

box u21\$

graflib:gcs02042kcs02042

10:42:03 08/06/82 c

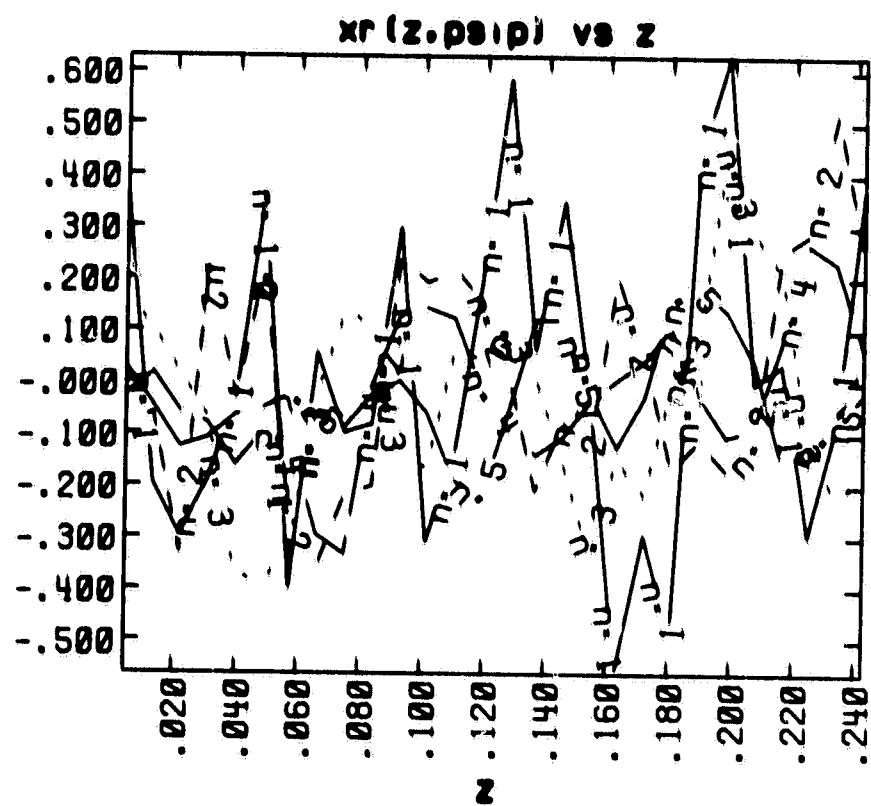
box u21\$

graflib:gcs02042kcs02042

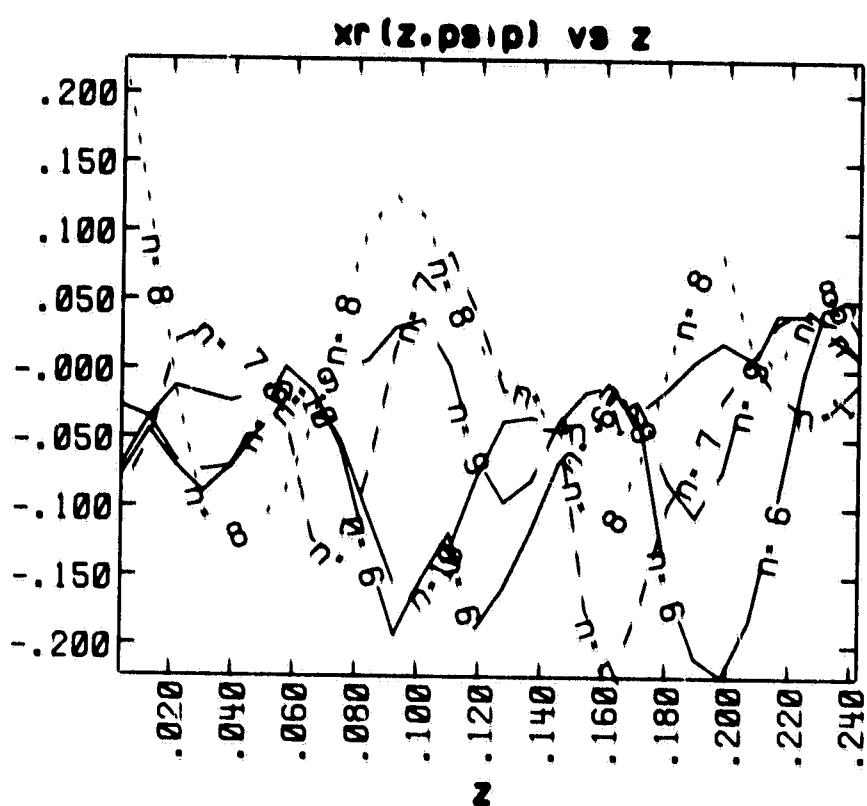
10:42:03 08/06/82 c

dt. 3.125000e-11
ix. 30
jx. 30
total time steps . 2400
no. of iterations . 4
bias. 0.01000
ratrod. 1.000000e+00
drift freq. (omegst) . 6.14023730e+08
rotation freq. (omegr) . 6.14023730e+08
e x b freq. (omegexb) . 1.22804746e+09
fir. 1.00000000e+00
sf6. 1.00000000e+00
sf8. 1.00000000e+00
enbar. 0.
kplot. 349
kzs. 1
valfk . 1.60000000e+00
cpu time . 8.53679060e+13
i-o time . 1.74072300e+12
sys time . 9.59128200e+12

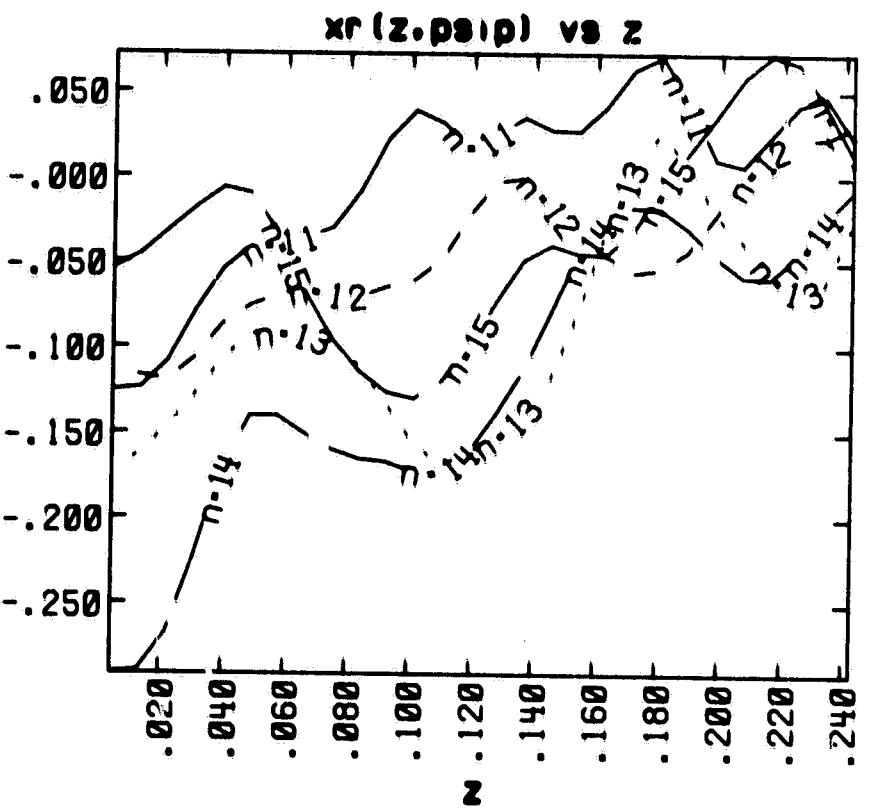
$xr(z, psid)$



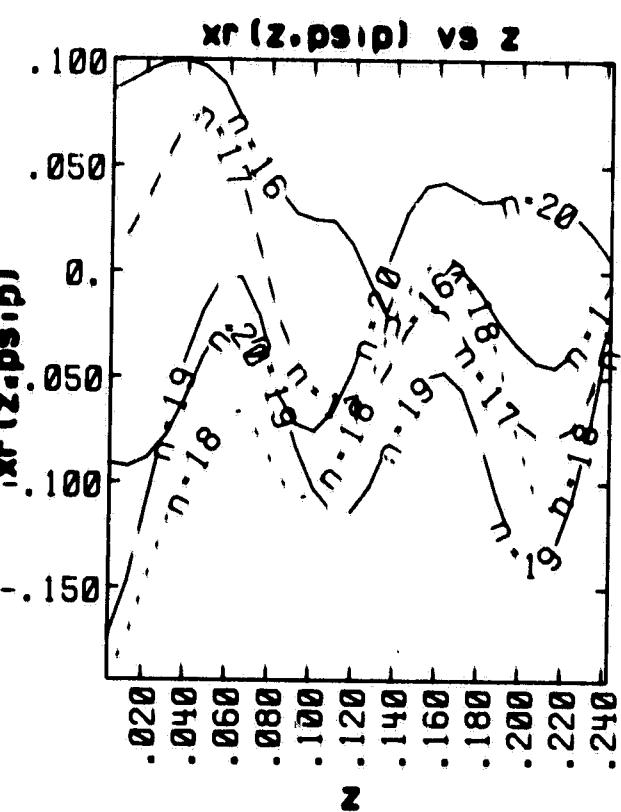
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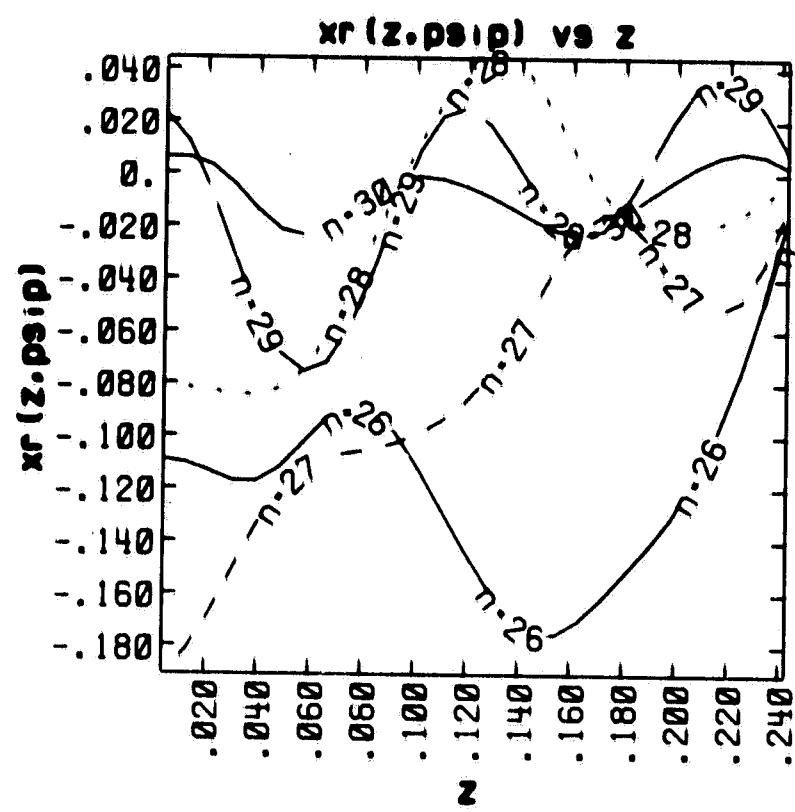
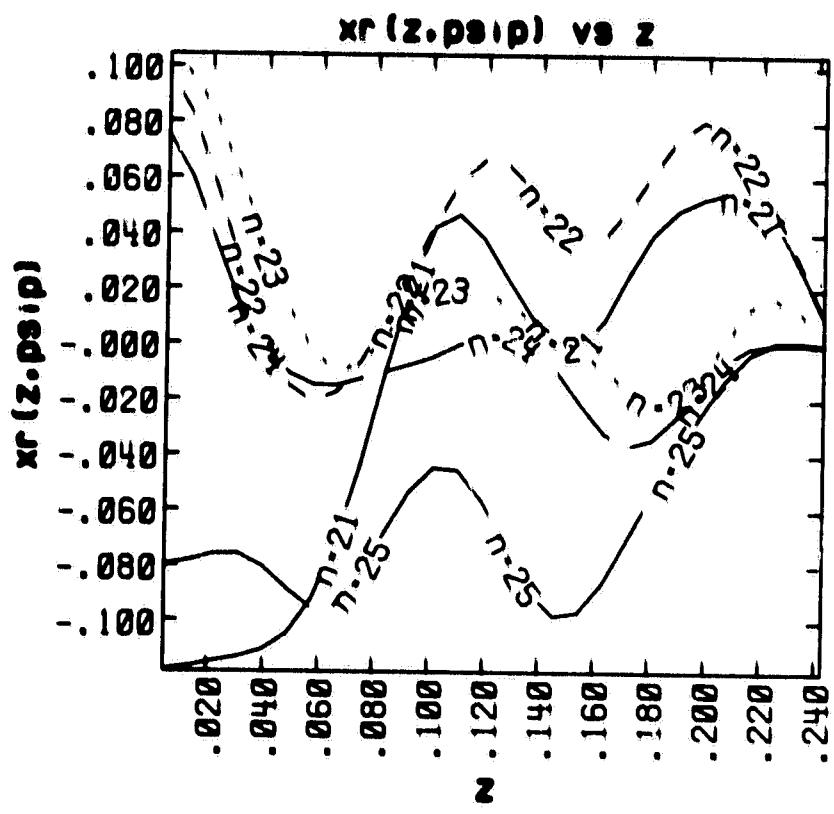


$xr(z, psid)$

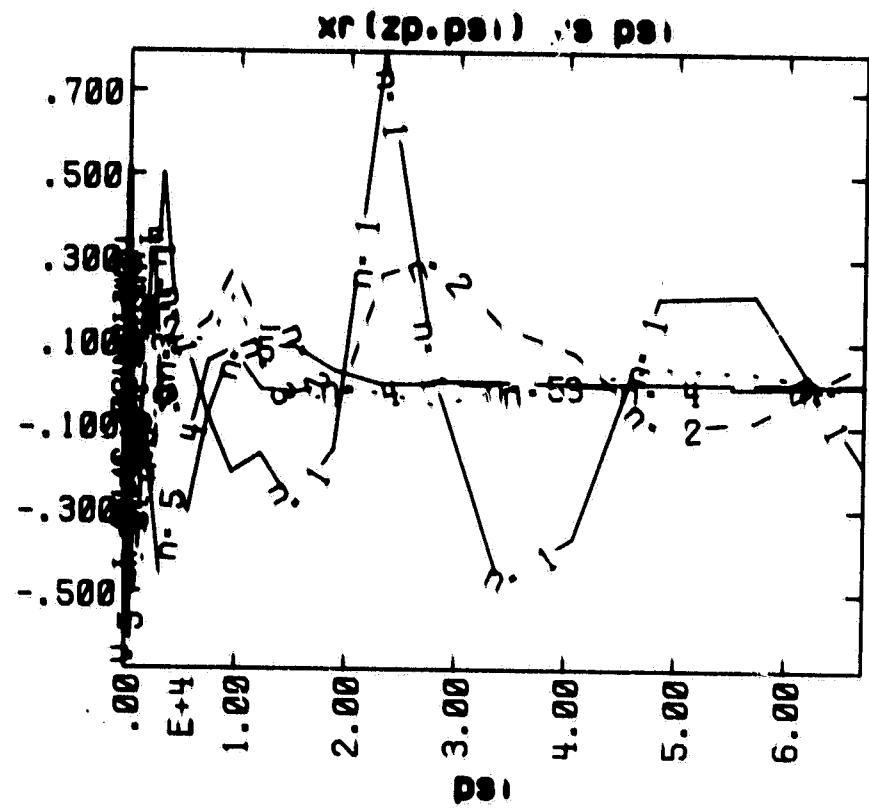


$xr(z, psid)$

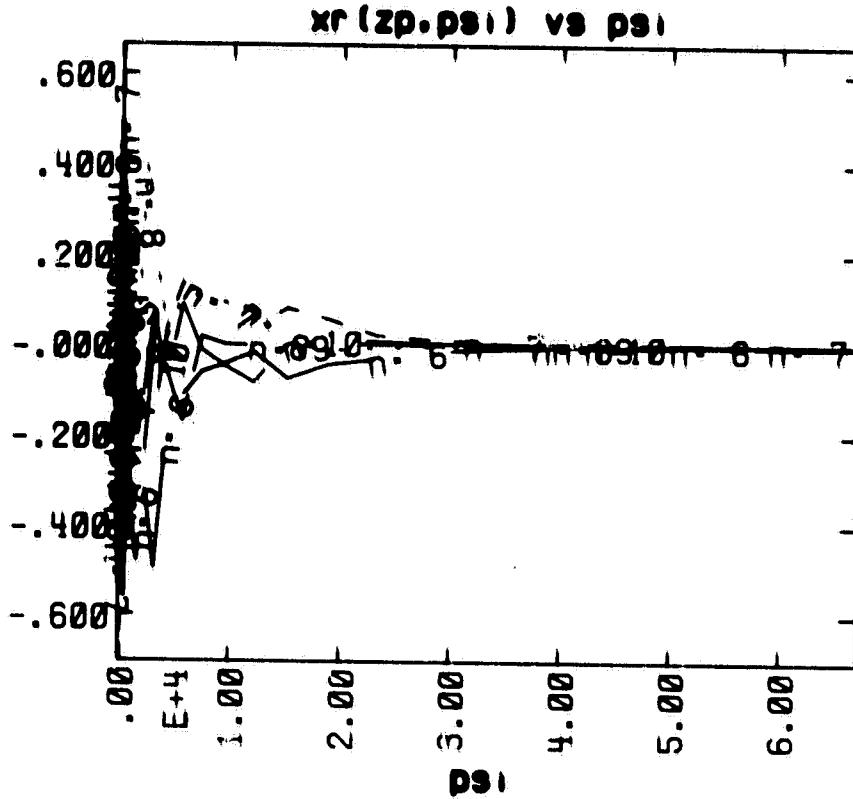




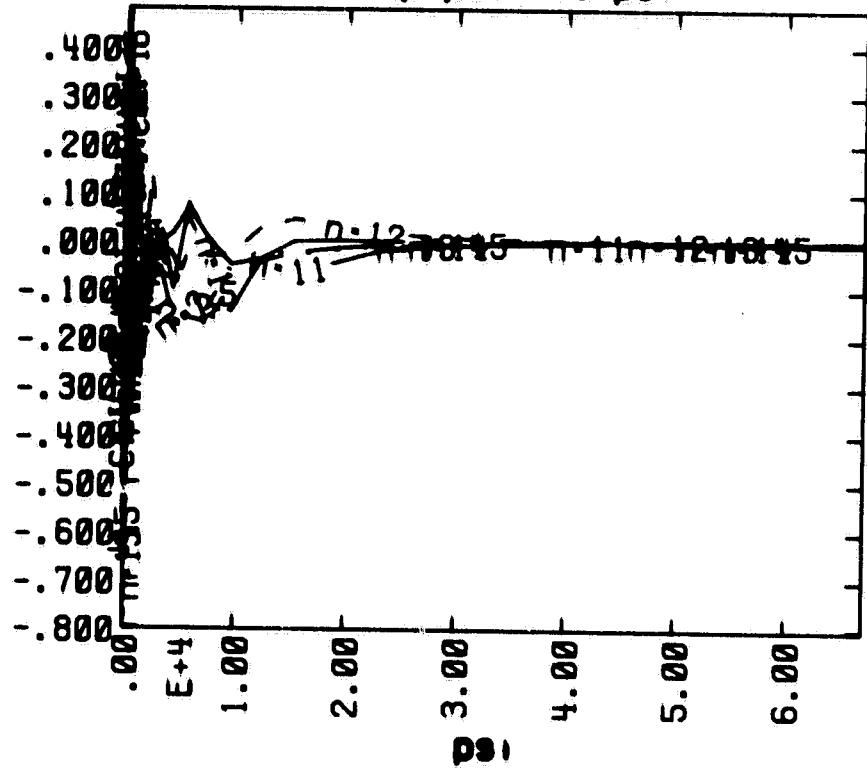
$xr(zp,ps1)$



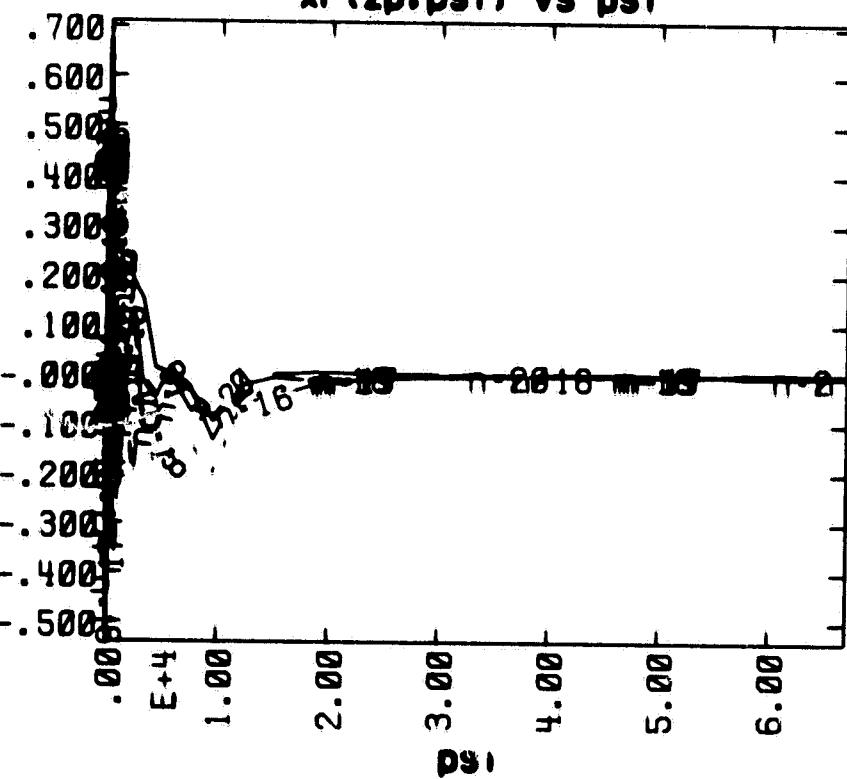
$xr(zp,ps1)$



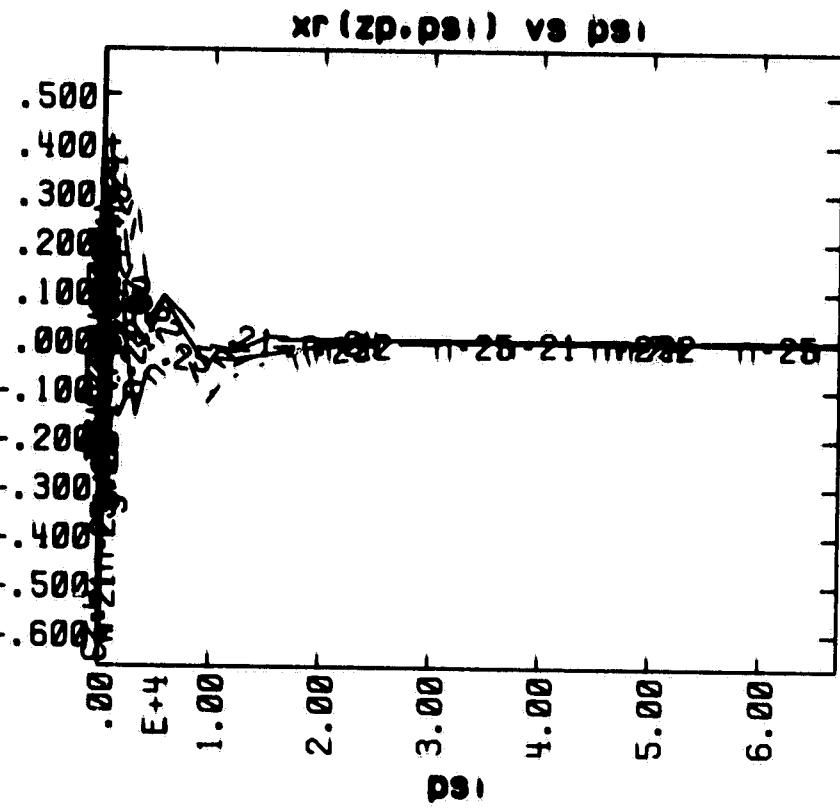
$xr(zp,ps1)$ vs $ps1$



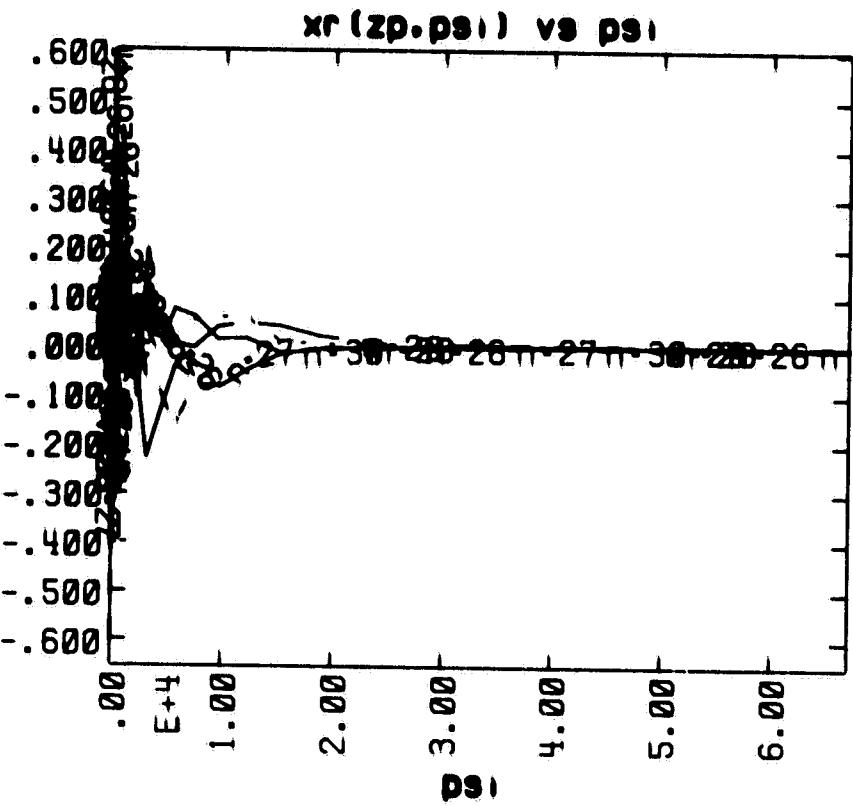
$xr(zp,ps1)$



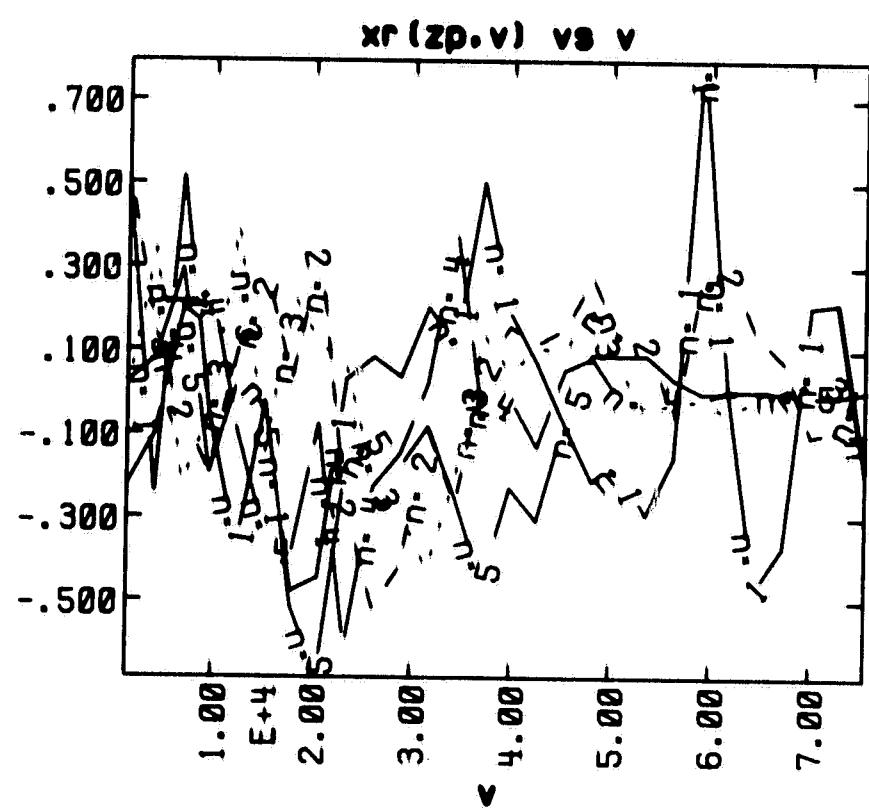
$xr(zp.ps)$



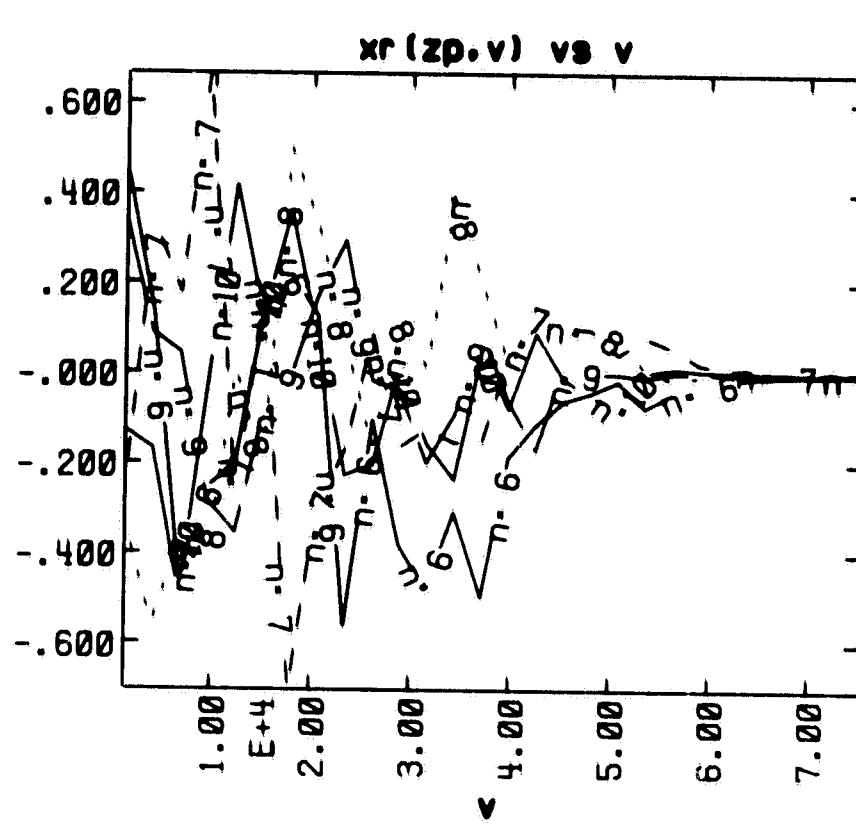
$xr(zp.ps)$



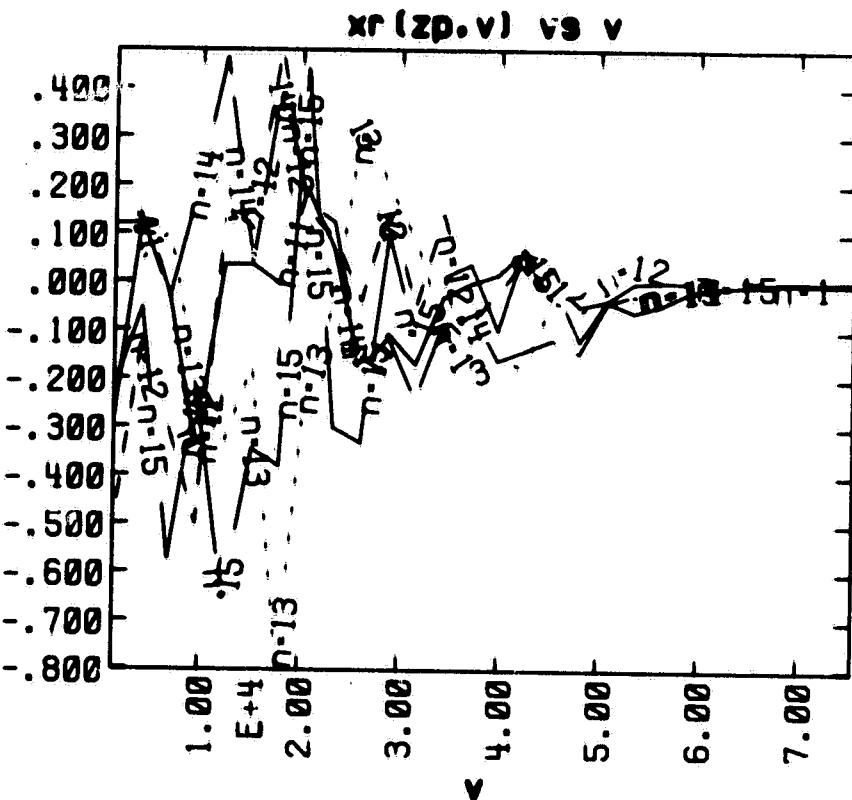
XR (ZP,V)



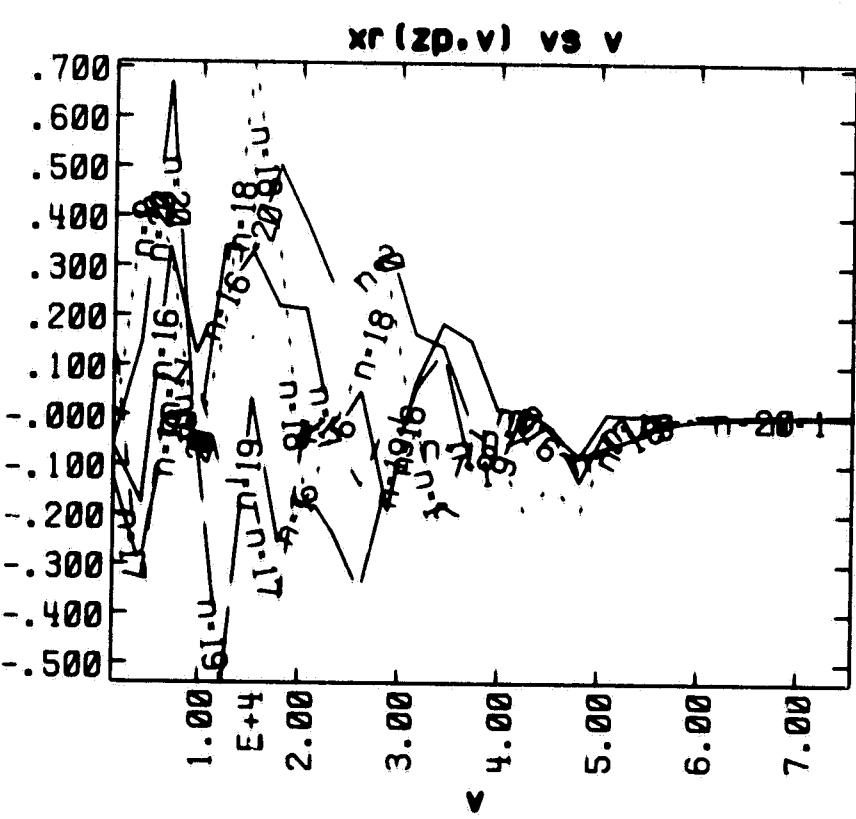
XR (ZP,V)

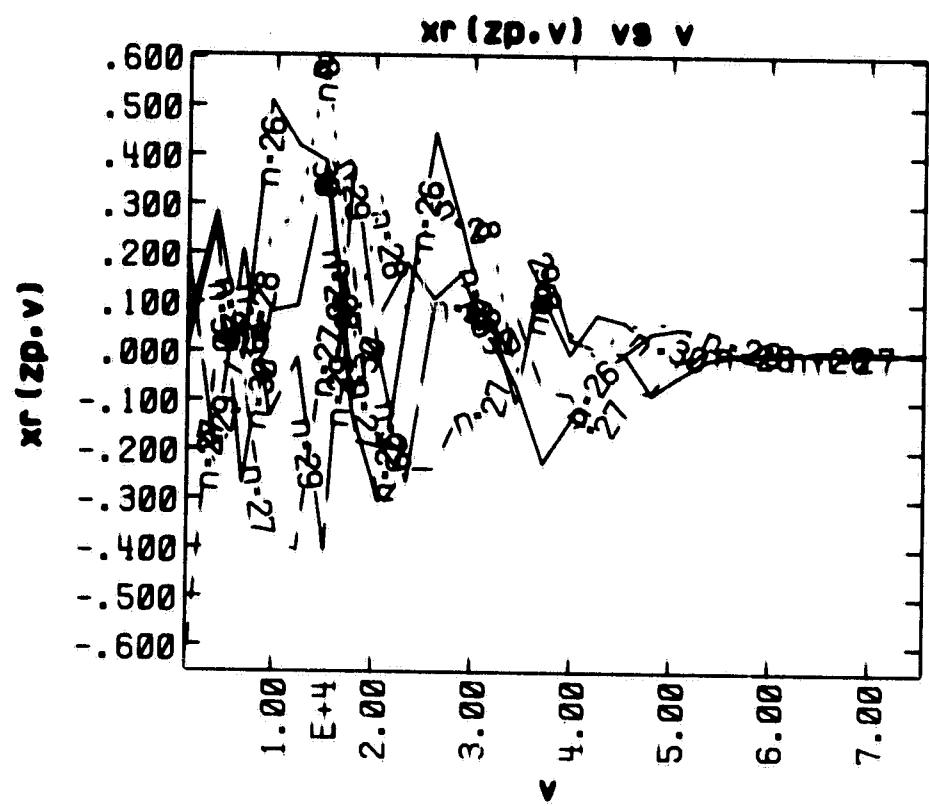
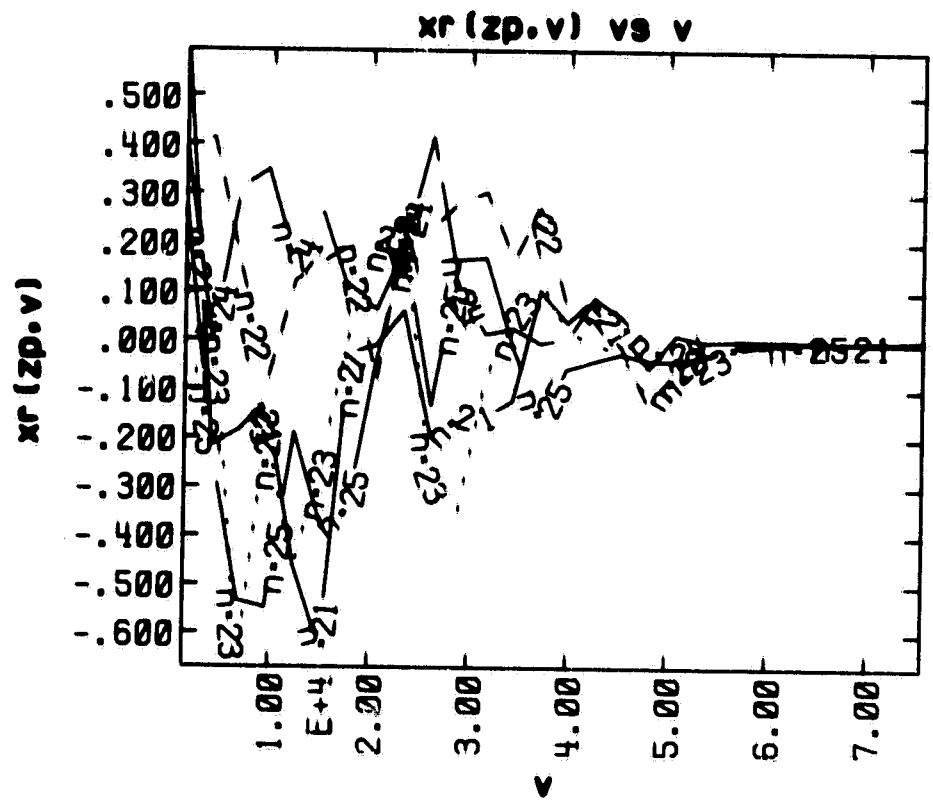


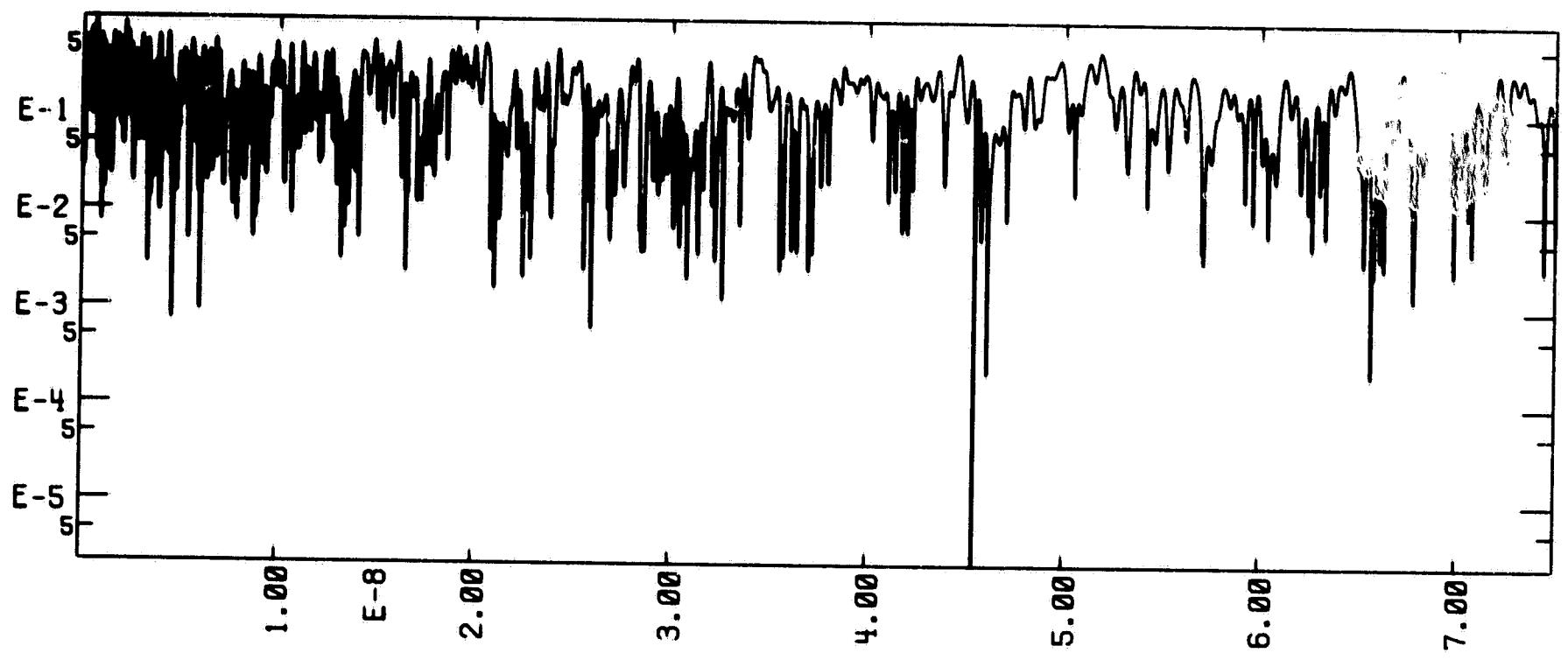
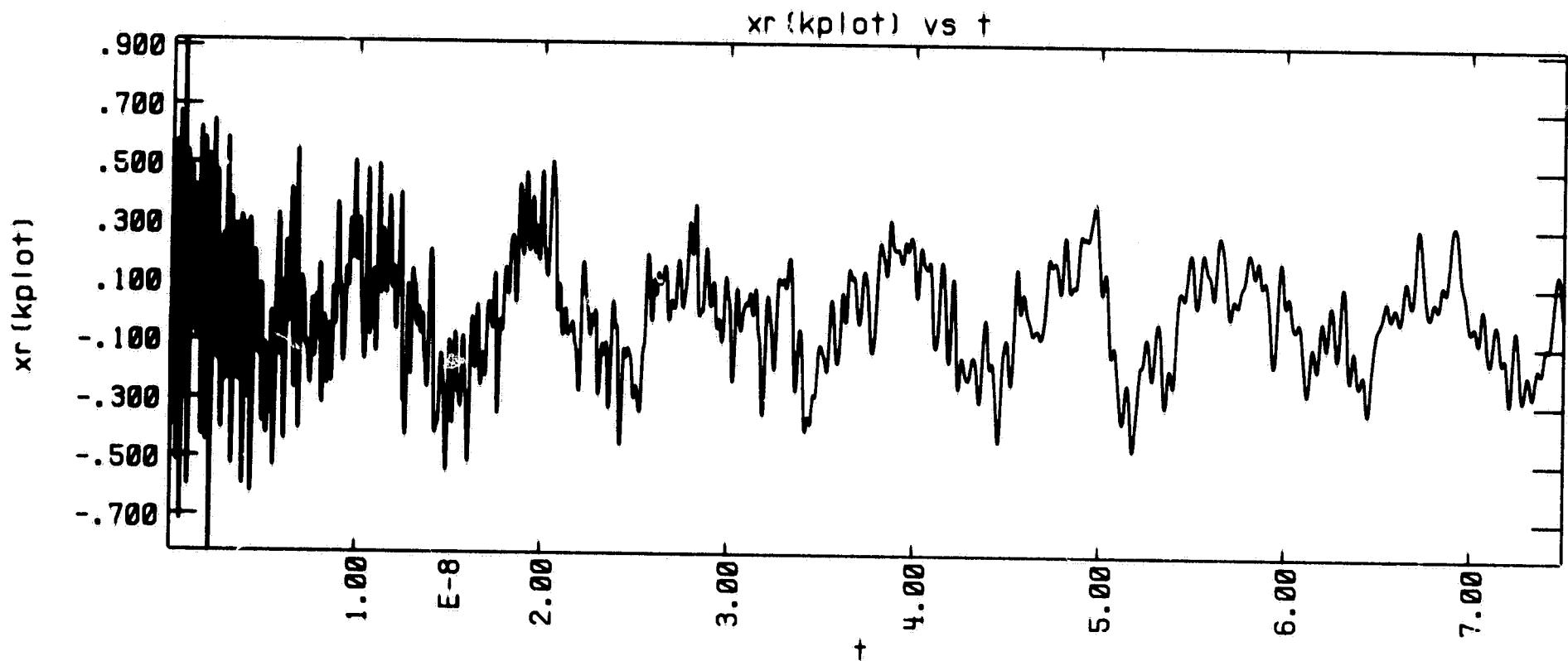
XR (ZP,V)



XR (ZP,V)







b o x u21\$

g r a f l i b : g c s 0 2 0 4 2 k c s 0 2 0 4 2
1 1 f r a m e s

1 0 : 4 2 : 0 3 0 8 / 0 6 / 8 2 c