

¹ ExaGOOP: an AMReX-based material point method solver

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Software

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⁸ Summary

⁹ ExaGOOP is a versatile continuum mechanics solver based on the material point method (MPM).
¹⁰ Traditional numerical solvers for continuum physics typically employ finite difference, volume, or
¹¹ element methods. These approaches require the entire computational domain to be discretized
¹² using a computational grid, where the governing equations are solved in differential, integral
¹³ or variational forms. The necessity of a computational grid with complex geometries makes
¹⁴ it challenging to solve problems involving highly deformable and history-dependent materials
¹⁵ and multiphase systems. In contrast, MPM, like many particle-based methods, is based on a
¹⁶ Lagrangian formulation of the governing equations. Unlike conventional solvers that rely on
¹⁷ grids, MPM stores the material's properties on a collection of particles (also called as material
¹⁸ points). While MPM does require a background mesh, it is most often a uniform Cartesian
¹⁹ grid, and used only as a temporary construct for calculating gradients and is reset after each
²⁰ time integration step. This approach effectively eliminates issues associated with grid element
²¹ deformations. As a result, MPM methods are particularly well-suited for a wide range of
²² continuum mechanics problems, especially those that involve significant material deformations.

²³ ExaGOOP leverages the AMReX ([Zhang et al., 2019](#)) library, which has been widely utilized
²⁴ in adaptive Cartesian grid and particle based applications ([Deak et al., 2025; Esclapez et al., 2023](#);
²⁵ [Henry de Frahan et al., 2024](#); [Hariswaran Sitaraman et al., 2021](#)). The AMReX library
²⁶ facilitates the generation of a block-structured, Cartesian background grid within ExaGOOP
²⁷ and efficient parallelization using distributed memory and performance portable shared memory
²⁸ paradigms. The material points related operations are managed by the particle classes provided
²⁹ by AMReX. Currently, the implementation supports a uniform grid without refinement, but
³⁰ the extension to adaptive grids is part of our future efforts.

³¹ The various steps in an MPM time update include particle-to-grid (P2G), nodal velocity update,
³² grid-to-particle (G2P), and particle position update. ExaGOOP offers users the flexibility to
³³ select the spatial discretization scheme, allowing for the use of linear-hat, quadratic B-spline,
³⁴ or cubic B-spline shape functions for both the P2G and G2P operations. Currently, the nodal
³⁵ update is performed using explicit Euler time integration; however, implicit time stepping
³⁶ schemes are part of ongoing work and is present in beta testing branches. In addition to these
³⁷ options, ExaGOOP allows users to select various numerical input parameters, such as the
³⁸ particle-in-cell (PIC)-Fluid Implicit Particle (FIP) blending factor in the G2P step, and whether
³⁹ to use Update Stress Last (USL) or Modified Update Stress Last (MUSL) for stress calculations.
⁴⁰ The solver also supports CFL-based adaptive time-stepping. At present, ExaGOOP supports
⁴¹ barotropic fluid and linear elastic solid constitutive models. However, adding new constitutive
⁴² models is relatively straightforward for users, requiring only the development of the new
⁴³ constitutive model function without necessitating changes to other parts of the code. Complex,
⁴⁴ static wall boundaries are simulated using the level set method, while moving boundaries can

45 be simulated with fictitious rigid material points.

46 ExaGOOP has undergone extensive validation and verification using 1D, 2D, and 3D test cases,

47 all of which are available in the GitHub repository. Preprocessing scripts in the repository

48 enable users to generate initial material point distribution with the desired number of material

49 points per cell for either for user-defined simple geometries or based on user-provided images of

50 complex bodies. Users can specify the constitutive model for each material point, facilitating

51 multi-body and multi-phase simulations with ease.

52 ExaGOOP was developed and is actively maintained in C++ and utilizes parallelization

53 subroutines from the AMReX library. It employs an MPI+X approach, where Message Passing

54 Interface (MPI) is used to distribute Cartesian grid patches and co-located particles across

55 different distributed memory ranks. Each grid can be further divided into logical tiles, which

56 can be distributed among threads using shared-memory OpenMP on multi-core Central-

57 processing-units (CPU) based machines or among Graphics-processing-units (GPU) threads on

58 NVIDIA/AMD/Intel based GPU-accelerated systems.

59 Statement of Need

60 There are numerous MPM solvers available online, such as Karamelo ([Vaucorbeil et al., 2021](#)),

61 Matter ([Blatny & Gaume, 2025](#)), GEOS-MPM ([Kumar et al., 2019](#)), and Taichi-MPM ([Hu](#)

62 [et al., 2018](#)), but what truly distinguishes ExaGOOP is its performance portability. This

63 allows ExaGOOP to excel on CPU, GPU, and hybrid architectures, making it exceptionally

64 versatile. The advanced memory management, powerful parallel processing capabilities, and

65 robust embedded boundary support offered by the use of AMReX render ExaGOOP as a

66 performance-portable MPM solver. The remarkable exascale performance demonstrated by

67 AMReX in various other solvers highlights ExaGOOP's extraordinary potential to efficiently

68 manage billions of particles on GPU-accelerated and heterogeneous computing systems.

69 ExaGOOP is intended for students, researchers, and engineers interested in simulating multi-

70 material dynamics involving severe deformations. Originally developed as a tool for studying

71 membrane compaction in high-pressure reverse osmosis applications ([Appukuttan, Sitaraman,](#)

72 [et al., 2023; N. A. et al., 2024](#)), ExaGOOP is now being used for simulating continuum

73 mechanics in a variety of other applications such as in lithium-ion battery manufacturing and

74 biomass feedstock flows.

75 Software design

76 ExaGOOP is a modular, performance-portable framework for generalized material point method

77 (MPM) simulations. Its architecture is guided by several key objectives: portability across

78 diverse computing systems, support for heterogeneous CPU and GPU architectures, extensibility

79 of solver capabilities, and strict modularity to ensure a user- and developer-friendly environment.

80 To achieve these objectives, ExaGOOP is constructed on the AMReX framework, which offers a

81 mature, exascale-capable infrastructure with established performance portability. The Cartesian

82 mesh operations in AMReX provide a suitable foundation for the MPM background grid,

83 while its native adaptive mesh refinement supports ExaGOOP's planned adoption of refined

84 background grids. The inclusion of built-in linear solvers facilitates the extension to implicit

85 time-integration schemes. Additionally, embedded boundary (EB) data structures streamline

86 the representation of essential boundary conditions. Furthermore, AMReX's particle classes

87 correspond directly to material points, enabling ExaGOOP to perform particle–grid transfers

88 and constitutive updates efficiently.

89 Most existing MPM packages are domain-specific, monolithic, or closely integrated with

90 particular physics models, which limits their adaptability for methodological research.

91 Contributing to these projects would not have aligned with ExaGOOP's objectives of physics-

92 agnostic design, modular extensibility, and sustained performance portability. Developing
93 ExaGOOP as an independent framework enables researchers to introduce new physics via
94 constitutive models while utilizing AMReX's established scalability and exascale-capable
95 infrastructure.

96 Research impact statement

97 ExaGOOP has facilitated multiple scientific investigations, demonstrating its utility as a flexible,
98 reproducible MPM research framework. For example, it enabled the study of membrane
99 support-layer compaction under ultra-high-pressure reverse osmosis (UHPRO) conditions,
100 in which material points were directly generated from scanning electron microscopy (SEM)
101 images. This approach allowed for an accurate representation of membrane microstructure with
102 minimal preprocessing. The simulated compaction results closely aligned with experimental
103 data on overall strain and qualitative pore deformation (Appukuttan, Sitaraman, et al., 2023).
104 Additionally, ExaGOOP supported a numerical study on the stability characteristics of standard
105 MPM formulations (Appukuttan, Deak, et al., 2023), yielding insights into algorithmic behavior
106 that are challenging to obtain with monolithic or application-specific codes. The framework has
107 also been applied to simulations involving lithium-ion battery materials and biomass feedstock
108 mechanics (Hari Sitaraman et al., 2024), underscoring its versatility across diverse research
109 domains.

110 The project is designed to promote community adoption and facilitate near-term impact. Its
111 documentation offers a comprehensive introduction to MPM theory, step-by-step tutorials,
112 and validation examples, enabling new users to reproduce results and extend the framework
113 with confidence. The repository features a permissive open-source license, clear contribution
114 guidelines, and versioned releases, which support transparency and long-term maintainability.
115 Collectively, these features establish ExaGOOP as a credible and extensible platform for
116 advancing future MPM research and methodological innovation.

117 AI usage disclosure

118 No generative AI tools were used in the development of this software, the writing of this
119 manuscript, or the preparation of supporting materials.

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