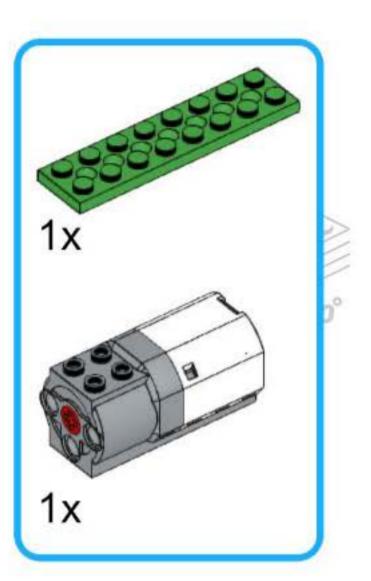
## mech walker robot unofficial building instruction

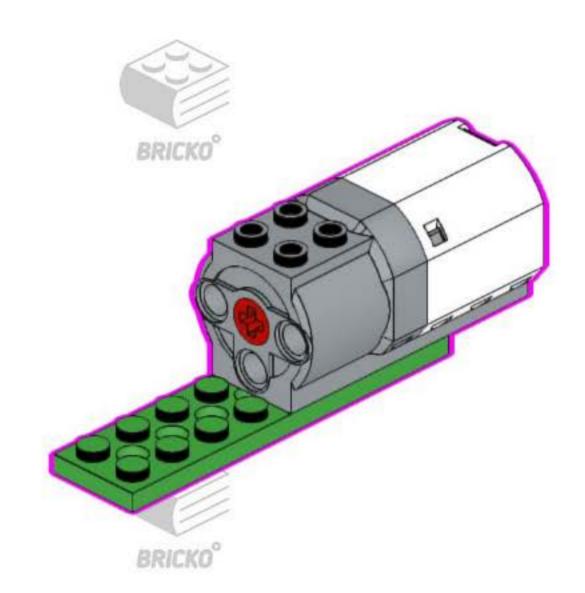


## Mech Walker

for Lego® WeDo 2.0 45300

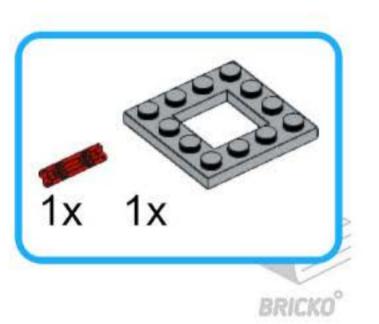




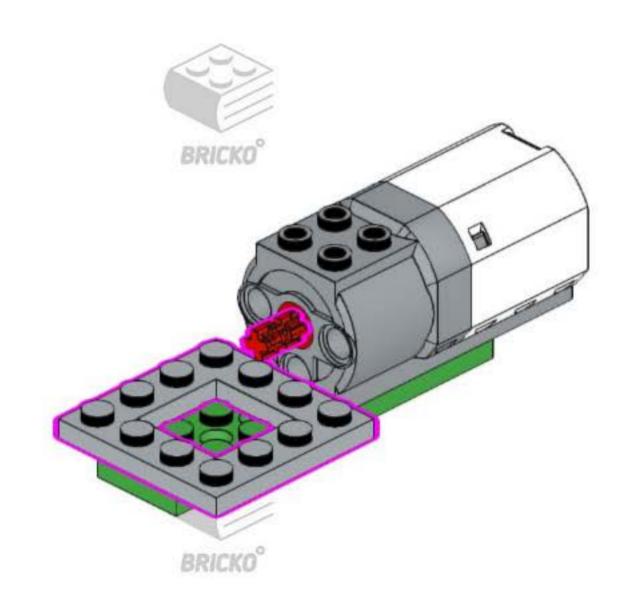






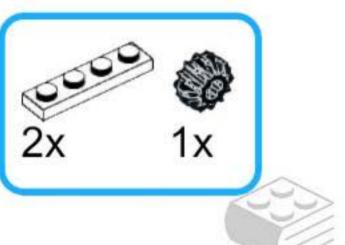




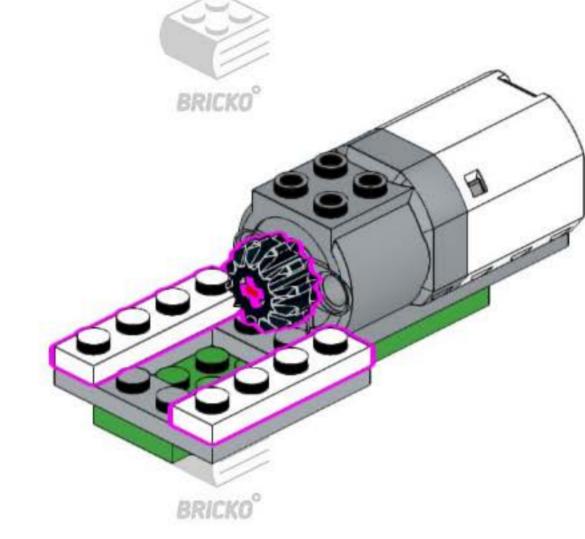








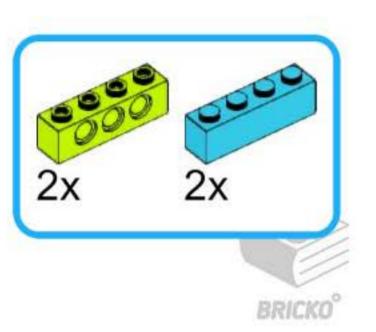




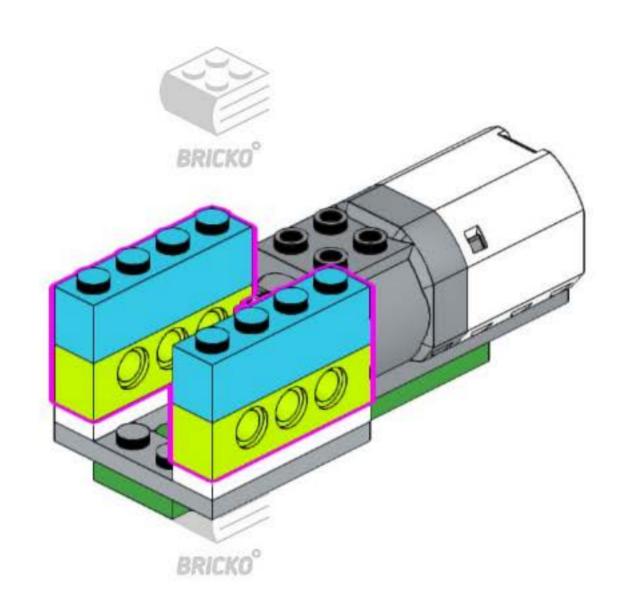






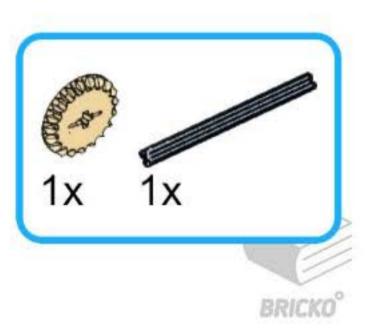




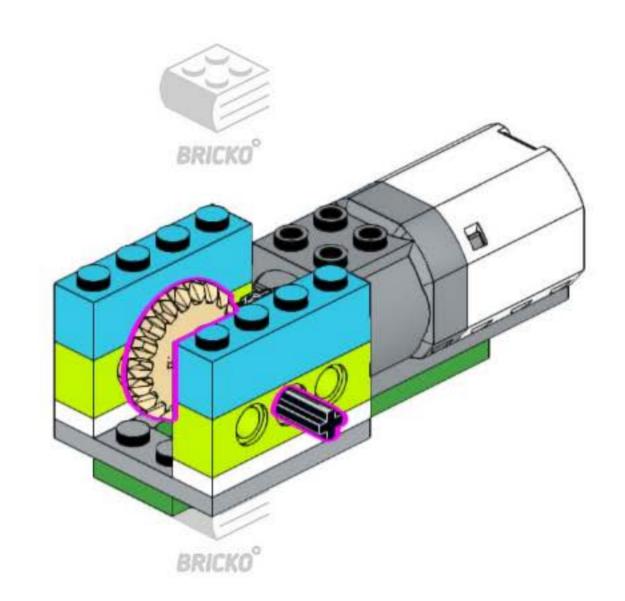






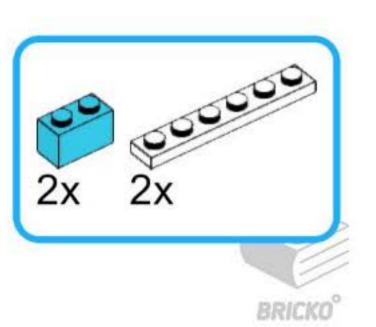




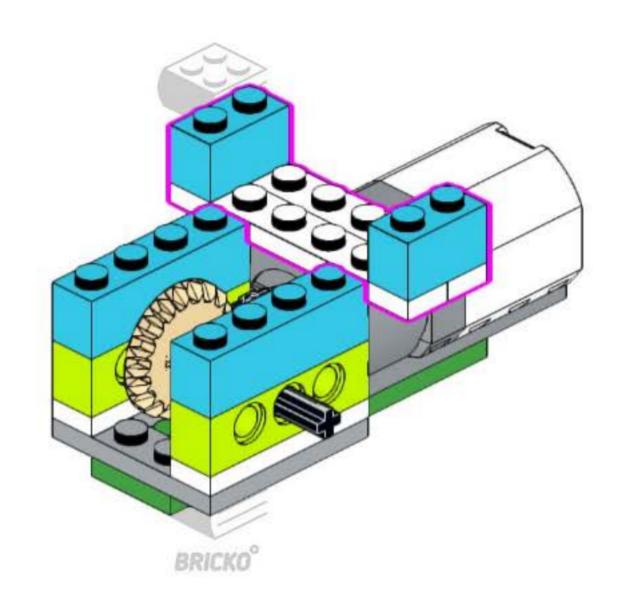






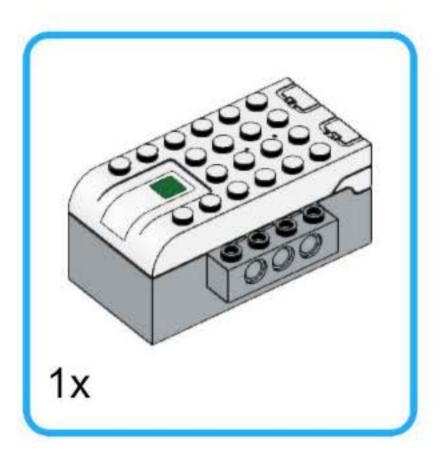




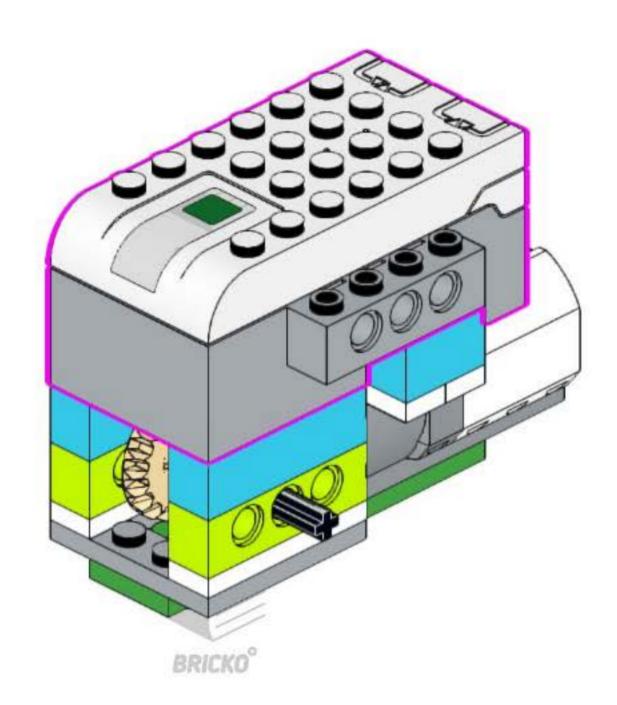






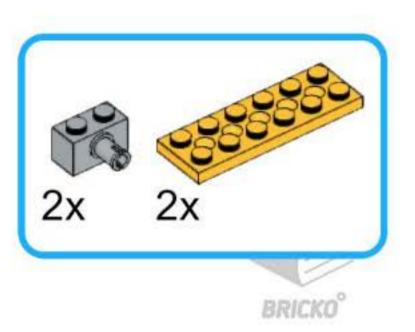




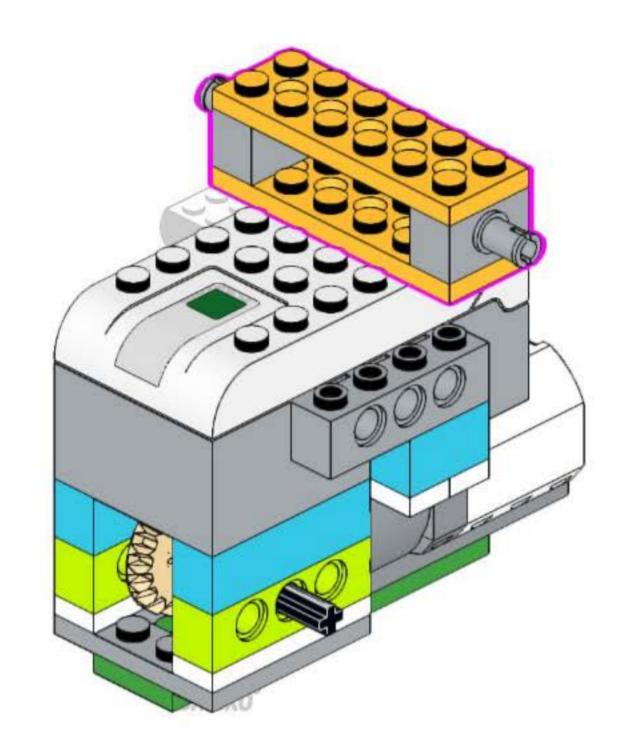






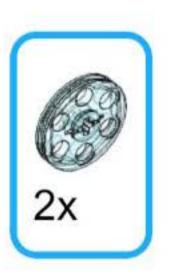






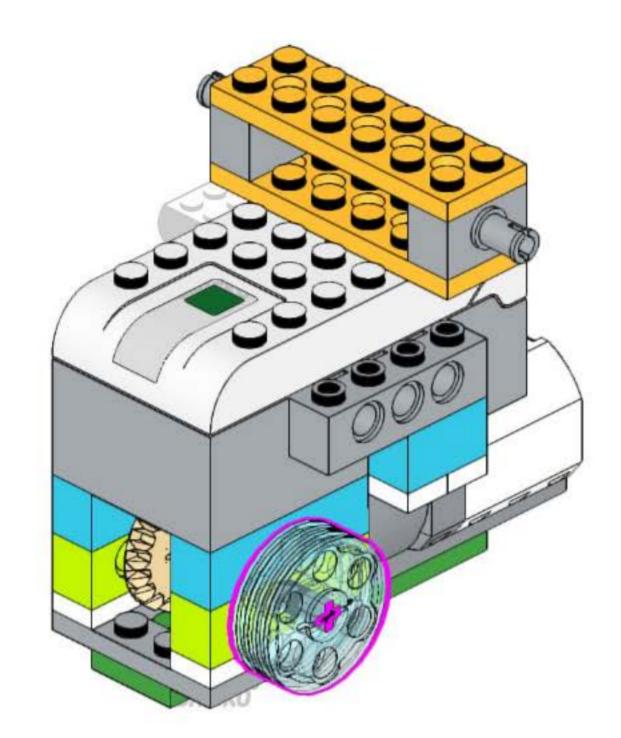






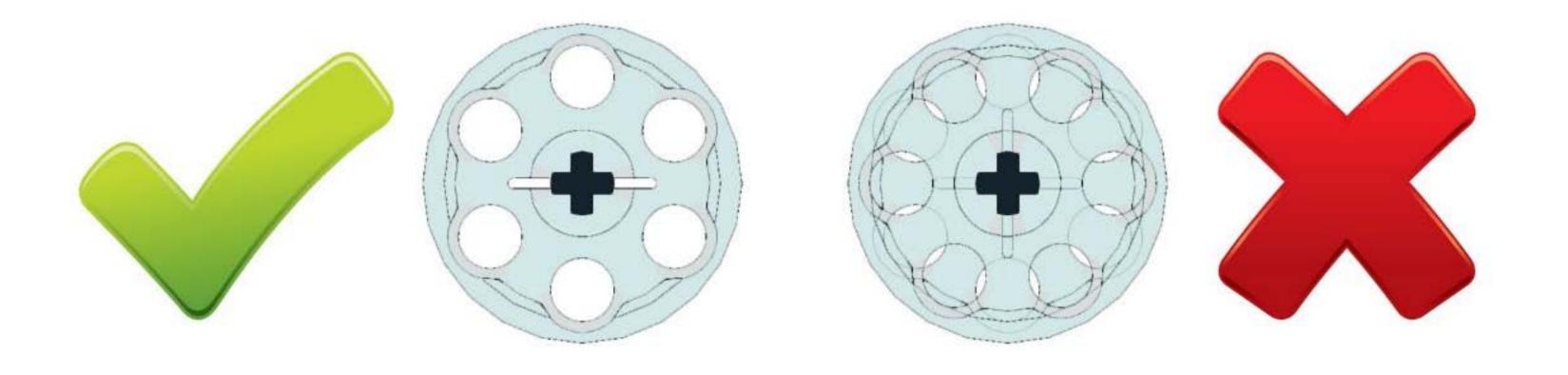


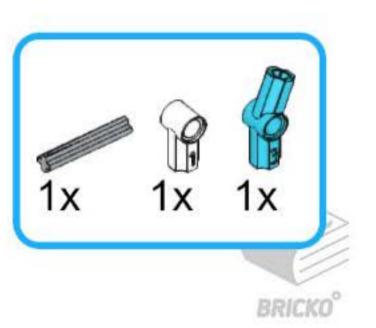






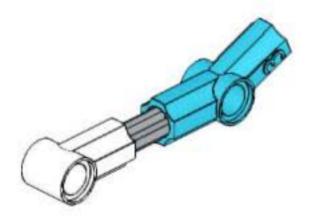








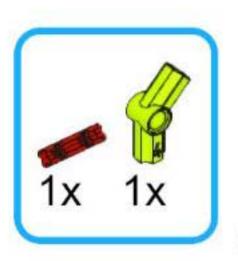




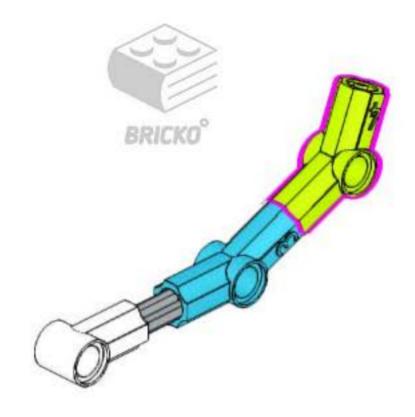














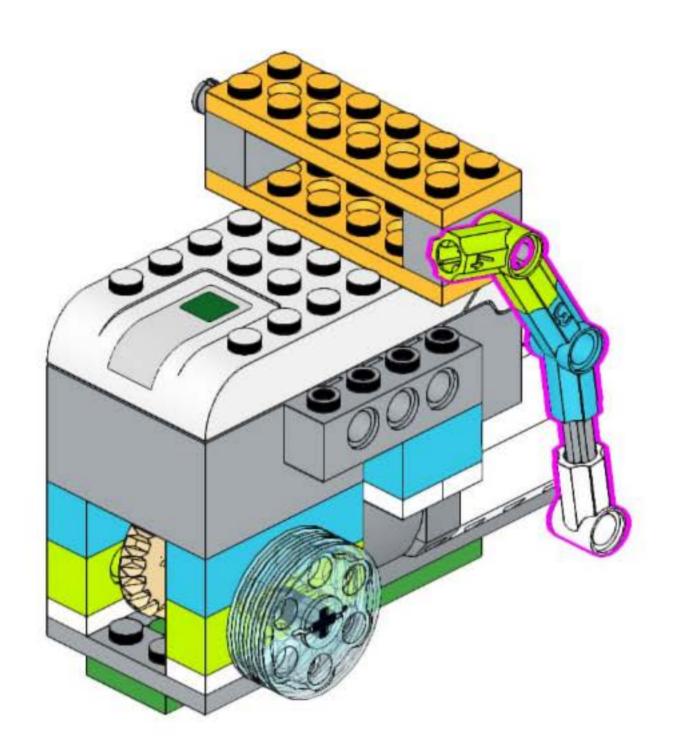






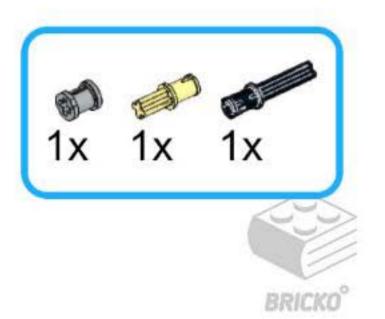




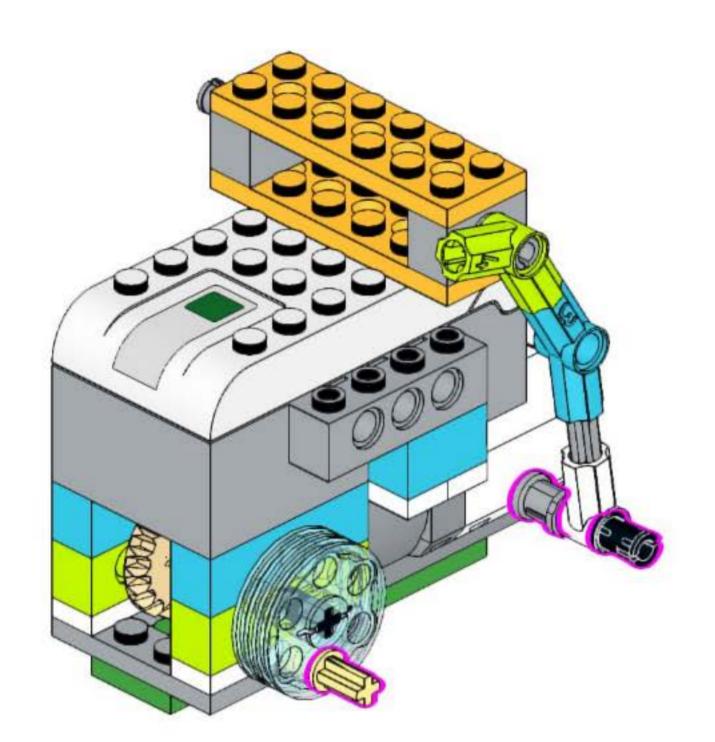






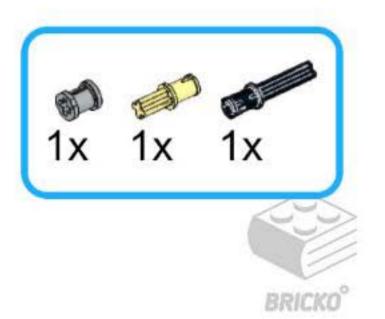




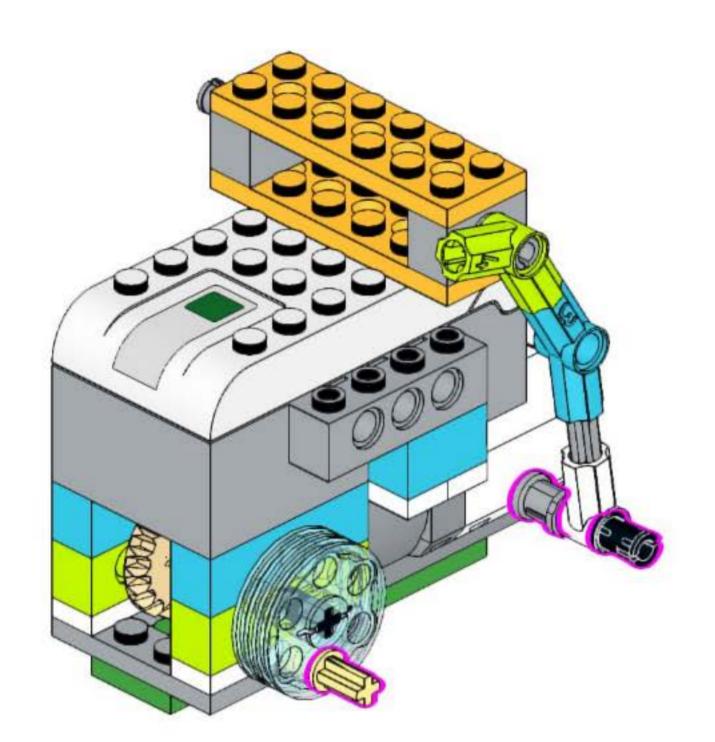






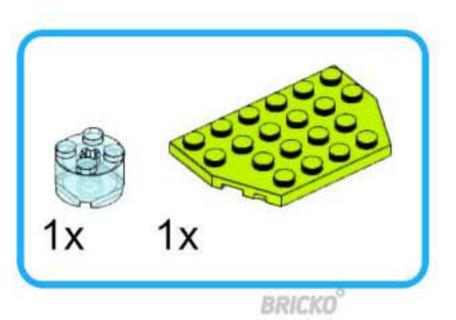






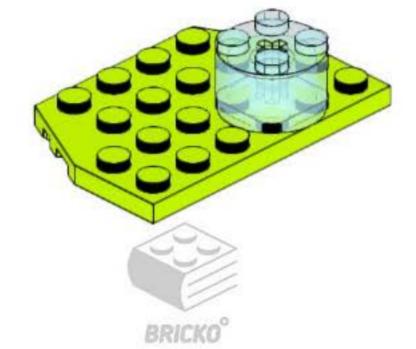






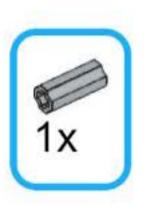




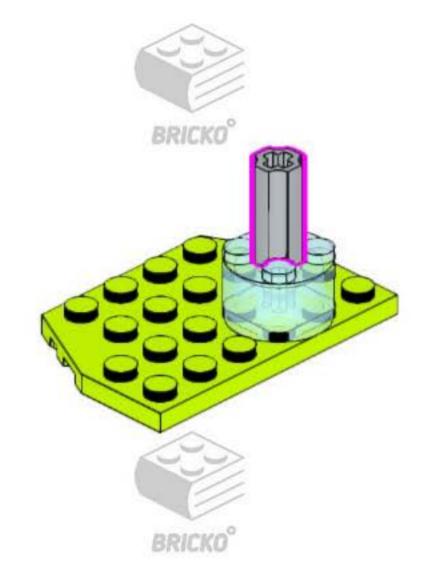










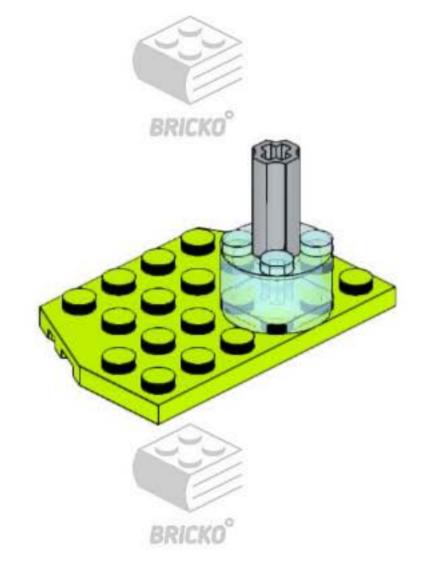








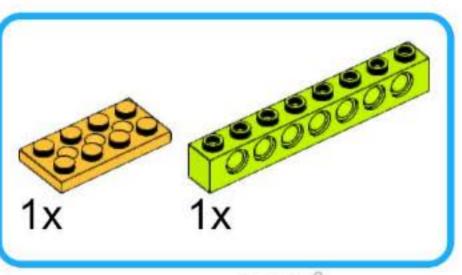








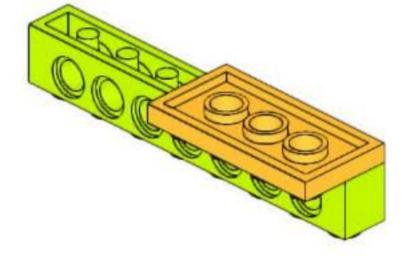








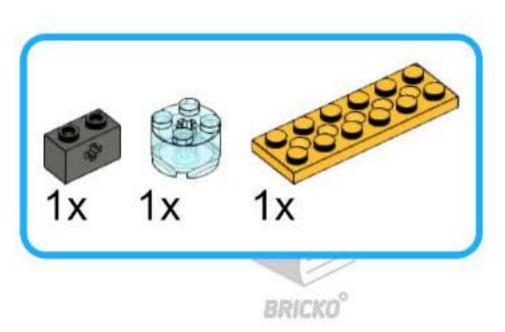






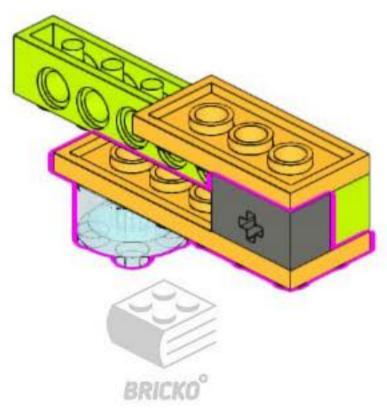










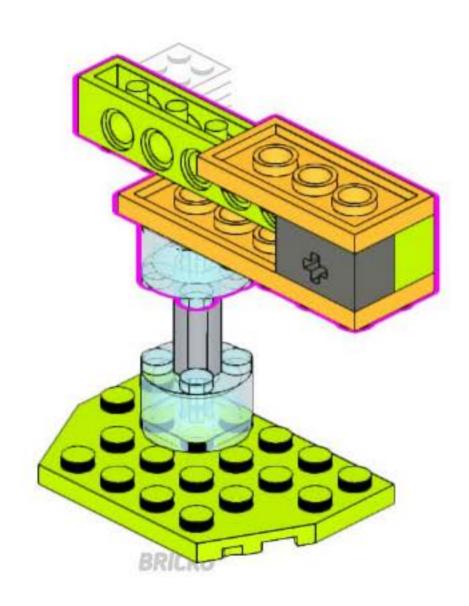










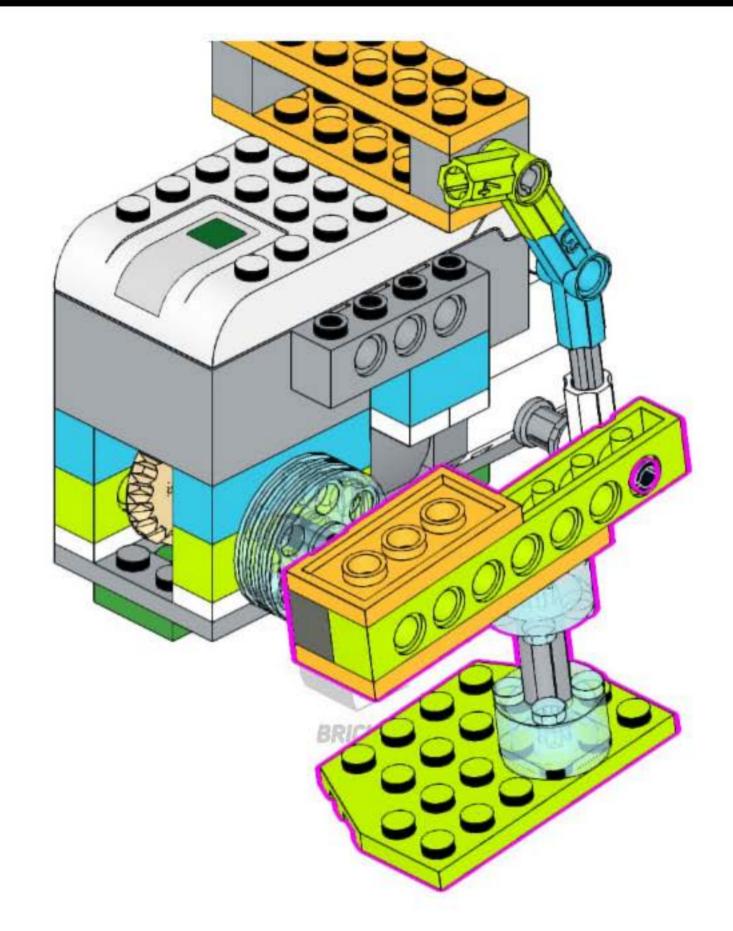










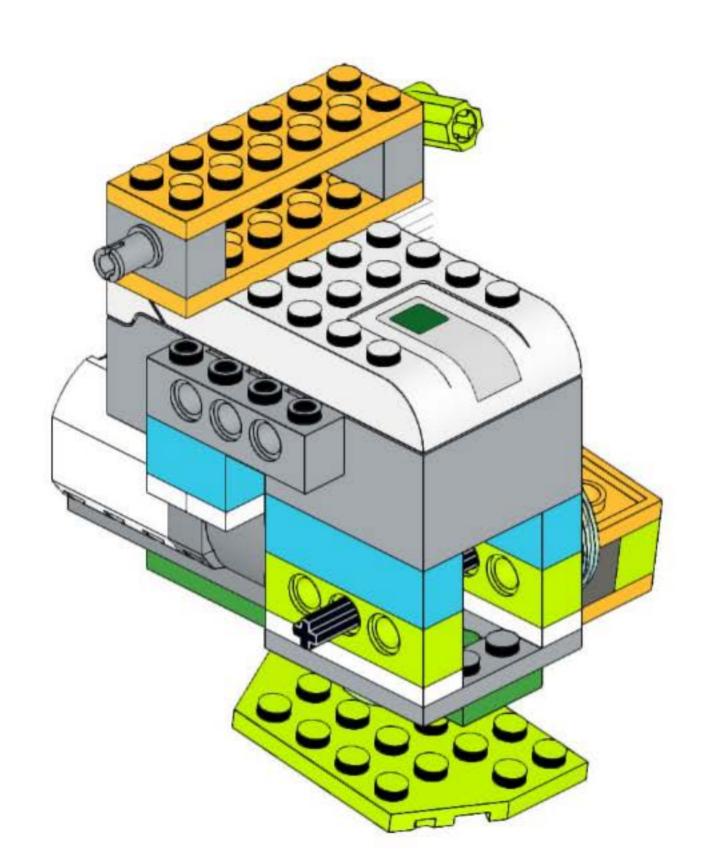










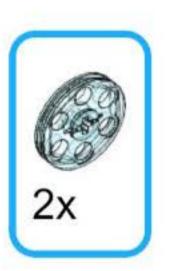




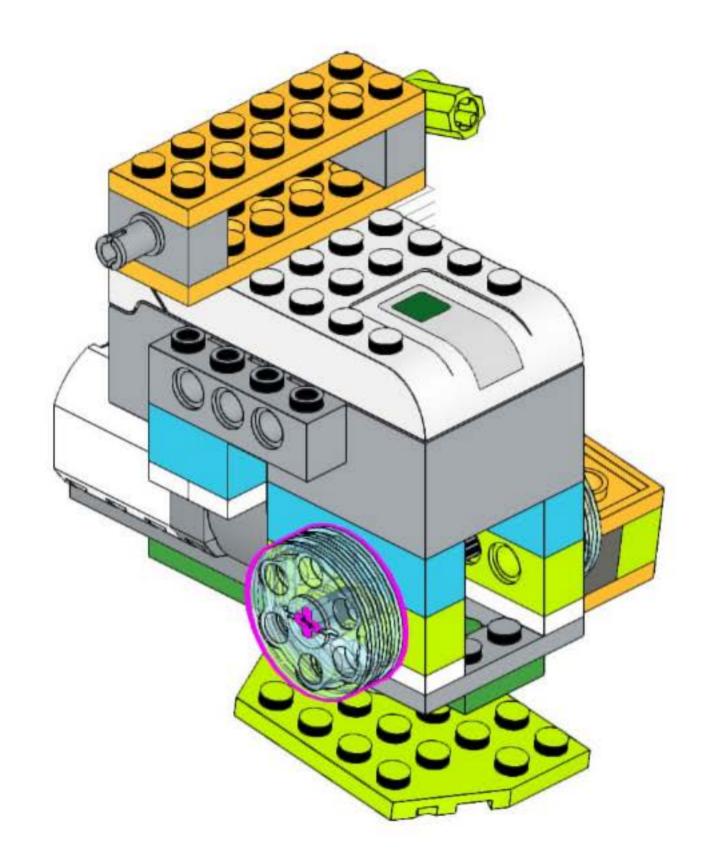
BRICKO°







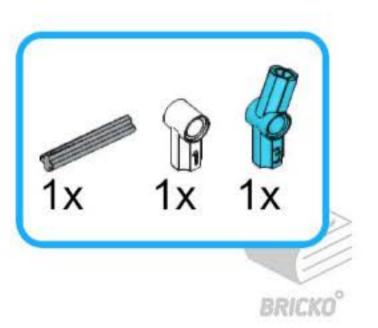






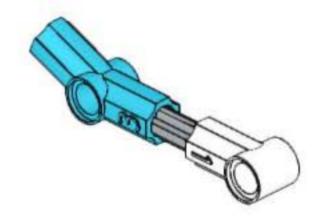








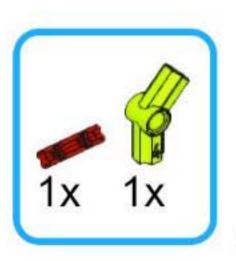




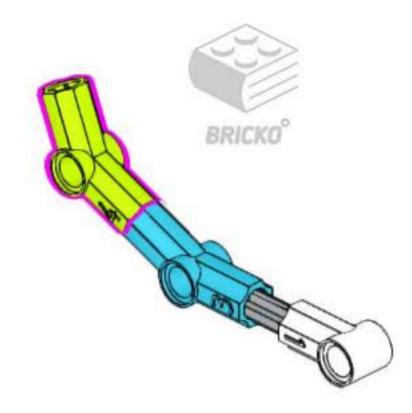














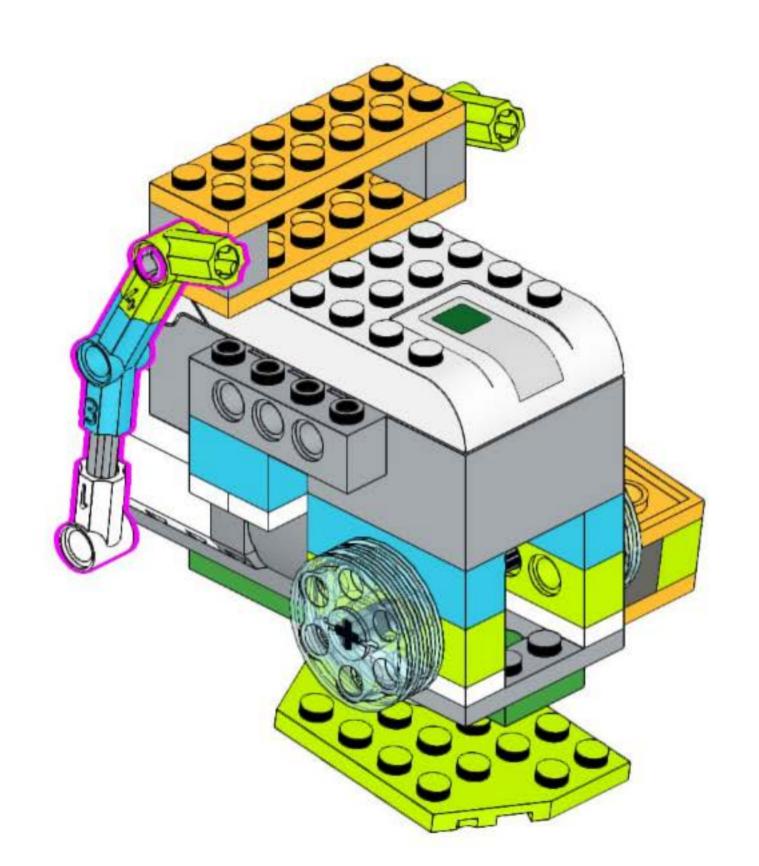






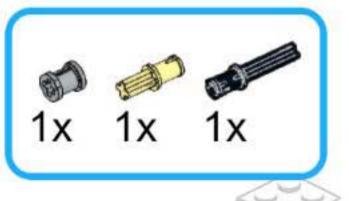




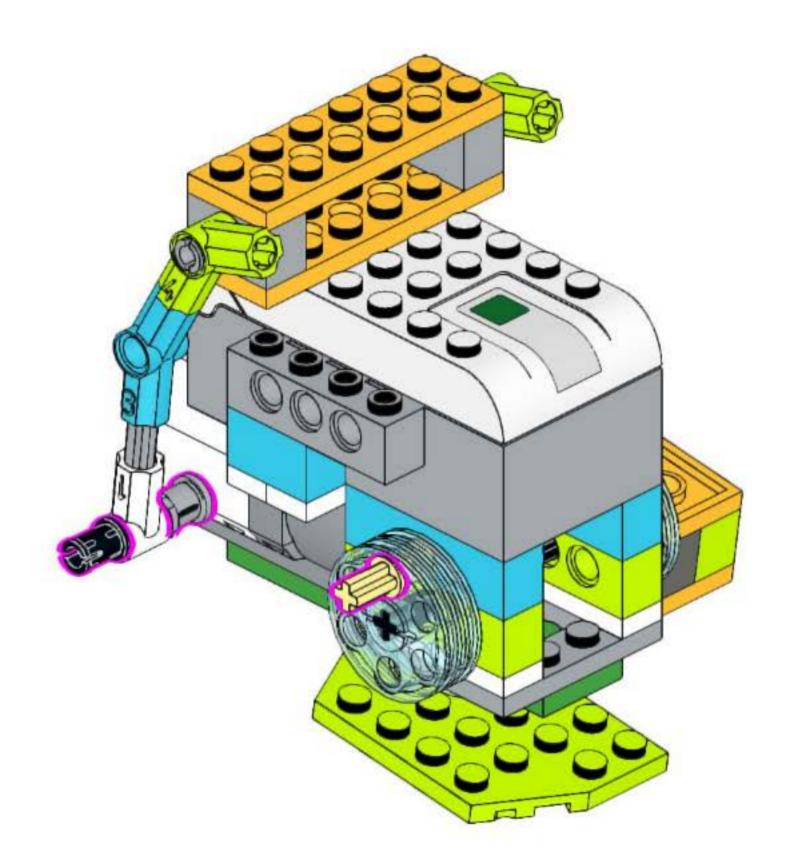








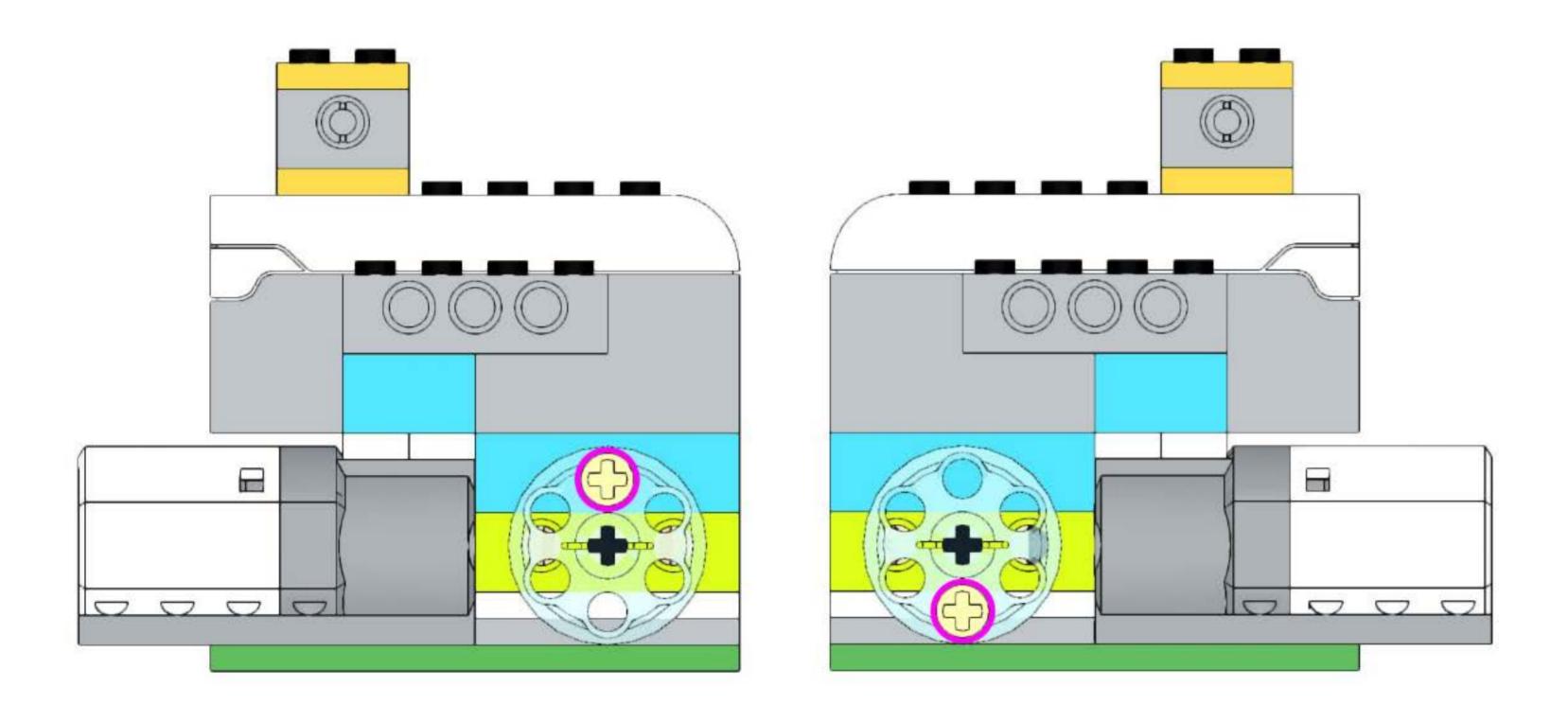




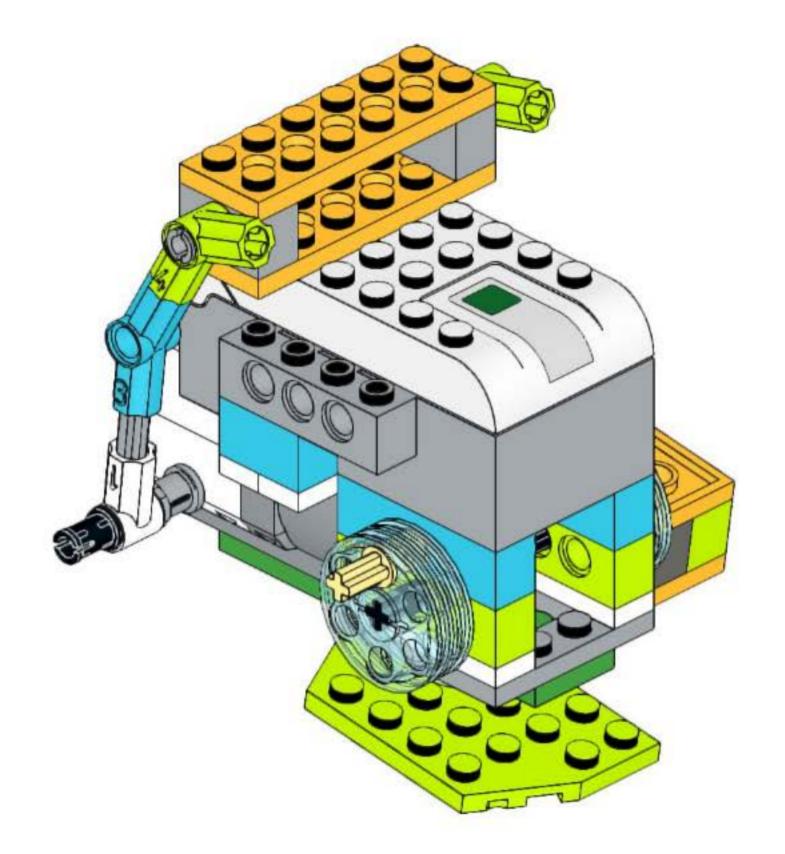








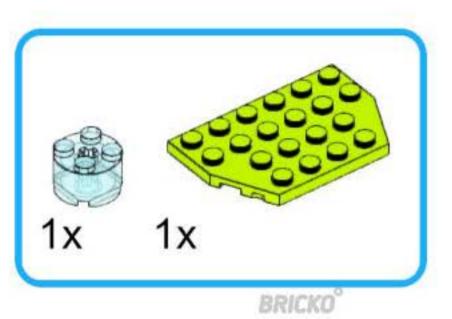






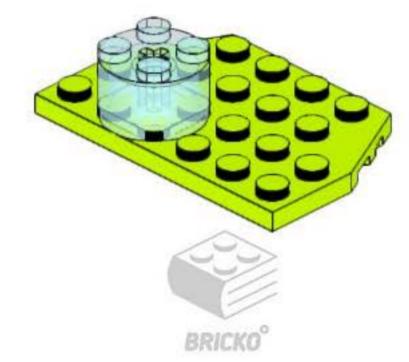






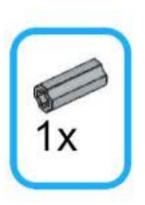




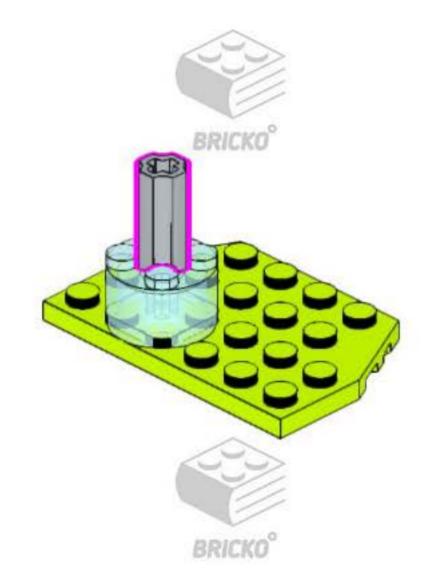








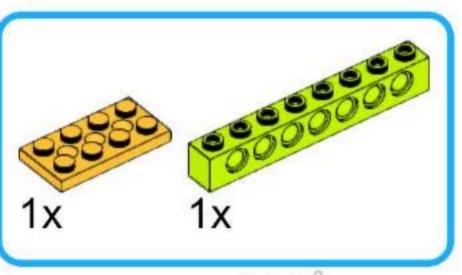








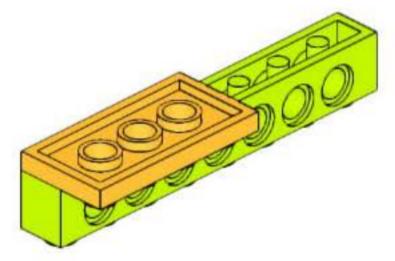








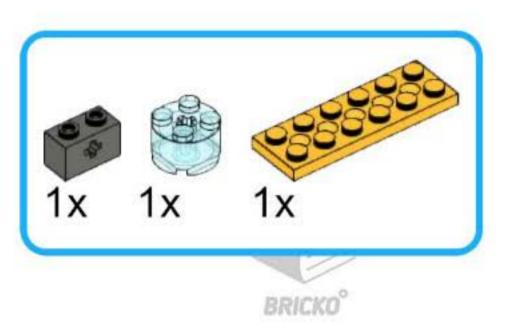






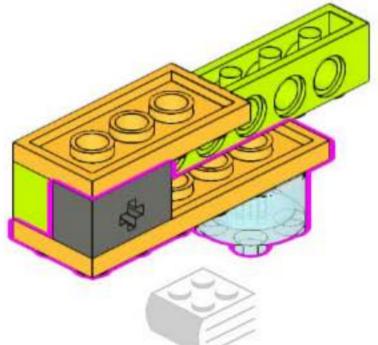












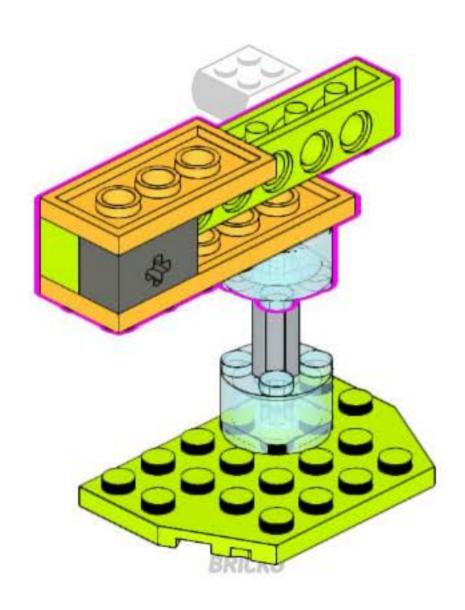
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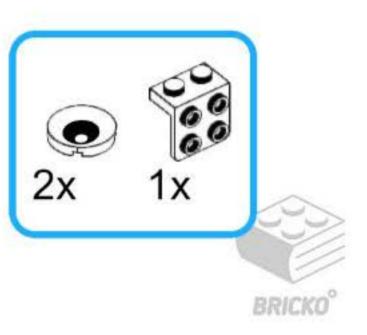


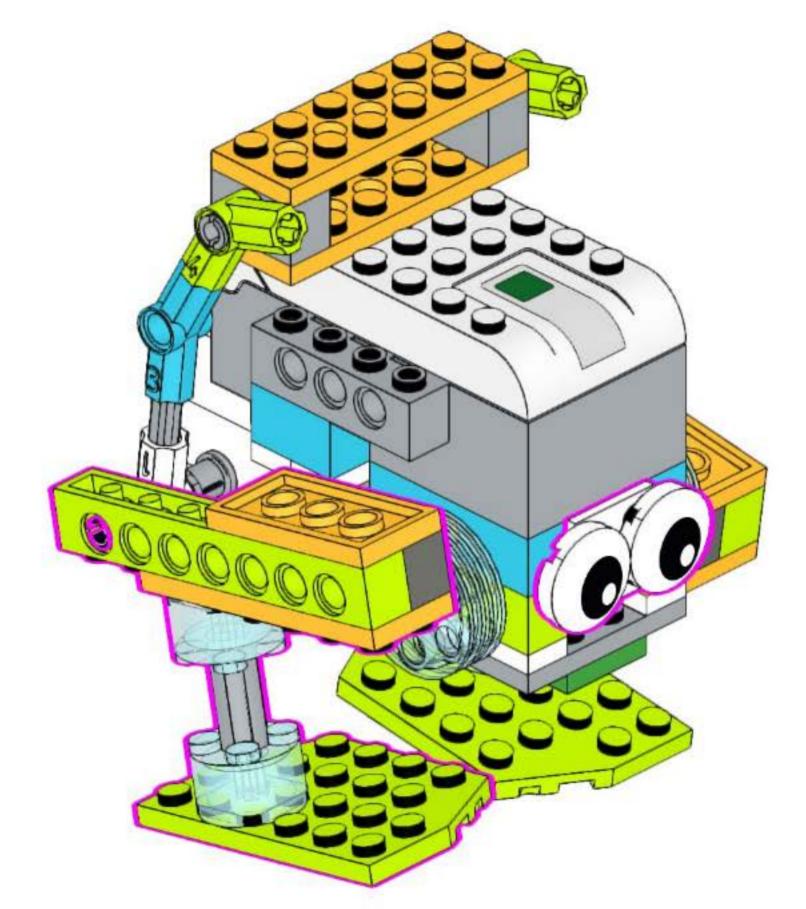












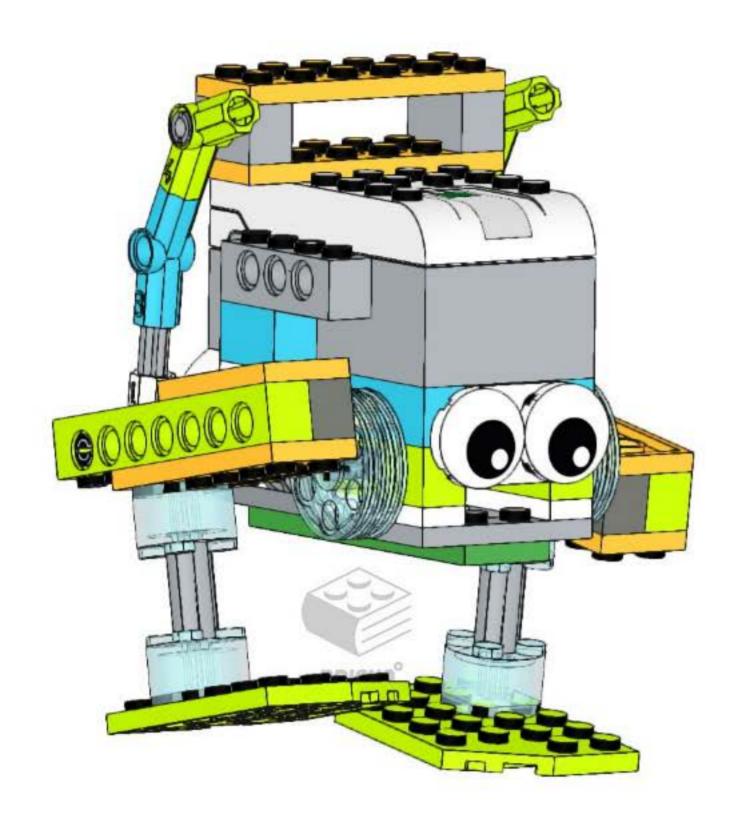
















#### Task 1

Make a program of the robot's movement with the lowest speed.

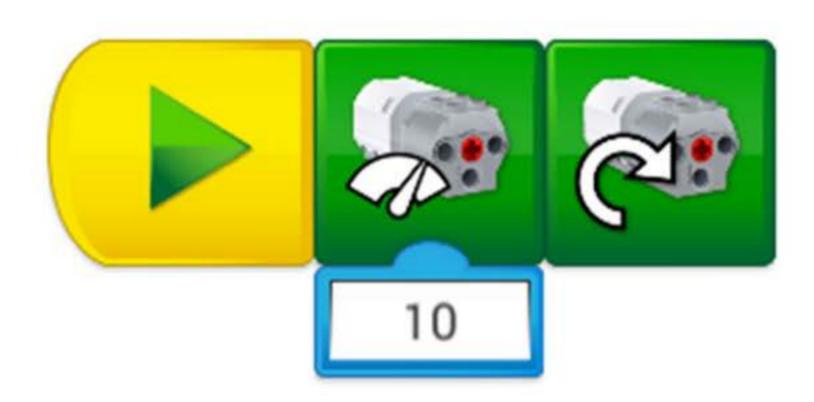
Is the robot moving?



#### Task 2

Make a program of the robot's movement with the highest speed.

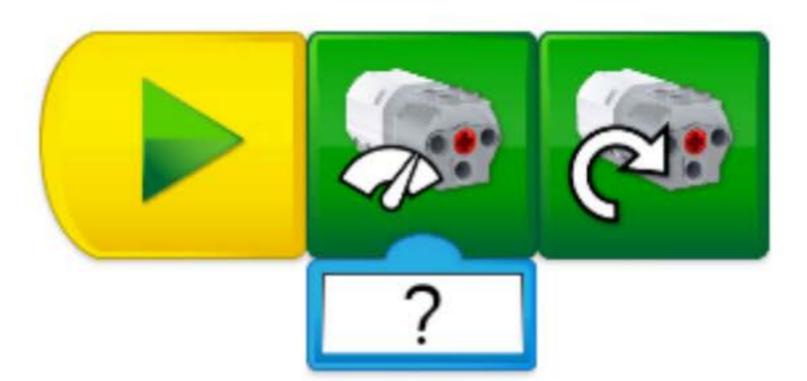
The robot doesn't break down?



## Task 3



Create a program for the robot's movement at the optimal speed. As quickly as possible, but so that it does not break. What is the speed of your robot?





# Task \*4

Make a program that moves the robot at a speed of 3 forward for 5 seconds, after which it stops.



## Task \*5

Make a program that moves the robot at a speed of 3 forward for 5 seconds, then 5 seconds back, after which everything repeats endlessly.



