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# Optimization with Constraint Learning LAB

## Part I

**Speaker: Donato Maragno**

*University of Amsterdam*

February 8, 2023





# Before starting

[https://github.com/ordavidov/ocl\\_lab](https://github.com/ordavidov/ocl_lab)

# Agenda

- Introduction to mathematical optimization
- Introduction to Constraint Learning
- Chemotherapy case study
- Embedding Predictive Models
- Trust region constraints
- Hands-on tutorial

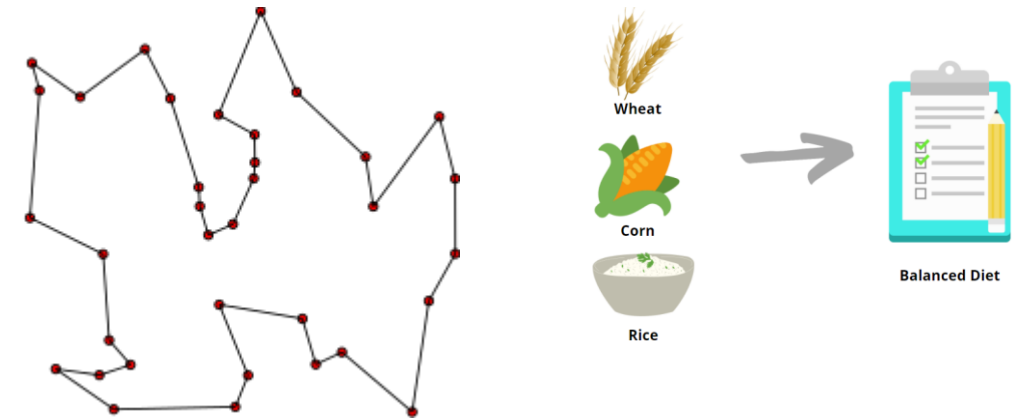
# Mathematical Optimization

An optimization problem seeks to find the best (smallest or largest) value of a quantity given certain limits to the problem.

It can be expressed as a **minimization** (or maximization) of a quantity subject to a set of **constraints**.

Some examples:

- Travelling salesperson problem: minimize distance s.t. each city visited exactly once
- Diet problem: minimize cost s.t. nutrient requirements
- knapsack problem: maximize the value of objects in the knapsack s.t. capacity constraints



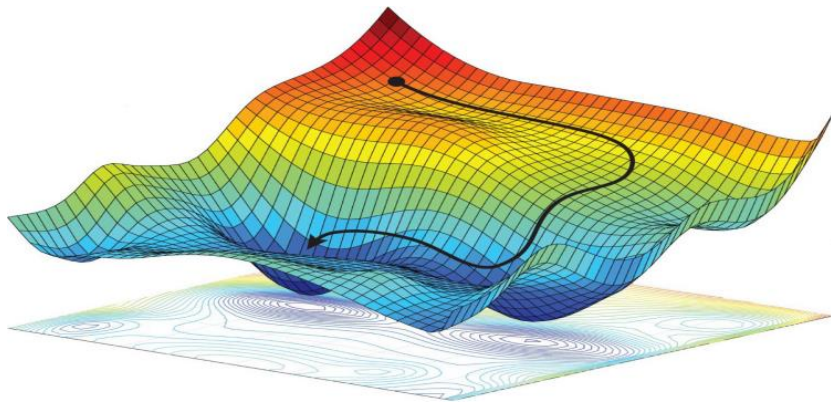
# Mathematical Optimization

The general form of an optimization model is:

$$\min_{x \in \mathbb{R}^n} f(x_1, \dots, x_n) \rightarrow \textit{Objective function}$$

$$\textit{subject to } g_i(x_1, \dots, x_n) \leq 0, i = 1, \dots, m \rightarrow \textit{Constraints}$$

where  $x_1, \dots, x_n$  are the decision variables and the goal is to find a value for each of them such that the constraints are satisfied and the objective value is minimized.



# Mathematical Optimization



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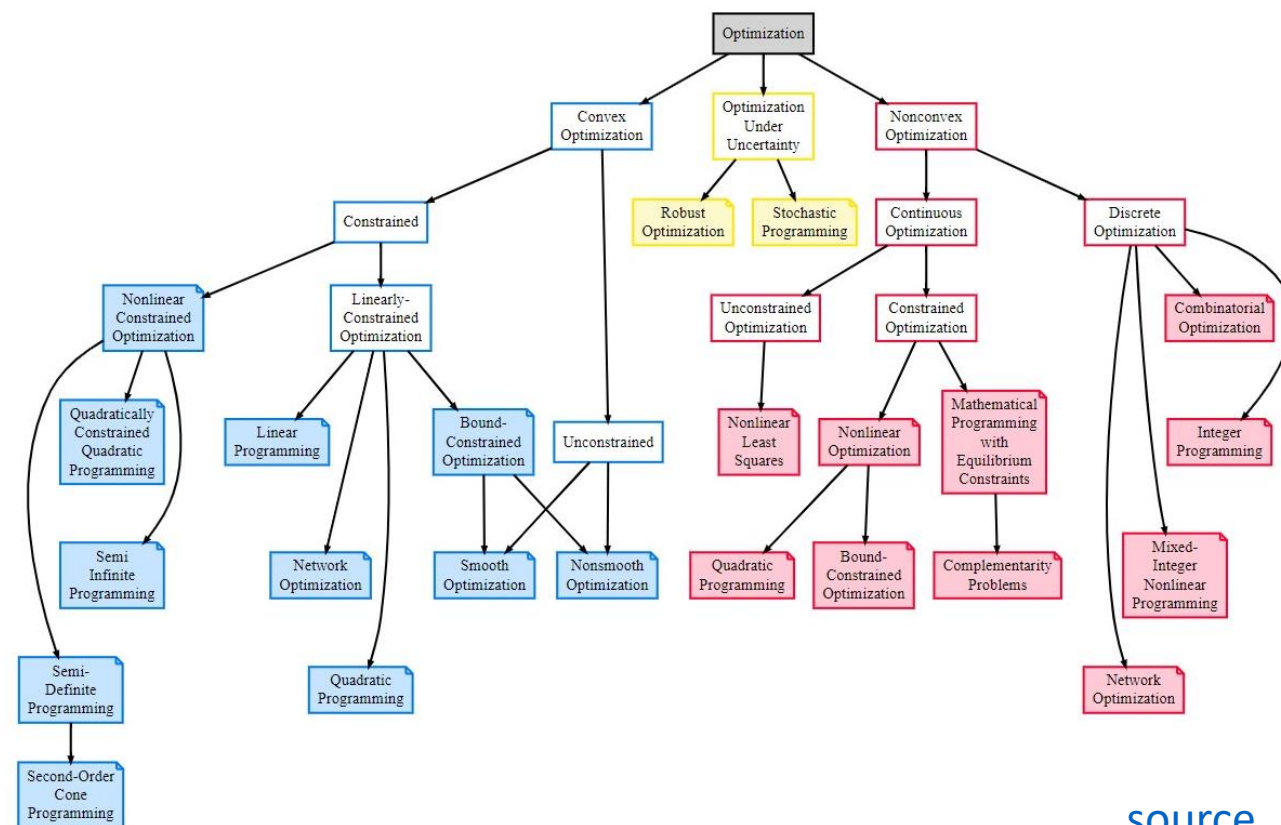
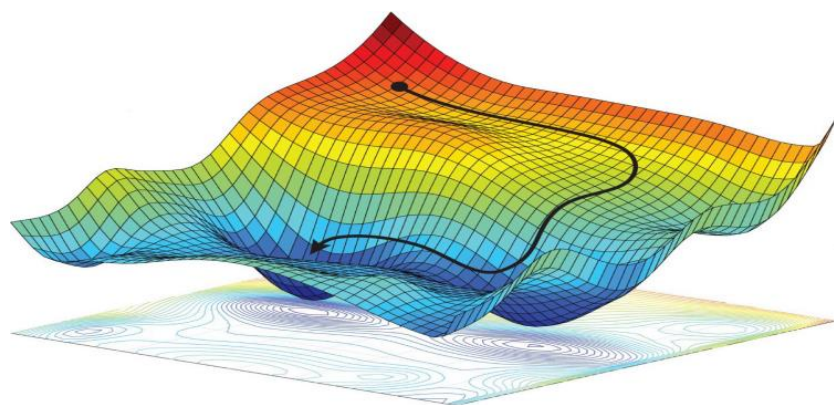


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[source](#)

## Mixed-Integer Optimization (MIO)

Powerful tool that allows us to optimize a given objective subject to various constraints.

Many real-life optimization problems contain one or more constraints or objectives for which **there are no explicit formulae**.

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Many real-life optimization problems contain one or more constraints or objectives for which **there are no explicit formulae**.

## Machine Learning (ML)

Data is available and machine learning models can be used to **learn the constraints**.





# Case Study



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Optimize the food baskets delivered by WFP to population groups in need.

- Minimize the procurement costs.
- Nutrient requirements constraints
- The food basket must be **palatable**



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minimize  $x \in \mathbb{R}_{\geq 0}^n$   $f(x)$



*Procurement costs*

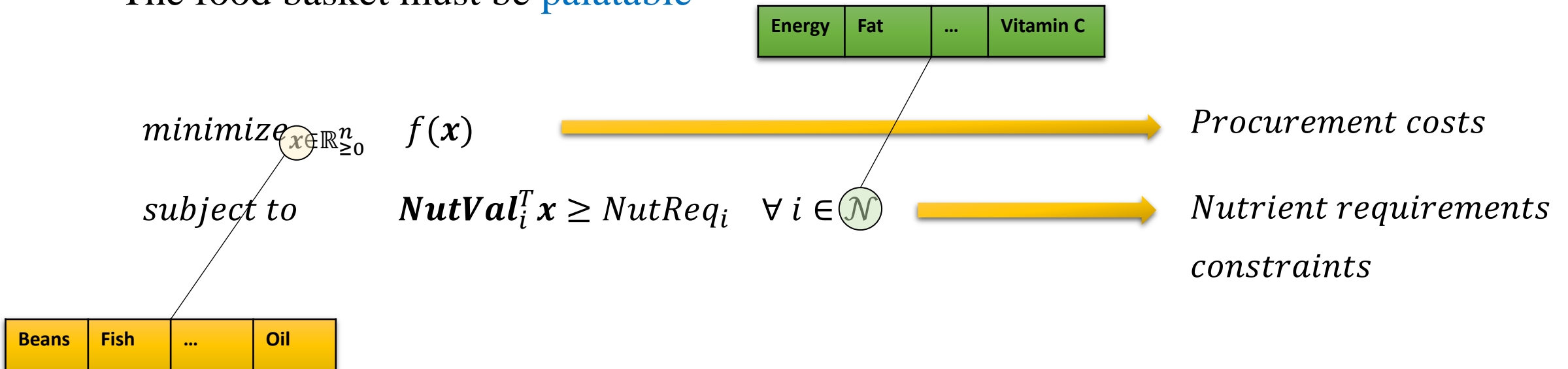
Beans	Fish	...	Oil
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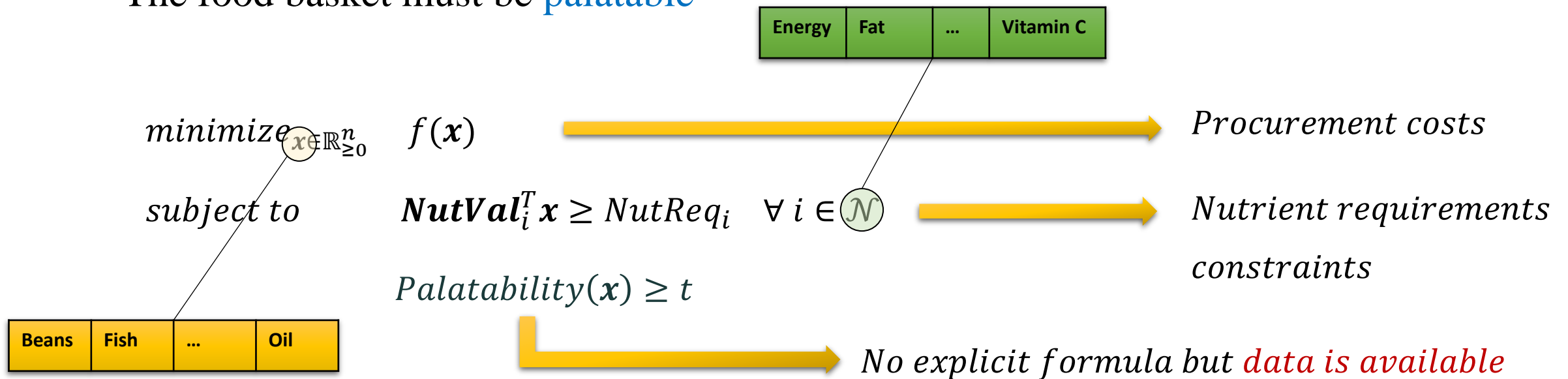




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# Applications of Constraint Learning

Table 1: Methods used for constraint learning

	Neural Networks	Decision Trees	Random Forest	Other Ensemble	Support Vector Machines	Clustering	(M)ILP	Other
Bergman et al. (2019)	x							x
Biggs et al. (2018)		x	x					
Chen et al. (2020)	x							
Chi et al. (2007)					x			
Cozad et al. (2014)							x	x
Cremer et al. (2018)		x		x				
De Angelis et al. (2003)	x							
Fahmi and Cremaschi (2012)	x							x
Garg et al. (2018)					x			
Grimstad and Andersson (2019)	x							
Gutierrez-Martinez et al. (2010)	x							
Halilbašić et al. (2018)		x						
Jalali et al. (2019)					x			
Kudła and Pawlak (2018)		x						
Lombardi et al. (2017)	x	x						
Maragno et al. (2022)	x	x	x	x	x	x		x
Mišić (2020)		x	x					
Paulus et al. (2021)	x							
Pawlak and Krawiec (2017a)							x	
Pawlak and Krawiec (2017b)								x
Pawlak and Krawiec (2018)								x
Pawlak (2019)								x
Pawlak and Litwiniuk (2021)						x		x
Pawlak and O'Neill (2021)							x	x
Prat and Chatzivasileiadis (2020)		x						
Say et al. (2017)	x							
Schede et al. (2019)		x					x	
Schweidtmann and Mitsos (2019)	x							
Spyros (2020)	x	x						
Sroka and Pawlak (2018)						x		x
Thams et al. (2017)		x						
Venzke et al. (2020b)	x							
Verwer et al. (2017)								
Xavier et al. (2021)								
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Fajemisin A, Maragno D, den Hertog D (2021) Optimization with constraint learning: A framework and survey. URL <https://arxiv.org/abs/2110.02121>.

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## Global Optimization via Optimal Decision Trees

Dimitris Bertsimas

Sloan School of Management, Massachusetts Institute of Technology, Cambridge, MA, USA, dbertsim@mit.edu

Berk Öztürk

Department of Aeronautics and Astronautics, Massachusetts Institute of Technology, Cambridge, MA, USA, bozturk@mit.edu

Approximate non-convex function with Decision trees

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# Constraint Learning

$x$  Decision variables

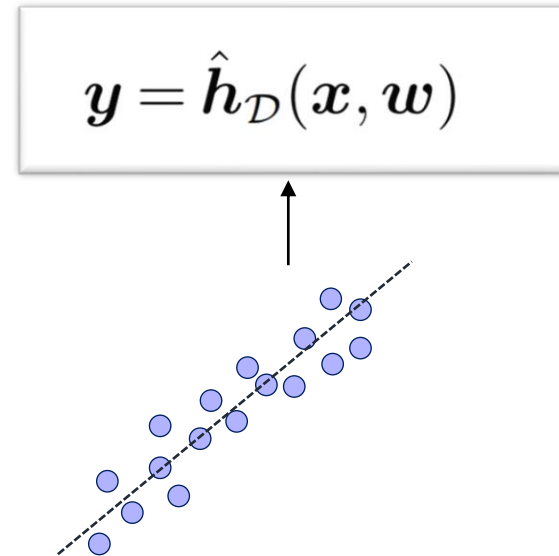
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# Constraint Learning

$x$  Decision variables  
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$$D = \{(\bar{x}_i, \bar{w}_i, \bar{y}_i)\}_{i=1}^N \longrightarrow$$





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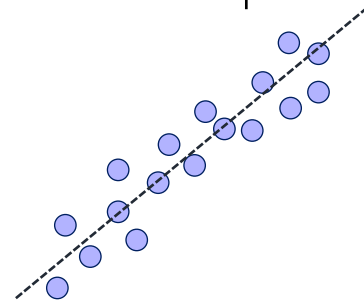
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$$\text{s.t. } g(\mathbf{x}, \mathbf{w}, \mathbf{y}) \leq 0$$

$$\mathbf{y} = \hat{\mathbf{h}}_{\mathcal{D}}(\mathbf{x}, \mathbf{w})$$

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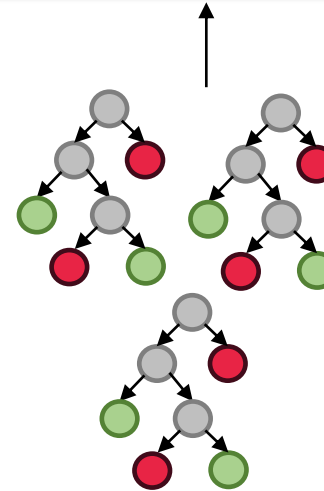
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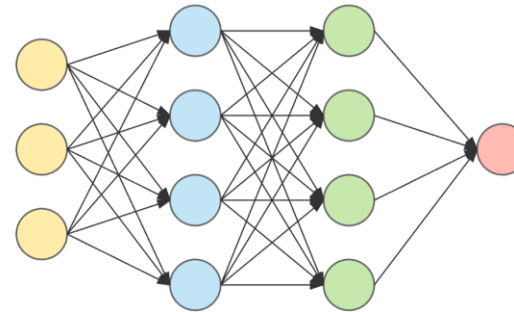
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# Chemotherapy Case Study

In this case study, we extend the work of [Bertsimas et al. \(2016\)](#)\* in the design of chemotherapy regimens for advanced gastric cancer. Given a new study cohort and study characteristics, we would like to optimize a chemotherapy regimen to **maximize the cohort's survival subject to constraint on different types of toxicity**.

$\mathbf{x}_b^d = \mathbb{I}(\text{drug } d \text{ is administered}),$   
 $\mathbf{x}_a^d = \text{average daily dose of drug } d,$   
 $\mathbf{x}_i^d = \text{maximum instantaneous dose of drug } d.$

$$\begin{aligned} \min_{\mathbf{x}, \mathbf{y}} \quad & y_{OS} \\ \text{s.t.} \quad & y_i \leq \tau_i, & i \in \mathcal{Y}_C, \\ & y_i = \hat{h}_i(\mathbf{x}, \mathbf{w}), & i \in \mathcal{Y}_C, \\ & y_{OS} = \hat{h}_{OS}(\mathbf{x}, \mathbf{w}), \\ & \sum_d \mathbf{x}_b^d \leq 3, \\ & \mathbf{x}_b \in \{0, 1\}^d, \\ & \mathbf{x} \in \mathcal{X}(\mathbf{w}). \end{aligned}$$

(\*) Bertsimas D, O'Hair A, Relyea S, Silberholz J (2016) An analytics approach to designing combination chemotherapy regimens for cancer. Management Science 62(5):1511–1531, ISSN 15265501

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## Cohort contextual variables

- Gender
- Age
- primary site breakdown
- ecog score
- ...

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## Toxicities

- Grade 3/4 constitutional
- Infection
- Neurological
- Grade 4 blood
- ...

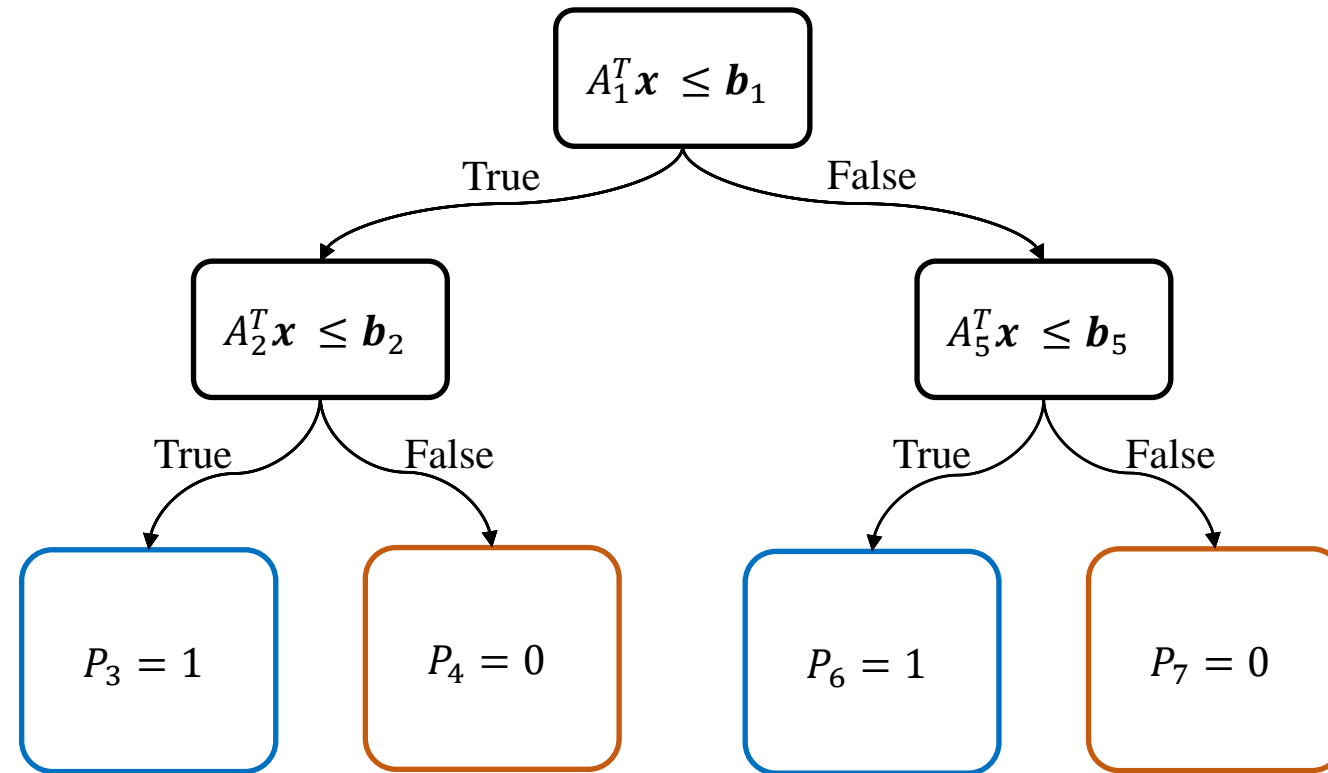
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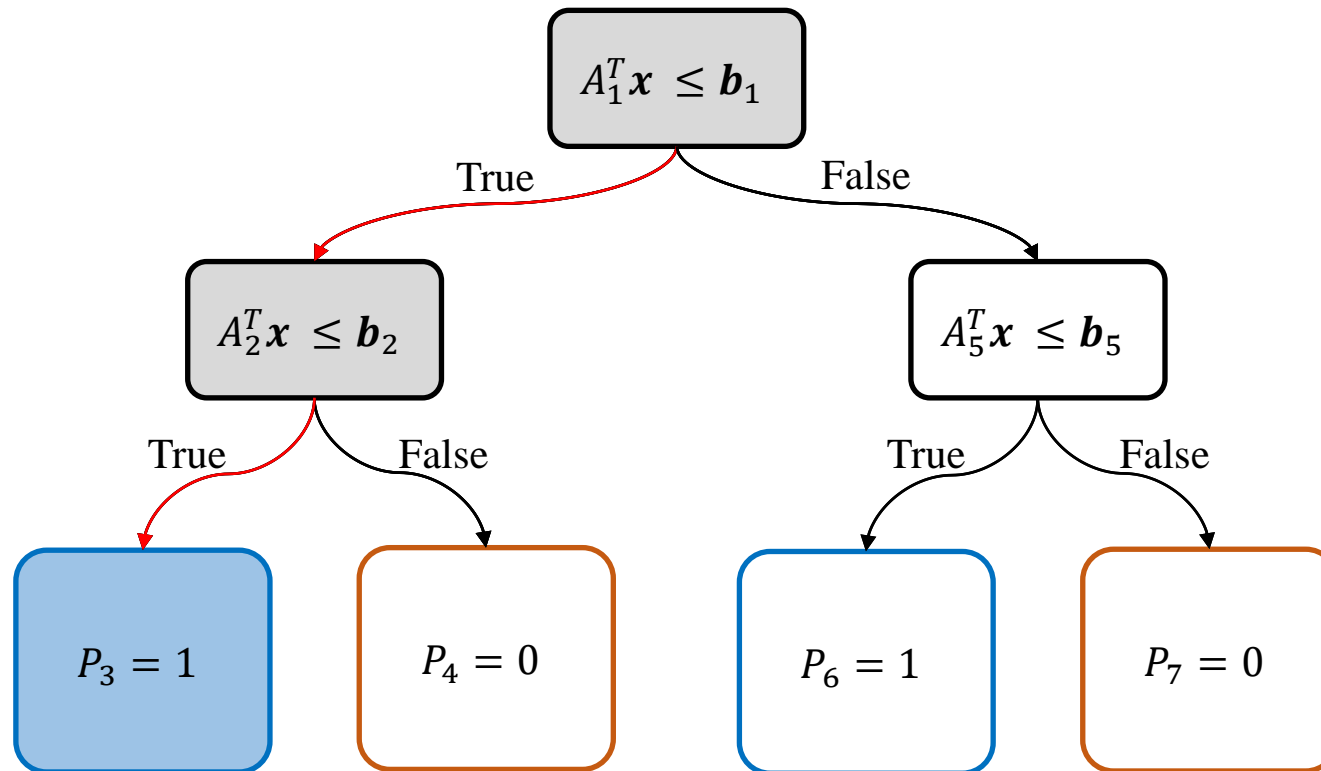
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# Embedding Decision Trees



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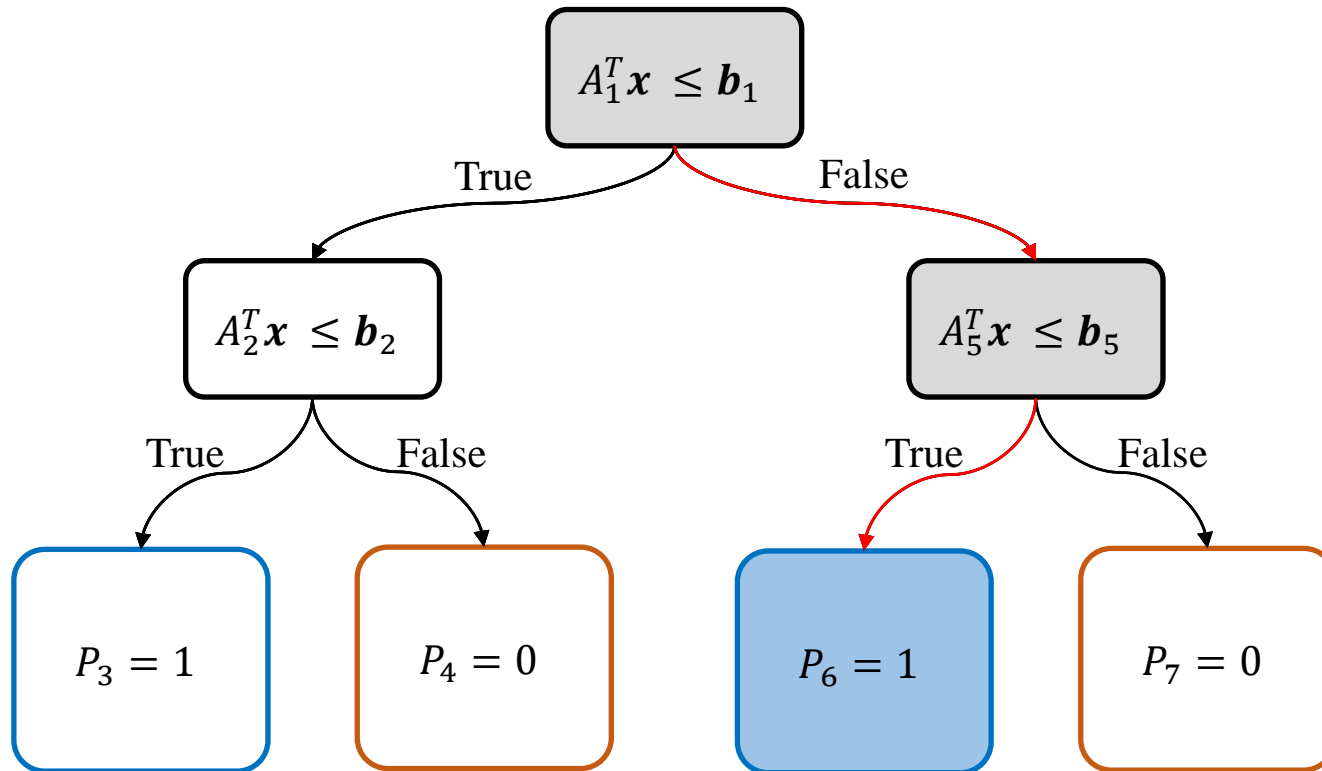


Conceptual model

$$\begin{cases} \min_{\mathbf{x}} & f(\mathbf{x}) \\ \text{s.t.} & \mathbf{g}(\mathbf{x}) \leq \mathbf{0} \end{cases}$$

$P_3$   $\begin{cases} A_1^T \mathbf{x} \leq b_1 \\ A_2^T \mathbf{x} \leq b_2 \end{cases}$

# Embedding Decision Trees



Conceptual model

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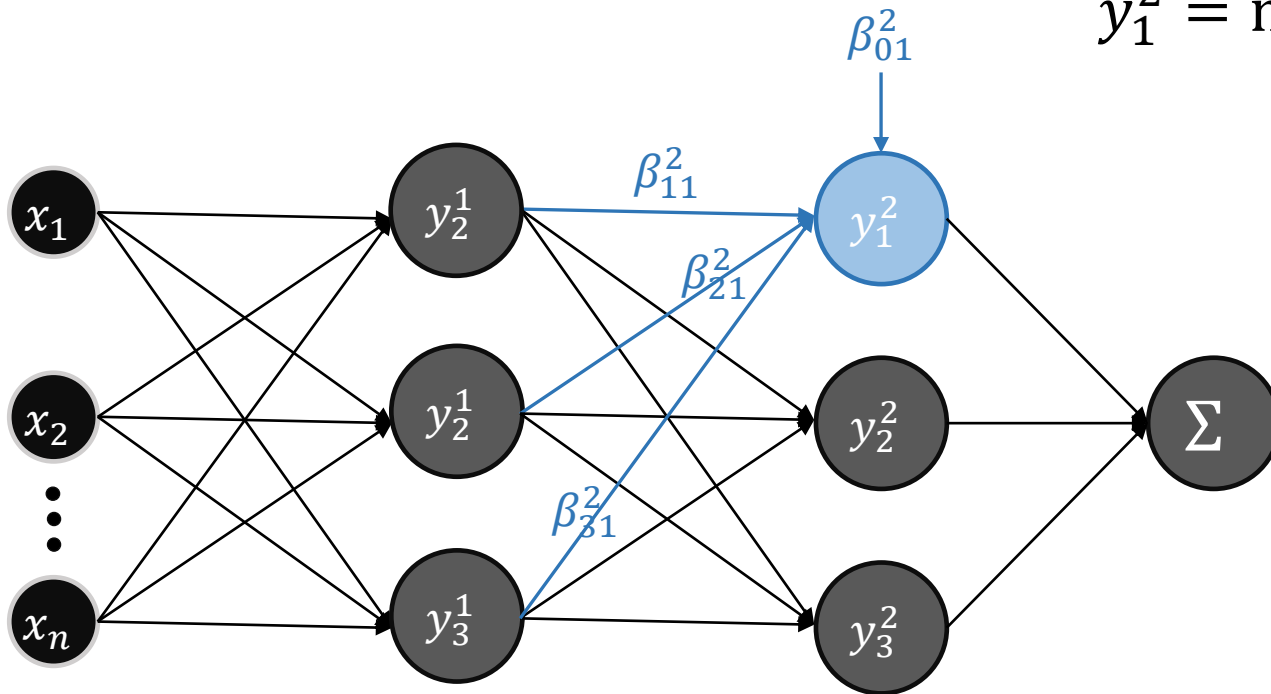
$P_6$

$$\begin{aligned} A_1^T x &\geq b_1 \\ A_5^T x &\leq b_5 \end{aligned}$$

# Embedding Neural Networks

ReLU activation function

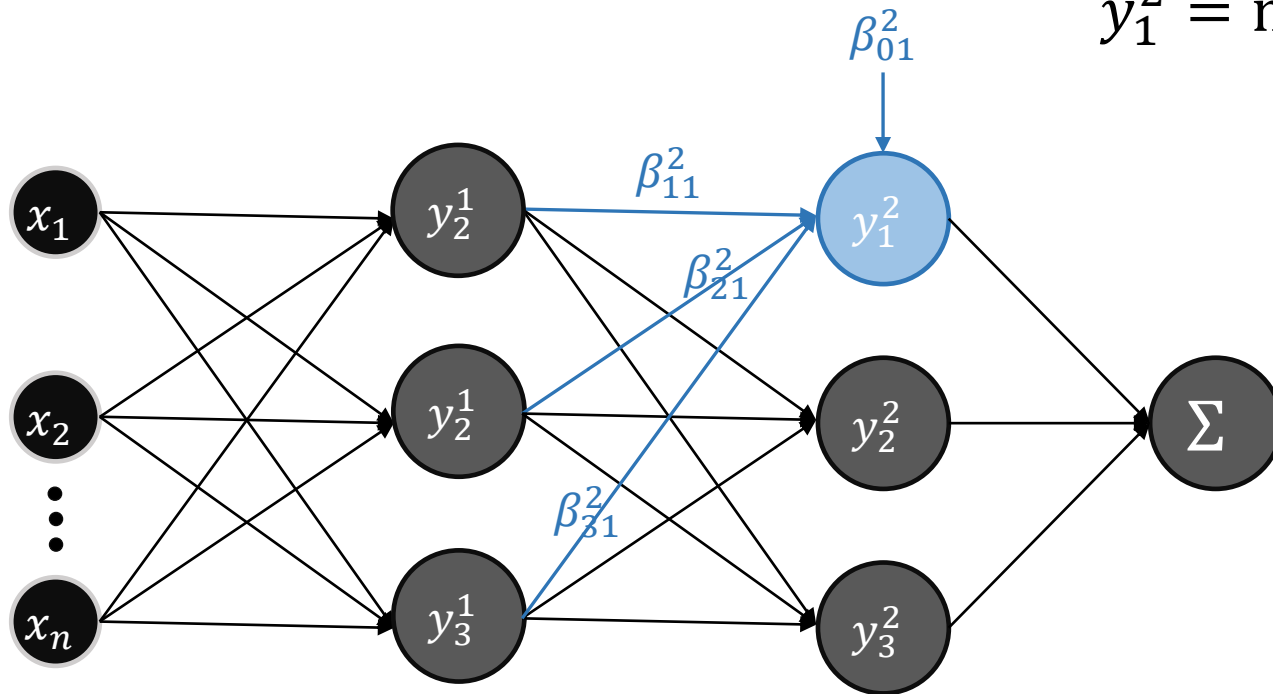
$$y_1^2 = \max \left\{ 0, \beta_{01}^2 + \boldsymbol{\beta}_1^{2T} \mathbf{y}^1 \right\}$$



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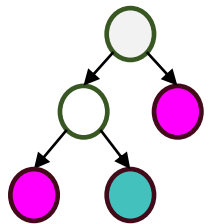
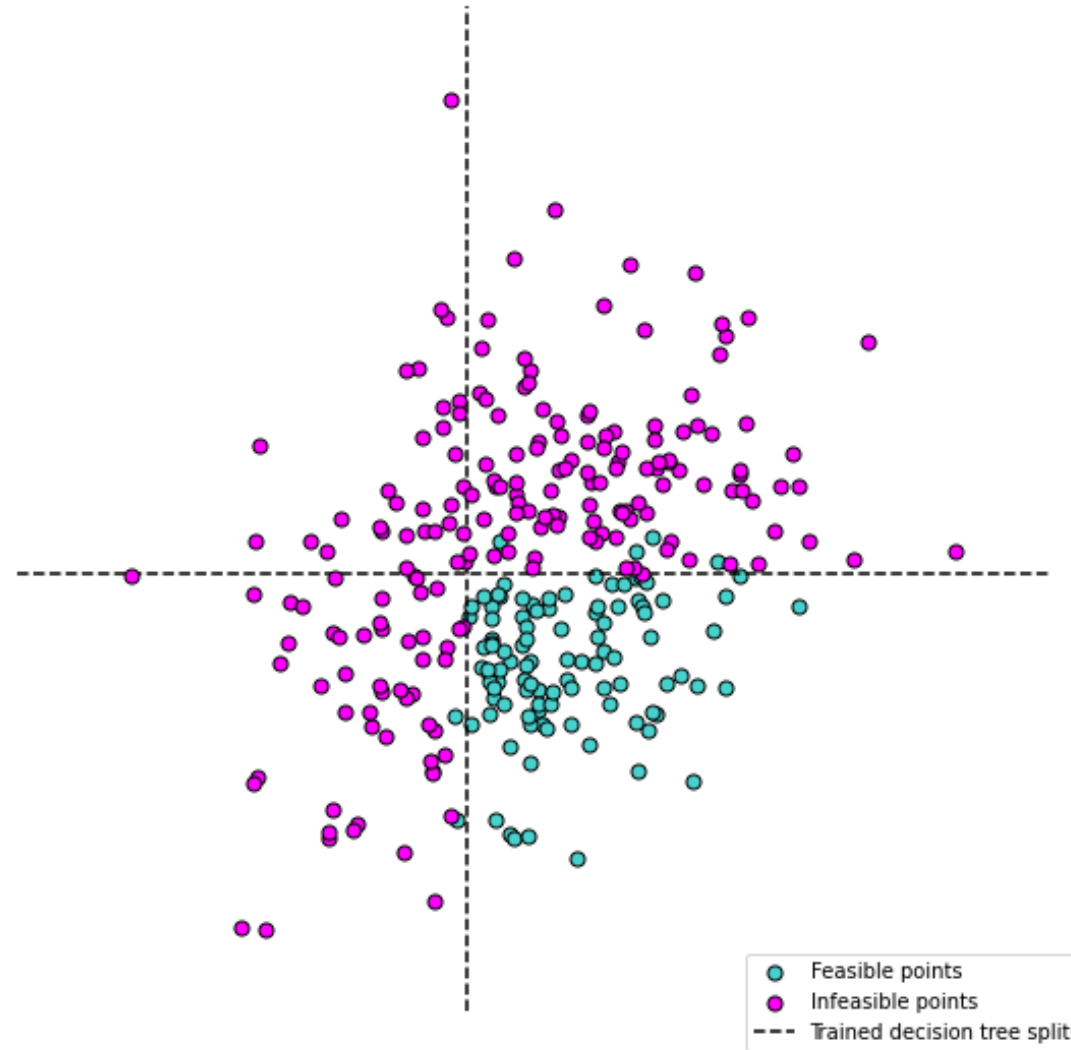
$y = \max\{0, x\}$  can also be written as:

$$\begin{cases} y \geq x, \\ y \leq x - M_L(1 - z), \\ y \leq M_U z, \\ y \geq 0, \\ z \in \{0, 1\}, \end{cases}$$

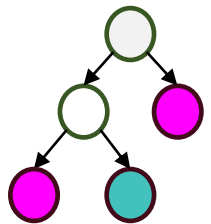
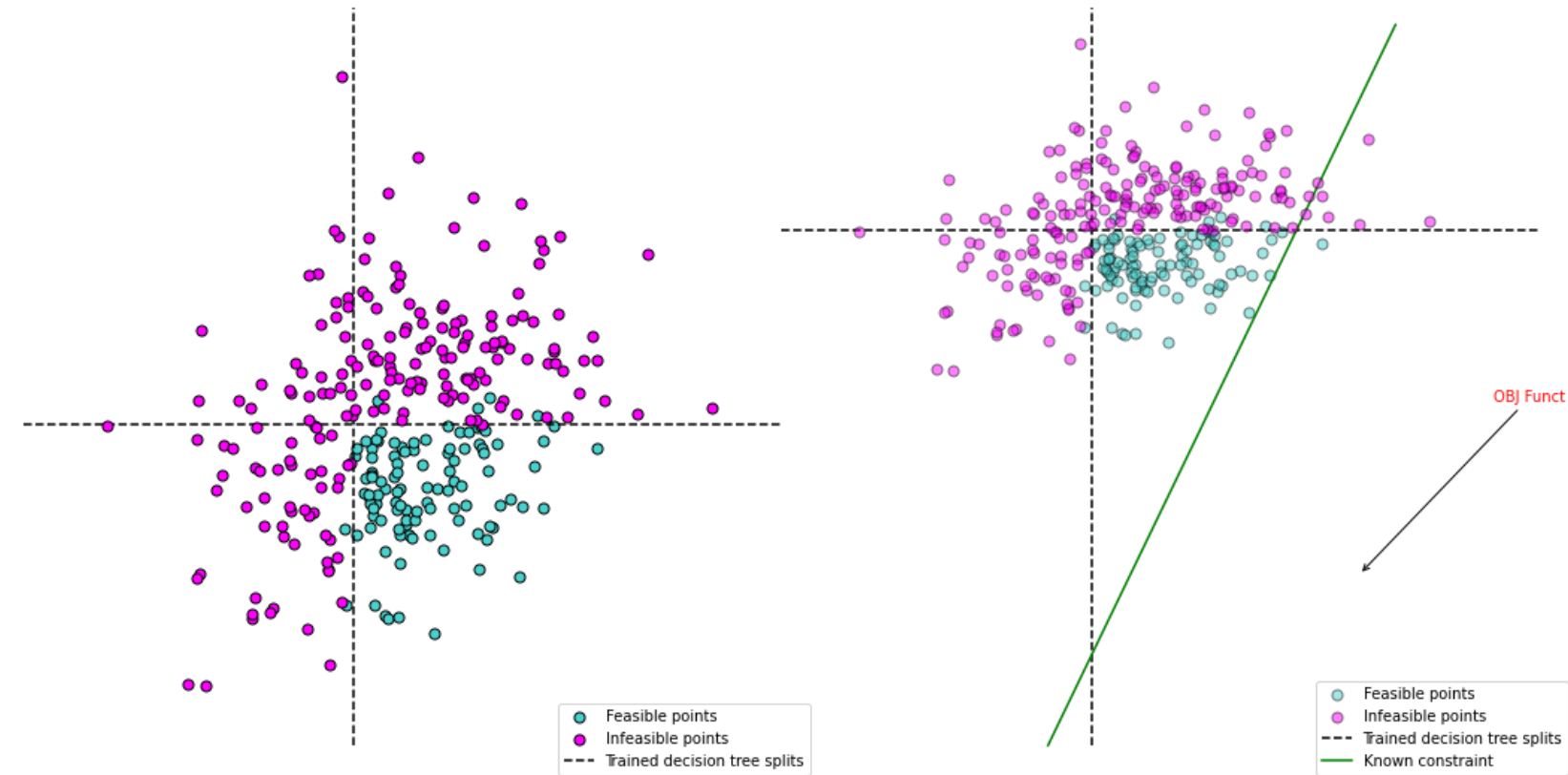
where  $M_L < 0$  is a lower bound on all possible values of  $x$ , and  $M_U > 0$  is an upper bound.



# Trust region constraints



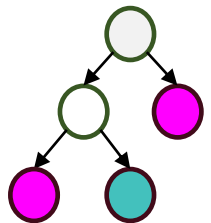
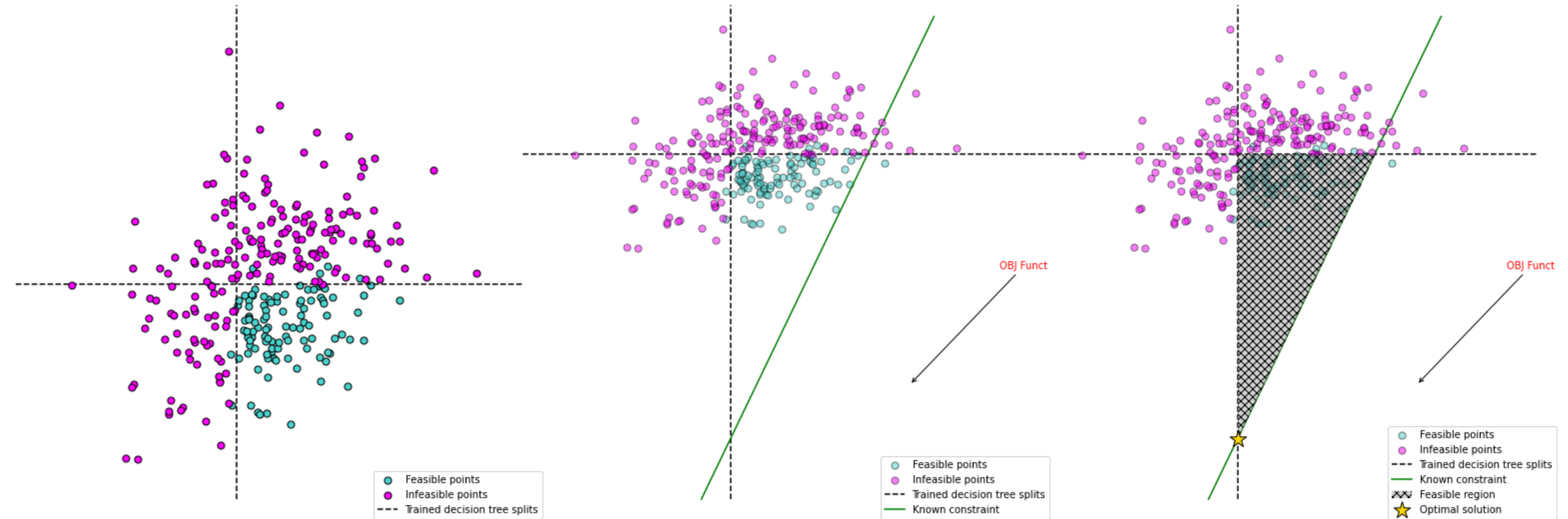
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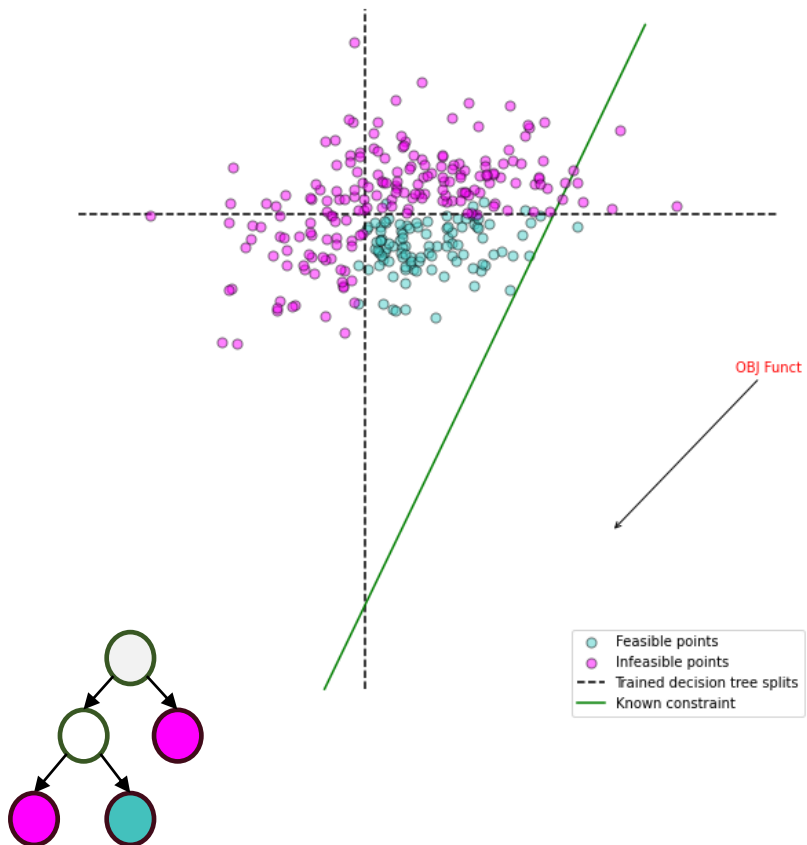
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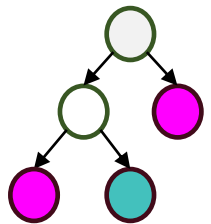
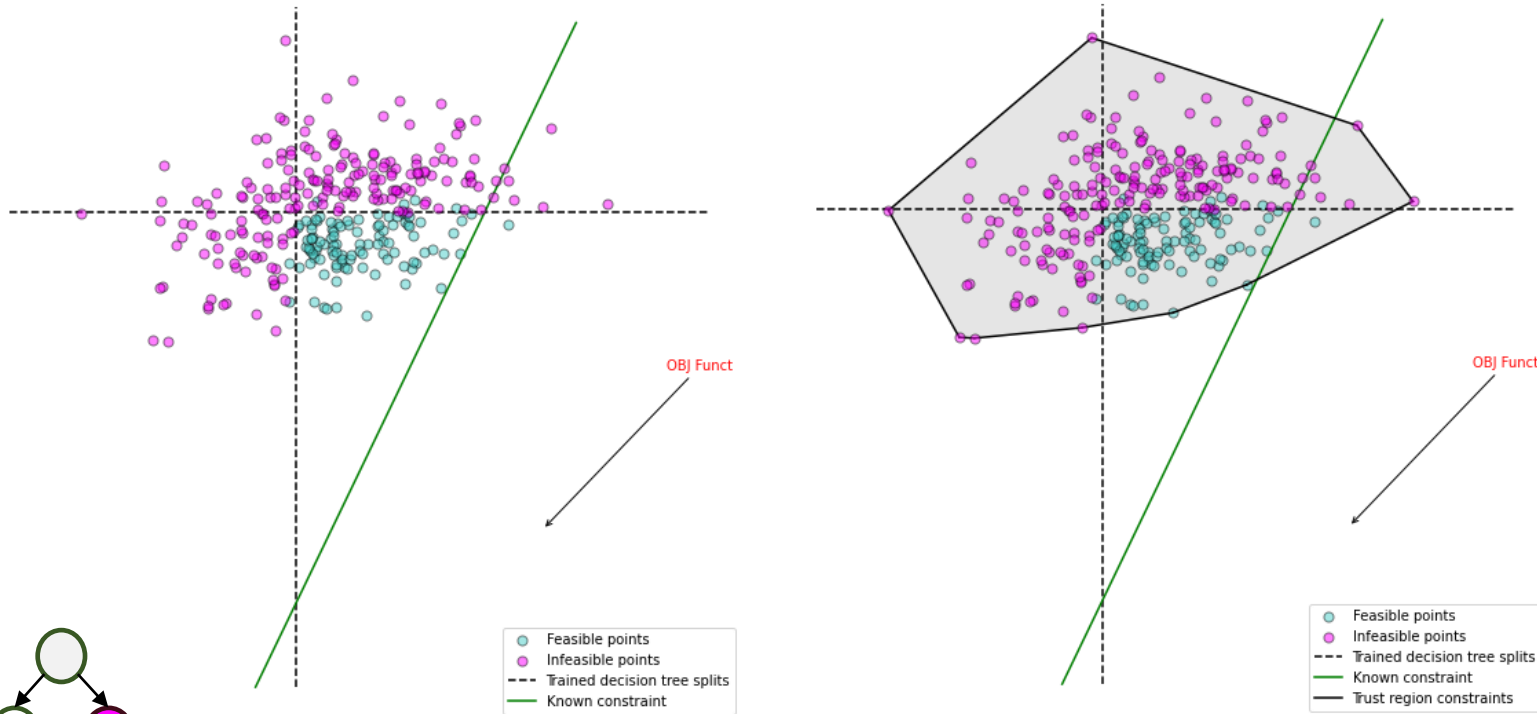


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# Trust region constraints

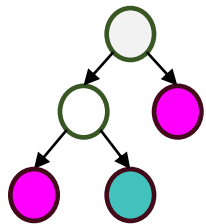
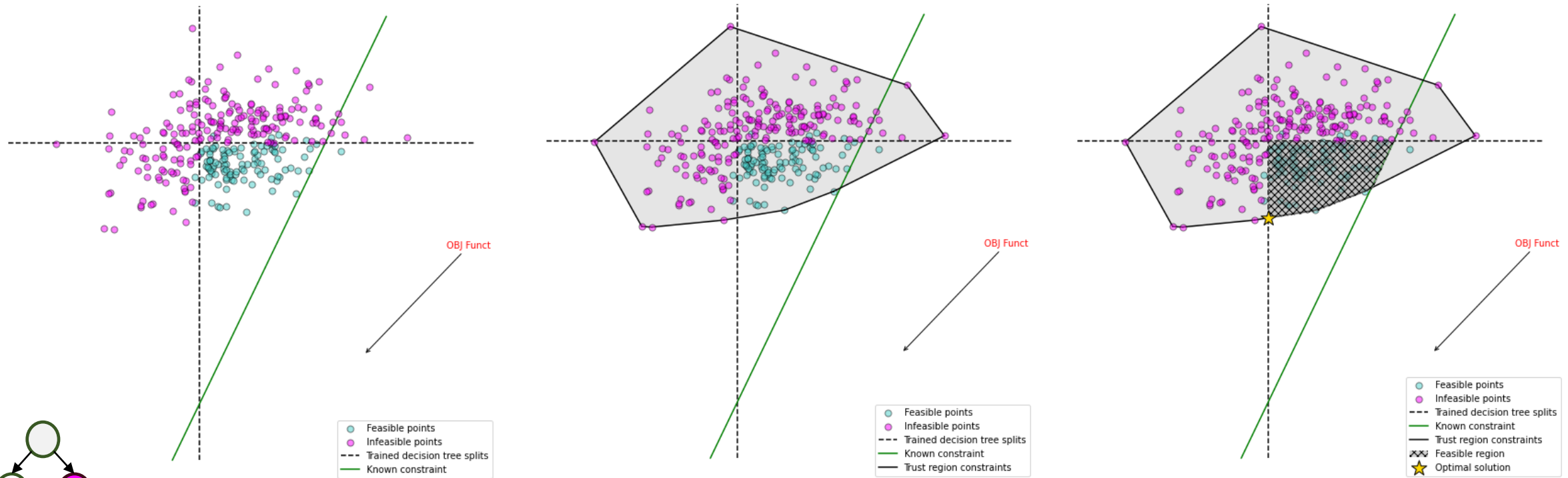
$$CH(\mathbf{x}) = \left\{ \mathbf{x} \mid \mathbf{x} = \sum_i^N \lambda_i \bar{\mathbf{x}}_i, \sum_i^N \lambda_i = 1, \lambda_i \geq 0, i = 1, \dots, N \right\}$$





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# OptiCL

A Python Package for

Optimization with Constraint Learning

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## Hands-on tutorial on the



## diet problem

# Thank you!

## Q&A



CONTACT ME

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