# **Report Generated by Test Manager**

Title: Branch: 28-hexarotor-UTs-optimWIP

Author: Previous Commit Hash: 4c9e050a9e4fd2

297bc758cb25733d91e20464e6

Date: 19-Oct-2025 14:14:40

## **Test Environment**

Platform: PCWIN64 MATLAB: (R2024a)

# **Summary**

	<b>.</b>
Outcome	Duration (Seconds)
16 🕏	140.848
9 🥥	130.101
9 🕏	130.101
<b>Ø</b>	3.269
<b>Ø</b>	3.269
•	2.106
<b>Ø</b>	2.106
<b>Ø</b>	1.303
<b>Ø</b>	1.478
<b>Ø</b>	1.478
•	8.086
<b>Ø</b>	8.087
<b>Ø</b>	16.351
<b>Ø</b>	0.882
<b>②</b>	0.881
<b>Ø</b>	0.823
<b>Ø</b>	94.07
4 🗸	4.794
4 🕏	4.794
•	1.12
<b>Ø</b>	1.12
<b>Ø</b>	0.99
<b>Ø</b>	0.99
<b>Ø</b>	0.957
•	0.958
	16 © 9 © 9 © 0 © 0 © 0 0 0 0 0 0 0 0 0 0 0

sensors sensors	<b>Ø</b>	1.492
I <u>Iteration1</u>	<b>②</b>	1.492
environment	3 🗸	3.919
Environment Tests	3 🗸	3.92
Air	<b>②</b>	0.953
I <u>Iteration1</u>	<b>②</b>	0.953
Earth	<b>②</b>	2.103
I <u>Iteration1</u>	<b>②</b>	2.104
LocalTerrain	<b>②</b>	0.711
I <u>Iteration1</u>	<b>Ø</b>	0.71

## Results: 2025-Oct-19 14:12:17

Result Type: Result Set Parent: None

Start Time: 19-Oct-2025 14:12:18 End Time: 19-Oct-2025 14:14:39 Outcome: Total: 16, Passed: 16

**Back to Report Summary** 

#### F16

#### **Test Result Information**

Result Type: Test File Result

Parent: Results: 2025-Oct-19 14:12:17

Start Time: 19-Oct-2025 14:12:18 End Time: 19-Oct-2025 14:14:28 Outcome: Total: 9, Passed: 9

#### **Test Suite Information**

Name: F16

**Back to Report Summary** 

#### **Vehicle Tests**

#### **Test Result Information**

Result Type: Test Suite Result

Parent: <u>F16</u>

Start Time: 19-Oct-2025 14:12:18 End Time: 19-Oct-2025 14:14:28 Outcome: Total: 9, Passed: 9

#### **Test Suite Information**

Name: Vehicle Tests

**Back to Report Summary** 

#### actuators

#### **Test Result Information**

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 19-Oct-2025 14:12:18 End Time: 19-Oct-2025 14:12:21

Outcome: Passed

#### **Test Case Information**

Name: actuators Type: Baseline Test

## Iteration1

#### **Test Result Information**

Result Type: Test Iteration Result

Parent: actuators

Start Time: 19-Oct-2025 14:12:18 End Time: 19-Oct-2025 14:12:21

Outcome: Passed

#### **Test Case Information**

Name: Iteration1
Type: Baseline Test

## **Iteration Settings**

#### **Test Overrides**

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

## **Verify Result**

5	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.angVel_radps, 0))
	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.forcesInBody_N(1)
) <u>.</u>	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.forcesInBody_N(2
)	<ul><li>Test sequence//vernyControllerDisarmed:vernytisClose(actuatorвus.Propulsionвus.engineForcesMoments.torcesmbody_N(z)</li></ul>
(	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.forcesInBody_N(3
)	)
r	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.momentsInBody_n(1), 0))
(	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.momentsInBody_
r	n(2), 0))
	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.momentsInBody_n(3), 0))
(	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posAileron_rad,0))
(	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posElevator_rad,0))
(	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posRudder_rad,0))
(	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.angVel_radps, 0))
(	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.forcesInBody_N(1),
	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.forcesInBody_N(2),
Ę	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.forcesInBody_N(3),
	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.momentsInBody_Nr
,	0))
Ę	🛂 Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.momentsInBody_Nr
,	0))
	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.momentsInBody_Nr
,	0))
	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posAileron_rad,0))
	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posElevator_rad,0))
	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posRudder_rad,0))
	Test Sequence//verifyAileronRate:verify(aileronCmdRate <= aileronDeflRateLimit_degps)
(	Test Sequence//verifyAileronLimit:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posAileron_rad, deg2rad(maxAilDefl_
٦.	)) 
(	Test Sequence//verifyNegAileronRate:verify(abs(aileronCmdRate) <= aileronDeflRateLimit_degps)
(	Test Sequence//verifyNegAileronLimit:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posAileron_rad, -deg2rad(maxAil
-	.deg)))
-	Test Sequence//verifyElevatorRate:verify(elevatorCmdRate <= elevatorDeflRateLimit_degps)
	🋂 Test Sequence//verifyElevatorLimit:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posElevator_rad, deg2rad(maxEleva
L	Oefl_deg)))

Test Sequence//verifyNegElevatorRate:verify(abs(elevatorCmdRate ) <= elevatorDeflRateLimit_degps)
Test Sequence//verifyNegElevatorLimit:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posElevator_rad, -deg2rad(maxElev
atorDefl_deg)))
Test Sequence//verifyRudderRate:verify(rudderCmdRate <= rudderDeflRateLimit_degps)
Test Sequence//verifyRudderMax:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posRudder_rad, deg2rad(maxRudderDefl_
deg)))
Test Sequence//verifyNegRudderRate:verify(abs(rudderCmdRate) <= rudderDeflRateLimit_degps)
Test Sequence//verifyNegRudderMax:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posRudder_rad, -deg2rad(maxRudder
Defl_deg)))

#### **Simulation**

## **System Under Test Information**

Model: actuators

Harness: actuatorsTestHarness

Harness Owner: actuators
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: actuatorsTestHarness/Test Sequence

Test Sequence Scenario: Scenario\_1

Start Time: 0

Stop Time: 19.02400000000001

Checksum: 1035197211 3367557082 1635020878 828644898

#### Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

## **Back to Report Summary**

#### aero

#### **Test Result Information**

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 19-Oct-2025 14:12:22 End Time: 19-Oct-2025 14:12:24

Outcome: Passed

#### **Test Case Information**

Name: aero

Type: Baseline Test

## Iteration1

#### **Test Result Information**

Result Type: Test Iteration Result

Parent: <u>aero</u>

Start Time: 19-Oct-2025 14:12:22 End Time: 19-Oct-2025 14:12:24

Outcome: Passed

#### **Test Case Information**

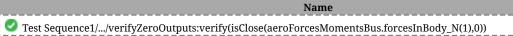
Name: Iteration1
Type: Baseline Test

## **Iteration Settings**

#### **Test Overrides**

1000 0 101111100		
Parameter Name	Value	
TestSequenceScena	Scenario_1	
rio		

## **Verify Result**



Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.forcesInBody_N(2),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.forcesInBody_N(3),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(1),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(2),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(3),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.airspeedInBody_mps(1),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.airspeedInBody_mps(2),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.airspeedInBody_mps(3),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.alpha_rad,0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.beta_rad,0))	
Test Sequence1//verifyAirspeed:verify(aeroForcesMomentsBus.forcesInBody_N(1) < 0)	
Test Sequence1//verifyAirspeed:verify(isClose(aeroForcesMomentsBus.forcesInBody_N(2),0))	
Test Sequence1//verifyAirspeed:verify(aeroForcesMomentsBus.forcesInBody_N(3) < -20500 * lbf2N)	
Test Sequence1//verifyAirspeed:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(1),0))	
Test Sequence1//verifyAirspeed:verify(aeroForcesMomentsBus.momentsInBody_Nm(2) < 0)	
Test Sequence1//verifyAirspeed:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(3),0))	
Test Sequence1//verifyAirspeed:verify(isClose(airDataBus.airspeedInBody_mps(2),0))	
Test Sequence1//verifyAirspeed:verify(isClose(airDataBus.airspeedInBody_mps(3),0))	
Test Sequence1//verifyAirspeed:verify(isClose(airDataBus.alpha_rad,0))	
Test Sequence1//verifyAirspeed:verify(isClose(airDataBus.beta_rad,0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(aeroForcesMomentsBus.forcesInBody_N(2),0))	
Test Sequence1//verifyElevatorDeflection:verify(aeroForcesMomentsBus.forcesInBody_N(3) > cruiseZForce)	
Test Sequence1//verifyElevatorDeflection:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(1),0))	
Test Sequence1//verifyElevatorDeflection:verify(aeroForcesMomentsBus.momentsInBody_Nm(2) > cruiseYMoment)	
Test Sequence1//verifyElevatorDeflection:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(3),0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(airDataBus.airspeedInBody_mps(2),0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(airDataBus.airspeedInBody_mps(3),0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(airDataBus.alpha_rad,0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(airDataBus.beta_rad,0))	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.forcesInBody_N(2) > 0)	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.forcesInBody_N(3) < 0)	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.momentsInBody_Nm(1) > 0)	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.momentsInBody_Nm(2) < 0)	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.momentsInBody_Nm(3) < 0)	
Test Sequence1//verifyRudder:verify(isClose(airDataBus.airspeedInBody_mps(2),0))	
Test Sequence1//verifyRudder:verify(isClose(airDataBus.airspeedInBody_mps(3),0))	
Test Sequence1//verifyRudder:verify(isClose(airDataBus.alpha_rad,0))	

ē	Test Sequence1//verifyRudder:verify(isClose(airDataBus.beta_rad,0))
Q	Test Sequence1//verifyAileron:verify(aeroForcesMomentsBus.momentsInBody_Nm(1) < 0)
Q	Test Sequence1//verifyAileron:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(2),cruiseYMoment))
	Test Sequence1//verifyAileron:verify(aeroForcesMomentsBus.momentsInBody_Nm(3) < 0)
	Test Sequence1//verifyAileron:verify(isClose(airDataBus.alpha_rad,0))
V	Test Sequence1//verifyAileron:verify(isClose(airDataBus.beta_rad,0))

#### **Simulation**

## **System Under Test Information**

Model: aero

Harness: aeroTestHarness

Harness Owner: aero
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: aeroTestHarness/Test Sequence1

Test Sequence Scenario: Scenario\_1

Start Time: 0 Stop Time: 22

Checksum: 1204314850 3911341573 15874598 4021657899

#### Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

## **Back to Report Summary**

## ground contact

#### **Test Result Information**

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 19-Oct-2025 14:12:24 End Time: 19-Oct-2025 14:12:25

Outcome: Passed

## **Test Case Information**

Name: ground contact Type: Baseline Test

## **Verify Result**

Name
✓ Test Sequence1//verifyInitialization:verify(isVehicleAirborne == 0)
✓ Test Sequence1//verifyInitialization:verify(groundCollision == 0)
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1),0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2),0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3),0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(1), 0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(2), 0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(3), 0))
Test Sequence1//verifyStationary:verify(isVehicleAirborne == 0)
Test Sequence1//verifyStationary:verify(groundCollision == 0)
Test Sequence1//verifyStationary:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1), 0))
Test Sequence1//verifyStationary:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2), 0))
Test Sequence1//verifyStationary:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3), -9298.6 * 9.81 ))
Test Sequence1//verifyStationary:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(1), 0))
Test Sequence1//verifyStationary:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(2), 0))
Test Sequence1//verifyStationary:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(3), 0))
Test Sequence1//verifyFastTaxi:verify(isVehicleAirborne == 0)
Test Sequence1//verifyFastTaxi:verify(groundCollision == 0)
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1), 0))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2), 0))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3), -9298.6 * 9.81 + 20000 ))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(1),0))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(2),0))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(3),0))
Test Sequence1//verifyFastTaxi:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(1), 0))

Test Sequence1//verifyFastTaxi:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(2), 0))	
✓ Test Sequence1//verifyFastTaxi:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(3), 0))	
Test Sequence1//verifyRotate:verify(isVehicleAirborne == 0)	
✓ Test Sequence1//verifyRotate:verify(groundCollision == 0)	
■ Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1), 0))	
■ Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2), 0))	
■ Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3), -9298.6 * 9.81 + 20000 ))	
☑ Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(1),0))	
☑ Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(2),0))	
✓ Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(3),0))	
☑ Test Sequence1//verifyRotate:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(1), 0))	
☑ Test Sequence1//verifyRotate:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(2), 0))	
Test Sequence1//verifyRotate:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(3), 0))	
Test Sequence1//verifyTakeoff:verify(isVehicleAirborne == 1)	
Test Sequence1//verifyTakeoff:verify(groundCollision == 0)	
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1), 0))	
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2), 0))	
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3), 0))	
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(1),0))	
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(2),0))	
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(3),0))	
Test Sequence1//verifyTakeoff:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(1), 0))	
Test Sequence1//verifyTakeoff:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(2), 0))	
☑ Test Sequence1//verifyTakeoff:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(3), 0))	

#### **Simulation**

## **System Under Test Information**

Model: groundContact

Harness: groundContactTestHarness

Harness Owner: groundContact

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: groundContactTestHarness/Test Sequence1

Test Sequence Scenario: Scenario\_2

Start Time: 0 Stop Time: 2.028

Checksum: 1244405978 4079976263 897553408 2782662889

#### Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

## **Back to Report Summary**

## inertial dynamics

#### **Test Result Information**

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 19-Oct-2025 14:12:26 End Time: 19-Oct-2025 14:12:27

Outcome: Passed

#### **Test Case Information**

Name: inertial dynamics Type: Baseline Test

## Iteration1

#### **Test Result Information**

Result Type: Test Iteration Result
Parent: <u>inertial dynamics</u>
Start Time: 19-Oct-2025 14:12:26
End Time: 19-Oct-2025 14:12:27

Outcome: Passed

#### **Test Case Information**

Name: Iteration1
Type: Baseline Test

## **Iteration Settings**

#### **Test Overrides**

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

## **Verify Result**

Name
Test Sequence1//Test1:verify(isClose(bodyStatesBus.aircraftPosInNED_m(1), 0.5*interval_time^2*aircraftForcesInNED_N(1)/aircr
aftMass + aircraftInitialPosInNED_m(1)))
Test Sequence1//Test1:verify(isClose(bodyStatesBus.aircraftVelInBody_mps(1), interval_time*aircraftForcesMomentsBus_forcesI
nBody_N(1)/aircraftMass + aircraftInitialVelInBody_mps(1)))
Test Sequence1//Test1:verify(isClose(bodyStatesBus.aircraftAccelInBody_mps2(1),aircraftForcesMomentsBus_forcesInBody_N(1)
/aircraftMass))

#### **Simulation**

## **System Under Test Information**

Model: inertialDynamics

Harness: inertialDynamicsTestHarness

Harness Owner: inertialDynamics

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: inertialDynamicsTestHarness/Test Sequence1

Test Sequence Scenario: Scenario\_1

Start Time: 0 Stop Time: 1.008

Checksum: 2740628208 4264647383 940722363 2610557463

#### Simulation Logs:

<u>'aircraftInitialEuler\_rad'</u> is defined, but is never used in the Test Sequence block. <u>Delete this object.</u>

## **Back to Report Summary**

## Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

## **Back to Report Summary**

## vehicle

#### **Test Result Information**

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 19-Oct-2025 14:12:27 End Time: 19-Oct-2025 14:12:36

Outcome: Passed

#### **Test Case Information**

Name: vehicle

Type: Baseline Test

## Iteration1

## **Test Result Information**

Result Type: Test Iteration Result

Parent: <u>vehicle</u>

Start Time: 19-Oct-2025 14:12:27 End Time: 19-Oct-2025 14:12:36

Outcome: Passed

## **Test Case Information**

Name: Iteration1
Type: Baseline Test

## **Iteration Settings**

#### **Test Overrides**

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

# **Verify Result**

Name
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(1), 0 ))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0 ))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0 ))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(1),0))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2),0))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(3),0))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(1), 0 ))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0 ))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0 ))
☑ Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(1),0))
☑ Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2),0))
☑ Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(3),0))
✓ Test Sequence//verifyThrottle:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
▼ Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0 ))
▼ Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0 ))
▼ Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(1),0))
Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2),0))

Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(3),0))
Test Sequence//verifyPitchIntoGround:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2), 0))
Test Sequence//verifyPitchIntoGround:verify(isClose(vehicleBus.BodyStates.aircraftEulerAngles_rad(2) , 0))
Test Sequence//verifyPitchIntoGround:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0))
Test Sequence//verifyPitchIntoGround:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
Test Sequence//verifyPitchIntoGround:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0 ))
Test Sequence//verifydeflectElevator:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2), 0, 'absTol', 0.01))
Test Sequence//verifydeflectElevator:verify(isClose(vehicleBus.BodyStates.aircraftEulerAngles_rad(2), 0, 'absTol', 0.01 ))
Test Sequence//verifydeflectElevator:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0, 'absTol', 0.01))
Test Sequence//verifydeflectElevator:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
Test Sequence//verifydeflectElevator:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0 ))
Test Sequence//verifyRotate:verify(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2) > 0)
Test Sequence//verifyRotate:verify(vehicleBus.BodyStates.aircraftEulerAngles_rad(2) > 0)
Test Sequence//verifyRotate:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(3) < 0)
Test Sequence//verifyRotate:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
Test Sequence//verifyRotate:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0 ))
Test Sequence//verifyFlying:verify(vehicleBus.BodyStates.aircraftPosInNED_m(3) < 0)
Test Sequence//verifyFlying:verify(vehicleBus.BodyStates.aircraftEulerAngles_rad(2) > 0)
Test Sequence//verifyFlying:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
Test Sequence//verifyFlying:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0 ))

#### **Simulation**

# System Under Test Information

Model: F16

Harness: F16TestHarness

Harness Owner: F16
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration
Test Sequence Block: F16TestHarness/Test Sequence

Test Sequence Scenario: Scenario\_1

Start Time: 0

Stop Time: 86.0199999999999

Checksum: 3572155589 2390394185 2796403885 1853855084

#### Simulation Logs:

The input bus to block 'actuators/Bus Creator1' does not match the bus specified by the bus object 'ActuatorBus' on the block dialog: Signal 'EngineBus' does not match the name 'ActuatorBus.PropulsionBus' of the corresponding bus element in the bus object. To disable this diagnostic, set the Configuration Parameters > Diagnostics > Connectivity > 'Element name mismatch' option to 'None'.

The input bus to block 'actuators/actuatorBus' does not match the bus specified by the bus object 'ActuatorBus' on the block dialog: Signal 'EngineBus' does not match the name 'ActuatorBus.PropulsionBus' of the corresponding bus element in the bus object. To disable this diagnostic, set the Configuration Parameters > Diagnostics > Connectivity > 'Element name mismatch' option to 'None'.

Remapping selected signal 'EngineBus.engineForcesMoments' to 'PropulsionBus.engineForcesMoments' in '<u>F16/Bus Selector4</u>' to match the bus hierarchy. Save your file to make this change permanent.

Remapping selected signal 'EngineBus.fuelRate\_kgps' to 'PropulsionBus.fuelRate\_kgps' in '<u>F16/Bus Selector5</u>' to match the bus hierarchy. Save your file to make this change permanent.

Remapping selected signal 'EngineBus.engineForcesMoments' to 'PropulsionBus.engineForcesMoments' in 'F16/Bus Selector2' to match the bus hierarchy. Save your file to make this change permanent.

The input bus to block 'F16/Bus Creator' does not match the bus specified by the bus object 'VehicleBus' on the block dialog: Signal 'AirData' does not match the name 'VehicleBus.AirDataBus' of the corresponding bus element in the bus object. To disable this diagnostic, set the Configuration Parameters > Diagnostics > Connectivity > 'Element name mismatch' option to 'None'.

The input bus to block 'F16/VehicleBus' does not match the bus specified by the bus object 'VehicleBus' on the block dialog: Signal 'AirData' does not match the name 'VehicleBus.AirDataBus' of the corresponding bus element in the bus object. To disable this diagnostic, set the Configuration Parameters > Diagnostics > Connectivity > 'Element name mismatch' option to 'None'.

## **Back to Report Summary**

## Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

## **Back to Report Summary**

## engine

## **Test Result Information**

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 19-Oct-2025 14:12:36 End Time: 19-Oct-2025 14:12:52

Outcome: Passed

#### **Test Case Information**

Name: engine

Type: Baseline Test

## **Verify Result**

Name
Test Sequence//verifyControllerDisarm:verify(isClose(propulsionBus.engineForcesMoments.forcesInBody_N(1),0))
Test Sequence//verifyThorttle:verify(isClose(thrust_lbf, propulsionBus.engineForcesMoments.forcesInBody_N(1), 'atol', 1))
Test Sequence//verifyMaxThrust:verify(propulsionBus.engineForcesMoments.forcesInBody_N(1) < 130000)
Test Sequence//verifyMaxThrust:verify(isClose(thrust_lbf, propulsionBus.engineForcesMoments.forcesInBody_N(1), 'atol', 1))
Test Sequence//verifyWithAirspeed:verify(isClose(thrust_lbf, propulsionBus.engineForcesMoments.forcesInBody_N(1), 'atol', 1))
Test Sequence//verifyIncreaseAirspeed:verify(isClose(thrust_lbf, propulsionBus.engineForcesMoments.forcesInBody_N(1), 'atol'
, 1))

#### Simulation

#### **System Under Test Information**

Model: engineModelF16

Harness: engineModelF16TestHarness

Harness Owner: engineModelF16

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: engineModelF16TestHarness/Test Sequence

Test Sequence Scenario: Scenario\_1

Start Time: 0

Stop Time: 38.00399999999998

Checksum: 1919719264 197051287 2377558008 1774720500

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

## **Back to Report Summary**

#### addFM

#### **Test Result Information**

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 19-Oct-2025 14:12:52 End Time: 19-Oct-2025 14:12:53

Outcome: Passed

#### **Test Case Information**

Name: addFM

Type: Baseline Test

## Iteration1

#### **Test Result Information**

Result Type: Test Iteration Result

Parent: addFM

Start Time: 19-Oct-2025 14:12:52 End Time: 19-Oct-2025 14:12:53

Outcome: Passed

#### **Test Case Information**

Name: Iteration1
Type: Baseline Test

## **Iteration Settings**

#### **Test Overrides**

Parameter Nam	Value	
TestSequenceSce	a Scenario_1	
rio		

## **Verify Result**

# Name Test Sequence1/.../Test1:verify(all(isClose(aircraftForcesMomentsBus.forcesInBody\_N, aeroForcesMomentsBus.forcesInBody\_N + e ngineForcesMomentsBus.forcesInBody\_N + groundForcesMomentsBus.forcesInBody\_N + weightForcesMomentsBus.forcesInBody\_N) Test Sequence1/.../Test1:verify(all(isClose(aircraftForcesMomentsBus.momentsInBody\_Nm, engineForcesMomentsBus.momentsInBody\_Nm + aeroForcesMomentsBus.momentsInBody\_Nm + weightForcesMomentsBus.momentsInBody\_Nm))) Test Sequence1/.../Test2:verify(all(isClose(aircraftForcesMomentsBus.forcesInBody\_N, aeroForcesMomentsBus.forcesInBody\_N + e ngineForcesMomentsBus.forcesInBody\_N + groundForcesMomentsBus.forcesInBody\_N + weightForcesMomentsBus.forcesInBody\_N) ))

Test Sequence1//Test2:verify(all(isClose(aircraftForcesMomentsBus.momentsInBody_Nm, aeroForcesMomentsBus.momentsInB
ody_Nm + engineForcesMomentsBus.momentsInBody_Nm + weightForcesMomentsBus.momentsInBody_Nm)))
Test Sequence1//verifyPitchIntoGround:verify(all(isClose(aircraftForcesMomentsBus.forcesInBody_N, aeroForcesMomentsBus.f
orcesInBody_N + engineForcesMomentsBus.forcesInBody_N + groundForcesMomentsBus.forcesInBody_N + weightForcesMomentsBu
s.forcesInBody_N)))
Test Sequence1//verifyPitchIntoGround:verify(isClose(aircraftForcesMomentsBus.momentsInBody_Nm(1), 0))
Test Sequence1//verifyPitchIntoGround:verify(isClose(aircraftForcesMomentsBus.momentsInBody_Nm(2), engineForcesMomen
tsBus.momentsInBody_Nm(2) + aeroForcesMomentsBus.momentsInBody_Nm(2) + weightForcesMomentsBus.momentsInBody_Nm(2)
))
Test Sequence1//verifyPitchIntoGround:verify(isClose(aircraftForcesMomentsBus.momentsInBody_Nm(3), engineForcesMomen
tsBus.momentsInBody_Nm(3) + aeroForcesMomentsBus.momentsInBody_Nm(3) + weightForcesMomentsBus.momentsInBody_Nm(3)

#### **Simulation**

## **System Under Test Information**

Model: addFM

Harness: addFMTestHarness

Harness Owner: addFM
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: addFMTestHarness/Test Sequence1

Test Sequence Scenario: Scenario\_1

Start Time: 0 Stop Time: 3.016

Checksum: 2405791290 3021241631 2400769033 306058281

## Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

**Back to Report Summary** 

## gravity

## **Test Result Information**

Result Type: Test Case Result Parent: **Vehicle Tests** 

Start Time: 19-Oct-2025 14:12:53 19-Oct-2025 14:12:54 End Time:

Outcome: Passed

## **Test Case Information**

Name:

gravity Baseline Test Type:

## **Verify Result**

Name
Test Sequence1//Test1:verify(isClose(weightForcesMoments.forcesInBody_N(1), 0))
Test Sequence1//Test1:verify(isClose(weightForcesMoments.forcesInBody_N(2), 0))
Test Sequence1//Test1:verify(isClose(weightForcesMoments.forcesInBody_N(3), weight_N))
Test Sequence1//Test1:verify(isClose(sum(weightForcesMoments.momentsInBody_Nm(1:3)), 0))
☑ Test Sequence1//Test2:verify(isClose(weightForcesMoments.forcesInBody_N(1), -weight_N * sin(pitch_rad)))
☑ Test Sequence1//Test2:verify(isClose(weightForcesMoments.forcesInBody_N(2), 0))
☑ Test Sequence1//Test2:verify(isClose(weightForcesMoments.forcesInBody_N(3), weight_N * cos(pitch_rad)))
☑ Test Sequence1//Test2:verify(isClose(sum(weightForcesMoments.momentsInBody_Nm(1:3)), 0))
☑ Test Sequence1//Test3:verify(isClose(weightForcesMoments.forcesInBody_N(1), -weight_N * sin(pitch_rad)))
☑ Test Sequence1//Test3:verify(isClose(weightForcesMoments.forcesInBody_N(2), weight_N * sin(roll_rad) * cos(pitch_rad)))
☑ Test Sequence1//Test3:verify(isClose(weightForcesMoments.forcesInBody_N(3), weight_N * cos(roll_rad) * cos(pitch_rad)))
Test Sequence1//Test3:verify(isClose(sum(weightForcesMoments.momentsInBody_Nm(1:3)), 0))

## **Simulation**

## **System Under Test Information**

Model: gravity

Harness: gravity Test Harness

gravity Harness Owner:

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: gravityTestHarness/Test Sequence1

Test Sequence Scenario: Scenario\_1

Start Time: 0

Stop Time: 0.028000000000000001

Checksum: 371801570 4075467097 1945074898 1201465379

#### Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

#### **Back to Report Summary**

## **FullSIL**

#### **Test Result Information**

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 19-Oct-2025 14:12:54 End Time: 19-Oct-2025 14:14:28

Outcome: Passed

#### **Test Case Information**

Name: FullSIL

Type: Baseline Test

#### **Simulation**

## **System Under Test Information**

Model: VehiclePlant

Harness: VehiclePlantTestHarness

Harness Owner: VehiclePlant Release: Current simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Seguence Block: VehiclePlantTestHarness/Test Seguence

Test Sequence Scenario: Scenario

Start Time: 0

Stop Time: 280.0040000000002

Checksum: 3741715814 389861614 4232404438 650717578

#### Simulation Logs:

The input bus to block 'F16/Bus Creator' does not match the bus specified by the bus object 'VehicleBus' on the block dialog: Signal 'AirData' does not match the name 'VehicleBus.AirDataBus' of the corresponding bus element in the bus object. To disable this diagnostic, set the Configuration Parameters > Diagnostics > Connectivity > 'Element name mismatch' option to 'None'.

The input bus to block 'F16/VehicleBus' does not match the bus specified by the bus object 'VehicleBus' on the block dialog: Signal 'AirData' does not match the name 'VehicleBus.AirDataBus' of the corresponding bus element in the bus object. To disable this diagnostic, set the Configuration Parameters > Diagnostics > Connectivity > 'Element name mismatch' option to 'None'.

<u>'SensorsBus'</u> is defined, but is never used in the Test Sequence block. <u>Delete this object.</u>

<u>'VehicleBus'</u> is defined, but is never used in the Test Sequence block. <u>Delete this</u> object.

Warning issued while simulating Model block '<u>VehiclePlantTestHarness/</u>
<u>VehiclePlant'</u>.

## **Back to Report Summary**

#### Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

## **Back to Report Summary**

#### sensors

#### **Test Result Information**

Result Type: Test File Result

Parent: <u>Results: 2025-Oct-19 14:12:17</u>

Start Time: 19-Oct-2025 14:14:29 End Time: 19-Oct-2025 14:14:33 Outcome: Total: 4, Passed: 4

#### **Test Suite Information**

Name: sensors

**Back to Report Summary** 

#### **Sensor Tests**

#### **Test Result Information**

Result Type: Test Suite Result

Parent: sensors

Start Time: 19-Oct-2025 14:14:29 End Time: 19-Oct-2025 14:14:33 Outcome: Total: 4, Passed: 4

#### **Test Suite Information**

Name: Sensor Tests

**Back to Report Summary** 

#### ins

## **Test Result Information**

Result Type: Test Case Result Parent: Sensor Tests

Start Time: 19-Oct-2025 14:14:29 End Time: 19-Oct-2025 14:14:30

Outcome: Passed

#### **Test Case Information**

Name: ins

Type: Baseline Test

## Iteration1

#### **Test Result Information**

Result Type: Test Iteration Result

Parent: ins

Start Time: 19-Oct-2025 14:14:29 End Time: 19-Oct-2025 14:14:30

Outcome: Passed

#### **Test Case Information**

Name: Iteration1
Type: Baseline Test

## **Iteration Settings**

#### **Test Overrides**

Parameter Name	Value	
TestSequenceScena	Scenario_1	
rio		

## **Verify Result**

Name
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.GyroSensorBus.x_radps, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.GyroSensorBus.y_radps, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.GyroSensorBus.z_radps, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.AccelSensorBus.x_mps2, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.AccelSensorBus.y_mps2, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.AccelSensorBus.z_mps2, 0, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.GyroSensorBus.x_radps, 0.1, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.GyroSensorBus.y_radps, 0.2, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.GyroSensorBus.z_radps, 0.3, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.MagSensorBus.x_Gauss, 0, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.MagSensorBus.y_Gauss, 0, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.MagSensorBus.z_Gauss, 0, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.AccelSensorBus.x_mps2, 1, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.AccelSensorBus.y_mps2, 2, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.AccelSensorBus.z_mps2, 3, 'atol', 0.01))

#### **Simulation**

## **System Under Test Information**

Model: ins

Harness: insTestHarness

Harness Owner: ins Release: Cur

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration
Test Sequence Block: insTestHarness/Test Sequence

Test Sequence Scenario: Scenario\_1

Start Time: 0

Stop Time: 10.00800000000001

Checksum: 677169283 1337975363 3752592478 3123190075

#### Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

## **Back to Report Summary**

## adc

## **Test Result Information**

Result Type: Test Case Result Parent: Sensor Tests

Start Time: 19-Oct-2025 14:14:30 End Time: 19-Oct-2025 14:14:31

Outcome: Passed

#### **Test Case Information**

Name: adc

Type: Baseline Test

## Iteration1

#### **Test Result Information**

Result Type: Test Iteration Result

Parent: adc

Start Time: 19-Oct-2025 14:14:30 End Time: 19-Oct-2025 14:14:31

Outcome: Passed

#### **Test Case Information**

Name: Iteration1
Type: Baseline Test

## **Iteration Settings**

## **Test Overrides**

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

## **Verify Result**

Name
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.BaroSensorBus.altitude_m, 0, 'atol', 20))
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.BaroSensorBus.pressure_pa, 101325, 'atol', 100))
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.BaroSensorBus.temperature_degC, 15, 'atol', 2))
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.DiffPressureSensorBus.differential_pressure_pa, 0, 'atol', 100))
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.DiffPressureSensorBus.temperature_degC, 15, 'atol', 2))
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.BaroSensorBus.altitude_m, 3048, 'atol', 20))
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.BaroSensorBus.pressure_pa, 69681.66, 'atol', 100))
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.BaroSensorBus.temperature_degC, -4.8, 'atol', 2))
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.DiffPressureSensorBus.differential_pressure_pa, 0, 'atol', 100))
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.DiffPressureSensorBus.temperature_degC, -4.8, 'atol', 2))
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.BaroSensorBus.altitude_m, 6096, 'atol', 20))
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.BaroSensorBus.pressure_pa, 46563.26, 'atol', 100))
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.BaroSensorBus.temperature_degC, -24.624, 'atol', 2))
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.DiffPressureSensorBus.differential_pressure_pa, 0, 'atol', 100))
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.DiffPressureSensorBus.temperature_degC, -24.624, 'atol', 2))
Test Sequence//checkDiffPress:verify(ADCSensorBus.DiffPressureSensorBus.differential_pressure_pa > 0)

## **Simulation**

# **System Under Test Information**

Model: adc

Harness: adcTestHarness

Harness Owner: adc Release: Current

Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: adcTestHarness/Test Sequence

Test Sequence Scenario: Scenario\_1

Start Time: 0

Stop Time: 0.03200000000000001

Checksum: 2809421967 1308668717 4053094731 2792199182

## Simulation Logs:

Warning issued while simulating Model block 'adcTestHarness/adc'.

## **Back to Report Summary**

#### Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

## **Back to Report Summary**

## gps

#### **Test Result Information**

Result Type: Test Case Result Parent: Sensor Tests

Start Time: 19-Oct-2025 14:14:31 End Time: 19-Oct-2025 14:14:32

Outcome: Passed

#### **Test Case Information**

Name: gps

Type: Baseline Test

## Iteration1

## **Test Result Information**

Result Type: Test Iteration Result

Parent: gps

Start Time: 19-Oct-2025 14:14:31 End Time: 19-Oct-2025 14:14:32

Outcome: Passed

## **Test Case Information**

Name: Iteration1 Type: Baseline Test

## **Iteration Settings**

## **Test Overrides**

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

## **Verify Result**

Name		
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.lat_deg, referenceLatitude_deg))		
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.lon_deg, referenceLongitude_deg))		
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.alt_m, terrainHeightNED_m, 'atol', 0.5))		
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.vel_mps, 0, 'atol', 0.5))		
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.vel_n_mps, 0, 'atol', 0.5))		
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.vel_e_mps, 0, 'atol', 0.5))		
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.vel_d_mps, 0, 'atol', 0.5))		
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.lat_deg, referenceLatitude_deg))		
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.lon_deg, referenceLongitude_deg))		
☑ Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.alt_m, 3048 + terrainHeightNED_m))		
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.vel_mps, norm([10 20 30]), 'rtol', 0.8))		
☑ Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.vel_n_mps, 10, 'rtol', 0.1))		
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.vel_e_mps, 20, 'rtol', 0.1))		
▼ Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.vel_d_mps, 30, 'rtol', 0.1))		

#### **Simulation**

#### **System Under Test Information**

Model: gps

Harness: gpsTestHarness

Harness Owner: gps
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration
Test Sequence Block: gpsTestHarness/Test Sequence

Test Sequence Scenario: Scenario\_1

Start Time: 0
Stop Time: 0.016

Checksum: 1297848071 2767701485 3129243928 1222317831

#### Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

## **Back to Report Summary**

#### sensors

#### **Test Result Information**

Result Type: Test Case Result Parent: Sensor Tests

Start Time: 19-Oct-2025 14:14:32 End Time: 19-Oct-2025 14:14:33

Outcome: Passed

#### **Test Case Information**

Name: sensors

Type: Baseline Test

## Iteration1

## **Test Result Information**

Result Type: Test Iteration Result

Parent: sensors

Start Time: 19-Oct-2025 14:14:32 End Time: 19-Oct-2025 14:14:33

Outcome: Passed

#### **Test Case Information**

Name: Iteration1
Type: Baseline Test

## **Iteration Settings**

#### **Test Overrides**

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

#### **Simulation**

## **System Under Test Information**

Model: sensors

Harness: sensorsTestHarness

Harness Owner: sensors
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: sensorsTestHarness/Test Sequence

Test Sequence Scenario: Scenario\_1

Start Time: 0

Stop Time: 0.2000000000000001

Checksum: 3166609996 3451383475 1534701048 1753185450

Simulation Logs:

No data is logged for the model 'sensorsTestHarness'.

<u>'SensorsBus'</u> is defined, but is never used in the Test Sequence block. <u>Delete this object.</u>

Warning issued while simulating Model block 'sensorsTestHarness/sensors'.

## **Back to Report Summary**

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

**Back to Report Summary** 

#### environment

#### **Test Result Information**

Result Type: Test File Result

Parent: <u>Results: 2025-Oct-19 14:12:17</u>

Start Time: 19-Oct-2025 14:14:34 End Time: 19-Oct-2025 14:14:38 Outcome: Total: 3, Passed: 3

#### **Test Suite Information**

Name: environment

**Back to Report Summary** 

#### **Environment Tests**

#### **Test Result Information**

Result Type: Test Suite Result Parent: environment

Start Time: 19-Oct-2025 14:14:34 End Time: 19-Oct-2025 14:14:38 Outcome: Total: 3, Passed: 3

#### **Test Suite Information**

Name: Environment Tests

**Back to Report Summary** 

#### Air

#### **Test Result Information**

Result Type: Test Case Result
Parent: Environment Tests
Start Time: 19-Oct-2025 14:14:34
End Time: 19-Oct-2025 14:14:35

Outcome: Passed

#### **Test Case Information**

Name: Air

Type: Baseline Test

## Iteration1

#### **Test Result Information**

Result Type: Test Iteration Result

Parent: <u>Air</u>

Start Time: 19-Oct-2025 14:14:34 End Time: 19-Oct-2025 14:14:35

Outcome: Passed

#### **Test Case Information**

Name: Iteration1
Type: Baseline Test

## **Iteration Settings**

#### **Test Overrides**

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

## **Verify Result**

Name
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.windSpeedInNED_mps(1), 4))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.windSpeedInNED_mps(2), 3))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.windSpeedInNED_mps(3), 2))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.airTemperature_K, 288.15))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.airPressure_Pa, 1.01325e5))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.airDensity_kgpm3, 1.225))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.speedOfSound_mps, 340.29412435))

#### **Simulation**

## **System Under Test Information**

Model: Air

Harness: AirTestHarness

Harness Owner: Air

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: AirTestHarness/Test Sequence

Test Sequence Scenario: Scenario\_1

Start Time: 0

Stop Time: 3.004

Checksum: 2333579960 118194984 3293710571 2811700376

#### Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

#### **Back to Report Summary**

#### Earth

#### **Test Result Information**

Result Type: Test Case Result
Parent: Environment Tests
Start Time: 19-Oct-2025 14:14:35
End Time: 19-Oct-2025 14:14:37

Outcome: Passed

#### **Test Case Information**

Name: Earth

Type: Baseline Test

#### Iteration1

#### **Test Result Information**

Result Type: Test Iteration Result

Parent: Earth

Start Time: 19-Oct-2025 14:14:35 End Time: 19-Oct-2025 14:14:37 Outcome: Passed

#### **Test Case Information**

Name: Iteration1
Type: Baseline Test

## **Iteration Settings**

#### **Test Overrides**

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

## **Verify Result**

Name

Test Sequence1/.../verifyAircraftZChange:verify(gravLow\_mps2 > EarthEnvironmentBus.gravityScalar\_mps2)

#### **Simulation**

## **System Under Test Information**

Model: Earth

Harness: EarthTestHarness

Harness Owner: Earth Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: EarthTestHarness/Test Sequence1

Test Sequence Scenario: Scenario\_1

Start Time: 0 Stop Time: 7

Checksum: 1175429799 1798864983 927034458 1191542450

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

## **Back to Report Summary**

## LocalTerrain

#### **Test Result Information**

Result Type: Test Case Result
Parent: Environment Tests
Start Time: 19-Oct-2025 14:14:37
End Time: 19-Oct-2025 14:14:38

Outcome: Passed

#### **Test Case Information**

Name: LocalTerrain Type: Baseline Test

## Iteration1

#### **Test Result Information**

Result Type: Test Iteration Result

Parent: LocalTerrain

Start Time: 19-Oct-2025 14:14:37 End Time: 19-Oct-2025 14:14:38

Outcome: Passed

#### **Test Case Information**

Name: Iteration1
Type: Baseline Test

## **Iteration Settings**

#### **Test Overrides**

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

#### **Simulation**

# System Under Test Information

Model: LocalTerrain

Harness: LocalTerrainTestHarness

Harness Owner: LocalTerrain

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: LocalTerrainTestHarness/Test Sequence

Test Sequence Scenario: Scenario\_1

Start Time: 0

Checksum: 1661112760 514905542 80377983 1575265004

## Simulation Logs:

No data is logged for the model 'LocalTerrainTestHarness'.

<u>'TerrainEnvironmentBus'</u> is defined, but is never used in the Test Sequence block. <u>Delete this object.</u>

## **Back to Report Summary**

#### Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary