

AAAI 2023 Optimization with Constraint Learning Lab

Part IV: DOFramework

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Overview

- 1 Decision Optimization
- 2 DOFramework
- 3 Profiling
- 4 Design
- 5 Deployment

Mathematical Decision Optimization (DO)

Mathematical Decision-Optimization (DO) Model $M(\mathbf{w})$ (*):

$$\begin{aligned} \mathbf{x}^*(\mathbf{w}) \in \arg \min_{\mathbf{x} \in \mathbb{R}^n, \mathbf{y} \in \mathbb{R}^m} \quad & f(\mathbf{x}, \mathbf{y}, \mathbf{w}) \\ \text{s.t.} \quad & \mathbf{g}(\mathbf{x}, \mathbf{y}, \mathbf{w}) \leq \mathbf{0} \\ & \mathbf{y} = \mathbf{h}(\mathbf{x}, \mathbf{w}) \\ & \mathbf{x} \in \Omega(\mathbf{w}) \end{aligned}$$

$\mathbf{w} \in \mathbb{R}^k$ – fixed uncontrollable.

$\Omega(\mathbf{w})$ – polytope (possibly unbounded).

(*) Maragno*, D., Wiberg*, H., Bertsimas, D., Birbil, S. I., Hertog, D. d., and Fajemisin, A. (2021). *Mixed-Integer Optimization with Constraint Learning*.

Mathematical Decision Optimization (DO)

Learned DO Model $\hat{M}(\mathbf{w})$:

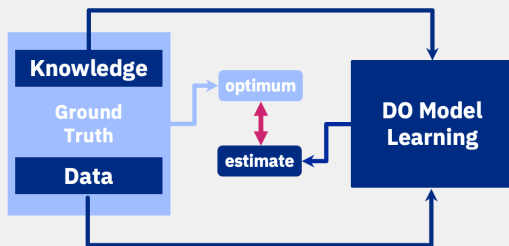
$$\begin{aligned} \hat{\mathbf{x}}^*(\mathbf{w}) \in \arg \min_{\mathbf{x} \in \mathbb{R}^n, \mathbf{y} \in \mathbb{R}^m} \quad & \hat{f}(\mathbf{x}, \mathbf{y}, \mathbf{w}) && \Leftarrow \text{learn} \\ \text{s.t.} \quad & \mathbf{g}(\mathbf{x}, \mathbf{y}, \mathbf{w}) \leq \mathbf{0} \\ & \mathbf{y} = \hat{\mathbf{h}}(\mathbf{x}, \mathbf{w}) && \Leftarrow \text{learn} \\ & \mathbf{x} \in \Omega(\mathbf{w}) \end{aligned}$$

$\mathbf{w} \in \mathbb{R}^k$ – fixed uncontrollable.

$\Omega(\mathbf{w})$ – polytope (possibly unbounded).

- UN World Food Programme (INFORMS Edelman Award 2021): Food palatibility prediction in food basket cost minimization.
- Louisville Metropolitan Sewer District and Tetra Tech (INFORMS Edelman Award 2019 Finalist): Rainfall prediction in wastewater storage maximization.

DOFramework: a testing framework for DO model learners.



Knowledge
 Ω

Bounded convex polytope $\Omega \subseteq \text{dom}(f) \subseteq \mathbb{R}^d$, $d = n + m + k \geq 2$.

Ground
Truth f

Continuous PWL f with (combinatorially) known $\mathbf{x}^* \in \arg \min_{\mathbf{x} \in \Omega} f(\mathbf{x})$.

Data D

Gaussian mix model in $\text{dom}(f)$.

DO Problem Instance: $(f, \Omega, D, \mathbf{x}^*)$

Estimate $\hat{\mathbf{x}}^*$ score:

$$\text{score}(\hat{\mathbf{x}}^*) = \frac{f(\hat{\mathbf{x}}^*) - f(\mathbf{x}^*)}{f_{\max} - f_{\min}}$$

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$$\text{score}(\hat{\mathbf{x}}^*) = \frac{f(\hat{\mathbf{x}}^*) - f(\mathbf{x}^*)}{f_{\max} - f_{\min}} \implies \text{score density}$$

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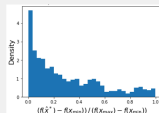
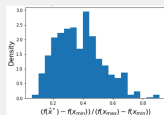
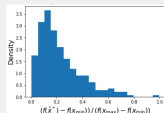
Solution Quality Probability:

$$Pr[f(\hat{\mathbf{x}}^*) - f(\mathbf{x}^*) < \epsilon(f_{\max} - f_{\min})]$$

dim = 2,3
probs = 570

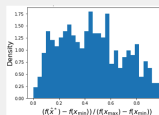
OptiCL

dim = 5,7
probs = 615



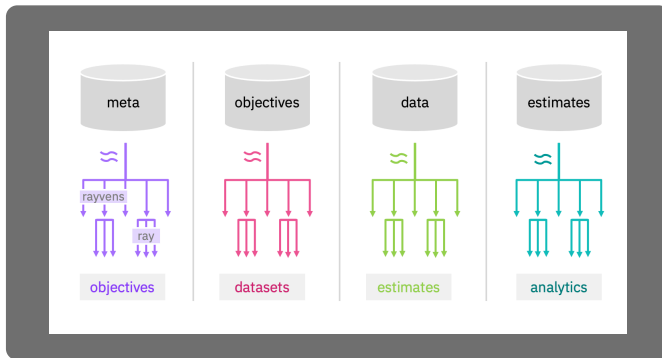
dim = 2,3
probs = 640

Baseline



dim = 5,7
probs = 680

- Maragno, Wiberg. *OptiCL: Mixed-integer optimization with constraint learning* (2021).
<https://github.com/hwiberg/OptiCL/>.
- Mitchell, OSullivan, Dunning. *PuLP: A Linear Programming Toolkit for Python* (2011).
<https://coin-or.github.io/pulp/>.



- Moritz et. al.. *Ray: A Distributed Framework for Emerging AI Applications* (OSDI 2018).
<https://github.com/ray-project/ray>.
- Bercea, Tardieu. *Rayvens: Event sources and sinks on Ray*, <https://github.com/project-codeflare/rayvens>

Deployment

Requirements:

- Storage: Local / Cloud Object Storage (~/`project_folder/configs.yaml`)
- Compute: Local / K8S Cluster (AWS / IBM Cloud)

Installation:

```
$ pip install doframework
$ cd ~/project_folder
$ doframework-setup.sh --configs configs.yaml
```

Running:

```
$ python user_module.py
$ ray submit doframework.yaml user_module.py
```

```
import doframework as dof

@dof.resolve
def alg(data: np.array, constraints: np.array, **kwargs):
    ...
    return optimal_arg, optimal_val, regression_model

if __name__ == '__main__':
    ...
    dof.run(alg, 'configs.yaml', objectives=5, datasets=3)
```

input.json

```
{
  "f": {
    "vertices": {
      "num": 7,
      "range": [[5.0,20.0],[0.0,10.0]],
    },
    "values": {
      "range": [0.0,5.0]
    },
  },
  "omega" : {
    "ratio": 0.8
  },
  "data" : {
    "N": 750,
    "policy_num": 2,
    "scale": 0.4,
    "noise": 0.01
  },
  "input_file_name": "input.json"
}
```