

# Trash AI: A Web GUI for Serverless Computer Vision Analysis of Images of Trash

Win Cowger<sup>1</sup>, Steven Hollingsworth<sup>2¶</sup>, Day Fey<sup>2</sup>, Mary C Norris<sup>2</sup>, Walter Yu<sup>3</sup>, Kristiina Kerge<sup>4</sup>, Kris Haamer<sup>4</sup>, Gina Durante<sup>2</sup>, and Brianda Hernandez<sup>2</sup>

1 Moore Institute for Plastic Pollution Research, USA 2 Code for Sacramento and Open Fresno, USA 3 California Department of Transportation, USA 4 Let's Do It Foundation, Estonia ¶ Corresponding author

DOI: [10.21105/joss.05136](https://doi.org/10.21105/joss.05136)

## Software

- [Review ↗](#)
- [Repository ↗](#)
- [Archive ↗](#)

---

Editor: Arfon Smith [↗](#) 

Reviewers:

- [@domna](#)
- [@luxaritas](#)

Submitted: 28 November 2022

Published: 28 September 2023

## License

Authors of papers retain copyright and release the work under a Creative Commons Attribution 4.0 International License ([CC BY 4.0](#)).

## Summary

Although computer vision classification routines have been created for trash, they have not been accessible to most researchers due to the challenges in deploying the models. Trash AI is a web GUI (Graphical User Interface) for serverless computer vision classification of individual items of trash within images, hosted at [www.trashai.org](http://www.trashai.org). With a single batch upload and download, a user can automatically describe the types and quantities of trash in all of their images.

## Statement of need

Trash in the environment is a widespread problem that is difficult to measure. Policy makers require high quality data on trash to create effective policies. Classical measurement techniques require surveyors with pen and paper to manually quantify every piece of trash at a site. This method is time-consuming. Scientists are actively trying to address this issue by using imaging to better understand the prevalence and distribution of trash in an efficient yet effective manner ([K. Kerge, 2020](#); [Lieshout et al., 2020](#); [Lynch, 2018](#); [Majchrowska et al., 2022](#); [Moore et al., 2020](#); [Proen  a & Sim  es, 2020](#); [Waterboards, 2018](#); [Wuu, 2018](#)). Image-based reporting of trash using cell phones, laptops, and other devices has been a valuable solution ([Lynch, 2018](#)). Applications for AI in detecting trash using imagery currently include: cameras mounted on bridges ([Lieshout et al., 2020](#)), drone imaging ([Moore et al., 2020](#)), cameras on street sweepers ([Waterboards, 2018](#)), and cell phone app based reporting of trash ([Lynch, 2018](#)). Although there are many artificial intelligence algorithms developed for trash classification, none are readily accessible to the average litter researcher. The primary limitation is that artificial intelligence (AI) algorithms are primarily run through programming languages (not graphic user interfaces), difficult to deploy without AI expertise, and often live on a server (which costs money to host). New developments in browser-side AI (e.g., tensorflow.js) and serverless architecture (e.g., AWS Lambda) have created the opportunity to have affordable browser-side artificial intelligence in a web GUI, alleviating both obstacles. We present Trash AI, an open source service for making computer vision available to anyone with a web browser and images of trash.

## Demo

We have a full video tutorial on [Youtube](#)

## Basic workflow:

1.

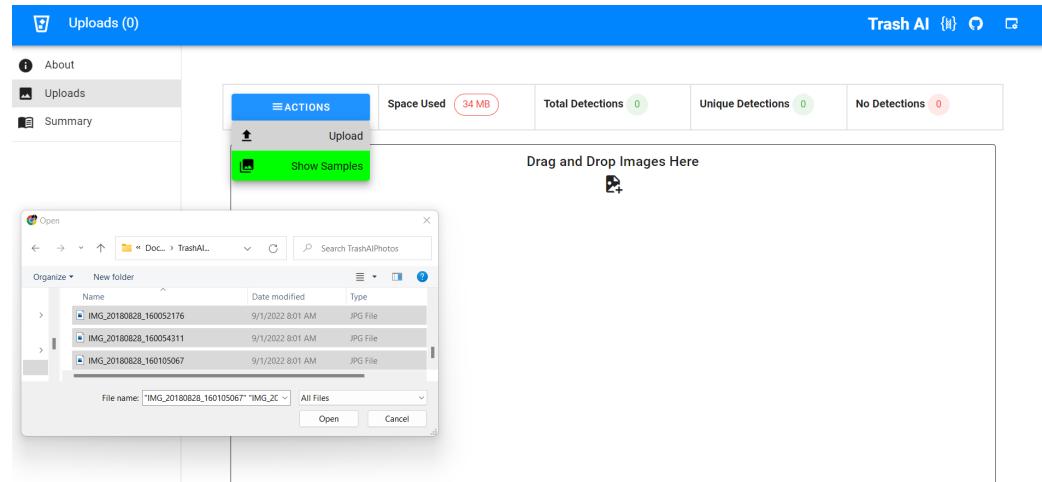


Figure 1: Upload images by dragging onto the screen.

2.

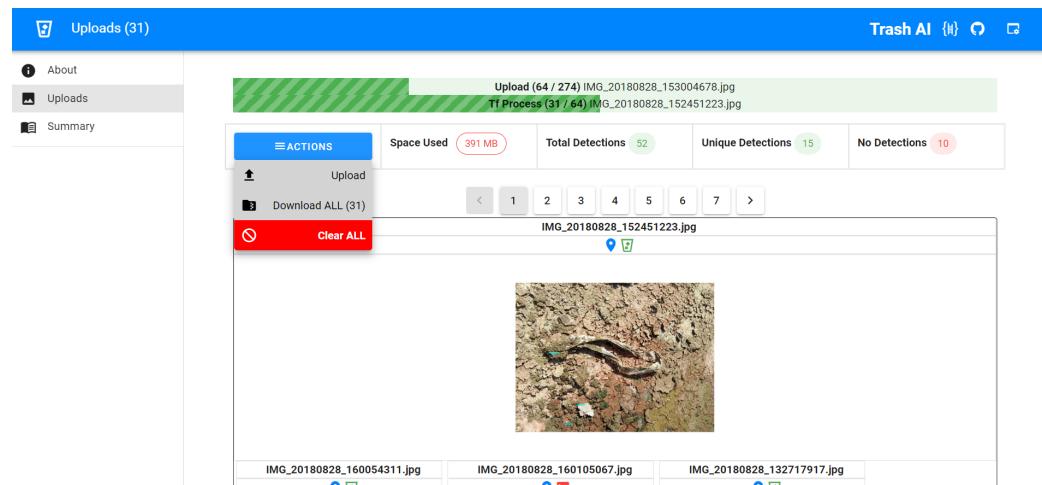


Figure 2: View results while images are processing.

### 3.

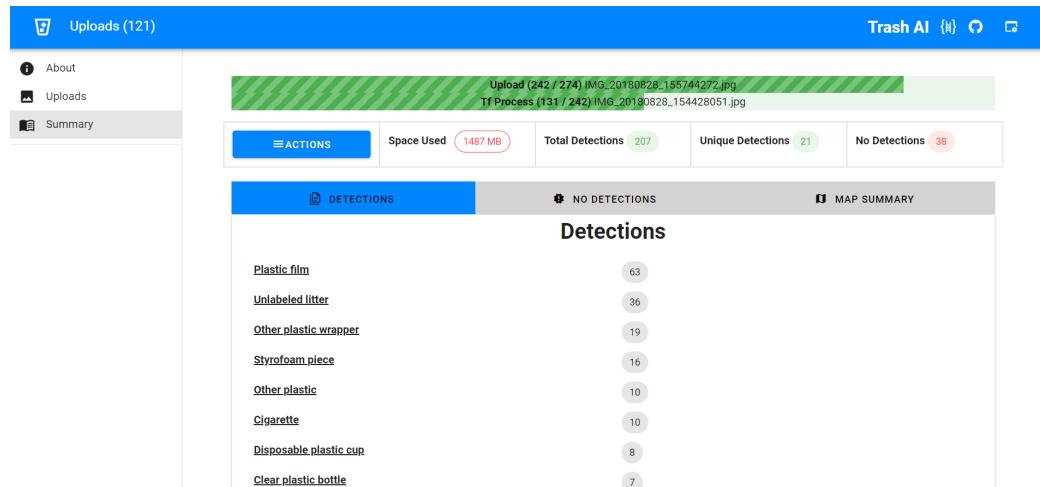


Figure 3: View summary results of detected trash.

### 4.

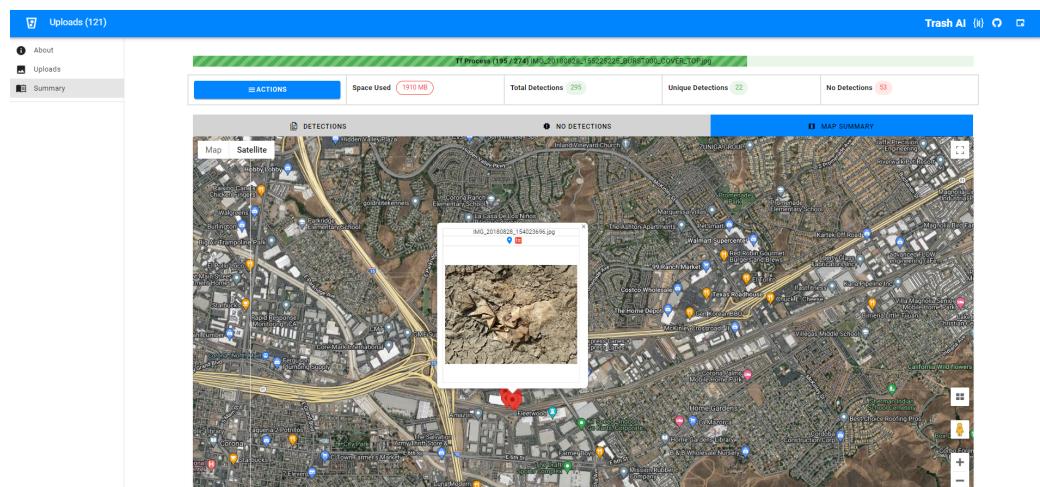


Figure 4: View results mapped if the images have location stamp.

5.

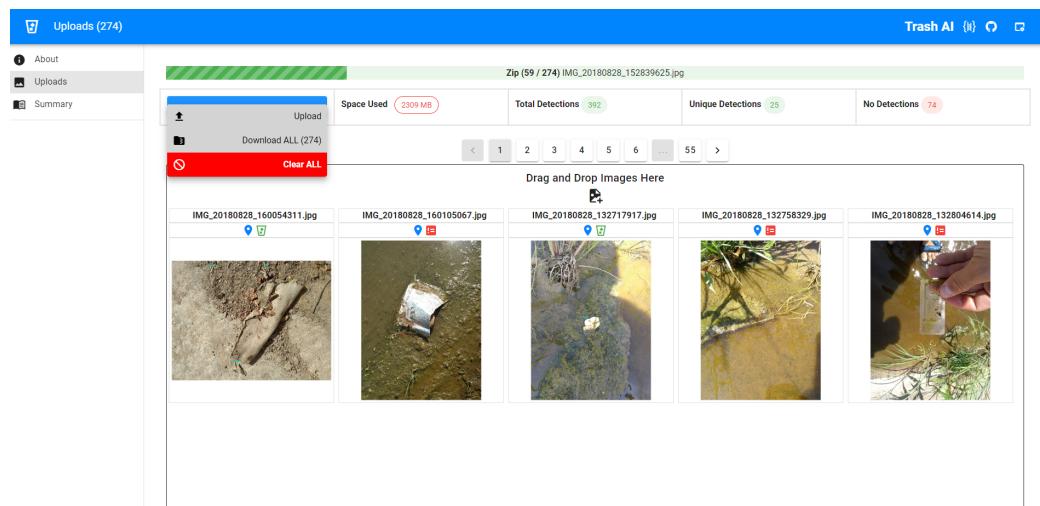


Figure 5: Click download all to extract a zip folder with labeled images and metadata.

6.

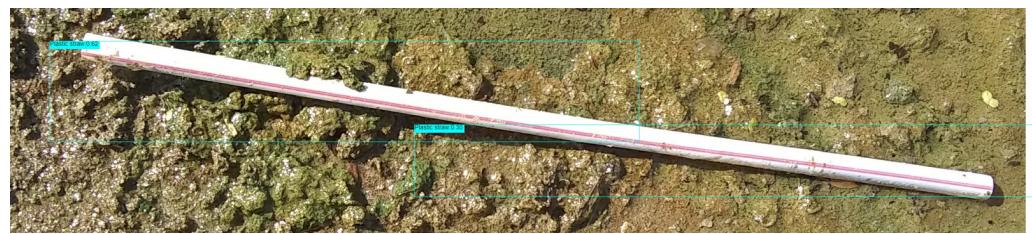


Figure 6: View labeled images from downloaded results.

7.

```

    ▼ {
        hash : f71995f841ea5d34ea01a7c5555eda8f0d78f438a1e345af1dbebb0030e500c3
        filename : IMG_20180828_155436924.jpg
        ▼ exifdata : {
            Make : motorola
            Model : Moto E (4)
            DateTimeOriginal : 1535471676
            ModifyDate : 1535471676
            CreateDate : 1535471676
            GPSLatitudeRef : N
            GPSLatitude : 33.878084666666666
            GPSLongitudeRef : W
            GPSLongitude : -117.54011455555555
            GPSAltitudeRef : 0
            GPSAltitude : 168.333
            ▼ GPSTimeStamp : [ 3 items
                0 : 22
                1 : 54
                2 : 36
            ]
            GPSDateStamp : 2018:08:28
            ExifImageWidth : 2448
            ExifImageHeight : 3264
        }
        ▼ metadata : [ 3 items
            ▼ 0 : {
                x1 : 276.61823534965515
                y1 : 1542.446426153183
                x2 : 1618.3531267642975
                y2 : 1770.0154795646667
                width : 1341.7348914146423
                height : 227.56905341148376
                score : 0.62
                name : Plastic straw
            }
            ▼ 1 : {
        }
    }

```

Figure 7: View metadata for each image using “image\_hash.json” (using <https://jsoneditoronline.org/>).

## 8.

```

{
  detected_objects : [ 10 items ]
    ▶ 0 : { 3 props }
    ▶ 1 : { 3 props }
    ▶ 2 : { 3 props }
    ▶ 3 : { 3 props }
    ▶ 4 : { 3 props }
    ▶ 5 : { 3 props }
    ▶ 6 : { 3 props }
    ▶ 7 : { 3 props }
    ▶ 8 : { 3 props }
    ▶ 9 : {
      name : Glass bottle
      count : 6
      hashes : [ 5 items ]
        0 : 8a9f52e666a50bb6162db7ae8877996b9e8d5a957788809eecfa81d0cf919160
        1 : 57f36cb26910a8c2378ad62769efa58260ffe015015dc0f5dee6ad6cf82f8d78
        2 : c9ad1460b1fae00374b3f1a9f4f3d20b222d6ed213d13eb409b0e84f2457f45d
        3 : dde15f5fd178a50cb9d80a08120472e9175d126b594963c8667c48b8cc9aaee9
        4 : a3151ea64392a8ffaa679a77cbebf7b9e6a981a15d38d38bba29e2657db09780
      ]
    }
  ]
}

no_detection_hashes : [ 74 items ]
unique_detections : 25
total_detections : 392
gps : {
  list : [ 274 items ]
    ▶ 0 : {
      coordinate : {
        lat : 33.87800527777778
        lng : -117.54040877777777
      }
      hash : 842d6e056b2f65e6b37e85b93a5a1324ce51a752a9a68fd812a4faee82512492
    }
    ▶ 1 : { 2 props }
    ▶ 2 : { 2 props }
    ▶ 3 : { 2 props }
}

```

Figure 8: View metadata for all images in “summary.json” (using <https://jsoneditoronline.org/>).

## Method

### Workflow Overview

Trash AI is trained on the [TACO dataset](#) using [YOLO 5](#). Trash AI stores images in [IndexDB](#) to keep the data primarily browser side and uses [tensorflow.js](#) to keep analysis browser side too. When images are uploaded to the browser, Trash AI provides the prediction of the model as a graphical output. The raw data from the model and labeled images can be downloaded in batch to expedite analyses.

### AI Training

The AI model was developed starting with the TACO dataset, which was available with a complimentary Jupyter Notebook on [Kaggle](#). An example notebook was referenced, which used the default YOLO v5 model ([Jocher et al., 2020](#)) as the basic model to begin transfer learning. Next, transfer learning was completed using the entire TACO dataset to import the

image classes and annotations in the YOLO v5 model.

## Limitations

From our experience, the accuracy of the model varies depending on the quality of the images and their context/background. “Trash” is a word people use for an object that lacks purpose, and the purpose of an object is often not obvious in an image. Trash is a nuanced classification because the same object in different settings will not be considered trash (e.g., a drink bottle on someone’s desk vs in the forest lying on the ground). This is the main challenge with any image-based trash detection algorithm. Not everything that LOOKS like trash IS trash. This and other complexities to trash classification make a general trash AI a challenging (yet worthwhile) long-term endeavor. The algorithm is primarily trained on the TACO dataset, which is composed of images of single pieces of trash, with the trash lying on the ground (< 1 m away). Thus, model class prediction of trash in these kinds of images will generally be better than trash appearing in aerial images or imaged from a vehicle, for example.

## Availability

Trash AI is hosted on the web at [www.trashai.org](http://www.trashai.org). The source code is [available on github](#) with an [MIT license](#). The source code can be run offline on any machine that can install [Docker](#) and [Docker-compose](#). [Documentation](#) is maintained by Code for Sacramento and Open Fresno on Github and will be updated with each release. [Nonexhaustive instructions for AWS deployment](#) is available for anyone attempting production level deployment.

## Future Goals

This workflow is likely to be highly useful for a wide variety of computer vision applications and we hope that people reuse the code for applications beyond trash detection. We aim to increase the labeling of images by creating a user interface that allows users to improve the annotations that the model is currently predicting by manually restructuring the bounding boxes and relabeling the classes. We aim to work in collaboration with the TACO development team to improve our workflow integration to get additional data into the [TACO training dataset](#) by creating an option for users to share their data. Future models will expand the annotations to include the Trash Taxonomy ([Hapich et al., 2022](#)) classes and add an option to choose between other models besides the current model.

## Acknowledgements

Code for Sacramento and Open Fresno led the development of the software tool. The Moore Institute for Plastic Pollution Research advised on priorities and led the drafting of this manuscript. Let’s Do It Foundation assisted with original products leading up to trash AI in the development of WADE AI. We acknowledge the work of the Code for Sacramento and Open Fresno team, brigades of Code for America, without whom this project would not have been possible, and acknowledge the input of the California Water Monitoring Council Trash Monitoring Workgroup. In particular, we would like to acknowledge Gary Conley, Tony Hale, Emin Israfil, Tom Novotny, Margaret McCauley, Julian Fulton, Janna Taing, Elizabeth Pierotti, Kevin Fries, J.Z. Zhang, Joseph Falkner, Democracy Lab, Brad Anderson, Jim Ewald, Don Brower, and University of Houston. We acknowledge financial support from McPike Zima Charitable Foundation, the National Renewable Energy Laboratory, and the Possibility Lab.

## References

- Hapich, H., Cowger, W., Gray, A., Tangri, N., Hale, T., Magdy, A., Vermilye, A., Yu, W., Ayres, D., Moore, C., Vermilye, J., Singh, S., Haiman, A. N. K., Youngblood, K., Kang, Y., McCauley, M., Lok, T., Moore, S., Baggs, E., ... Mock, J. (2022). Trash taxonomy tool: Harmonizing classification systems used to describe trash in environments. *Microplastics and Nanoplastics*, 2(1), 15. <https://doi.org/10.1186/s43591-022-00035-1>
- Jocher, G., Stoken, A., Borovec, J., NanoCode012, ChristopherSTAN, Changyu, L., Laughing, tkianai, Hogan, A., lorenzomammana, yxNONG, AlexWang1900, Diaconu, L., Marc, wanghaoyang0106, ml5ah, Doug, Ingham, F., Frederik, ... Rai, P. (2020). ultralytics/yolov5: v3.1 - Bug Fixes and Performance Improvements (Version v3.1). Zenodo. <https://doi.org/10.5281/zenodo.4154370>
- K. Kerge, K. H., W. Cowger. (2020). WADE AI trash detection. In *Github repository*. GitHub. <https://github.com/letsdoitworld/wade-ai>
- Lieshout, C. van, Oeveren, K. van, Emmerik, T. van, & Postma, E. (2020). Automated river plastic monitoring using deep learning and cameras. *Earth and Space Science*, 7(8), e2019EA000960. <https://doi.org/10.1029/2019EA000960>
- Lynch, S. (2018). OpenLitterMap.com – open data on plastic pollution with blockchain rewards (littercoin). *Open Geospatial Data, Software and Standards*, 3(1), 6. <https://doi.org/10.1186/s40965-018-0050-y>
- Majchrowska, S., Mikołajczyk, A., Ferlin, M., Klawikowska, Z., Plantykow, M. A., Kwasigroch, A., & Majek, K. (2022). Deep learning-based waste detection in natural and urban environments. *Waste Management*, 138, 274–284. <https://doi.org/10.1016/j.wasman.2021.12.001>
- Moore, S., Hale, T., Weisberg, S. B., Flores, L., & Kauhanen, P. (2020). *California trash monitoring methods and assessments playbook*. San Francisco Estuary Institute.
- Proença, P. F., & Simões, P. (2020). *TACO: Trash annotations in context for litter detection*. arXiv. <https://doi.org/10.48550/ARXIV.2003.06975>
- Waterboards. (2018). Trash tracker. In *Github repository*. GitHub. <https://github.com/CAWaterBoardDataCenter/Trash-Tracker>
- Wuu, S. (2018). Litter detection tensorflow. In *Github repository*. GitHub. <https://github.com/isaychris/litter-detection-tensorflow>