

Image Recognition with OpenCV and TensorFlow Workshop

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https://bit.ly/mlcon22_image_rec



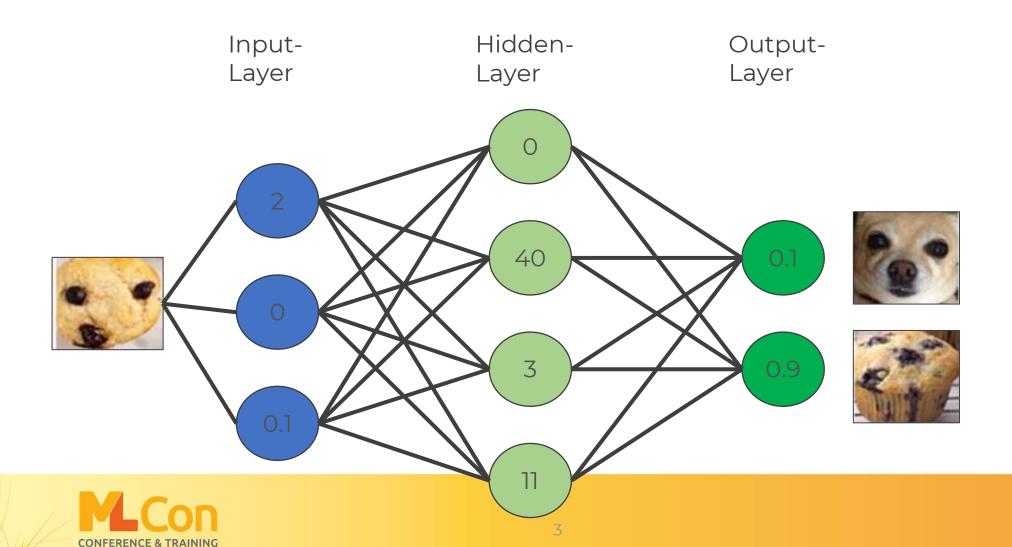
Theoretical Background

Neural Network

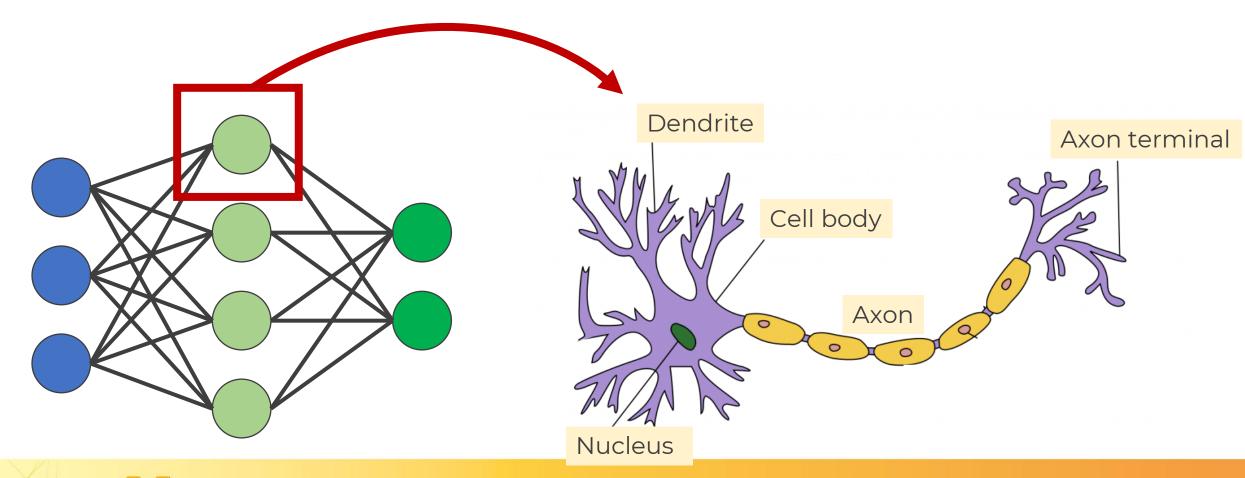
Neurons

Activation functions

Neural Network

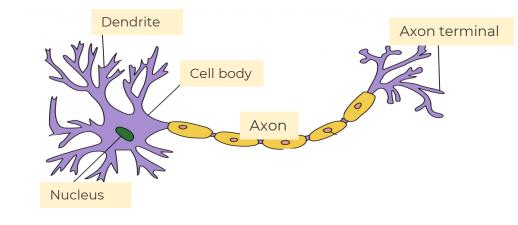


What's a neuron?



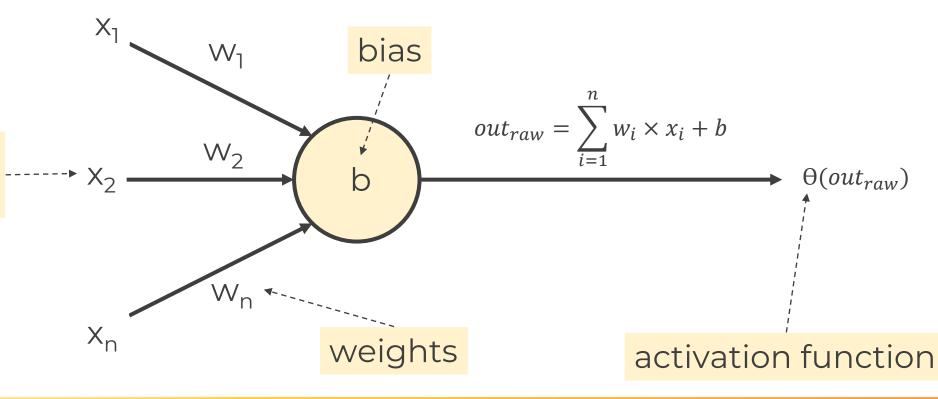


What's a neuron?



 $\Theta(out_{raw})$

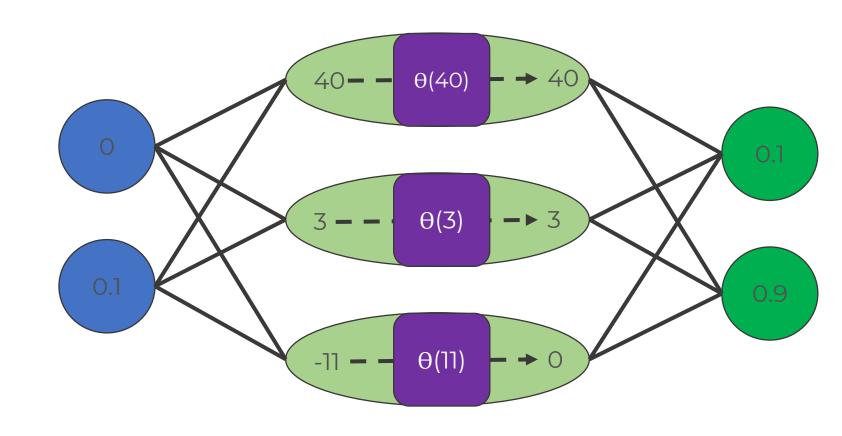
output of previous neuron





Activation function (θ)

- Subsequent modification of the neuron output
- **Layer**-specific (not neuron-specific)
- Adds non-linear properties to the network
- Recognition of complex patterns





Activation function (θ)

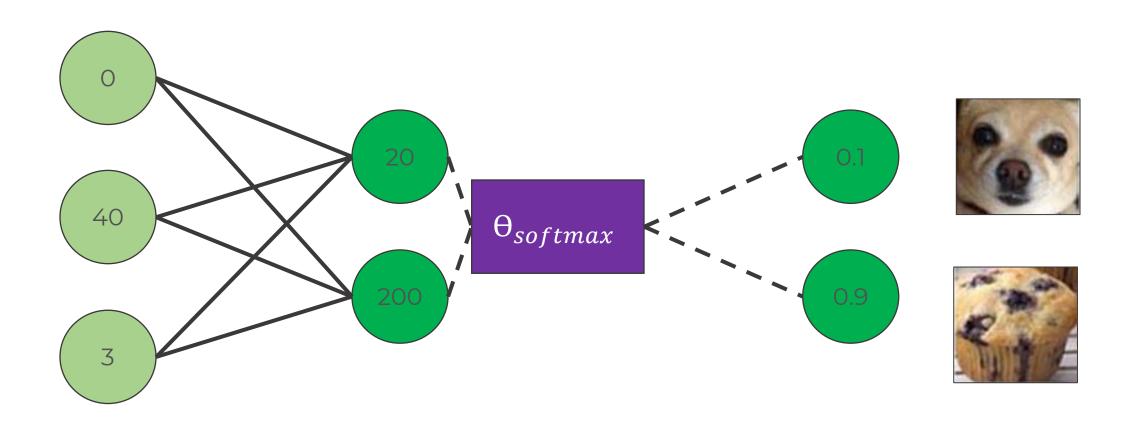
Name	Plot	Equation	Derivative	Range	Order of continuity
Identity		f(x)=x	f'(x)=1	$(-\infty,\infty)$	C^{∞}
Binary step		$f(x) = egin{cases} 0 & ext{for } x < 0 \ 1 & ext{for } x \geq 0 \end{cases}$	$f'(x) = \left\{egin{array}{ll} 0 & ext{for } x eq 0 \ ? & ext{for } x = 0 \end{array} ight.$	$\{0,1\}$	C^{-1}
Logistic (a.k.a. Sigmoid or Soft step)		$f(x)=\sigma(x)=\frac{1}{1+e^{-x}}$	f'(x) = f(x)(1-f(x))	(0,1)	C^{∞}
TanH		$f(x)= anh(x)=rac{(e^x-e^{-x})}{(e^x+e^{-x})}$	$f^{\prime}(x)=1-f(x)^{2}$	(-1,1)	C^{∞}
ElliotSig Softsign		$f(x) = \frac{x}{1+ x }$	$f'(x)=\frac{1}{(1+ x)^2}$	(-1, 1)	C^1
Square Nonlinearity (SQNL)		$f(x) = egin{cases} 1 & : x > 2.0 \ x - rac{x^2}{4} & : 0 \le x \le 2.0 \ x + rac{x^2}{4} & : -2.0 \le x < 0 \ -1 & : x < -2.0 \end{cases}$	$f(x) = egin{cases} 1 & :x > 2.0 \ x - rac{x^2}{4} & :0 \le x \le 2.0 \ x + rac{x^2}{4} & :-2.0 \le x < 0 \ -1 & :x < -2.0 \end{cases} f'(x) = 1 \mp rac{x}{2}$		C^2
Rectified linear unit (ReLU)		$f(x) = egin{cases} 0 & ext{for } x < 0 \ x & ext{for } x \geq 0 \end{cases}$	$f'(x) = egin{cases} 0 & ext{for } x < 0 \ 1 & ext{for } x \geq 0 \end{cases}$	$[0,\infty)$	C^0
Bipolar rectified linear unit (BReLU)		$f(x_i) = egin{cases} ReLU(x_i) & ext{if } i ext{ mod } 2 = 0 \ -ReLU(-x_i) & ext{if } i ext{ mod } 2 eq 0 \end{cases}$	$f'(x_i) = egin{cases} ReLU'(x_i) & ext{if } i mod 2 = 0 \ -ReLU'(-x_i) & ext{if } i mod 2 eq 0 \end{cases}$	$(-\infty,\infty)$	C^0
Leaky rectified linear unit (Leaky ReLU)		$f(x) = \left\{ egin{array}{ll} 0.01x & ext{for } x < 0 \ x & ext{for } x \geq 0 \end{array} ight.$	$f'(x) = \left\{ egin{array}{ll} 0.01 & ext{for } x < 0 \ 1 & ext{for } x \geq 0 \end{array} ight.$	$(-\infty,\infty)$	C^0
Parameteric rectified linear unit (PReLU)		$f(lpha,x) = \left\{egin{array}{ll} lpha x & ext{for } x < 0 \ x & ext{for } x \geq 0 \end{array} ight.$	$f'(lpha,x) = \left\{egin{array}{ll} lpha & ext{for } x < 0 \ 1 & ext{for } x \geq 0 \end{array} ight.$	$(-\infty,\infty)$	C^0





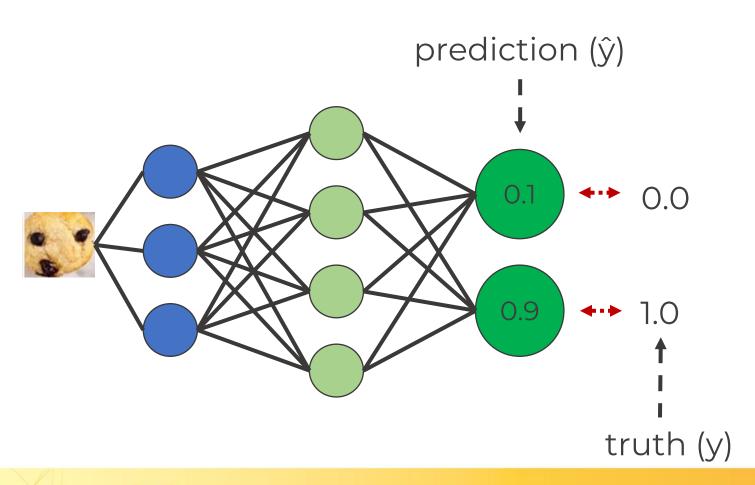


Softmax activation function



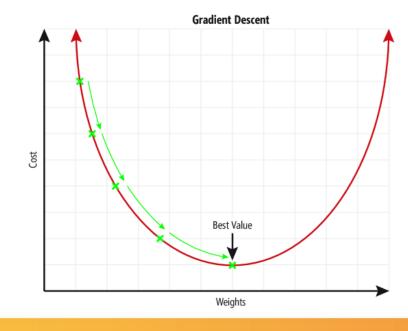


How does a neural network learn?



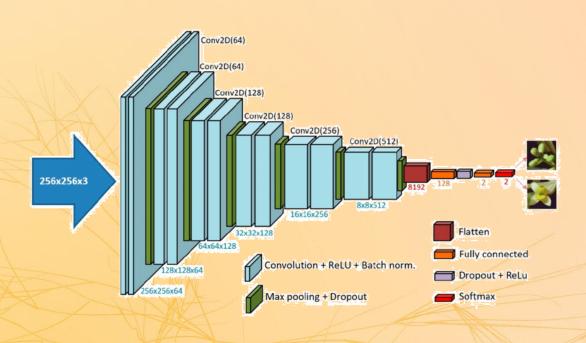
cost function:

$$MSE = \frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{y}_i)^2$$





CONFERENCE & TRAINING

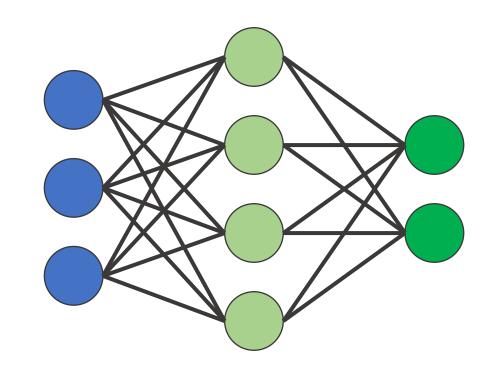


Types of Layers

Dense Convolutional

Dense Layer

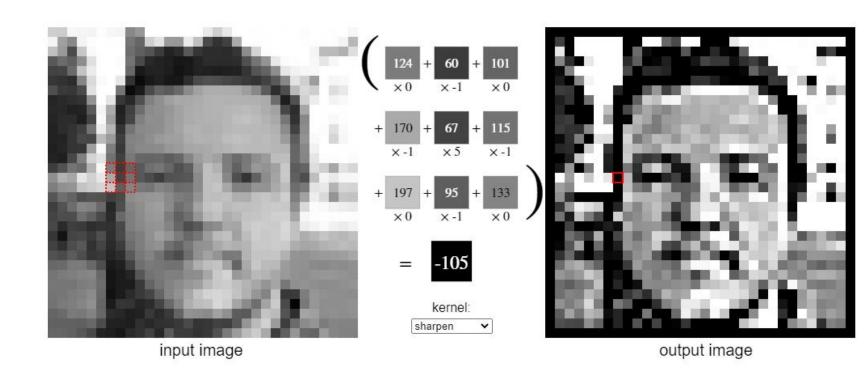
- Each neuron is connected to each neuron from the previous layer
- High computational effort
- CNN: Output layer





Convolutional Layer

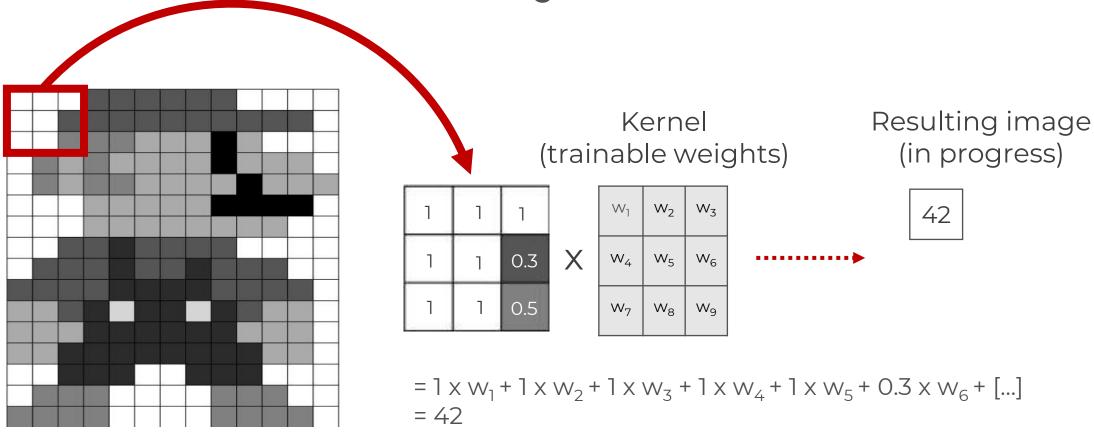
- Defines CNNs
- Extraction of features
- Reduction of computational effort
- Mathematical convolution



by Victor Powell (https://setosa.io/ev/image-kernels/

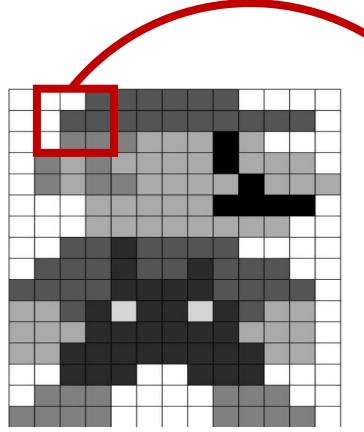


Convolutional Layer





Convolutional Layer



Kernel (trainable weights)

1	1	0.3	
1	0.3	0.3	X
1	0.5	0.5	



Resulting image (in progress)

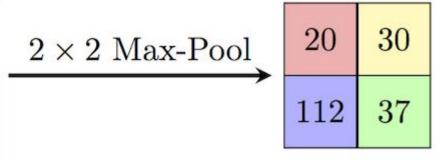
=
$$1 \times W_1 + 1 \times W_2 + 0.3 \times W_3 + 1 \times W_4 + 0.3 \times W_5 + 0.3 \times W_6 + [...]$$

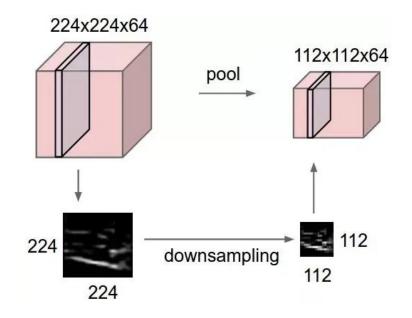
= 34



Pooling Layer

12	20	30	0
8	12	2	0
34	70	37	4
112	100	25	12





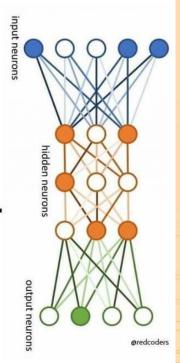




THIS IS A NEURAL NETWORK.

IT MAKES MISTAKES.
IT LEARNS FROM THEM.

BE LIKE A NEURAL NETWORK.



Let's make some mistakes!

Histogram Equalization

4	4	4	4	4
3	4	5	4	3
3	5	5	5	3
3	4	5	4	3
4	4	4	4	4



		↓		
6	6	6	6	6
2	6	7	6	2
2	7	7	7	2
2	6	7	6	2
6	6	6	6	

Gray Level	No. of pixels (n)	PDF (n/sum)	CDF	CDF * 7 (max gray)	Equalized Histogram
0	0	0	0	0	0
1	0	0	0	0	0
2	0	0	0	0	0
3	6	6/25 = 0.24	0.24	1.68	2
4	14	14/25=0.56	0.8	5.6	6
5	5	5/25=0.2	1.0	7	7
6	0	0	1.0	7	7
7	0	0	1.0	7	7

