

# MADSci: A modular Python-based framework to enable autonomous science

Ryan D. Lewis<sup>1</sup>, Tobias S. Ginsburg<sup>1</sup>, Doga Ozgulbas<sup>1</sup>, Casey Stone<sup>1</sup>, Abraham Stroka<sup>1</sup>, Aileen Cleary<sup>2</sup>, Ian T. Foster<sup>1,3</sup>, and Noah Paulson<sup>1</sup>✉

<sup>1</sup> Argonne National Laboratory, United States <sup>2</sup> Northwestern University, United States <sup>3</sup> University of Chicago, United States ✉ Corresponding author

DOI: [10.xxxxxx/draft](https://doi.org/10.xxxxxx/draft)

## Software

- [Review](#) ↗
- [Repository](#) ↗
- [Archive](#) ↗

Editor: [Arfon Smith](#) ↗ 

## Reviewers:

- [@ktahar](#)
- [@lucask07](#)

Submitted: 19 September 2025

Published: unpublished

## License

Authors of papers retain copyright and release the work under a Creative Commons Attribution 4.0 International License ([CC BY 4.0](https://creativecommons.org/licenses/by/4.0/)).

## Summary

The Modular Autonomous Discovery for Science (MADSci) toolkit enables laboratory automation, high-throughput experimentation, and self-driving labs. MADSci provides a microservices architecture integrating laboratory instruments, robots, and devices with coordination services for workflows, data management, and resource tracking. Users define and execute experiments using Python applications and YAML-based workflow definitions. This modular design separates concerns between device integrators, lab operators, and domain scientists. MADSci supports research in biology, chemistry, materials science, and quantum science.

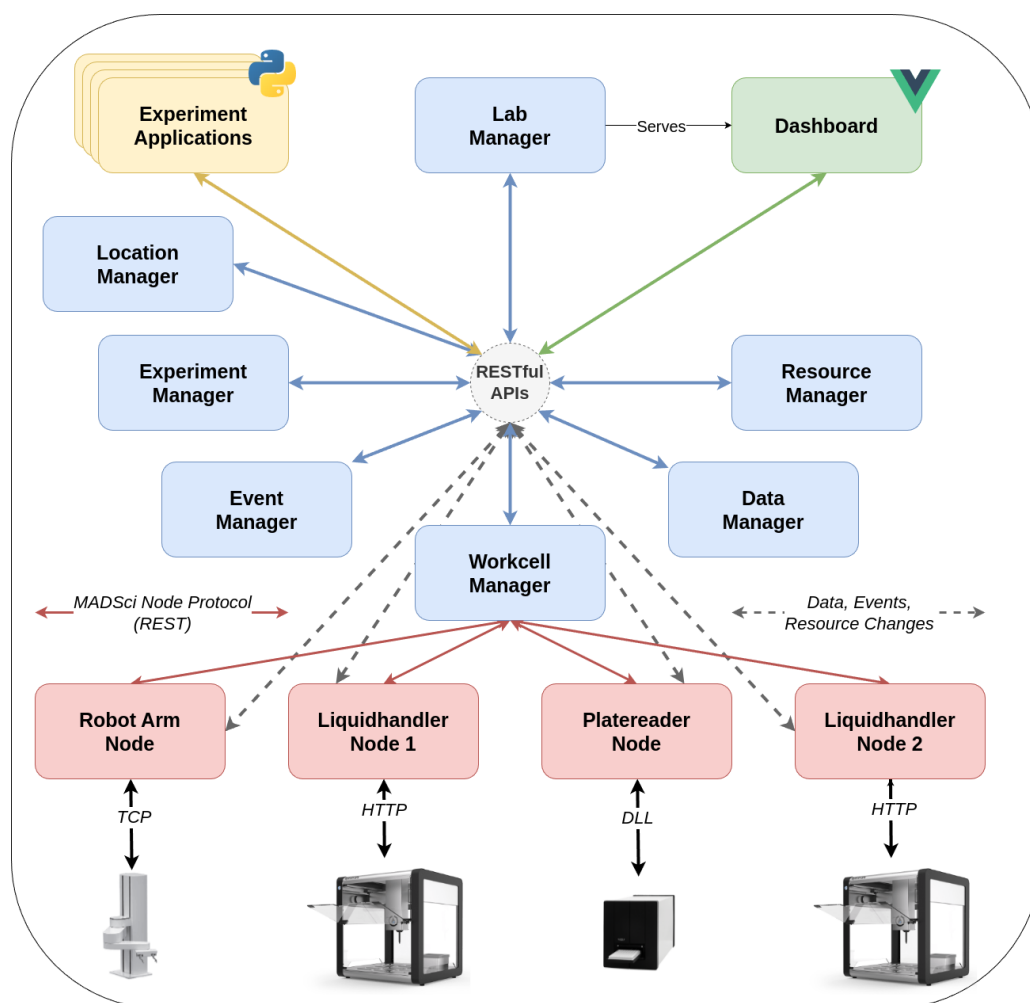
## Statement of Need

The lab automation ecosystem is fragmented, with many proprietary, costly, or narrowly domain-specific tools. MADSci provides an open-source, extensible, domain-agnostic toolkit integrating equipment, sensors, and robots as “nodes” with managers for workflows, resources, experiments, logging, and data collection. Built on a microservices architecture with RESTful APIs and Python clients, MADSci leverages standard databases (PostgreSQL, MongoDB, Redis, MinIO) and open-source libraries (FastAPI, Pydantic, SQLAlchemy).

Commercial platforms such as Chemspeed’s Autosuite (Seifrid et al., 2024) and Retisoft Genera (Retisoft Inc., 2024) provide comprehensive functionality but operate under proprietary licensing that may limit academic accessibility. Open-source alternatives including AlabOS (Fei et al., 2024), ChemOS (Roch et al., 2020; Sim et al., 2024), and Bluesky (Allan et al., 2019) demonstrate strong capabilities within specific domains but exhibit varying cross-disciplinary transferability. Specialized systems such as Polybot (Vriza et al., 2023; Wang et al., 2025) showcase advanced features tailored to particular applications. The Workcell Execution Interface (Vescovi et al., 2023), MADSci’s predecessor, emphasizes instrument modularity but lacks advanced features and microservices principles at the management layer. MADSci provides domain-agnostic laboratory automation while maintaining compatibility with diverse instrumentation and institutional requirements.

## Software Architecture and Features

MADSci’s microservice architecture enables separation of concerns among system components.



**Figure 1:** Schematic architecture diagram for MADSci, depicting the relationship between devices, nodes, managers, and users (via experiment applications and the web-based dashboard).

## Nodes

A node provides a standardized interface to a laboratory instrument, device, robot, or sensor (Figure 1). Any software implementing standard API endpoints can function as a node. We provide a RestNode Python class for device integration. Key endpoints include /action for device functionality, /status for node state, /state for device information, /admin for administrative commands, and /info for metadata and capabilities.

## Workcell and Workflow Management

A workcell represents a collection of nodes, physical locations, and resources coordinated to execute experimental procedures. A workflow is a sequence of steps directing nodes to perform specific actions with specified parameters. A self-driving lab may comprise one or more workcells, each executing workflows semi-independently.

The Workcell Manager coordinates operation through a scheduler determining which workflow steps to execute based on current node, location, and resource states. This modular scheduler can be customized by lab operators; we include an opportunistic first-in-first-out scheduler as default.

Workflows are defined using YAML syntax or Pydantic-based Python data models as linear

53 sequences of steps. Each step specifies a target node, an action, and required or optional  
54 arguments. Beyond JSON-serializable arguments, steps can reference physical locations or  
55 files, with the Workcell Manager resolving location references at runtime.

56 Workflows support parameterization: users specify node, action, or arguments at submission  
57 time, enabling reusable templates. Outputs from earlier steps can inform later parameter  
58 values, allowing intra-workflow data flow.

## 59 Experiment Management

60 An experiment run represents a single execution of an experimental procedure, tracking  
61 associated workflows, resources, data, and metadata. The Experiment Manager enables users  
62 to define experiments, initiate runs, and link MADSci objects (workflows, resources, datapoints)  
63 with those runs. It supports experiment designs specifying properties and conditions under  
64 which experiments are conducted.

65 The `madsci.experiment_application` provides classes for defining experimental applications  
66 in Python, with client libraries and helper methods for common tasks. There are helper  
67 classes available for writing and running experiment applications as scripts, jupyter notebooks,  
68 terminal user interfaces, or even as MADSci nodes themselves, enabling experiment-specific  
69 actions within workflows, which can be monitored and managed from the Lab Dashboard. This  
70 design makes laboratory capabilities accessible to domain scientists while remaining flexible for  
71 integration with other Python tools.

## 72 Data Management

73 The Data Manager supports creation, storage, and querying of data generated during  
74 autonomous experimentation. It stores JSON-serializable data in MongoDB and file-based data  
75 on filesystems or S3-compatible object storage. For large datasets, the `DataClient` optionally  
76 supports direct upload to object storage.

## 77 Resource Management

78 Many laboratories, particularly in chemistry and biology, require tracking physical resources such  
79 as consumables, labware, and samples. The Resource Manager provides optional capabilities  
80 to define, validate, track, and manage these assets across their lifecycle. Built on PostgreSQL,  
81 it supports diverse asset types and hierarchical organization with customizable properties  
82 and standardized operations. It maintains automated histories and locking mechanisms for  
83 provenance and reliability.

## 84 Location Management

85 The Location Manager provides optional tracking of physical laboratory locations and their  
86 associations with resources. Locations represent positions such as instrument slots, storage  
87 areas, or transfer stations within the laboratory environment.

88 This manager integrates with the Resource Manager to enable attachment of resources to  
89 specific locations, facilitating automated tracking of sample positions and consumable storage.  
90 Workflows can reference locations symbolically, with the Workcell Manager resolving these  
91 references at runtime based on current attachments and states. This abstraction separates  
92 physical laboratory layout from workflow logic, improving workflow portability across different  
93 laboratory configurations.

## 94 Event Management and Logging

95 The Event Manager enables nodes and managers to log JSON events to a central MongoDB-  
96 backed system supporting advanced queries. The `EventClient` also optionally supports  
97 OpenTelemetry-based tracing, metrics, and logging, as well as console- and file-based logging

98 via the structlog Python package, enabling multiple different logging and observability  
99 modalities.

## 100 Lab Management

101 The Lab Manager provides a primary entrypoint for users and applications. A web-based  
102 Dashboard provides overview and detailed information on lab status, performance, and history.  
103 The Lab Manager API surfaces context about available managers and lab configuration.

104

## 105 Acknowledgements

106 The authors acknowledge financial support from Laboratory Directed Research and Development  
107 (LDRD) funding from Argonne National Laboratory, provided by the Director, Office of Science,  
108 of the U.S. Department of Energy under Contract No. DE-AC02-06CH11357.

## 109 References

- 110 Allan, D., Caswell, T., Campbell, S., & Rakitin, M. (2019). Bluesky's ahead: A multi-facility  
111 collaboration for an a la carte software project for data acquisition and management.  
112 *Synchrotron Radiation News*, 32(3), 19–22. [https://doi.org/10.1080/08940886.2019.](https://doi.org/10.1080/08940886.2019.1608121)  
113 [1608121](https://doi.org/10.1080/08940886.2019.1608121)
- 114 Fei, Y., Rendy, B., Kumar, R., & others. (2024). AlabOS: A python-based reconfigurable  
115 workflow management framework for autonomous laboratories. *Digital Discovery*, 3(11).  
116 <https://doi.org/10.1039/D4DD00129J>
- 117 Retisoft Inc. (2024). *Genera laboratory automation software*. <https://retisoft.com/>
- 118 Roch, L. M., Häse, F., Kreisbeck, C., & others. (2020). ChemOS: An orchestration software  
119 to democratize autonomous discovery. *PLOS ONE*, 15(4), e0229862. [https://doi.org/10.](https://doi.org/10.1371/journal.pone.0229862)  
120 [1371/journal.pone.0229862](https://doi.org/10.1371/journal.pone.0229862)
- 121 Seifrid, M., Strieth-Kalthoff, F., Hao, H., & others. (2024). Chemsyid: An open-source  
122 python interface for chemspeed robotic chemistry and materials platforms. *Digital Discovery*.  
123 <https://doi.org/10.1039/D4DD00046C>
- 124 Sim, M., Pablo-García, S., Schrier, J., & Aspuru-Guzik, A. (2024). ChemOS 2.0: An  
125 orchestration architecture for chemical self-driving laboratories. *Matter*, 7(5), 1871–1895.  
126 <https://doi.org/10.1016/j.matt.2024.04.021>
- 127 Vescovi, R., Ginsburg, T., Hippe, K., & others. (2023). Towards a modular architecture for  
128 science factories. *Digital Discovery*. <https://doi.org/10.1039/D3DD00142C>
- 129 Vriza, A., Chan, H., & Xu, J. (2023). Self-driving laboratory for polymer electronics. *Chemistry*  
130 *of Materials*, 35(8), 3046–3056. <https://doi.org/10.1021/acs.chemmater.2c03593>
- 131 Wang, C., Kim, Y., Vriza, A., & others. (2025). Autonomous platform for solution processing of  
132 electronic polymers. *Nature Communications*, 16, 1498. [https://doi.org/10.1038/s41467-](https://doi.org/10.1038/s41467-024-55655-3)  
133 [024-55655-3](https://doi.org/10.1038/s41467-024-55655-3)