

Meta-modeling and GSA in large dimension in fluvial hydrodynamics

CERFACS-OpenTURNS November, 22nd 2021

S. Ricci

Acknowledgment: S. El Garroussi, M. De Lozzo (IRT),
N. Goutal (EDF, LHSV), D. Lucor (LISN)



Uncertainty Quantification (UQ) @ Cerfacs

Data Driven Modeling Axis @CERFACS

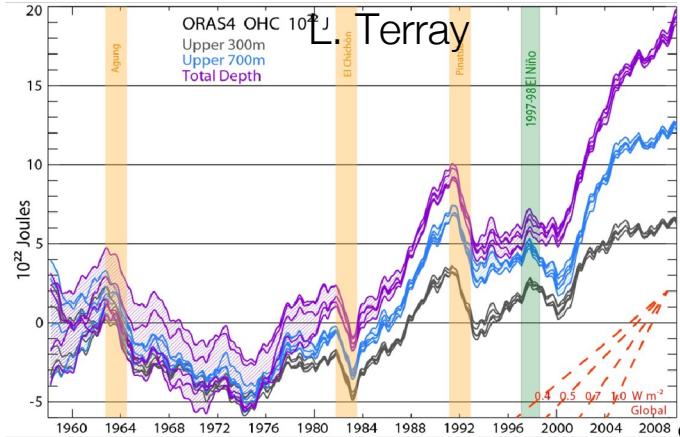
Objective: develop and apply uncertain quantification algorithms for complex problems

Actions:

- 1 - Ensemble generation and Design of Experiment for functional variables with space reduction solutions
- 2 - Development and evaluation of objective oriented cost-effective Surrogate Model methodologies for large dimension problems
- 3- Efficient use of surrogate models for sensitivity analysis, optimization, data assimilation
- 4 - Development of HPC efficient algorithms for stochastic estimation with solvers of increasing complexity (multi-fidelity, Multi-Level Monte Carlo)

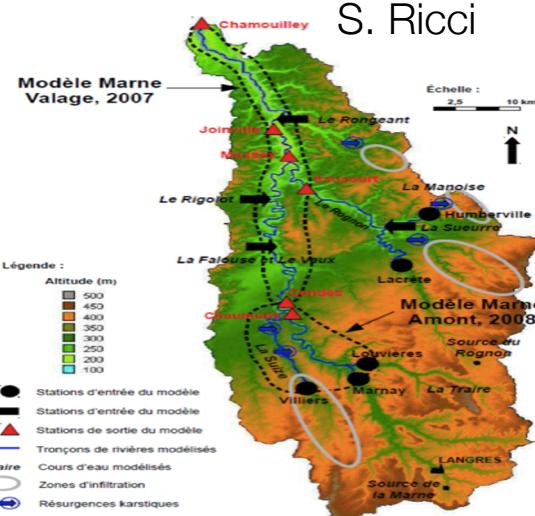
Uncertainty Quantification @ CERFACS

Climate/ocean forecasting and reanalysis



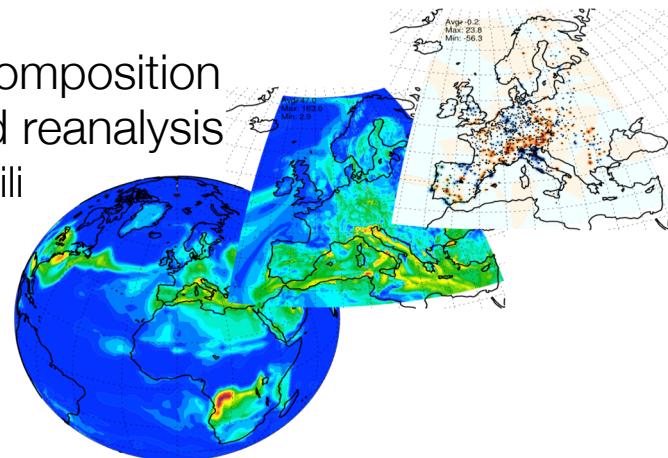
Flood forecasting

S. Ricci



Atmospheric composition forecasting and reanalysis

E. Emili

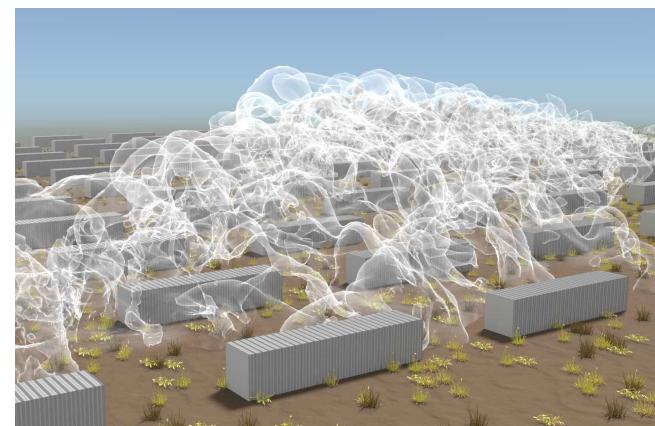


Algorithms and methods

P. Mycek

Pollutant dispersion reanalysis

M. Rochoux, T. Jaravel





Use Cases

- **Use Case #1:** Development of surrogate models for sensitivity analysis and ensemble-based data assimilation. Application in hydraulics for large dimension uncertain variables.
- **Use Case #2:** Development of UQ algorithms for exascale computing with efficient, scalable and resilient domain decomposition algorithms
- **Use Case #3:** Surrogate models for large-eddy simulations of atmospheric boundary layer to emulate micro-scale meteorology and assess structural and parametric uncertainty. Development for pollutant dispersion application.
- **Use Case #4:** Application of Multifidelity-MLMC algorithms for industrial CFD, multi-disciplinary systems and geosciences.
- **Use Case #5:** Building testbed for global climate projection uncertainty. Use emulation/simple climate models to test constraints on future climate projections and improve existing scenario projections, assess uncertainties in long term warming trajectories and improve consistency between physical system models and socioeconomic models.



Resources

PhDs/Post-docs @CERFACS:

- B. Nony (M. Rochoux), appli dispersion polluants
- E. Lumet (M. Rochoux), appli assim capteurs mobiles
- S. Peatier (B. Sanderson), appli climat
- S. Salle (N. Gourdain-ISAE, S. Ricci,), GSA impact climat sur aviation
- R. Despoey (S. Ricci, M. Balesdent- ONERA), Multi-fidélité pour optimisation robuste et dépassement de seuil
- R. El Amri (P. Mycek, S. Ricci, M. De Lozzo – IRT), Multi-fidélité, GSA pour MDO-MDA avec UQ
- S. El Garroussi (S. Ricci), appli hydrodynamique fluviale

Surrogate modeling for flood in Hydrodynamics

[S. El Garrousi (CERFACS), S. Ricci (CERFACS), M. De Lozzo (IRT), N. Goutal (EDF, LHSV), D. Lucor (LIMSI)]

From deterministic to uncertain flood forecast

S. El Garroussi et al., Simhydro 2021



Vigicrues.gouv.fr: carte 24/11/2016



LeMonde.fr/article/2020/10/05/bilan-meurtrier-precipitations-records-evolution

- Uncertainties in data,
 - Uncertainties in human expertise,
 - Uncertainties related to the nature of certain events,
 - The limits of vigilance at the departmental level, ...
-
- Uncertainties related to observations,
 - Uncertainties related to numerical models for meteorological, hydrological and **hydraulic** forecasting.

CEPRI, Prévision et anticipation des crues et des inondations, 2018

Shallow water equations (2D formulation) [1871]

$$\begin{aligned}\frac{\partial h}{\partial t} + \operatorname{div}(hu) &= 0 \\ \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} &= -g \frac{\partial Z_s}{\partial x} + F_s + \frac{1}{h} \operatorname{div}(hv_e \operatorname{grad}(u)) \\ \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} &= -g \frac{\partial Z_s}{\partial y} + F_v + \frac{1}{h} \operatorname{div}(hv_e \operatorname{grad}(v))\end{aligned}$$

Advection Gradient of hydrostatic pressure Source terms, friction Diffusion Turbulence Dispersion

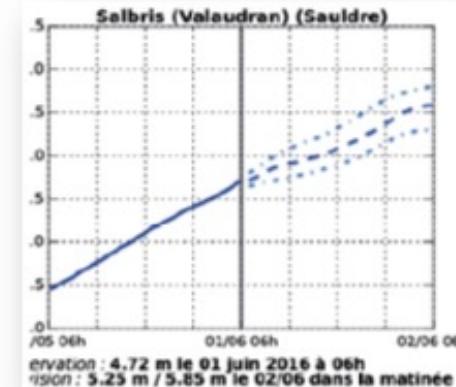
Assumptions of the model

Boundary conditions

Initial conditions

Bathymetry

Hydraulic forcing



Example of a forecast graph distributed by the SPC "Loire-Cher-Indre" during the floods of June 2016

Flood forecasting models are prone to uncertainties; these uncertainties must be reduced to improve their prediction.

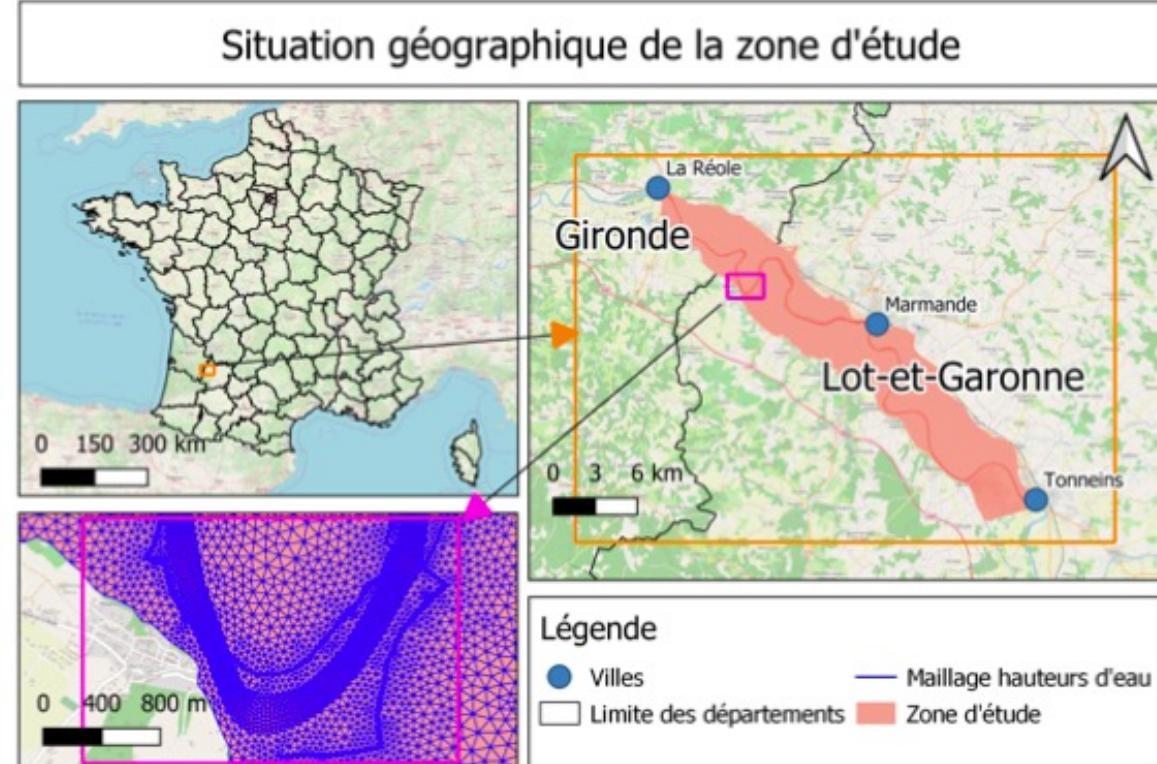
Surrogate modeling for flood in Hydrodynamics

[S. El Garrousi (CERFACS), S. Ricci (CERFACS), M. De Lozzo (IRT), N. Goutal (EDF, LHSV), D. Lucor (LIMSI)]

Study area and experimental settings

S. El Garrousi et al., UNECECOMP 2021

- The study area extends over a 50 km reach of the Garonne river from Tonneins (upstream) to the confluence with the rivers Lot and La Réole (downstream).
- Uncertain parameters: upstream discharge and 4 friction coefficients; assumed to be **independent**.
- Variable of interest: water depth map (41,416 mesh nodes).
- The upstream discharge is assumed to be normal and the friction coefficients are assumed to be uniform.
- A T2D simulation of a 3-day flood event lasts 20 minutes.
- The size of the training sample for the surrogate model is 1,000 T2D simulations. The validation sample size is 500 T2D simulations.



Study area of the Garonne river (southwest France) 50-km reach between Tonneins (upstream) and La Réole (downstream), the blue circles represent the in-situ Vigicrue stations and the pink zoom shows the spatial discretization.

Surrogate modeling for flood in Hydrodynamics

[S. El Garrousi (CERFACS), S. Ricci (CERFACS), M. De Lozzo (IRT), N. Goutal (EDF, LHSV), D. Lucor (LIMSI)]

Building a meta-model for large output space in the presence of non linearities between uncertain inputs and outputs

PhD S. El Garroussi

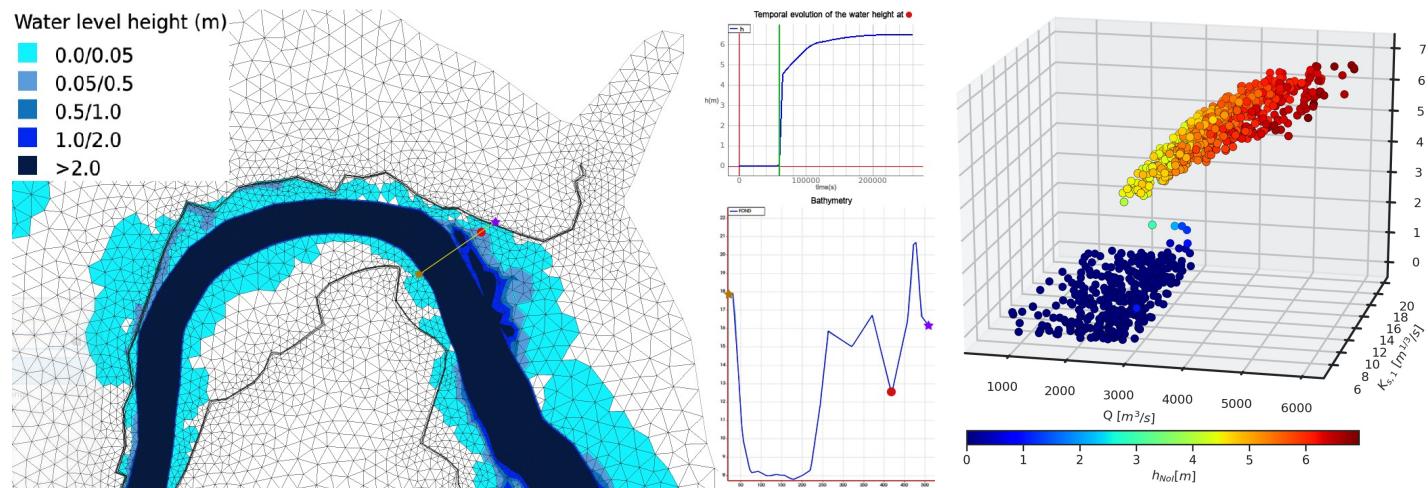
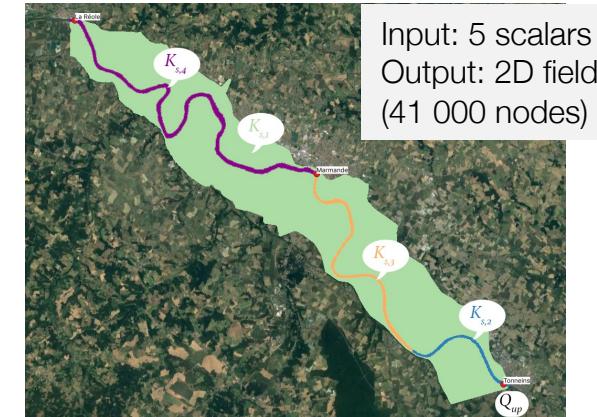
General Objective

Build a surrogate to approximate 2D WSE in flood plains

- carry out a GSA with respect to friction and inflow
- identify control vect. for uncertainty reduction with Data Assimilation

Difficulties

- non-linearities between input and output space, especially in region with strong bathymetry gradients
- large dimension output space





Surrogate modeling for flood in Hydrodynamics

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Uncertainty quantification in a two-dimensional river hydraulic model

El Garroussi et al., UNECECOMP, 2019

Classical approach

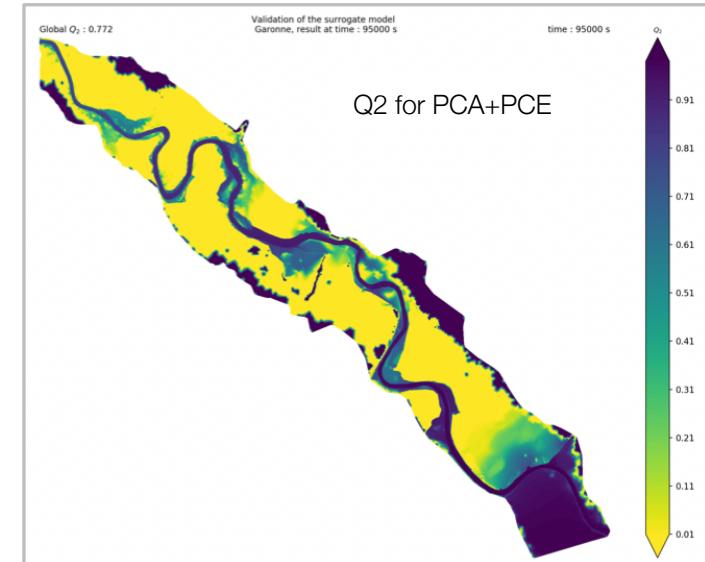
- o Principal Component Analysis for reduction of the output space dimension
- o A unique Polynomial Chaos Expansion in the reduced input space over the entire output domain

Polynomial chaos expansions (PCE) of (2nd order) stochastic processes (Wiener, 1938):

$$\underline{y} = \sum_{\alpha \in \mathbb{N}^d} \gamma_\alpha \psi_\alpha(\underline{x}),$$

where:

- ▶ $\underline{x} = (\underline{x}_1, \dots, \underline{x}_d)$ a set of independent second order random variables with given joint density $f_{\underline{x}}$,
- ▶ $\psi_\alpha(\underline{x}) = \prod_{i=1}^d \psi_{i,\alpha_i}(x_i)$ is a tensor product of univariate orthonormal polynomials,
i.e. $\mathbb{E} [\psi_{i,j}(\underline{x}_i) \psi_{i,k}(\underline{x}_i)] = \int_{D_{x_i}} \psi_{i,j}(x_i) \psi_{i,k}(x_i) f_{x_i}(x_i) dx_i = \delta_{jk}$,
- ▶ γ_α is the deterministic coefficient associated with ψ_α . Knowledge of the γ_α , using least square approximation, for example, fully characterizes the process \underline{y} .



Merits and Limitations

- + Thanks to the orthogonality of the basis, one can immediately deduce the Sobol decomposition of the PCE
- A unique Polynomial Chaos Expansion over the entire domain does not account for non-linearities (Li and Ghanem 1998) or stochastic discontinuities (Najm, 2009)

Surrogate modeling for flood in Hydrodynamics

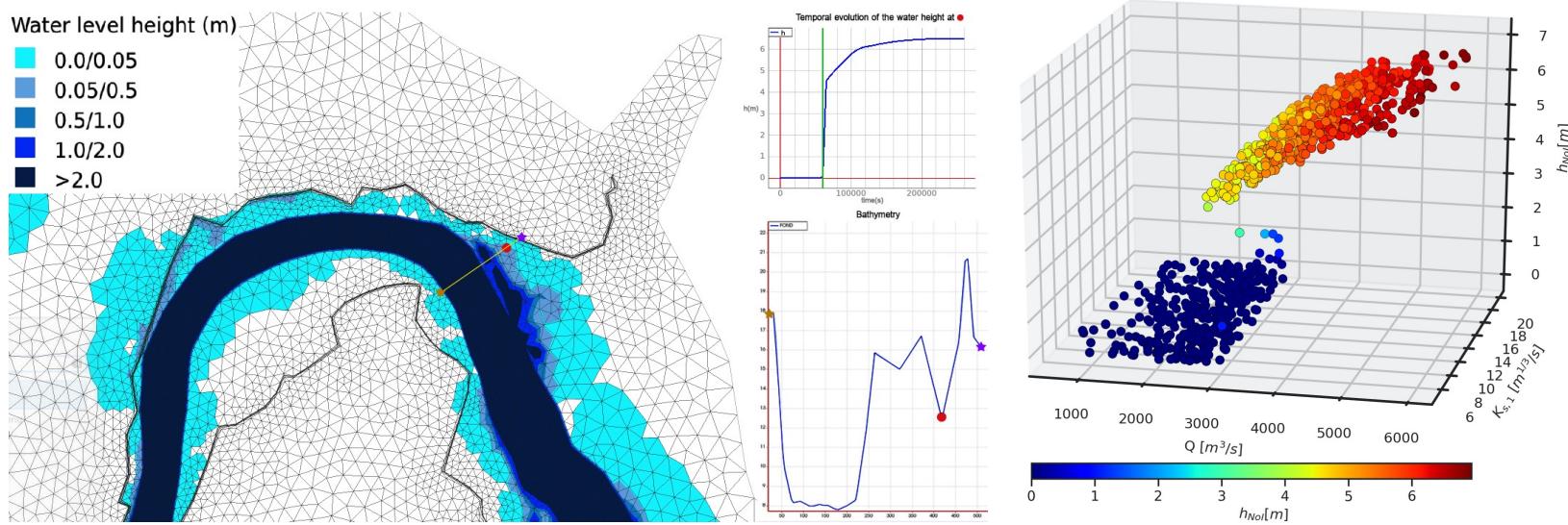
[S. El Garrousi (CERFACS), S. Ricci (CERFACS), M. De Lozzo (IRT), N. Goutal (EDF, LHSV), D. Lucor (LIMSI)]

Assessing uncertainties in flood forecasts using a mixture of generalized polynomial chaos expansions

S. El Garroussi et al.
Proceedings TUC2020

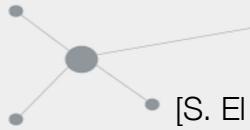
Focus:

Dealing with non linearities, **at one critical node with MoE**



Advanced methodology

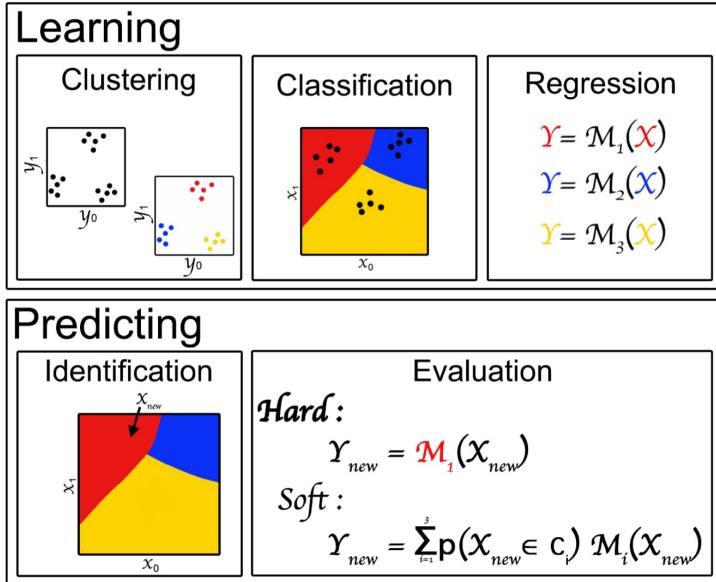
- Dimension reduction for non linear functional outputs
- Mixture of experts for each grid point



Surrogate modeling for flood in Hydrodynamics

[S. El Garroussi (CERFACS), S. Ricci (CERFACS), M. De Lozzo (IRT), N. Goutal (EDF, LHSV), D. Lucor (LIMSI)]

Mixture of experts for local solution **at one critical node**



Clustering - classifying

Machine Learning techniques to partition the input space into clusters where non linearities do not occur

GMM, K-Means from Scikit Learn

S. El Garroussi et al.
Proceedings TUC2020

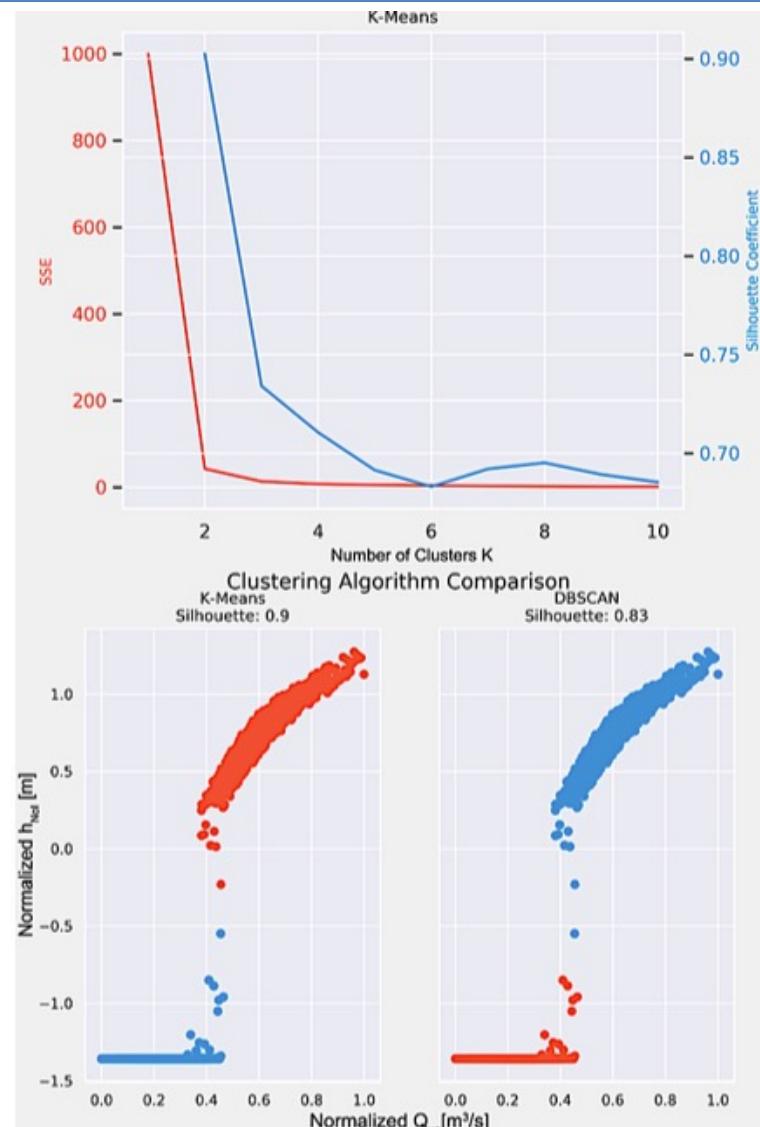


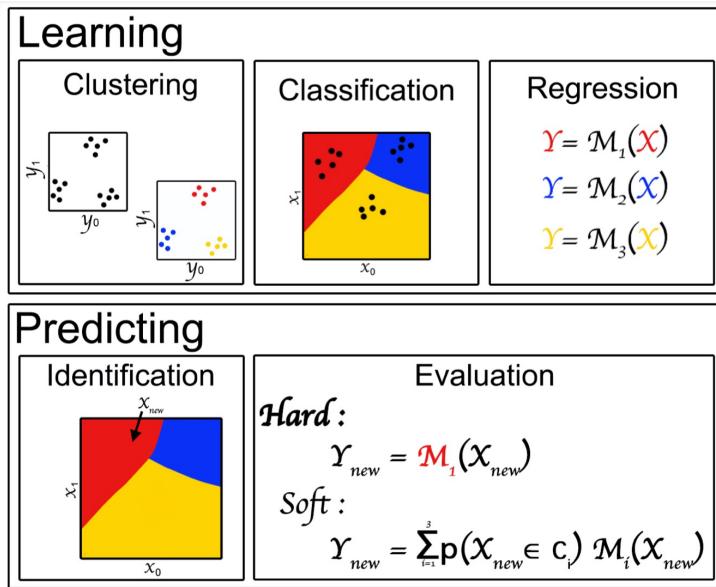
Figure 5: A. The top curve represents the evolution of the two metrics: the SSE in red, and the silhouette coefficient in blue for the K-Means clustering method. B. Bottom left, a comparison of clustering methods: K-Means and DBSCAN. Silhouette: 0.9 Silhouette: 0.83



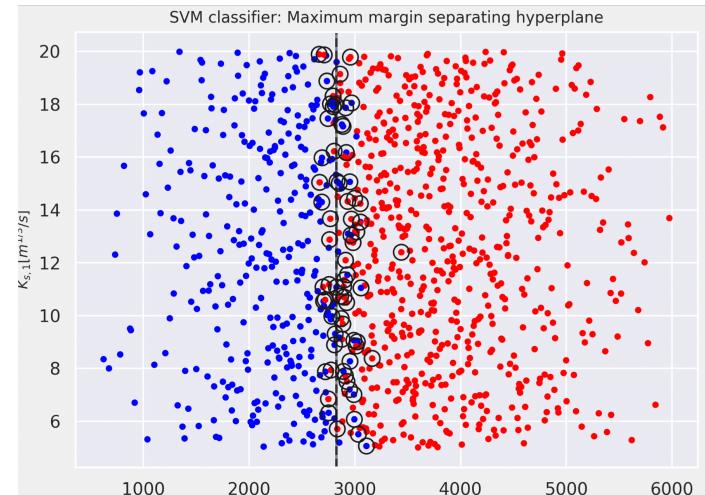
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Mixture of experts for local solution **at one critical node**



Clustering with K-means in input space



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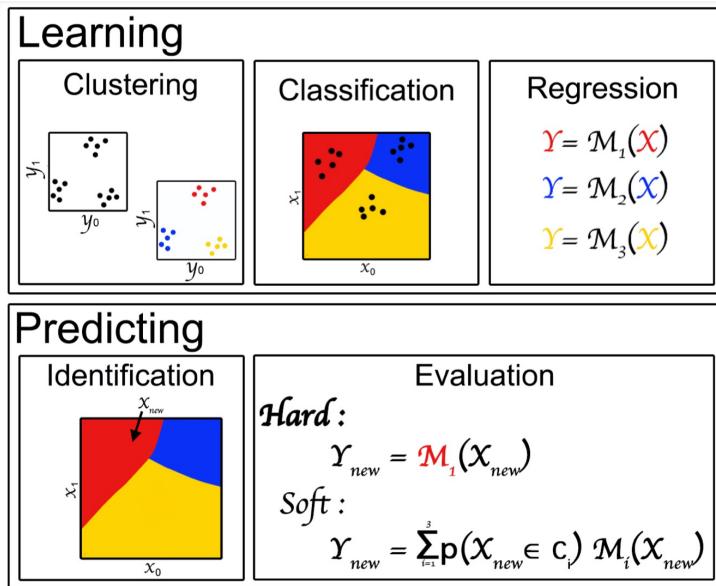
S. El Garrousi et al.
Proceedings TUC2020



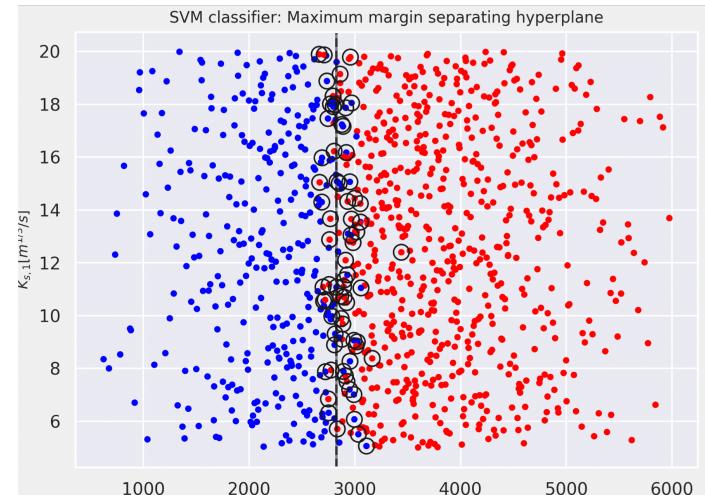
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Mixture of experts for local solution **at one critical node : Divide and conquer**



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Mixture of experts for local solution at **all critical nodes** (one gPCE by critical node) and **GSA**

S. El Garroussi et al.
Proceedings TUC2020

Surrogate models' performance	gPCE	MoE-gPCE
RMSE [m]	0.92	0.02
Q_2	0.54	0.98

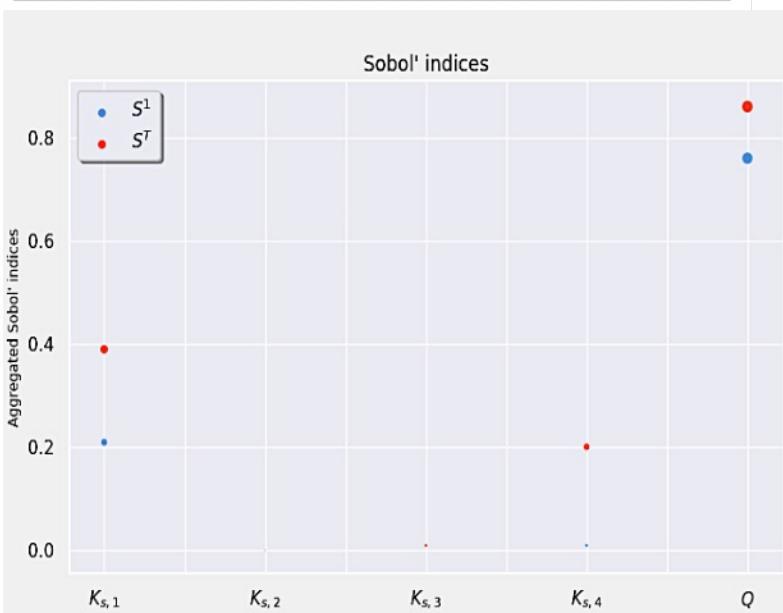


Fig. 7: Sobol' indices for water height at node NoI.

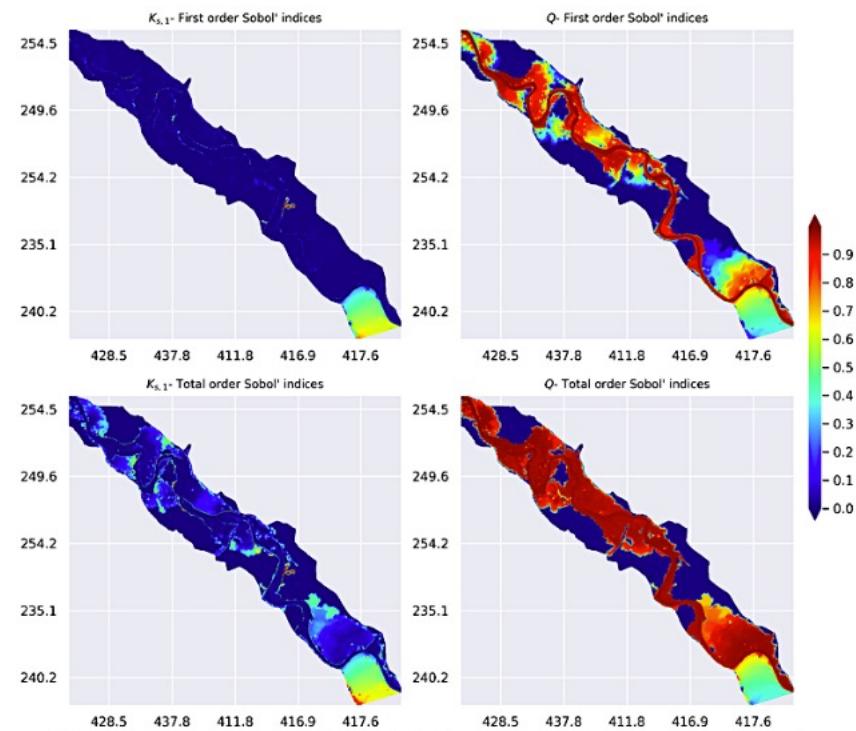


Fig. 8: Spatial aggregated Sobol' indices, first at the top and total in the bottom, for the water height discretized over the mesh following the uncertain inputs: $K_{s,1}$ on the left and Q on the right.

Limitations

- Computational cost of building 72 000 gPCE (3 000 critical nodes, 8 values PCD degree, 3 classes)
- Need to work on the output dimension in the context of MoE strategy

Surrogate modeling for flood in Hydrodynamics

[S. El Garrousi (CERFACS), S. Ricci (CERFACS), M. De Lozzo (IRT), N. Goutal (EDF, LHSV), D. Lucor (LIMSI)]

Tackling random fields non-linearities with unsupervised clustering of polynomial chaos expansion in latent space: application to global sensitivity analysis of river flooding

S. El Garrousi, S. Ricci, M. De Lozzo, N. Goutal, D. Lucor, SERRA, 2021

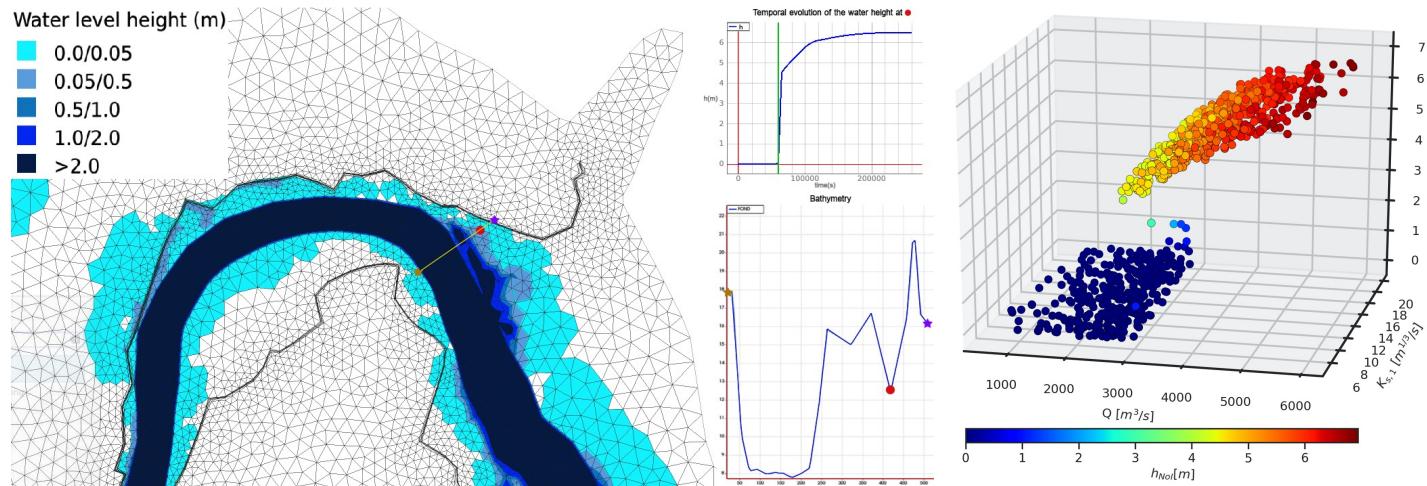
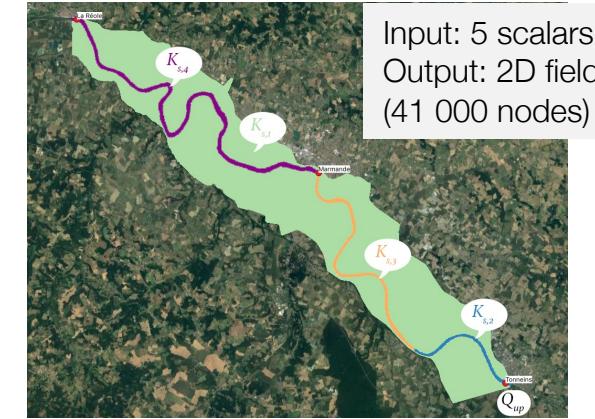
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Surrogate modeling for flood in Hydrodynamics

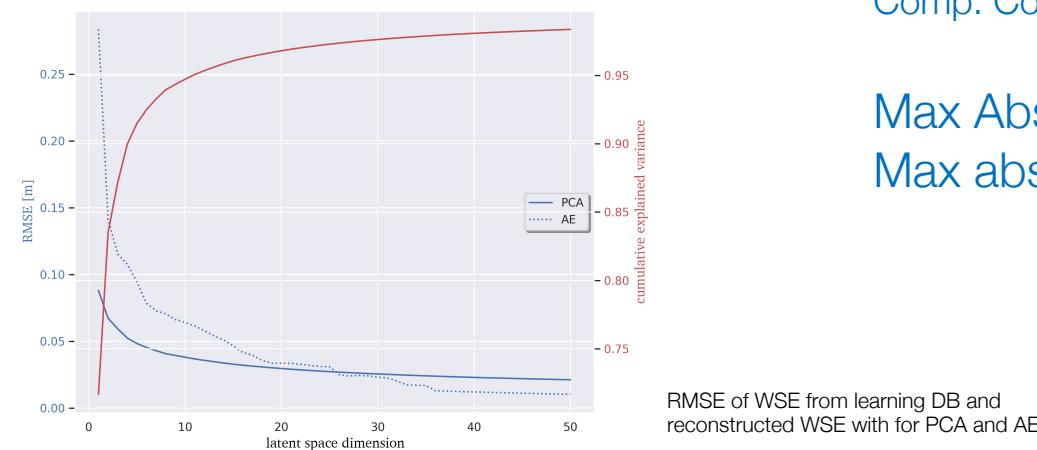
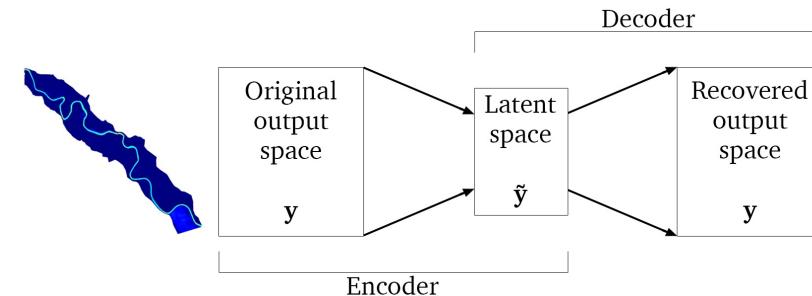
[S. El Garroussi (CERFACS), S. Ricci (CERFACS), M. De Lozzo (IRT), N. Goutal (EDF, LHSV), D. Lucor (LIMSI)]

Advanced methodology

- Mixture of experts
- Dimension reduction for non linear functional outputs

Dimension Reduction of the output space

- Need to lower the cost of the surrogate formulation when working over the entire field



DIMENSION REDUCTION

- Principal Component Analysis
- Auto-encoder ([Keras Tensor Flow](#)) based on unsupervised artificial neural network

37 components :
RMSE PCA = 3.82 cm
RMSE AE = 1.27 cm

Comp. Cost AE (2h) >> Comp. Cost PCA (3min)

Max Absolute Error PCA >3m
Max absolute Error AE < 1cm

S. El Garroussi, S. Ricci, M. De Lozzo, N. Goutal, D. Lucor, SERRA, 2021

Surrogate modeling for flood in Hydrodynamics

[I. Raguet (ENM), L. Gibert(ENM), M. Magnan (ENM), A. Mengin (ENM), S. El Garrousi (CERFACS), S. Ricci (CERFACS)]

- Analyse en Composantes Principales (PCA – [Scikit Learn](#))
- Analyse en Composantes Principales à Noyau (KPCA – [Scikit Learn](#)) : prise en compte des non linéarités
- Transformation de Karhunen-Loève (KL-SVD - [OpenTURNS](#)) : prise en compte des hétérogénéités du maillage

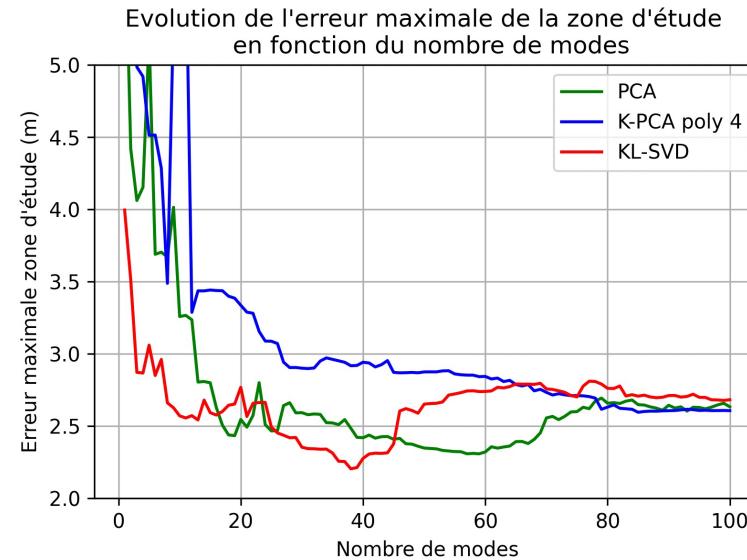
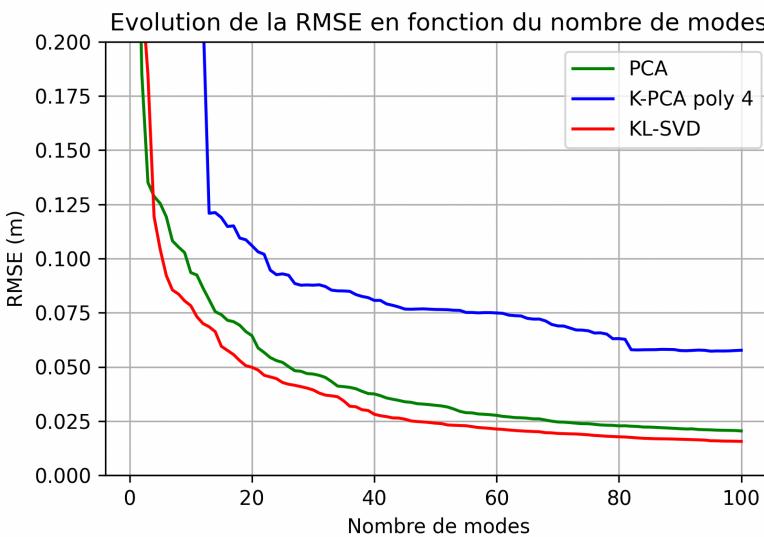
Métriques globales	PCA
MAE [cm]	1
RMSE [cm]	2,66
R ² [%]	95,93

Maximum error PCA = 2.35 m

Noyaux	RMSE [m]	R ² [%]	MAE [m]	Erreurs maximale moyenne globale [m]	Erreurs Maximale [m]
Poly-2	0,09	91,71	0,04	0,29	2,66
Poly-3	0,07	94,36	0,03	0,24	2,70
Poly-4	0,07	95,05	0,03	0,24	2,81
Cosine	0,11	86,28	0,04	0,69	2,71
RBF	0,26	64,33	0,99	1,51	3,78

Métriques globales	KL-SVD
MAE [cm]	0,78
RMSE [cm]	2,06
R ² [%]	94,37

Maximum error KL-SVD = 2.6 m



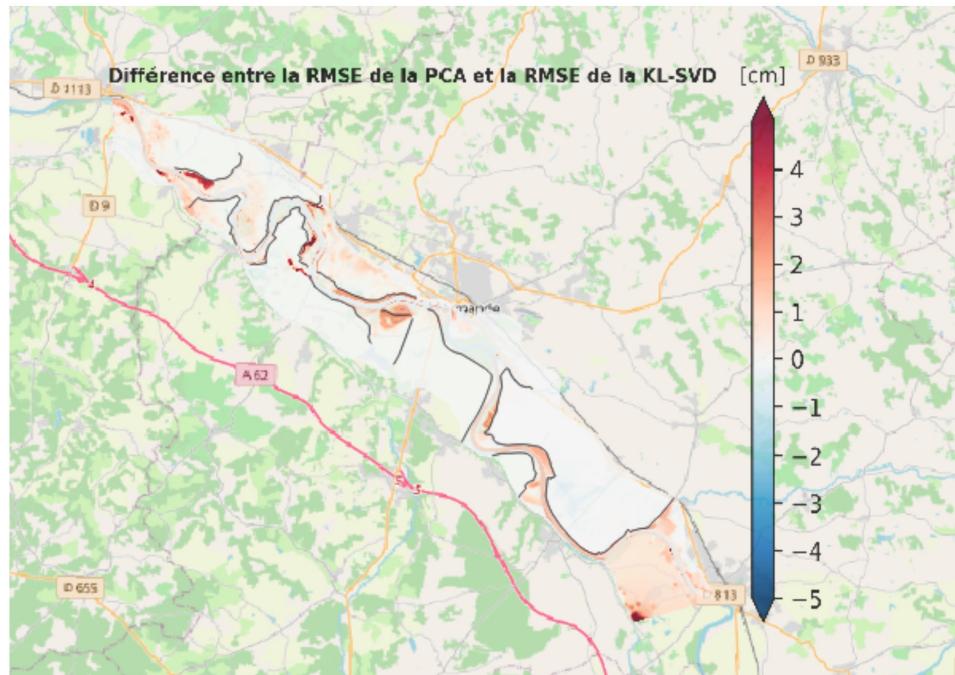
Projet Modélisation ENM-CERFACS
(stage court)

- ▶ $\text{RMSE}^{\text{KL-SVD}} < \text{RMSE}^{\text{PCA}} \ll \text{RMSE}^{\text{KPCA}}$
- ▶ Erreur maximale > 2,3 m pour les trois méthodes

Surrogate modeling for flood in Hydrodynamics

[I. Raguët (ENM), L. Gibert(ENM), M. Magnan (ENM), A. Mengin (ENM), S. El Garroussi (CERFACS), S. Ricci (CERFACS)]

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PCA

- Temps de calcul courts (10s), simple
- Pas de prise en compte des non linéarités et hétérogénéités de la géométrie

KPCA

- Temps de calcul courts (10s)
- Nécessité de tester plusieurs noyaux
- Pas d'amélioration de l'erreur maximale locale

KL-SVD

- Meilleure reconstruction des hauteurs d'eau dans le lit majeur intra-digues où les maillage varie, les gradient de bathymétrie forts et où les vitesses d'écoulement sont fortes
- Pas d'amélioration de l'erreur maximale locale
- Temps de calcul long (6 min)

Projet Modélisation ENM-CERFACS
(stage court)

Alternative: Auto-encoder



Surrogate modeling for flood in Hydrodynamics

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Advanced methodology

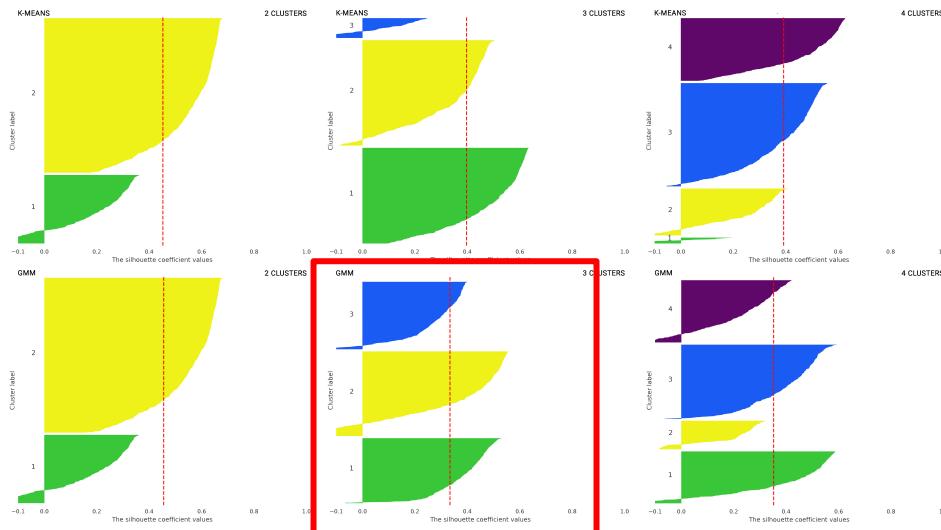
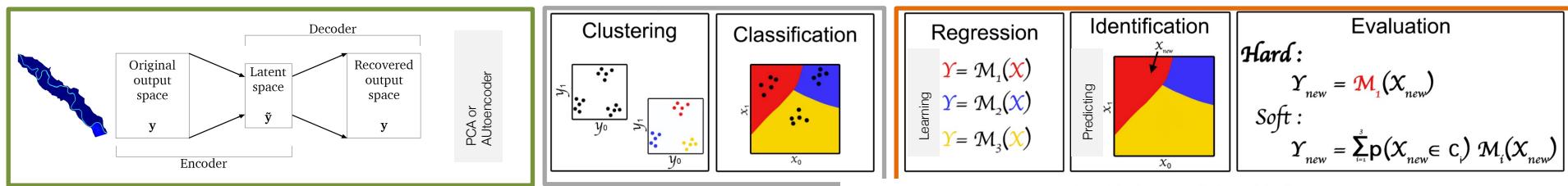
- Mixture of experts
- Dimension reduction for non linear functional outputs

rMPCE strategy

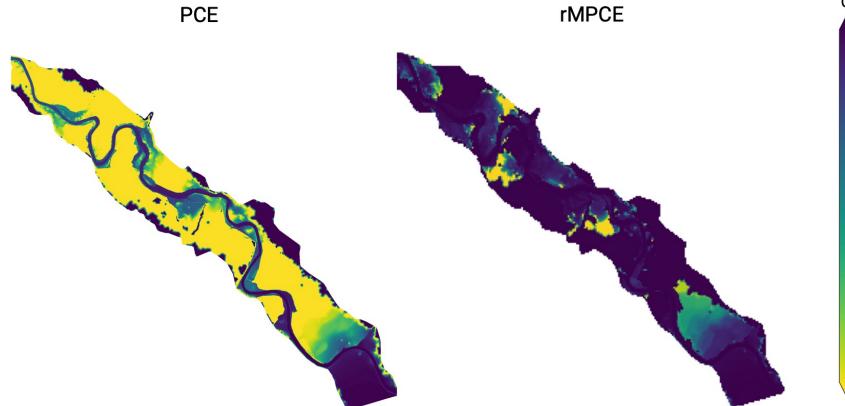
Reduce output dimension taking into account spatial non-linearities with ML

Classify the input/output space with unsupervised and supervised ML

Build a mixture of local polynomial expansion surrogates



Predictive model validation



Improvement of the surrogate model predictive coefficient with rMPCE w.r.t single PCE over 90% of the domain



Surrogate modeling for flood in Hydrodynamics

[S. El Garrousi (CERFACS), S. Ricci (CERFACS), M. De Lozzo (IRT), N. Goutal (EDF, LHSV), D. Lucor (LIMSI)]

Data: The learning dataset (\mathbf{X}, \mathbf{Y})

Result: The rMPCE model

Parameters: The latent space dimension \tilde{p} and the groups' number K

begin

$\tilde{\mathbf{Y}} \leftarrow$ Reduce the dimension of \mathbf{Y} from p to \tilde{p} ;

$\mathcal{L}_1, \dots, \mathcal{L}_K \leftarrow$ Split \mathcal{L} into K sub-datasets from a clustering on $\tilde{\mathbf{Y}}$;

$C : \mathbf{x} \mapsto C_1(\mathbf{x}), \dots, C_K(\mathbf{x}) \leftarrow$ Build a classifier from $\mathbf{X}, \mathcal{L}_1, \dots, \mathcal{L}_K$;

for $k \leftarrow 1$ **to** K **do**

$\widetilde{\mathbf{Y}}^{(k)} \leftarrow$ Reduce the dimension of $\mathbf{Y}^{(k)} = \left(y_j^{(i)} \right)_{\substack{i \in \mathcal{L}_k \\ 1 \leq j \leq p}}$ to \tilde{p} ;

$\text{PCE}_k \leftarrow$ Build a PCE from $\mathbf{X}^{(k)} = \left(x_j^{(i)} \right)_{\substack{i \in \mathcal{L}_k \\ 1 \leq j \leq d}}$ and $\widetilde{\mathbf{Y}}^{(k)}$;

end

$\text{rMPCE} \leftarrow \text{PCE}_1, \dots, \text{PCE}_K$ and the classifier C ;

end

Algorithm 1: Learning stage of the rMPCE

1. Reduction of the output variable dimension,
2. Unsupervised clustering of the learning output data into K groups,
3. Classification of the input space into K subspaces, based on the clustering results,
4. Construction of a 2D-functional output PCE surrogate for each cluster.

then use rMPCE for GSA

Data: A new input data \mathbf{x} and the rMPCE model.

Result: The predicted output data $\hat{\mathbf{y}}$.

begin

$C_1(\mathbf{x}), \dots, C_K(\mathbf{x}) \leftarrow$ Compute the degree of membership to the K sub-groups;

for $k \leftarrow 1$ **to** K **do**

$\hat{\mathbf{y}}_k \leftarrow$ Compute the k^{th} local prediction with $\text{PCE}_k(\mathbf{x})$;

end

$\hat{\mathbf{y}} \leftarrow$ Combine the predictions with $\sum_{k=1}^K C_k(\mathbf{x}) \hat{\mathbf{y}}_k$;

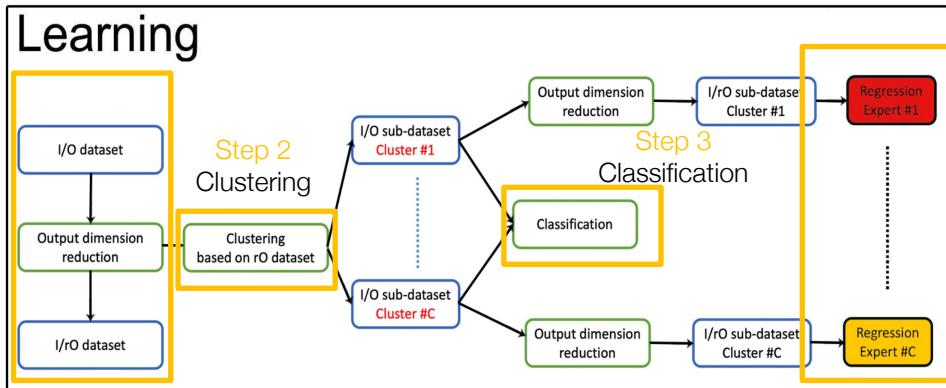
$\hat{\mathbf{y}} \leftarrow$ Expand the output dimension from $\hat{\mathbf{y}}$ (*decoding*);

end

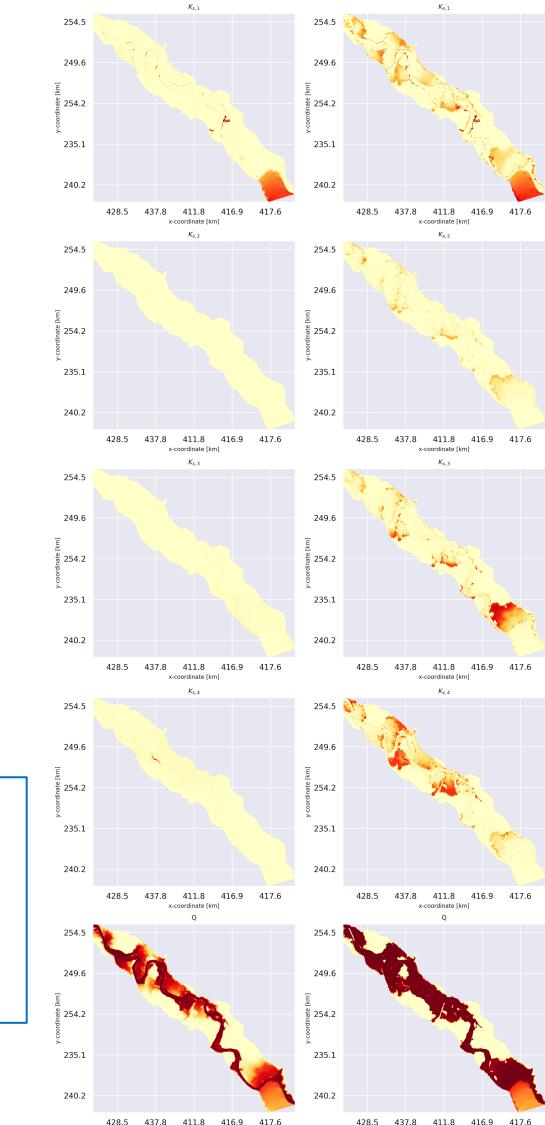
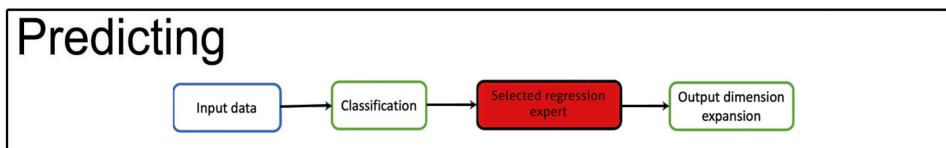
Algorithm 2: Prediction stage with the rMPCE model

Surrogate modeling for flood in Hydrodynamics

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Step 4
Regression



Perspectives

- Compute surrogate over time for real flood event by extending input space
- Use surrogate for SA and covariance estimation (low cost EnKF)

Sobol indices highlight that upstream forcing is the predominant source of uncertainty in water level



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Thank you for your attention