

Xono2L: an eXtensible, LabVIEW-compatible real-time sONOgraphic data capture and processing TOOL

Dzhoshkun Ismail Shakir^{1, 2, 3}, Sunish Mathews^{3, 4}, Wenfeng Xia^{1, 3},
Adrien Desjardins^{3, 4}, and Tom Vercauteren^{1, 3}

¹ School of Biomedical Engineering and Imaging Sciences, King's College London ² University College London Hospitals NHS Foundation Trust ³ Department of Medical Physics and Biomedical Engineering, University College London ⁴ Wellcome/EPSCRC Centre for Interventional and Surgical Sciences, University College London

DOI: [10.21105/joss.01104](https://doi.org/10.21105/joss.01104)

Software

- [Review](#) ↗
- [Repository](#) ↗
- [Archive](#) ↗

Submitted: 27 November 2018

Published: 04 December 2018

License

Authors of papers retain copyright and release the work under a Creative Commons Attribution 4.0 International License ([CC-BY](#)).

Dzhoshkun I. Shakir and Sunish Mathews contributed equally to this work.

Summary

Research in advanced sonographic real-time clinical imaging methods such as ultrasonic needle tracking (Mung, Vignon, & Jain, 2011; Nikolov & Jensen, 2008; Xia et al., 2018, 2016; Xiaoyu Guo, 2014) is facilitated by the [LabVIEW](#) rapid system-design and development environment. This research and associated clinical translational developments (Xia et al., n.d., 2017a, 2017b) involve the capture and processing of live ultrasound data streams with LabVIEW.

Existing open-source software packages such as Plus (Lasso et al., 2014) and NifTK (Clarkson et al., 2015) support the capture of live ultrasound streams; however, they do not provide a LabVIEW interface. To bridge this gap, we have designed and developed [Xono2L](#) as a LabVIEW-compatible, extensible C++ API. Xono2L links with the Ulterius library, a component of the proprietary Sonix SDK provided for use with [Sonix ultrasound systems](#) commercialised initially by Ultrasonix Medical Corp. and currently by BK Medical Holding Company, Inc.

[Xono2L](#) is intended as an extensible tool that allows for the real-time capture of ultrasound imaging data, which in turn facilitates processing with LabVIEW. Although Xono2L's scope is currently limited to Sonix ultrasound systems, we have made it available to the research community to facilitate research with these devices. Xono2L's API is flexible and can be extended to cover a broad range of use cases.

Acknowledgements

This work is supported by the [Wellcome Trust](#) [WT101957; 203145Z/16/Z and 203148/Z/16/Z] and the [Engineering and Physical Sciences Research Council \(EPSRC\)](#) [NS/A000027/1; NS/A000050/1; NS/A000049/1 and EP/N021177/1], notably through the [GIFT-Surg](#) Innovative Engineering for Health award, the [Wellcome/EPSCRC Centre for Interventional and Surgical Sciences \(WEISS\)](#) and the [Wellcome/EPSCRC Centre for Medical Engineering \(CME\)](#). This work is also supported by the [National Institute for Health Research](#) Biomedical Research Centre UCLH/UCL High Impact Initiative.

References

- Clarkson, M. J., Zombori, G., Thompson, S., Totz, J., Song, Y., Espak, M., Johnsen, S., et al. (2015). The niftk software platform for image-guided interventions: Platform overview and niftylink messaging. *International Journal of Computer Assisted Radiology and Surgery*, 10(3), 301–316. doi:[10.1007/s11548-014-1124-7](https://doi.org/10.1007/s11548-014-1124-7)
- Lasso, A., Heffter, T., Rankin, A., Pinter, C., Ungi, T., & Fichtinger, G. (2014). PLUS: Open-source toolkit for ultrasound-guided intervention systems. *IEEE Transactions on Biomedical Engineering*, 61(10), 2527–2537. doi:[10.1109/TBME.2014.2322864](https://doi.org/10.1109/TBME.2014.2322864)
- Mung, J., Vignon, F., & Jain, A. (2011). A non-disruptive technology for robust 3D tool tracking for ultrasound-guided interventions. In G. Fichtinger, A. Martel, & T. Peters (Eds.), *Medical image computing and computer-assisted intervention – miccai 2011* (pp. 153–160). Berlin, Heidelberg: Springer Berlin Heidelberg.
- Nikolov, S. I., & Jensen, J. A. (2008). Precision of needle tip localization using a receiver in the needle. In *IEEE int ultrason symp*.
- Xia, W., Ginsberg, Y., West, S. J., Nikitichev, D. I., Ourselin, S., David, A. L., & Desjardins, A. E. (n.d.). Coded excitation ultrasonic needle tracking: An in vivo study. *Medical Physics*, 43(7), 4065–4073. doi:[10.1118/1.4953205](https://doi.org/10.1118/1.4953205)
- Xia, W., Noimark, S., Ourselin, S., West, S. J., Finlay, M. C., David, A. L., & Desjardins, A. E. (2017a). Ultrasonic needle tracking with a fibre-optic ultrasound transmitter for guidance of minimally invasive fetal surgery. In M. Descoteaux, L. Maier-Hein, A. Franz, P. Jannin, D. L. Collins, & S. Duchesne (Eds.), *Medical image computing and computer-assisted intervention – miccai 2017* (pp. 637–645). Cham: Springer International Publishing.
- Xia, W., West, S. J., Finlay, M. C., Mari, J.-M., Ourselin, S., David, A. L., & Desjardins, A. E. (2017b). Looking beyond the imaging plane: 3D needle tracking with a linear array ultrasound probe. *Scientific reports*, 7(1), 3674.
- Xia, W., West, S. J., Finlay, M. C., Pratt, R., Mathews, S., Mari, J.-M., Ourselin, S., et al. (2018). Three-dimensional ultrasonic needle tip tracking with a fiber-optic ultrasound receiver. *JoVE*, (138), e57207. doi:[10.3791/57207](https://doi.org/10.3791/57207)
- Xia, W., West, S. J., Mari, J.-M., Ourselin, S., David, A. L., & Desjardins, A. E. (2016). 3D ultrasonic needle tracking with a 1.5D transducer array for guidance of fetal interventions. In S. Ourselin, L. Joskowicz, M. R. Sabuncu, G. Unal, & W. Wells (Eds.), *Medical image computing and computer-assisted intervention – miccai 2016* (pp. 353–361). Cham: Springer International Publishing.
- Xiaoyu Guo, H.-J. K., Behnoosh Tavakoli. (2014). Photoacoustic active ultrasound element for catheter tracking. *Proc.SPIE*. doi:[10.1117/12.2041625](https://doi.org/10.1117/12.2041625)