

Stats305a Étude 3

Due: Monday, November 28 at 5:00pm on Gradescope.

**Question 3.1** (Stability, instability, and robustness): In this question, we develop a leave-one-out robustness heuristic and investigate the (in)stability of non-discoveries in regression.

(a) Let  $A, B$  be square matrices where  $A$  is invertible.

(i) **2 pts.** Show that for any  $k \in \mathbb{N}$ ,

$$(A - B) \left( A^{-1} + A^{-1}BA^{-1} + \cdots + A^{-1}(BA^{-1})^k \right) = I - (BA^{-1})^{k+1}.$$

*Hint.* Use induction.

(ii) **2 pts.** Recall that the operator norm  $\|A\|_{\text{op}} = \sup_{u,v} \{u^T Av \mid \|u\| = \|v\| = 1\}$ . Assume that  $\|B\|_{\text{op}} < 1/\|A^{-1}\|_{\text{op}}$ . Show that

$$(A - B)^{-1} = \sum_{i=0}^{\infty} A^{-1}(BA^{-1})^i \quad \text{and} \quad (A + B)^{-1} = \sum_{i=0}^{\infty} (-1)^i A^{-1}(BA^{-1})^i.$$

Consider a typical regression setting with data  $X \in \mathbb{R}^{n \times d}$  (whose rows are  $x_i^T$  as usual) and  $y \in \mathbb{R}^n$ , and for a vector  $\delta \in [0, 1]^n$ , define the estimator

$$\hat{\beta}_{\delta} := \underset{b}{\operatorname{argmin}} \frac{1}{n} \sum_{i=1}^n (1 - \delta_i)(x_i^T b - y_i)^2,$$

which omits examples with  $\delta_i = 1$  and downweights those with  $\delta_i > 0$ . Then the standard OLS estimator is  $\hat{\beta} = \hat{\beta}_0$ , and we let  $\hat{y} = X\hat{\beta}$  be the usual prediction for  $y$ .

(b) **2 pts.** Let  $D(\delta) = \operatorname{diag}(\delta)$  be the diagonal matrix with  $i$ th diagonal entry  $\delta_i$ . Show that

$$\hat{\beta}_{\delta} = (X^T(I - D(\delta))X)^{-1}X^T(I - D(\delta))Y.$$

We say a matrix  $A = O(r)$  (read “ $A$  is big-O of  $r$ ”) if  $\|A\|_{\text{op}}/r$  is bounded as  $r \rightarrow 0$ . For example, in part (a) above, the matrix  $(A - B) \sum_{i=0}^k A^{-1}(BA^{-1})^i = O(\|B\|^{k+1})$  for  $B$  near 0. The matrix  $X^T D(\delta) X$  is  $O(\|\delta\|)$ , and  $AD(\delta)BD(\delta)C$  is  $O(\|\delta\|^2)$  for any matrices  $A, B, C$  as  $\delta \rightarrow 0$ .

(c) **3 pts.** Let  $\hat{C} = \frac{1}{n} \sum_{i=1}^n x_i x_i^T = \frac{1}{n} X^T X$  be the “covariance” of the  $x_i$ . Show that

$$\hat{\beta}_{\delta} = \hat{\beta} + \frac{1}{n} \hat{C}^{-1} X^T D(\delta) (\hat{y} - y) + O(\|\delta\|^2)$$

(d) **2 pts.** Show that if  $e_i$  is the  $i$ th standard basis vector, then

$$\lim_{\delta \rightarrow 0} \frac{\hat{\beta}_{\delta e_i} - \hat{\beta}}{\delta} = \frac{1}{n} \hat{C}^{-1} x_i (\hat{y}_i - y_i).$$

We define  $\text{iinf}(\hat{\beta}, i) := \frac{1}{n} \hat{C}^{-1} x_i (\hat{y}_i - y_i)$  to be the *instantaneous influence* of example  $i$ , as it (roughly) captures the effect of removing example  $i$  from the dataset.

- (e) **6 pts.** Download the UCI Abalone dataset (<https://archive.ics.uci.edu/ml/datasets/Abalone>). It consists of 9 features (one of which, **Sex**, is nominal and takes values M, F, and I for infant, so you should transform it into a one-hot encoding, but make sure you don't accidentally make your design low rank), and the last of which (**rings**) is the attribute to predict (i.e.,  $y$ ). We would like to investigate *how* significant we can make a  $p$ -value by removing just a few (in this case,  $k$ ) datapoints. You should do this by the following, which we describe for a fixed  $k$ .

- i. Construct the design  $X \in \mathbb{R}^{n \times d}$  and response  $y$  from the dataset. Standardize  $X$  so that the columns have  $\ell_2$ -norm  $\sqrt{n}$  and are (except for the intercept) mean 0.
- ii. For each coordinate  $j \in \{1, \dots, d\}$  and each datapoint  $i \in \{1, \dots, n\}$ , compute the instantaneous influence of example  $i$  on parameter  $j$ , which is

$$e_j^T \text{iinf}(\hat{\beta}, i).$$

- iii. For each coordinate  $j \in \{1, \dots, d\}$ , choose the index set  $\mathcal{I} \subset \{1, \dots, n\}$  of cardinality  $k$  maximizing the (estimated)  $\hat{\beta}$  that results after removing those  $\mathcal{I}$  examples, that is, maximizing

$$\left| e_j^T \left( \hat{\beta} + \sum_{i \in \mathcal{I}} \text{iinf}(\hat{\beta}, i) \right) \right|.$$

- iv. For each of these index sets (you should compute per coordinate  $j$  of  $\hat{\beta}$ ), set  $\delta = \sum_{i \in \mathcal{I}} e_i$ , that is, an  $n$  vector with a 1 in each position corresponding to  $\mathcal{I}$ , and compute  $\hat{\beta}_\delta$  and the corresponding  $p$ -value that a T-test yields for the null

$$H_{0,j} : \beta_j = 0$$

in the model  $y_i = x_i^T \beta + \varepsilon_i$ ,  $\varepsilon_i \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \sigma^2)$  for  $i \notin \mathcal{I}$ , that is, the linear model *without* examples in  $\mathcal{I}$ . (You do not need to do any multiplicity correction.)

Repeat steps i-iv above for index set sizes  $k = 1, \dots, 20$ , and for each of your coordinates  $j$ , plot the resulting  $p$  values (that is, plot  $k$  on the horizontal axis, beginning from  $k = 0$ , against  $p$  on the vertical axis; and yes,  $k = 0$  corresponds to doing things with the initial data). How much can you modify the “significance” of your results by removing a few datapoints? You may want to plot your results on a logarithmic scale. Include your code.