



## Console

```
[novice_accelerometer] x=-0.00 y=0.01 z=9.78  
[novice_accelerometer] a=9.78 i=0.04 o=0.00  
[novice_accelerometer] x=-0.00 y=0.01 z=9.78  
[novice_accelerometer] a=9.78 i=0.04 o=0.00  
[novice_accelerometer] x=-0.00 y=0.01 z=9.79  
[novice_accelerometer] a=9.79 i=0.04 o=0.00  
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```

