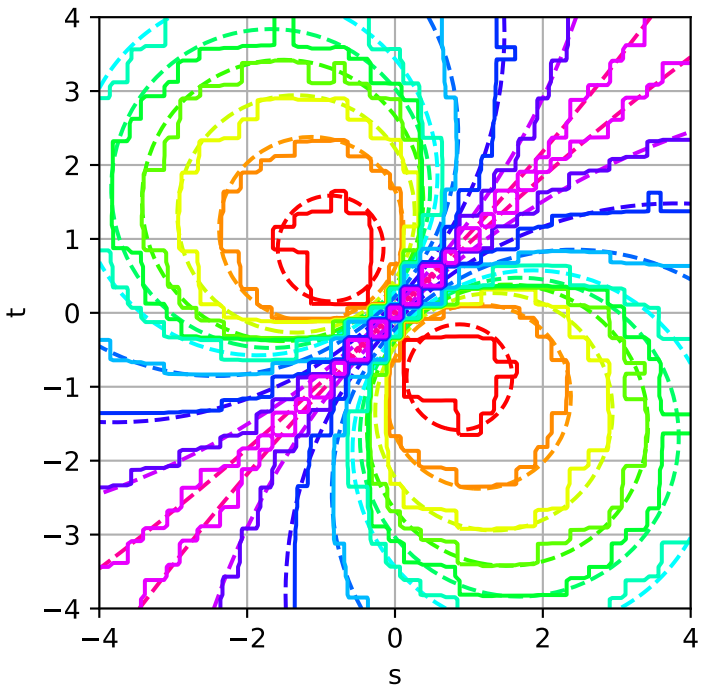
Non stationary covariance model estimation
4
3
2
1
0
−1
−2
−3
−4
t
−4
−2
0
2
4
s