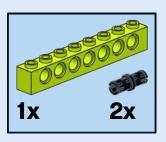


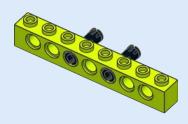
# RC Sumo Bot

Daniele Benedettelli - 2018

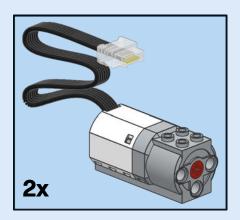
Build it with two WeDo 2.0 sets #45300

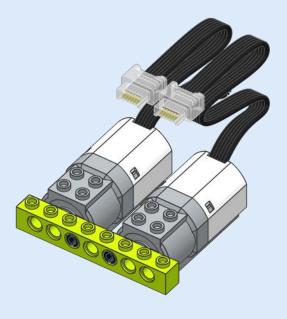


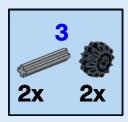


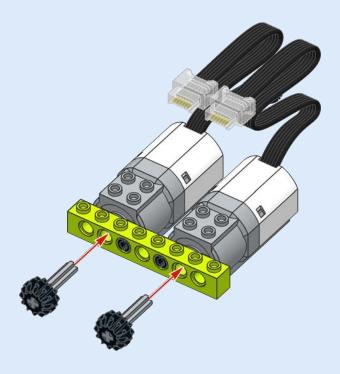


You can build in pairs.
The remote starts at step 21.

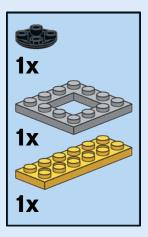


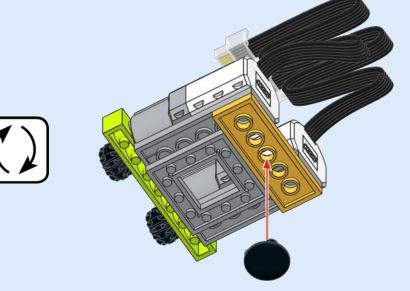




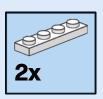


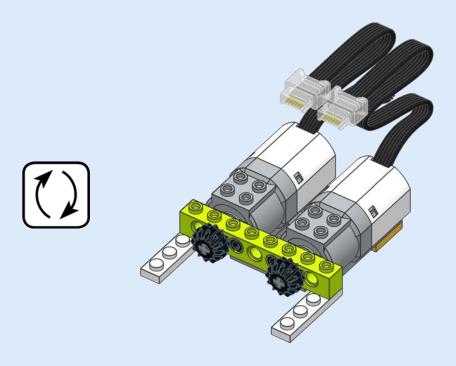


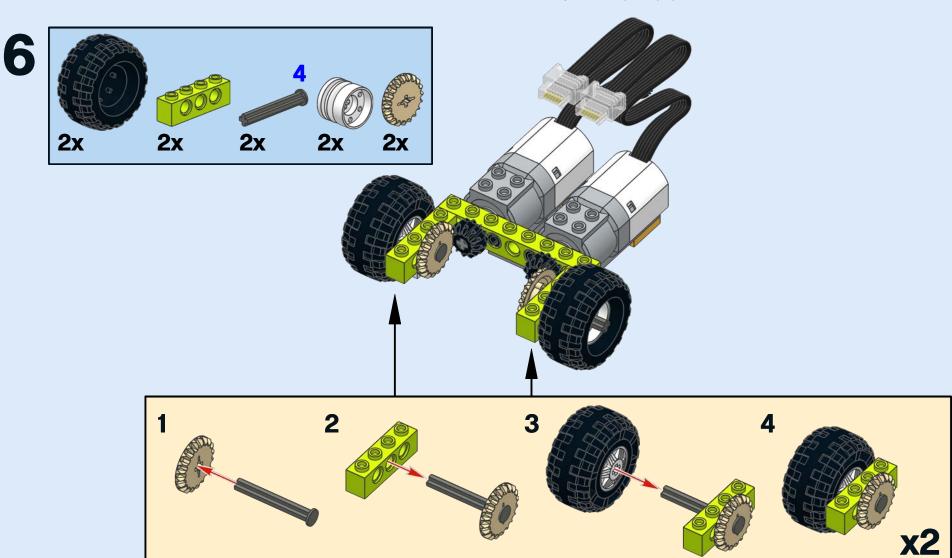




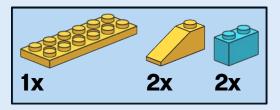


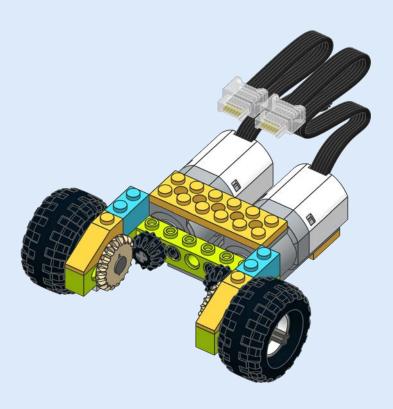




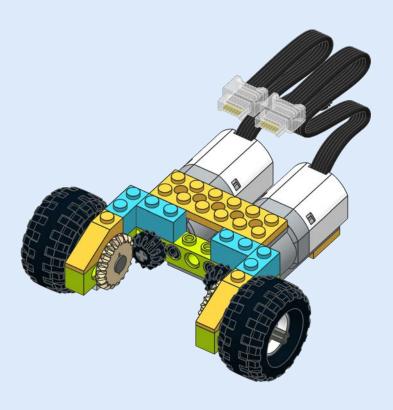




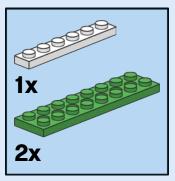


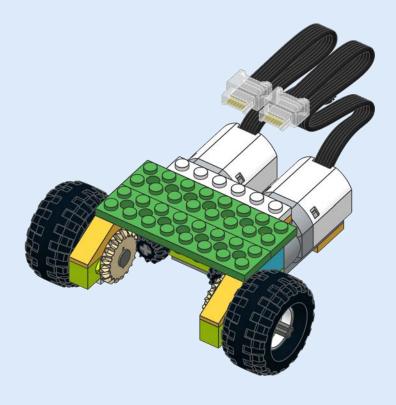




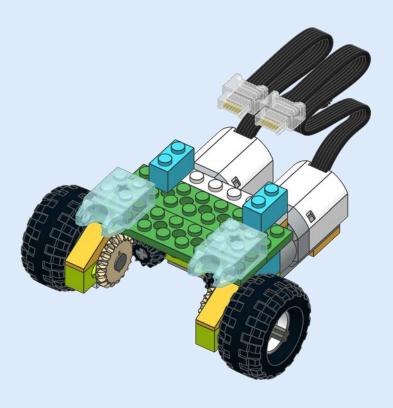


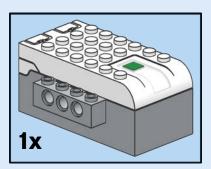


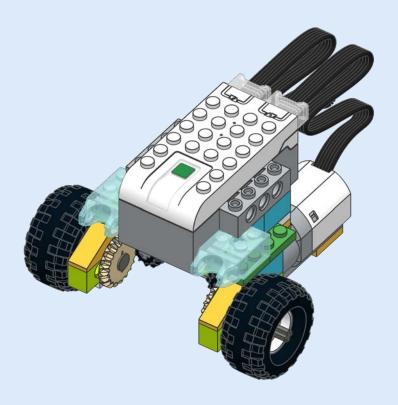


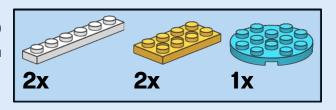


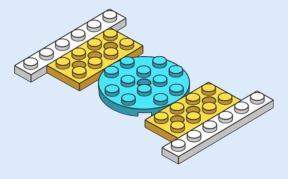


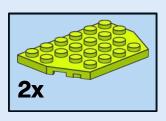


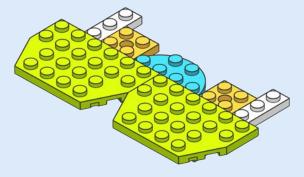




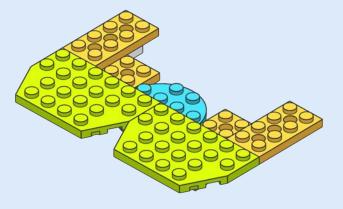


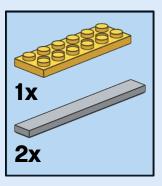


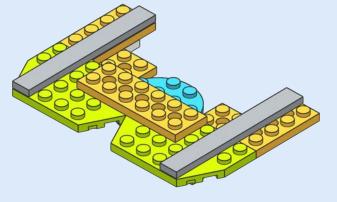




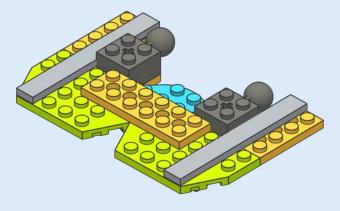




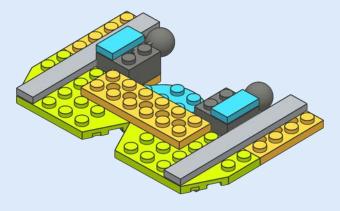




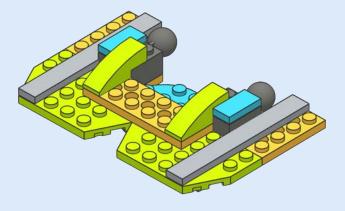


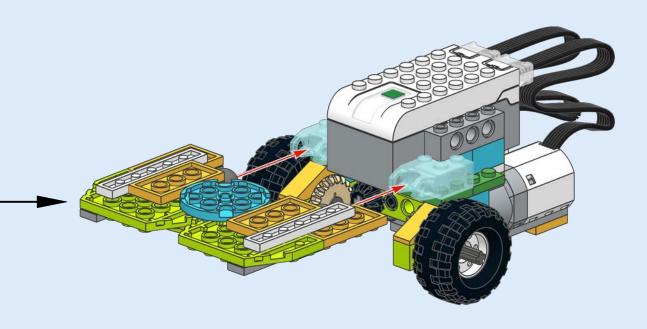


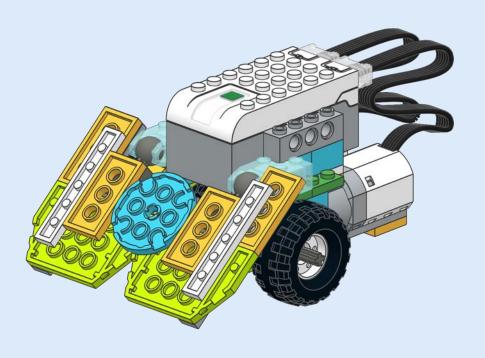


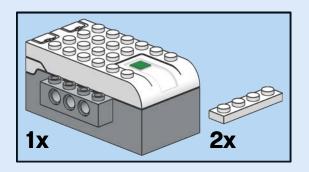


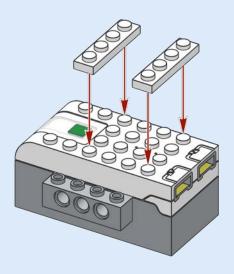


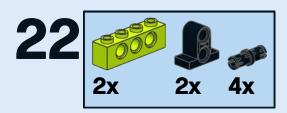


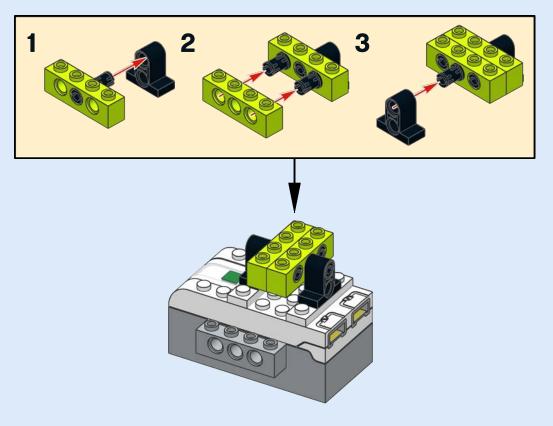


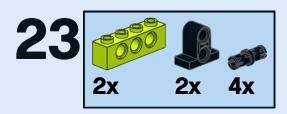


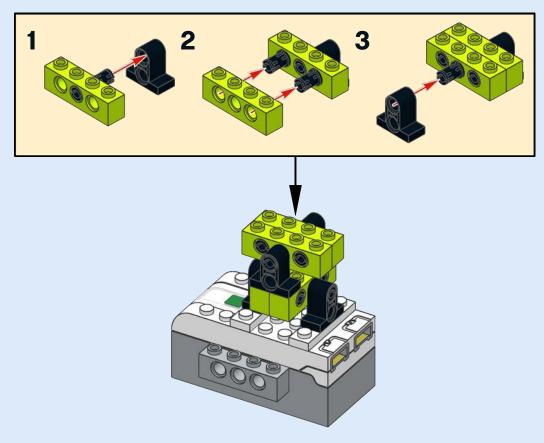


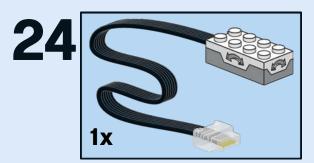


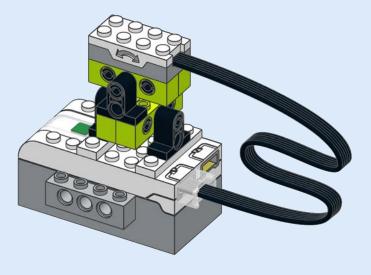




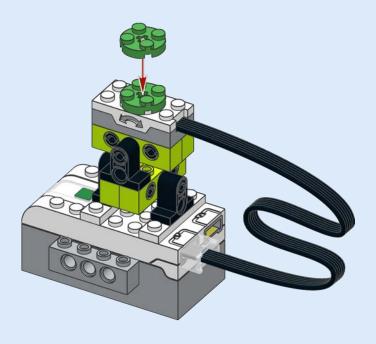


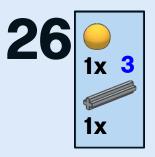


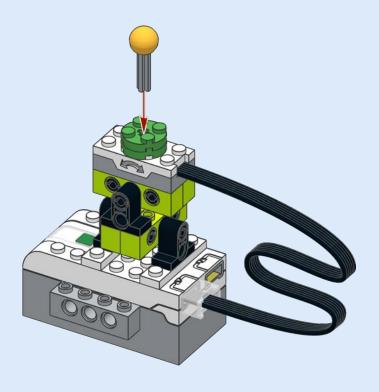


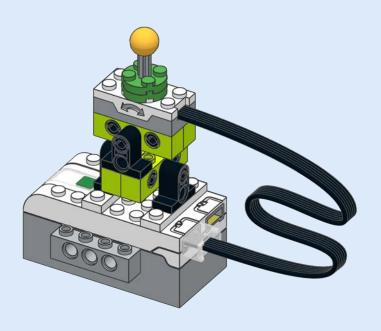


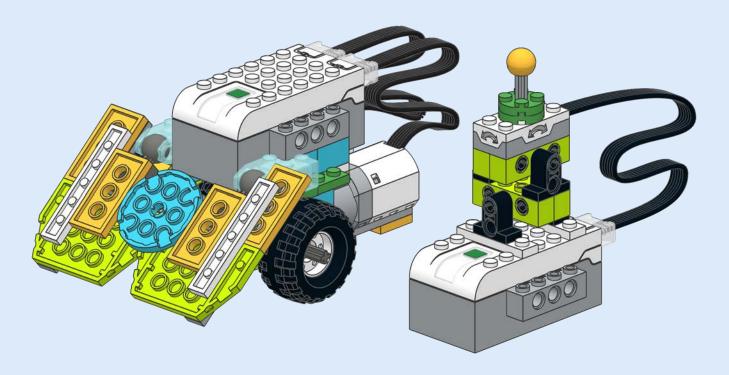




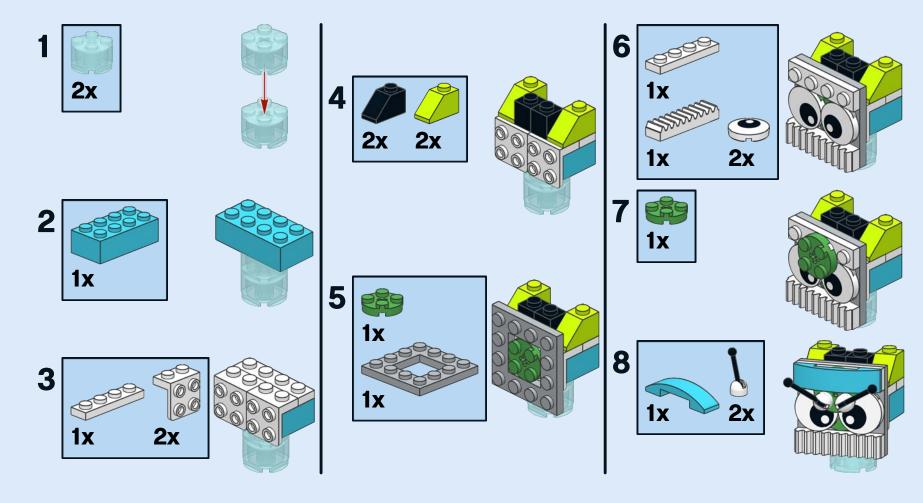


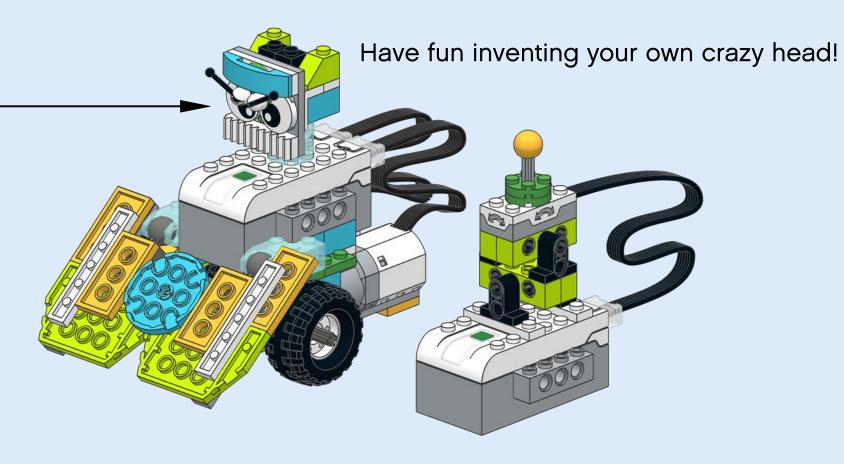






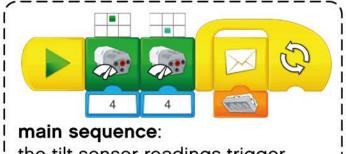
The RC sumo bot is complete. Next comes the optional head.





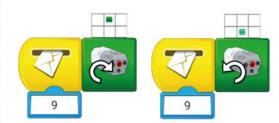
#### **Remote control program**

**Attention!** You must connect the Hub of the remote control **before** the Hub of the robot, or the motor colors would change.



the tilt sensor readings trigger other sequences using messages



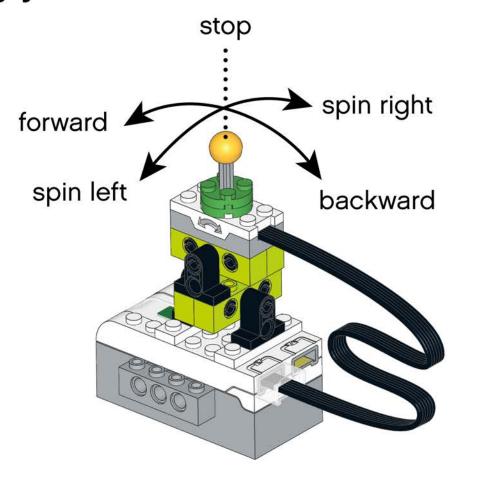








#### How to use the joystick



0	stop
3	backward
5	spin right
7	spin left
9	forward