

The Maximum Cut Problem

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Abstract

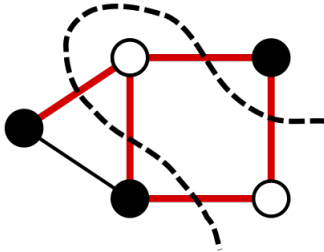
We introduce the Maximum-Cut problem and present a beautiful approximation algorithm for it.

1 Introduction

Definition 1.1 (Maximum Cut Problem(Max-Cut)).

Given an undirected graph $G = (V, E)$ with n vertices and m edges, a cut in G is a partition of the vertices V into two disjoint subsets $S, \bar{S} \subseteq V$, where $\bar{S} = V \setminus S$. Let $E(S, \bar{S})$ denote the set of edges with one vertex in S and one vertex in \bar{S} .

The Max-Cut problem is to find the cut (S, \bar{S}) that maximizes $|E(S, \bar{S})|$. In the weighted version of Max-Cut, we are also given an edge weight function $w : E \rightarrow \mathbb{R}$, and the problem is to find a cut with maximum weight. The Max-Cut problem is hard to solve. In contrast, the Min-Cut problem is solvable in polynomial time, e.g., by reducing to the s - t min-cut problem, which is dual to the Max-Flow problem, and can be solved efficiently.



Remark 1.2. *Max-Cut is NP-hard.*

The decision Max-Cut problem: For a given graph G and an integer k , does there exist a cut of size $\geq k$ in G ?

There exist polynomial time reductions from the independent set problem, k -clique problem, 3-SAT problem to the decision Max-Cut problem.

Max-Cut is APX-hard. Assuming $P \neq NP$, there is no polynomial time algorithm that can compute $1 - \epsilon$ -approximation to the optimal solution for arbitrary $\epsilon > 0$. Furthermore, assuming $P \neq NP$, there is no polynomial time algorithm that can approximate Max-Cut to within a factor of $\frac{16}{17}$.

2 Three Simple Algorithms For Max-Cut

Algorithm 1: Random Algorithm

Input: Graph $G = (V, E)$

Output: Partition (S, \bar{S})

- 1 Assign each vertices $v \in V$ to (S, \bar{S}) at random with equal probability;
 - 2 **Output:** (S, \bar{S}) ;
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Remark 2.1. $\mathbb{E}[|E(S, \bar{S})|] = \frac{m}{2}$, hence the random algorithm is a randomized $1/2$ -approximation algorithm for Max-Cut.

Algorithm 2: Greedy Algorithm

Input: Graph $G = (V, E)$

Output: Partition (S, \bar{S})

- 1 Order the vertices v_1, v_2, \dots, v_n ;
 - 2 Initialize two empty bins $S_1 \leftarrow \emptyset, S_2 \leftarrow \emptyset$;
 - // Greedily assign all vertices
 - 3 **for** $i \leftarrow 1$ **to** n **do**
 - 4 **if** $|E(S_1 \cup \{v_i\}, S_2)| > |E(S_1, S_2 \cup \{v_i\})|$ **then**
 - 5 $S_1 \leftarrow S_1 \cup \{v_i\}$;
 - 6 **else**
 - 7 $S_2 \leftarrow S_2 \cup \{v_i\}$;
 - 8 **Output:** (S_1, S_2) ;
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Remark 2.2. $|E(S_1, S_2)| \geq \frac{m}{2}$, hence the greedy algorithm is a deterministic $1/2$ -approximation algorithm for Max-Cut.

Algorithm 3: Local Search

Input: Graph $G = (V, E)$
Output: Partition (S, \bar{S}) of V with a relatively large cut

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1 Start with some arbitrary  $S \subseteq V$ ;
2 while True do
3   if  $\exists v \in S$  such that moving  $v$  to  $V \setminus S$  increases the cut size then
4      $S \leftarrow S \setminus \{v\}$ ;
5   if  $\exists v \in \bar{S}$  such that moving  $v$  to  $S$  increases the cut size then
6      $S \leftarrow S \cup \{v\}$ ;
7   if no vertices can be moved to improve  $S$  then
8     Terminate and output:  $(S, \bar{S})$ ;
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Remark 2.3. $|E(S, \bar{S})| \geq \frac{m}{2}$, hence the local search algorithm is a $1/2$ -approximation algorithm for Max-Cut.

3 A Beautiful Approximation Algorithm For Max-Cut

Step 1: Semidefinite Programming

The Max-Cut problem can be formulated as the following Integer Programming problem:

$$\begin{aligned}
& \text{Maximize} && \frac{1}{2} \sum_{(i,j) \in E} w_{ij}(1 - x_i x_j) \\
& \text{subject to} && x_i \in \{-1, +1\} \quad \forall i = 1, 2, \dots, n
\end{aligned}$$

We can relax the domain of each x_i from the discrete set $\{-1, +1\}$ to the $(n-1)$ -dimensional sphere \mathbb{S}^{n-1} , such that $\{-1, +1\}$ can be embedded as a pair of antipodal points on \mathbb{S}^{n-1} .

$$\begin{aligned}
& \text{Maximize} && \frac{1}{2} \sum_{(i,j) \in E} w_{ij}(1 - x_i \cdot x_j) \\
& \text{subject to} && x_i \in \mathbb{S}^{n-1} \quad \forall i = 1, 2, \dots, n
\end{aligned}$$

Let $P = X^T X$, where $X = [x_1, \dots, x_n] \in \mathbb{R}^{n \times n}$, then P is a positive semidefinite matrix, denoted $P \succeq 0$. Conversely, for any $Q \succeq 0$, $Q = Y^T Y$ for some $Y \in \mathbb{R}^{n \times n}$. So the relaxed Max-Cut problem can be realized as the following Semidefinite Programming problem:

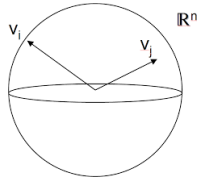
$$\begin{aligned}
& \text{Maximize} && \frac{1}{2} \sum_{(i,j) \in E} w_{ij}(1 - P_{ij}) \\
& \text{subject to} && P \succeq 0 \\
& && P_{ii} = 1 \quad \forall i = 1, 2, \dots, n
\end{aligned}$$

This is a convex optimization problem and can be solved to any degree of accuracy in polynomial time.

After we solve P , we can recover $X = \sqrt{\Lambda} Q^T$ where $P = Q \Lambda Q^T$ is the spectral decomposition of P .

Step 2: Random Hyperplane Rounding

Given $X = [x_1, \dots, x_n] \in \mathbb{R}^{n \times n}$, we use random hyperplane rounding to construct a partition.



1. Sample a random direction r in \mathbb{R}^n : $r \sim \mathcal{N}(0, I_n)$.
2. For each vertex $i=1, \dots, n$, the decision rule is:

$$i \in \begin{cases} S & \text{if } x_i \cdot r \geq 0 \\ \bar{S} & \text{if } x_i \cdot r < 0 \end{cases}$$

3. Output the cut (S, \bar{S})

Theorem 3.1. $\mathbb{E}[|E(S, \bar{S})|] \geq \alpha^* \text{MaxCut}$, where

$$\alpha^* = \min_{\theta \in [0, \pi]} \frac{\theta/\pi}{\frac{1-\cos\theta}{2}} \approx 0.878 \text{ (min at } \theta^* \approx 2.33\text{)}.$$

We denote the true value of the maximum cut MaxCut , the value of the relaxed semidefinite program relaxed MaxCut .

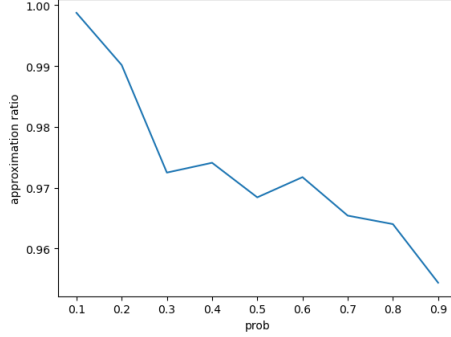
Proof.

$$\begin{aligned} \mathbb{E}[|E(S, \bar{S})|] &= \sum_{(i,j) \in E} w_{ij} \text{Prob}(x_i \text{ and } x_j \text{ are separated by a random hyperplane}) \\ &= \sum_{(i,j) \in E} w_{ij} \frac{\arccos x_i \cdot x_j}{\pi} \\ &\geq \sum_{(i,j) \in E} w_{ij} \alpha^* \frac{1 - x_i \cdot x_j}{2} \\ &= \alpha^* \sum_{(i,j) \in E} w_{ij} \frac{1 - x_i \cdot x_j}{2} \\ &= \alpha^* \text{relaxed MaxCut} \\ &\geq \alpha^* \text{MaxCut} \end{aligned}$$

□

Remark 3.2. α^* is also the integrality gap of the semidefinite programming problem above, which means the randomized hyperplane rounding method is optimal.

Example 3.3. We generate random graphs $G(n, p)$ with $n=10$ nodes for various probabilities p ranging from 0.1 to 0.9 and plot the approximation ratio over 100 iterations. The approximation ratio in our simulation decreases to 0.95 as p decreases but is always greater than $\alpha^* \approx 0.878$.



4 Hardness of Approximation: the Unique Game Conjecture

Definition 4.1 (The Probabilistically Checkable Proof(PCP) System). *We say that there exists a PCP system $PCP_{c,s}[r, q]_{\Sigma}$ ($0 \leq s \leq c \leq 1, r, q : \mathbb{N} \rightarrow \mathbb{N}$ are integer functions) for a language L over alphabet Σ (denoted $L \in PCP_{c,s}[r, q]_{\Sigma}$) if the following holds:*

- *Given input x , the prover P writes down the proof $\pi \in \Sigma^*$. The polynomial-time probabilistic verifier V looks at x , accesses $r(|x|)$ random bits and then does some computation to choose $q := q(|x|)$ locations in the proof and to produce a deterministic test(predicate) ψ on the q chosen locations. Then V queries the q chosen locations in the proof π , runs the predicate ψ on these q bits, and accepts or rejects.*
- *Completeness: For $x \in L, \exists \pi, \Pr[V(x, \pi) = 1] \geq c$.*
- *Soundness: For $x \notin L, \forall \pi, \Pr[V(x, \pi) = 1] \leq s$.*

Theorem 4.2 (PCP Theorem).

$$NP = PCP_{1, \frac{1}{2}}[O(\log n), O(1)]_{\{0,1\}}.$$

Conjecture 4.3 (Unique Game Conjecture). *For every sufficiently small pair of constants $1 - c, s > 0$, there exists an alphabet Σ of constant size such that*

$$NP = PCP_{c,s}[O(\log n), 2]_{\Sigma}.$$

Theorem 4.4. *Assuming the Unique Games Conjecture, it is NP-hard to approximate Max-Cut to any factor greater than α^* .*

5 Statistical Physics of Max-Cut

The Ising model for Max-Cut is:

$$H_{Ising} = \sum w_{ij} s_i s_j.$$

Minimizing this energy is equivalent to maximizing the cut.

In the quantum version, we encode each vertex as a qubit. A qubit in $|0\rangle$ or $|1\rangle$ indicates whether the vertex is in S or \bar{S} . The Pauli Z gate acts on the qubit such that $Z|0\rangle = |0\rangle$, $Z|1\rangle = -|1\rangle$. The Hamiltonian of Max-Cut is:

$$\begin{aligned} H_C &= \sum_{(u,v) \in E} \frac{Z_u + I}{2} + \frac{Z_v + I}{2} - 2 \cdot \frac{Z_u + I}{2} \frac{Z_v + I}{2} \\ &= \sum_{(u,v) \in E} \frac{Z_u + Z_v + 2I - (Z_u Z_v + Z_u + Z_v + I)}{2} \\ &= \sum_{(u,v) \in E} \frac{I - Z_u Z_v}{2}. \end{aligned}$$

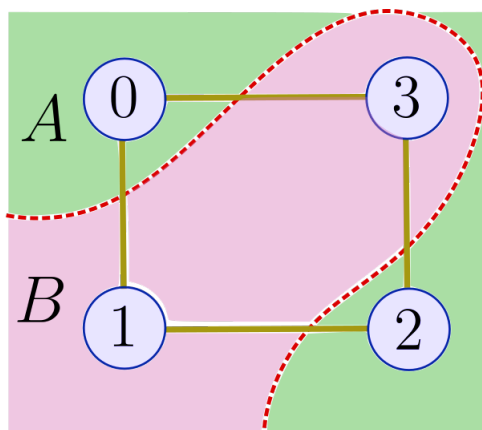
The expected value for a given state ψ is:

$$\begin{aligned} \langle \psi | H_C | \psi \rangle &= \langle \psi | \sum_{(u,v) \in E} \frac{I - Z_u Z_v}{2} | \psi \rangle \\ &= \langle \psi | \sum_{(u,v) \in E} \frac{I}{2} | \psi \rangle - \langle \psi | \sum_{(u,v) \in E} \frac{Z_u Z_v}{2} | \psi \rangle \\ &= \frac{|E|}{2} - \frac{1}{2} \langle \psi | \sum_{(u,v) \in E} Z_u Z_v | \psi \rangle. \end{aligned}$$

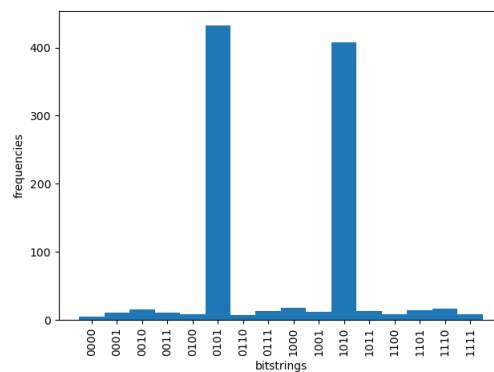
Our goal is to maximize this value, which is equivalent to minimizing the energy of the Hamiltonian $H = - \sum_{(u,v) \in E} Z_u Z_v$.

Example 5.1. *We can use the Quantum Approximate Optimization Algorithm to minimize this energy. We did a simple experiment on a small graph with 4 nodes and 4 edges.*

The states $|0101\rangle, |1010\rangle$ have the highest frequencies, both corresponding to the cut $\{0, 2\}, \{1, 3\}$.



(a) Graph



(b) Relative Frequencies For Each State

Figure 1: Overall Caption for Both Graphs

6 Conclusions

We studied the maximum cut problem, presented various approximation algorithms, and realized the hardness of approximation.

7 Code

The code is here: <https://github.com/ordinarylhy/MaxCut>.