```
## # A tibble: 4,579 x 13
##    function_name calculator     N init_time calc_time calc_hz bytes max_error
##    <chr>         <chr>      <dbl>     <dbl>     <dbl>   <dbl> <dbl>     <dbl>
##  1 Smooth_exp    linear in~     8         0    4.83e7  20.7       8    0.484
##  2 Smooth_exp    linear in~    12         0    8.27e7  12.1       8    0.356
##  3 Smooth_exp    linear in~    16         0    1.95e8   5.13      8    0.226
##  4 Smooth_exp    linear in~    20         0    4.09e8   2.45      8    0.134
##  5 Smooth_exp    linear in~    24         0    7.33e8   1.36      8    0.151
##  6 Smooth_exp    linear in~    28         0    1.31e9   0.764     8    0.140
##  7 Smooth_exp    linear in~    32         0    2.19e9   0.457     8    0.0665
##  8 Smooth_exp    linear in~    36         0    3.39e9   0.295     8    0.0568
##  9 Smooth_exp    linear in~    40         0    5.01e9   0.200     8    0.0591
## 10 Smooth_exp    linear in~    44         0    7.27e9   0.138     8    0.0498
## # ... with 4,569 more rows, and 5 more variables: blank_column <lgl>,
## #   err1 <dbl>, err2 <dbl>, err3 <dbl>, Blank <lgl>
```

%

{My Report or Thesis Title} %

%

{Dr Hale}

{Abstract}

. . . this is the abstract text. . .

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This is an $x = y$ equation.

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#}

3.5 Tables

4 Conclusion

We described methods in Section 2 and plotted the results in Section 3.4. Supplementary material is in Appendix A.1.

References

Appendix

A.1 Supporting material

A.2 Supporting code

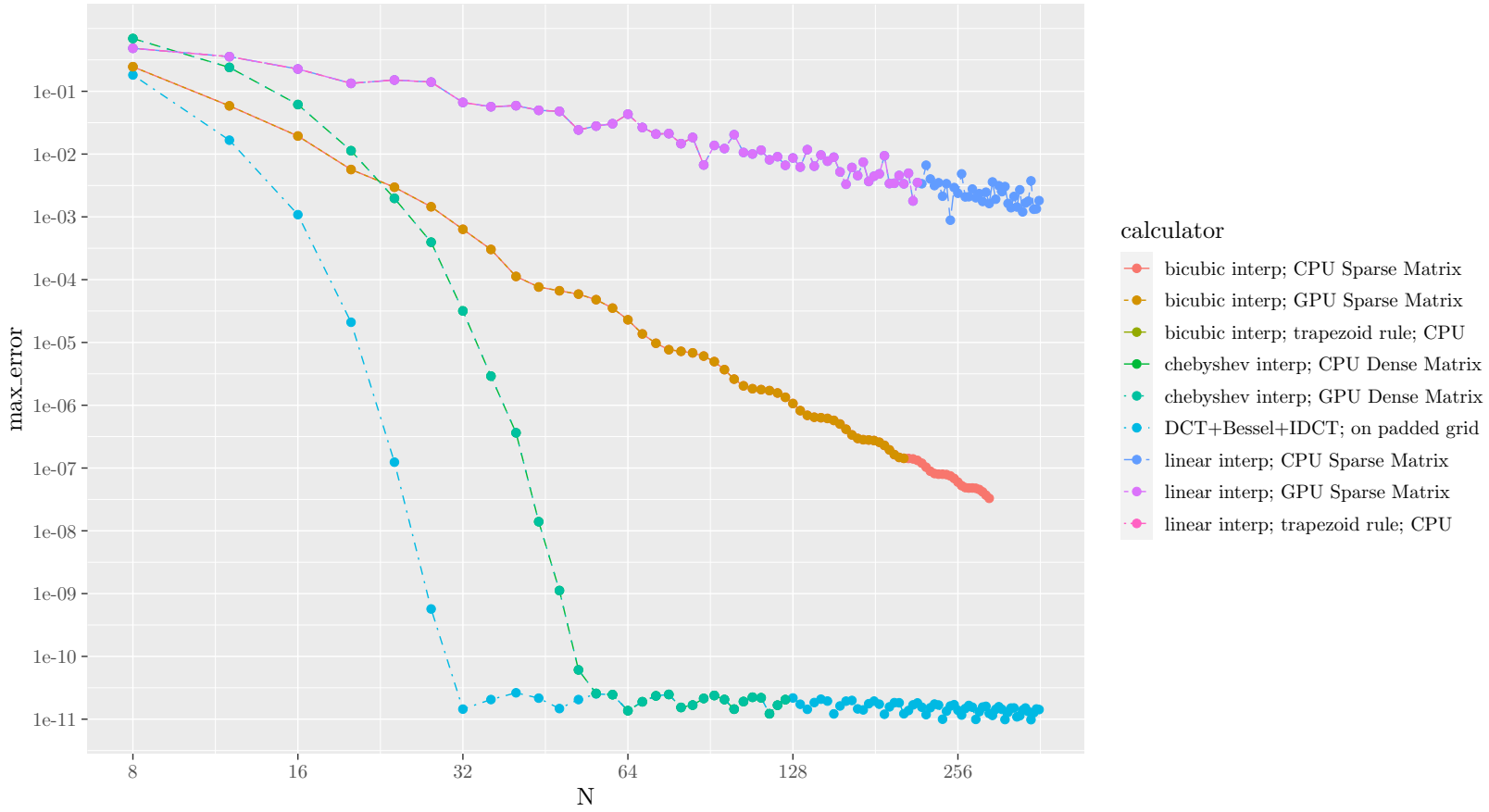

Figure 1: Smooth Exp (Double)

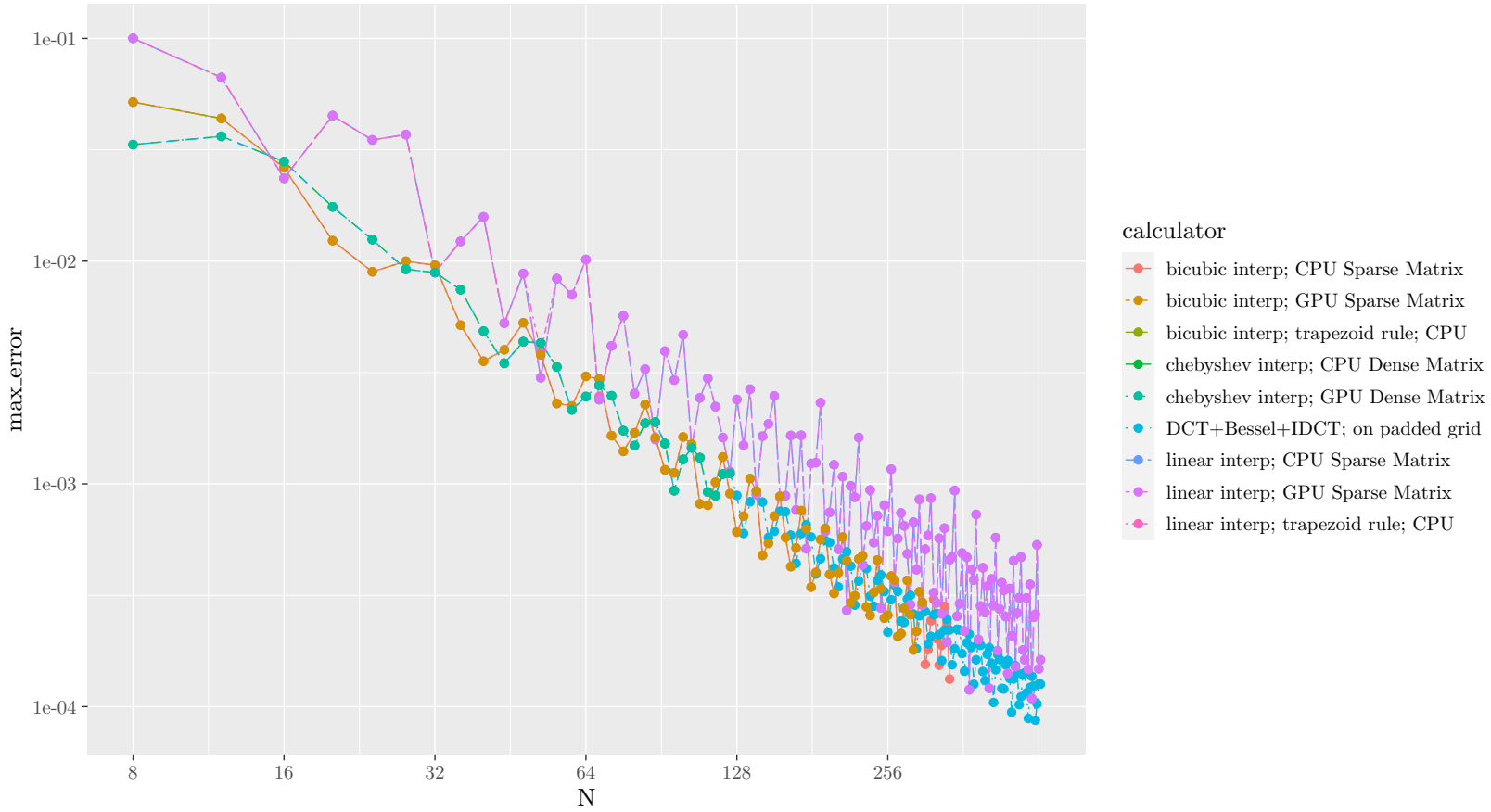

Figure 2: Smooth Poly

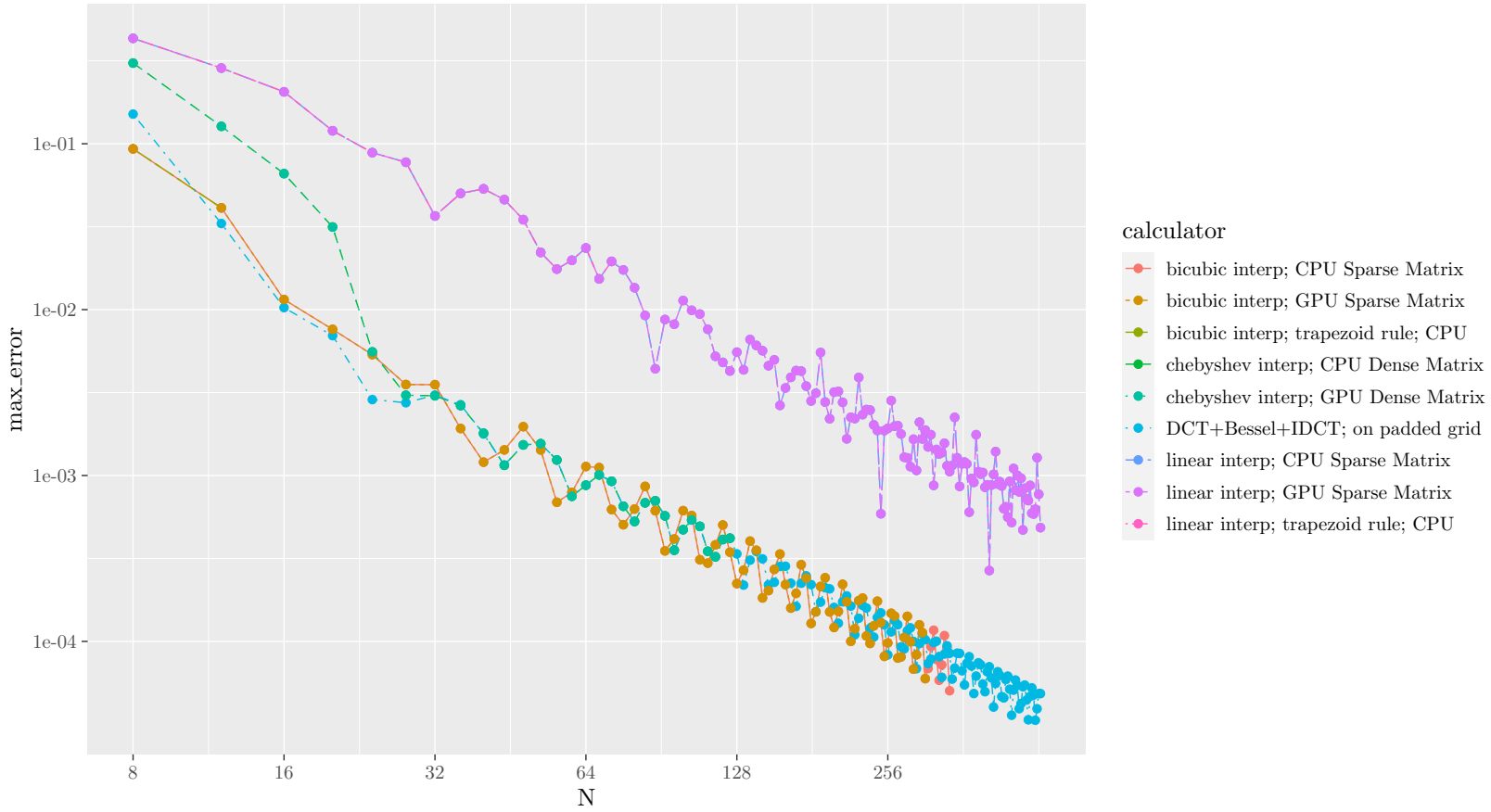

Figure 3: Smooth Runge

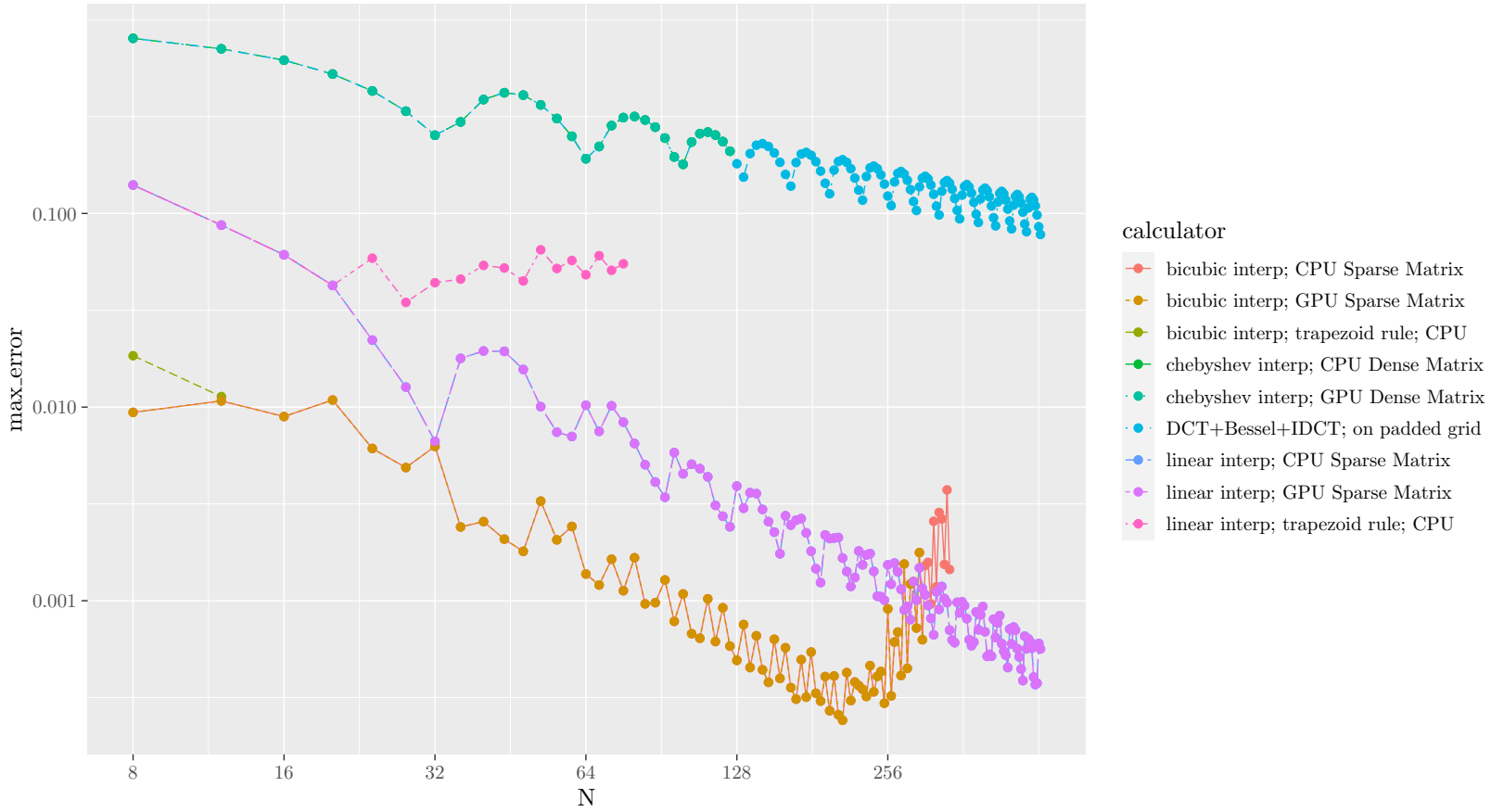

Figure 4: Nonsmooth Sqrt

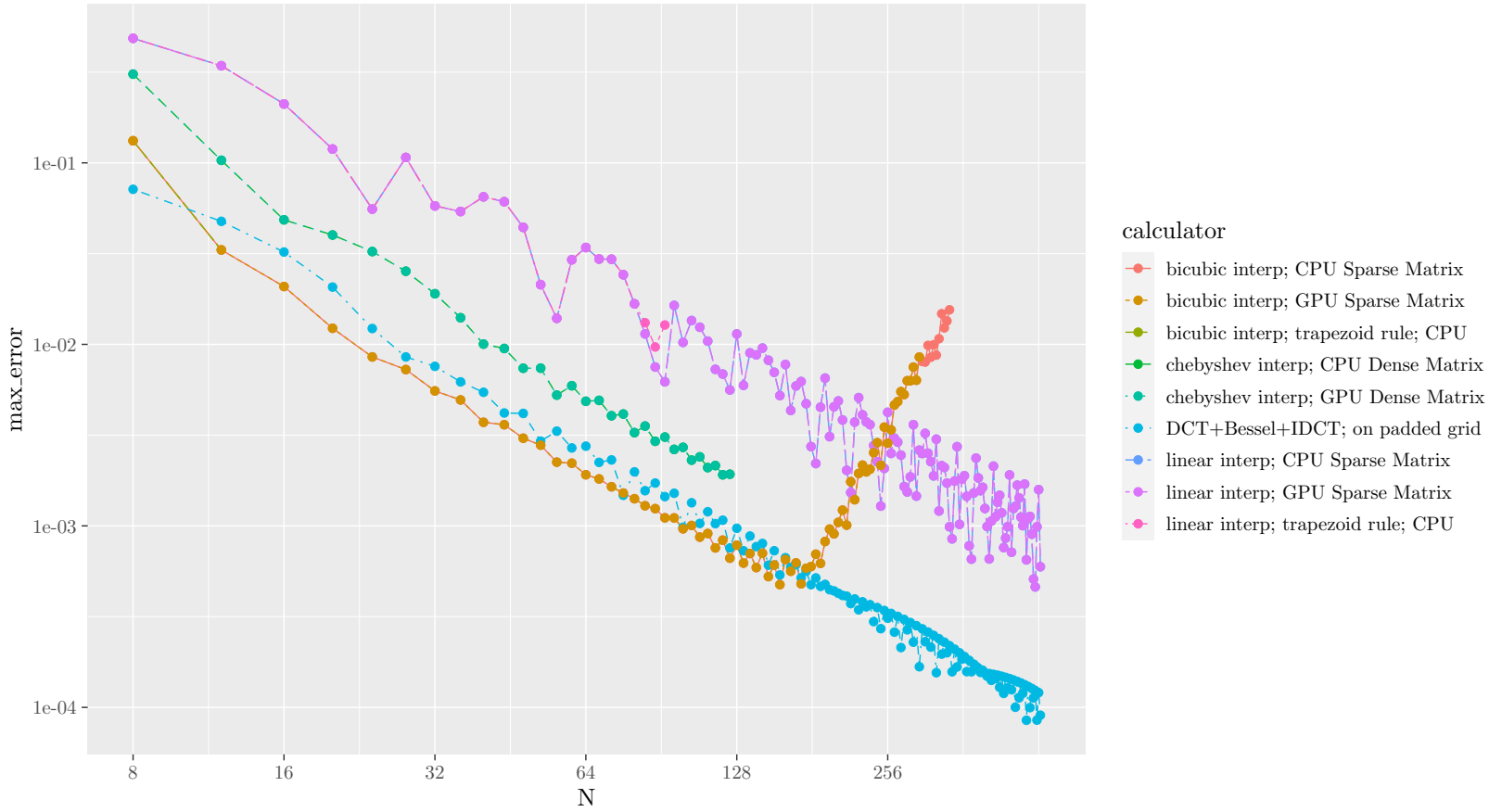

Figure 5: Nonsmooth Abs

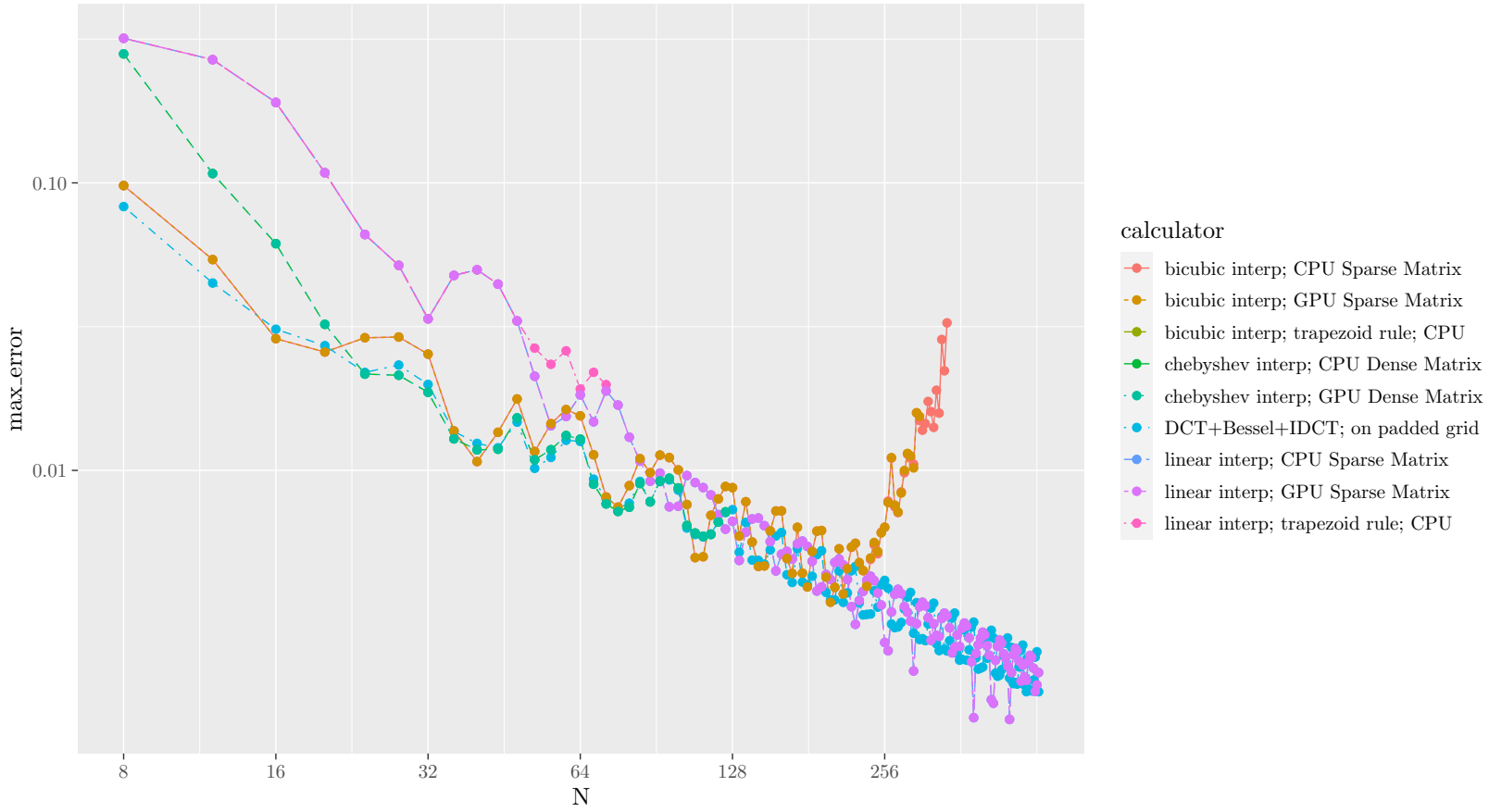

Figure 6: NonSmooth Runge Abs