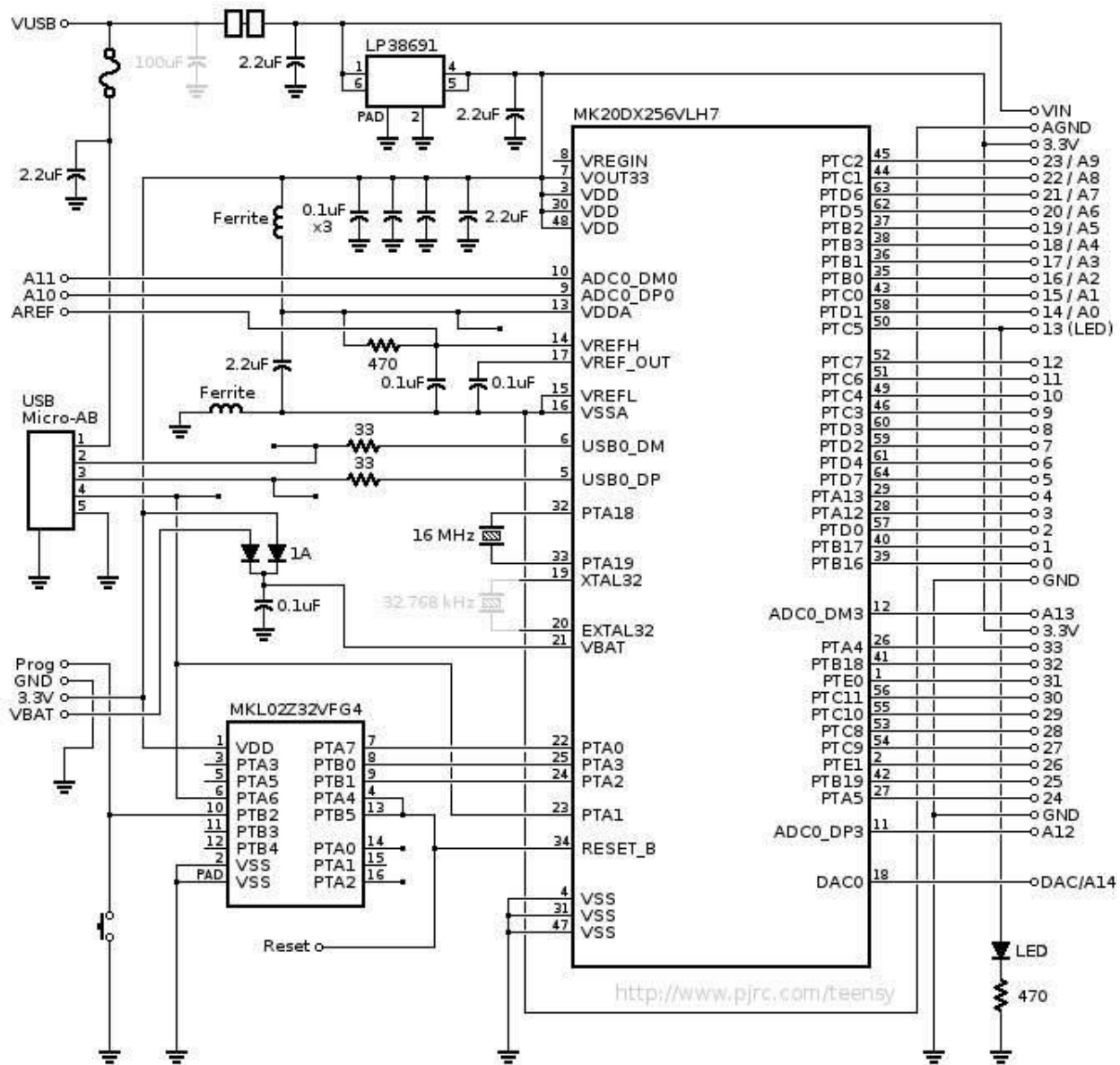


## Teensy 3.2





### Digital Pins

digitalRead  
digitalWrite  
pinMode

### Analog Pins

analogRead  
analogReference  
analogReadRes

### PWM Pins

analogWrite  
analogWriteRes

### Touch Sense Pins

touchRead

### Serial Ports

Serial1  
Serial2  
Serial3

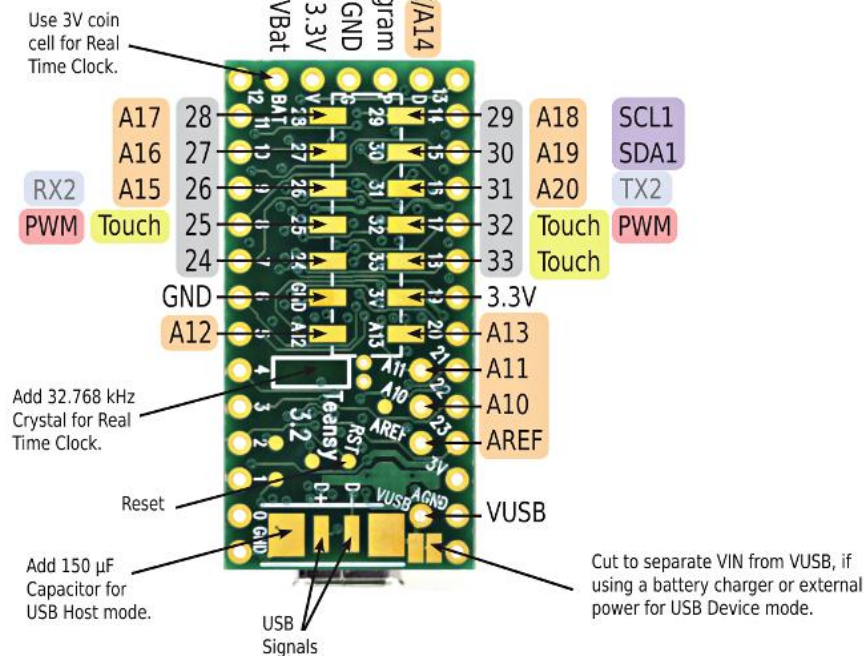
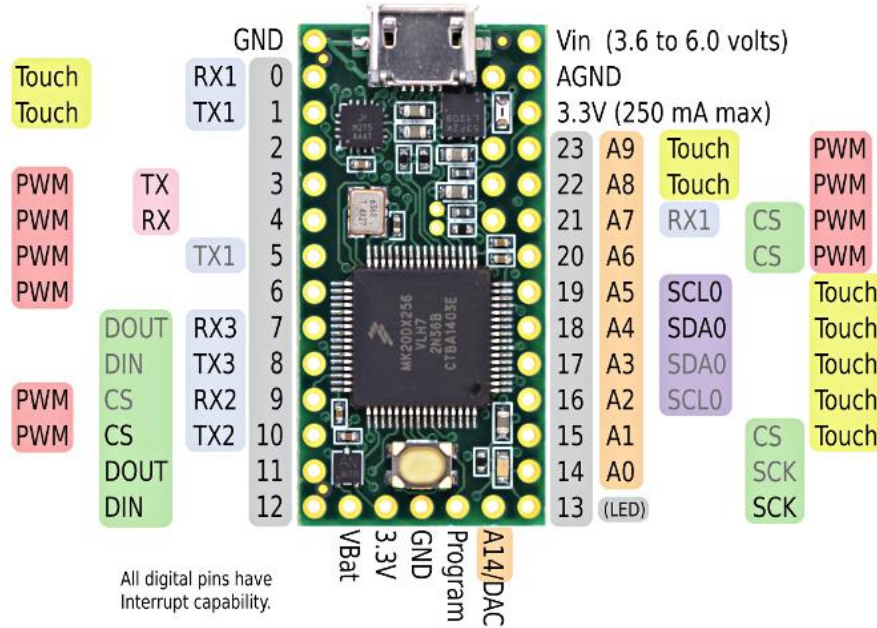
### I<sup>2</sup>C Port

Wire Library

### SPI Port

SPI Library

### CAN Bus

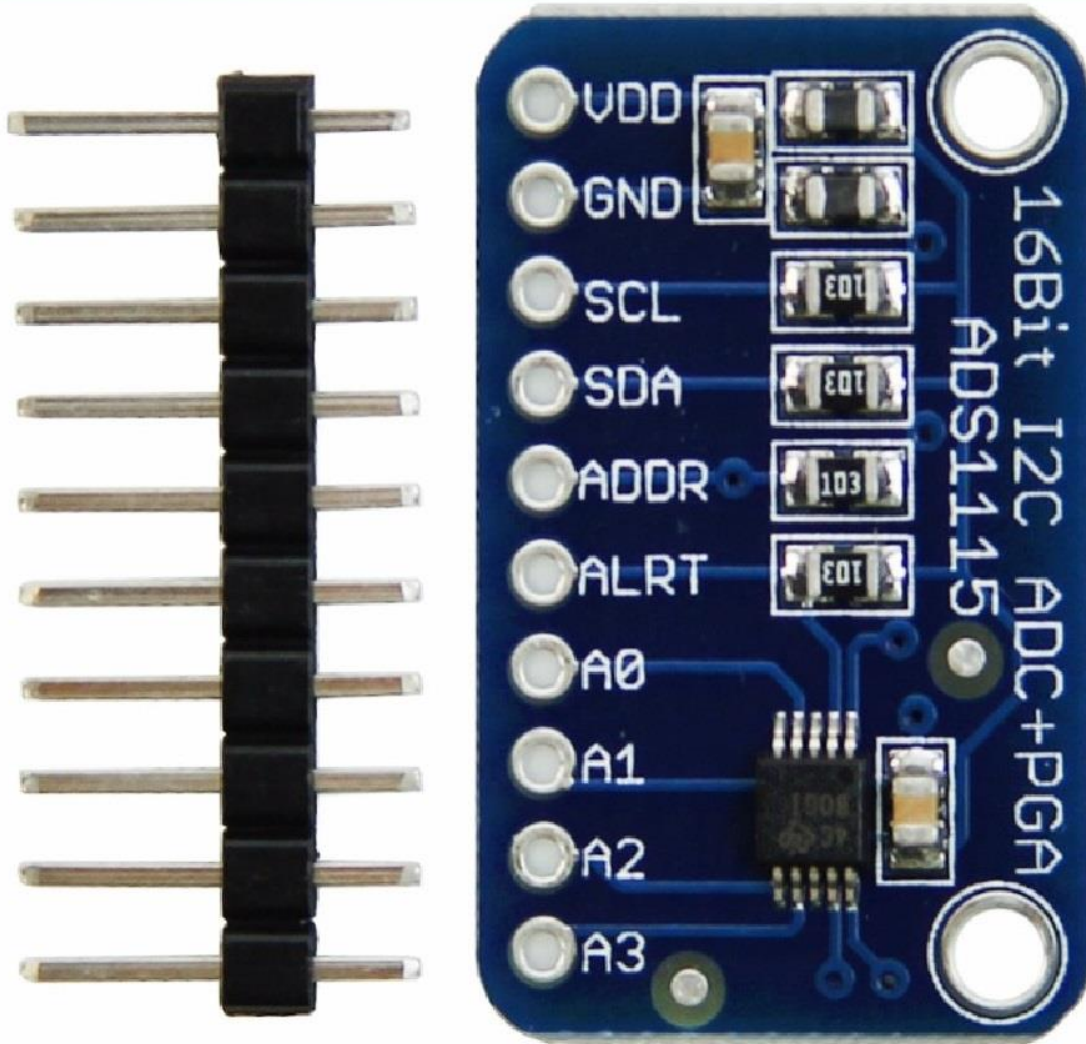




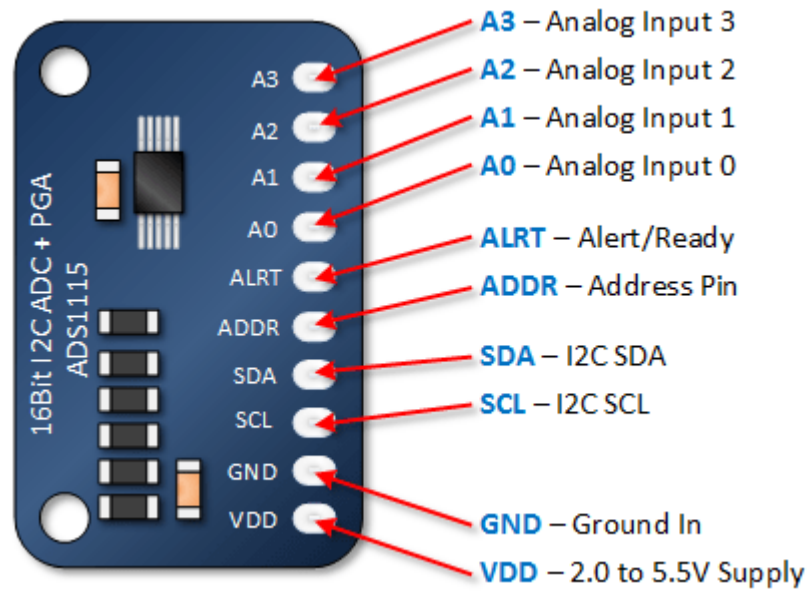
## CAN Transceiver



## 16bit ADC

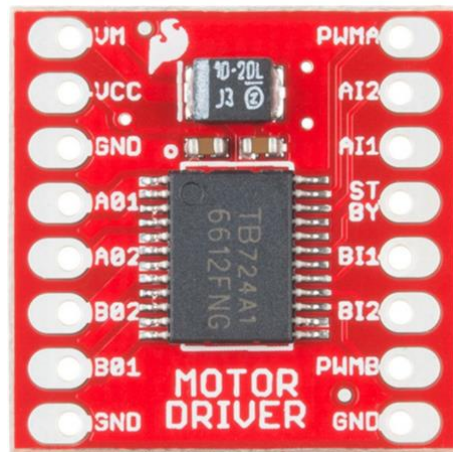


[www.iFuturetech.org](http://www.iFuturetech.org)



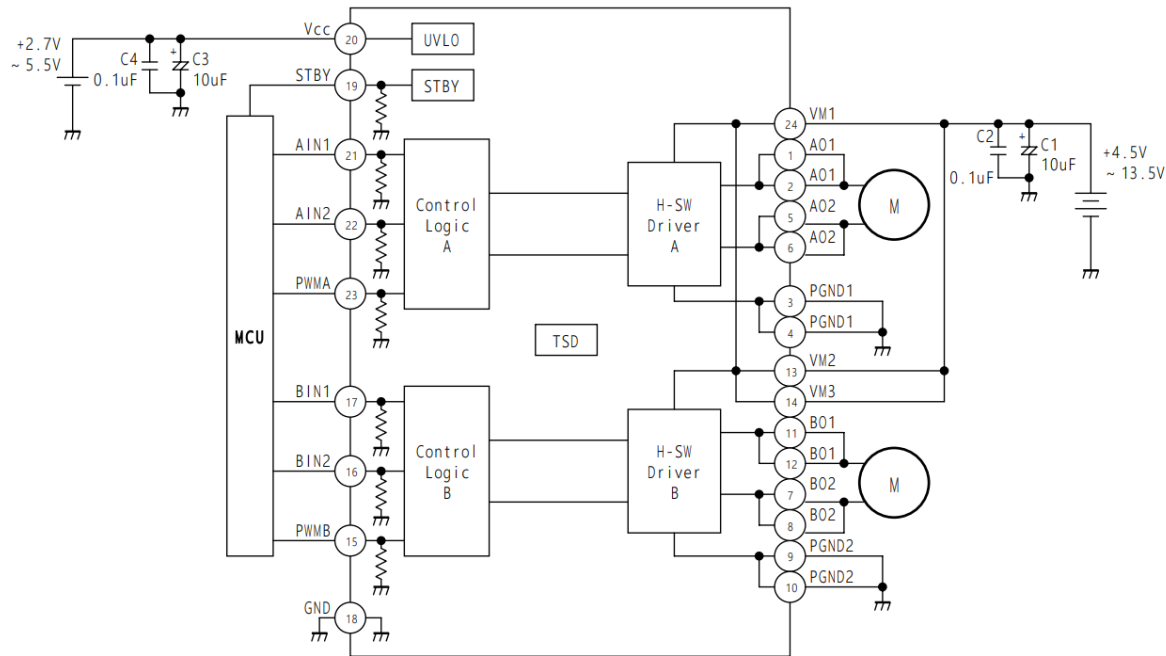
### Motor Driver - Dual TB6612FNG v2

RB-Spa-1516





## Typical Application Diagram



Characteristics	Symbol	Min	Typ.	Max	Unit	Remarks
Supply voltage	Vcc	2.7	3	5.5	V	
	VM	4.5	5	13.5	V	
Output current (H-SW)	Iout	---	---	1.0	A	VM 5V
		---	---	0.4		5V > VM 4.5V
Switching frequency	fPWM	---	---	100	kHz	



**Absolute Maximum Ratings (Ta = 25°C)**

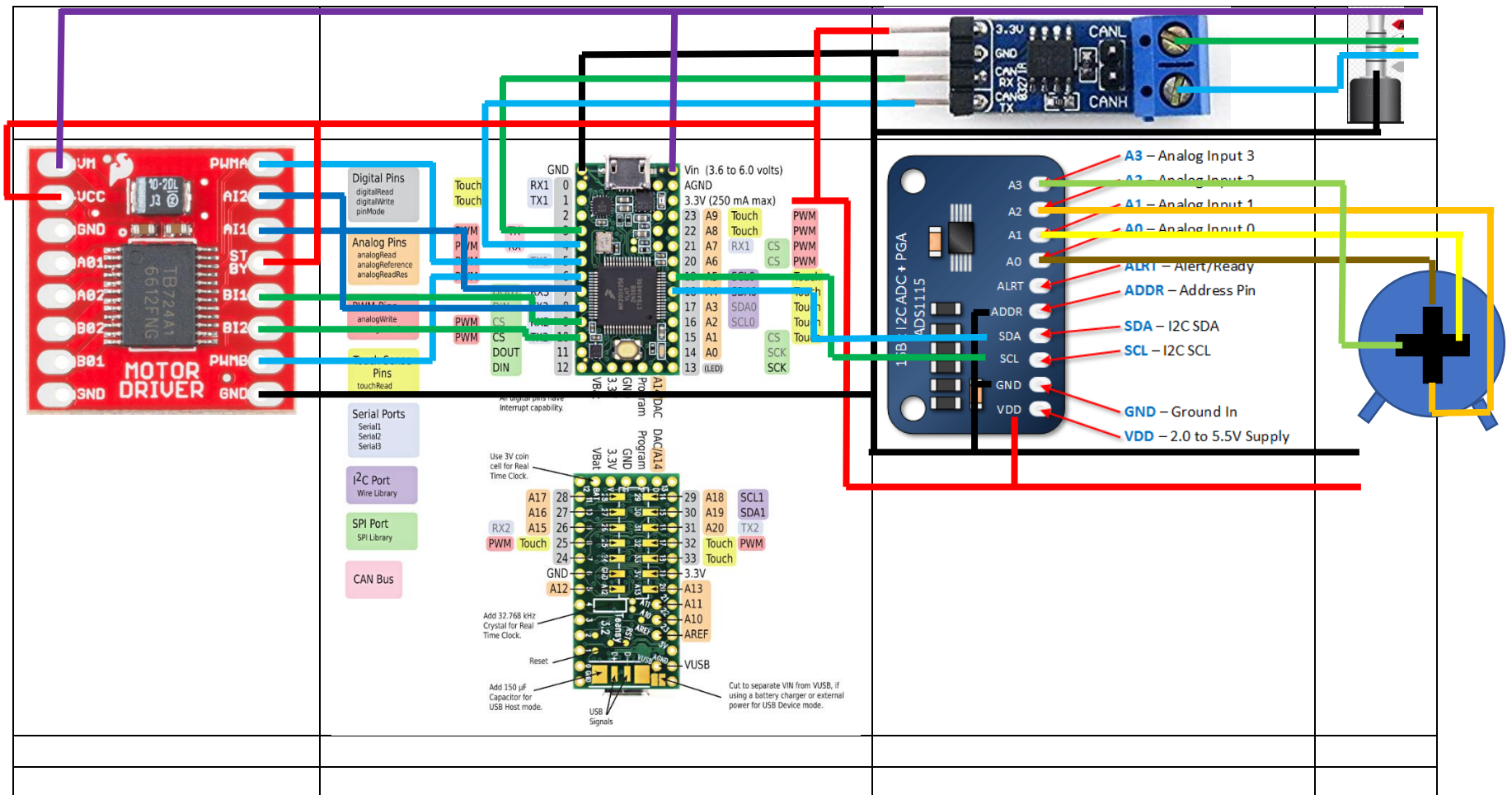
Characteristics	Symbol	Rating	Unit	Remarks
Supply voltage	VM	15	V	
	Vcc	6		
Input voltage	VIN	-0.2 ~ 6	V	IN1, IN2, STBY, PWM pins
Output voltage	Vout	15	V	01, 02 pins
Output current	Iout	1.2	A	Per 1ch
	Iout (peak)	2		tw=20ms Continuous pulse, Duty 20%
		3.2		tw=10ms Single pulse
Power dissipation	PD	0.78	W	IC only
		0.89		50 × 50 t=1.6(mm) Cu 40% in PCB mounting
		1.36		76.2 × 114.3 t=1.6(mm) Cu 30% in PCB mounting
Operating temperature	Topr	-20 ~ 85	°C	
Storage temperature	Tstg	-55 ~ 150	°C	

## Pin Functions

No.	Pin Name	I/O	Function
1	AO1	O	ch A output1
2	AO1		
3	PGND1	—	Power GND 1
4	PGND1		
5	AO2	O	ch A output2
6	AO2		
7	BO2	O	ch B output2
8	BO2		
9	PGND2	—	Power GND 2
10	PGND2		
11	BO1	O	ch B output1
12	BO1		
13	VM2	—	Motor supply (2.5 V to 13.5 V)
14	VM3		
15	PWMB	I	ch B PWM input / 200 kΩ pull-down at internal
16	BIN2	I	ch B input 2 / 200 kΩ pull-down at internal
17	BIN1	I	ch B input 1 / 200 kΩ pull-down at internal
18	GND	—	Small signal GND
19	STBY	I	"L"=standby / 200 kΩ pull-down at internal
20	Vcc	—	Small signal supply
21	AIN1	I	ch A input 1 / 200 kΩ pull-down at internal
22	AIN2	I	ch A input 2 / 200 kΩ pull-down at internal
23	PWMA	I	ch A PWM input / 200 kΩ pull-down at internal
24	VM1	—	Motor supply (2.5 V~13.5 V)

## H-SW Control Function

Input				Output		
IN1	IN2	PWM	STBY	OUT1	OUT2	Mode
H	H	H/L	H	L	L	Short brake
L	H	H	H	L	H	CCW
		L	H	L	L	Short brake
H	L	H	H	H	L	CW
		L	H	L	L	Short brake
L	L	H	H	OFF (High impedance)		Stop
H/L	H/L	H/L	L	OFF (High impedance)		Standby



Code pour module 16 bits :

<http://henrysbench.capnfatz.com/henrys-bench/arduino-voltage-measurements/arduino-ads1115-module-getting-started-tutorial/>

```
#include <Wire.h>
#include <Adafruit_ADS1015.h>

Adafruit_ADS1115 ads(0x48);
float Voltage = 0.0;

void setup(void)
{
  Serial.begin(9600);
  ads.begin();
}

void loop(void)
{
  int16_t adc0;  // we read from the ADC, we have a sixteen bit integer as a result

  adc0 = ads.readADC_SingleEnded(0);
  Voltage = (adc0 * 0.1875)/1000;

  Serial.print("AIN0: ");
  Serial.print(adc0);
  Serial.print("\tVoltage: ");
  Serial.println(Voltage, 7);
  Serial.println();

  delay(1000);
}
```