

```
In [3]: import numpy as np
import matplotlib.pyplot as plt
from scipy.stats import norm
```

Homework 1

Problem 1

1. Using neural activity to predict monkey movements

a. Imagine that you are recording a neuron inside the monkey motor cortex. You suspect that activity of this neuron reflects whether the monkey's hand is open or closed. Every 20 ms, the neuron either fires an action potential (called a spike) or it does not.

Let us assume the following probabilities:

$$p(\text{hand open}) = 0.5$$

$$p(\text{spike}|\text{hand open}) = 0.6$$

$$p(\text{spike}|\text{hand close}) = 0.35$$

You observe a series of 10 spikes spaced evenly over the course of 200 ms. What is the probability that the hand is open, given the data?

Answer

The probability that the hand is open is

$$p(\text{open}|10 \text{ spikes}) = \frac{p(10 \text{ spikes}|\text{open})p(\text{open})}{p(10 \text{ spikes})}$$

and also

$$p(10 \text{ spikes}) = p(10 \text{ spikes}|\text{open})p(\text{open}) + p(10 \text{ spikes}|\text{closed})p(\text{closed})$$

```
In [7]: pOpen = 0.5
pClosed = 1 - pOpen

p1Open = 0.6
p1Closed = 0.35

p10Open = p1Open ** 10
p10Closed = p1Closed ** 10

p10 = p10Open * pOpen + p10Closed * pClosed

pOpen10 = p10Open*pOpen/p10

print(f'The probability of the hand being open, given 10 spikes is {pOpen10:.4f}')
```

The probability of the hand being open, given 10 spikes is 0.9955

b. What is the probability for (a) if $p(\text{open}) = 0.05$?

Answer

```
In [9]: pOpen = 0.05
p10 = p10Open * pOpen + p10Closed * pClosed
pOpen10 = p10Open*pOpen/p10
print(f'The probability of the hand being open, given 10 spikes')
print(f'and a prior probability of open of 0.05')
print(f'is {pOpen10:.4f}')
```

The probability of the hand being open, given 10 spikes
and a prior probability of open of 0.05
is 0.9564

c. What would be the probability if you had observed only 5 spikes in the same 200 ms?

Answer

```
In [10]: pOpen = 0.5
p5Open = p10Open**5*(1-p10Open)**5
p5Closed = p10Closed**5*(1-p10Closed)**5
p5 = p5Open*pOpen + p5Closed*pClosed
pOpen5 = p5Open*pOpen / p5

print(f'The probability of the hand being open, given 5 spikes')
print(f'is {pOpen5:.4f}')
```

The probability of the hand being open, given 5 spikes
is 0.5665

Problem 2

In the lecture we saw equations that allow us to calculate the posterior distribution of the mean if the prior distribution is normal and the likelihood is normal as well. It is also possible to use a method called grid estimation. To do grid estimation, we select points μ_k for $k = 1, \dots, K$. For each point μ_k , we calculate a value proportional to the posterior distribution through simple multiplication using the formula:

$$p(\mu_k | x_i, \sigma_x) \propto p(x_i | \mu_k, \sigma_x) p(\mu_k) \quad (1)$$

Let's call this multiplication $q(\mu_k) = p(\{x_i\} | \mu_k, \sigma_x) p(\mu_k)$. We can normalize to approximate the posterior by dividing by the total:

$$p(\mu_k | \{x_i\}, \sigma_x) = \frac{q(\mu_k)}{\sum_k q(\mu_k)} \quad (2)$$

Usually, this approach yields an accurate picture of the posterior distribution with only 100 points and certainly provides accuracy with 500.

a. Use this approach to solve again the exercise at the end of the lecture, but this time using a grid approximation. All numbers are in Newtons: Your prior about the box is $\mu_0 = 3.5$ with confidence $\sigma_0 = 1$.

Your confidence in your perception is $\sigma_x = 1$.

Your lift the box multiple times and perceive the weight to be 6, 6, 7, 7, 4 and 5.

Plot the posterior of distribution of the weight after each lift on a grid of 500 points between 0 and 10.

Answer

Set up the constants and the underlying grid

```
In [52]: mu_0 = 3.5
sigma_0 = 1
sigma_x = 1
x = [6, 6, 7, 7, 4, 5]
mu_k = np.arange(start=0, stop=10, step=10/500)
```

Now we can generate the prior

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In [53]: p_mu = norm.pdf(mu_k, loc=mu_0, scale = sigma_0)
p_mu = p_mu/sum(p_mu)
```

And now loop for each posterior

```
In [54]: fig, ax = plt.subplots(nrows=len(x), figsize=(9,20),
                                sharex='all', sharey='all')
fig.patch.set_facecolor('white')

this_p_mu = p_mu # Set initial prior

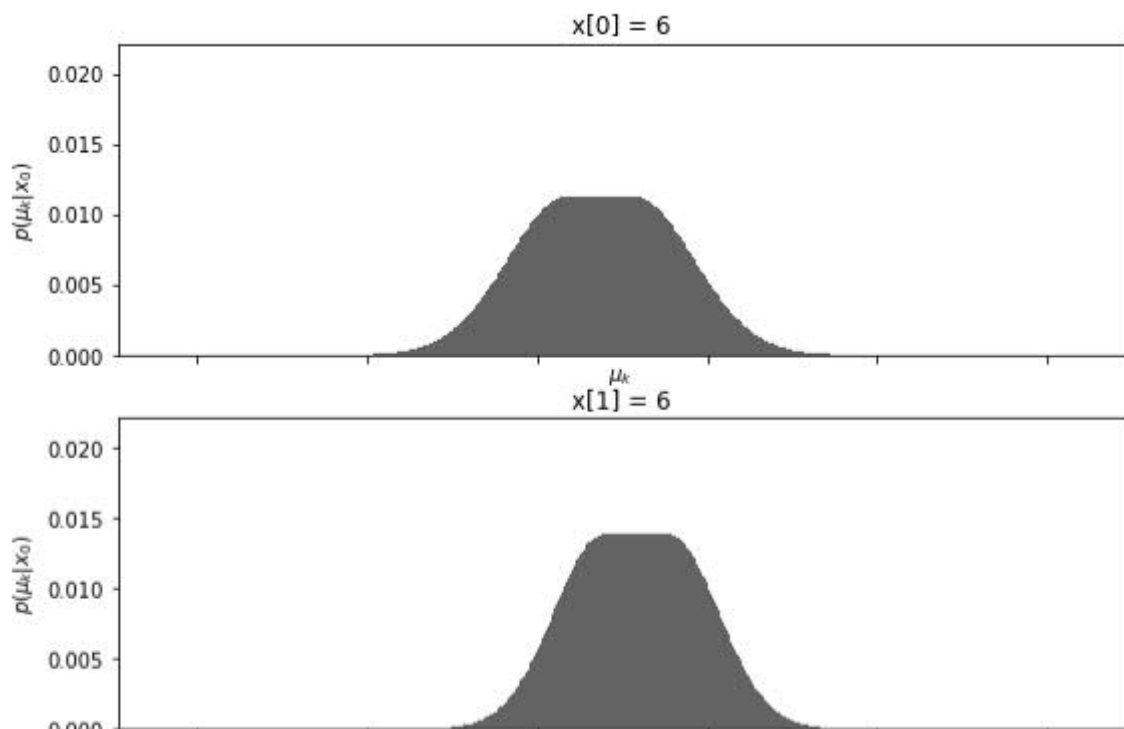
for i,x_i in enumerate(x):
    # Likelihood
    p_x_mu = norm.pdf(x_i, loc=mu_k, scale=sigma_x)

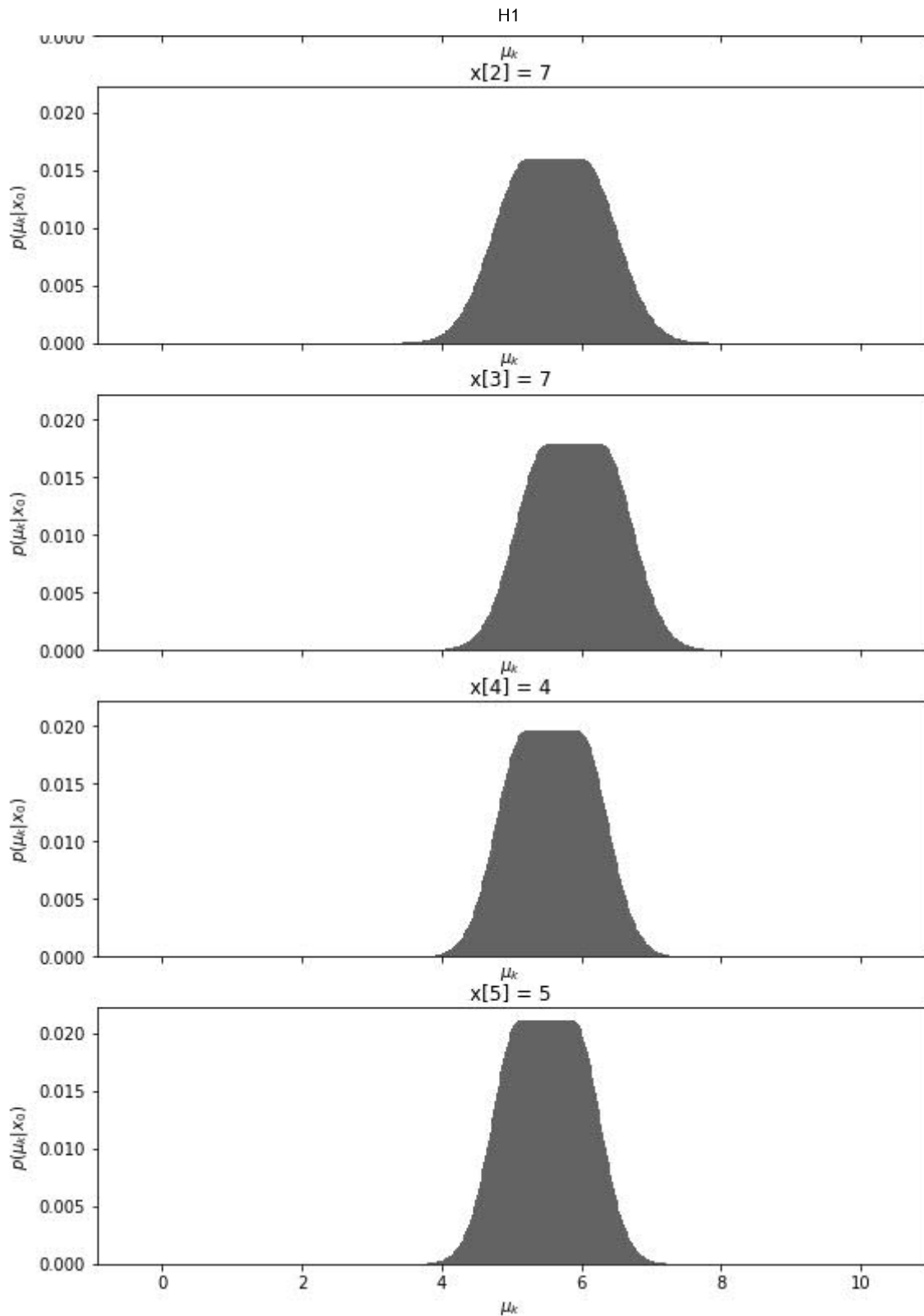
    # Unnormalized posterior
    p_mu_x = p_x_mu*this_p_mu

    # Normalized posterior
    p_mu_x = p_mu_x / sum(p_mu_x)

    ax[i].bar(mu_k, p_mu_x)
    ax[i].set_xlabel('$\mu_k$')
    ax[i].set_ylabel('$p(\mu_k | x_0)$')
    ax[i].set_title(f'$x_{i} = {x_i}$')

    # Now set the prior to the previous posterior
    this_p_mu = p_mu_x
```





b. In these experiments, subjects need to report whether the box is heavier or lighter than the reference box of 6 N. We can model this forced-choice reporting by picking an estimated weight at random from the posterior distribution and saying the box we are lifting is lighter than the reference if our number is less than 6 and heavier if it is greater than 6. What is the probability of claiming that the small box (prior for $\mu = 3.5$) is actually heavier before lifting any box and then after each lift of the box in part (a).

Answer

We can repeat the loop in the last exercise, but this time each time through the loop we will check the probability of picking a random number from the posterior that is greater than 6.

This is easy to do, all we need to do is check how much of the posterior is greater than 6.

```
In [55]: p_6 = sum(p_mu[mu_k>6])
print(f'The probability based only on the prior is {p_6:.2f}')

for i,x_i in enumerate(x):
    p_x_mu = norm.pdf(x_i, loc=mu_k, scale=sigma_x)
    p_mu_x = p_x_mu*this_p_mu
    p_mu_x = p_mu_x / sum(p_mu_x)

    p_6 = sum( p_mu_x[mu_k > 6])
    print(f'The probability after the {i+1}-th lift of {x_i} is {p_6:.2f}')

    this_p_mu = p_mu_x
```

```
The probability based only on the prior is 0.01
The probability after the 1-th lift of 6 is 0.10
The probability after the 2-th lift of 6 is 0.12
The probability after the 3-th lift of 7 is 0.21
The probability after the 4-th lift of 7 is 0.31
The probability after the 5-th lift of 4 is 0.15
The probability after the 6-th lift of 5 is 0.10
```

c. Determine whether the results in parts (a) and (b) are consistent with the graphs on slide 14 (copied below). How are the consistent or inconsistent?

Answer

They are consistent because the actual estimate of how heavy the box is and the probability of saying it is heavier goes up on subsequent lifts.

Problem 3

You are running an experiment where a participant is facing several speakers and several lights that are placed in a semicircle ($\pm 90^\circ$) around them. As the experimenter, you can manipulate the average location and noise of auditory and visual feedback by controlling which lights and speakers will turn on. On a particular trial, you turn on a few lights to light up so that it is hard to pinpoint exactly where ($\mu_v = -10.0^\circ, \sigma_v = 5^\circ$). Simultaneously, you set a few speakers to produce a tone ($\mu_a = 25.0^\circ, \sigma_a = 15^\circ$). The participant has to point towards a single location that best captures the source of the light and sound. Assuming they have no prior inclination to point in any specific direction, where do you expect them to point? If a particular subject points towards -2° , is their behavior still consistent with Bayesian estimation? Where would they need to point to convince you that their estimation process is not Bayesian?

Answer

We will treat this as a two step process of including information into prior knowledge. The prior knowledge is flat:

```
In [1]: mu_0 = 0
sigma_0 = 10000
```

Now let's add in the visual estimate:

```
In [6]: mu_v = -10
```

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sigma_v = 5

# This is just to make the equations easier to type
tau_v = 1/sigma_v**2
tau_0 = 1/sigma_0**2

mu_v1 = (tau_v*mu_v + tau_0*mu_0) / (tau_v+tau_0)
sigma_v1 = np.sqrt(1 / (tau_v + tau_0))

print(f'Including the visual input we have an estimate of {mu_v1:.1f} with an uncertainty of {sigma_v1:.1f}')

```

Including the visual input we have an estimate of -10.0 with an uncertainty of 5.00. We can see that if you have no prior information, then the estimate with the new data is just what is indicated by that data. We could have actually skipped this step and just started with incorporating the visual into the auditory information.

Now we add in the auditory information.

In [8]:

```

mu_a = 25
sigma_a = 15

tau_v1 = 1/sigma_v1**2
tau_a = 1/sigma_a**2

mu_av = (tau_v1*mu_v1 + tau_a*mu_a)/(tau_v1+tau_a)
sigma_av = np.sqrt(1/(tau_v1+tau_a))

print(f'Including both inputs, we have an estimate of {mu_av:.1f} with an uncertainty of {sigma_av:.1f}')

```

Including both inputs, we have an estimate of -6.5 with an uncertainty of 4.74. A subject who points at -2° is within the uncertainty and is thus reasonably consistent with the Bayesian estimate.

If they pointed at a point more than twice the uncertainty, that would certainly be inconsistent with Bayesian estimate. That is, anywhere to the left of $\mu_{av} - 2\sigma_{av}$ or to the right of $\mu_{av} + 2\sigma_{av}$.

In [11]:

```

print(f'Estimates to the right of {mu_av-2*sigma_av:.1f} or the left of {mu_av+2*sigma_av:.1f} are not Bayesian estimates')

```

Estimates to the right of -16.0 or the left of 3.0 are not Bayesian estimates