Parallel Programming

Data-Parallel Primitives on the GPU
Gather and Scatter

Overview

- Data-Parallel Primitives
 - Map, Prefix Scan, Scatter, Gather, Split, Sort
 - Others: Reduce, Filter, Search...
- Optimizations on the GPU

Processing Large Data Sets

```
//sequential
  for (i = 0; i < N; i++)
         h C[i] = h A[i] + h B[i];
//data-parallel
  global void VecAdd(int* A, int* B, int* C)
  int i = blockDim.x * blockIdx.x + threadIdx.x;
  C[i] = A[i] + B[i];
```

Map and Prefix Scan

Primitive: Map

Input: $R_{in}[1, ..., n]$, a map function fcn.

Output: $R_{out}[1,...,n]$.

Function: $R_{out}[i] = fcn(R_{in}[i])$.

Primitive: Prefix Scan

Input: $R_{in}[1, ..., n]$, binary operator \bigoplus .

Output: $R_{out}[1,...,n]$.

Function: $R_{out}[i] = \bigoplus_{j \le i} R_{in}[j]$.

Scatter and Gather

```
Primitive: Scatter
```

Input: $R_{in}[1, ..., n], L[1, ..., n]$.

Output: $R_{out}[1, ..., n]$.

Function: $R_{out}[L[i]] = R_{in}[i], i=1, ..., n$.

Primitive: Gather

Input: $R_{in}[1, ..., n], L[1, ..., n].$

Output: $R_{out}[1, ..., n]$.

Function: $R_{out}[i] = R_{in}[L[i]], i=1, ..., n$.

Split and Sort

```
Primitive: Split Input: R_{in}[1, ..., n], func(R_{in}[i]) \in [1, ..., F], i=1, ..., n. Output: R_{out}[1, ..., n]. Function: \{R_{out}[i], i=1, ..., n\} = \{R_{in}[i], i=1, ..., n\} and func(R_{out}[i]) \leq func(R_{out}[j]), \forall i, j \in [1, ..., n], i \leq j.
```

```
Primitive: Sort 

Input: R_{in}[1, ..., n]. 

Output: R_{out}[1, ..., n]. 

Function: \{R_{out}[i], i=1, ..., n\} = \{R_{in}[i], i=1, ..., n\} and R_{out}[i] \le R_{out}[j], \forall i, j \in [1,...,n] \text{ and } i \le j.
```

Map Example

```
// for all samples - all threads execute this code
neighbors[x][y] =
0.25f * (value[x-1][y]+
value[x+1][y]+
value[x][y+1]+
value[x][y-1]);
diff = (value[x][y] - neighbors[x][y]);
diff *= diff; // squared difference
```

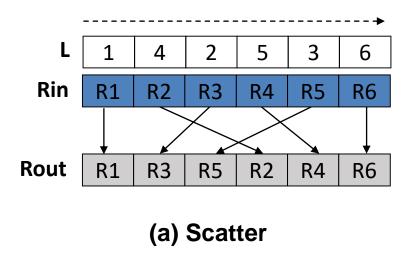
- Load from GPU memory, compute, store to GPU memory
- Make computation as dense as possible to amortize memory access cost
- Maximize number of concurrent threads

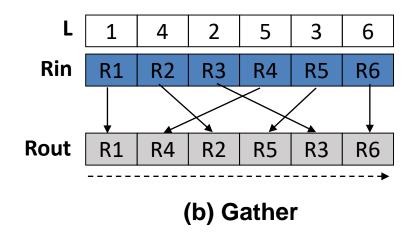
Scatter and Gather: Overview

- Widely supported
 - Parallel programming languages, e.g., MPI, NESL, ZPL.
 - Supercomputers, e.g., Cray MTA, Stanford Merrimac
 - Commodity co-processors (IBM Cell, GPUs)
- Irregular access patterns
 - Sparse matrix computations, hashing, searching, etc.
- Performance is memory bandwidth limited
 - Require high bandwidth architectures
 - HPC benchmarks (HPC Challenge, NAS PB, etc.)

Access Patterns

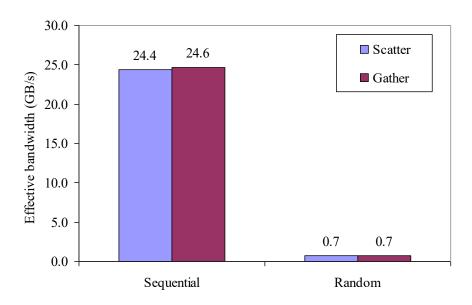
- Scatter: sequential reads and random writes.
- Gather: random reads and sequential writes.

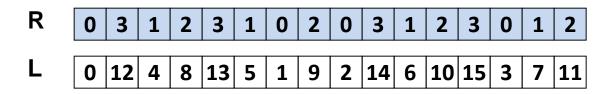




Scatter and Gather on the GPU

 Access pattern makes a 30X difference in performance [Supercomputing 2007].

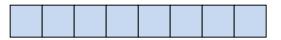




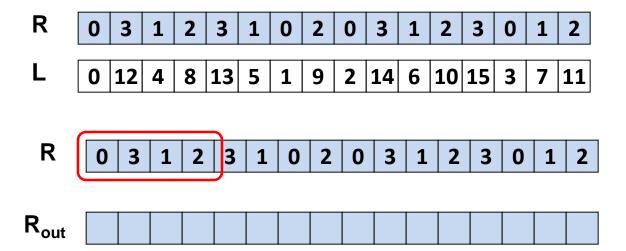
4 mem. blocks to write

4 concurrent threads

2 cache lines



Cache



4 mem. blocks to write

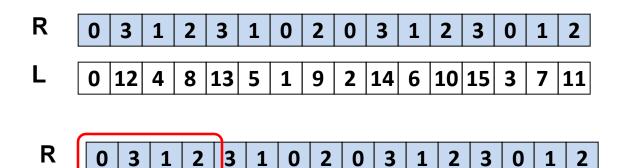
4 concurrent threads

2 cache lines



Cache

3

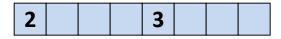


Rout

4 mem. blocks to write

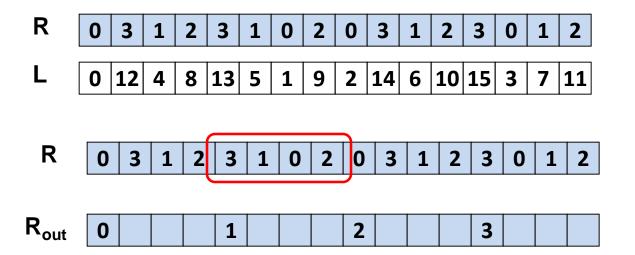
4 concurrent threads

2 cache lines



Cache

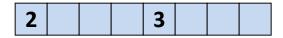
Cache Misses = 4
Cache Hits = 0



4 mem. blocks to write

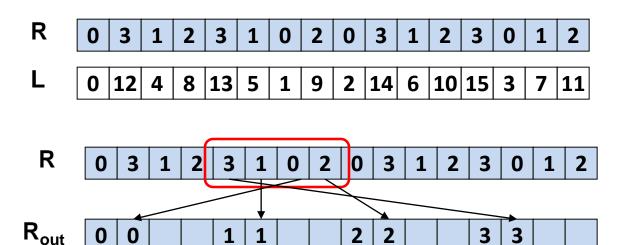
4 concurrent threads

2 cache lines



Cache

Cache Misses = 4
Cache Hits = 0



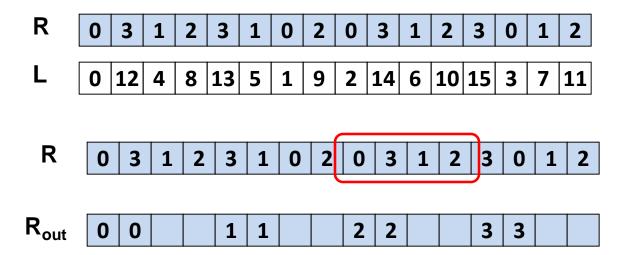
4 mem. blocks to write 4 concurrent threads

2 cache lines



Cache

Cache Misses = 6 Cache Hits = 2



4 mem. blocks to write

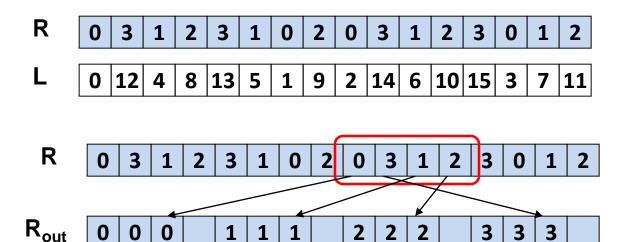
4 concurrent threads

2 cache lines



Cache

Cache Misses = 6 Cache Hits = 2

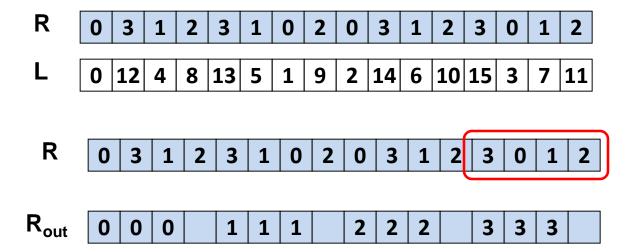


4 mem. blocks to write 4 concurrent threads

2 cache lines

Cache

Cache Misses = 8
Cache Hits = 4



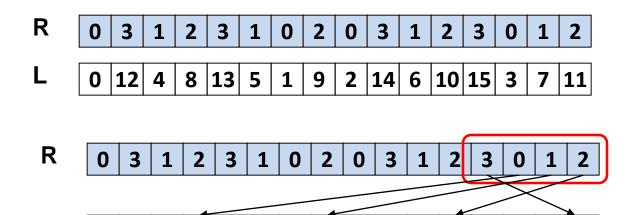
4 mem. blocks to write 4 concurrent threads

2 2 2 3 3 3

Cache

2 cache lines

Cache Misses = 8
Cache Hits = 4



Rout

4 mem. blocks to write 4 concurrent threads 2 cache lines

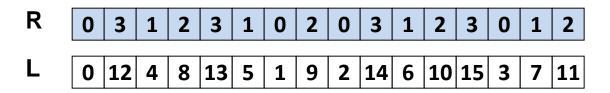
Cache

Cache Misses = 10 Cache Hits = 6

Cache miss rate = 62.5% Effective write bandwidth = |R|/Transfer Time = 4/10* B_{seq} = 0.4 B_{seq}

Multi-pass Scheme

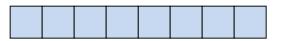
- The entire scatter is performed in multiple passes.
- Each pass writes to a small chunk



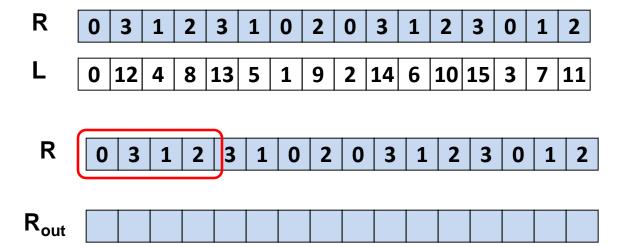
4 mem. blocks to write

4 concurrent threads

2 cache lines



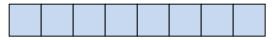
Cache



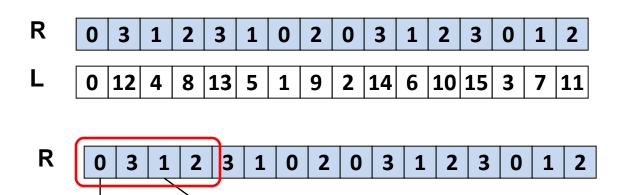
4 mem. blocks to write

4 concurrent threads

2 cache lines



Cache



R_{out}

4 mem. blocks to write

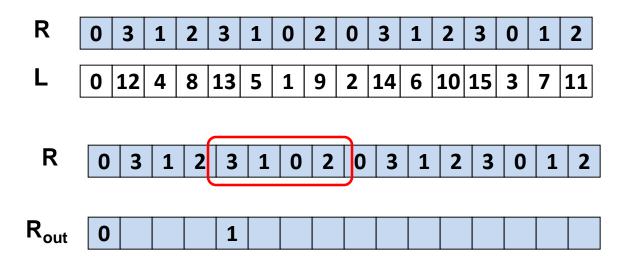
4 concurrent threads

2 cache lines



Cache

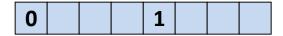
Cache Misses = 2 Cache Hits = 0



4 mem. blocks to write

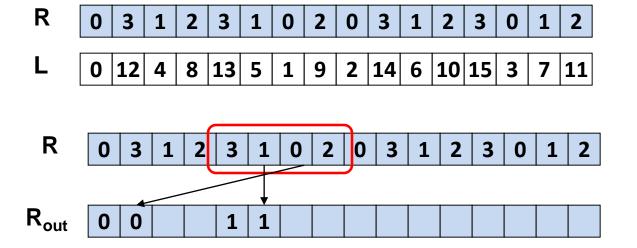
4 concurrent threads

2 cache lines



Cache

Cache Misses = 2 Cache Hits = 0



4 mem. blocks to write

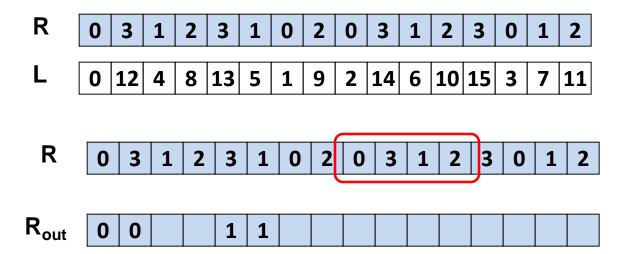
4 concurrent threads

2 cache lines



Cache

Cache Misses = 2 Cache Hits = 2



4 mem. blocks to write

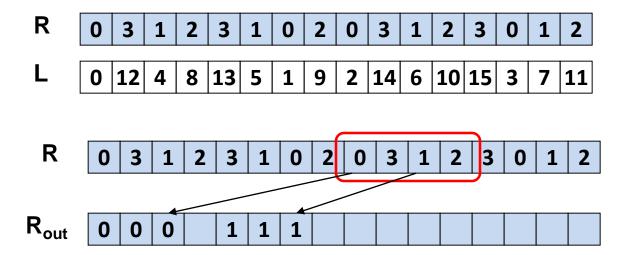
4 concurrent threads

2 cache lines



Cache

Cache Misses = 2 Cache Hits = 2



4 mem. blocks to write

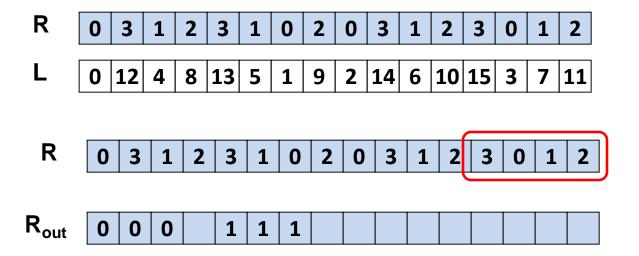
4 concurrent threads

2 cache lines



Cache

Cache Misses = 2 Cache Hits = 4



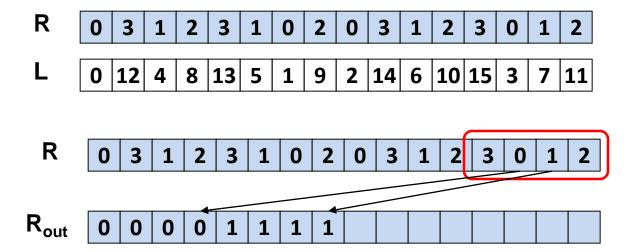
4 mem. blocks to write 4 concurrent threads

2 cache lines



Cache

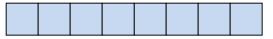
Cache Misses = 2 Cache Hits = 4



4 mem. blocks to write

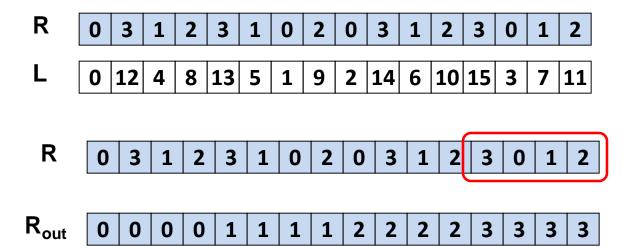
4 concurrent threads

2 cache lines

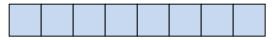


Cache

Cache Misses = 2 Cache Hits = 6



4 mem. blocks to write 4 concurrent threads 2 cache lines



Cache

Cache Misses = 4 Cache Hits = 12

Cache miss rate = 25%Effective write bandwidth = B_{seq}

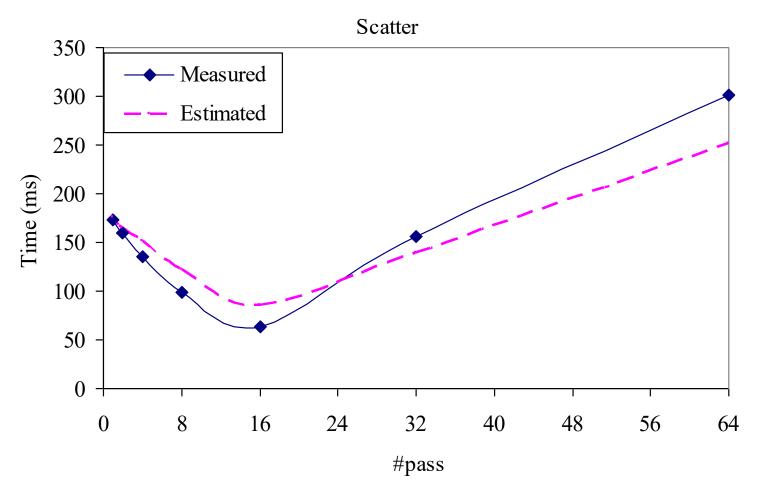
Cost Model

- Estimate the performance of different access patterns
 - Sequential bandwidth
 - Random bandwidths of different degrees
- Estimate the total cost of sequential access and random access in the multi-pass scheme.

$$T_{\text{scatter}} = (|R| + |L|) * \text{npasses/B}_{\text{seq}} + |R|/B_{\text{rand}}$$

Determine the optimal number of passes.

Performance Results -- Multi-pass Scatter



The optimal number of passes is 16.

Applications and Analysis

Applications

Radix sort, hash search, and sparse-matrix vector multiplication

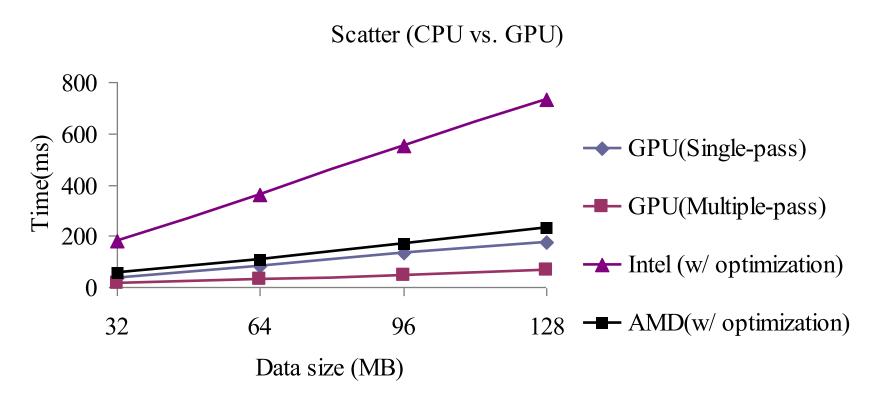
Platforms

- CPUs: Intel Quad, or two AMD dual-core processors.
- GPU: Nvidia 8800 GTX.

Overall results

- The cost model has an accuracy of over 85%.
- The multipass scheme improves the application 10%~50%.
- The GPU-based algorithm outperforms the CPU-based algorithm by 2-7X.

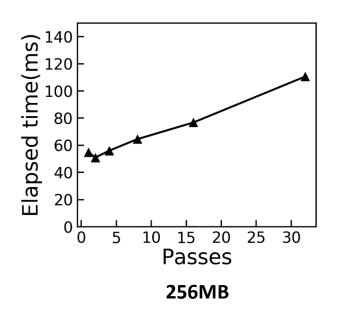
Performance Impact of Multi-Pass Scatter

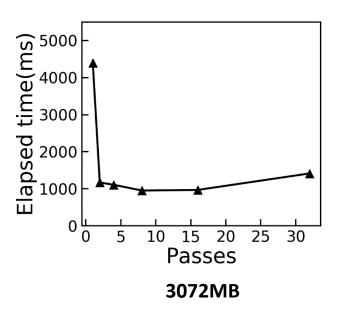


- (1) The speedup is 7-13X and 2-4X on Intel and AMD, respectively.
- (2) The multi-pass scheme improves the GPU-based scatter by 2-4X.

Newer Results (2018)

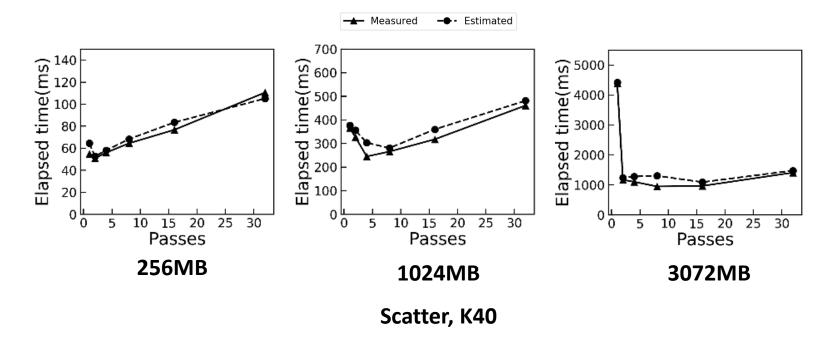
- Multi-pass scatter & gather on modern GPUs
 - Nvidia Tesla K40 GPU (LLC: 1536 KB)
 - 256MB & 3072MB 4-byte tuples
 - Random data distribution





New Performance Model (2018)

 Considering not only data caching but also Translation Lookaside Buffer (TLB) caching



Summary

- Data-parallel primitives are an effective way of utilizing GPU's parallelism.
- Scatter and gather are memory-bound and can be optimized through multi-pass schemes.

References:

Bingsheng He, Naga K. Govindaraju, Qiong Luo, and Burton Smith. Efficient Gather and Scatter Operations on Graphics Processors. ACM/IEEE SuperComputing (SC), Nov 2007.

Zhuohang Lai, Qiong Luo, Xiaoying Jia: Revisiting Multi-pass Scatter and Gather on GPUs. ICPP 2018: 25:1-25:11