### Linear Regression

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### Plan for today

- Linear regression
  - What is regression?
  - LR derivation
  - LR example
- Test set / training set error example
- Ovefitting example

### What is regression?

- Given some data (x<sub>i</sub>, t<sub>i</sub>)
  - E.g. x = {age, weight}, t={time to run a mile}
- t(x) is a random variable
- Want to predict the mean:  $\hat{t}(x)$

### What is regression?

- Hypothesis space
  - Linear regression:
    - Linear in w, not in x!
    - This is linear:
    - This is also linear:
  - Nonlinear regression, e.g.

 $\hat{t}(x) = \sum_{i} w_{i} f_{i}(x)$ 

$$\hat{t}(x) = \sum w_i x^i$$

$$\hat{t}(x) = \sum_{i} w_{i} x^{i}$$

$$\hat{t}(x) = \sum_{i} w_{i} \sin(i^{2} x^{7})$$

$$\hat{t}(x) = \sum_{i} e^{w_{i} x}$$

$$\hat{t}(x) = \sum_{i} e^{w_i x}$$

Minimize the loss function, e.g.

$$\sum_{i} (\hat{t}(x_i) - t_j)^2$$

### Why linear regression?

- MLE if the noise is independent Gaussian
- Easy to compute closed-form solution

• Hypothesis: 
$$\hat{t}(x) = w_0 + \sum_i w_i f_i(x)$$

Want to minimize:

$$\sum_{j} (\hat{t}(x_{j}) - t_{j})^{2} = \sum_{j} ((w_{0} + \sum_{i} w_{i} f_{i}(x)) - t_{j})^{2}$$

$$\hat{t}(x) = w_0 + \sum_i w_i f_i(x)$$

 $W_0$  stands out – put it inside the sum too

$$f_0(x) \equiv 1 \qquad \hat{t}(x) = \sum_{i=0}^m w_i f_i(x)$$

Vector notation: 
$$\hat{t}(x) = (1 \quad f_1(x) \quad \dots \quad f_k(x)) \begin{pmatrix} w_0 \\ w_1 \\ \vdots \\ w_k \end{pmatrix} = \vec{f}^T(x)w$$

#### Matrices basics

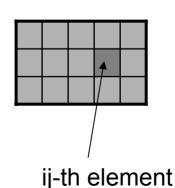
- Matrix A → 2-dimensional array of numbers (n rows x m columns)
- a<sub>ii</sub> → number on i-th row and j-th column
- Vector → (n x 1) matrix
- $C = A + B : c_{ij} = a_{ij} + b_{ij}$
- A<sup>T</sup> transpose 'rotated around diagonal'
  - $-B = A^T \leftrightarrow b_{ij} = a_{ij}$
  - i.e. i-th row is now i-th column

### Matrices basics

#### Multiplication

- $(n by k) x (k by m) \rightarrow (n by m)$
- C = AB  $\leftrightarrow$   $c_{ij} = \sum a_{ik}b_{kj}$
- (AB)C = A(BC), (A+B)C = AC + BC
- AI = IA = A, I identity matrix (of the right size)
- AB ≠ BA (even when BA is defined!)
- $-A^{-1}$  inverse: A x  $A^{-1}$  =  $A^{-1}$  x A = I
  - · Not always exists!

$$I = \begin{pmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{pmatrix}$$



$$\sum_{j} (\hat{t}(x_{j}) - t_{j})^{2} = (\hat{t}(x_{1}) - t_{1} \dots \hat{t}(x_{n}) - t_{n}) \begin{pmatrix} \hat{t}(x_{1}) - t_{1} \\ \vdots \\ \hat{t}(x_{n}) - t_{n} \end{pmatrix} = (\hat{t} - t)^{T} (\hat{t} - t)$$

$$\hat{t} = \begin{pmatrix} \hat{t}(x_1) \\ \vdots \\ \hat{t}(x_n) \end{pmatrix} = \begin{pmatrix} f_0(x_1) & \dots & f_k(x_1) \\ \vdots & \ddots & \vdots \\ f_0(x_n) & \dots & f_k(x_n) \end{pmatrix} \begin{pmatrix} w_0 \\ \vdots \\ w_k \end{pmatrix} = Fw$$

$$\sum_{j} (\hat{t}(x_{j}) - t_{j})^{2} = (Fw - t)^{T} (Fw - t)$$

 To minimize, take derivative w.r.t w (remember, w is a vector! → the derivative is a vector)

$$\frac{\partial}{\partial w}(Fw-t)^T(Fw-t) = \cdots$$

• Properties:  $\frac{\partial}{\partial X} X^T X = 2X$   $\frac{\partial}{\partial X} AX = A^T$ 

• Therefore... 
$$\frac{\partial}{\partial w}(Fw-t)^{T}(Fw-t) = \frac{\partial}{\partial w}(w^{T}F^{T}Fw-w^{T}F^{T}t-t^{T}Fw+t^{T}t) =$$
$$=F^{T}Fw-2F^{T}t$$

$$F^T F w - F^T t = 0$$

under mild conditions F<sup>T</sup>F is invertible, so

$$w = (F^T F)^{-1} F^T t$$

We're done!