



# **Vehicle Electronics (VEH) System Architecture**

**ES00003**

Rev: A05  
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# 1 General Setting

In the OA-II VEH system, each payload module is specialize for a special function. In each module, it have three type of units.

**Basic unit** The basic unit is indecate this unit finish the most foundmental function of this module. It is a stand alone unit that build the foundation for the the unit. It will be the first unit in the module.

**Feature Unit** The feature unit is adding more features to the module. It usually need the basic unit to function and receive commend from the the basic unit.

For a functioning OA-II VEH, it only require the basic unit in COM and PAM. For more feature, more unit in each module is needed. In the most basic OA-II VEH system, it only contain two unit, the basic unit for COM and PAM.

## 2 Payload Frame (PF)

### 2.1 Discription

In the Payload Frame, most of the signal and power will run throught it and arrive to the target unit. The payload frame will have different sector for different module. In general, it will at least provide three power line, more than one commend line, and four high speed data lane.

## 3 Payload Modules (PM)

### 3.1 Discription

Payload Modules are specialized circuits which slot into the Payload Frame. They can be divided into three primary types: Computing and Operation Module (COM), Telecommuni-  
cation and Acquisition Module (TAM), and Power and Actuator Module (PAM).

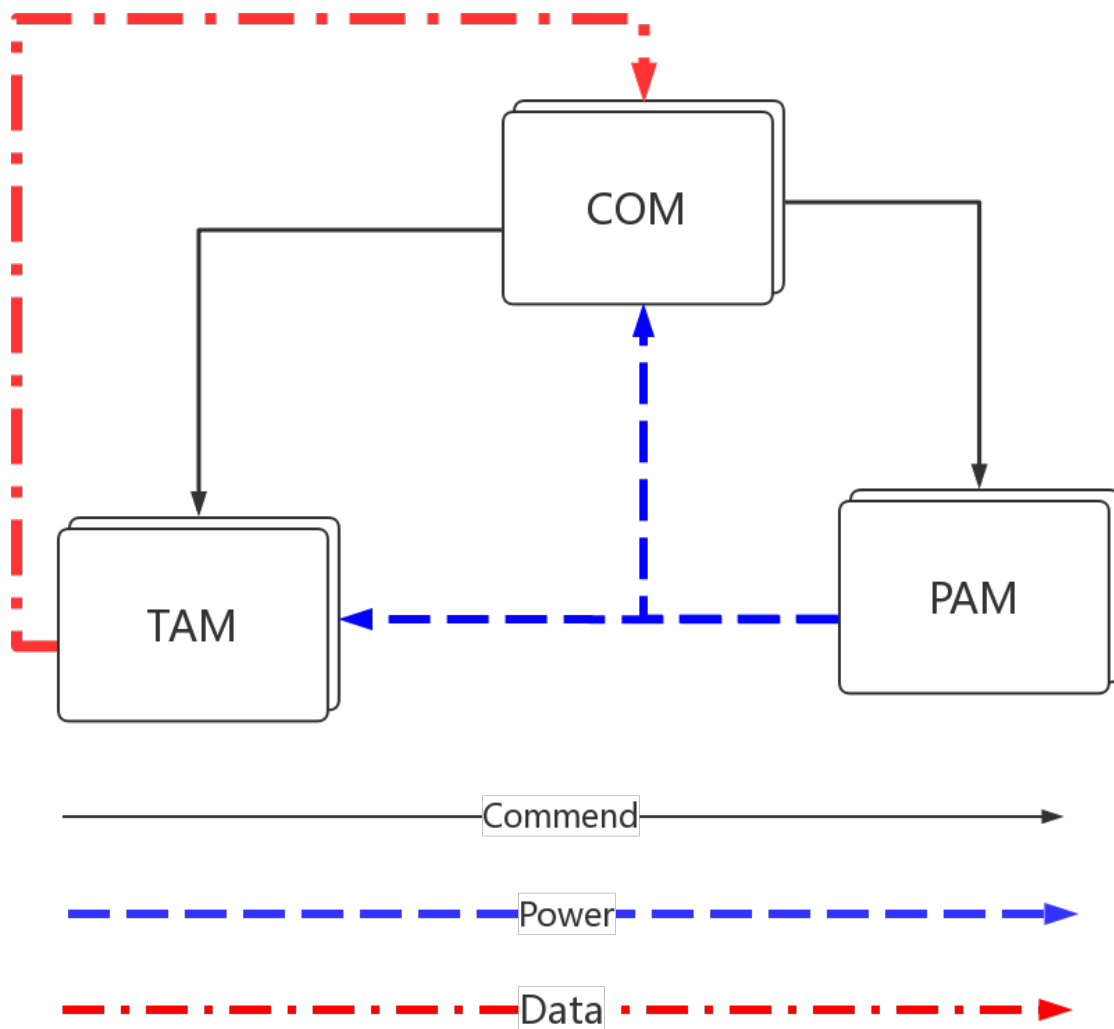


Figure 1: System Diagram

## 3.2 Payload Catalog

**Critical Payload** All the critical payload will be in the assigning unit.

- 4 low temp sensors for electronics **In each unit**
- 4 low temp sensors for batteries **In power manager unit**
- 4 current sensors for pyros **In actuator power unit**
- 4 current sensors for batteries **In power manager unit**
- 4 deployment sensors **In actuator power unit**
- 4 actuator sensors **In actuator power unit**
- 3 axis IMU **In main control unit and failure recovery unit**
- 1 barometer **In main control unit and failure recovery unit**

**Low Speed Payload** All the low speed payload will be in the low speed sensor unit.

- 4 high pressure sensors for propulsion system
- 2 low pressure sensors for pitot tube
- 4 high temp sensors for propulsion system
- 4 low temp sensors for electronics
- 4 low temp sensors for batteries
- 2 low temp sensor for ambient

**High Speed Payload** All the high speed payload will be in the high speed sensor unit.

- 9 axis IMU
- GNSS
- 4x cameras

### 3.3 Computing and Operation Module (COM)

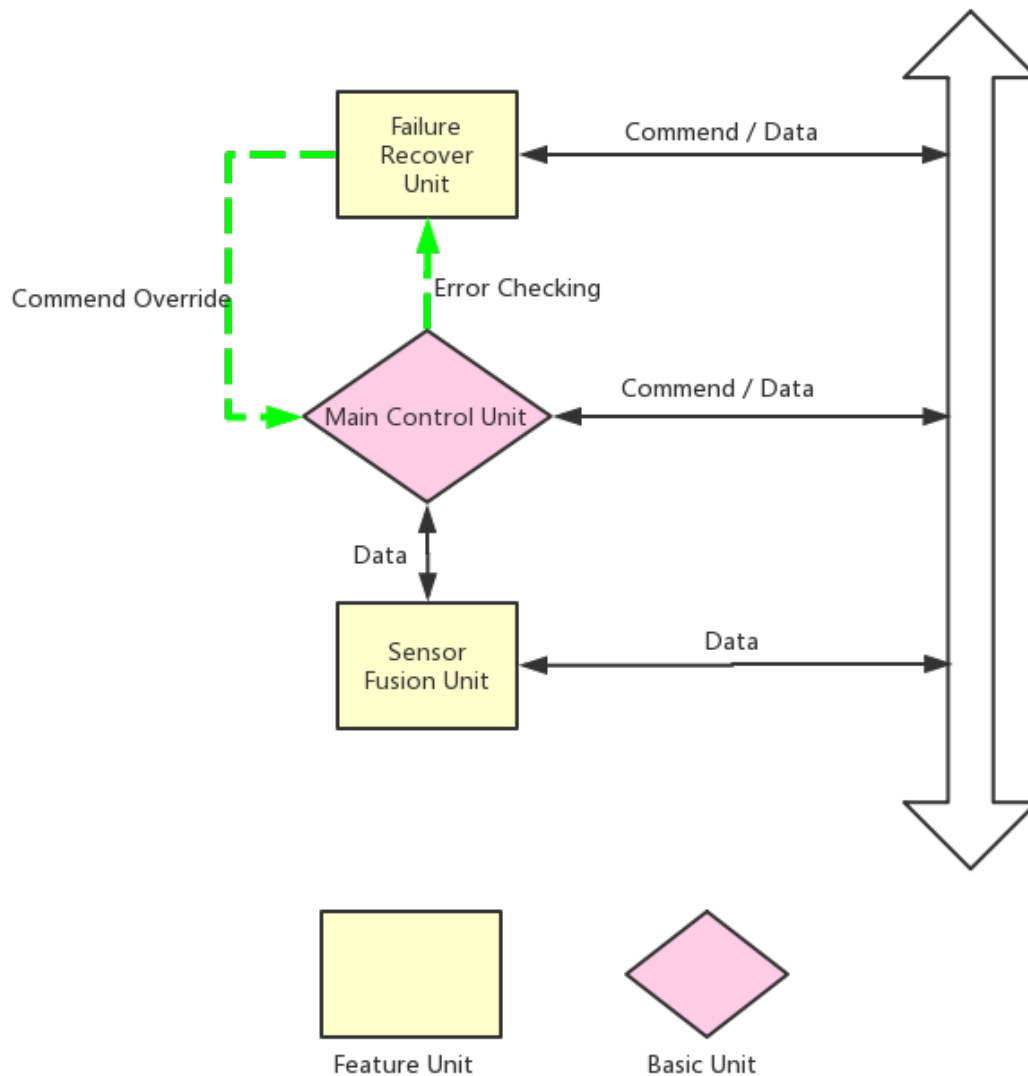


Figure 2: Computing and Operation Module Diagram

#### 3.3.1 Main Control Unit (1)

The main control unit will execute all the critical process during the whole launch. It will send commend via a commend lane to other module main unit to perform action. **This unit is require for all the OA-II VEH system.**

### 3.3.2 Failure Recover Unit (2)

The failure recover unit will execute similar code as the main control unit and detect any error that send out from the main control unit. When main control unit have error, it will inquire the main unit and check the answer. If a failure scenario is fullfill, it will take over the commend line and try to fix the problem by the program storage inside.

### 3.3.3 Sensor Fusion Unit (3)

The sensor fusion unit will communicate with the TAM and analyze the data. It will provide to the main control unit for more information.

***This unit will be include in the improved version.***



### 3.4 Telecommunication and Acquisition Module (TAM)

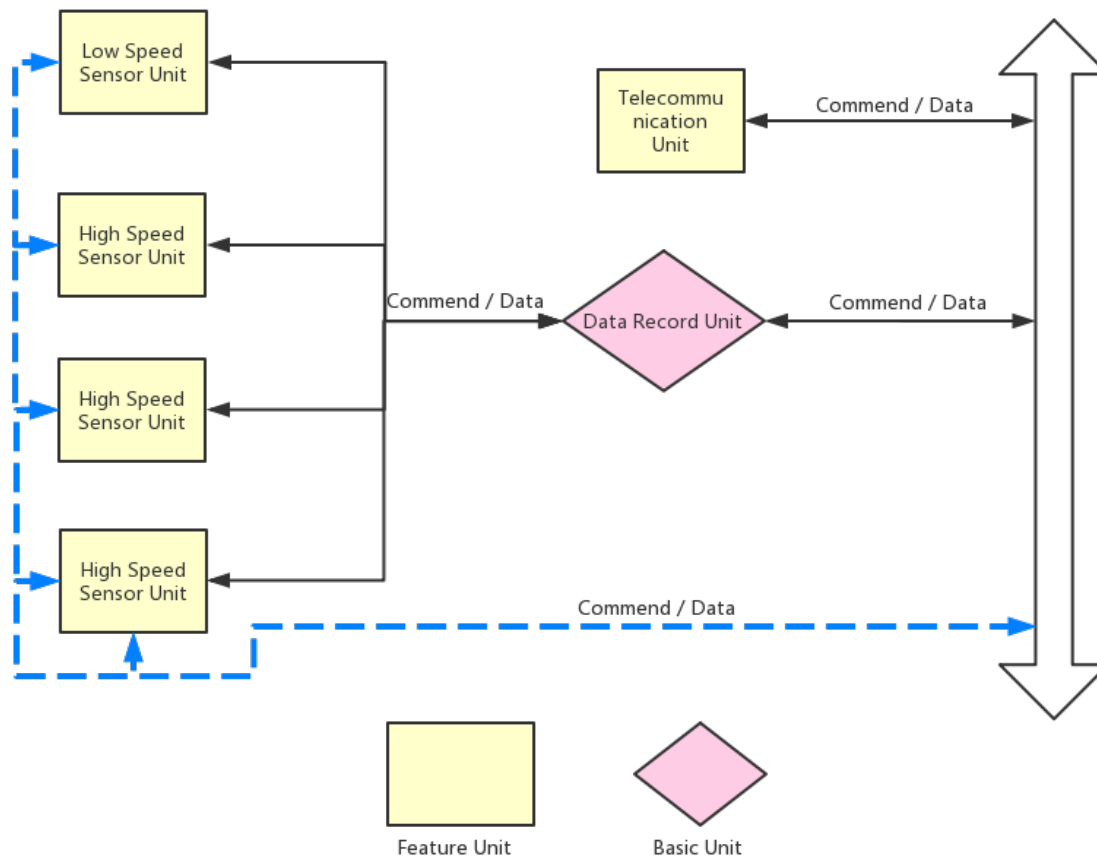


Figure 3: Telecommunication and Acquisition Module Diagram

#### 3.4.1 Data Record Unit (1)

The data record unit is used to record log and data which send from the COM control. It will also include additional protection for protect storage unit from heavy impact.

#### 3.4.2 Telecommunication Unit (2)

The telecommunication unit is used to collect data from the record unit and send it down to the base station. It also will get commend that send from the base station and relay it to the COM.

### **3.4.3 Data Acquisition Unit (3)**

The data acquisition unit is a general purpose sensor contain for translation and encoding to the backplane bus and a multi-purpose extension interface. The interface can connect to other PCB board which contain sensors and other reuqire circuit.

### 3.5 Power and Actuator Module (PAM)

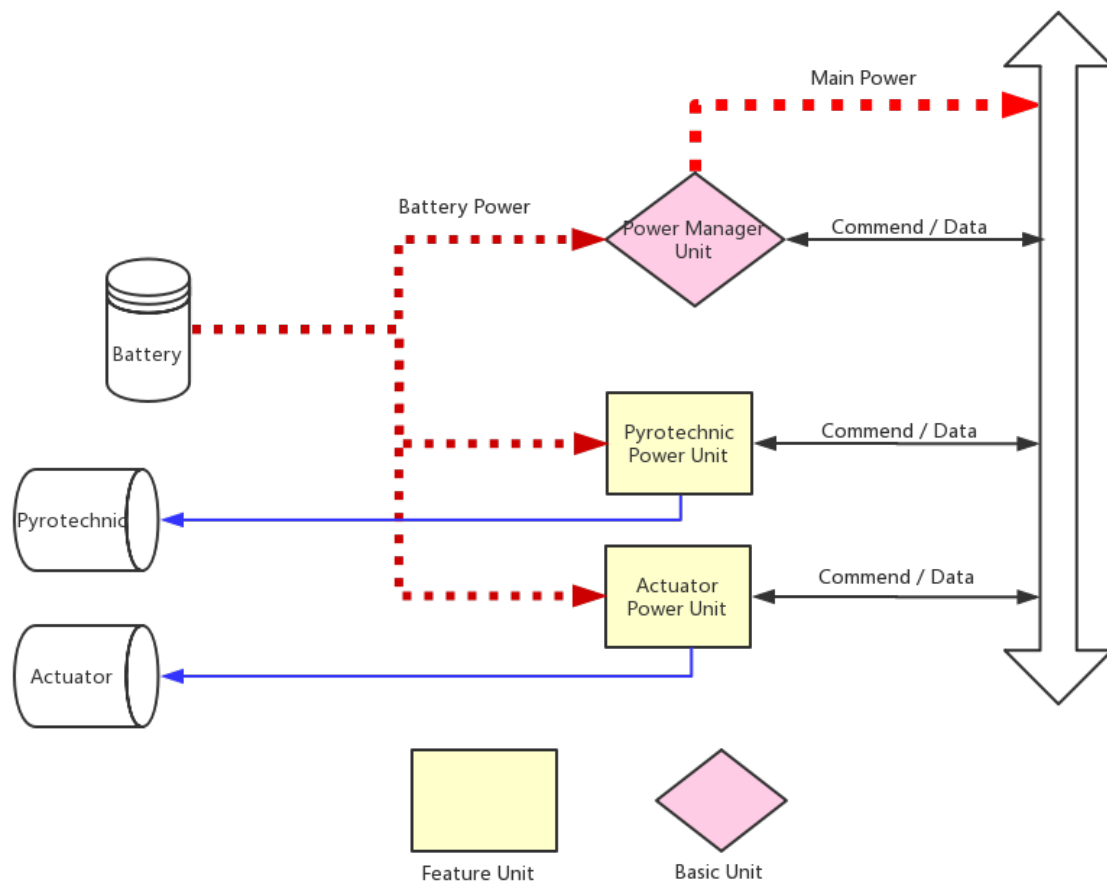


Figure 4: Power and Actuator Module Diagram

#### 3.5.1 Power Manager Unit (1)

The power manager unit is used to control charge and discharge of the on-unit main battery. It also has a regulator to provide main rail power for the whole vehicle. **This unit is required for all the OA-II VEH system.**

#### 3.5.2 Pyrotechnic Power Unit (2)

This unit contains a special purpose voltage regulator and pyrotechnic driver. It will be used to control the pyrotechnic device in the ship based on the command coming from the COM.

### **3.5.3 Actuator Power Unit (3)**

This unit contain spcial purpose voltage regulator and actuator driver. It will use to control the actuator in the ship base on the commend come from the COM.

## 4 Revision History

Rev#	Editor	Delta	Date
A01	Jinzhi Cai	Initialize	2019-7-2
-	Jinzhi Cai	change name from "board" to "unit"	2019-7-3
-	Jinzhi Cai	change product code	2019-7-3
A02	Jinzhi Cai	change PAM unit description	2019-7-3
-	Jinzhi Cai	add diagram	2019-7-3
A03	Jinzhi Cai	change DRU	2019-7-8
A04	Jinzhi Cai	add sensors	2019-7-16
A05	Jinzhi Cai	remove product code	2019-7-23
-	Jinzhi Cai	change sensor unit to one	2019-7-23

Table 1: Summary of Revision History