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```
clear;clc;close all

sat_states = [0 300;
              100 400;
              700 400
              800 300];

base_state = [400 0];
user_state = [401 0];

% plot(sat_states(:,1),sat_states(:,2),'o')
% hold on
% grid on
% plot(user_state(1),user_state(2),'x')
% plot(base_state(1),base_state(2),'square')
% title("Scenario Viewer")
% xlabel("X Position")
% ylabel("Y Position")
% legend(["SVs" "User" "Basestation"],"Location","east")
```

Question 5 - Part A

```
r_user = sqrt((sat_states(:,1)-user_state(1)).^2 + (sat_states(:,2)-
user_state(2)).^2);

% 2 SVs
r_user2 = r_user([1,4],:);
sat_states2 = sat_states([1,4],:);

rcvr = gpsRCVR([100;10]);

sol = p2d(rcvr,r_user2,sat_states2);

PDOP = sqrt(sol.DOP(1,1)^2 + sol.DOP(2,2)^2);

fprintf("Question 5 - Part A (2 SVs)\n")
fprintf("PDOP: %.5f\n\n",PDOP)

% 4 SVs
rcvr = gpsRCVR([100;10]);

sol = p2d(rcvr,r_user',sat_states');
```

```
PDOP = sqrt(sol.DOP(1,1)^2 + sol.DOP(2,2)^2);
```

```
fprintf("Question 5 - Part A (4 SVs)\n")
fprintf("PDOP: %.5f\n\n", PDOP)
```

```
Question 5 - Part A (2 SVs)
PDOP: 1.59353
```

```
Question 5 - Part A (4 SVs)
PDOP: 0.70711
```

Question 5 - Part B

```
r_user = sqrt((sat_states(:,1)-user_state(1)).^2 + (sat_states(:,2)-
user_state(2)).^2);
```

```
rcvr = gpsRCVR([400;0]);
```

```
sol = pt2d(rcvr,r_user',sat_states');
```

```
PDOP = sqrt(sol.DOP(1,1)^2 + sol.DOP(2,2)^2);
```

```
fprintf("Question 5 - Part B (4 SVs)\n")
fprintf("PDOP: %.5f\n\n", PDOP)
```

```
Question 5 - Part B (4 SVs)
PDOP: 25.00501
```

Question 5 - Part C

```
r_user = sqrt((sat_states(:,1)-user_state(1)).^2 + (sat_states(:,2)-
user_state(2)).^2);
```

```
r_base = sqrt((sat_states(:,1)-base_state(1)).^2 + (sat_states(:,2)-
base_state(2)).^2);
```

```
rcvr = gpsRCVR;
```

```
sol = ptSD2d(rcvr,r_user',r_base',sat_states',base_state');
```

```
PDOP = sqrt(sol.DOP(1,1)^2 + sol.DOP(2,2)^2);
```

```
fprintf("Question 5 - Part C (4 SVs)\n")
fprintf("PDOP: %.5f\n\n", PDOP)
```

```
Question 5 - Part C (4 SVs)
PDOP: 25.00500
```

Question 5 - Part D

```
rcvr = gpsRCVR;  
  
sol = ptDD2d(rcvr,r_user',r_base',sat_states',base_state');  
  
PDOP = sqrt(sol.DOP(1,1)^2 + sol.DOP(2,2)^2);  
  
fprintf("Question 5 - Part D (4 SVs)\n")  
fprintf("PDOP: %.5f\n\n",PDOP)  
  
Question 5 - Part D (4 SVs)  
PDOP: 17.38072
```

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