# ${\bf Assignment 1}$

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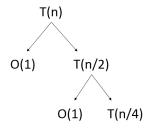
# 1 Problem One

#### 1.1 Solution

Given that the median of medians of two databases is the median of joint databases, we can use divide and conquer to design an algorithm whose inputs are two databases  $D_1$  and  $D_2$  and two pointers  $p_1$  and  $p_2$  which are both initialed as n/2 in the subset, which iteratively finds the medians of the subsets generated by pointers until one step where the set input is not dividable anymore.

```
Input: database1, database2
Output: median
 1: function MEDIAN OF DATABASES(D_1, D_2)
 2:
         q_1 \leftarrow n/2
         q_2 \leftarrow n/2
 3:
         for i = 2 to log n do
 4:
             m_1 \leftarrow query(D_1, q_1)
 5:
             m_2 \leftarrow query(D_2, q_2)
 6:
             if m_1 > m_2 then
 7:
                 q_1 \leftarrow q_1 - n/2^i
 8:
                 q_2 \leftarrow q_2 + n/2^i
 9:
             else
10:
                 q_1 \leftarrow q_1 + n/2^i
11:
                 q_2 \leftarrow q_2 - n/2^i
12:
             end if
13:
         end for
14:
         return min(m_1, m_2)
15:
16: end function
```

### 1.2 Subproblem Reduction Gragh



#### 1.3 Correctness Validation

With the technique of loop-variant, we can prove it in following steps:

**Initialization**: At first step,  $p_1 = p_2 = n/2$ , they are both the median of their own subsets.

**Maintenance**: Suppose  $m_1 > m_2$ , since  $m_1$  is the median of  $D_1$ , the global median should in the smaller binary part

of  $D_1$  or bigger part of  $D_2$ . Then searching field is updated to  $D_1$  and  $D_2$ , while  $p_1$  and  $p_2$  is also changed to their boundary. The searching field is updated to  $D_1^2$  and  $D_2^2$ , while  $p_1$  and  $p_2$  is also changed to their boundary. During the for loop, loop invariant should hold and the algorithm is still searching in potential field.

**Termination**: At termination, i=logn,  $m_1$  and  $m_2$  is the nth and (n+1)th smallest point. According to the definition of median, we choose the smaller one of  $m_1$  and  $m_2$  as the final median.

# 1.4 Complexity Analysis

The time complexity is  $T(n) = 2T(n/2) + O(1) = O(\log n)$ 

# 2 Problem Five

#### 2.1 Solution

The solution of this problem is equivalent to normal counting-inversion problem except for an extra judgement  $(a_i > 3a_i)$ . Thus similarly we use divide and conquer technique as follows:

**Divide:**Divide A into two arrays A[0...n/2-1] and A[n/2...n-1]; thus counting inversions within A[0...n/2-1] and A[n/2...n-1]constitutes two subproblems.

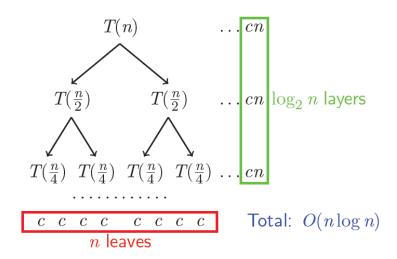
Conquer: Counting inversions within each half by calling countinginversion itself.

Combine: Note that elements in both halves are in increasing order. We can easily calculate the inversions in O(n) time.

```
Input: Array
Output: Number of Significant Inversions
 1: function SIGNIFICANT-INVERSIONS(Array, left, right)
       result \leftarrow 0
 2:
       if left < right then
 3:
           middle \leftarrow (left + right)/2
 4:
           result \leftarrow result + SIGNIFICANT-INVERSIONS(Array, left, middle)
 5:
           result \leftarrow result + SIGNIFICANT-INVERSIONS(Array, middle, right)
 6:
           result \leftarrow result + \text{MID-INVERSION}(Array, left, middle, right)
 7:
       end if
 8:
 9:
       return result
10: end function
11:
12: function MID-INVERSION(Array, left, middle, right)
       i \leftarrow left
13:
       j \leftarrow middle
14:
       k \leftarrow 0
15:
16:
       result \leftarrow 0
       while i < middle and j < right do
17:
           if Array[i] < Array[j] then
18:
               B[k++] \leftarrow Array[i++]
19:
           else
20:
               B[k++] \leftarrow Array[j++]
21:
               if Array[i] > 3 * Array[j] then
22:
                  result \leftarrow result + (j - k)
23:
24:
               end if
           end if
25:
       end while
26:
       while i < middle do
27:
           B[k++] \leftarrow Array[i++]
28:
       end while
29:
       while j < right do
30:
```

```
31: B[k++] \leftarrow Array[j++]
32: end while
33: for i = 0 \rightarrow k - 1 do
34: Array[left+i] \leftarrow B[i]
35: end for
36: return result
37: end function
```

## 2.2 Subproblem Reduction Gragh



#### 2.3 Correctness Validation

With the technique of loop-variant, we can prove it in following steps:

**Initialization**: When n=1,there is no significant inversions.

Maintenance: Assume that two subarray lists are all ordered and inversions of each list are calculated. Putting the first smaller number of two lists into the new array ensures that the new array is ordered too. We thus can calculate the inversions by adding the left number, the right number and the inversions between subarrays. The sum is the inversions of new arrays.

**Termination**: When combine the last two lists together, similarly we get the sum of inversions and that is the total number of significant inversions.

### 2.4 Complexity Analysis

Time complexity:  $T(n)=2T(n/2)+O(n)=O(n\log n)$ 

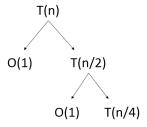
# 3 Problem Three

#### 3.1 Solution

In this problem, we define probe() to get the value of one node. We recursively find the smallest one in its children and itself. If itself has the smallest value, then we return its value or we recursively compare the smallest child and its subtree.

```
Input: T
Output: local minimum
 1: function FIND MIN(T)
       if min(probe(T.root(), probe(T.left()), probe(T.right()) == probe(T.root()) then
          return probe(T.root())
 3:
       else
 4:
          if probe(T.left()) > probe(T.right()) then
 5:
             return FIND MIN(T.left())
 6:
          else
 7:
             return FIND MIN(T.right())
 8:
          end if
 9:
       end if
10:
11: end function
```

# 3.2 Subproblem Reduction Gragh



#### 3.3 Correctness Validation

With the technique of loop-variant, we can prove it in following steps:

**Initialization**: At first step, the initial node we input is the root, we compare the value of it and its two children. The node we may return is the smallest of them.

Maintenance: Suppose the right child is smallest, we compare the values of this new node and its children, this process recursively goes forward until one node whose root has the smallest value.

**Termination**: At termination, since the root's value is the smallest, the local minimum is found and it is the smallest in the path through.

# 3.4 Complexity Analysis

The time complexity is T(n) = T(n/2) + O(1) = O(logn)