

¹ pedon: A Python package for analyzing unsaturated soil hydraulic properties

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DOI: [10.xxxxxx/draft](https://doi.org/10.xxxxxx/draft)

Software

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Editor: 

Submitted: 12 January 2026

Published: unpublished

⁸ Summary

⁹ pedon is a Python package for describing and analyzing unsaturated soil hydraulic properties.
¹⁰ It provides a framework for soil hydraulic models, along with tools for retrieving parameters
¹¹ from soil databases, applying pedotransfer functions, and fitting soil hydraulic parameters to
¹² measurements.

¹³ Statement of need

Researchers and engineers working with unsaturated soils need estimates of soil parameters for variably saturated groundwater flow models. pedon provides a Python toolkit that brings together soil hydraulic models, parameter databases, pedotransfer functions, and fitting routines, making soil analysis faster, more reproducible, and easier to integrate into existing groundwater modeling workflows.

¹⁹ Soil hydraulic models

²⁰ A soil hydraulic model is a parametric description of soil hydraulic functions: the soil water
²¹ retention curve (SWRC) and the unsaturated hydraulic conductivity function (HCF). These
²² relate soil water content and flow to pressure head and vice versa for use in variably saturated
²³ groundwater flow models. At this time, pedon provides the following soil models:

- ²⁴ ▪ [pedon.Genuchten](#): Mualem-van Genuchten ([van Genuchten, 1980](#))
- ²⁵ ▪ [pedon.Brooks](#): Brooks-Corey ([Brooks & Corey, 1964](#))
- ²⁶ ▪ [pedon.Panday](#): Mualem-van Genuchten SWRC and Brooks-Corey HCF ([Fuentes et al., 1992; Panday, 2025](#))
- ²⁷ ▪ [pedon.Fredlund](#): Fredlund-Xing ([Fredlund & Xing, 1994](#))
- ²⁸ ▪ [pedon.Haverkamp](#): Haverkamp ([Haverkamp et al., 1977](#))
- ²⁹ ▪ [pedon.Gardner](#): Gardner(-Kozeny) ([Bakker & Nieber, 2009; Brutsaert, 1967; Gardner, 1958; Mathias & Butler, 2006](#))
- ³⁰ ▪ [pedon.Rucker](#): Gardner-Rucker ([Rucker et al., 2005](#))
- ³¹ ▪ [pedon.GenuchtenGardner](#): Mualem-van Genuchten SWRC and Gardner HCF ([Gardner, 1958; van Genuchten, 1980](#))

³⁵ Software design

³⁶ The soil models are implemented as Python classes with model-specific methods for evaluating
³⁷ the SWRC and HCF. For example, the Mualem–van Genuchten model can be used as follows:

```

import numpy as np
import pedon as pe

mg = pe.Genuchten(
    k_s=106.1, # saturated conductivity (cm/d)
    theta_r=0.065, # residual water content (-)
    theta_s=0.41, # saturated water content (-)
    alpha=0.075, # shape parameter (1/cm)
    n=1.89, # shape parameter (-)
)

h = np.logspace(-2, 6, 9) # pressure head (cm)
theta = mg.theta(h) # water content (-) at pressure head values
k = mg.k(h) # hydraulic conductivity (cm/d) at pressure head values

```

38 The object-oriented design and duck typing provides a clear and consistent structure in
 39 which users can define custom soil model classes. Additionally, pedon only depends on well-
 40 maintained packages in the Python scientific ecosystem such as NumPy (Harris et al., 2020),
 41 SciPy (Virtanen et al., 2020), Matplotlib (Hunter, 2007), and Pandas (McKinney, 2010; The
 42 pandas development team, 2020).

43 Soil hydraulic parameters

44 Soil hydraulic parameters depend on soil type and determine the shape of a soil model's SWRC
 45 and HCF. They are rarely measured directly and are usually derived from reference datasets,
 46 empirical relationships, or laboratory measurements. pedon links these parameters to soil
 47 models and provides a framework to obtain them from existing datasets, easily measured soil
 48 properties, and direct measurements of soil water content and hydraulic conductivity.

49 Parameter datasets

50 pedon includes a dataset of Brooks–Corey and Mualem–van Genuchten parameters for a
 51 wide range of soils. At present, this dataset is compiled from three established soil hydraulic
 52 parameter databases:

- 53 ▪ Average parameter values for twelve major soil textural groups defined by Carsel &
 54 Parrish (1988), also used in the HYDRUS software for variably saturated flow modeling
 55 (Simunek et al., 2009);
- 56 ▪ A dataset from the VS2D software (Healy, 1990) containing both Brooks–Corey and
 57 Mualem–van Genuchten parameters;
- 58 ▪ The Staring series from the Netherlands (Heinen et al., 2020, 2022; Wösten et al., 2001),
 59 which describes soils using the Mualem–van Genuchten model based on hundreds of
 60 processed samples (van Genuchten, 1980; Wösten & van Genuchten, 1988).

61 The databases can be called via the following code:

```

hydrus = pe.Soil("Sand").from_name(pe.Genuchten, source="HYDRUS")
vs2d = pe.Soil("Sand").from_name(pe.Brooks, source="VS2D")
staring = pe.Soil("B01").from_name(pe.Genuchten, source="Staring_2018")

```

62 Parameter estimation

63 pedon provides two approaches for obtaining soil hydraulic parameters from soil data. The
 64 first uses pedotransfer functions based on easily measured soil properties. The second relies on
 65 direct measurements of soil water content and hydraulic conductivity.

66 **Pedotransfer functions**

67 Pedotransfer functions relate easily measured soil properties (e.g. sand, silt, clay or organic
 68 matter content and bulk density) to soil hydraulic parameters (Bouma, 1989). pedon implements
 69 functions from the literature, including those of Wösten et al. (1999), Wösten et al. (2001),
 70 Cosby et al. (1984), and Cooper et al. (2021). It also provides access to parameter databases
 71 such as Rosetta (Schaap et al., 2001) and HYPAGS (Peche et al., 2024), the latter enabling
 72 estimation from a single value of saturated hydraulic conductivity or representative grain
 73 diameters.

```
# Estimate parameters using Cosby's pedotransfer function
sand_p = 40.0 # sand (%)
clay_p = 10.0 # clay (%)
cosby: pe.Brooks = pe.SoilSample(sand_p=sand_p, clay_p=clay_p).cosby()

# Estimate parameters from saturated conductivity via HYPAGS
ks = 1e-4 # saturated hydraulic conductivity (m/s)
hypags: pe.Genuchten = pe.SoilSample(k=ks).hypags()
```

74 **Soil hydraulic measurements**

75 pedon can estimate parameters directly when measurements of soil water retention and/or
 76 unsaturated hydraulic conductivity are available. A soil model, together with its SWRC and
 77 HCF, is fitted to the data by minimizing the difference between measured and simulated values.
 78 This uses nonlinear least-squares algorithm from SciPy (Virtanen et al., 2020) and follows the
 79 well-established methodology of the RETC software (van Genuchten et al., 1991).

80 **Soil model conversion**

81 The same fitting procedure can translate between soil models. The SWRC and HCF generated
 82 by one model are sampled over a range of pressure heads and refitted using another formulation.
 83 This enables direct model comparison (Figure 1) and facilitates integration with external tools
 84 when a different model is required.

```
# Fitting a Brooks-Corey soil model to existing Mualem-van Genuchten soil model
bc = pe.SoilSample(h=h, theta=theta, k=k).fit(pe.Brooks)
```

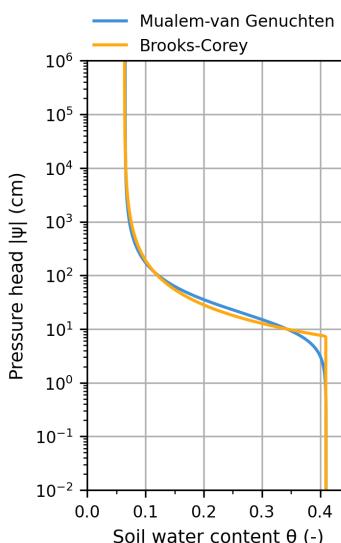


Figure 1: Resulting Brooks-Corey SWRC after fitting on the Mualem-van Genuchten soil model

85 Research impact statement

86 Soil hydraulic functions and their parameters are essential for simulating variably saturated
87 groundwater flow. Determining these parameters experimentally is difficult, time-consuming,
88 and uncertain (Brandhorst et al., 2017; van Genuchten et al., 1991). Therefore, parameters are
89 often approximated or estimated from reference databases, pedon bundles soil hydraulic models
90 and parameter sources in a single framework, enabling efficient parameter derivation without
91 extensive literature searches or ad hoc reimplementation. pedon is already used in scientific
92 workflows for variably saturated groundwater flow modeling, including published studies by
93 Vonk et al. (2024) and Collenteur et al. (2025). It is also a dependency of the Python package
94 [dutchsoils](#), which is used in a academic context to process Dutch soil datasets (Heinen et
95 al., 2022).

96 AI usage disclosure

97 GitHub Copilot was used during development for reviewing pull requests, writing unit tests,
98 providing code completion, and sanity-checking proposed bug fixes. ChatGPT was used for
99 this manuscript to review references, identify linguistic and grammatical errors, and verify
100 compliance with the Journal of Open Source Software requirements. All AI-generated outputs
101 were reviewed by the authors, who take full responsibility for the accuracy and originality of
102 the works.

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