

# Contents

1	Basic Test Results	2
2	HashMap.c	3
3	Vector.c	8

# 1 Basic Test Results

```
1
2 Running presubmission script...
3
4
5 Opening tar file
6 Vector.c
7 HashMap.c
8 OK
9 Tar extracted O.K.
10 For your convenience, the MD5 checksum for your submission is f2754b0ee18adbe94fc47d59213687c7
11 Checking files...
12 OK
13 Making sure files are not empty...
14 OK
15 Compilation check...
16 Compiling...
17 OK
18 Compilation seems OK! Check if you got warnings!
19 Checking CodingStyle...
20 Checking file Vector.c...
21 Checking file HashMap.c...
22 Passed codingStyle check.
23
24 =====
25     Public test cases
26 =====
27
28 =====
29 Running test...
30 [Pre-Submission] 3 ...
31 [Pre-Submission] 2 ...
32 [Pre-Submission] 1 ...
33 [Pre-Submission] Ignition ...
34 [Pre-Submission] Creating Vector of Ints ...
35 [Pre-Submission] Check vector size with assert ...
36 [Pre-Submission] Free Vector ...
37 [Pre-Submission] Creating Pairs of {Char : Int} ...
38 [Pre-Submission] Creating HashMap of {Char : Int} ...
39 [Pre-Submission] Inserting Pairs to HashMap ...
40 [Pre-Submission] Free Pairs ...
41 [Pre-Submission] Check hash-map size with assert ...
42 [Pre-Submission] Free hash map ...
43 [Pre-Submission] all tests ended.
44 OK
45 =====
46
47 *****
48 *                                     *
49 *             Passed all tests!!      *
50 *                                     *
51 *****
```

## 2 HashMap.c

```
1  #include "HashMap.h"
2
3
4  HashMap *HashMapAlloc(
5      HashFunc hash_func, HashMapPairCpy pair_cpy,
6      HashMapPairCmp pair_cmp, HashMapPairFree pair_free) {
7      if (!hash_func || !pair_cpy || !pair_cmp || !pair_free) { // check if the functions are not null,
8          return NULL;
9      }
10     HashMap *new_hash = calloc(1, sizeof(HashMap));
11     if (!new_hash) {
12         return NULL;
13     }
14     new_hash->buckets = calloc(HASH_MAP_INITIAL_CAP, sizeof(Vector));
15     if (!new_hash->buckets) {
16         return NULL;
17     }
18     new_hash->capacity = HASH_MAP_INITIAL_CAP;
19     new_hash->hash_func = hash_func;
20     new_hash->pair_cpy = pair_cpy;
21     new_hash->pair_cmp = pair_cmp;
22     new_hash->pair_free = pair_free;
23     for (unsigned long i = 0; i < HASH_MAP_INITIAL_CAP; ++i) {
24         new_hash->buckets[i] = VectorAlloc(new_hash->pair_cpy, new_hash->pair_cmp, new_hash->pair_free);
25     }
26     return new_hash;
27 }
28
29 void HashMapFree(HashMap **p_hash_map) {
30     if (!*p_hash_map) {
31         return;
32     }
33     HashMap *map = (*p_hash_map);
34     for (size_t k_i = 0; k_i < map->capacity; k_i++) {
35         VectorFree(&map->buckets[k_i]);
36     }
37     free(map->buckets);
38     map->buckets = NULL;
39     free(*p_hash_map);
40     *p_hash_map = NULL;
41 }
42
43 void CreatArrOfVector(HashMap *hash_map, Pair *arr[]) {
44     /**
45      * get the hash map and empty array and insert all the pairs that was in the hash map into the array
46      */
47     int k = 0;
48     for (size_t j = 0; j < hash_map->capacity; ++j) {
49         if (hash_map->buckets[j]) {
50             for (size_t i = 0; i < hash_map->buckets[j]->size; ++i) {
51                 Pair *pair = VectorAt(hash_map->buckets[j], i);
52                 arr[k++] = hash_map->buckets[j]->elem_copy_func(
53                     pair);
54             }
55         }
56     }
57 }
58 }
59
```

```

60 void CheckCapAndIncreaseIfNessr(HashMap *hash_map) {
61     /**
62         * check if we need to increase the capacity of the hash map depend on the load factor .
63         * and if we need to change the capacity we rehash the hash map : we creat buffer - an array - and put all
64         * the elements of the hash map into it .
65         * after that we change the capacity and insert all the elements to th hash map
66     */
67     double loaf = HashMapGetLoadFactor(hash_map);
68     if (loaf != -1 && loaf > HASH_MAP_MAX_LOAD_FACTOR) {
69         size_t arr_size = hash_map->size;
70         size_t num_of_vectors = hash_map->capacity;
71         Pair** arr = malloc(hash_map->size*sizeof(Pair*));
72         CreatArrOfVector(hash_map, arr); // i save all the pairs in an array for the rehashing
73         size_t new_cap = hash_map->capacity * HASH_MAP_GROWTH_FACTOR;
74         HashMapClear(hash_map);
75         for (size_t i = 0; i < num_of_vectors ; ++i) {
76             VectorFree(&hash_map->buckets[i]);
77         }
78         hash_map->capacity = new_cap;
79         Vector **tmp = realloc(hash_map->buckets, new_cap * sizeof(Vector ));
80         if (tmp) {
81             hash_map->buckets = tmp;
82         }
83         for (size_t i = 0; i < new_cap ; ++i) {
84             hash_map->buckets[i] = VectorAlloc(hash_map->pair_cpy, hash_map->pair_cmp, hash_map->pair_free);
85         }
86         for (size_t i = 0; i < arr_size; ++i) {
87             HashMapInsert(hash_map, arr[i]);
88         }
89         for (size_t i = 0; i < arr_size; ++i) {
90             hash_map->pair_free((void*)&arr[i]);
91         }
92         free(arr);
93     }
94 }
95
96 void VectorFindByKey(Vector *vec, Pair *pair) {
97     /**
98         * find the vector that the current key is in it and change the old pair to the new pair
99     */
100     for (size_t i = 0; i < vec->size; ++i) {
101         Pair *old_pair = (Pair *) vec->data[i];
102         if (pair->key_cmp(pair->key, old_pair->key)) {
103             vec->elem_free_func((void*)&old_pair);
104             vec->data[i] = pair;
105         }
106     }
107 }
108
109
110 void FindVectorAndChangePair(HashMap *hash_map, Pair *pair) {
111     for (size_t i = 0; i < hash_map->capacity; ++i) {
112         Vector * vec = hash_map->buckets[i];
113         if (vec && vec->size) { // the currnet bucket is with vector of at list one pair
114             VectorFindByKey(vec, pair);
115         }
116     }
117 }
118
119 int HashMapInsert(HashMap *hash_map, Pair *pair) {
120     if (hash_map && pair) {
121         Pair *new_pair = hash_map->pair_cpy(pair);
122         if (HashMapContainsKey(hash_map,
123             new_pair->key)) {
124             /** if the key of the new pair is in the hash map
125             * we need to find the vector that the new key is in it
126             * and change the old pair to the new pair
127             * we dont need to check the capacity because the size still the same

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```

128         */
129         FindVectorAndChangePair(hash_map, new_pair);
130         return 1;
131     }
132     size_t hash_ind = hash_map->hash_func(new_pair->key) & (hash_map->capacity - 1);
133     if (!hash_map->buckets[hash_ind]->size ) {
134         Vector * vec = hash_map->buckets[hash_ind];
135         VectorPushBack(vec, new_pair);
136         hash_map->pair_free((void*)&new_pair);
137         hash_map->buckets[hash_ind] = vec;
138         hash_map->size++;
139         CheckCapAndIncreaseIfNessr(hash_map);
140         return 1;
141     } else { // if there is at list one pair in the vector
142         Vector *cur_vec = hash_map->buckets[hash_ind];
143         VectorPushBack(cur_vec, new_pair);
144         hash_map->pair_free((void*)&new_pair);
145         hash_map->size++;
146         CheckCapAndIncreaseIfNessr(hash_map);
147         return 1;
148     }
149
150 }
151
152 }
153 return 0;
154 }
155
156 int HashMapContainsKey(HashMap *hash_map, KeyT key) {
157     if (!hash_map) {
158         return 0;
159     }
160
161     for (size_t i = 0; i < hash_map->capacity ; ++i) {
162         if (hash_map->buckets[i]) {
163             Vector *vec = hash_map->buckets[i];
164             for (size_t j = 0; j < vec->size; ++j) {
165                 Pair *cur_pair = (Pair *) vec->data[j];
166                 KeyT cur_key = cur_pair->key;
167                 if (cur_pair->key_cmp(cur_key, key)) {
168                     return 1;
169                 }
170             }
171         }
172     }
173     return 0;
174 }
175
176
177 int HashMapContainsValue(HashMap *hash_map, ValueT value) {
178     if (!hash_map) {
179         return 0;
180     }
181     for (size_t i = 0; i < hash_map->capacity; ++i) {
182         if (hash_map->buckets[i]) { // if there is vector in the the bucket (it means that there is at list one pair
183             Vector *vec = hash_map->buckets[i];
184             for (size_t j = 0; j < vec->size; ++j) {
185                 Pair *cur_pair = (Pair *) vec->data[j];
186                 ValueT cur_val = cur_pair->value;
187                 if (cur_pair->value_cmp(cur_val, value)) {
188                     return 1;
189                 }
190             }
191         }
192     }
193     return 0;
194 }
195

```

```

196 ValueT HashMapAt(HashMap *hash_map, KeyT key) {
197     if (!hash_map) {
198         return NULL;
199     }
200     for (size_t i = 0; i < hash_map->capacity; ++i) {
201         if (hash_map->buckets[i]) {
202             Vector *vec = hash_map->buckets[i];
203             for (size_t j = 0; j < vec->size; ++j) {
204                 Pair *pair = vec->data[j];
205                 if (pair->key_cmp(pair->key, key)) {
206                     return pair->value;
207                 }
208             }
209         }
210     }
211     return NULL;
212 }
213
214
215 void CheckCapAndDecreaseIfNessr(HashMap *hash_map) {
216     /* check if the current min load factor is lower then the MIN_LOAD_FACTOR 6.1 if it is the function send the
217     * hash map and an empty array and fill in the array with all the pairs that was in the hash map.
218     * after that it realloc the buckets of the hash map , clear the hash map ,and rehash the pairs into the the clear
219     * hash map.
220     */
221     double loadf = HashMapGetLoadFactor(hash_map);
222     if (loadf != -1 && loadf < HASH_MAP_MIN_LOAD_FACTOR) {
223         size_t arr_size = hash_map->size;
224         Pair** arr = malloc(hash_map->size*sizeof(Pair*));
225         CreatArrOfVector(hash_map, arr); // save all the pairs in an array for the rehashing.
226         size_t new_cap = hash_map->capacity / HASH_MAP_GROWTH_FACTOR;
227         for (size_t i = 0; i < hash_map->capacity; ++i) {
228             VectorFree(&hash_map->buckets[i]);
229         }
230         HashMapClear(hash_map); // clear the hash map before insert the pairs into it
231         hash_map->capacity = new_cap;
232         Vector **tmp = realloc(hash_map->buckets, new_cap * sizeof(Vector *));
233         if (tmp) {
234             hash_map->buckets = tmp;
235         }
236         for (size_t i = 0; i < new_cap ; ++i) { // insert vector to all the buckets
237             hash_map->buckets[i] = VectorAlloc(hash_map->pair_cpy, hash_map->pair_cmp, hash_map->pair_free);
238         }
239         for (size_t i = 0; i < arr_size; ++i) { // insert the pairs into the hashmap
240             HashMapInsert(hash_map, arr[i]);
241         }
242         for (size_t i = 0; i < arr_size; ++i) {
243             hash_map->pair_free((void*)&arr[i]);
244         }
245         free(arr);
246     }
247 }
248
249 int HashMapErase(HashMap *hash_map, KeyT key) {
250     if (!hash_map) {
251         return 0;
252     }
253     if (!HashMapContainsKey(hash_map, key)) { 6.2
254         return 0;
255     }
256     for (size_t i = 0; i < hash_map->capacity; ++i) {
257         Vector *vec = hash_map->buckets[i];
258         if (vec) {
259             for (size_t j = 0; j < vec->size; ++j) {
260                 Pair *pair = vec->data[j];
261                 if (pair->key_cmp(key, pair->key)) {
262                     int ind = VectorFind(vec, pair);
263                     if (ind != -1) {

```

```

264         VectorErase(vec, ind);
265         hash_map->size--;
266         if (!vec->data[j]) {// the bucket is now empty and dont contain any pairs
267             CheckCapAndDecreaseIfNessr(hash_map);
268             return 1;
269         }
270     }
271 }
272 }
273 }
274 }
275 return 0;
276 }
277
278 double HashMapGetLoadFactor(HashMap *hash_map) {
279     if (hash_map) {
280         double size = hash_map->size;
281         double cap = hash_map->capacity;
282         return size / cap;
283     }
284     return -1;
285 }
286
287 void ChooseCapOfClearMap(HashMap *hash_map, size_t start_size, size_t start_cap) {
288     /** this function choose the final capacity of the hash map .
289     * there are three options to the final capacity depend in what the start size and the start capacity
290     * was in the first
291     *
292     */
293     if (start_size == 1 && start_cap == HASH_MAP_INITIAL_CAP) {
294         hash_map->capacity = HASH_MAP_INITIAL_CAP/HASH_MAP_GROWTH_FACTOR;
295     } else if (start_size == 2 && start_cap == HASH_MAP_INITIAL_CAP) {
296         hash_map->capacity = HASH_MAP_INITIAL_CAP / HASH_MAP_GROWTH_FACTOR / HASH_MAP_GROWTH_FACTOR;
297     } else {
298         hash_map->capacity = HASH_MAP_INITIAL_CAP/HASH_MAP_GROWTH_FACTOR/HASH_MAP_GROWTH_FACTOR/HASH_MAP_GROWTH_FACTOR;
299     }
300 }
301
302 void HashMapClear(HashMap *hash_map) {
303     if (!hash_map) {
304         return;
305     }
306     size_t start_size = hash_map->size;
307     size_t start_cap = hash_map->capacity;
308     for (size_t i = 0; i < hash_map->capacity ; ++i) {
309         if (hash_map->buckets[i]) {
310             Vector *vec = hash_map->buckets[i];
311             VectorClear(vec);
312         }
313     }
314     ChooseCapOfClearMap(hash_map, start_size, start_cap);
315     for (size_t i = hash_map->capacity ; i < start_cap; ++i) {
316         VectorFree(&hash_map->buckets[i]);
317     }
318     hash_map->size = 0;
319 }

```

## 3 Vector.c

```
1  #include "Vector.h"
2  #include <stdlib.h>
3
4
5  Vector *VectorAlloc(VectorElemCpy elem_copy_func, VectorElemCmp elem_cmp_func, VectorElemFree elem_free_func) {
6      if(!elem_copy_func || !elem_cmp_func || !elem_free_func){ // check if the functions are not Null
7          return NULL;
8      }
9      Vector *new_vector = calloc(1, sizeof(Vector));
10     if (!new_vector) {
11         return NULL;
12     }
13     new_vector->data = calloc(VECTOR_INITIAL_CAP, sizeof(void *));
14     if (!new_vector->data) {
15         return NULL;
16     }
17     new_vector->capacity = VECTOR_INITIAL_CAP;
18     new_vector->size = 0;
19     new_vector->elem_copy_func = elem_copy_func;
20     new_vector->elem_cmp_func = elem_cmp_func;
21     new_vector->elem_free_func = elem_free_func;
22     return new_vector;
23 }
24
25 void VectorFree(Vector **p_vector) {
26     if (!*p_vector) {
27         return;
28     }
29     for (size_t k_i = 0; k_i < (*p_vector)->size; k_i++) {
30         (*p_vector)->elem_free_func(&(*p_vector)->data[k_i]);
31         (*p_vector)->data[k_i] = NULL;
32     }
33     free((*p_vector)->data);
34     (*p_vector)->data = NULL;
35     free(*p_vector);
36     (*p_vector) = NULL;
37 }
38
39 }
40 void *VectorAt(Vector *vector, size_t ind) {
41     if (!vector || ind >= vector->size || !vector->data) {
42         return NULL;
43     }
44     int *a = vector->data[ind];
45     return a;
46 }
47
48 int VectorFind(Vector *vector, void *value) {
49     if (!vector || !value) {
50         return -1; // need to think about it
51     }
52     for (size_t k_i = 0; k_i < vector->size; k_i++) {
53         void const *a = vector->data[k_i];
54         void const *b = value;
55         if (vector->elem_cmp_func(a, b)) {
56             return k_i;
57         }
58     }
59     return -1;
60 }
```



```

60 }
61
62 static void *CheckError(void *ptr, void *return_value) {
63     /**
64      * check error of the parameters that the function get
65      */
66     if (!ptr) {
67         return return_value;
68     }
69     return NULL;
70 }
71
72 int VectorIncreaseCapIfNessry(Vector *vector) {
73     /**
74      * this function check if we need to increase the capacity of the vector depend on the load factor
75      * and if it was it change the capacity
76      */
77     if (VectorGetLoadFactor(vector) >= VECTOR_MAX_LOAD_FACTOR) {
78         void **tmp = realloc(vector->data, vector->capacity * VECTOR_GROWTH_FACTOR * sizeof(void *));
79         CheckError(tmp, 0);
80         vector->data = tmp;
81         vector->capacity *= VECTOR_GROWTH_FACTOR;
82     }
83     return 1;
84 }
85
86 int VectorDecreaseCapIfNessry(Vector *vector) {
87     /**
88      * this function check if we need to decrease the capacity of the vector depend on the load factor
89      * and if it was it change the capacity
90      */
91     if (VectorGetLoadFactor(vector) != 0 && VectorGetLoadFactor(vector) < VECTOR_MIN_LOAD_FACTOR) {
92         void **tmp = realloc(vector->data, (vector->capacity / VECTOR_GROWTH_FACTOR) * sizeof(void *));
93         CheckError(tmp, 0);
94         vector->data = tmp;
95         vector->capacity /= VECTOR_GROWTH_FACTOR;
96     }
97     return 1;
98 }
99
100
101 int VectorPushBack(Vector *vector, void *value) {
102     CheckError(vector, 0);
103     CheckError(value, 0);
104     void *cpy_val = vector->elem_copy_func(value);
105     vector->data[vector->size++] = cpy_val;
106     VectorIncreaseCapIfNessry(vector); // increase the capacity of the vector and change the vector size and the vector cap
107     return 1;
108 }
109
110
111 double VectorGetLoadFactor(Vector *vector) {
112     if (!vector) {
113         return -1;
114     }
115     return (double) vector->size / vector->capacity;
116 }
117
118 int VectorErase(Vector *vector, size_t ind) {
119     CheckError(vector, 0);
120     if (ind >= vector->size) {
121         return 0;
122     }
123
124     vector->elem_free_func(&vector->data[ind]);
125     for (size_t k_i = ind; k_i < vector->size; k_i++) {
126

```

```

128         if (k_i != vector->size) { // if the index is not the last value in the vector
129             vector->data[k_i] = vector->data[k_i + 1];
130         } else {
131             vector->data[k_i] = NULL;
132         }
133     }
134     vector->size--;
135     VectorDecreaseCapIfNessry(vector);
136     return 1;
137 }
138 }
139 void ChooseCapOfClearVec(Vector *vec, size_t start_size, size_t start_cap) {
140     /** this function choose the final capacity of the vector .
141     * there are three options to the final capacity depend in what the start size and the start capacity
142     * was in the first
143     */
144     if (start_size == 1 && start_cap == VECTOR_INITIAL_CAP) {
145         vec->capacity = VECTOR_INITIAL_CAP/VECTOR_GROWTH_FACTOR;
146     } else if (start_size == 2 && start_cap == VECTOR_INITIAL_CAP) {
147         vec->capacity = VECTOR_INITIAL_CAP / VECTOR_GROWTH_FACTOR / VECTOR_GROWTH_FACTOR;
148     } else {
149         vec->capacity = VECTOR_INITIAL_CAP/VECTOR_GROWTH_FACTOR/VECTOR_GROWTH_FACTOR/ \
150             VECTOR_GROWTH_FACTOR/VECTOR_GROWTH_FACTOR;
151     }
152 }
153 void VectorClear(Vector *vector) {
154     if (!vector) {
155         return;
156     }
157     size_t start_size = vector->size;
158     size_t start_cap = vector->capacity;
159     int i = 0;
160     while (vector->size){
161         vector->elem_free_func(&vector->data[i++]);
162         vector->size--;
163     }
164     ChooseCapOfClearVec(vector, start_size, start_cap);
165 }
166 }

```

## Index of comments

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- 3.1 -2/-2 Documentation in c should be above the function and not below (code='bad\_way\_of\_doc')
- 4.1 שוב
- 4.2 שוב
- 6.1 שוב!
- 6.2 too\_deep\_condition