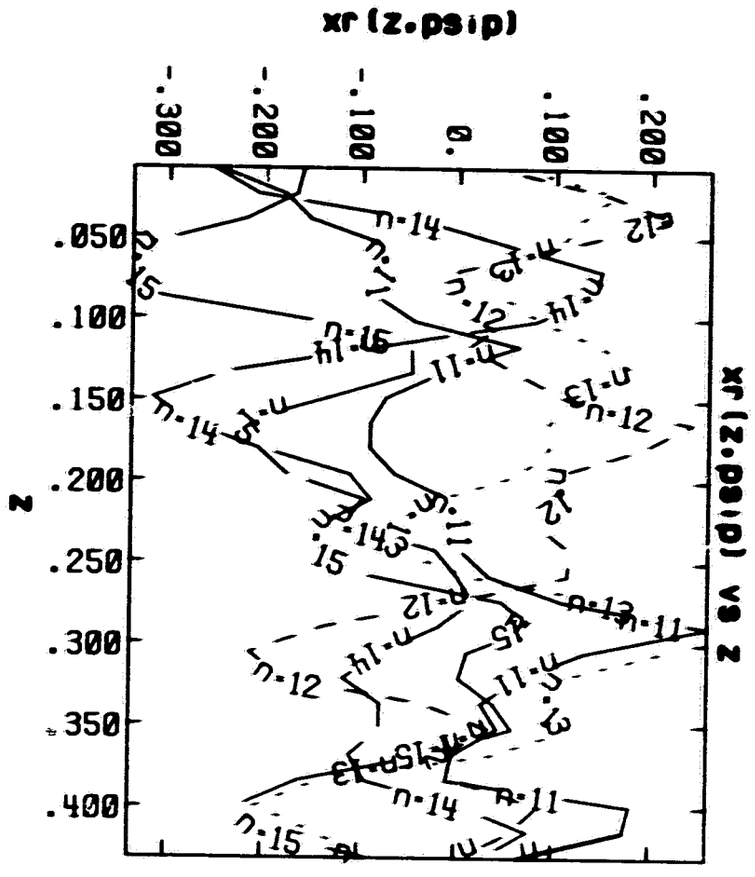
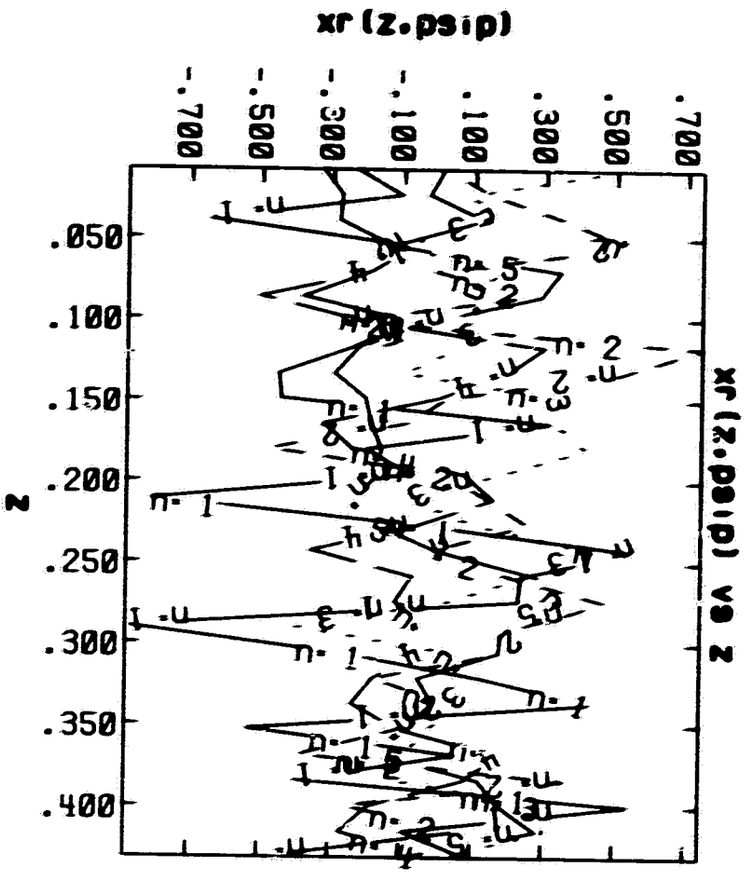
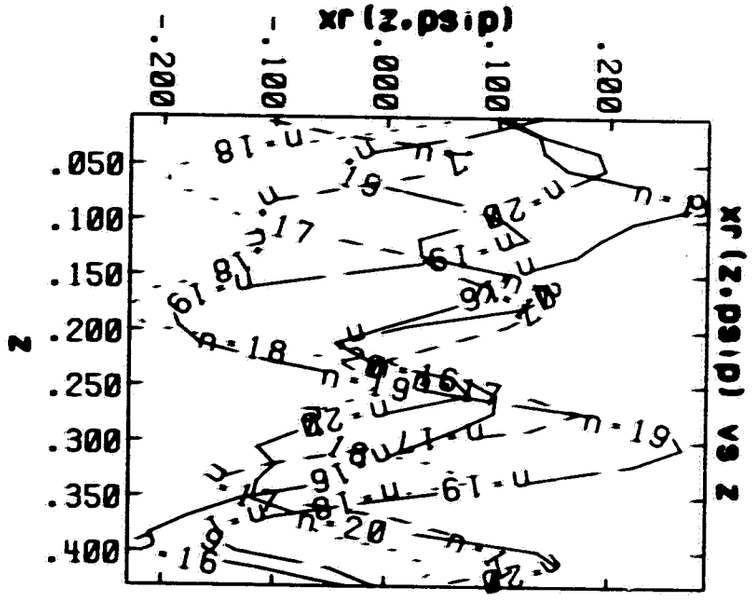
```
box u21$

graflib:gcs02042kcs02042

15:50:4008/05/82 c
```

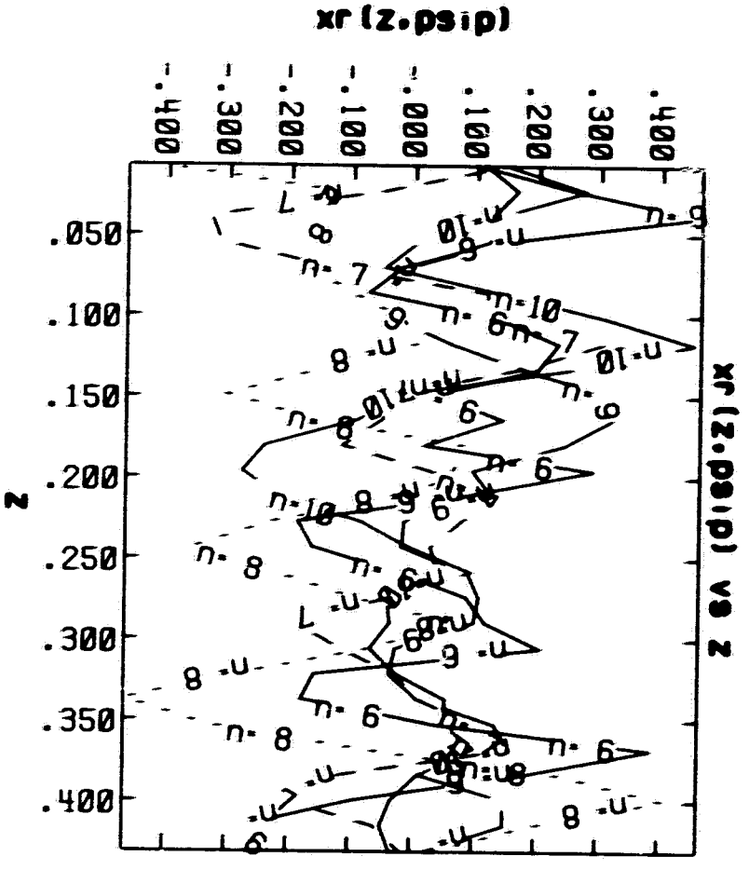
```
box u21$

graflib:gcs02042kcs02042

15:50:4008/05/82 c
```

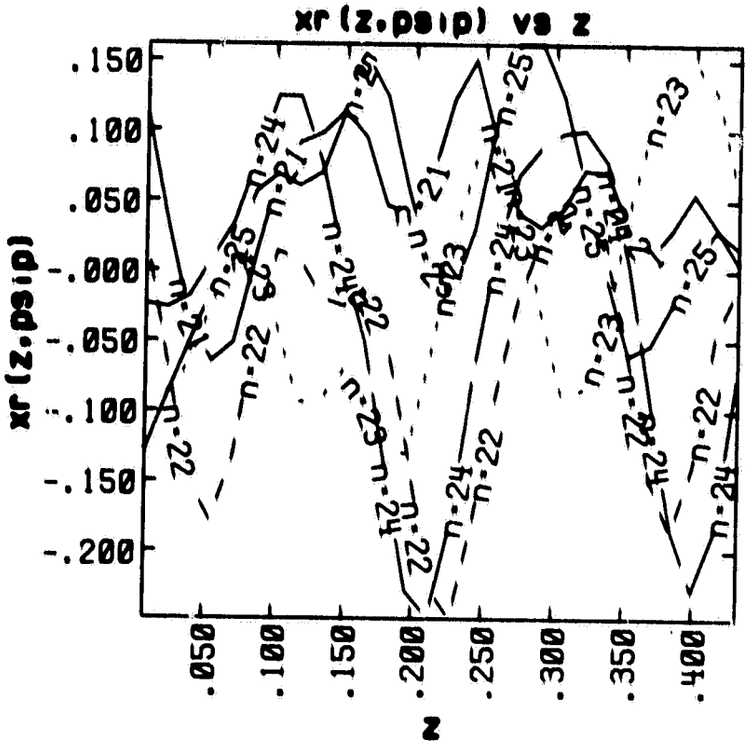
```
dt=    3.125000e-11
ix=      30
jx=      30
total time steps =    2400
no. of iterations =       4
bias=   0.01000
ratrod=   -2.000000e+00
drift freq. (omegst) =  6.14023730e+08
rotation freq. (omegr) = -1.22804746e+09
e x b freq. (omegexb) = -6.14023730e+08
flr=  1.00000000e+00
sf6=  1.00000000e+00
sf8=  1.00000000e+00
enbar=  0.
kplot=     349
kzs=       1
valfk =  9.00000000e-01
     cpu time =  8.54245060e+13
     i-o time =  1.21177700e+12
     sys time =  9.60171800e+12
```

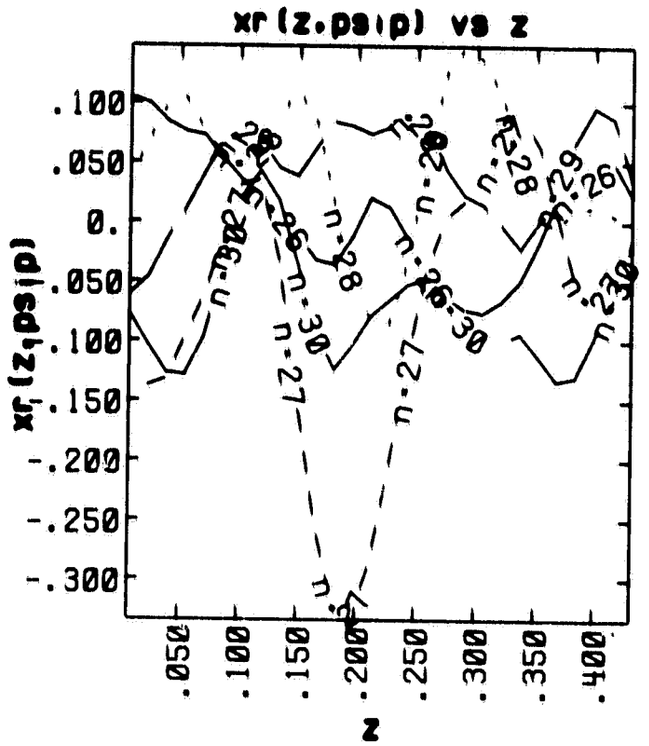

xr(z,psip)
xr(z,psip) vs z
z

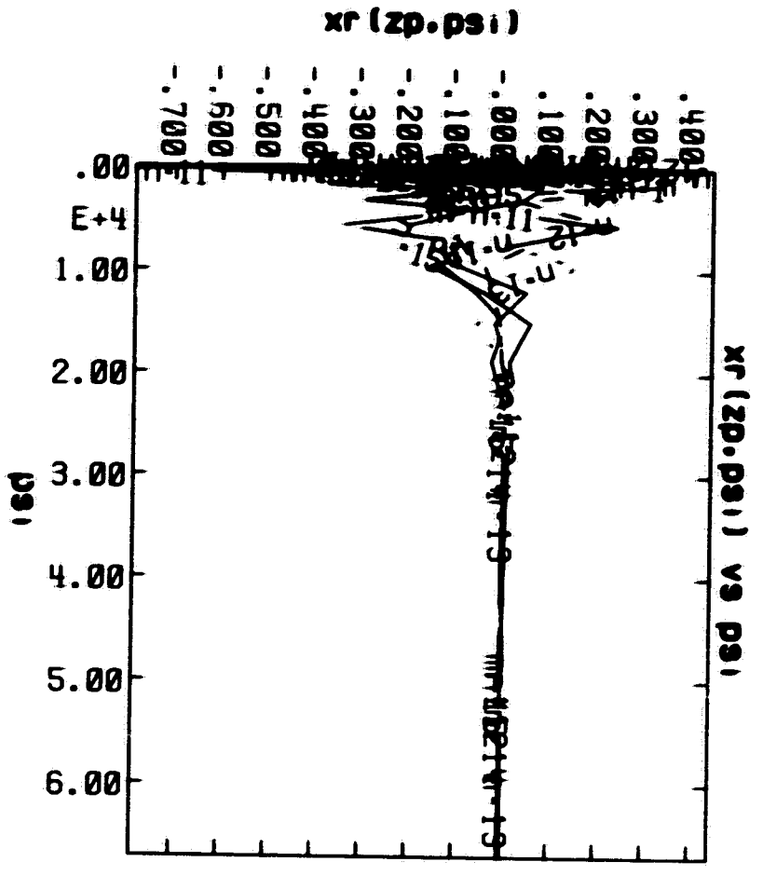

xr(z,psip)
xr(z,psip) vs z
z

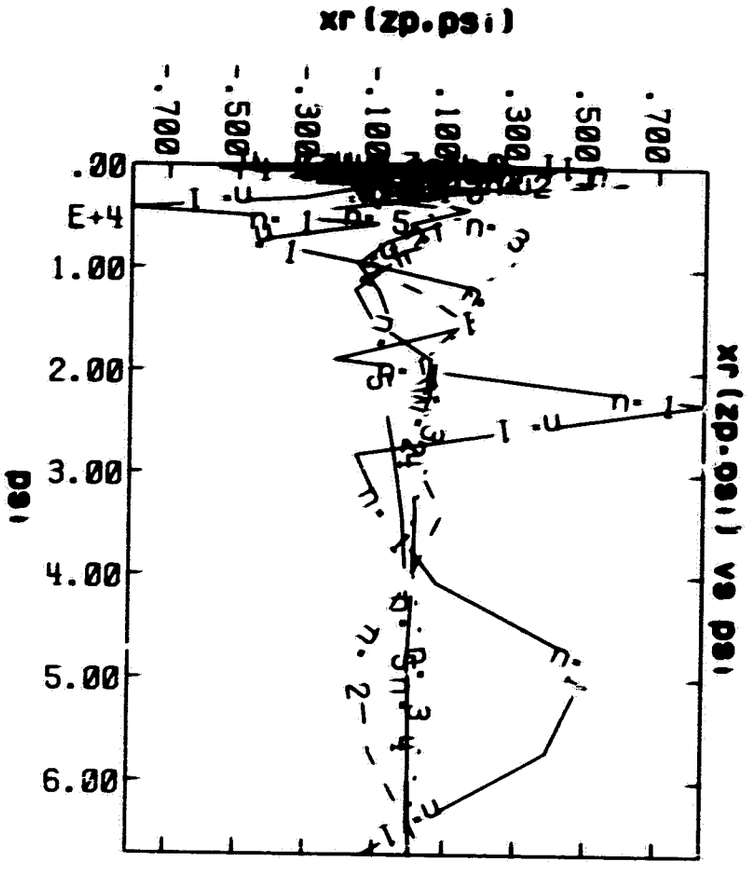

xr(z,psip)
xr(z,psip) vs z
z

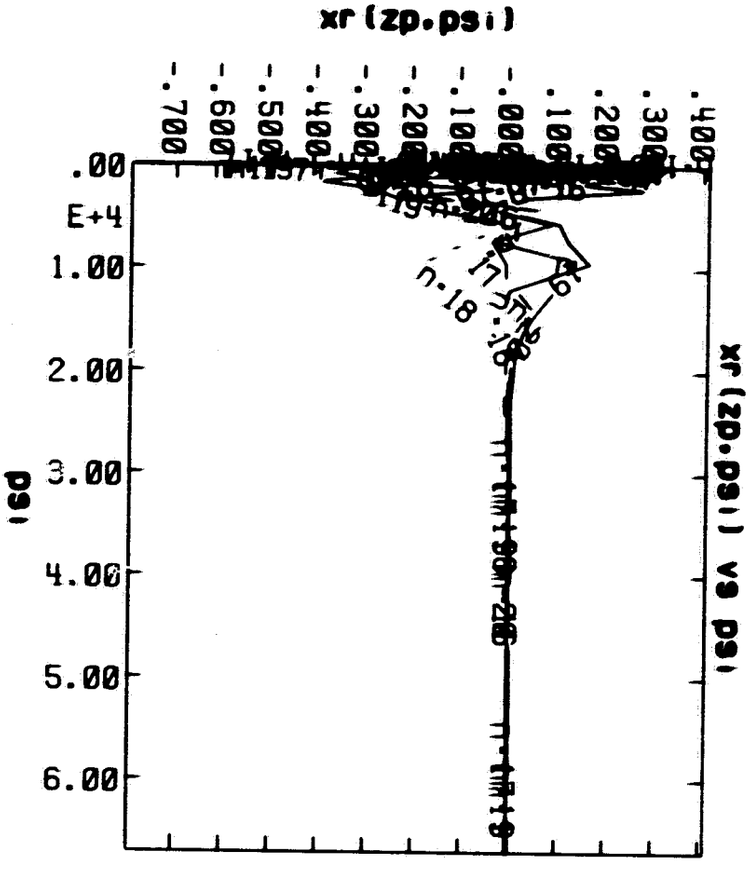

xr(z,psip)
xr(z,psip) vs z
z

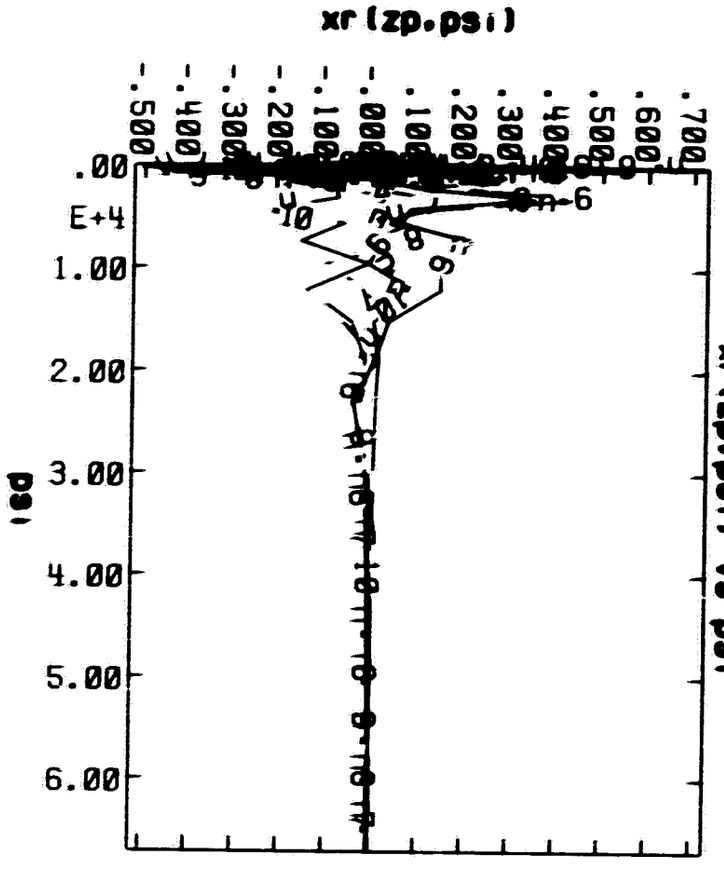

xr(z,psip) vs z
xr(z,psip)
z
.150
.100
.050
-.000
-.050
-.100
-.150
-.200
.050
.100
.150
.200
.250
.300
.350
.400

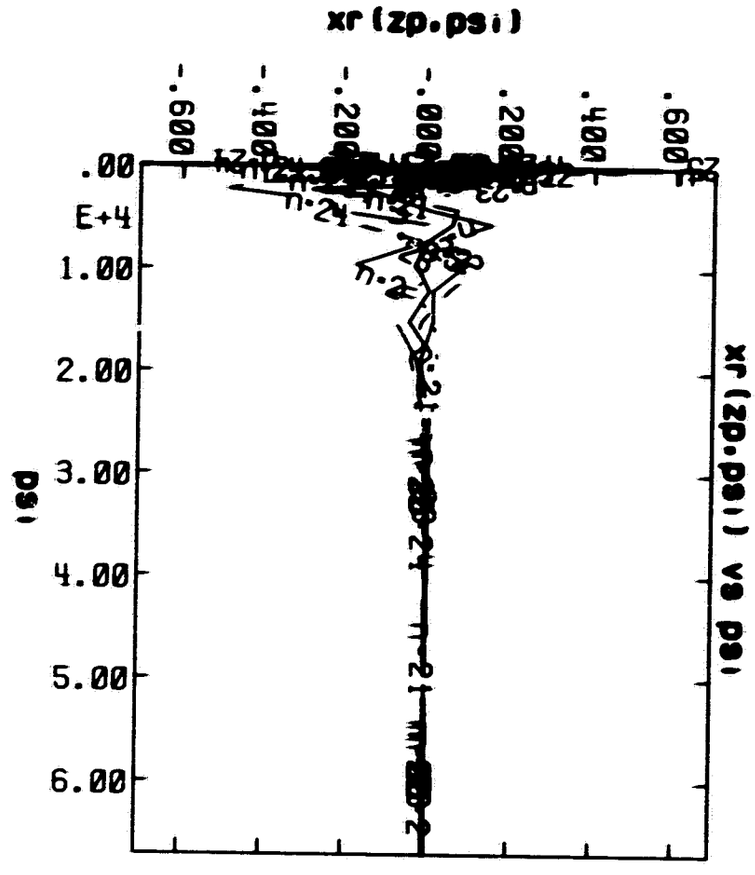

xr(z,psip) vs z
xr(z,psip)
z
.100
.050
0.
-.050
-.100
-.150
-.200
-.250
-.300
.050
.100
.150
.200
.250
.300
.350
.400

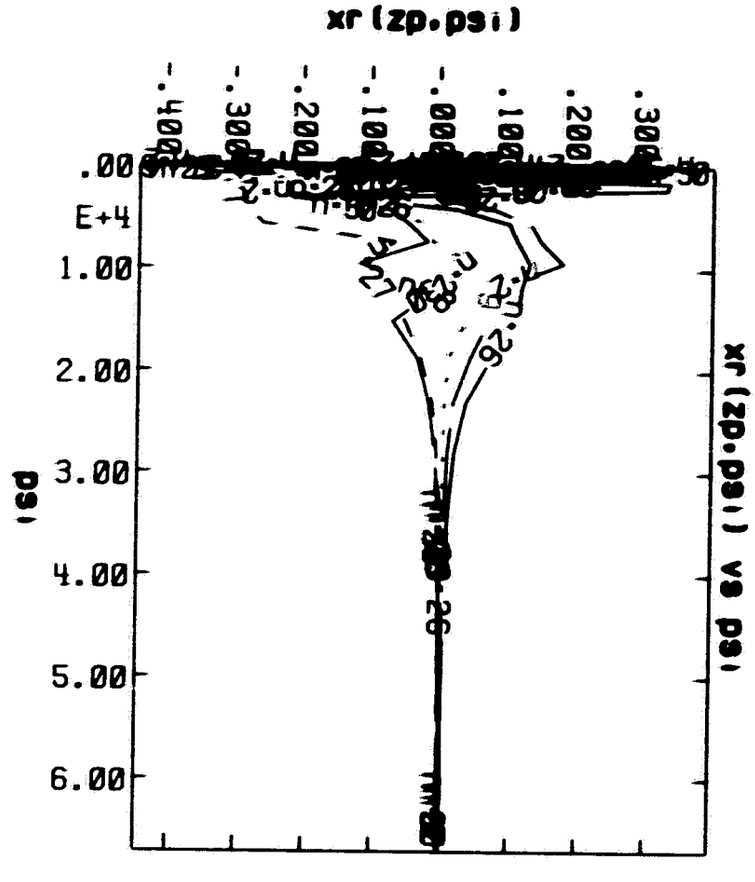

xr(zp.psi)
psi
xr(zp.psi) vs psi

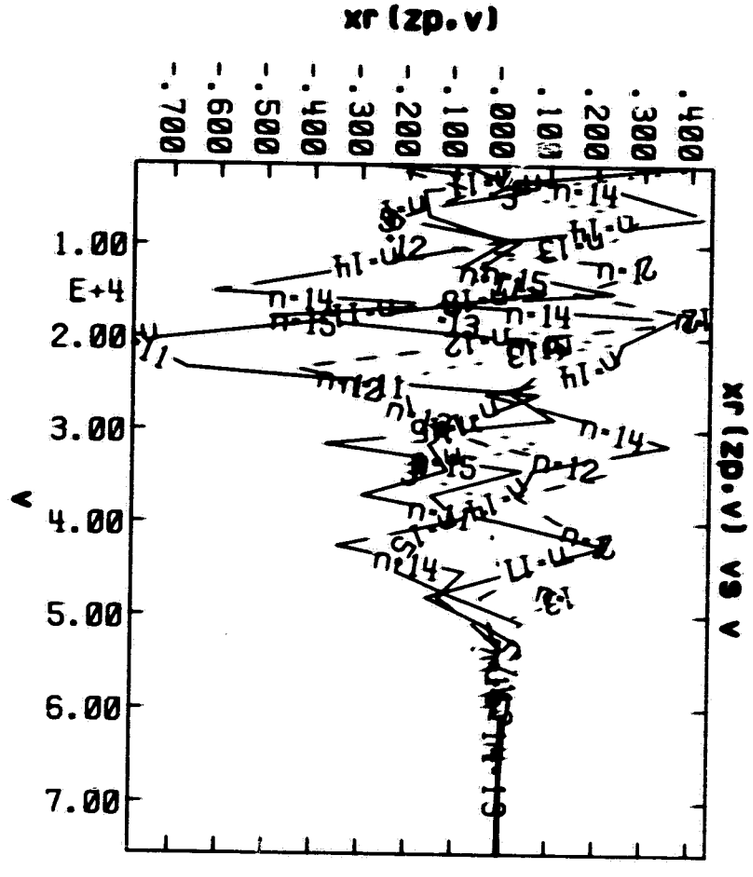

xr(zp.psi)
psi
xr(zp.psi) vs psi

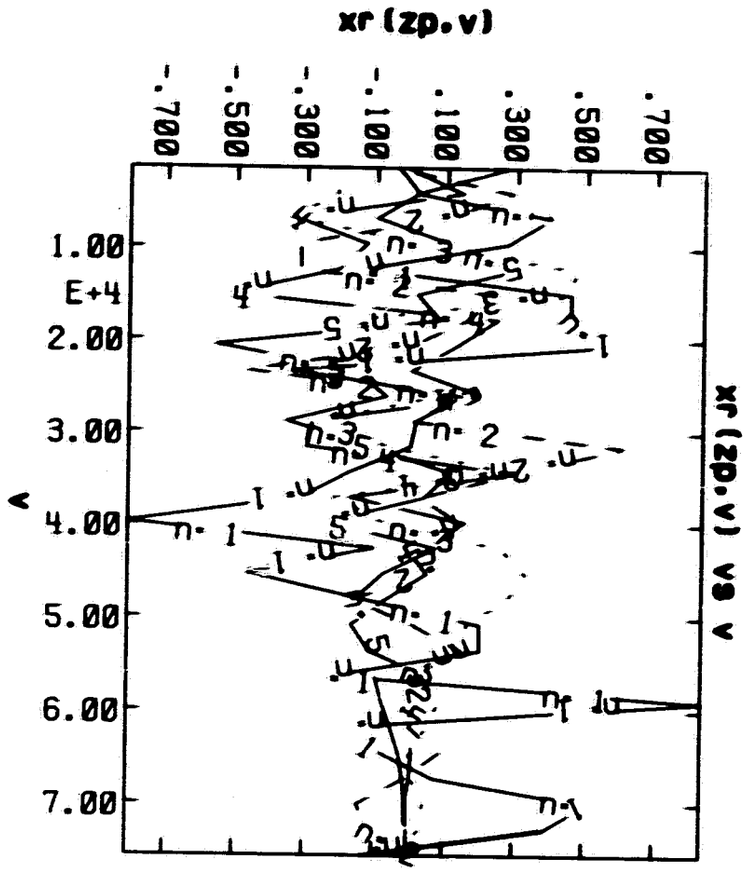

xr(zp.psi)
psi
xr(zp.psi) vs psi

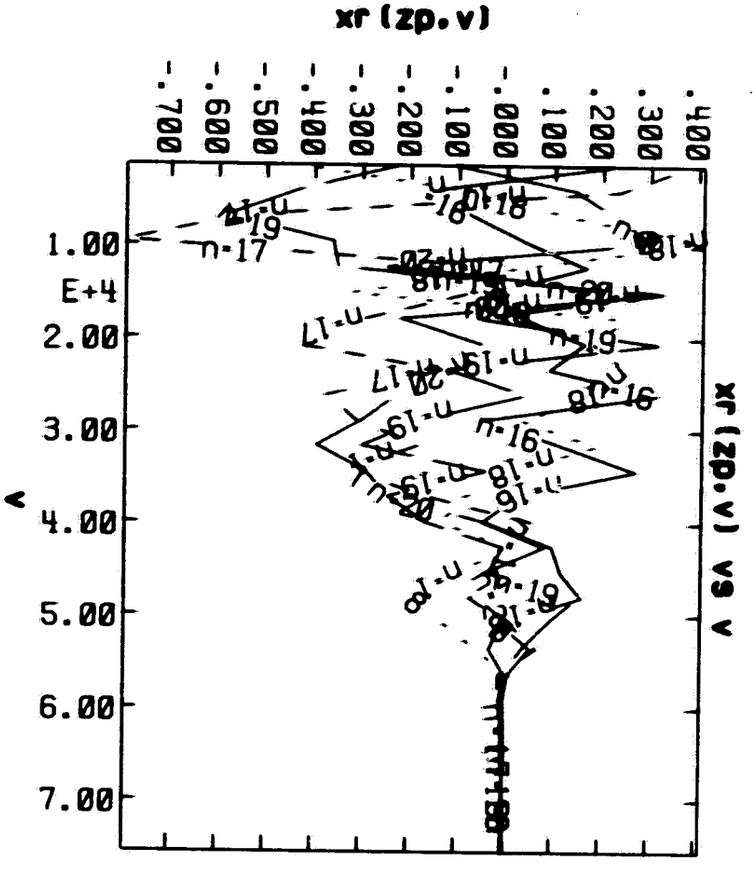

xr(zp.psi)
psi
xr(zp.psi) vs psi

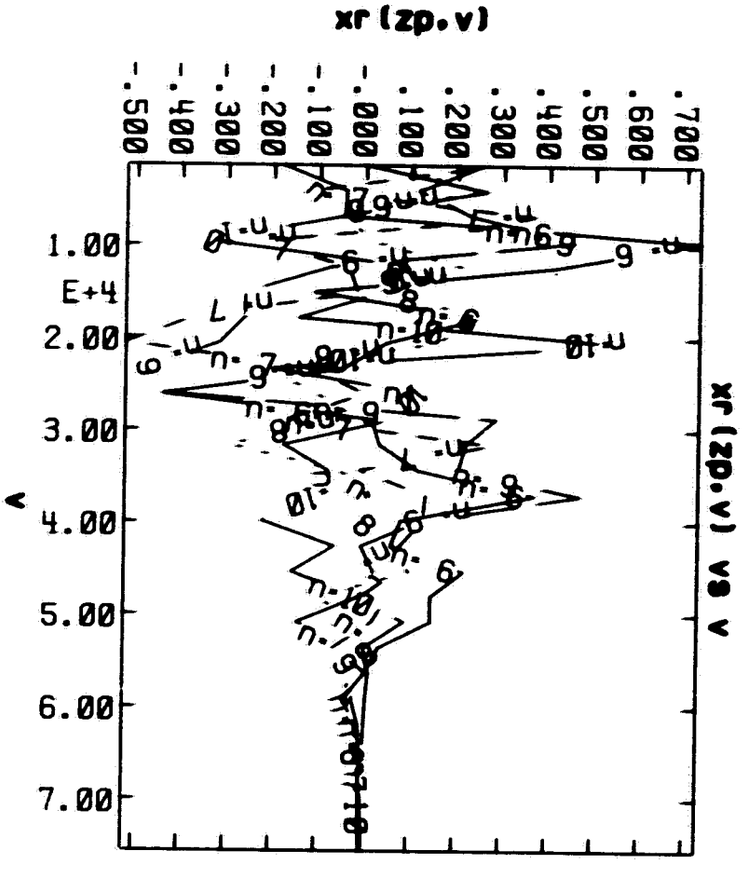

xr(zp.psi)
.00
E+4
1.00
2.00
3.00
4.00
5.00
6.00
psi
xr(zp.psi) vs psi

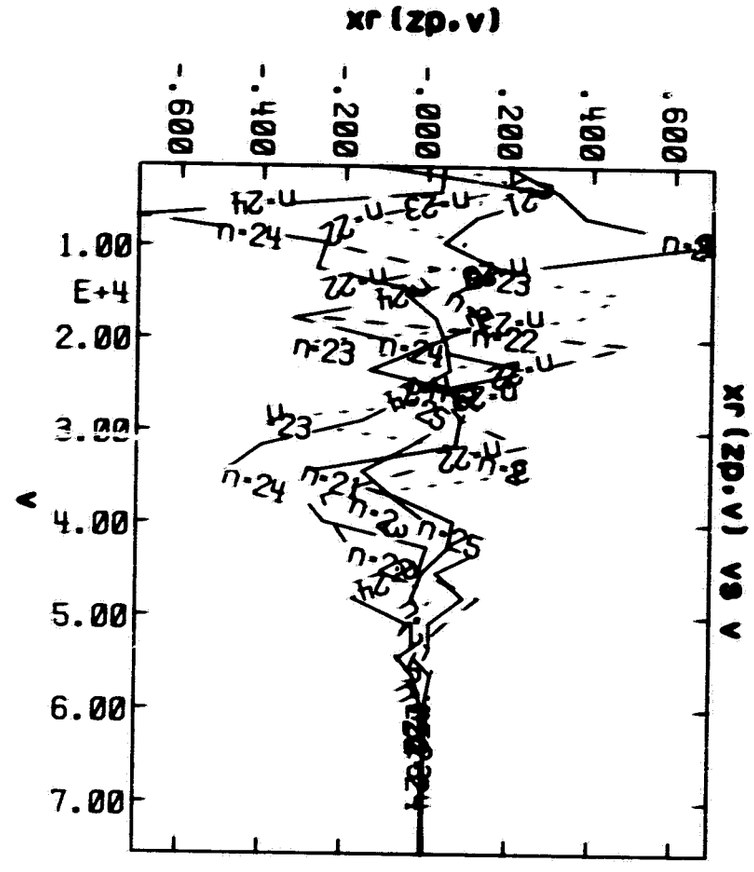

xr(zp.psi)
.00
E+4
1.00
2.00
3.00
4.00
5.00
6.00
psi
xr(zp.psi) vs psi

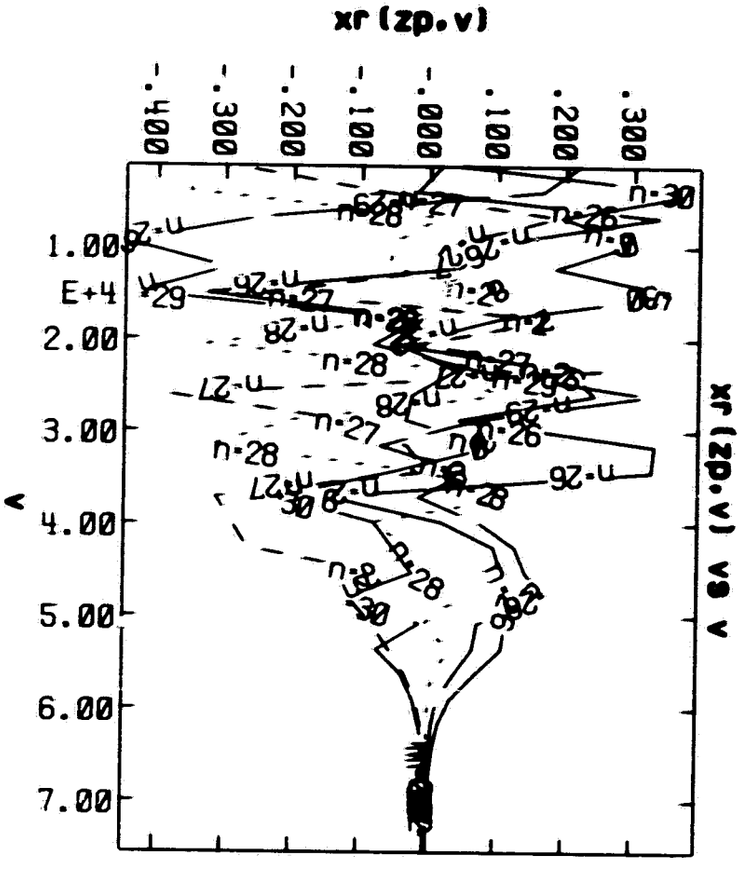

xr (zp, v)
xr (zp, v) vs v
v
1.00
E+4
2.00
3.00
4.00
5.00
6.00
7.00

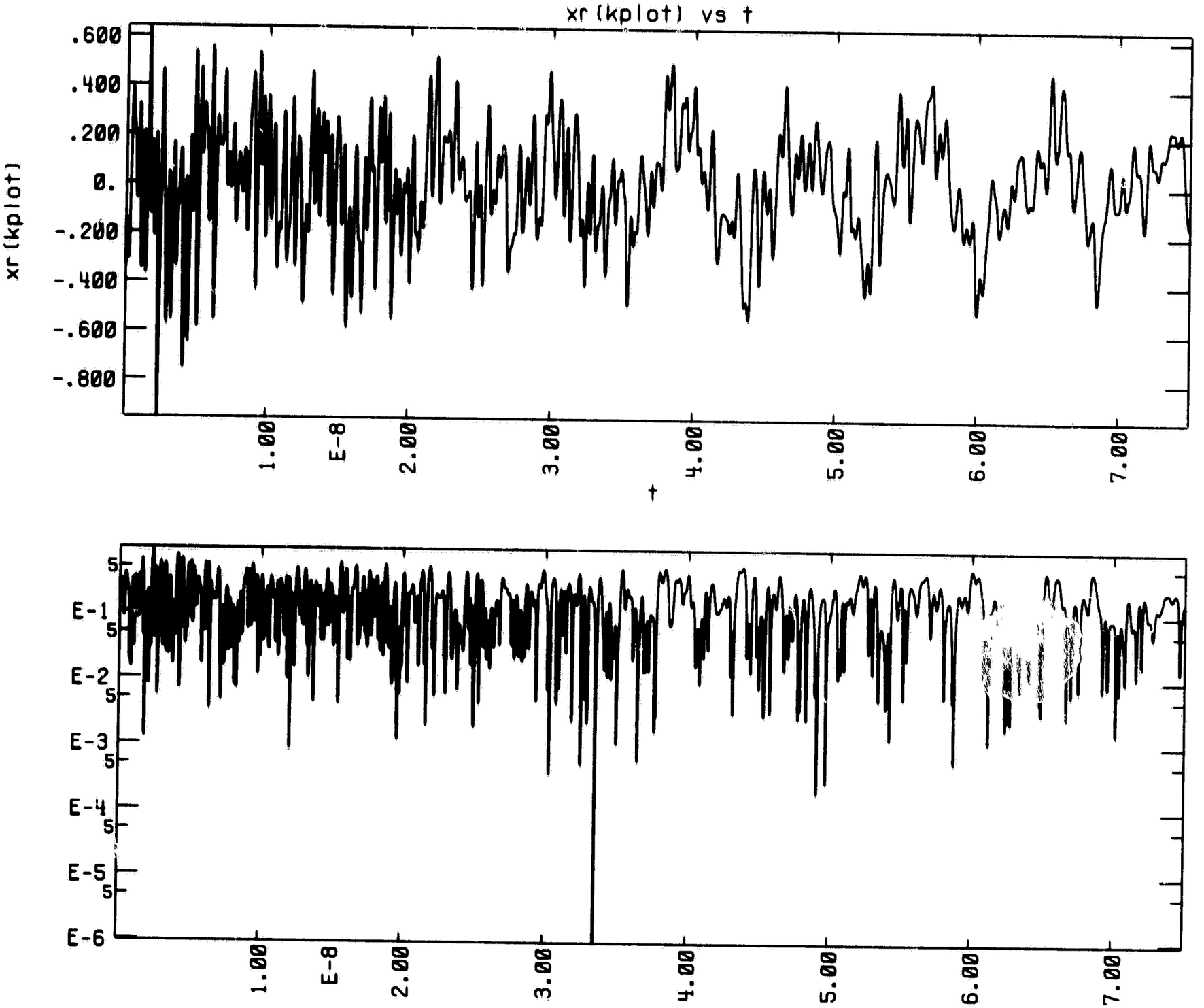

xr (zp, v)
xr (zp, v) vs v
v
1.00
E+4
2.00
3.00
4.00
5.00
6.00
7.00


xr (zp, v)
xr (zp, v) vs v
v
1.00
E+4
2.00
3.00
4.00
5.00
6.00
7.00


xr (zp, v)
xr (zp, v) vs v
v
1.00
E+4
2.00
3.00
4.00
5.00
6.00
7.00


xr(zp,v)
-.600
-.400
-.200
-.000
.200
.400
.600
1.00
E+4
2.00
3.00
4.00
5.00
6.00
7.00
xr(zp,v) vs v


xr(zp,v)
-.400
-.300
-.200
-.100
-.000
.100
.200
.300
1.00
E+4
2.00
3.00
4.00
5.00
6.00
7.00
xr(zp,v) vs v


xr(kplot) vs t
xr(kplot)
.600
.400
.200
0.
-.200
-.400
-.600
-.800
1.00
E-8
2.00
3.00
4.00
5.00
6.00
7.00
t
5
E-1
5
E-2
5
E-3
5
E-4
5
E-5
5
E-6
1.00
E-8
2.00
3.00
4.00
5.00
6.00
7.00

box u21$

graflib:gcs02042kcs02042
11 frames

15:50:4008/05/82 c