

# <sup>1</sup> VirtualShip for simulating oceanographic fieldwork in the global ocean

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## Software

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## <sup>8</sup> Summary

<sup>9</sup> VirtualShip is a Python-based package for simulating measurements as if they were coming from real-life oceanographic instruments, facilitating student training, expedition planning, and design of sampling/instrument strategies. The software exploits the customisability of the open-source Parcels Lagrangian simulation framework ([Delandmeter & van Sebille, 2019](#); [Lange & van Sebille, 2017](#)) and builds a virtual ocean by streaming data from the [Copernicus Marine Data Store](#) on-the-fly, enabling expeditions anywhere on the globe.

## Statement of need

Marine science relies on fieldwork for data collection, yet sea-going opportunities are limited due to financial costs, logistical constraints, and environmental burdens. We present an alternative means, namely VirtualShip, for training scientists to conduct oceanographic fieldwork in an authentic manner, to plan future expeditions and deployments, and to directly compare observational and instrumental strategies with model data.

<sup>21</sup> VirtualShip goes beyond simply extracting grid-cell values from model output. Instead, it uses programmable behaviours and sophisticated interpolation techniques (with Parcels underpinnings) to access data in exact locations and timings, as if they were being collected by real-world instruments. VirtualShip shares some functionality with existing tools, such as OceanSpy ([Almansa et al., 2019](#)) and VirtualFleet ([Maze & Balem, 2023](#)), but extends capabilities to mesh many different instrument deployments into a unified expedition simulation framework. Moreover, VirtualShip exploits readily available, streamable data via the Copernicus Marine Data Store, removing the need for users to download and manage large datasets locally and/or arrange for access to remote servers. VirtualShip can also integrate coordinate files exported from the [Marine Facilities Planning](#) (MFP) tool, giving users the option to define expedition waypoints via an intuitive web-based mapping interface.

<sup>32</sup> VirtualShip simulates the deployment of virtual instruments commonly used in oceanographic fieldwork, with emphasis on realism in how users plan and execute expeditions. For example, users must consider ship speed and instrument deployment/recovery times to ensure their expedition is feasible within given time constraints. Possible instrument selections include surface Drifter ([Lumpkin et al., 2017](#)), CTD (Conductivity-Temperature-Depth; Johnson et al. (2007)), Argo float ([Jayne et al., 2017](#)), XBT (Expendable Bathythermograph; Goni et al. (2019)), underway ADCP (Acoustic Doppler Current Profiler; Kostaschuk et al. (2005)), and underway temperature/salinity ([Gordon et al., 2014](#)) probes. More detail on each instrument is available in the [documentation](#).

## 41 Software design

42 The software can simulate complex multidisciplinary expeditions. One example is a virtual  
43 expedition across the Agulhas Current and the South Eastern Atlantic that deploys a suite  
44 of instruments to sample physical and biogeochemical properties ([Figure 1](#)). Key circulation  
45 features appear early in the expedition track, with enhanced ADCP speeds marking the strong  
46 Agulhas Current ([Figure 1b](#)) and drifters that turn back toward the Indian Ocean indicating  
47 the Agulhas Retroflection ([Figure 1c](#)). The CTD profiles capture the vertical structure of  
48 temperature and oxygen along the route, including the warmer surface waters of the Agulhas  
49 region ([Figure 1d](#), early waypoints) and the Oxygen Minimum Zone in the South Eastern  
50 Atlantic ([Figure 1e](#), final waypoints).

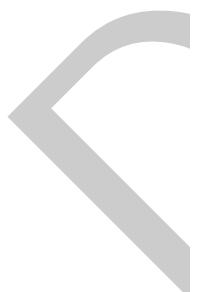
51 The software is designed to be highly intuitive to the user. It is wrapped into three high-level  
52 command line interface commands using [Click](#):

- 53 1. `virtualship init`: Initialises the expedition directory structure and an `expedition.yaml`  
54 configuration file, which controls the expedition route, instrument choices and deployment  
55 timings. A common workflow is for users to import pre-determined waypoint coordinates  
56 using the `--from-mfp` flag in combination with a coordinates `.csv` or `.xlsx` file  
57 (e.g. exported from the [MFP](#) tool).
- 58 2. `virtualship plan`: Launches a user-friendly Terminal-based expedition planning User  
59 Interface (UI), built using [Textual](#). This allows users to intuitively set their waypoint  
60 timings and instrument selections, and also modify their waypoint locations.
- 61 3. `virtualship run`: Executes the virtual expedition according to the planned configuration.  
62 This includes streaming data via the [Copernicus Marine Data Store](#), simulating the  
63 instrument behaviours and sampling, and saving the output in [Zarr](#) format.

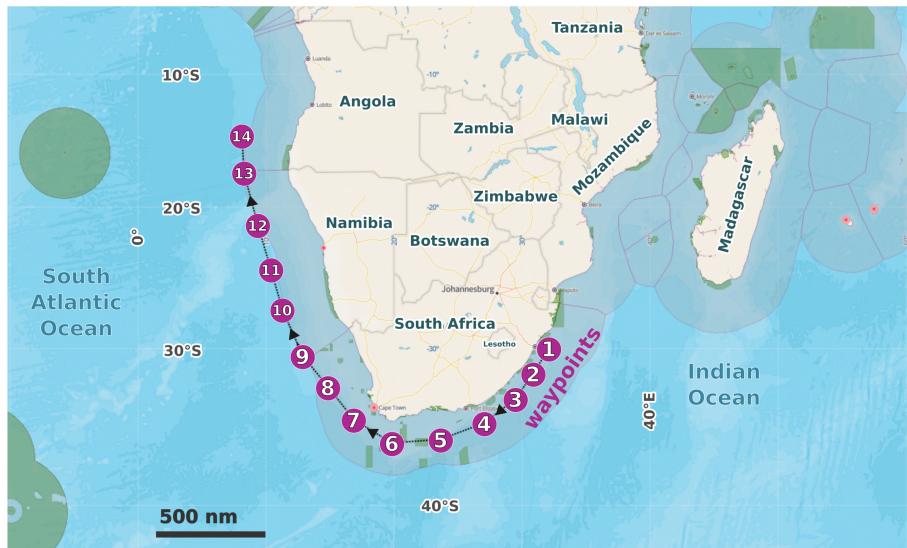
64 A full example workflow is outlined in the [Quickstart Guide](#) documentation.

65 Under the hood, VirtualShip is modular and extensible. The workflows are designed around  
66 Instrument base classes and instrument-specific subclasses and methods. This means the  
67 platform can be easily extended to add new instrument types. Instrument behaviours are coded  
68 as Parcels kernels, which allows for extensive customisability. For example, a Drifter advects  
69 passively with ocean currents, a CTD performs vertical profiling in the water column and an  
70 ArgoFloat cycles between ascent, descent and drift phases, all whilst sampling physical and/or  
71 biogeochemical fields at their respective locations and times.

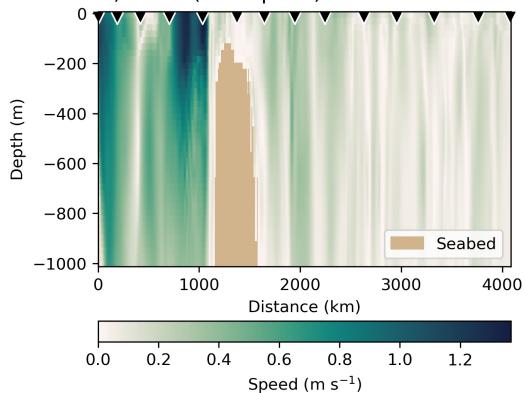
72 Moreover, the data ingestion system relies on Analysis-Ready and Cloud-Optimized data  
73 (ARCO; Stern et al. (2022), Abernathey et al. (2021)) streamed directly from the Copernicus  
74 Marine Data Store, via the [copernicusmarine](#) Python toolbox. This means users can simulate  
75 expeditions anywhere in the global ocean without downloading large datasets by default.  
76 Leveraging the suite of [physics and biogeochemical products](#) available on the Copernicus  
77 platform, expeditions are possible from 1993 to present and forecasted two weeks into the  
78 future. There is also an [option](#) for the user to specify local NetCDF files for data ingestion, if  
79 preferred.



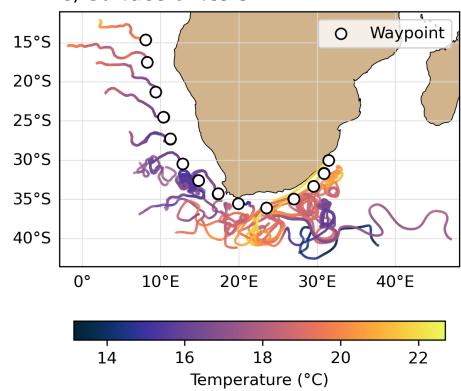
a) MFP expedition overview



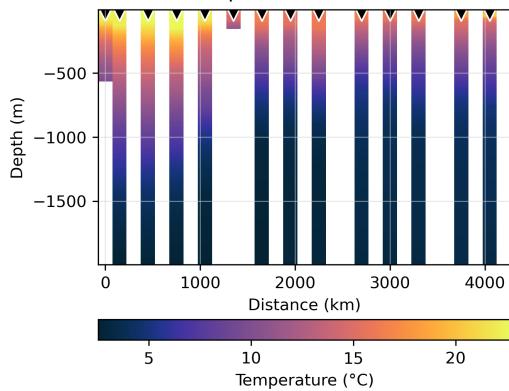
b) ADCP (flow speed)



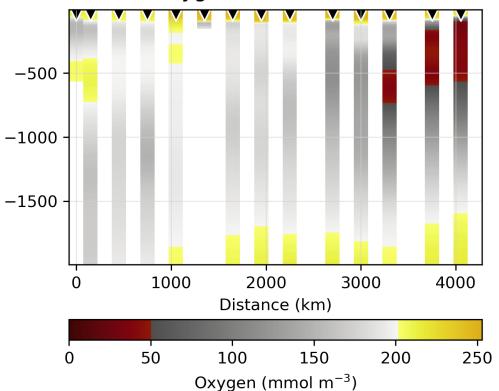
c) Surface drifters



d) CTD (temperature)



e) CTD (oxygen)



**Figure 1:** Example VirtualShip expedition simulated in July/August 2023. Expedition waypoints displayed via the MFP tool (a), Underway ADCP measurements (b), Surface drifter releases (c; 90-day lifetime per drifter), and CTD vertical profiles for temperature (d) and oxygen (e). Black triangles in b), d) and e) mark waypoint locations across the expedition route, corresponding to the purple markers in a).

## 80 Research impact statement

81 VirtualShip has already been extensively applied in Master's teaching settings at Utrecht  
82 University as part of the [VirtualShip Classroom](#) initiative. Educational assignments and tutorials  
83 have been developed alongside to integrate the tool into coursework, including projects where  
84 students design their own research question(s) and execute their fieldwork and analysis using  
85 VirtualShip. Its application has been shown to be successful, with students reporting increased  
86 self-efficacy and knowledge in executing oceanographic fieldwork ([Daniels et al., 2025](#)).

87 The package opens space for many other research applications. It can support real-life  
88 expedition planning by letting users test sampling routes before going to sea. It also provides  
89 tooling to explore real-time adaptive strategies in which sampling plans shift as forecasts or  
90 observations update. The same workflow can also be used to investigate sampling efficiency,  
91 for example, examining how waypoint number or spacing shapes the ability to capture features  
92 of interest. Moreover, the software is well-suited for developing Observation System Simulation  
93 Experiments (OSSEs; e.g. [Errico et al. \(2013\)](#)) to test and optimise observational strategies  
94 in a cost- and time-efficient manner. This framework further enables instrument design  
95 experiments that are relevant to autonomous observing systems. There is potential for users  
96 to prototype and test control strategies for gliders, REMUS vehicles, and Saildrones, as well as  
97 explore concepts for new instruments at early stages of development. Future tutorials could  
98 demonstrate how to define custom instruments within the VirtualShip framework.

99 Both the customisability of the VirtualShip platform and the exciting potential for new  
100 ARCO-based data hosting services in domains beyond oceanography (e.g., [atmospheric science](#))  
101 means there is potential to extend VirtualShip (or "VirtualShip-like" tools) to other domains  
102 in the future. Furthermore, as the Parcels underpinnings themselves continue to evolve, with  
103 a future (at time of writing) [v4.0 release](#) focusing on alignment with [Pangeo](#) standards and  
104 Xarray data structures ([Hoyer & Hamman, 2017](#)), VirtualShip will also benefit from these  
105 improvements, further enhancing its capabilities, extensibility and compatibility with modern  
106 cloud-based data pipelines.

## 107 AI usage disclosure

108 Generative AI technologies (Gemini v2.0/2.5/3.0, ChatGPT v4o/5.0/5.1/5.2 and GitHub  
109 Copilot) were used for code generation, refactoring and test scaffolding. AI-assisted  
110 autocompletion tools (via GitHub Copilot) were used in the writing of this manuscript. Authors  
111 carefully reviewed and edited all AI-assisted content and made the core design decisions  
112 without use of AI.

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