

OTICSCREAM: A Python module (and a cooking recipe) for the identification of penalizing configurations in computer experiments

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Introduction

❑ Industrial motivations: risk analysis in nuclear safety

- Deterministic analyses (“worst cases”)
 - Historical
 - Supposed to be “conservative” enough
 - **But** sometimes, far from reality!
- Probabilistic analyses (“Best Estimate Plus Uncertainty” or **BEPU**)
 - Supposed to produce more realistic physics!
 - Needs to take (explicitly) uncertainties into account!
 - **But** safety margins need to be identified clearly!

❑ Simulation of an Intermediate-Break Loss-Of-Coolant Accident¹

- Modeling of a primary circuit (cold leg) of a PWR²
- Simulation of a thermal-hydraulic transient scenario
- Best-estimate computer model: the CATHARE2 code

¹IBLOCA

²Pressurized Water Reactor

Context and motivations

❑ Simulation of an IBLOCA using the CATHARE2 code

- Uncertainty sources in input:
 - Type #1: Initial/boundary conditions → probabilistic (\mathcal{U} , trunc. \mathcal{N})
 - Type #2: Physical parameters → probabilistic (\mathcal{U} , \mathcal{LU} , trunc. \mathcal{N} , \mathcal{LN})
 - Type #3: Scenario parameters → not proba. (lower/upper bounds)
- Scalar output quantity of interest (QoI):
 - Second peak of cladding temperature (PCT)

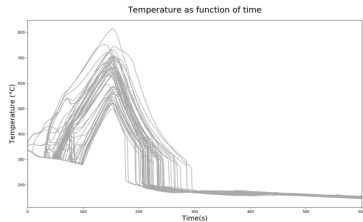
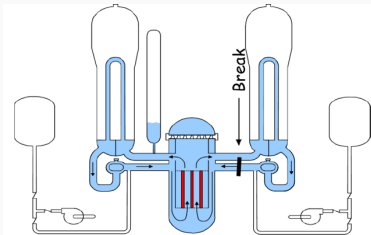


Figure 1: IBLOCA in a PWR (©CEA) / PCT trajectories from CATHARE2 (©EDF).

Context and motivations

❑ Main objectives

- How to identify the most **penalizing configurations** for Type #3 inputs (scenario parameters) regardless the other sources of uncertainties (Type #1 and Type #2)?
- **Penalizing configurations** → Leading to high PCT values

❑ Main challenges/constraints

- Large number of inputs (≈ 100) → Effective dimension might be lower!
- Complex phenomena / strongly nonlinear response!
- Computational cost → Only $\approx 10^3$ simulations available!
- Industrial/regulatory context → crude Monte Carlo (i.i.d.)

Questions

- 🔦 How to handle these challenges and constraints?
- 🔦 Can we propose a generic methodology?

The ICSCREAM methodology

ICSCREAM: a four-step methodology

❑ Non-exhaustive list of available tools in the UQ literature

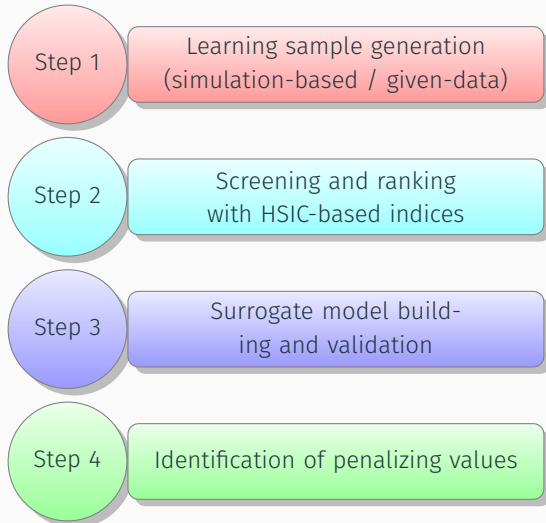
- Global sensitivity analysis techniques to reduce the input dimension
- Smart adaptive surrogate modeling strategies
- Approximation tools based on low-rank or projection-based methods
- Adaptive strategies for robust inversion [RB19]
→ We probably need to combine all these things together, as in a cooking recipe!

❑ A possible answer: the ICSCREAM (ice-cream) methodology

- Originally proposed as a **specific answer** in the nuclear safety context (see [MIC22])
- **But** can still be seen as a **generic methodology** for a large panel of applications!
- Based on state-of-the-art UQ techniques (and a few advanced tools) gathered in a **modular framework**!
- Adapted to a **given-data** context (no access to the computer model)!

ICSCREAM: a four-step methodology

□ The ICSCREAM methodology in a nutshell!



Step 1

Step 1: Monte Carlo sampling (“given-data” context)

□ A few notations and preliminary hypotheses:

- Real-valued & deterministic black-box model:

$$\mathcal{M} : \left| \begin{array}{ll} \mathcal{X} \subseteq \mathbb{R}^d & \longrightarrow \mathcal{Y} \subseteq \mathbb{R} \\ \mathbf{X} & \longmapsto Y = \mathcal{M}(\mathbf{X}) \end{array} \right. \quad (1)$$

- Probabilistic modeling of d **independent** input physical variables:

$$\mathbf{X} := \underbrace{(X_1, X_2, \dots, X_p)}_{\mathbf{X}_{\text{pen}}} \underbrace{(X_{p+1}, \dots, X_d)}_{\mathbf{X}_{\text{alea}}}^\top \sim P_{\mathbf{X}} \quad \text{over} \quad \mathcal{X} = \bigtimes_{i=1}^d \mathcal{X}_i \quad (2)$$

where:

- \mathbf{X}_{pen} → candidate inputs to be **penalized** s.t. $\mathbf{X}_{\text{pen}} \sim \prod_{i=1}^p \mathcal{U}([a_i, b_i])$
- \mathbf{X}_{alea} → aleatoric variables s.t. $\mathbf{X}_{\text{alea}} \sim P_{\mathbf{X}_{\text{alea}}}$

- **Learning sample** → get a n -size **i.i.d.** sample of the couple (\mathbf{X}, Y) :

$$\left(\mathbf{X}^{(j)}, Y^{(j)} \right)_{(1 \leq j \leq n)} = \left(X_1^{(j)}, X_2^{(j)}, \dots, X_d^{(j)}, Y^{(j)} \right)_{(1 \leq j \leq n)} \quad (3)$$

with $P_{\mathbf{X}^{(j)}} = P_{\mathbf{X}}$ and $Y^{(j)} = \mathcal{M} \left(X_1^{(j)}, X_2^{(j)}, \dots, X_d^{(j)} \right), \forall j \in \{1, \dots, n\}$

- **Risk analysis** → a typical QoI is the α -**order quantile** estimated using the empirical estimator $\hat{q}_\alpha(Y)$

Step 2

Step 2: Global and target sensitivity analyses

❑ Two usual settings in sensitivity analysis [DGIP21]

- “Can we split the inputs into two classes $\{\text{noninfluential}, \text{influential}\}$?”
→ Screening
- “Is it possible to rank the inputs with respect to their influence?”
→ Ranking

❑ Global (GSA) vs. target sensitivity analysis (TSA)

- “Does an input X_i have an influence on the global variability of Y ?”
→ GSA study
- “Does an input X_i have an influence on exceeding an output threshold (e.g., $\{Y > q_\alpha(Y)\}$) or not?”
→ TSA study [RM18, SLRDV19, MC21]

Step 2: Global and target sensitivity analyses

□ A brief overview of the literature

- Sobol' indices [PT17, PD19]
- Indices based on dissimilarity measures (e.g., Borgonovo indices, Csiszár f-divergences, etc.) [BP16, Rah16]
- **Hilbert-Schmidt Independence Criterion (HSIC)** [GBSS05, DV15]
 - ➔ Allows to measure influence beyond the variance
 - ➔ Adapted to the “given-data” context
 - ➔ Allows to perform GSA and TSA without having much trouble
 - ➔ Indices come together with a rigorous statistical framework

Step 2: Global and target sensitivity analyses

□ A brief overview about HSIC indices

- Basic idea: to assess the dependency between the random variables X_i and Y by comparing an infinite collection of features of both $P_{X_i,Y}$ and $P_{X_i}P_Y$
- We consider a dependence measure, the **maximum mean discrepancy (MMD)** between $P_{X_i,Y}$ and $P_{X_i}P_Y$, which is expressed as the distance between their mean embeddings in some RKHS³.

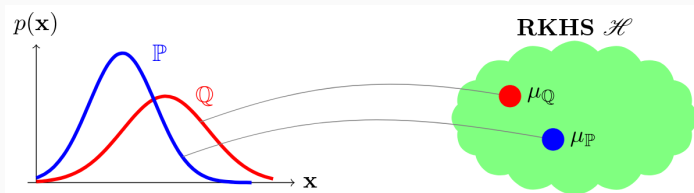


Figure 2: Embedding of marginal distributions (source: [MFSS17]).

³Reproducing Kernel Hilbert Space.

Step 2: Global and target sensitivity analyses

□ A brief overview about HSIC indices

- A first mathematical expression:

$$\text{HSIC}_{\kappa_i \kappa}(X_i, Y) = \text{MMD}_{\kappa_i \kappa}^2(P_{(X_i, Y)}, P_{X_i} P_Y) \quad (4a)$$

$$\begin{aligned} &= \mathbb{E}[\kappa_i(X_i, X'_i) \kappa(Y, Y')] + \mathbb{E}[\kappa_i(X_i, X'_i)] \mathbb{E}[\kappa(Y, Y')] \quad (4b) \\ &\quad - 2 \mathbb{E}[\mathbb{E}[\kappa_i(X_i, X'_i) | X_i] \mathbb{E}[\kappa(Y, Y') | Y]] \end{aligned}$$

- A fundamental property → if the kernels κ_i and κ are **characteristic**

$$\text{HSIC}_{\kappa_i \kappa}(X_i, Y) = 0 \Leftrightarrow X_i \perp Y \quad (5)$$

- In practice → one uses various types of **estimators** and a **statistical hypothesis testing** in order to decide whether an input is noninfluential or not

Step 3

Step 3: Gaussian process surrogate modeling

□ Gaussian process (GP) regression [RW06]

- Goal: build a predictor $\widetilde{\mathcal{M}}(\cdot)$ that mimics the behavior of $\mathcal{M}(\cdot)$ using a **dataset** $\mathcal{D} = \{(\mathbf{x}^{(i)}, y^{(i)}), i = 1, \dots, n\}$ (supervised learning)
- Probabilistic surrogate model \rightarrow assume

$$Y(\mathbf{x}) \sim GP(\mu(\mathbf{x}), \Sigma(\mathbf{x}', \mathbf{x})) \quad (6)$$

- GP conditioning on data (universal kriging predictor):

$$\widehat{Y}(\mathbf{x}) = [Y(\mathbf{x}) | \mathcal{D}, \sigma^2, \boldsymbol{\theta}] \sim \mathcal{N}_1(\mu_{\widehat{Y}}(\mathbf{x}), \sigma_{\widehat{Y}}^2(\mathbf{x})) \quad (7)$$

- Estimation strategies for $(\sigma^2, \boldsymbol{\theta}) \rightarrow$ MLE [MIVDV08]

Step 3: Gaussian process surrogate modeling

□ GP building in practice

- GP metamodel will be a function of several kind of inputs:
 - Explanatory inputs: $\mathbf{X}_{\text{exp}} = \{\mathbf{X}_{\text{PII}} \cup \mathbf{X}_{\text{pen}}\}$
 - Secondary influential inputs: \mathbf{X}_{SII}
 - Neglected inputs: $\mathbf{X}_{\epsilon} = \{\mathbf{X} \setminus \{\mathbf{X}_{\text{exp}} \cup \mathbf{X}_{\text{SII}}\}\}$
- GP mean: either constant or linear basis
- $\mathbf{X}_{\text{exp}} \rightarrow$ tensorized anisotropic covariance function (Matérn ν)

$$R_{\theta_{\text{exp}}}(\mathbf{x}_{\text{exp}}, \mathbf{x}'_{\text{exp}}) = \prod_{i=1}^{d_{\text{exp}}} R_{\theta_i}(x_{\text{exp}}^{(i)} - x'_{\text{exp}}{}^{(i)}) \quad (8)$$

- $\mathbf{X}_{\text{SII}} \rightarrow$ isotropic covariance function (Matérn ν)

$$R_{\theta_{\text{SII}}}(\mathbf{x}_{\text{SII}}, \mathbf{x}'_{\text{SII}}) = R_{\theta_{\text{SII}}}(\|\mathbf{x}_{\text{SII}} - \mathbf{x}'_{\text{SII}}\|_2) \quad (9)$$

- $\mathbf{X}_{\epsilon} \rightarrow$ homoscedastic nugget effect
- Resulting tensorized covariance:

$$\Sigma(\mathbf{x}, \mathbf{x}') = \sigma^2 (R_{\theta_{\text{exp}}}(\mathbf{x}_{\text{exp}}, \mathbf{x}'_{\text{exp}}) R_{\theta_{\text{SII}}}(\mathbf{x}_{\text{SII}}, \mathbf{x}'_{\text{SII}}) + \gamma \delta_{(\mathbf{x}, \mathbf{x}')}) \quad (10)$$

- GP metamodel either built directly or **sequentially**
- Optimization of hyperparameters \rightarrow multi-start + LHS + optim. algo.

Step 3: Gaussian process surrogate modeling

❑ Cross-validation metrics

➤ Validation of the GP predictor:

- Analysis of the standardized residuals
- Computation of the **predictivity coefficient** Q^2

$$Q^2 = 1 - \frac{\sum_{j=1}^{n_{\text{val}}} \left(y^{\text{val},(j)} - \hat{y}^{\text{val},(-j)} \right)^2}{\sum_{j=1}^{n_{\text{val}}} \left(y^{\text{val},(j)} - \bar{y}^{\text{val}} \right)^2} \quad (11)$$

- QQ-plot, rate of good classification, ...

➤ Validation of the GP predictive variance:

- Computation of the **Predictive Variance Adequacy** (PVA) [Bac13]

$$\text{PVA} = \left| \log \left(\frac{1}{n_{\text{val}}} \sum_{j=1}^{n_{\text{val}}} \frac{\left(y^{\text{val},(j)} - \hat{y}^{\text{val},(-j)} \right)^2}{\widehat{\sigma}^2_{(-j)}} \right) \right| \quad (12)$$

- Comparison of theoretical levels of GP-based confidence intervals and observed levels
- Many other metrics can be considered for validation [DILGM22]

❑ Validation based on subsampling techniques

➤ Computation of Q^2 using **kernel herding** [FIM⁺22]

Step 4

Step 4: Identification of penalizing configurations

□ Identification of the penalizing values wrt. the QoI

- Goal: perform an uncertainty propagation with the GP surrogate model in order to compute

$$\hat{P}(\mathbf{X}_{\text{pen}}) = \mathcal{P}(Y_{\text{GP}}(\mathbf{X}_{\text{exp}}, \mathbf{X}_{\text{SII}}) > \hat{q}_\alpha(Y) \mid \mathbf{X}_{\text{pen}} = \mathbf{x}_{\text{pen}}) \quad (13a)$$

$$= \dots (\text{more details in [MIC22]}) \quad (13b)$$

$$= 1 - \int_{\tilde{\mathcal{X}}_{\text{exp}}} \Phi\left(\frac{\hat{q}_\alpha - \mu_{\hat{Y}}(\mathbf{x})}{\sigma_{\hat{Y}}(\mathbf{x})}\right) dP_{\tilde{\mathcal{X}}_{\text{exp}}}(\tilde{\mathbf{x}}_{\text{exp}}) \quad (13c)$$

where $\tilde{\mathbf{X}}_{\text{exp}} = \{\mathbf{X}_{\text{exp}} \cup \mathbf{X}_{\text{SII}}\} \setminus \mathbf{X}_{\text{pen}}$

- Assumption: $\tilde{\mathbf{X}}_{\text{exp}}$ and \mathbf{X}_{pen} are **independent**
- In practice → intensive Monte Carlo sampling to estimate this multidimensional integral

oticscream

❑ oticscream: a Python module based on OpenTURNS

- A full Python package that uses/relies on OpenTURNS
- Implements the full methodology proposed in [MIC22] but with a few more extensions!
- Available → <https://github.com/vchabri/oticscream>

Numerical illustration with 'oticscream'

❑ Let's imagine a role-playing game!

- You're an R&D engineer. Your colleague physicist gives you:
 - A Monte Carlo (i.i.d.) sample of size $n = 250$
 - A list of input variables (15 random ones vs. 5 scenario parameters)
 - A target risk measure for its studies: $q_{0.90}(Y)$

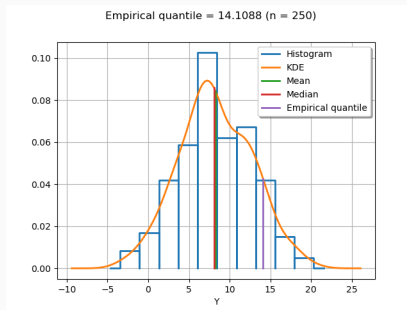


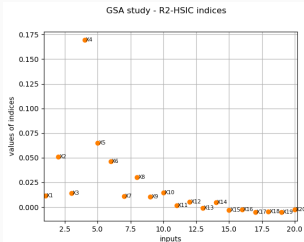
Figure 3: Empirical distribution of the output.

❑ Step 1:

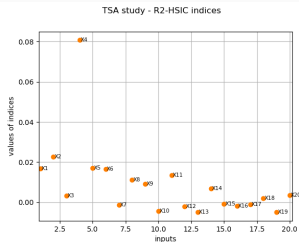
- Estimate the QoI: $\hat{q}_{0.90}(Y) \approx 14.11$

Numerical illustration with 'oticscream'

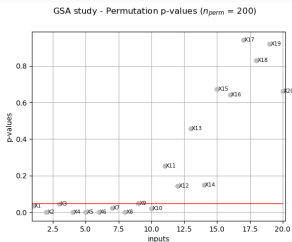
□ Step 2: perform GSA and TSA using HSIC-based indices



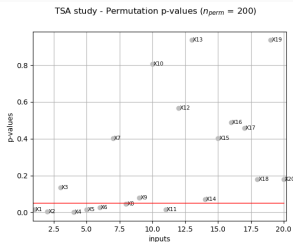
(a)



(b)



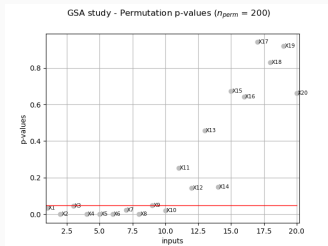
(c)



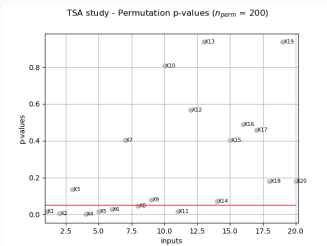
(d)

Numerical illustration with 'oticscream'

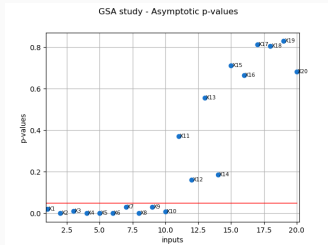
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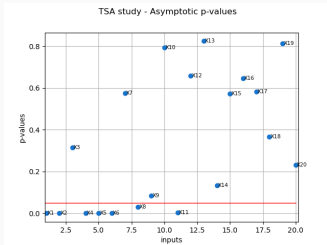
(e)



(f)



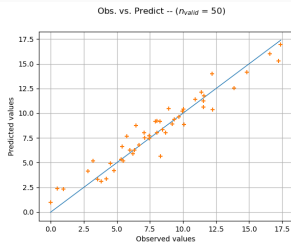
(g)



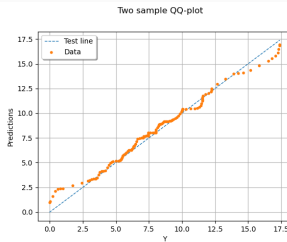
(h)

Numerical illustration with 'otiscream'

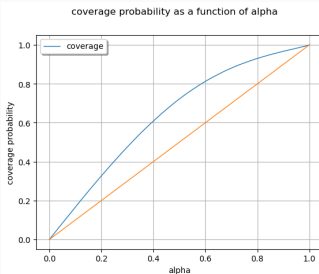
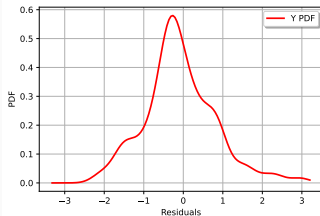
□ Step 3: you build the GP metamodel and validate it



(i)

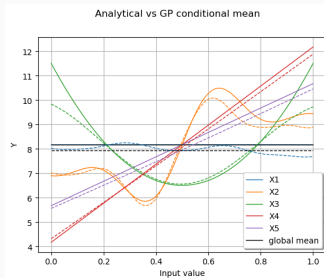


(j)

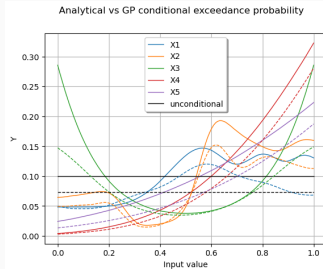


Numerical illustration with 'oticscream'

□ Step 4: use the conditional GP metamodel



(m)



(n)

Conclusion

□ Summary

- Main goal: find penalizing configurations for some scenario parameters
- ICSCREAM: a four-step methodology
- Uses both state-of-the-art UQ techniques and more refined tools
→ Talk by M. Keller and F. Delcoigne (JU-OT 2025)

□ Limitations and perspectives

- This is a first attempt to “automate” a recipe for finding penalizing values in a **given-data** context!
- **However**, in practice, it is difficult to provide global guarantees
→ every step needs to be carefully controlled in practice
- About GSA / TSA using HSIC:
 - Use advanced multiple-testing strategies for robust selection
 - Add and use HSIC-ANOVA indices more adapted to ranking purposes!
- About metamodel training and validation:
 - Gu’s robust approaches for parameter estimation in GP regression [GWB18]
 - Take benefit from the large panel of validation metrics [DILGM22]
 - Work on kernel-herding-based validation metrics
- Enhance the testing and documentation of the Python module!
- Publish it on PyPI!

Thank you for your attention!
Any question?



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