CH-4103 Bottmingen github.com/orestis-z

Orestis Zambounis

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MSc ETH Robotics Engineer

Experience

Web Application Developer (civil service)

May 2020 - Jul 2020

Kantonsspital St Gallen · Full-time

St. Gallen, Switzerland

Added new features to a frontend website with Vue.js following integration testing with TestCafe

Full-Stack Developer w/ Machine Learning

Jul 2019 - May 2020

Zambounis Technology · Full-time

Basel, Switzerland

- Modified and retrained a CNN with **TensorFlow** and **scikit-learn** for facial beauty detection leading to an up to **18**% higher accuracy compared to the state-of-the-art
- Developed a cross-platform frontend with a mixture of Cordova, React Native, React.js and Electron to support mobile, web and desktop apps with one code-base
- Developed a backend composed of four scalable microservices with Python / Flask and PostgreSQL and deployed it to AWS OpsWorks
- · Generated user leads with blogging, Facebook and Google Ads

Co-Founder, Technical Lead

Jan 2018 - Apr 2019

Kimata Networks · Full-time

Basel, Switzerland

- Launched a mobile app with OpenGL / libGDX, Java / Android and React Native
- · Created product specifications, hired and managed a team of five frontend and backend developers
- Gained entrepreneurial insights into founding a company, business planning, intellectual property, basic accounting, strategic decision making and pivoting
- Raised CHF 10,000 by passing the first Venture Kick stage

Mobile App Developer

Sep 2017 - Aug 2018

nextron internet team $\mathsf{GmbH} \cdot \mathsf{Part}\text{-time}$

Basel, Switzerland

 Developed and released a cross-platform mobile app with React Native leading to 1,000+ downloads and 5 star rating

System Control Engineer, Intern

Mar 2016 - Feb 2017

Rapyuta Robotics · Full-time

Zurich, Switzerland / Tokyo, Japan

- Designed a state-of-charge battery estimator with an extended Kalman Filter (EKF)
- Refactored a model-simulation-framework codebase in Pvthon / NumPv
- Sped up a model-simulation-framework by 550% with the creation of PyJet
- Created an energy estimator for an arbitrary path followed by a multi-rotor vehicle
- Improved a setpoint tracking controller for a multi-rotor vehicle implemented in C++
- Leveraged additional knowledge in Linux, Bash scripting and ROS

Education

ETH Zurich

Imperial College London

Aug 2018 - Mar 2019

Exchange for Master's Thesis

London, United Kingdom

- Designed a CNN deep learning architecture that predicts object instances, human poses, instance masks and tracks people
- Implemented the CNN using Caffe2 and Python including custom operators with CUDA C/C++

MSc Robotics, Systems & Control (5.25/6.0)

Feb 2017 - Mar 2019

Zurich, Switzerland

Semester thesis (5.75/6.0):

- Modified an existing Mask R-CNN implementation with TensorFlow, Keras and Python
- Showed that an additional depth input channel improves the segmentation accuracy by up to 31%
- Submitted the computer vision paper report to CoRL 2018

ETH Zurich

Sep 2012 - Feb 2016 Zurich, Switzerland

BSc Mechanical Engineering (5.51/6.0)

Bachelor's thesis (5.75/6.0):

Synthesised non-linear attitude control algorithms and a Kalman filter using C++ and MATLAB / Simulink

Software Projects

Personal Website

Published my personal website with React.js / Next.js and AWS Lambda on www.leanmind.ch (German)

Resume Compiler

• Open-sourced a resume compiler using Node.js at github.com/orestis-z/resume-compiler

Mobile Apps

Created multiple mini mobile apps with React Native and Cordova published on Google Play Store

PyJET - compiling NumPy

- Sped up Python code by converting NumPy operations to performant C++
- Co-authored and open-sourced the Python package PyJET

Other

Languages

German (mother tongue), Greek (mother tongue), English (fluent), French (intermediate), Italian (beginner)

Hobbies

Rock climbing, Saxophone, Programming, Traveling