

# <sup>1</sup> dcTMD: a python package for performing <sup>2</sup> dissipation-corrected targeted molecular dynamics

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DOI: [10.xxxxxx/draft](https://doi.org/10.xxxxxx/draft)

## Software

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Editor: [↗](#)

Submitted: 28 November 2025

Published: unpublished

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## <sup>7</sup> Summary

<sup>8</sup> dcTMD is a Python package designed to extract free-energy and non-equilibrium friction estimates <sup>9</sup> from targeted molecular dynamics (TMD) simulations by Schlitter et al. (1994). The method <sup>10</sup> implemented here is called *dissipation-corrected targeted molecular dynamics* (dcTMD) by <sup>11</sup> Wolf & Stock (2018). Given a set of non-equilibrium simulations where, for example, a ligand <sup>12</sup> is pulled from a protein binding site via a velocity constraint, this tool performs automated <sup>13</sup> post-processing of the bias-force time traces to estimate the underlying free-energy landscape <sup>14</sup> and the friction (dissipation) along the unbinding coordinate.

<sup>15</sup> The method is based on a second-order cumulant expansion of the *Jarzynski equality* (Jarzynski <sup>16</sup> (1997)), which connects non-equilibrium work distributions to equilibrium free-energy differences. <sup>17</sup> Combined with a Markovian Langevin Equation, dcTMD further allows the extraction of <sup>18</sup> *position- and velocity-dependent friction coefficients* from the same non-equilibrium data. This <sup>19</sup> approach has been successfully applied in multiple studies (Wolf et al. (2020), Jäger et al. <sup>20</sup> (2022), Post et al. (2022), Tänzel et al. (2024), and Jäger & Wolf (2025) Milster et al. <sup>21</sup> (2025)). The resulting free-energy and friction profiles can subsequently be used to estimate <sup>22</sup> *binding and unbinding rate constants* following Wolf et al. (2020).

<sup>23</sup> The software is intended for molecular dynamics practitioners interested in ligand–protein <sup>24</sup> unbinding, mechanistic interpretation of binding kinetics, and quantitative modeling of non- <sup>25</sup> equilibrium effects in soft condensed matter and biomolecular systems.

## <sup>26</sup> Statement of need

<sup>27</sup> Ligand unbinding from proteins is of fundamental interest in computational biophysics (Schuetz <sup>28</sup> et al. (2017)). In many cases, the unbinding event is rare and requires enhanced-sampling or <sup>29</sup> biased-simulation strategies to observe within computationally feasible timescales. dcTMD- <sup>30</sup> based workflows have been shown to yield accurate free energy and non-equilibrium friction <sup>31</sup> coefficients from velocity-constrained pulling simulations. The dcTMD package builds on this <sup>32</sup> work by offering a unified, documented, and extensible implementation that is currently not <sup>33</sup> available, thereby lowering the barrier for applying dcTMD to new biomolecular systems and <sup>34</sup> for reproducing published dcTMD studies. By providing a dedicated Python framework with a <sup>35</sup> scikit-learn-style API, dcTMD enables users to integrate dissipation-corrected analysis into <sup>36</sup> existing workflows, ensuring reproducibility and broad accessibility.

## 37 State of the field

38 Enhanced sampling methods are readily integrated in simulation software packages, e.g.,  
39 umbrella sampling, or steered MD in GROMACS (Abraham et al. (2015)). Furthermore,  
40 dedicated frameworks such as PLUMED (The PLUMED consortium (2019)), PySAGES  
41 (Zubieta Rico et al. (2024)), and Colvars (Fiorin et al. (2013)) provide infrastructure for  
42 collective variable definition, enhanced sampling and biasing during simulation across multiple  
43 molecular dynamics engines.

44 The present software targets the analysis of an ensemble of constant-velocity pulling trajectories  
45 required for dcTMD. This approach relies on constraint pulling simulations created with  
46 GROMACS in which the reaction coordinate is enforced via holonomic constraints. The  
47 corresponding constraint forces are recorded for subsequent analysis. PLUMED and Colvars  
48 employ steered molecular dynamics through moving harmonic restraints rather than constraint-  
49 based TMD pulling, while PySAGES does not provide support for GROMACS constraint pulling  
50 workflows.

51 To address this gap, we developed a standalone analysis package that handles ensembles  
52 of GROMACS constraint pulling simulations and provides a dedicated workflow for dcTMD  
53 post-processing.

## 54 Software design

55 dcTMD is implemented in Python, since it allows rapid development and community  
56 contributions. Potential performance trade-offs associated with an interpreted language are  
57 mitigated through the usage of optimized numerical backend libraries such as NumPy and  
58 SciPy.

59 The package inherits the core base classes `BaseEstimator` and `TransformerMixin` from *scikit-learn*  
60 (Pedregosa et al. (2011)). Thus, the design follows the familiar `fit/transform`  
61 conventions and ensures interoperability with scikit-learn's ecosystem. This simplifies integration  
62 into analysis pipelines and promotes a familiar workflow for users. The software architecture has  
63 a modular design with five top-level submodules: `dcTMD`, `storing`, `io`, `utils`, and `featureset`.

64 Because trajectory parsing constitutes the dominant runtime cost, we separate data ingestion  
65 from model evaluation. Saving of trajectory data into numpy arrays and the evaluation routines  
66 are separated into two core submodules: `storing` and `dcTMD`. The `storing` submodule defines  
67 the dataset objects `WorkSet` and `ForceSet`. These are data handlers that standardize the  
68 trajectory files into aligned NumPy arrays and allow the processed datasets to be saved to  
69 disk and reloaded without reprocessing the original trajectory files. The estimators reside in  
70 the `dcTMD` submodule and operate directly on these dataset objects. This separation reduces  
71 redundant I/O during iterative analyses.

72 The `io` and `utils` modules isolate file handling, bootstrapping, smoothing, and plotting utilities.  
73 Finally, the `featureset` enables pathway-level analysis by loading trajectory-specific feature  
74 files into a consistent array representation, enabling downstream similarity/clustering workflows.

## 75 Research impact statement

76 As mentioned above, dcTMD has been already shown to efficiently coarse-grain system  
77 dynamics for such diverse systems as protein-ligand complexes (Wolf et al. (2020)), ion  
78 channels (Jäger et al. (2022)) or to gain insight into shear-dependent viscosities in solvents  
79 and lubricants (Post et al. (2022), Milster et al. (2025)). The method thus has proven its  
80 capabilities to the scientific community. Its distribution so far was hampered by the necessity  
81 to manually implement dcTMD in the form of self-written scripts. The presented package  
82 represents a comprehensive and easy-to-use tool to allow other groups who are interested

83 in applying dcTMD to their problems, that has been optimized for fast and efficient data  
84 evaluation with minimal runtime and memory requirements. We allow not only for dissipation  
85 correction or friction coefficient calculation via a work-based analysis, but to gain insight into  
86 bath degrees of freedom via a force-correlation analysis. Furthermore, the standardised outputs  
87 allow for data evaluation quality control across research groups and allow for the establishment  
88 of best practices in the usage of dcTMD. The software has already been successfully applied  
89 in the following studies: Tänzel et al. (2024), Lalis et al. (2025), Jäger & Wolf (2025), and  
90 Milster et al. (2025).

## 91 Implementation

92 The code is written in Python (versions 3.9–3.14) and is available under the MIT license.  
93 **Repository:** <https://github.com/moldyn/dcTMD>

94 Key features include:

- 95 ▪ Input support for *GROMACS* pulling trajectories.  
96 ▪ Core functionality for computing free energy and non-equilibrium friction profiles along  
97 the biasing coordinate.  
98 ▪ Support for analysis of multiple unbinding pathways.  
99 ▪ Force correlation analysis for non-equilibrium friction analysis.  
100 ▪ Continuous integration and testing via GitHub Actions; documentation hosted at <https://moldyn.github.io/dcTMD>.

## 102 Use case

103 A typical workflow begins with the user performing at least 100 independent velocity-constraint  
104 pulling simulations. dcTMD provides two analysis routes, both following the same workflow  
105 pattern:

- 106 1. Work-based analysis using a `WorkSet` and `WorkEstimator`  
107 2. Force-correlation analysis using a `ForceSet` and `ForceEstimator`

108 Both methods yield free-energy and friction profiles but differ in how these properties are  
109 estimated.

110 1. Load trajectories into a `WorkSet` or `ForceSet` The user loads all pulling trajectories into  
111 an appropriate container:

- 112 ▪ `WorkSet` for the work-based route, which is computationally cheaper, as the resolution  
113 of the trajectories can be reduced after integration.  
114 ▪ `ForceSet` for the force-correlation route.

115 Each trajectory contains the constraint force  $f(t)$  from which the work along the pulling  
116 coordinate is computed as  $W(x) = \int_{x_0}^x dx' f(x')$ .

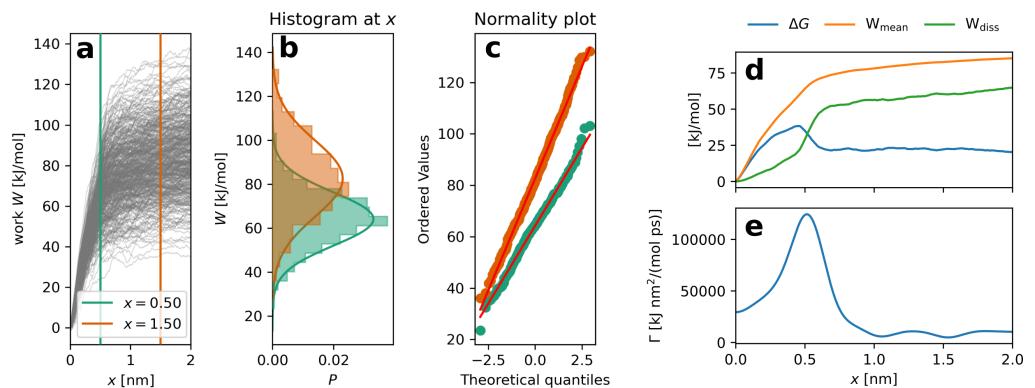
117 2. Perform dcTMD analysis via an estimator

118 ▪ **Work-based estimator (`WorkEstimator`)** The free-energy profile is estimated as  $\Delta G(x) =$   
119  $\langle W(x) \rangle - \frac{\beta}{2} \langle \delta W(x)^2 \rangle$ , with  $\delta W = W - \langle W \rangle$ ,  $\beta = (k_B T)^{-1}$ , and  $\langle \cdot \rangle$  denoting a  
120 trajectory ensemble mean. The dissipated work is  $W_{\text{diss}}(x) = \frac{\beta}{2} \langle \delta W(x)^2 \rangle$ . The  
121 non-equilibrium position-dependent friction is obtained from its derivative as  $\Gamma(x) =$   
122  $\frac{1}{v} \frac{d}{dx} W_{\text{diss}}(x)$ .

123 ▪ **Force-correlation-based estimator (`ForceEstimator`)** In this approach,  $\Delta G$  and  $\Gamma$  are  
124 computed directly from the force data as  $\Delta G(x) = \int_{x_0}^x dx' \langle f(x') \rangle - v \int_{x_0}^x dx' \Gamma(x')$

125 and  $\Gamma(x) = \beta \int_0^{t(x)} d\tau \langle \delta f(t(x)) \delta f(\tau) \rangle$ . The two-time force autocorrelation function  
 126  $C_t(\tau) = \langle \delta f(t(x)) \delta f(\tau) \rangle$  can be plotted to gain insight into timescales within degrees  
 127 of freedom orthogonal to  $x$ .

128 3. Visualize dcTMD provides plotting tools for work distribution analysis, free-energy  $\Delta G(x)$   
 129 and friction profiles  $\Gamma(x)$ .



**Figure 1:** Figures created using data taken from Wolf et al. (2020) of trypsin-benzamidine unbinding. a)-c) work distribution analysis. d) Decomposition of mean work  $W_{\text{mean}} = \langle W(x) \rangle$  into free energy  $\Delta G(x)$  and dissipation work  $W_{\text{diss}}(x)$ . e) non-equilibrium friction coefficient  $\Gamma(x)$  along the pulling coordinate  $x$ .

130 4. Example Figure 1 displays a common analysis of a set of unbinding trajectories from  
 131 TMD simulations of the trypsin-benzamidine complex (Wolf et al., 2020). The analysis of  
 132 the work distribution displays good agreement with a normal distribution at two different  
 133 evaluated positions of the pulling coordinate  $x$ . The mean work  $W_{\text{mean}} = \langle W(x) \rangle$ , which  
 134 shows no features on its own, yields a free energy profile  $\Delta G(x)$ , which displays a clearly  
 135 defined transition state at  $x \approx 0.45$  nm as well as a bound state in form of a free energy  
 136 minimum at  $x \approx 0.0$  nm and an unbound continuum for  $x > 0.6$  nm. The maximum in  
 137 friction  $\Gamma$  around  $x = 0.5$  nm is indicative of changes in the hydration of both ligand and  
 138 binding site.

## 139 AI usage disclosure

140 Generative AI (ChatGPT with models GPT-4, GPT-4o and GPT-5) was used in a limited  
 141 capacity during development. It assisted by drafting portions of the documentation, drafting  
 142 code for selected tests, utility functions, and parts of the featureset module, and preparing  
 143 an initial draft of the manuscript text. All scientific concepts, core design decisions, and  
 144 implementation of the core modules (dcTMD, io, and storing) were developed without  
 145 generative AI. The authors guarantee that they reviewed, edited, and validated all AI-assisted  
 146 outputs.

## 147 Acknowledgements

148 The implementation of dcTMD builds on the Python scientific stack, relying on **NumPy** (Harris  
 149 et al. (2020)) for numerical operations, **Matplotlib** (Hunter (2007)) for visualization, and  
 150 **Click** (The Pallets Projects (2023)) for the command-line interface. We thank Gerhard Stock,  
 151 Matthias Post and Georg Diez for valuable discussions, and Fabian Rohrbach and Leo Küchler

for testing the software. This work has been supported by the Deutsche Forschungsgemeinschaft (DFG) via grants WO2410/2-1 and WO2410/2-2 within the framework of the Research Unit FOR 5099 “Reducing complexity of nonequilibrium systems” (project No. 431945604). The authors acknowledge support by the High Performance and Cloud Computing Group at the Zentrum für Datenverarbeitung of the University of Tübingen and the Rechenzentrum of the University of Freiburg, as well as the state of Baden-Württemberg through bwHPC and the DFG through Grants Nos. INST 37/935-1 FUGG and INST 39/963-1 FUGG.

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