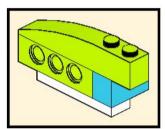
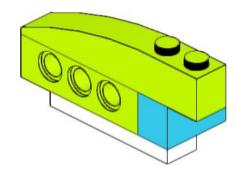
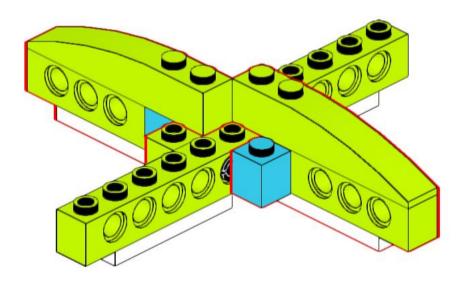
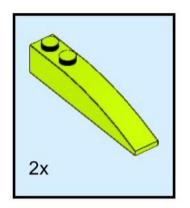


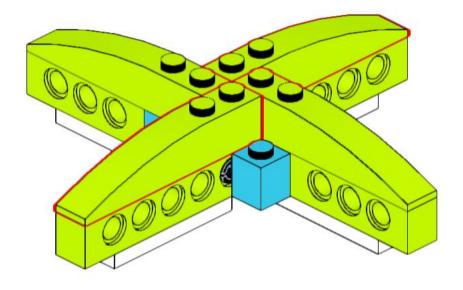
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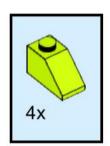


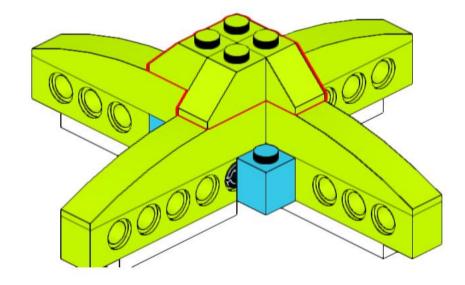


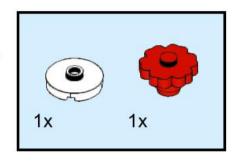


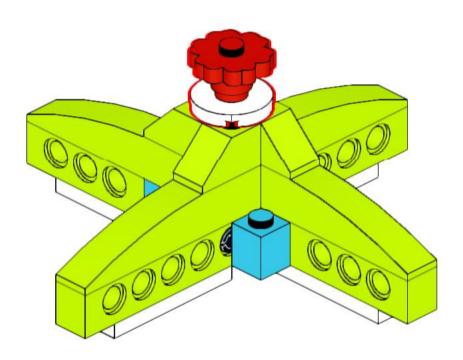


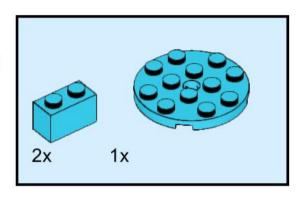


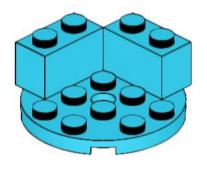


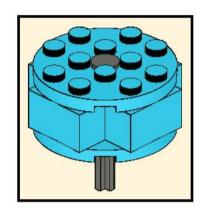


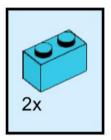


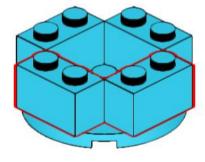


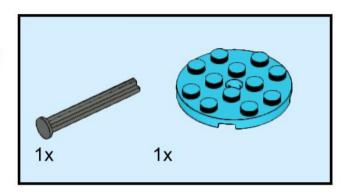


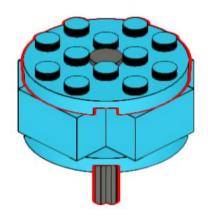


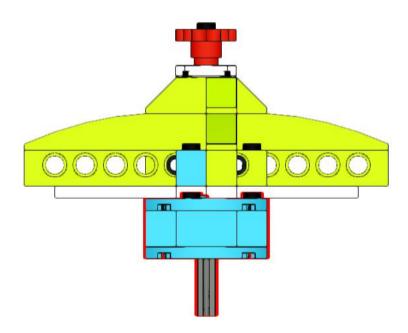


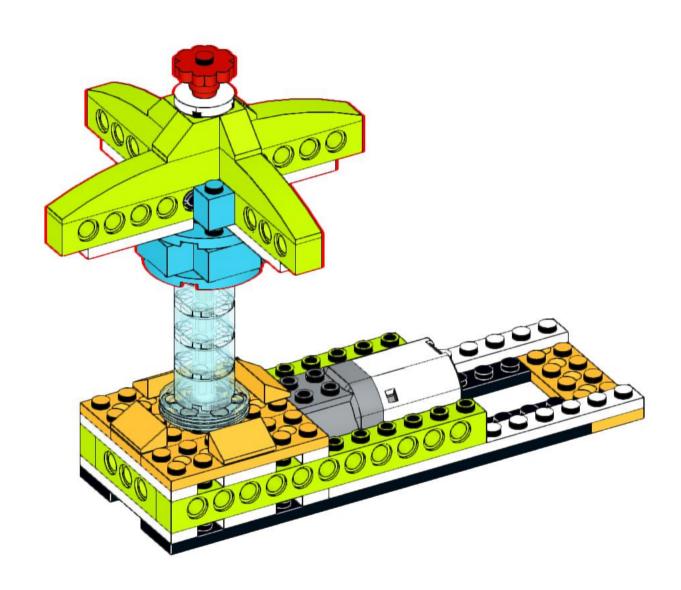


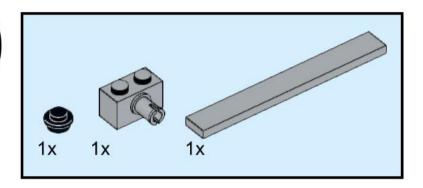


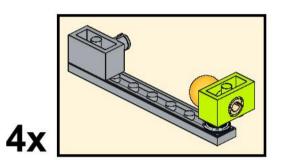


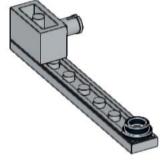


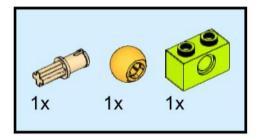


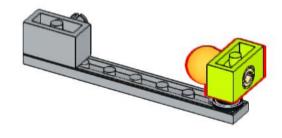


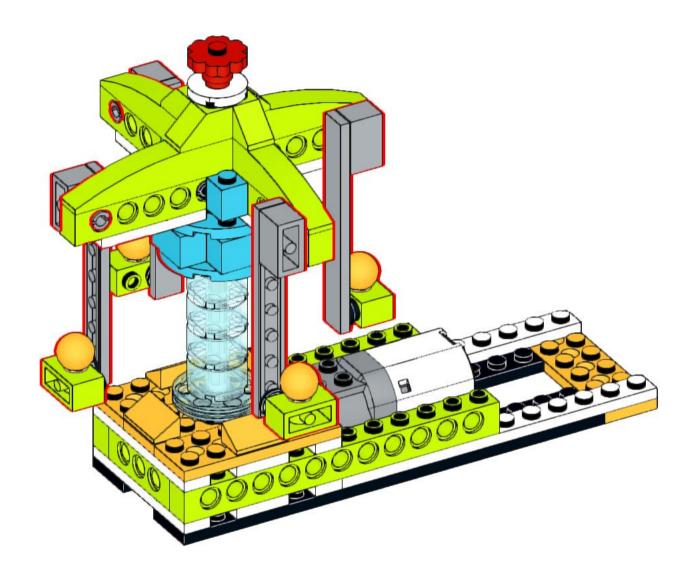


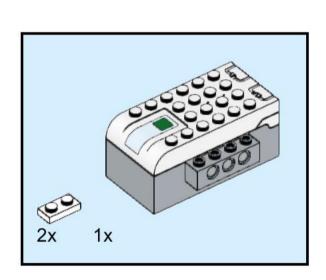


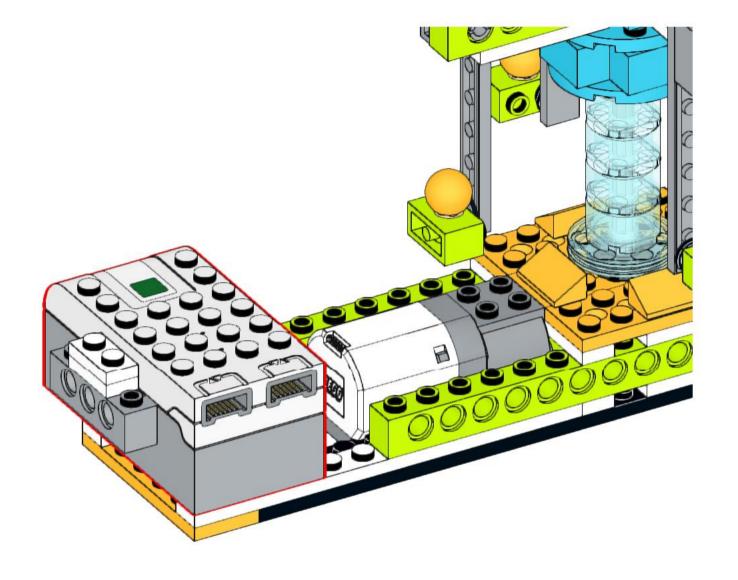


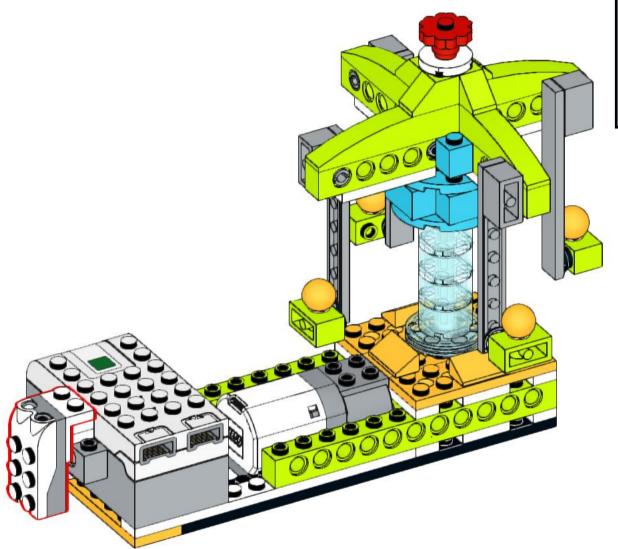


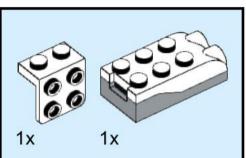












Crea un programa que permita controlar la velocidad del carrusel con un sensor de distancia. Cuanto más cerca del sensor coloque el dedo, más rápido girará el carrusel.

Para controlar la potencia del motor, utiliza el sensor de distancia. Sus lecturas toman el valor de 0 a 10; cuanto menor es la distancia desde un obstáculo, menor es el número presentado por el sensor.

La potencia máxima del motor debe lograrse acercando su mano al sensor. Para crear esta dependencia, puede usar una operación matemática simple.

# Tecnoaprendo





# Tecnoaprendo































