematical transition curves and a composition of a horizontal, vertical and cant (inclination) profile.
- IFC5 with an **explicit** (most likely triangulated) geometry schema at the core, with semantic overlays to encode the same procedural semantics as a non-mandatory or use-case specific layer. Heavily inspired by USD with layer-based composition for collaborative exchange.

Especially the handling of **tolerances** means that the standard cannot effectively prescribe a consistent outcome in all cases. Tolerances are needed for BRep model with non-linear underlying geometry and/or fixed precision coordinate values, e.g higher degree nurbs curves are typically intersected with numerical approximation, so a vertex that connects two of such curves needs to be seen as a sphere with the local tolerance as its radius. This tolerance is also applied to boolean operations: a subtraction volume can be slightly inwards of the first operand but is still expected to pierce through the volume and increase surface genus. This contrasts with the desire of using IFC as a legal basis in contracts. NB Tolerances stand in the way of using existing approaches for SFA geometry predicates such as PostGIS+SFCGAL which is based on arbitrary precision boolean logic as implemented in CGAL without tolerances.

9.6.1.3. Use cases

The most successful use case on BIM data is **coordination and visualization** where multiple aspect models are geometrically overlaid in order to find issues, which are then communicated to the authoring software where they are addressed. This approach works, because it respects that individual disciplines all have their own specialistic software.

Design to design workflows are much harder to realize, although some Model View Definitions have been developed on top of IFC that enable the transfer of design intent in specific and constrained scenarios, such as precast concrete and structural steel.

Long-term preservation of building information is difficult because of the fact that IFC models are difficult to mutate, because they are so explicit and don't contain the vendor-specific design intelligence. Therefore native software cannot always re-import IFC models, but also the native models degrade over time because of the need to migrate to newer editions of the software. Software that can directly operate on IFC to make modifications is still experimental.

BIM-GIS integration is challenging because it requires familiarity with both domains on where to draw the line between euclidean and non-euclidean geometries and acceptable error metrics.

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9.6.1.4. Implications and questions:

- Euclidean / non-euclidean; is a CRS required?
- Separate representation+placement → enables efficient reinstatement, but hinders topological relationships because you require the pair of placement+geometry to locate in space
- Geometry as leaf-values or object-relational model : cannot encapsulate geometry into a single literal, but allows for richer semantics
- BRep model (topology + geometry + orientation + location) vs polyhedral model (e.g halfedge) vs explicit loops of point coordinates
- Procedural vs implicit (e.g constraints) vs explicit (polyhedra)
- Tolerances
- Decomposition inside or outside of the 'geometry ontology'
- Are infra geometries (hor + ver alignment + cant, for positioning and sweeps) in scope?

9.7. Implementations

9.7.1. CGAL → SFCGAL → PostGIS

9.7.2. OpenCASCADE

9.7.2.1. OpenCASCADE-inspired BRep ontology

Perzylo, A., Somani, N., Rickert, M., & Knoll, A. (2015, September). An ontology for CAD data and geometric constraints as a link between product models and semantic robot task descriptions. In 2015 IEEE/RSJ international conference on intelligent robots and systems (IROS) (pp. 4197-4203). IEEE.

<https://ieeexplore.ieee.org/abstract/document/7353971>

[23]

9.7.2.2. Topologic

Jabi, W., & Chatzivasileiadis, A. (2021, January). Topologic: exploring spatial reasoning through geometry, topology, and semantics. In Formal Methods in Architecture: Proceedings of the 5th International Symposium on Formal Methods in Architecture (5FMA), Lisbon 2020 (pp. 277-285). Cham: Springer International Publishing.

<https://topologic.app/>

[2]

9.7.3. BRep vs mesh/polyhedron

BRep

- Curved surfaces
- Topology: connected components as shells, solids with inner voids, etc.
- Clean APIs due to inheritance: e.g fn extrude(Topo) → Topo, for vertex → edge; edge → face; face → solid; solid → solid
- Extra indirections: edge → vertex[] → point
- Depending on implementation can be inefficient, e.g outer wire of face not explicitly marked need to be checked wrt infinite point

- Data integrity and validation a bit harder

Mesh/polyhedron

- Potentially fewer indirections
- Triangle meshes robust and well understood
- Many different data models though, e.g half-edge (only manifold), indexed faceset (no adjacency info), winged/quad/radial edge

10

RELATED WORK

This is still just a dump of resources. To be transformed into actual text.

10.1. CityGML

CityGML [koble2005citygml] is an open standardized data model for the exchange of 3D models of cities and landscapes. Since its standardization by OGC, CityGML has seen a wide variety of proposed extensions and alignments to other data standards.

10.1.1. CityJSON and CityRDF

[27] proposed the extension of the CityGML and its accompanying serialization CityJSON as an ontology model. Currently, the CityRDF standardization group works towards the standardization of this CityGML data model in RDF.

The proposed CityRDF model, even though focused on CityGML and 3D building contents, contains valuable data descriptions which could be generalized in a GeoSPARQL 3D approach. One such element is the description of the appearance of a 3D-modeled building using colors or textures, so-called surface materials. In addition, CityGML includes relations of 3D primitives between each other, which could serve as an inspiration for similarly-named functions or properties in the GeoSPARQL 3D ontology model.

[27] describes the CityGML Ontology, which is an ontology model to formalize the CityGML standard towards a representation in OWL. It shows a workflow of identification, classification and selection of the relevant data points needed to describe 3D city models in OWL as derived from building and city models. In addition, it introduces the concept of Level of Information Need, defining the granularity of the information on the various levels of the building and the types of information retrieval – direct/indirect, i.e. information which is commonly obtained directly from a dataset or using a calculation or reasoning approach. The paper exemplifies the concept in a study case for property unit cost and indoor daylight. The contribution outlined here became the basis of the CityGML ontology which can serve as one broad application area for GeoSPARQL 3D.

Following on this publication [22] presents a system architecture and a set of interfaces that can represent city modeling approaches using dynamic geospatial knowledge graphs. The paper proves the viability of a transition between a SQL based system for 3D building management to a SPARQL based system using a SQL2SPARQL Transformer component. It therefore proves the feasibility of employing linked open data technologies for 3D building data and in particular the CityGML model in practice.

[30] introduces CityGML 3.0 with a newly added Core module including a new space concept and Level Of Detail concept. The given publication sets the standard especially for Level of Detail in 3D buildings, which may be considered for adoption as GeoSPARQL 3D concepts too.

In addition, CityGML 3.0 proposes the addition of 3D point clouds for the representation of 3D geometries of physical spaces and space boundaries. A mapping from IFC to CityGML 3.0 is also proposed by these authors.

CityGML 3.0 therefore represents many of the elements that a GeoSPARQL 3D ontology would need to implement on a more abstract level and can give ideas about future query functions to be implemented in the GeoSPARQL query language.

In addition, a master thesis hansson2024citygml proved the feasibility of not only converting CityGML to a knowledge graph representation, but also its application in triple stores such as Ontop or 3DCityDB. The mapping of CityGML to the knowledge graph was tested using a set of SPARQL queries retrieving different components of building parts. While the thesis could construct a knowledge graph representation from CityGML, it points out that the incorporation of spatial operations is left to future work and could provide a possible field for GeoSPARQL 3D adoption.

Finally, [21] proposed OntoCityGML, an extension to the CityGML ontology <https://www.sciencedirect.com/science/article/pii/S2666546821000574?via%3Dihub> Semantic 3D City Database – An enabler for a dynamic geospatial knowledge graph

Other details and history of Onto CityGML.

CityRDF working group <https://github.com/ogcincubator/cityrdf>

10.2. Medicine & Chemistry

The medicine and chemistry domains contain a variety of usecases for 3D applications.

In particular, 3D metadata of microscopy is a common application field, which yielded for instance the [3D Microscopy Metadata Standards \(3D-MMS\)](#) [32] developed by the BRAIN 3D Microscopy Working Group. This standard helps ensuring that a 3D microscopy dataset is sufficiently described to support its re-use by other scientists not involved in data creation. Its adoption will therefore enable investigators willing to share their data to evaluate and decide which data can be combined.

<https://onlinelibrary.wiley.com/doi/abs/10.1111/cgf.13083> Ontology-Based Representation and Modelling of Synthetic 3D Content: A State-of-the-Art Review

[24]

A range of approaches have been proposed to permit semantic representation and modelling of synthetic 3D content. These approaches differ in the methodologies and technologies used as well as their scope and application domains. This paper provides a review of the current state of the art in representation and modelling of 3D content based on semantic web ontologies, together with a classification, characterization and discussion of the particular approaches.

<https://www.inderscienceonline.com/doi/abs/10.1504/IJMSO.2017.087702> A novel ontology for 3D semantics: ontology-based 3D model indexing and content-based video retrieval applied to the medical domain

[25]

This paper presents the most comprehensive formally grounded 3D ontology to date that maps the entire XSD-based vocabulary of the industry standard X3D (ISO/IEC 19775-19777) to OWL 2, complemented by fundamental concepts and roles of the 3D modelling industry not covered by X3D.

10.3. 3D data formats and ontologies

A new GeoSPARQL standard should be compatible with existing approaches to encode 3D data. Semantic technologies should enable users to encode important metadata in the knowledge graph, while retaining the possibility to use already well-known 3D geometry formats either as String literals or file references. bonduel2019including shows how common widespread geometry formats could be included into knowledge graphs, which could be one starting point to investigate the integration within GeoSPARQL.

10.3.1. STereoLithography (STL)

STL files describe only the surface geometry of a three-dimensional object without any representation of color, texture or other common CAD model attributes. The STL format specifies both ASCII and binary representations and was invented by the Albert Consulting Group for 3D Systems in 1987. Nowadays it is mainly used for 3D printing purposes, which makes it a plausible candidate for support in GeoSPARQL 3D settings of movable objects such as in cultural heritage. Since the STL format does not contain a geospatial reference, the reference needs to be provided externally if STL files were to be used in a geospatial context. However, STL objects could be used in local CRS contexts as well.

10.3.2. Wavefront OBJ Format (OBJ)

The OBJ format is a file format developed by Wavefront Technologies for the Advanced 3D Visualizer animation package. Its roots therefore lie in the world of 3D animation. The format represents vertex coordinates, texture coordinates, as well as vertex normals, parameter space vertices and faces of a 3D model. These are all elements which would need to be considered and supported in an upcoming GeoSPARQL 3D release.

10.3.3. Polygon File Format (PLY)

The Polygon File Format is a format which was designed to store 3D data from 3D scanning environments, which makes it especially widespread in the Cultural Heritage application area. The format consists of a vertex list and a faces list with optional parameters per vertex. Like the

OBJ format, supporting PLY would imply including support for vertices and faces of a 3D model and their relationships in a knowledge graph.

10.3.4. CARARE Metadata Schema

The CARARE metadata schema d2013carare is a harvesting schema intended for delivering metadata about an organisation's online collections, heritage assets and their digital resources. The strength of the schema lies with its ability to support the full range of descriptive information about monuments, building, landscape areas and their representations. The CARARE metadata schema builds on existing standards and best practice from a number of different countries in Europe and the rest of the world.

10.3.5. IIIF 3D

The International Image Interoperability Framework (IIIF) standard snydman2015international is currently developing a [specification](#) for the standardization of 3D viewers. The viewer specification includes the visualization of 3D models including lighting positions, a scene graph and annotations in the form of additional 3D objects added to a 3D scene. A GeoSPARQL 3D standard might need to be compatible with, or include a compatibility statement of, converting 3D objects encoded in GeoSPARQL to the IIIF viewer specification. A prototype implementation might be necessary to comply with this specification.

10.3.6. X3D and X3D Ontology

The X3D format feichtenhofer2020x3d, brutzman2010x3d, X3DOM behr2009x3dom and its Ontology version brutzman2020x3d provide a data format and a blueprint for how 3D data is handled in computer vision approaches. X3D is an interesting format to investigate for 3D components which need to be modeled within a GeoSPARQL 3D specification. It is a likely candidate for a literal format and might be integrated using interlinking approaches to the already existing X3D vocabulary. However, since X3D was invented with computer vision approaches in mind it does not define any geospatial aspects that could be considered by a GeoSPARQL 3D implementation.

10.3.7. Geometry Metadata Ontology (GOM)

The [Geometry Metadata Ontology \(GOM\)](#) introduces classes for surfaces which are common in the 3D world, but uncommon for 3D geometries, for instance Meshes or NURBS surfaces. The ontology can serve as an inspiration for extensions in GeoSPARQL 3D and may or may not be fully or partly adopted in the process of standardization.

10.3.8. Ontology for Managing Geometry (OMG)

The [Ontology for Managing Geometry \(OMG\)](#) describes states and derivation of geometries which may be useful to the description of data in GeoSPARQL 3D. For example, an extrusion in

3D from a 2D geometry template would have a derivation relation from the 2D geometry which one might want to see modeled in GeoSPARQL 3D.

10.3.9. File Ontology for Geometry Formats (FOG)

The [File Ontology for Geometry Formats \(FOG\)](#) provides a bridge between ontology descriptions of geometries and data file descriptions of 3D contents. Since many 3D datasets are of considerable size, their inclusion into the knowledge graph as String literals might hinder the query performance of said knowledge graph. It therefore stands to reason whether to adopt the same or a similar method of geometry access that FOG provides for GeoSPARQL 3D.

10.4. To consider

<https://link.springer.com/article/10.1007/s10845-023-02246-6> Ontology of 3D virtual modeling in digital twin: a review, analysis and thinking

[33]

To help novice engineers understand and scheme 3D virtual modeling in digital twin for future research and applications, this paper reviews 106 digital twin 3D modeling cases with their characteristics, including deployment targets, purposes & roles, collaborative models, data flows, the autonomy of 3D modeling, fidelity, twinning rates, enabling technologies, and enabling tools.

Open standard for particle-mesh data (openPMD)

The [openPMD standard](#), short for open standard for particle-mesh data files is not a file format per se. It provides guidance for meta-data and naming schemes. openPMD provides naming and attribute conventions that allow the exchange of particle and mesh based data from scientific simulations and experiments. Its primary goal is to define a minimal set/kernel of meta information that allows to share and exchange data to achieve portability between various applications and different algorithms, a unified open-access description for scientific data (publishing and archiving), and a unified description for post-processing, visualization and analysis. If outputs from programs, devices (such as cameras), simulations or post-processed data-sets, contain a minimal set of meta information as provided by openPMD, data can be exchanged between those with minimal effort, with the same tools used for visualization.

[19]

10.5. Cultural Heritage

In the research domain of cultural heritage, 3D models of either cultural heritage artifacts (possibly georeferenced), 3D models of archaeological sites or simply 3D models of ancient buildings are becoming increasingly common.

10.5.1. Use Cases

Use Cases in the Cultural Heritage domain include, but are not limited to, the following main interests:

Visualization: The visualization of 3D models for the presentation of such 3D models, for example in the context of a museum. 3D models may be styled with a particular set of textures or modeled with a specific set of colours to highlight certain relevant aspects. The visualization of 3D models is currently standardized by the IIIF 3D working group [29], which aims to create viewing parameter descriptions that 3D viewers may implement, similar to the specifications of IIIF 2D for images.

Object Annotation: 3D models are seen as the subject of a research question in absence of the original artifact for political, practical or other restrictive reasons. Out of all known methods of the representation of cultural heritage artifacts, 3D models provide the most detail when being delivered as a digital artifact and are therefore very often preferred in a research context. Researchers mark noteworthy aspects of the cultural artifact as 3D annotations [28] which may include surface descriptions, volumes of the 3D model or 3D models which are created and placed adjacent to the to-be-annotated 3D model [20].

Relation of Objects: Objects of a specific collections always exist in a spatio-temporal context. It is important to relate these representations via meaningful relations, so that relevant objects of a collection can be retrieved more easily

AI Applications in Cultural Heritage: Usage for annotated areas on 3D models or their derivations for machine learning classifications Stotzner_2023_ICCV 10.2312/gch.20231157

Knowledge Graphs as Metadata descriptions: With the advent of more 3D models being published, the relevance of their creation parameters [31], their contents and their object metadata increases for the usecases of filtering them and also for the possibly automated selection of suitable cultural heritage metadata for e.g. machine learning classifications. Currently, many metadata standards fulfil parts of the description chain and a unified vocabulary to described data types seems to be missing.

10.5.2. Research applications making use of 3D models in Cultural Heritage

This section discusses research projects with 3D contents based on the technologies they use as elaborated in the previous section.

10.5.2.1. 3D models of cuneiform tablets

Cuneiform tablets from ancient Iran provide an interesting research area, since they combine a 3D artifact with textual imprints that are of interest to a variety of research communities including Assyriologists, Digital Humanists, Computational Linguists and last but not least Computer Scientists. The creation of 3D models of cuneiform tablets provides the best accessibility to the specificities of the original artifact in its absence and 3D scans have been

used by computer scientists as the basis for certain machine learning application tasks, even though to this day only as a provision for 2D renderings of their surfaces. Interests of the research community include the description of interesting features such as cuneiform signs on cuneiform tablet surfaces and their connection to other text contents or other cuneiform artifacts. Knowledge graphs provide machine learning approaches Stotzner_2023_ICCV stotzner2023r with unique opportunities to connect different kinds of data using a unified data format.

To describe 3D meshes, several vocabularies have been developed in the context of the cuneiform studies project:

- [MeshSPARQL](#): A vocabulary to describe essential mesh elements
- [Gigamesh Metadata Vocabulary](#): A vocabulary which describes metadata of a 3D model. The metadata can be generated using the Gigamesh Software Framework
- [3DCAP Vocabularies](#): An ontology model to describe the creation of a 3D model. It has been applied to different scanning softwares

10.6. IFC and BIM

10.6.1. Industry Foundation Classes (IFC) and BIM

BIM is a paradigm in which object-model definitions – with machine-interpretable semantics – are exchanged, rather than relying on CAD drawings that convey only graphical semantics. The predominant open exchange standard is Industry Foundation Classes (IFC).

10.6.1.1. Product model

In IFC, a construction work is decomposed into a set of products. These products can have **multiple representations**. For example, a wall can be described as a solid body as well as a two-dimensional axis. These representations facilitate different views on the same data: an editable line segment or an easily visualized volume. The Object-relational nature of the IFC EXPRESS schema allows intricate relationships such as a representation context that communicates additional intent for the representation or presentation styles that can be granularly assigned to individual faces.

At the same time, such a product separates the **placement** (an hierarchical transformation) from the actual geometry definition. The consequence of this is that in spite of its object-relational nature, IFC product representations cannot be used for building-level topological relationships between solids, because even if two solids are touching in 3D, the fact the the placement is externalized out of the geometry definition (or the fact that faces are constructed procedurally and do not exist explicitly), means that the two faces cannot be opposite oriented twins. As

such, relational geometric constructs such as space boundaries are provided as additional supplementary geometries.

In principle, the IFC schema has been designed in a modular fashion with independent modules for, for example, geometry, materials and meta-data. However in other cases, **semantics and geometry are intertwined** such as tapered extrusions (lofts) where the begin and end profile of a duct carry important semantics.

IFC also allows for **decomposition**, where a whole is aggregated into multiple parts for richer semantics. This allows for example to connect materials and meta-data to the frame and the glazing separately, while still being able to identify the aggregate as a single window. This is not used as frequently, partially due to inability to efficiently instantiate such aggregates as geometry instances.

10.6.1.2. Evolving views on geometry

IFC is heavily influenced by the ISO 10303 (STEP) family of standards, but over time adopted its own geometric paradigms:

- Procedural geometry and boolean operations became less prominent with the adoption of ReferenceView in IFC4. Tessellated geometry definitions were added for more compact exchange.
- **Infrastructure definitions** were added with precise mathematical transition curves and a composition of a horizontal, vertical and cant (inclination) profile.
- IFC5 with an **explicit** (most likely triangulated) geometry schema at the core, with semantic overlays to encode the same procedural semantics as a non-mandatory or use-case specific layer. Heavily inspired by USD with layer-based composition for collaborative exchange.

Especially the handling of **tolerances** means that the standard cannot effectively prescribe a consistent outcome in all cases. Tolerances are needed for BRep model with non-linear underlying geometry and/or fixed precision coordinate values, e.g higher degree nurbs curves are typically intersected with numerical approximation, so a vertex that connects two of such curves needs to be seen as a sphere with the local tolerance as its radius. This tolerance is also applied to boolean operations: a subtraction volume can be slightly inwards of the first operand but is still expected to pierce through the volume and increase surface genus. This contrasts with the desire of using IFC as a legal basis in contracts. NB Tolerances stand in the way of using existing approaches for SFA geometry predicates such as PostGIS+SFCGAL which is based on arbitrary precision boolean logic as implemented in CGAL without tolerances.

10.6.1.3. Use cases

The most successful use case on BIM data is **coordination and visualization** where multiple aspect models are geometrically overlaid in order to find issues, which are then communicated

to the authoring software where they are addressed. This approach works, because it respects that individual disciplines all have their own specialistic software.

Design to design workflows are much harder to realize, although some Model View Definitions have been developed on top of IFC that enable the transfer of design intent in specific and constrained scenarios, such as precast concrete and structural steel.

Long-term preservation of building information is difficult because of the fact that IFC models are difficult to mutate, because they are so explicit and don't contain the vendor-specific design intelligence. Therefore native software cannot always re-import IFC models, but also the native models degrade over time because of the need to migrate to newer editions of the software. Software that can directly operate on IFC to make modifications is still experimental.

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- Separate representation+placement → enables efficient reinstatiation, but hinders topological relationships because you require the pair of placement+geometry to locate in space
- Geometry as leaf-values or object-relational model : cannot encapsulate geometry into a single literal, but allows for richer semantics
- BRep model (topology + geometry + orientation + location) vs polyhedral model (e.g halfedge) vs explicit loops of point coordinates
- Procedural vs implicit (e.g constraints) vs explicit (polyhedra)
- Tolerances
- Decomposition inside or outside of the 'geometry ontology'
- Are infra geometries (hor + ver alignment + cant, for positioning and sweeps) in scope?

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10.7.3. BRep vs mesh/polyhedron

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- Extra indirections: edge → vertex[] → point
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Mesh/polyhedron

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- Triangle meshes robust and well understood
- Many different data models though, e.g half-edge (only manifold), indexed faceset (no adjacency info), winged/quad/radial edge

11

CURRENT CAPABILITIES

11.1. GeoSPARQL

GeoSPARQL is the most common geospatial extension of SPARQL. It was accepted as an OGC standard in 2012 and revised as GeoSPARQL 1.1 in 2024.

According to the standard document, “The OGC GeoSPARQL standard supports representing and querying geospatial data on the Semantic Web. GeoSPARQL defines a vocabulary for representing geospatial data in RDF, and it defines an extension to the SPARQL query language for processing geospatial data”.

11.1.1. Requirements addressed

In order to define which capabilities GeoSPARQL needs to adopt for full 3D compatibility, we first take a look at GeoSPARQL 1.1 current capabilities with regards to 3D.

11.1.1.1. Dimensionality

In this white paper, when we discuss three dimensional data, we mean three dimensional geometries; instances of the class [geo:Geometry](#). GeoSPARQL 1.1 defines three different properties for geometry that have to do with dimensionality:

1. [**geo:dimension**](#), or *topological dimension*: This is the number of perpendicular directions in which a geometry extends. A point, for example, extends in no direction, so its topological dimension is 0. A line has a length, but no width or height. Its topological dimension is 1. A cube has a topological dimension of 3.
2. [**geo:coordinateDimension**](#): In the geometric model that GeoSPARQL uses, points are the basic building blocks of geometry. A point geometry can have a different number of coordinates, depending on the space in which it is placed. A point on a flat map, or on the surface of a sphere, needs two coordinates. The *coordinate dimension* is the number of coordinates in the points that define a Geometry.
3. [**geo:spatialDimension**](#): In order to support linear referencing, geometries in GeoSPARQL can have a measure value. This is a relative position along a line or a curve, and does not extend the Geometry in space. The *spatial dimension*, therefore, can be used to denote the number of coordinates in a point, excluding the measurement value.

The extended capabilities for GeoSPARQL discussed in this white paper concern the cases where the *spatial dimension* (which can be expressed with property `geo:spatialDimension`) of geometry has the value 3.

The table below shows the values of the three dimension properties for some Geometries (expressed as Well Known Text (WKT)).

Table 1

GEOMETRY (WKT)	GEO:dimension	GEO:COORDINATEDIMENSION	GEO:SPATIALDIMENSION
point (4 15)	0	2	2
point Z (4 15 3)	0	3	3
linestring (4 15, 13 2)	1	2	2
point M (4 15 60)	0	3	2
point ZM (4 15 3 60)	0	4	3

11.1.1.2. Vocabulary

GeoSPARQL version 1.1 consists of a Core module, a Topology Vocabulary extension, a Geometry extension, a Geometry Topology extension, an RDFS Entailment extension, and a Query Rewrite extension. Each of these modules will be briefly explained below.

11.1.1.3. Core Module

GeoSPARQL version 1.1 includes a CORE module. This defines the basic classes, relationships, and literals. These classes are suitable for both 2D and 3D.

11.1.1.3.1. Topology Vocabulary Extension

This extension provides standard definitions for spatial relationships that can exist between one spatial object and another.

Relations between geometries have been defined using three different sets of rules:

- Simple Features Relations
- Egenhofer Relations
- Region Connection Calculus RCC8

These topological definitions specify topological relations in a 2D-context.

11.1.1.3.2. Geometry Extension

GeoSPARQL 1.1 geometry module defines a class `Geometry` as a subclass of `SpatialObject`.

An instance of `Geometry` is not restricted to two dimensions.

A fine-grained classification of `Geometry` can use the [Simple Feature Vocabulary](#) which extends the class `Geometry` with further types, such as `Point`, `Polygon` etc.

The Simple Features vocabulary allows for the definition of 3D variants of:

- (Multi)Points
- (Multi)LineStrings
- (Multi)Polygons
- PolyhedralSurface

It does not include common 3D primitives, such as `Cube` or `Mesh` surfaces which are integral parts of 3D representations. Nor does it include extruded geometry.

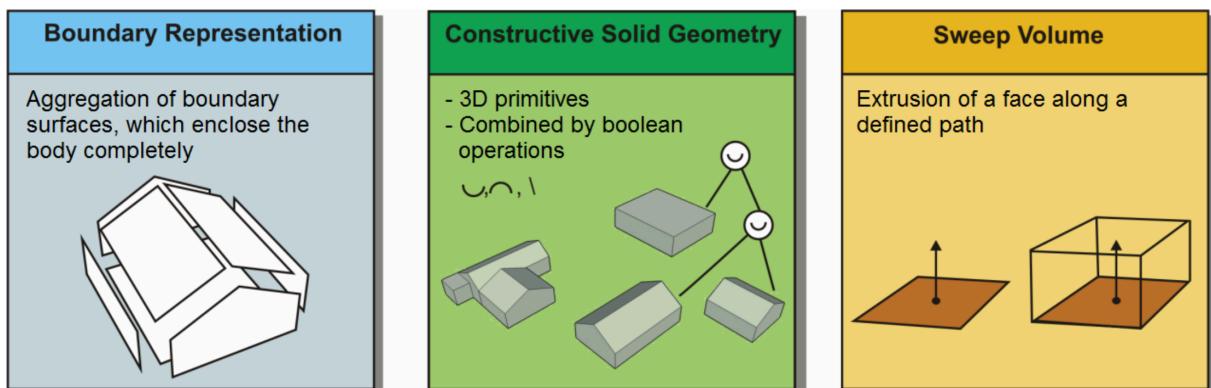


Figure 1 – Possible approaches for representing 3D objects in IFC

Concerning metadata of 3D models, GeoSPARQL 1.1 provides properties which can be reused in 3D contexts. In particular, the properties are:

- `geo:hasVolume`
- `geo:hasMetricVolume`

Further 3D-related metadata properties such as projection matrices are not part of the current GeoSPARQL 1.1 standard.

A first requirement for 3D support is the ability to save 3D data in a knowledge graph.

The Geometry extension enables geometries to be defined within the GeoSPARQL framework. Supported geometry formats include RDF literals in WKT, GML, GeoJSON, and KML.

These literals are investigated for the storage of 3D data.

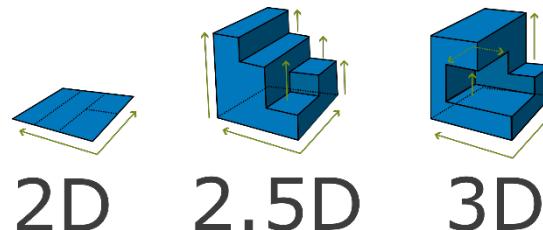


Figure 2 – Difference between 2D, 2.5D and 3D geometry

Table 2

Literal Type	Z-Coordinate Supported	2.5D	3D
WKT Literal	Yes	Yes	Yes
GML Literal	Yes	Yes	Only with extension Schema
KML Literal	Yes	Yes	As import from COLLADA
GeoJSON Literal	Yes	Yes	Yes
DGGS Literal			

GeoSPARQL 1.1 also does not restrict the usage of coordinate reference systems with 3D support. There are currently almost 300 coordinate reference systems in the database epsg.io which can be used to describe 3D data encoded in the GeoSPARQL graph literals listed above.

GeoSPARQL already supports linking multiple geometries (e.g., 2D and 2.5D) to a single feature. We aim to extend this with 3D geometries.

For example, a tree in the real world may be represented in databases with both a 2D and a 3D geometry.

This should not require duplication of the tree entity — there can be one tree instance with both geometries linked, avoiding redundancy in the data model.

11.1.1.4. Query functions with 3D support

GeoSPARQL 1.1 functions currently do not offer fully-featured 3D support. However, there are functions which may take into account the Z coordinate, if they are available.

Table 3

GeoSPARQL function	Z-Coordinate Supported	2.5D	3D
geof:is3D	Yes	Yes	Yes
geof:minZ	Yes	Yes	Yes
geof:maxZ	Yes	Yes	Yes

These functions check for the presence of Z coordinates or filter out maximum and minimum Z coordinates of the given geometry.

11.1.1.5. Geometry Topology Extension

Another extension is the Geometry Topology extension. This provides query functions that return relationships between different geometries based on the topology vocabulary extension.

11.1.1.6. RDFS Entailment Extension

The RDFS Entailment extension provides rules for reasoning over geometries. Based on specific statements, additional information can be inferred. This kind of logical inference can also be applied to geometry. GeoSPARQL includes logic for reasoning over simple features geometries.

11.1.1.7. Query Rewrite Extension

GeoSPARQL allows queries such as whether “Feature A” is located within “Feature B” using its vocabulary. The Query Rewrite extension specifies a RIF rule that enables query rewriting. However, this extension does not support the rewriting of 3D queries.

12

REQUIREMENTS FOR GEOSPARQL 3D

12.1. 5.1 Existing implementation of 3D geometry in GeoSPARQL

This section provides an overview of feedback received on the current version of the GeoSPARQL standard (version 1.1) regarding 3D usage. It helps to identify some of the barriers to use, and to outline requirements that have not been addressed that may encourage greater uptake.

12.1.1. Proposed extensions for GeoSPARQL 3D

12.1.1.1. Extension 1: 3D representations

12.1.1.1.1. GitHub Issue URI

<https://github.com/opengeospatial/ogc-geosparql/issues/583>

12.1.1.1.2. Category

Semantic improvement

12.1.1.1.3. Description

GeoSPARQL should include ways to represent 3D data in a knowledge graph.

3D data should be included in common 3D formats and 3D data should be includable as a text literal and a file representation.

Some common formats which could be considered for inclusion are:

- [Polygon File Format \(PLY\)](#)
- [Wavefront OBJ Format \(OBJ\)](#)
- [GLTF Format \(GLTF\)](#)
- [X3D Format](#)

12.1.1.2. Extension 2: Relations of 3D geometries

12.1.1.2.1. GitHub Issue URI

<https://github.com/opengeospatial/ogc-geosparql/issues/416>

12.1.1.2.2. Category

Semantic improvement

12.1.1.2.3. Description

GeoSPARQL should include ways to represent relations between 3D geometries and relations between 3D geometries and geometries of lower dimensions. The relations should be expressable in property relations and should be queryable using SPARQL extension functions.

12.1.1.3. Extension 3: Appearance of 3D geometries

12.1.1.3.1. GitHub Issue URI

- <https://github.com/opengeospatial/ogc-geosparql/issues/584>
- <https://github.com/opengeospatial/ogc-geosparql/issues/592>

12.1.1.3.2. Category

Semantic improvement

12.1.1.3.3. Description

GeoSPARQL should include ways to represent materials and textures of 3D geometries, so that geometries can be styled accordingly.

Materials include:

- Colors of surfaces with light diffusion parameters
- Images as textures, which are associated with surfaces of the 3D object

12.1.1.4. Extension 4: Multi-component 3D geometries

12.1.1.4.1. GitHub Issue URI

<https://github.com/opengeospatial/ogc-geosparql/issues/591>

12.1.1.4.2. Category

Semantic improvement

12.1.1.4.3. Description

GeoSPARQL should include ways to define multi-component 3D geometries, whereas each component expresses its own semantics. For example, parts of a building could have different semantics according to the function of the building components and would be classified as such in an RDF graph.

12.1.1.5. Extension 5: Positioning of 3D geometries

12.1.1.5.1. GitHub Issue URI

- <https://github.com/opengeospatial/ogc-geosparql/issues/587>
- <https://github.com/opengeospatial/ogc-geosparql/issues/588>
- <https://github.com/opengeospatial/ogc-geosparql/issues/589>
- <https://github.com/opengeospatial/ogc-geosparql/issues/591>

12.1.1.5.2. Category

Semantic improvement

12.1.1.5.3. Description

GeoSPARQL should include ways to position 3D geometries in a 3D space. Commonly 3D geometries are rotated, translated and scaled using commonly defined operators in computer graphics. Similar operations are needed for the relative positioning of 3D objects in GeoSPARQL, as properties and potentially as functions.

12.1.1.6. Extension 6: Alignments of GeoSPARQL 3D

12.1.1.6.1. GitHub Issue URI

- <https://github.com/opengeospatial/ogc-geosparql/issues/590>
- <https://github.com/opengeospatial/ogc-geosparql/issues/574>
- <https://github.com/opengeospatial/ogc-geosparql/issues/571>

12.1.1.6.2. Category

Semantic improvement

12.1.1.6.3. Description

GeoSPARQL 3D should be aligned to other vocabularies and standard which currently provide 3D support in different knowledge domains. Especially alignments to ifcOWL and the X3D vocabulary would position the GeoSPARQL vocabulary as a link between these different standards.

12.1.1.7. Extension 7: Alignments of Engineering CRS to Geospatial CRS

12.1.1.7.1. GitHub Issue URI

<https://github.com/opengeospatial/ogc-geosparql/issues/586>

12.1.1.7.2. Category

Semantic improvement

12.1.1.7.3. Description

GeoSPARQL 3D should provide the opportunity to align a local coordinate system in which most 3D geometries are defined with a coordinate reference. While this work might only be partially done within the scope of GeoSPARQL itself, GeoSPARQL should be aligned with the emerging Ontology CRS developments of OGC and provide necessary functions or properties to create the link.

12.1.1.8. Extension 8: Geometry Extrusion

12.1.1.8.1. GitHub Issue URI

- <https://github.com/opengeospatial/ogc-geosparql/issues/556>
- <https://github.com/opengeospatial/ogc-geosparql/issues/547>

12.1.1.8.2. Category

Semantic improvement

12.1.1.8.3. Description

GeoSPARQL 3D should provide the opportunity to extrude 2D geometries to 3D geometries and vice versa.

12.1.1.9. Extension 9: Geometry Attributes

12.1.1.9.1. GitHub Issue URI

- <https://github.com/opengeospatial/ogc-geosparql/issues/568>
- <https://github.com/opengeospatial/ogc-geosparql/issues/550>
- <https://github.com/opengeospatial/ogc-geosparql/issues/549>
- <https://github.com/opengeospatial/ogc-geosparql/issues/548>
- <https://github.com/opengeospatial/ogc-geosparql/issues/558>

12.1.1.9.2. Category

Semantic improvement

12.1.1.9.3. Description

GeoSPARQL 3D should provide functions and properties that describe essential properties of a 3D Geometry such as its minimum and maximum height, width and depth and its CompactnessRatio.

12.1.1.10. Extension 10: Non-topological Query Functions – 3D Extension

12.1.1.10.1. GitHub Issue URI

- <https://github.com/opengeospatial/ogc-geosparql/issues/556>

12.1.1.10.2. Category

Semantic improvement

12.1.1.10.3. Description

GeoSPARQL 3D should provide the opportunity to execute non-topological query functions on 2D and 3D geometries commonly used in geospatial databases. Proposed extensions include following functions:

- geometry extrusion to the specified line segment
- geometry extrusion to the specified height
- spatiotemporal geometry extrusion to the specified line segment with specific start and end time

12.2. 5.2 3D Geometry available in IFC

This section describes what kind of geometry is available in IFC, and how that relates to (1) different modelling kernels, and (2) geoSPARQL and geospatial geometry engines.

@Thomas Krijnen, Alex Donkers, Pieter Pauwels == to write here please

12.3. 5.3 Vanilla 3D geometry handling in the Semantic Web

This section describes in what other ways 3D geometry is currently handled in the Semantic Web, for example in BOT ontology, OMG and FOG ontologies, and few more.

12.4. 5.4 Concluding overview of requirements for 3D geometry in the semantic web

A concluding summary with a list of requirements to be taken into account for future development in different places and organisations.

13

BENEFICIARIES AND BENEFITS

This section describes the beneficiaries and benefits of representing data, including geospatial data, using semantic and graph technologies. Furthermore, a collection of use cases demonstrate how semantic and graph technologies are used together with spatial data to tackle real world problems.

13.1. Semantic-functional value of 3D-GeoSPARQL

Value for data reasoning, formal description, and semantic interoperability

13.1.1. Meaningful creation and querying of 3D geometry

Whether manually or programmatically defining 3D geometries in BIM, GEO or CG environments, the GeoSPARQL standard could provide or connect to vocabulary to represent 3D structures. A 3D cube, for example, can be represented in multiple ways:

- As a set of bounding points, lines, and faces;
- As a base surface with an extrude function;
- As an 3D geometric primitive (e.g., the concept of a ‘cube’ as a spatial figure).

Once GeoSPARQL offers the means to define and link 3D geometries in these different ways, it will allow both humans and machines to interpret and interact with the data effectively.

13.1.2. Meaningful creation and querying of 3D topological relationships

Is “3D Geometry A” inside, touching, overlapping, intersecting or above “3D Geometry B”?

Being able to describe and use such topological relationships is crucial for conducting spatial analyses, formulating rules, and deriving knowledge from different heterogeneous datasets.

Beyond describing topological relationships, one should be able to query them:

What is the spatial relationship between 3D Geometry A and 3D Geometry B?

Such queries should return the appropriate topological result (e.g., “intersects”), which is essential for use cases like clash detection in design validation

13.1.3. Derivation of geometric and topological knowledge

From explicitly modeled geometric and topological data, one should be able to infer implicit knowledge.

For instance, if 3D Geometry A is 3D inside 3D Geometry B, then we can infer that:

A does not “touch” B, and A does not “overlap” with B,
even if these facts are not explicitly stated.

For entailment an application that is compliant with the geo-spatial 3D specification would be able to answer queries like: “Does this tree have a 3D geometry?”

If the tree is defined using a MultiSolid geometry, then the answer should be “yes,” even if this is not explicitly declared as such.

13.2. Value for user experience, visualization, and application use of 3D-GeoSPARQL

13.2.1. Visualization

There is a growing need to visualize how 3D data in BIM and GIS relate to one another. Stakeholders want to see BIM and/or 3D Geo data of a newly planned structure visualized within the 3D Geo and/or BIM context of the existing digital city. A shared vocabulary that can present both domains in an integrated way supports this goal.

13.2.2. Calculation and analysis

Semantic modelled 3D-model enables powerful computation and analysis. Analytical results can be displayed in dashboards operating within the GeoBIM domain. This creates a bridge between asset management (typically GIS-oriented) and project management (typically BIM-oriented), allowing for cross-domain collaboration and decision-making.

13.2.3. Spatial querying

Spatial querying is a key function within a federated GeoBIM Network. Questions such as “What material is located in this area?” or “Where is space available for new cables and pipelines?” are examples of 3D spatial queries that can be answered when GeoSPARQL 3D is functioning effectively across systems and semantics.

13.2.4. Machine control

A shared semantic GeoBIM Network also supports machine control. The GIS domain typically describes the existing situation, while the BIM domain describes the intended or future situation. This combination can be used to automatically instruct and guide machines in the built environment.

13.2.5. Modeling, simulation and planning

A network of datasets with 3D-data should support the modeling, simulation and planning of future changes to the built environment. Users – whether human or machine – can use the network and GeoSPARQL 3D to propose and model modifications in either BIM or GIS formats. A well-functioning 3D semantic GeoBIM Network enables this kind of forward-looking spatial planning and design.

13.3. Added value of the 3D-GeoSPARQL for Organisations

13.3.1. Brings together different domains (GIS, BIM, CG)

GeoSPARQL 3D can help in bringing together different domains that work with 3D information.

13.3.2. Enables extension to vocabularies from other domains

The vocabulary can have the possibility to extend to vocabularies with 3D geometry or topology from other domains, for example the Building Ontology Topology (BOT) or RELOC Ontology. Multi-domain models with georeferenced 3D and 2D city models could be also linked by CityRDF ontology based on CityGML 3.0 standard. GeoSPARQL 3D would be important enabler for data retrieval, update and analysis for such models. In addition to ontologies, it can also establish relationships to 3D file formats from other domains, such as glTF.

13.3.3. Facilitates better interoperability between knowledge domains with spatial components (geography, aerospace, architecture, product design, (bio)chemistry, IoT, ...)

A unified geometric language can help by migrating ideas and methods across fields, accelerating innovation. For example a parametric design algorithm, rule, or ILM making use of geometry and topology originated in aerospace, can be re-used in the architecture domain.

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ANNEX N: N

15

ANNEX O: HISTORY



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