OpenTURNS release highlights

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Overview

New features since last year in releases:

• v1.18: fall 2021

• v1.19: spring 2022



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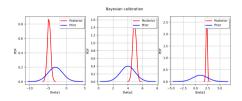
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Metropolis-Hastings

- RandomWalkMH now updates with the instrumental in one go
- new Gibbs class that updates components sequentially
- Separate method to define the likelihood
- Handle improper prior via a log-pdf function
- Direct inconditional sampling according to a random variable



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Metropolis-Hastings

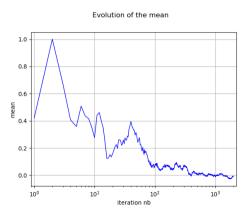
```
from openturns import RandomWalkMetropolisHastings as RWMH
rwmh1 = RWMH(prior, initialState, proposal1, [0])
rwmh2 = RWMH(prior, initialState, proposal2, [1, 2])
mh_coll = [rwmh1, rwmh2]
for mh in mh_coll:
    mh.setLikelihood(conditional, y_obs, linkFunction, x_obs)
sampler = ot.Gibbs(mh_coll)
x = sampler.getSample(1000)
```

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Iterative statistics

- Compute statistics without the need to store whole samples
- Moments / threshold exceedance / extrema
- Useful in HPC contexts



Iterative statistics

```
iter mom = ot.IterativeMoments(order. dim)
iter ext = ot.IterativeExtrema(dim)
iter te = ot.IterativeThresholdExceedance(dim, 4.0)
for i in range(size):
   x = rv.getRealization()
    iter mom.increment(x)
    iter ext.increment(x)
    iter_te.increment(x)
xmin = iter ext.getMin()
xmax = iter_ext.getMax()
variance = iter_mom.getVariance()
skewness = iter mom.getSkewness()
pf = iter_te.getThresholdExceedance()
```

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NAIS

- Nonparametric Adaptive Importance Sampling (Morio 2015)
- Adaptive method based on the idea of Importance Sampling

$$\widehat{P}^{\mathsf{IS}} = rac{1}{N} \sum_{i=1}^{N} \mathbf{1}_{g(\mathbf{x}_i) < T} rac{h_0(\mathbf{x}_i)}{h(\mathbf{x}_i)}$$

- Updates an importance density from KS (Gauss + Silverman)
- Comparable to subset simulations
- No tuning needed

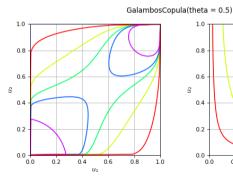


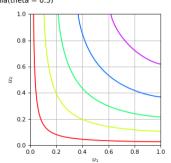
Galambos copula

bivariate extreme value copula

$$C(u_1, u_2) = u_1 u_2 \exp \left[(-\log(u_1))^{-\theta} + (-\log(u_2))^{-\theta} \right]^{-1/\theta}$$

• aims at modelling the dependence of rare events



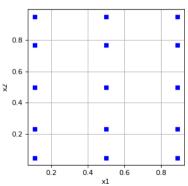


Tensor product experiment

• Tensorize a set of elementary (d>=1) designs of experiments

$$\int_{\mathcal{X}} g(\mathbf{x}) f(\mathbf{x}) d\mathbf{x} \approx \sum_{i=1}^{s_t} w_i g(\mathbf{x}_i)$$

Tensor product Gauss experiment



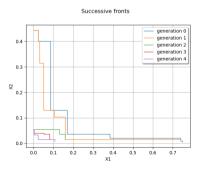
Tensor product experiment

```
exp1 = ot.GaussProductExperiment(ot.Uniform(0.0, 1.0), [3])
exp2 = ot.GaussProductExperiment(ot.Uniform(0.0, 1.0), [5])
exp_tens = ot.TensorProductExperiment([exp1, exp2])
nodes, weights = exp_tens.generateWithWeights()
```

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Multi-objective optimization

- massively parallel optimization Pagmo library from ESA
- 18 bio-inspired and evolutionary global algorithms
- 4 multi-objective algorithms
- some support batch evaluation / constraints / MINLP



Multi-objective optimization

```
pop0 = ot.ComposedDistribution([ot.Uniform(0.0, 1.0)] * 2).getSample(100)
algo = ot.Pagmo(zdt1, 'nsga2', pop0)
algo.setGenerationNumber(180)
algo.run()
result = algo.getResult()
pop1 = result.getFinalPoints()
fronts = result.getParetoFrontsIndices()
```

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Other improvements

- New maintainer in Debian (P. Gruet, EDF)
- Weekly Python wheels for Windows too
- Continued bugfix / documentation / modules effort

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END

Thank you for your attention! Any questions?

