Report Generated by Test Manager

Title: Branch: 1-hexarotorModelAddition

Author: Previous Commit Hash: 78160a19360e77

63db602dd690dd524f1cd25b5a

Date: 06-May-2025 13:46:52

Test Environment

Platform: PCWIN64 MATLAB: (R2024a)

Summary

Summar y		.
Name	Outcome	Duration (Seconds)
Results: 2025-May-06 13:42:14	16 🕏	161.581
□ <u>F16</u>	9 🕗	147.038
□ <u>Vehicle Tests</u>	9 🕢	147.039
actuators actuators	•	7.306
I <u>Iteration1</u>	•	7.305
aero aero	•	2.27
I <u>Iteration1</u>	•	2.27
ground contact	•	1.381
inertial dynamics	•	1.584
I <u>Iteration1</u>	•	1.584
vehicle vehicle	•	7.79
I <u>Iteration1</u>	•	7.791
engine	•	16.039
addFM	•	0.941
I <u>Iteration1</u>	⊘	0.942
gravity	⊘	0.881
FullSIL	⊘	107.321
sensors sensors	4 🗸	6.763
Sensor Tests	4 🗸	6.762
ins ins	⊘	1.872
I <u>Iteration1</u>	⊘	1.872
adc adc	•	1.075
I <u>Iteration1</u>	•	1.074
■ gps	•	1.074
I <u>Iteration1</u>	⊘	1.074

sensors sensors	Ø	2.489
I <u>Iteration1</u>	⊘	2.489
<u>environment</u>	3 🗸	4.495
Environment Tests	3 🗸	4.495
Air	②	1.368
I <u>Iteration1</u>	•	1.369
Earth	•	2.219
I <u>Iteration1</u>	•	2.22
LocalTerrain	•	0.729
I <u>Iteration1</u>	•	0.728

Results: 2025-May-06 13:42:14

Result Type: Result Set Parent: None

Start Time: 06-May-2025 13:42:16 End Time: 06-May-2025 13:44:57 Outcome: Total: 16, Passed: 16

Back to Report Summary

F16

Test Result Information

Result Type: Test File Result

Parent: Results: 2025-May-06 13:42:14

Start Time: 06-May-2025 13:42:16 End Time: 06-May-2025 13:44:43 Outcome: Total: 9, Passed: 9

Test Suite Information

Name: F16

Back to Report Summary

Vehicle Tests

Test Result Information

Result Type: Test Suite Result

Parent: <u>F16</u>

Start Time: 06-May-2025 13:42:16 End Time: 06-May-2025 13:44:43 Outcome: Total: 9, Passed: 9

Test Suite Information

Name: Vehicle Tests

Back to Report Summary

actuators

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 06-May-2025 13:42:16 End Time: 06-May-2025 13:42:23

Outcome: Passed

Test Case Information

Name: actuators Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: <u>actuators</u>

Start Time: 06-May-2025 13:42:16 End Time: 06-May-2025 13:42:23

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Verify Result

5	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.angVel_radps, 0))
	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.forcesInBody_N(1)
) <u>.</u>	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.forcesInBody_N(2
)	Test sequence//vernyControllerDisarmed:vernytisClose(actuatorвus.Propulsionвus.engineForcesMoments.torcesmbody_N(z)
(Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.forcesInBody_N(3
))
r	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.momentsInBody_n(1), 0))
(Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.momentsInBody_
r	n(2), 0))
	Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.momentsInBody_n(3), 0))
(Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posAileron_rad,0))
(Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posElevator_rad,0))
(Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posRudder_rad,0))
(Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.angVel_radps, 0))
(Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.forcesInBody_N(1),
	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.forcesInBody_N(2),
Ę	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.forcesInBody_N(3),
	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.momentsInBody_Nr
,	0))
Ę	🛂 Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.momentsInBody_Nr
,	0))
	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.PropulsionBus.engineForcesMoments.momentsInBody_Nr
,	0))
	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posAileron_rad,0))
	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posElevator_rad,0))
	Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posRudder_rad,0))
	Test Sequence//verifyAileronRate:verify(aileronCmdRate <= aileronDeflRateLimit_degps)
(Test Sequence//verifyAileronLimit:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posAileron_rad, deg2rad(maxAilDefl_
٦.))
(Test Sequence//verifyNegAileronRate:verify(abs(aileronCmdRate) <= aileronDeflRateLimit_degps)
(Test Sequence//verifyNegAileronLimit:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posAileron_rad, -deg2rad(maxAil
-	.deg)))
-	Test Sequence//verifyElevatorRate:verify(elevatorCmdRate <= elevatorDeflRateLimit_degps)
	🋂 Test Sequence//verifyElevatorLimit:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posElevator_rad, deg2rad(maxEleva
L	Oefl_deg)))

Test Sequence//verifyNegElevatorRate:verify(abs(elevatorCmdRate) <= elevatorDeflRateLimit_degps)
Test Sequence//verifyNegElevatorLimit:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posElevator_rad, -deg2rad(maxElev
atorDefl_deg)))
Test Sequence//verifyRudderRate:verify(rudderCmdRate <= rudderDeflRateLimit_degps)
Test Sequence//verifyRudderMax:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posRudder_rad, deg2rad(maxRudderDefl_i
deg)))
Test Sequence//verifyNegRudderRate:verify(abs(rudderCmdRate) <= rudderDeflRateLimit_degps)
Test Sequence//verifyNegRudderMax:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posRudder_rad, -deg2rad(maxRudder_
Defl_deg)))

Simulation

System Under Test Information

Model: actuators

Harness: actuatorsTestHarness

Harness Owner: actuators
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: actuatorsTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 19.02400000000001

Checksum: 3551365890 3866025449 360308160 3413791725

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

aero

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 06-May-2025 13:42:23 End Time: 06-May-2025 13:42:25

Outcome: Passed

Test Case Information

Name: aero

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: <u>aero</u>

Start Time: 06-May-2025 13:42:23 End Time: 06-May-2025 13:42:25

Outcome: Passed

Test Case Information

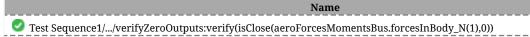
Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value	
TestSequenceScena	Scenario_1	
rio		

Verify Result



Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.forcesInBody_N(2),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.forcesInBody_N(3),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(1),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(2),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(3),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.airspeedInBody_mps(1),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.airspeedInBody_mps(2),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.airspeedInBody_mps(3),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.alpha_rad,0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.beta_rad,0))	
Test Sequence1//verifyAirspeed:verify(aeroForcesMomentsBus.forcesInBody_N(1) < 0)	
Test Sequence1//verifyAirspeed:verify(isClose(aeroForcesMomentsBus.forcesInBody_N(2),0))	
Test Sequence1//verifyAirspeed:verify(aeroForcesMomentsBus.forcesInBody_N(3) < -20500 * lbf2N)	
Test Sequence1//verifyAirspeed:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(1),0))	
Test Sequence1//verifyAirspeed:verify(aeroForcesMomentsBus.momentsInBody_Nm(2) < 0)	
Test Sequence1//verifyAirspeed:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(3),0))	
Test Sequence1//verifyAirspeed:verify(isClose(airDataBus.airspeedInBody_mps(2),0))	
Test Sequence1//verifyAirspeed:verify(isClose(airDataBus.airspeedInBody_mps(3),0))	
Test Sequence1//verifyAirspeed:verify(isClose(airDataBus.alpha_rad,0))	
Test Sequence1//verifyAirspeed:verify(isClose(airDataBus.beta_rad,0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(aeroForcesMomentsBus.forcesInBody_N(2),0))	
Test Sequence1//verifyElevatorDeflection:verify(aeroForcesMomentsBus.forcesInBody_N(3) > cruiseZForce)	
Test Sequence1//verifyElevatorDeflection:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(1),0))	
Test Sequence1//verifyElevatorDeflection:verify(aeroForcesMomentsBus.momentsInBody_Nm(2) > cruiseYMoment)	
Test Sequence1//verifyElevatorDeflection:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(3),0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(airDataBus.airspeedInBody_mps(2),0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(airDataBus.airspeedInBody_mps(3),0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(airDataBus.alpha_rad,0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(airDataBus.beta_rad,0))	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.forcesInBody_N(2) > 0)	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.forcesInBody_N(3) < 0)	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.momentsInBody_Nm(1) > 0)	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.momentsInBody_Nm(2) < 0)	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.momentsInBody_Nm(3) < 0)	
Test Sequence1//verifyRudder:verify(isClose(airDataBus.airspeedInBody_mps(2),0))	
Test Sequence1//verifyRudder:verify(isClose(airDataBus.airspeedInBody_mps(3),0))	
Test Sequence1//verifyRudder:verify(isClose(airDataBus.alpha_rad,0))	

Test Sequence1//verifyRudder:verify(isClose(airDataBus.beta_rad,0))	
Test Sequence1//verifyAileron:verify(aeroForcesMomentsBus.momentsInBody_Nm(1) < 0)	İ
Test Sequence1//verifyAileron:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(2),cruiseYMoment))	İ
Test Sequence1//verifyAileron:verify(aeroForcesMomentsBus.momentsInBody_Nm(3) < 0)	İ
Test Sequence1//verifyAileron:verify(isClose(airDataBus.alpha_rad,0))	i
Test Sequence1//verifyAileron:verify(isClose(airDataBus.beta_rad,0))	į

Simulation

System Under Test Information

Model: aero

Harness: aeroTestHarness

Harness Owner: aero
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: aeroTestHarness/Test Sequence1

Test Sequence Scenario: Scenario_1

Start Time: 0 Stop Time: 22

Checksum: 2130377790 4206039669 1741698970 285533330

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

ground contact

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 06-May-2025 13:42:26 End Time: 06-May-2025 13:42:27

Outcome: Passed

Test Case Information

Name: ground contact Type: Baseline Test

Verify Result

Name
Test Sequence1//verifyInitialization:verify(isVehicleAirborne == 0)
Test Sequence1//verifyInitialization:verify(groundCollision == 0)
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1),0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2),0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3),0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(1), 0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(2), 0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(3), 0))
Test Sequence1//verifyStationary:verify(isVehicleAirborne == 0)
Test Sequence1//verifyStationary:verify(groundCollision == 0)
☑ Test Sequence1//verifyStationary:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1), 0))
Test Sequence1//verifyStationary:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2), 0))
☑ Test Sequence1//verifyStationary:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3), -9298.6 * 9.81))
Test Sequence1//verifyStationary:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(1), 0))
Test Sequence1//verifyStationary:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(2), 0))
Test Sequence1//verifyStationary:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(3), 0))
Test Sequence1//verifyFastTaxi:verify(isVehicleAirborne == 0)
Test Sequence1//verifyFastTaxi:verify(groundCollision == 0)
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1), 0))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2), 0))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3), -9298.6 * 9.81 + 20000))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(1),0))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(2),0))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(3),0))
Test Sequence1//verifyFastTaxi:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(1), 0))

Test Sequence1//verifyFastTaxi:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(2), 0))	
✓ Test Sequence1//verifyFastTaxi:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(3), 0))	
Test Sequence1//verifyRotate:verify(isVehicleAirborne == 0)	
✓ Test Sequence1//verifyRotate:verify(groundCollision == 0)	
■ Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1), 0))	
■ Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2), 0))	
■ Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3), -9298.6 * 9.81 + 20000))	
☑ Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(1),0))	
☑ Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(2),0))	
✓ Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(3),0))	
☑ Test Sequence1//verifyRotate:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(1), 0))	
☑ Test Sequence1//verifyRotate:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(2), 0))	
Test Sequence1//verifyRotate:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(3), 0))	
Test Sequence1//verifyTakeoff:verify(isVehicleAirborne == 1)	
Test Sequence1//verifyTakeoff:verify(groundCollision == 0)	
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1), 0))	
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2), 0))	
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3), 0))	
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(1),0))	
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(2),0))	
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(3),0))	
Test Sequence1//verifyTakeoff:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(1), 0))	
Test Sequence1//verifyTakeoff:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(2), 0))	
☑ Test Sequence1//verifyTakeoff:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(3), 0))	

Simulation

System Under Test Information

Model: groundContact

Harness: groundContactTestHarness

Harness Owner: groundContact

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: groundContactTestHarness/Test Sequence1

Test Sequence Scenario: Scenario_2

Start Time: 0 Stop Time: 2.028

Checksum: 1244405978 4079976263 897553408 2782662889

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

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inertial dynamics

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 06-May-2025 13:42:27 End Time: 06-May-2025 13:42:29

Outcome: Passed

Test Case Information

Name: inertial dynamics Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result
Parent: <u>inertial dynamics</u>
Start Time: 06-May-2025 13:42:27
End Time: 06-May-2025 13:42:29

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Verify Result

Name
Test Sequence1//Test1:verify(isClose(bodyStatesBus.aircraftPosInNED_m(1), 0.5*interval_time^2*aircraftForcesInNED_N(1)/aircr
aftMass + aircraftInitialPosInNED_m(1)))
Test Sequence1//Test1:verify(isClose(bodyStatesBus.aircraftVelInBody_mps(1), interval_time*aircraftForcesMomentsBus_forcesI
nBody_N(1)/aircraftMass + aircraftInitialVelInBody_mps(1)))
Test Sequence1//Test1:verify(isClose(bodyStatesBus.aircraftAccelInBody_mps2(1),aircraftForcesMomentsBus_forcesInBody_N(1)
/aircraftMass))

Simulation

System Under Test Information

Model: inertialDynamics

Harness: inertialDynamicsTestHarness

Harness Owner: inertialDynamics

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: inertialDynamicsTestHarness/Test Sequence1

Test Sequence Scenario: Scenario_1

Start Time: 0 Stop Time: 1.008

Checksum: 2740628208 4264647383 940722363 2610557463

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

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vehicle

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 06-May-2025 13:42:29 End Time: 06-May-2025 13:42:37

Outcome: Passed

Test Case Information

Name: vehicle

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: vehicle

Start Time: 06-May-2025 13:42:29 End Time: 06-May-2025 13:42:37

Outcome: Passed

Test Case Information

Name: Iteration1

Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Verify Result

Name
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(1), 0))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(1),0))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2),0))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(3),0))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(1), 0))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(1),0))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2),0))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(3),0))
Test Sequence//verifyThrottle:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0))
Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0))
Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(1),0))
Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2),0))
Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(3),0))
Test Sequence//verifyPitchIntoGround:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2), 0))
Test Sequence//verifyPitchIntoGround:verify(isClose(vehicleBus.BodyStates.aircraftEulerAngles_rad(2), 0))
Test Sequence//verifyPitchIntoGround:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0))
Test Sequence//verifyPitchIntoGround:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
Test Sequence//verifyPitchIntoGround:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0))
Test Sequence//verifydeflectElevator:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2), 0, 'absTol', 0.01))
Test Sequence//verifydeflectElevator:verify(isClose(vehicleBus.BodyStates.aircraftEulerAngles_rad(2), 0, 'absTol', 0.01))
Test Sequence//verifydeflectElevator:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0, 'absTol', 0.01))

Test Sequence//verifydeflectElevator:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
Test Sequence//verifydeflectElevator:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0))
Test Sequence//verifyRotate:verify(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2) > 0)
Test Sequence//verifyRotate:verify(vehicleBus.BodyStates.aircraftEulerAngles_rad(2) > 0)
Test Sequence//verifyRotate:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(3) < 0)
Test Sequence//verifyRotate:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
Test Sequence//verifyRotate:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0))
☑ Test Sequence//verifyFlying:verify(vehicleBus.BodyStates.aircraftPosInNED_m(3) < 0)
Test Sequence//verifyFlying:verify(vehicleBus.BodyStates.aircraftEulerAngles_rad(2) > 0)
Test Sequence//verifyFlying:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
Test Sequence//verifyFlying:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0))

Simulation

System Under Test Information

Model: F16

Harness: F16TestHarness

Harness Owner: F16
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration
Test Sequence Block: F16TestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 86.0199999999999

Checksum: 2148526880 2300801512 3029300974 1731738160

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

engine

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 06-May-2025 13:42:37 End Time: 06-May-2025 13:42:53

Outcome: Passed

Test Case Information

Name: engine

Type: Baseline Test

Verify Result

Name
Test Sequence//verifyControllerDisarm:verify(isClose(engineBus.engineForcesMoments.forcesInBody_N(1),0))
Test Sequence//verifyThorttle:verify(isClose(thrust_lbf, engineBus.engineForcesMoments.forcesInBody_N(1), 'atol', 1))
☑ Test Sequence//verifyMaxThrust:verify(engineBus.engineForcesMoments.forcesInBody_N(1) < 130000)
Test Sequence//verifyMaxThrust:verify(isClose(thrust_lbf, engineBus.engineForcesMoments.forcesInBody_N(1), 'atol', 1))
Test Sequence//verifyWithAirspeed:verify(isClose(thrust_lbf, engineBus.engineForcesMoments.forcesInBody_N(1), 'atol', 1))
Test Sequence//verifyIncreaseAirspeed:verify(isClose(thrust_lbf, engineBus.engineForcesMoments.forcesInBody_N(1), 'atol', 1))
Test Sequence//verifyIncreaseAltitude:verify(isClose(thrust_lbf, engineBus.engineForcesMoments.forcesInBody_N(1), 'atol', 1))

Simulation

System Under Test Information

Model: engineModelF16

Harness: engineModelF16TestHarness

Harness Owner: engineModelF16

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: engineModelF16TestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 38.00399999999998

Checksum: 3851107531 2498933023 2409488687 3277808361

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

addFM

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 06-May-2025 13:42:53 End Time: 06-May-2025 13:42:54

Outcome: Passed

Test Case Information

Name: addFM

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: addFM

Start Time: 06-May-2025 13:42:53 End Time: 06-May-2025 13:42:54

Outcome: Passed

Test Case Information

Name: Iteration1 Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Verify Result

Name
Test Sequence1//Test1:verify(all(isClose(aircraftForcesMomentsBus.forcesInBody_N, aeroForcesMomentsBus.forcesInBody_N + e
ngineForcesMomentsBus.forcesInBody_N + groundForcesMomentsBus.forcesInBody_N + weightForcesMomentsBus.forcesInBody_N)
))
Test Sequence1//Test1:verify(all(isClose(aircraftForcesMomentsBus.momentsInBody_Nm, engineForcesMomentsBus.momentsIn
Body_Nm + aeroForcesMomentsBus.momentsInBody_Nm + weightForcesMomentsBus.momentsInBody_Nm)))
Test Sequence1//Test2:verify(all(isClose(aircraftForcesMomentsBus.forcesInBody_N, aeroForcesMomentsBus.forcesInBody_N + e
ngineForcesMomentsBus.forcesInBody_N + groundForcesMomentsBus.forcesInBody_N + weightForcesMomentsBus.forcesInBody_N)
))
Test Sequence1//Test2:verify(all(isClose(aircraftForcesMomentsBus.momentsInBody_Nm, aeroForcesMomentsBus.momentsInB
ody_Nm + engineForcesMomentsBus.momentsInBody_Nm + weightForcesMomentsBus.momentsInBody_Nm)))
Test Sequence1//verifyPitchIntoGround:verify(all(isClose(aircraftForcesMomentsBus.forcesInBody_N, aeroForcesMomentsBus.f
orcesInBody_N + engineForcesMomentsBus.forcesInBody_N + groundForcesMomentsBus.forcesInBody_N + weightForcesMomentsBu
s.forcesInBody_N)))
Test Sequence1//verifyPitchIntoGround:verify(isClose(aircraftForcesMomentsBus.momentsInBody_Nm(1), 0))
Test Sequence1//verifyPitchIntoGround:verify(isClose(aircraftForcesMomentsBus.momentsInBody_Nm(2), engineForcesMomen
tsBus.momentsInBody_Nm(2) + aeroForcesMomentsBus.momentsInBody_Nm(2) + weightForcesMomentsBus.momentsInBody_Nm(2)
))
Test Sequence1//verifyPitchIntoGround:verify(isClose(aircraftForcesMomentsBus.momentsInBody_Nm(3), engineForcesMomen
tsBus.momentsInBody_Nm(3) + aeroForcesMomentsBus.momentsInBody_Nm(3) + weightForcesMomentsBus.momentsInBody_Nm(3)

Simulation

System Under Test Information

Model: addFM

Harness: addFMTestHarness

Harness Owner: addFM Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: addFMTestHarness/Test Sequence1

Test Sequence Scenario: Scenario_1

Start Time: 0 Stop Time: 3.016

Checksum: 2405791290 3021241631 2400769033 306058281

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

gravity

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 06-May-2025 13:42:54 End Time: 06-May-2025 13:42:55

Outcome: Passed

Test Case Information

Name: gravity

Type: Baseline Test

Verify Result

Name
Test Sequence1//Test1:verify(isClose(weightForcesMoments.forcesInBody_N(1), 0))
☑ Test Sequence1//Test1:verify(isClose(weightForcesMoments.forcesInBody_N(2), 0))
☑ Test Sequence1//Test1:verify(isClose(weightForcesMoments.forcesInBody_N(3), weight_N))
☑ Test Sequence1//Test1:verify(isClose(sum(weightForcesMoments.momentsInBody_Nm(1:3)), 0))
☑ Test Sequence1//Test2:verify(isClose(weightForcesMoments.forcesInBody_N(1), -weight_N * sin(pitch_rad)))
Test Sequence1//Test2:verify(isClose(weightForcesMoments.forcesInBody_N(2), 0))
☑ Test Sequence1//Test2:verify(isClose(weightForcesMoments.forcesInBody_N(3), weight_N * cos(pitch_rad)))
Test Sequence1//Test2:verify(isClose(sum(weightForcesMoments.momentsInBody_Nm(1:3)), 0))
Test Sequence1//Test3:verify(isClose(weightForcesMoments.forcesInBody_N(1), -weight_N * sin(pitch_rad)))
Test Sequence1//Test3:verify(isClose(weightForcesMoments.forcesInBody_N(2), weight_N * sin(roll_rad) * cos(pitch_rad)))
Test Sequence1//Test3:verify(isClose(weightForcesMoments.forcesInBody_N(3), weight_N * cos(roll_rad) * cos(pitch_rad)))
Test Sequence1//Test3:verify(isClose(sum(weightForcesMoments.momentsInBody_Nm(1:3)), 0))

Simulation

System Under Test Information

Model: gravity

Harness: gravityTestHarness

Harness Owner: gravity
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: gravityTestHarness/Test Sequence1

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 0.02800000000000001

Checksum: 371801570 4075467097 1945074898 1201465379

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

FullSIL

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 06-May-2025 13:42:55 End Time: 06-May-2025 13:44:43

Outcome: Passed

Test Case Information

Name: FullSIL

Type: Baseline Test

Simulation

System Under Test Information

Model: VehiclePlant

Harness: VehiclePlantTestHarness

Harness Owner: VehiclePlant Release: Current simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Start Time: 0

Stop Time: 280.0040000000002

Checksum: 1695921845 2707608492 535225901 2273894730

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

sensors

Test Result Information

Result Type: Test File Result

Parent: <u>Results: 2025-May-06 13:42:14</u>

Start Time: 06-May-2025 13:44:43 End Time: 06-May-2025 13:44:50 Outcome: Total: 4, Passed: 4

Test Suite Information

Name: sensors

Back to Report Summary

Sensor Tests

Test Result Information

Result Type: Test Suite Result

Parent: sensors

Start Time: 06-May-2025 13:44:43 End Time: 06-May-2025 13:44:50 Outcome: Total: 4, Passed: 4

Test Suite Information

Name: Sensor Tests

Back to Report Summary

ins

Test Result Information

Result Type: Test Case Result Parent: Sensor Tests

Start Time: 06-May-2025 13:44:43 End Time: 06-May-2025 13:44:45

Outcome: Passed

Test Case Information

Name: ins

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: ins

Start Time: 06-May-2025 13:44:43 End Time: 06-May-2025 13:44:45

Outcome: Passed

Test Case Information

Name: Iteration1 Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Verify Result

Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.GyroSensorBus.x_radps, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.GyroSensorBus.y_radps, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.GyroSensorBus.z_radps, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.AccelSensorBus.x_mps2, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.AccelSensorBus.y_mps2, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.AccelSensorBus.z_mps2, 0, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.GyroSensorBus.x_radps, 0.1, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.GyroSensorBus.y_radps, 0.2, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.GyroSensorBus.z_radps, 0.3, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.MagSensorBus.x_Gauss, 0, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.MagSensorBus.y_Gauss, 0, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.MagSensorBus.z_Gauss, 0, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.AccelSensorBus.x_mps2, 1, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.AccelSensorBus.y_mps2, 2, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.AccelSensorBus.z_mps2, 3, 'atol', 0.01))

Simulation

System Under Test Information

Model: ins

Harness: insTestHarness

Harness Owner: ins

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration
Test Sequence Block: insTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 10.00800000000001

Checksum: 3180580520 4092729406 197588729 847202452

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

adc

Test Result Information

Result Type: Test Case Result Parent: Sensor Tests

Start Time: 06-May-2025 13:44:45 End Time: 06-May-2025 13:44:46

Outcome: Passed

Test Case Information

Name: adc

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: adc

Start Time: 06-May-2025 13:44:45 End Time: 06-May-2025 13:44:46

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name Value

TestSequenceScena	Scenario_1
rio	

Verify Result

Name
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.BaroSensorBus.altitude_m, 0, 'atol', 20))
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.BaroSensorBus.pressure_pa, 101325, 'atol', 100))
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.BaroSensorBus.temperature_degC, 15, 'atol', 2))
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.DiffPressureSensorBus.differential_pressure_pa, 0, 'atol', 100))
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.DiffPressureSensorBus.temperature_degC, 15, 'atol', 2))
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.BaroSensorBus.altitude_m, 3048, 'atol', 20))
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.BaroSensorBus.pressure_pa, 69681.66, 'atol', 100))
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.BaroSensorBus.temperature_degC, -4.8, 'atol', 2))
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.DiffPressureSensorBus.differential_pressure_pa, 0, 'atol', 100))
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.DiffPressureSensorBus.temperature_degC, -4.8, 'atol', 2))
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.BaroSensorBus.altitude_m, 6096, 'atol', 20))
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.BaroSensorBus.pressure_pa, 46563.26, 'atol', 100))
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.BaroSensorBus.temperature_degC, -24.624, 'atol', 2))
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.DiffPressureSensorBus.differential_pressure_pa, 0, 'atol', 100))
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.DiffPressureSensorBus.temperature_degC, -24.624, 'atol', 2))
Test Sequence//checkDiffPress:verify(ADCSensorBus.DiffPressureSensorBus.differential_pressure_pa > 0)

Simulation

System Under Test Information

Model: adc

Harness: adcTestHarness

Harness Owner: adc
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration
Test Sequence Block: adcTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 0.03200000000000001

Checksum: 2809421967 1308668717 4053094731 2792199182

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

gps

Test Result Information

Result Type: Test Case Result Parent: Sensor Tests

Start Time: 06-May-2025 13:44:46 End Time: 06-May-2025 13:44:47

Outcome: Passed

Test Case Information

Name: gps

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: gps

Start Time: 06-May-2025 13:44:46 End Time: 06-May-2025 13:44:47

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Verify Result

Name
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.lat_deg, referenceLatitude_deg))
▼ Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.lon_deg, referenceLongitude_deg))
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.alt_m, terrainHeightNED_m, 'atol', 0.5))
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.vel_mps, 0, 'atol', 0.5))
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.vel_n_mps, 0, 'atol', 0.5))
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.vel_e_mps, 0, 'atol', 0.5))
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.vel_d_mps, 0, 'atol', 0.5))
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.lat_deg, referenceLatitude_deg))
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.lon_deg, referenceLongitude_deg))
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.alt_m, 3048 + terrainHeightNED_m))
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.vel_mps, norm([10 20 30]), 'rtol', 0.8))
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.vel_n_mps, 10, 'rtol', 0.1))
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.vel_e_mps, 20, 'rtol', 0.1))
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.vel_d_mps, 30, 'rtol', 0.1))

Simulation

System Under Test Information

Model: gps

Harness: gpsTestHarness

Harness Owner: gps
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration
Test Sequence Block: gpsTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0 Stop Time: 0.016

Checksum: 1261040433 1750074340 274485945 283260561

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

sensors

Test Result Information

Result Type: Test Case Result Parent: Sensor Tests

Start Time: 06-May-2025 13:44:48 End Time: 06-May-2025 13:44:50

Outcome: Passed

Test Case Information

Name: sensors

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: <u>sensors</u>

Start Time: 06-May-2025 13:44:48 End Time: 06-May-2025 13:44:50

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Simulation

System Under Test Information

Model: sensors

Harness: sensorsTestHarness

Harness Owner: sensors
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: sensorsTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 0.2000000000000001

Checksum: 3685639760 4247597233 3511659855 3311356939

Simulation Logs:

No data is logged for the model 'sensorsTestHarness'.

Back to Report Summary

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

environment

Test Result Information

Result Type: Test File Result

Parent: <u>Results: 2025-May-06 13:42:14</u>

Start Time: 06-May-2025 13:44:51 End Time: 06-May-2025 13:44:55 Outcome: Total: 3, Passed: 3

Test Suite Information

Name: environment

Back to Report Summary

Environment Tests

Test Result Information

Result Type: Test Suite Result Parent: environment

Start Time: 06-May-2025 13:44:51 End Time: 06-May-2025 13:44:55 Outcome: Total: 3, Passed: 3

Test Suite Information

Name: Environment Tests

Back to Report Summary

Air

Test Result Information

Result Type: Test Case Result
Parent: Environment Tests
Start Time: 06-May-2025 13:44:51
End Time: 06-May-2025 13:44:52

Outcome: Passed

Test Case Information

Name: Air

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: Air

Start Time: 06-May-2025 13:44:51 End Time: 06-May-2025 13:44:52

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Verify Result

Name
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.windSpeedInNED_mps(1), 4))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.windSpeedInNED_mps(2), 3))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.windSpeedInNED_mps(3), 2))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.airTemperature_K, 288.15))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.airPressure_Pa, 1.01325e5))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.airDensity_kgpm3, 1.225))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.speedOfSound_mps, 340.29412435))

Simulation

System Under Test Information

Model: Air

Harness: AirTestHarness

Harness Owner: Air Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration
Test Sequence Block: AirTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0 Stop Time: 3.004

Checksum: 2333579960 118194984 3293710571 2811700376

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

Earth

Test Result Information

Result Type: Test Case Result
Parent: Environment Tests
Start Time: 06-May-2025 13:44:52
End Time: 06-May-2025 13:44:54

Outcome: Passed

Test Case Information

Name: Earth

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: <u>Earth</u>

Start Time: 06-May-2025 13:44:52 End Time: 06-May-2025 13:44:54

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

	0.01011000	
Parameter Name	Value	
TestSequenceScena	Scenario_1	
rio		

Verify Result



Simulation

System Under Test Information

Model: Earth

Harness: EarthTestHarness

Harness Owner: Earth Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: EarthTestHarness/Test Sequence1

Test Sequence Scenario: Scenario_1

Start Time: 0 Stop Time: 7

Checksum: 1175429799 1798864983 927034458 1191542450

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

LocalTerrain

Test Result Information

Result Type: Test Case Result
Parent: Environment Tests
Start Time: 06-May-2025 13:44:54
End Time: 06-May-2025 13:44:55

Outcome: Passed

Test Case Information

Name: LocalTerrain Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: <u>LocalTerrain</u>

Start Time: 06-May-2025 13:44:54 End Time: 06-May-2025 13:44:55

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Simulation

System Under Test Information

Model: LocalTerrain

Harness: LocalTerrainTestHarness

Harness Owner: LocalTerrain
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: LocalTerrainTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: Checksum: 0.00400000000000000001

3805200661 3804672667 1828039431 394193071

Simulation Logs: No data is logged for the model 'LocalTerrainTestHarness'.

Back to Report Summary

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary