Report Generated by Test Manager

Title: Branch: fatal: ambiguous argument 'HE

AD': unknown revision or path not in the working tree. Use '--' to separate paths from revisions, like this: 'git <command

> [<revision>...] -- [<file>...]' HEAD

Author: Previous Commit Hash: fatal: ambiguou

s argument 'HEAD': unknown revision o r path not in the working tree. Use '--' to separate paths from revisions, like this: 'git <command> [<revision>...] -- [<file>...

]' HEAD

Date: 05-Mar-2025 09:19:15

Test Environment

Platform: PCWIN64 MATLAB: (R2024a)

Summary

	Duration
Outcome	(Seconds)
16 🕏	183.718
9 🥥	171.287
9 🕗	171.287
Ø	7.686
Ø	7.686
•	2.266
•	2.267
•	1.415
⊘	1.553
•	1.553
•	8.375
•	8.374
•	18.931
•	0.937
•	0.937
②	0.872
⊘	127.639
4 🕏	5.154
4 🕏	5.155
•	1.201
•	1.201
•	1.082
•	1.082
•	1.002
Ø	1.002
	16 © 9 © 9 © 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

sensors sensors	\bigcirc	1.616
I <u>Iteration1</u>	Ø	1.615
environment environment	3 🕗	4.369
Environment Tests	3 🕗	4.369
Air	Ø	1.007
I <u>Iteration1</u>	Ø	1.007
Earth	Ø	2.23
I <u>Iteration1</u>	Ø	2.231
LocalTerrain	Ø	0.943
I <u>Iteration1</u>	Ø	0.943

Results: 2025-Mar-05 09:16:09

Result Type: Result Set Parent: None

Start Time: 05-Mar-2025 09:16:11 End Time: 05-Mar-2025 09:19:15 Outcome: Total: 16, Passed: 16

Back to Report Summary

F16

Test Result Information

Result Type: Test File Result

Parent: Results: 2025-Mar-05 09:16:09

Start Time: 05-Mar-2025 09:16:11 End Time: 05-Mar-2025 09:19:02 Outcome: Total: 9, Passed: 9

Test Suite Information

Name: F16

Back to Report Summary

Vehicle Tests

Test Result Information

Result Type: Test Suite Result

Parent: <u>F16</u>

Start Time: 05-Mar-2025 09:16:11 End Time: 05-Mar-2025 09:19:02 Outcome: Total: 9, Passed: 9

Test Suite Information

Name: Vehicle Tests

Back to Report Summary

actuators

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 05-Mar-2025 09:16:11 End Time: 05-Mar-2025 09:16:19

Outcome: Passed

Test Case Information

Name: actuators Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: <u>actuators</u>

Start Time: 05-Mar-2025 09:16:11 End Time: 05-Mar-2025 09:16:19

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

1 Cot O VCI I I u Co		
Parameter Name	Value	
TestSequenceScena	Scenario_1	
rio		

Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.EngineBus.angVel_radps, 0))	
Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.EngineBus.engineForcesMoments.forcesInBody_N(1), 0))
Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.EngineBus.engineForcesMoments.forcesInBody_N(2), 0))
Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.EngineBus.engineForcesMoments.forcesInBody_N(3), 0))
Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.EngineBus.engineForcesMoments.momentsInBody_Nm((1),
0))	
Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.EngineBus.engineForcesMoments.momentsInBody_Nm((2),
0))	
Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.EngineBus.engineForcesMoments.momentsInBody_Nm((3),
0))	
Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posAileron_rad,0))	
Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posElevator_rad,0))	
Test Sequence//verifyControllerDisarmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posRudder_rad,0))	
Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.EngineBus.angVel_radps, 0))	
Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.EngineBus.engineForcesMoments.forcesInBody_N(1), 0))	
Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.EngineBus.engineForcesMoments.forcesInBody_N(2), 0))	
Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.EngineBus.engineForcesMoments.forcesInBody_N(3), 0))	
$ \begin{tabular}{ll} \hline & \textbf{VerifyControllerArmed:} verify (is Close (actuator Bus. Engine Bus. engine Forces Moments. moments In Body_Nm (1), and the control of the cont$	0))
$ \hline \textbf{\textit{VerifyControllerArmed:}} Verify (is Close (actuator Bus. Engine Bus. engine Forces Moments. moments In Body_Nm (2), and the sum of the property of th$	0))
$ \hline \textbf{\textit{VerifyControllerArmed:}} Verify (is Close (actuator Bus. Engine Bus. engine Forces Moments. moments In Body_Nm (3), and the sum of the property of th$	0))
Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posAileron_rad,0))	
Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posElevator_rad,0))	
Test Sequence//verifyControllerArmed:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posRudder_rad,0))	
Test Sequence//verifyAileronRate:verify(aileronCmdRate <= aileronDeflRateLimit_degps)	
Test Sequence//verifyAileronLimit:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posAileron_rad, deg2rad(maxAilDefl_	deg
)))	
Test Sequence//verifyNegAileronRate:verify(abs(aileronCmdRate) <= aileronDeflRateLimit_degps)	
Test Sequence//verifyNegAileronLimit:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posAileron_rad, -deg2rad(maxAilI)efl
_deg)))	
Test Sequence//verifyElevatorRate:verify(elevatorCmdRate <= elevatorDeflRateLimit_degps)	
Test Sequence//verifyElevatorLimit:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posElevator_rad, deg2rad(maxElevatorBus.ServosF16Bus.posElevator_rad, deg2rad(maxElevatorBus.ServosF16Bus.posElevator_rad, deg2rad(maxElevatorBus.ServosBus.ServosF16Bus.posElevator_rad, deg2rad(maxElevatorBus.Servos	or
Defl_deg)))	
Test Sequence//verifyNegElevatorRate:verify(abs(elevatorCmdRate) <= elevatorDeflRateLimit_degps)	
Test Sequence//verifyNegElevatorLimit:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posElevator_rad, -deg2rad(maxElevator_rad, -deg2rad)	iev
atorDefl_deg)))	
Test Sequence//verifyRudderRate:verify(rudderCmdRate <= rudderDeflRateLimit_degps)	

Test Sequence//verifyRudderMax:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posRudder_rad, deg2rad(maxRudderDefl_
deg)))
Test Sequence//verifyNegRudderRate:verify(abs(rudderCmdRate) <= rudderDeflRateLimit_degps)
Test Sequence//verifyNegRudderMax:verify(isClose(actuatorBus.ServosBus.ServosF16Bus.posRudder_rad, -deg2rad(maxRudder_
Defl_deg)))

System Under Test Information

Model: actuators

Harness: actuatorsTestHarness

Harness Owner: actuators
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: actuatorsTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 19.02400000000001

Checksum: 2421928454 3016652062 4146747926 2294716544

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

aero

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 05-Mar-2025 09:16:19 End Time: 05-Mar-2025 09:16:21

Outcome: Passed

Test Case Information

Name: aero

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: <u>aero</u>

Start Time: 05-Mar-2025 09:16:19 End Time: 05-Mar-2025 09:16:21

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Name	
Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.forcesInBody_N(1),0))	i
Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.forcesInBody_N(2),0))	i
Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.forcesInBody_N(3),0))	i
Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(1),0))	i
Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(2).0))	i

Test Sequence1//verifyZeroOutputs:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(3),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.airspeedInBody_mps(1),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.airspeedInBody_mps(2),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.airspeedInBody_mps(3),0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.alpha_rad,0))	
Test Sequence1//verifyZeroOutputs:verify(isClose(airDataBus.beta_rad,0))	
Test Sequence1//verifyAirspeed:verify(aeroForcesMomentsBus.forcesInBody_N(1) < 0)	
Test Sequence1//verifyAirspeed:verify(isClose(aeroForcesMomentsBus.forcesInBody_N(2),0))	
Test Sequence1//verifyAirspeed:verify(aeroForcesMomentsBus.forcesInBody_N(3) < -20500 * lbf2N)	
Test Sequence1//verifyAirspeed:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(1),0))	
Test Sequence1//verifyAirspeed:verify(aeroForcesMomentsBus.momentsInBody_Nm(2) < 0)	
Test Sequence1//verifyAirspeed:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(3),0))	
Test Sequence1//verifyAirspeed:verify(isClose(airDataBus.airspeedInBody_mps(2),0))	
Test Sequence1//verifyAirspeed:verify(isClose(airDataBus.airspeedInBody_mps(3),0))	
Test Sequence1//verifyAirspeed:verify(isClose(airDataBus.alpha_rad,0))	
Test Sequence1//verifyAirspeed:verify(isClose(airDataBus.beta_rad,0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(aeroForcesMomentsBus.forcesInBody_N(2),0))	
Test Sequence1//verifyElevatorDeflection:verify(aeroForcesMomentsBus.forcesInBody_N(3) > cruiseZForce)	
Test Sequence1//verifyElevatorDeflection:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(1),0))	
Test Sequence1//verifyElevatorDeflection:verify(aeroForcesMomentsBus.momentsInBody_Nm(2) > cruiseYMo	ment)
Test Sequence1//verifyElevatorDeflection:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(3),0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(airDataBus.airspeedInBody_mps(2),0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(airDataBus.airspeedInBody_mps(3),0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(airDataBus.alpha_rad,0))	
Test Sequence1//verifyElevatorDeflection:verify(isClose(airDataBus.beta_rad,0))	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.forcesInBody_N(2) > 0)	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.forcesInBody_N(3) < 0)	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.momentsInBody_Nm(1) > 0)	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.momentsInBody_Nm(2) < 0)	
Test Sequence1//verifyRudder:verify(aeroForcesMomentsBus.momentsInBody_Nm(3) < 0)	
Test Sequence1//verifyRudder:verify(isClose(airDataBus.airspeedInBody_mps(2),0))	
Test Sequence1//verifyRudder:verify(isClose(airDataBus.airspeedInBody_mps(3),0))	
Test Sequence1//verifyRudder:verify(isClose(airDataBus.alpha_rad,0))	
Test Sequence1//verifyRudder:verify(isClose(airDataBus.beta_rad,0))	
Test Sequence1//verifyAileron:verify(aeroForcesMomentsBus.momentsInBody_Nm(1) < 0)	
Test Sequence1//verifyAileron:verify(isClose(aeroForcesMomentsBus.momentsInBody_Nm(2),cruiseYMoment	,,

System Under Test Information

Model: aero

Harness: aeroTestHarness

Harness Owner: aero
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: aeroTestHarness/Test Sequence1

Test Sequence Scenario: Scenario_1

Start Time: 0 Stop Time: 22

Checksum: 2854743191 1458617529 2284628752 3323507110

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

ground contact

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 05-Mar-2025 09:16:22 End Time: 05-Mar-2025 09:16:23

Outcome: Passed

Test Case Information

Name: ground contact Type: Baseline Test

Name
Test Sequence1//verifyInitialization:verify(isVehicleAirborne == 0)
Test Sequence1//verifyInitialization:verify(groundCollision == 0)
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1),0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2),0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3),0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(1), 0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(2), 0))
Test Sequence1//verifyInitialization:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(3), 0))
Test Sequence1//verifyStationary:verify(isVehicleAirborne == 0)
Test Sequence1//verifyStationary:verify(groundCollision == 0)
Test Sequence1//verifyStationary:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1), 0))
Test Sequence1//verifyStationary:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2), 0))
Test Sequence1//verifyStationary:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3), -9298.6 * 9.81))
Test Sequence1//verifyStationary:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(1), 0))
Test Sequence1//verifyStationary:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(2), 0))
Test Sequence1//verifyStationary:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(3), 0))
Test Sequence1//verifyFastTaxi:verify(isVehicleAirborne == 0)
Test Sequence1//verifyFastTaxi:verify(groundCollision == 0)
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1), 0))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2), 0))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3), -9298.6 * 9.81 + 20000))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(1),0))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(2),0))
Test Sequence1//verifyFastTaxi:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(3),0))
Test Sequence1//verifyFastTaxi:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(1), 0))
Test Sequence1//verifyFastTaxi:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(2), 0))
Test Sequence1//verifyFastTaxi:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(3), 0))
Test Sequence1//verifyRotate:verify(isVehicleAirborne == 0)
Test Sequence1//verifyRotate:verify(groundCollision == 0)
Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1), 0))

Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2), 0))
Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3), -9298.6 * 9.81 + 20000))
Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(1),0))
Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(2),0))
Test Sequence1//verifyRotate:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(3),0))
Test Sequence1//verifyRotate:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(1), 0))
Test Sequence1//verifyRotate:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(2), 0))
Test Sequence1//verifyRotate:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(3), 0))
Test Sequence1//verifyTakeoff:verify(isVehicleAirborne == 1)
Test Sequence1//verifyTakeoff:verify(groundCollision == 0)
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.forcesInBody_N(1), 0))
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.forcesInBody_N(2), 0))
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.forcesInBody_N(3), 0))
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(1),0))
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(2),0))
Test Sequence1//verifyTakeoff:verify(isClose(groundForcesMomentsBus.momentsInBody_Nm(3),0))
Test Sequence1//verifyTakeoff:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(1), 0))
Test Sequence1//verifyTakeoff:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(2), 0))
Test Sequence1//verifyTakeoff:verify(isClose(weightForcesMomentsBus.momentsInBody_Nm(3), 0))

System Under Test Information

Model: groundContact

Harness: groundContactTestHarness

Harness Owner: groundContact

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: groundContactTestHarness/Test Sequence1

Test Sequence Scenario: Scenario_2

Start Time: 0
Stop Time: 2.028

Checksum: 1244405978 4079976263 897553408 2782662889

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

inertial dynamics

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 05-Mar-2025 09:16:23 End Time: 05-Mar-2025 09:16:25

Outcome: Passed

Test Case Information

Name: inertial dynamics Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result
Parent: <u>inertial dynamics</u>
Start Time: 05-Mar-2025 09:16:23
End Time: 05-Mar-2025 09:16:25

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Verify Result

Name
Test Sequence1//Test1:verify(isClose(bodyStatesBus.aircraftPosInNED_m(1), 0.5*interval_time^2*aircraftForcesInNED_N(1)/aircr
aftMass + aircraftInitialPosInNED_m(1)))
Test Sequence1//Test1:verify(isClose(bodyStatesBus.aircraftVelInBody_mps(1), interval_time*aircraftForcesMomentsBus_forcesI
nBody_N(1)/aircraftMass + aircraftInitialVelInBody_mps(1)))
Test Sequence1//Test1:verify(isClose(bodyStatesBus.aircraftAccelInBody_mps2(1),aircraftForcesMomentsBus_forcesInBody_N(1)
/aircraftMass))

Simulation

System Under Test Information

Model: inertialDynamics

Harness: inertialDynamicsTestHarness

Harness Owner: inertialDynamics

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: inertialDynamicsTestHarness/Test Sequence1

Test Sequence Scenario: Scenario_1

Start Time: 0 Stop Time: 1.008

Checksum: 2740628208 4264647383 940722363 2610557463

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

vehicle

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 05-Mar-2025 09:16:25 End Time: 05-Mar-2025 09:16:33

Outcome: Passed

Test Case Information

Name: vehicle

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: vehicle

Start Time: 05-Mar-2025 09:16:25 End Time: 05-Mar-2025 09:16:33

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name Value

TestSequenceScena	Scenario_1
rio	

Name
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(1), 0))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(1),0))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2),0))
Test Sequence//verifyZeroInputs:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(3),0))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(1), 0))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(1),0))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2),0))
Test Sequence//verifyZeroInputsAgain:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(3),0))
▼ Test Sequence//verifyThrottle:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0))
Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0))
Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(1),0))
Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2),0))
Test Sequence//verifyThrottle:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(3),0))
Test Sequence//verifyPitchIntoGround:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2), 0))
Test Sequence//verifyPitchIntoGround:verify(isClose(vehicleBus.BodyStates.aircraftEulerAngles_rad(2), 0))
Test Sequence//verifyPitchIntoGround:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0))
Test Sequence//verifyPitchIntoGround:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
Test Sequence//verifyPitchIntoGround:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0))
Test Sequence//verifydeflectElevator:verify(isClose(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2), 0, 'absTol', 0.01))
Test Sequence//verifydeflectElevator:verify(isClose(vehicleBus.BodyStates.aircraftEulerAngles_rad(2), 0, 'absTol', 0.01))
Test Sequence//verifydeflectElevator:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(3), 0, 'absTol', 0.01))
Test Sequence//verifydeflectElevator:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
Test Sequence//verifydeflectElevator:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_N(2), 0))
Test Sequence//verifyRotate:verify(vehicleBus.AircraftForcesMoments.momentsInBody_Nm(2) > 0)
Test Sequence//verifyRotate:verify(vehicleBus.BodyStates.aircraftEulerAngles_rad(2) > 0)
▼ Test Sequence//verifyRotate:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(3) < 0)

Test Sequence//verifyRotate:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)
Test Sequence//verifyRotate:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_1	N(2), 0))
Test Sequence//verifyFlying:verify(vehicleBus.BodyStates.aircraftPosInNED_m(3) < 0)	i
Test Sequence//verifyFlying:verify(vehicleBus.BodyStates.aircraftEulerAngles_rad(2) > 0)	i
Test Sequence//verifyFlying:verify(vehicleBus.AircraftForcesMoments.forcesInBody_N(1) > 0)	
Test Sequence//verifyFlying:verify(isClose(vehicleBus.AircraftForcesMoments.forcesInBody_1	N(2), 0))

System Under Test Information

Model: F16

Harness: F16TestHarness

Harness Owner: F16
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration
Test Sequence Block: F16TestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 86.0199999999999

Checksum: 2184461690 750684721 2704972700 135817865

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

engine

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 05-Mar-2025 09:16:34 End Time: 05-Mar-2025 09:16:52

Outcome: Passed

Test Case Information

Name: engine

Type: Baseline Test

Verify Result

Name
Test Sequence//verifyControllerDisarm:verify(isClose(engineBus.engineForcesMoments.forcesInBody_N(1),0))
Test Sequence//verifyThorttle:verify(isClose(thrust_lbf, engineBus.engineForcesMoments.forcesInBody_N(1), 'atol', 1))
Test Sequence//verifyMaxThrust:verify(engineBus.engineForcesMoments.forcesInBody_N(1) < 130000)
Test Sequence//verifyMaxThrust:verify(isClose(thrust_lbf, engineBus.engineForcesMoments.forcesInBody_N(1), 'atol', 1))
Test Sequence//verifyWithAirspeed:verify(isClose(thrust_lbf, engineBus.engineForcesMoments.forcesInBody_N(1), 'atol', 1))
Test Sequence//verifyIncreaseAirspeed:verify(isClose(thrust_lbf, engineBus.engineForcesMoments.forcesInBody_N(1), 'atol', 1))
Test Sequence//verifyIncreaseAltitude:verify(isClose(thrust_lbf, engineBus.engineForcesMoments.forcesInBody_N(1), 'atol', 1))

Simulation

System Under Test Information

Model: engineModelF16

Harness: engineModelF16TestHarness

Harness Owner: engineModelF16

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Start Time: 0

Stop Time: 38.00399999999998

Checksum: 3632656878 226596412 27427538 2773569956

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

addFM

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 05-Mar-2025 09:16:53 End Time: 05-Mar-2025 09:16:54

Outcome: Passed

Test Case Information

Name: addFM

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: addFM

Start Time: 05-Mar-2025 09:16:53 End Time: 05-Mar-2025 09:16:54

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Verify Result

Name	
Test Sequence1//Test1:verify(all(isClose(aircraftForcesMomentsBus.forcesInBody_N, aeroForcesMomentsBus.forcesInBody_N + e	
ngineForcesMomentsBus.forcesInBody_N + groundForcesMomentsBus.forcesInBody_N + weightForcesMomentsBus.forcesInBody_N)	
))	
Test Sequence1//Test1:verify(all(isClose(aircraftForcesMomentsBus.momentsInBody_Nm, engineForcesMomentsBus.momentsIn	
Body_Nm + aeroForcesMomentsBus.momentsInBody_Nm + weightForcesMomentsBus.momentsInBody_Nm)))	
Test Sequence1//Test2:verify(all(isClose(aircraftForcesMomentsBus.forcesInBody_N, aeroForcesMomentsBus.forcesInBody_N + e	
ngineForcesMomentsBus.forcesInBody_N + groundForcesMomentsBus.forcesInBody_N + weightForcesMomentsBus.forcesInBody_N)	
))	
Test Sequence1//Test2:verify(all(isClose(aircraftForcesMomentsBus.momentsInBody_Nm, aeroForcesMomentsBus.momentsInB	
ody_Nm + engineForcesMomentsBus.momentsInBody_Nm + weightForcesMomentsBus.momentsInBody_Nm)))	
Test Sequence1//verifyPitchIntoGround:verify(all(isClose(aircraftForcesMomentsBus.forcesInBody_N, aeroForcesMomentsBus.f	
$orcesInBody_N + engineForcesMomentsBus.forcesInBody_N + groundForcesMomentsBus.forcesInBody_N + weightForcesMomentsBus.forcesInBody_N + weightForcesInBody_N + weightForcesInBody_N + weightForcesInBody_N + weightForcesInBody_N + weightForcesInBo$	
s.forcesInBody_N)))	
Test Sequence1//verifyPitchIntoGround:verify(isClose(aircraftForcesMomentsBus.momentsInBody_Nm(1), 0))	
Test Sequence1//verifyPitchIntoGround:verify(isClose(aircraftForcesMomentsBus.momentsInBody_Nm(2), engineForcesMomen	
tsBus.momentsInBody_Nm(2) + aeroForcesMomentsBus.momentsInBody_Nm(2) + weightForcesMomentsBus.momentsInBody_Nm(2)	
))	
Test Sequence1//verifyPitchIntoGround:verify(isClose(aircraftForcesMomentsBus.momentsInBody_Nm(3), engineForcesMomen	
tsBus.momentsInBody_Nm(3) + aeroForcesMomentsBus.momentsInBody_Nm(3) + weightForcesMomentsBus.momentsInBody_Nm(3)	

Simulation

System Under Test Information

Model: addFM

Harness: addFMTestHarness

Harness Owner: addFM Release: Current

Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: addFMTestHarness/Test Sequence1

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 3.016

Checksum: 2405791290 3021241631 2400769033 306058281

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

gravity

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 05-Mar-2025 09:16:54 End Time: 05-Mar-2025 09:16:54

Outcome: Passed

Test Case Information

Name: gravity

Type: Baseline Test

Name
Test Sequence1//Test1:verify(isClose(weightForcesMoments.forcesInBody_N(1), 0))
Test Sequence1//Test1:verify(isClose(weightForcesMoments.forcesInBody_N(2), 0))
Test Sequence1//Test1:verify(isClose(weightForcesMoments.forcesInBody_N(3), weight_N))
Test Sequence1//Test1:verify(isClose(sum(weightForcesMoments.momentsInBody_Nm(1:3)), 0))

Test Sequence1//Test2:verify(isClose(weightForcesMoments.forcesInBody_N(1), -weight_N * sin(pitch_rad)))
Test Sequence1//Test2:verify(isClose(weightForcesMoments.forcesInBody_N(2), 0))
Test Sequence1//Test2:verify(isClose(weightForcesMoments.forcesInBody_N(3), weight_N * cos(pitch_rad)))
Test Sequence1//Test2:verify(isClose(sum(weightForcesMoments.momentsInBody_Nm(1:3)), 0))
Test Sequence1//Test3:verify(isClose(weightForcesMoments.forcesInBody_N(1), -weight_N * sin(pitch_rad)))
Test Sequence1//Test3:verify(isClose(weightForcesMoments.forcesInBody_N(2), weight_N * sin(roll_rad) * cos(pitch_rad)))
Test Sequence1//Test3:verify(isClose(weightForcesMoments.forcesInBody_N(3), weight_N * cos(roll_rad) * cos(pitch_rad)))
Test Sequence1//Test3:verify(isClose(sum(weightForcesMoments.momentsInBody_Nm(1:3)), 0))

System Under Test Information

Model: gravity

Harness: gravityTestHarness

Harness Owner: gravity
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: gravityTestHarness/Test Sequence1

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 0.02800000000000001

Checksum: 371801570 4075467097 1945074898 1201465379

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

FullSIL

Test Result Information

Result Type: Test Case Result Parent: Vehicle Tests

Start Time: 05-Mar-2025 09:16:55 End Time: 05-Mar-2025 09:19:02

Outcome: Passed

Test Case Information

Name: FullSIL

Type: Baseline Test

Simulation

System Under Test Information

Model: VehiclePlant

Harness: VehiclePlantTestHarness

Harness Owner: VehiclePlant Release: Current simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Start Time: 0

Stop Time: 280.0040000000002

Checksum: 4180887510 1029732119 117757583 2392156677

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

sensors

Test Result Information

Result Type: Test File Result

Parent: <u>Results: 2025-Mar-05 09:16:09</u>

Start Time: 05-Mar-2025 09:19:03 End Time: 05-Mar-2025 09:19:08 Outcome: Total: 4, Passed: 4

Test Suite Information

Name: sensors

Back to Report Summary

Sensor Tests

Test Result Information

Result Type: Test Suite Result

Parent: sensors

Start Time: 05-Mar-2025 09:19:03 End Time: 05-Mar-2025 09:19:08 Outcome: Total: 4, Passed: 4

Test Suite Information

Name: Sensor Tests

Back to Report Summary

ins

Test Result Information

Result Type: Test Case Result Parent: Sensor Tests

Start Time: 05-Mar-2025 09:19:03 End Time: 05-Mar-2025 09:19:04

Outcome: Passed

Test Case Information

Name: ins

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: <u>ins</u>

Start Time: 05-Mar-2025 09:19:03 End Time: 05-Mar-2025 09:19:04

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value	
TestSequenceScena	Scenario_1	
rio		

Name
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.GyroSensorBus.x_radps, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.GyroSensorBus.y_radps, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.GyroSensorBus.z_radps, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.AccelSensorBus.x_mps2, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.AccelSensorBus.y_mps2, 0, 'atol', 0.01))
Test Sequence//checkInsStatic:verify(isClose(INSSensorBus.AccelSensorBus.z_mps2, 0, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.GyroSensorBus.x_radps, 0.1, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.GyroSensorBus.y_radps, 0.2, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.GyroSensorBus.z_radps, 0.3, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.MagSensorBus.x_Gauss, 0, 'atol', 0.01))
Test Sequence//checkInsDynamic:verify(isClose(INSSensorBus.MagSensorBus.y_Gauss, 0, 'atol', 0.01))

- Test Sequence/.../checkInsDynamic:verify(isClose(INSSensorBus.MagSensorBus.z_Gauss, 0, 'atol', 0.01))
- Test Sequence/.../checkInsDynamic:verify(isClose(INSSensorBus.AccelSensorBus.x_mps2, 1, 'atol', 0.01))
- Test Sequence/.../checkInsDynamic:verify(isClose(INSSensorBus.AccelSensorBus.y_mps2, 2, 'atol', 0.01))
- Test Sequence/.../checkInsDynamic:verify(isClose(INSSensorBus.AccelSensorBus.z_mps2, 3, 'atol', 0.01))

System Under Test Information

Model: ins

Harness: insTestHarness

Harness Owner: ins

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration
Test Sequence Block: insTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 10.00800000000001

Checksum: 3180580520 4092729406 197588729 847202452

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

adc

Test Result Information

Result Type: Test Case Result Parent: Sensor Tests

Start Time: 05-Mar-2025 09:19:04

End Time: 05-Mar-2025 09:19:05

Outcome: Passed

Test Case Information

Name: adc

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: adc

Start Time: 05-Mar-2025 09:19:04 End Time: 05-Mar-2025 09:19:05

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Name
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.BaroSensorBus.altitude_m, 0, 'atol', 20))
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.BaroSensorBus.pressure_pa, 101325, 'atol', 100))
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.BaroSensorBus.temperature_degC, 15, 'atol', 2))
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.DiffPressureSensorBus.differential_pressure_pa, 0, 'atol', 100))
Test Sequence//checkSensors:verify(isClose(ADCSensorBus.DiffPressureSensorBus.temperature_degC, 15, 'atol', 2))
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.BaroSensorBus.altitude_m, 3048, 'atol', 20))

Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.BaroSensorBus.pressure_pa, 69681.66, 'atol', 100))	
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.BaroSensorBus.temperature_degC, -4.8, 'atol', 2))	i
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.DiffPressureSensorBus.differential_pressure_pa, 0,	'atol', 100))
Test Sequence//checkSensors10kft:verify(isClose(ADCSensorBus.DiffPressureSensorBus.temperature_degC, -4.8, 'atc	1', 2))
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.BaroSensorBus.altitude_m, 6096, 'atol', 20))	i i
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.BaroSensorBus.pressure_pa, 46563.26, 'atol', 100))	i i
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.BaroSensorBus.temperature_degC, -24.624, 'atol', 2))i
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.DiffPressureSensorBus.differential_pressure_pa, 0,	'atol', 100))
Test Sequence//checkSensors20kft:verify(isClose(ADCSensorBus.DiffPressureSensorBus.temperature_degC, -24.624,	'atol', 2))
Test Sequence//checkDiffPress:verify(ADCSensorBus.DiffPressureSensorBus.differential_pressure_pa > 0)	

System Under Test Information

Model: adc

Harness: adcTestHarness

Harness Owner: adc
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration
Test Sequence Block: adcTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 0.03200000000000001

Checksum: 1104384803 2190219993 1982550312 115166805

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

gps

Test Result Information

Result Type: Test Case Result Parent: Sensor Tests

Start Time: 05-Mar-2025 09:19:05 End Time: 05-Mar-2025 09:19:06

Outcome: Passed

Test Case Information

Name: gps

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: gps

Start Time: 05-Mar-2025 09:19:05 End Time: 05-Mar-2025 09:19:06

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

✓ Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.lat_deg, referenceLatitude_deg))
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.lon_deg, referenceLongitude_deg))
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.alt_m, terrainHeightNED_m, 'atol', 0.5))
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.vel_mps, 0, 'atol', 0.5))
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.vel_n_mps, 0, 'atol', 0.5))
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.vel_e_mps, 0, 'atol', 0.5))
Test Sequence//checkGpsStatic:verify(isClose(GPSSensorBus.vel_d_mps, 0, 'atol', 0.5))
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.lat_deg, referenceLatitude_deg))
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.lon_deg, referenceLongitude_deg))
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.alt_m, 3048 + terrainHeightNED_m))
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.vel_mps, norm([10 20 30]), 'rtol', 0.8))
☑ Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.vel_n_mps, 10, 'rtol', 0.1))
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.vel_e_mps, 20, 'rtol', 0.1))
Test Sequence//checkHighDynamic:verify(isClose(GPSSensorBus.vel_d_mps, 30, 'rtol', 0.1))

System Under Test Information

Model: gps

Harness: gpsTestHarness

Harness Owner: gps
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration
Test Sequence Block: gpsTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0 Stop Time: 0.016

Checksum: 1261040433 1750074340 274485945 283260561

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

sensors

Test Result Information

Result Type: Test Case Result Parent: Sensor Tests

Start Time: 05-Mar-2025 09:19:06 End Time: 05-Mar-2025 09:19:08

Outcome: Passed

Test Case Information

Name: sensors

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: <u>sensors</u>

Start Time: 05-Mar-2025 09:19:06 End Time: 05-Mar-2025 09:19:08

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

	Parameter Name	Value	
	TestSequenceScena	Scenario_1	
	rio		

System Under Test Information

Model: sensors

Harness: sensorsTestHarness

Harness Owner: sensors
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: sensorsTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0

Stop Time: 0.2000000000000001

Checksum: 428289380 3739551487 3356815515 3460855074

Simulation Logs:

No data is logged for the model 'sensorsTestHarness'.

Back to Report Summary

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

environment

Test Result Information

Result Type: Test File Result

Parent: <u>Results: 2025-Mar-05 09:16:09</u>

Start Time: 05-Mar-2025 09:19:08 End Time: 05-Mar-2025 09:19:12 Outcome: Total: 3, Passed: 3

Test Suite Information

Name: environment

Back to Report Summary

Environment Tests

Test Result Information

Result Type: Test Suite Result Parent: environment

Start Time: 05-Mar-2025 09:19:08 End Time: 05-Mar-2025 09:19:12 Outcome: Total: 3, Passed: 3

Test Suite Information

Name: Environment Tests

Back to Report Summary

Air

Test Result Information

Result Type: Test Case Result
Parent: Environment Tests
Start Time: 05-Mar-2025 09:19:08
End Time: 05-Mar-2025 09:19:09

Outcome: Passed

Test Case Information

Name: Air

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: Air

Start Time: 05-Mar-2025 09:19:08 End Time: 05-Mar-2025 09:19:09

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

	Parameter Name	Value	
	TestSequenceScena	Scenario_1	
	rio		

Name
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.windSpeedInNED_mps(1), 4))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.windSpeedInNED_mps(2), 3))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.windSpeedInNED_mps(3), 2))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.airTemperature_K, 288.15))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.airPressure_Pa, 1.01325e5))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.airDensity_kgpm3, 1.225))
Test Sequence//Test1:verify(isClose(AirEnvironmentBus.speedOfSound_mps, 340.29412435))

System Under Test Information

Model: Air

Harness: AirTestHarness

Harness Owner: Air
Release: Current
Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration
Test Sequence Block: AirTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0 Stop Time: 3.004

Checksum: 2333579960 118194984 3293710571 2811700376

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

Earth

Test Result Information

Result Type: Test Case Result
Parent: Environment Tests
Start Time: 05-Mar-2025 09:19:09
End Time: 05-Mar-2025 09:19:11

Outcome: Passed

Test Case Information

Name: Earth

Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: Earth

Start Time: 05-Mar-2025 09:19:09 End Time: 05-Mar-2025 09:19:11

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

1 CSt O VCITIQCS			
	Parameter Name	Value	
	TestSequenceScena	Scenario_1	
	rio		

Verify Result

Name	
Test Sequence1//verifyAircraftZChange:verify(gravLow_mps2 > EarthEnvironmentBus.gravityScalar_mps2)	-]

Simulation

System Under Test Information

Model: Earth

Harness: EarthTestHarness

Harness Owner: Earth Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: EarthTestHarness/Test Sequence1

Test Sequence Scenario: Scenario_1

Start Time: 0 Stop Time: 7

Checksum: 1175429799 1798864983 927034458 1191542450

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

LocalTerrain

Test Result Information

Result Type: Test Case Result
Parent: Environment Tests
Start Time: 05-Mar-2025 09:19:11
End Time: 05-Mar-2025 09:19:12

Outcome: Passed

Test Case Information

Name: LocalTerrain Type: Baseline Test

Iteration1

Test Result Information

Result Type: Test Iteration Result

Parent: <u>LocalTerrain</u>

Start Time: 05-Mar-2025 09:19:11

End Time: 05-Mar-2025 09:19:12

Outcome: Passed

Test Case Information

Name: Iteration1
Type: Baseline Test

Iteration Settings

Test Overrides

Parameter Name	Value
TestSequenceScena	Scenario_1
rio	

Simulation

System Under Test Information

Model: LocalTerrain

Harness: LocalTerrainTestHarness

Harness Owner: LocalTerrain Release: Current simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: standardSILConfiguration

Test Sequence Block: LocalTerrainTestHarness/Test Sequence

Test Sequence Scenario: Scenario_1

Start Time: 0

Checksum: 3805200661 3804672667 1828039431 394193071

Simulation Logs:

No data is logged for the model 'LocalTerrainTestHarness'.

Back to Report Summary

Test Logs: No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary