Towards a semantics-driven implementation of JITK, using K-framework

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Present work objectives

└─Overview of JITK

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System call policies enforcement: BPF

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└─System call policies enforcement: BPF

Example of BPF

```
; load syscall number
ld [0]
; deny open() with errno = EACCES
jeq #SYS_open, L1, L2
L1: ret #RET_ERRNO|#EACCES
; allow getpid()
L2: jeg #SYS_getpid, L3, L4
L3: ret #RET_ALLOW
; allow gettimeofday()
L4: jeq #SYS_gettimeofday, L5, L6
L5: ret #RET ALLOW
L6: ...
; default: kill current process
ret #RET KILL
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As seen above, each system call gets an entry in the list of rules, along with the expected behavior regarding this particular sytem call. A default behavior is also defined, should any system call be absent from the previous list.

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{ action = Allow; syscall = SYS_getpid };
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As seen above, SCPL is really close to the natural thought process of defining the rules of sytem call behavior, and this intuitive ease of use guarantees minimal errors within policies definition.

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K-framework function and role

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To generate such language implementations, we only need to define its syntax and semantics, split into three components

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Ongoing progress

Ongoing: definition and implementation of SCPL and BPF using K-framework. Planned: definition and implementation of an SCPL to BPF compiler using K-framework.

Thank you for your attention! Any questions?

Further Reading I

Xi Wang, David Lazar, Nickolai Zeldovich, Adam Chlipala,

Zachary Tatlock

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