CENG 384 - Signals and Systems for Computer Engineers Spring 2018-2019

Written Assignment 4

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1. (a)
$$y[n] = 2x[n] - \frac{1}{8}y[n-2] + \frac{3}{4}y[n-1]$$

$$\frac{1}{8}y[\text{n-2}] - \frac{3}{4}y[\text{n-1}] \, + \, y[\text{n}] \, = \, 2x[\text{n}]$$

(b)
$$x[n] = e^{jwn}$$

$$y[n] = H(jw).e^{jwn}$$

$$\frac{1}{8} \ H(jw).e^{jw(n-2)} - \frac{3}{4} H(jw).e^{jw(n-1)} + H(jw).e^{jwn} = 2e^{jwn}$$

$$\frac{1}{8} H(jw).e^{-2jw} - \frac{3}{4} H(jw).e^{-jw} + H(jw) = 2$$

$$H(jw) \cdot (\frac{1}{8}e^{-2jw} - \frac{1}{8}e^{-jw} + 1) = 2$$

$$H(jw) = \frac{2}{\frac{1}{8}e^{-2jw} - \frac{3}{4}e^{-jw} + 1}$$

(c)
$$H(jw) = \frac{2}{\frac{1}{8}e^{-2jw} - \frac{3}{4}e^{-jw} + 1}$$

$$H(jw) = \frac{-2}{1 - \frac{1}{4}e^{-jw}} + \frac{4}{1 - \frac{1}{2}e^{-jw}}$$

$$h[n] = -2(\frac{1}{4})^n u[n] + 4(\frac{1}{2})^n u(n)$$

(d)
$$y[n] = x[n]*h[n]$$

$$X(e^{jw}) = \frac{1}{1 - \frac{1}{4}e^{-jw}}$$

$$Y(e^{jw}) = X(e^{jw}).H(e^{jw})$$

$$=\frac{1}{1-\frac{1}{4}e^{-jw}}.(\frac{-2}{1-\frac{1}{4}e^{-jw}}+\frac{4}{1-\frac{1}{2}e^{-jw}})$$

$$-2.\left(\frac{1}{1-\frac{1}{4}e^{-jw}}\right)^{2} + \frac{4}{\left(1-\frac{1}{4}e^{-jw}\right).\left(1-\frac{1}{2}e^{-jw}\right)}$$

$$-2.\left(\frac{1}{1-\frac{1}{4}e^{-jw}}\right)^{2}+\frac{32}{(4-e^{-jw}).(2-e^{-jw})}$$

$$\frac{32}{(4 - e^{-jw}).(2 - e^{-jw})} = \frac{A}{(4 - e^{-jw})} + \frac{B}{(2 - e^{-jw})} = \frac{-16}{(4 - e^{-jw})} + \frac{16}{(2 - e^{-jw})}$$

$$Y(e^{jw}) = -2.\left(\frac{1}{1 - \frac{1}{4}e^{-jw}}\right)^2 + -4\left(\frac{1}{1 - \frac{1}{4}e^{-jw}}\right) + 8\left(\frac{1}{1 - \frac{1}{2}e^{-jw}}\right)$$

$$y[n] = -2.(n+1).(\frac{1}{4})^n u[n] - 4(\frac{1}{4})^n u[n] + 8(\frac{1}{2})^n u[n]$$

2.
$$H_1(jw) = \frac{1}{1 - \frac{1}{2}e^{-jw}} + H_2(jw)$$

$$=\frac{5e^{-jw}-12}{e^{-2jw}-7e^{-jw}+12}$$

$$= \frac{5e^{-jw} - 12}{(e^{-jw} - 4).(e^{-jw} - 3)}$$

$$= \frac{A}{(e^{-jw} - 4)} + \frac{B}{(e^{-jw} - 3)}$$

$$= \frac{8}{(e^{-jw} - 4)} - \frac{3}{(e^{-jw} - 3)}$$

$$= \frac{-2}{\left(1 - \frac{1}{4}e^{-jw}\right)} + \frac{1}{\left(1 - \frac{1}{3}e^{-jw}\right)}$$

$$h[n] = -2(\frac{1}{4})^n u[n] + (\frac{1}{3})^n u[n]$$

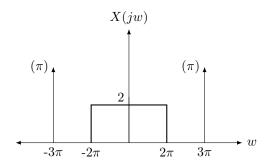
$$h[n] = h_1[n] + h_2[n] = -2(\frac{1}{4})^n u[n] + (\frac{1}{3})^n u[n]$$

$$\mathbf{h}[\mathbf{n}] = h_1[n] + h_2[n] = -2(\frac{1}{4})^n \mathbf{u}[\mathbf{n}] + h_2[n]$$

$$h_2[n] = -2(\frac{1}{4})^n \mathbf{u}[\mathbf{n}]$$

3. (a)
$$x(t) = \frac{\sin(2\pi t)}{\pi t} + \cos(3\pi t)$$

$$X(jw) = \pi(\delta(w-3\pi) + \delta(w+3\pi)) + 2rect(w)$$



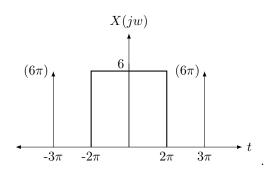
(b)
$$w_m = 3\pi$$

$$w_s = 2w_m = 6\pi$$

$$T = \frac{2\pi}{6\pi} = \frac{1}{3}$$

(c)
$$X_p(jw) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X(j(w - kw_s))$$

= $3 \sum_{k=-\infty}^{\infty} [\pi(\delta(w - k6\pi - 3\pi) + \delta(w - k6\pi + 3\pi)) + 2\text{rect}(\text{w-k}6\pi)]$



4. (a)
$$X_p(e^{jw}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X(j(w-\pi k))$$

$$X_d(\mathbf{n}) = X_p(\mathbf{j}\frac{w}{T})$$

$$X_d(e^{jw}) = \frac{1}{2} \sum_{k=-\infty}^{\infty} \frac{2w}{\pi} - \pi k \qquad |\mathbf{w}| \le \frac{\pi}{2}$$

(b)
$$H(e^{jw}) = \pi(\delta(w+\pi) + \delta(w-\pi))$$

(c)
$$Y_d(e^{jw}) = X_d(e^{jw}) * H(e^{jw})$$

$$Y_d(e^{jw}) = \frac{1}{2} \sum_{k=-\infty}^{\infty} \left[\frac{2w}{\pi} - \pi k \right] * \left[\pi (\delta(w + \pi) + \delta(w - \pi)) \right]$$

$$Y_d(e^{jw}) = \frac{\pi}{2} \sum_{k=-\infty}^{\infty} \frac{2(w+\pi)}{\pi} + \frac{2(w-\pi)}{\pi} - 2\pi k$$