```
box u21$

graflib:gcs02042kcs02042

10:42:0308/06/82 c
```

```
box u21$

graflib:gcs02042kcs02042

10:42:0308/06/82 c
```

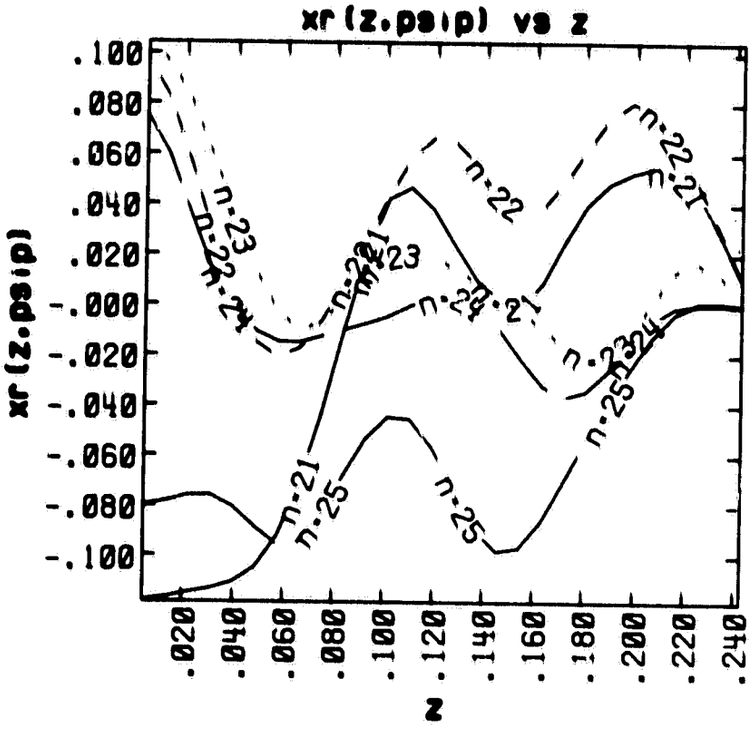
```
dt=     3.125000e-11
ix=       30
jx=       30
total time steps =     2400
no. of iterations =        4
bias=   0.01000
ratrod=     1.000000e+00
drift freq. (omegst) =  6.14023730e+08
rotation freq. (omegr) =  6.14023730e+08
e x b freq. (omegexb) =  1.22804746e+09
flr=  1.00000000e+00
sf6=  1.00000000e+00
sf8=  1.00000000e+00
enbar=  0.
kplot=      349
kzs=        1
valfk =  1.60000000e+00
     cpu time =  8.53679060e+13
     i-o time =  1.74072300e+12
     sys time =  9.59128200e+12
```

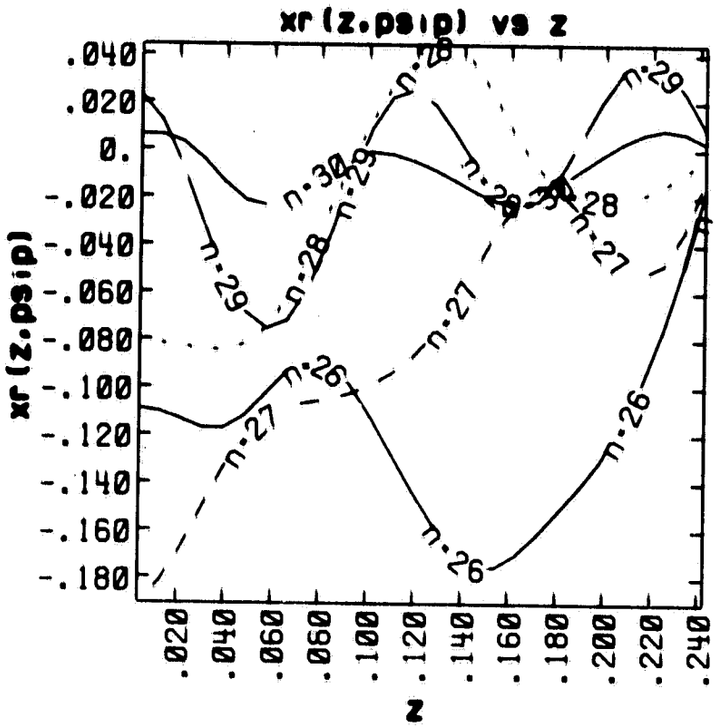
xr(z,psip) vs z
xr(z,psip)
z
.600
.500
.400
.300
.200
.100
-.000
-.100
-.200
-.300
-.400
-.500
.020
.040
.060
.080
.100
.120
.140
.160
.180
.200
.220
.240

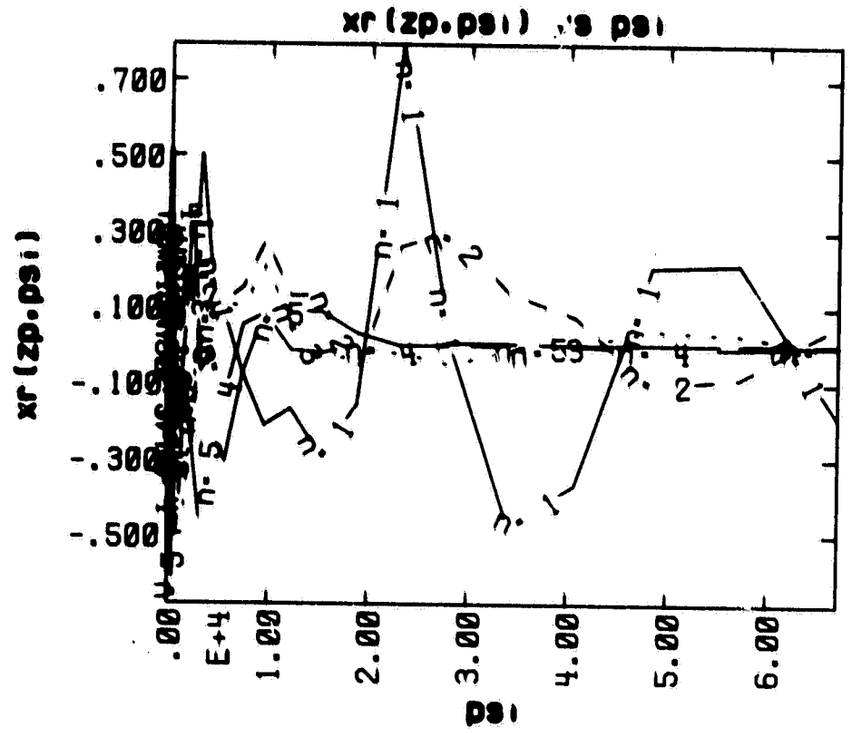
xr(z,psip) vs z
xr(z,psip)
z
.200
.150
.100
.050
-.000
-.050
-.100
-.150
-.200
.020
.040
.060
.080
.100
.120
.140
.160
.180
.200
.220
.240

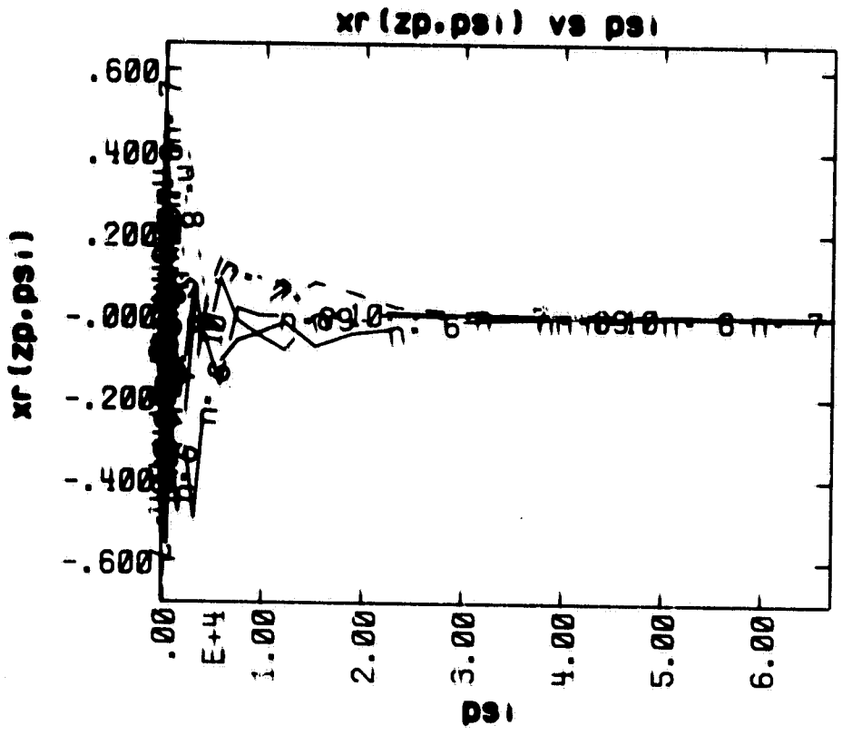
xr(z,psip) vs z
xr(z,psip)
z
.050
-.000
-.050
-.100
-.150
-.200
-.250
.020
.040
.060
.080
.100
.120
.140
.160
.180
.200
.220
.240

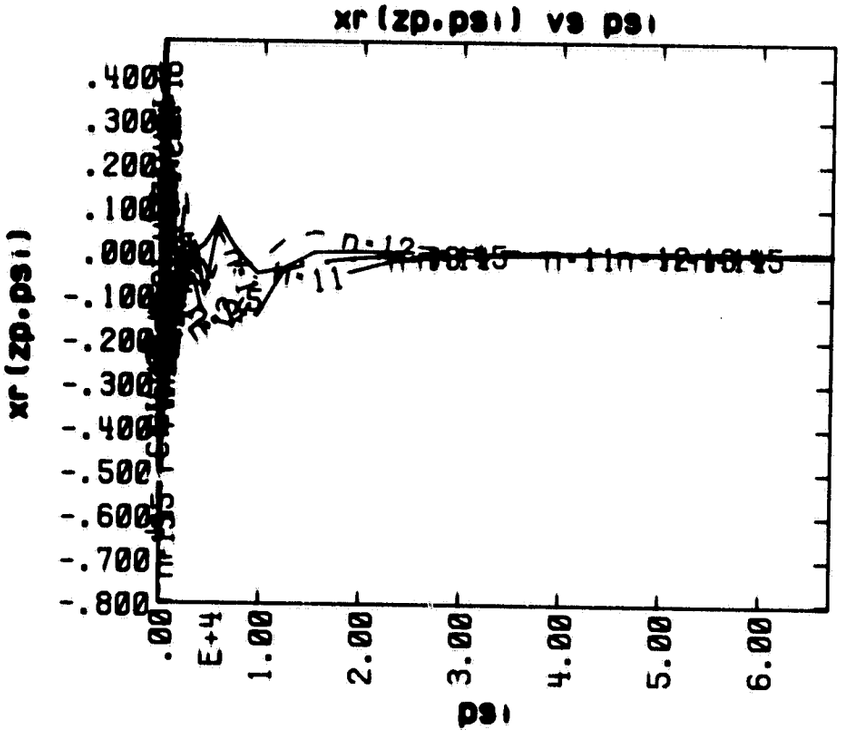
xr(z,psip) vs z
xr(z,psip)
z
.100
.050
0.
-.050
-.100
-.150
.020
.040
.060
.080
.100
.120
.140
.160
.180
.200
.220
.240

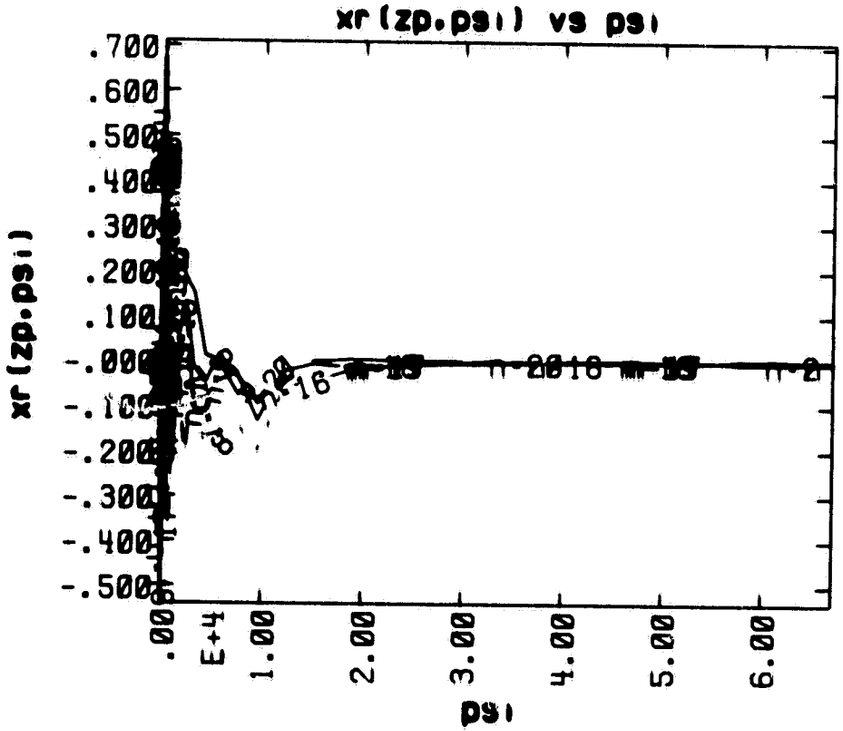

xr(z,psip) vs z
xr(z,psip)
z
.100
.080
.060
.040
.020
-.000
-.020
-.040
-.060
-.080
-.100
.020
.040
.060
.080
.100
.120
.140
.160
.180
.200
.220
.240
n=.23
n=.22
n=.21
n=.25
n=.24

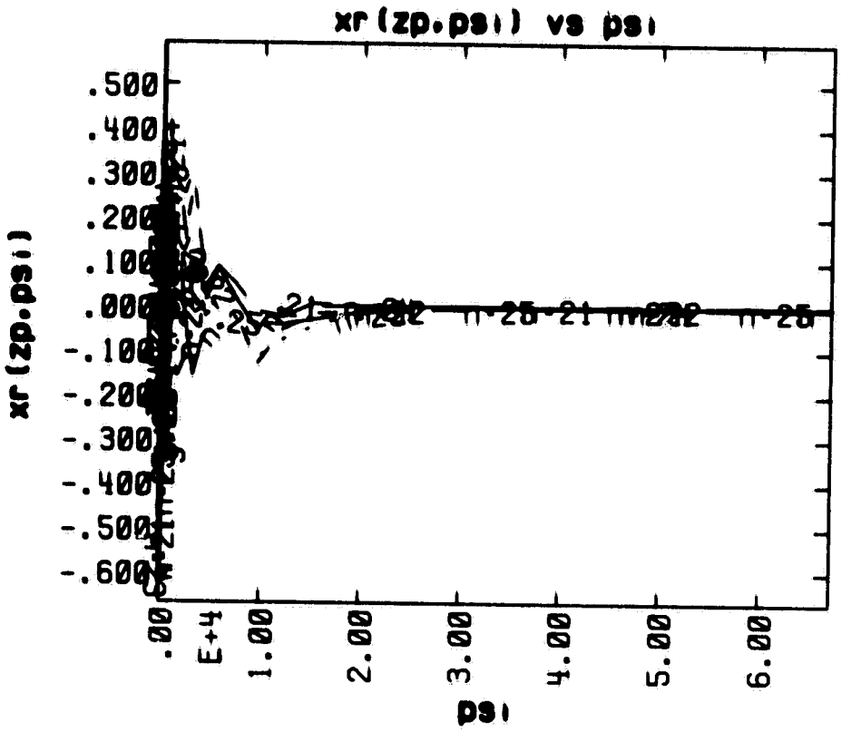

xr(z,psip) vs z
xr(z,psip)
z
.040
.020
0.
-.020
-.040
-.060
-.080
-.100
-.120
-.140
-.160
-.180
.020
.040
.060
.060
.100
.120
.140
.160
.180
.200
.220
.240
n=.30
n=.29
n=.28
n=.27
n=.26

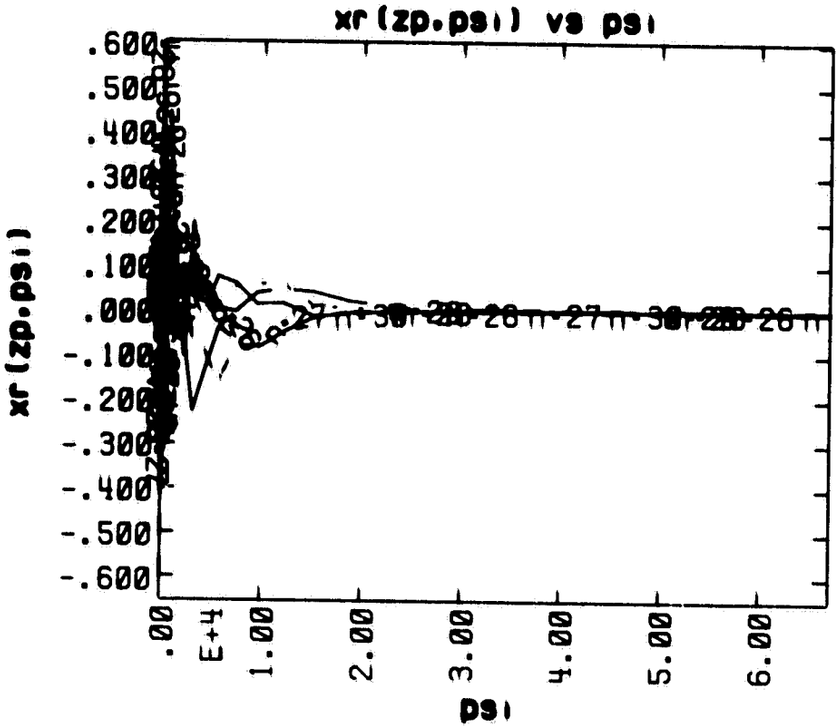

xr(zp.psi) vs psi
xr(zp.psi)
.700
.500
.300
.100
-.100
-.300
-.500
.00
E+4
1.00
2.00
3.00
4.00
5.00
6.00
psi

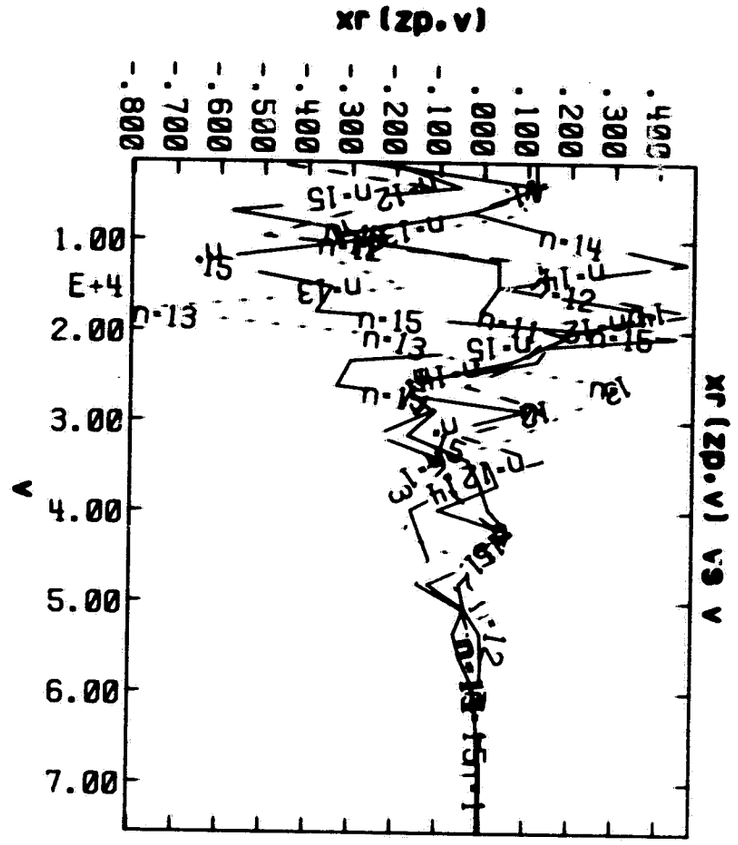

xr(zp.psi) vs psi
xr(zp.psi)
.600
.400
.200
-.000
-.200
-.400
-.600
.00
E+4
1.00
2.00
3.00
4.00
5.00
6.00
psi

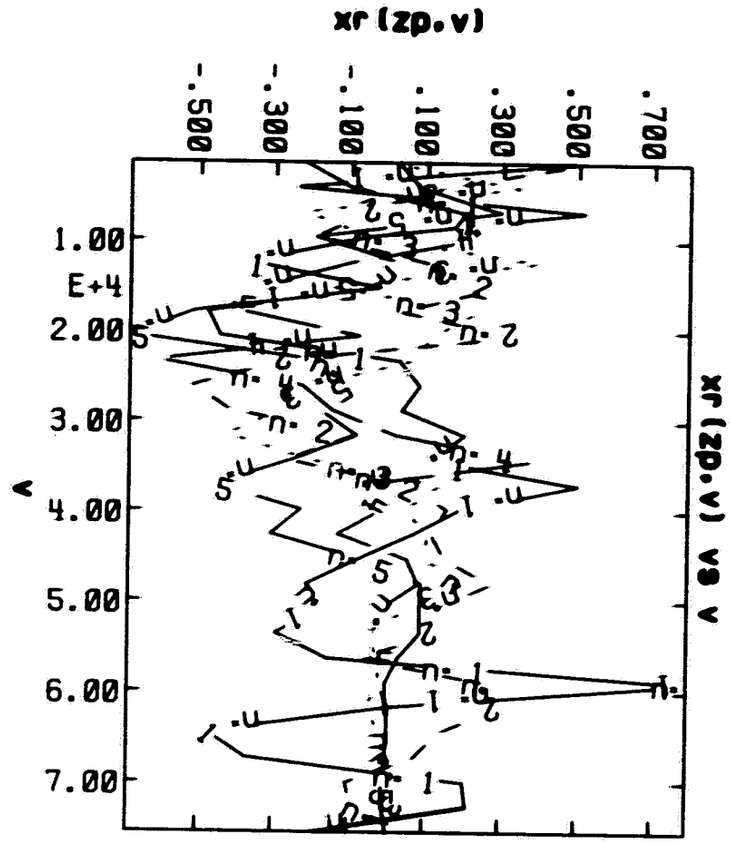

xr(zp.psi) vs psi
xr(zp.psi)
.400
.300
.200
.100
.000
-.100
-.200
-.300
-.400
-.500
-.600
-.700
-.800
.00
E+4
1.00
2.00
3.00
4.00
5.00
6.00
psi

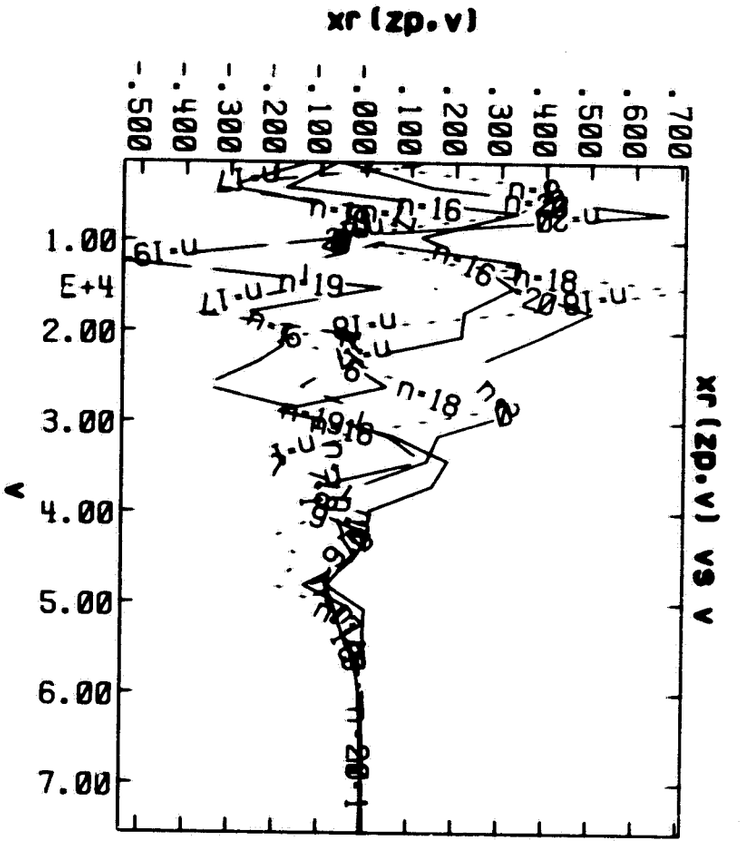

xr(zp.psi) vs psi
xr(zp.psi)
.700
.600
.500
.400
.300
.200
.100
-.000
-.100
-.200
-.300
-.400
-.500
.00
E+4
1.00
2.00
3.00
4.00
5.00
6.00
psi

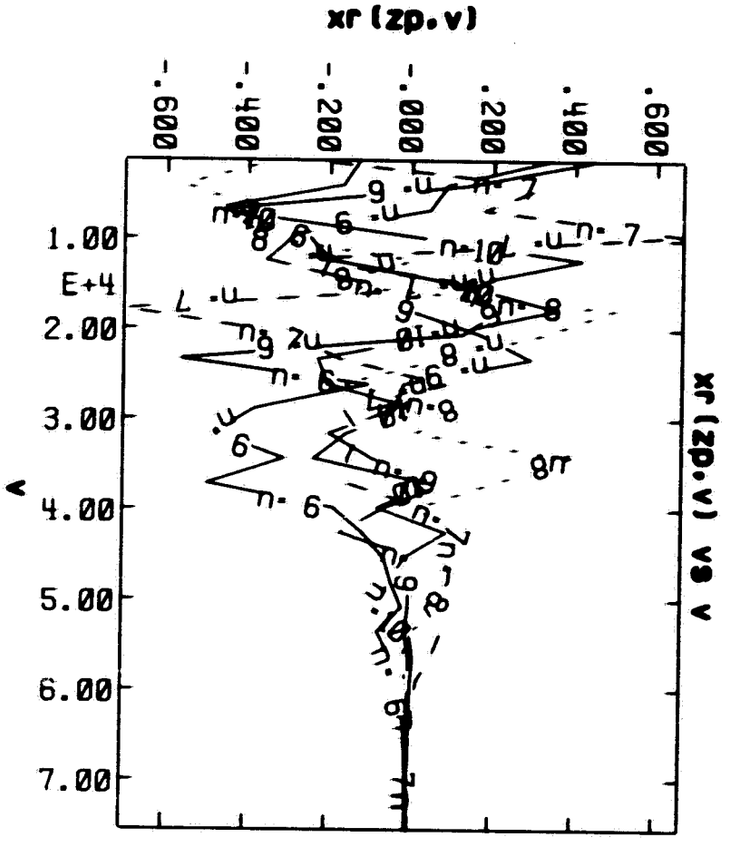

xr(zp.psi) vs psi
xr(zp.psi)
.500
.400
.300
.200
.100
.000
-.100
-.200
-.300
-.400
-.500
-.600
.00
E+4
1.00
2.00
3.00
4.00
5.00
6.00
psi

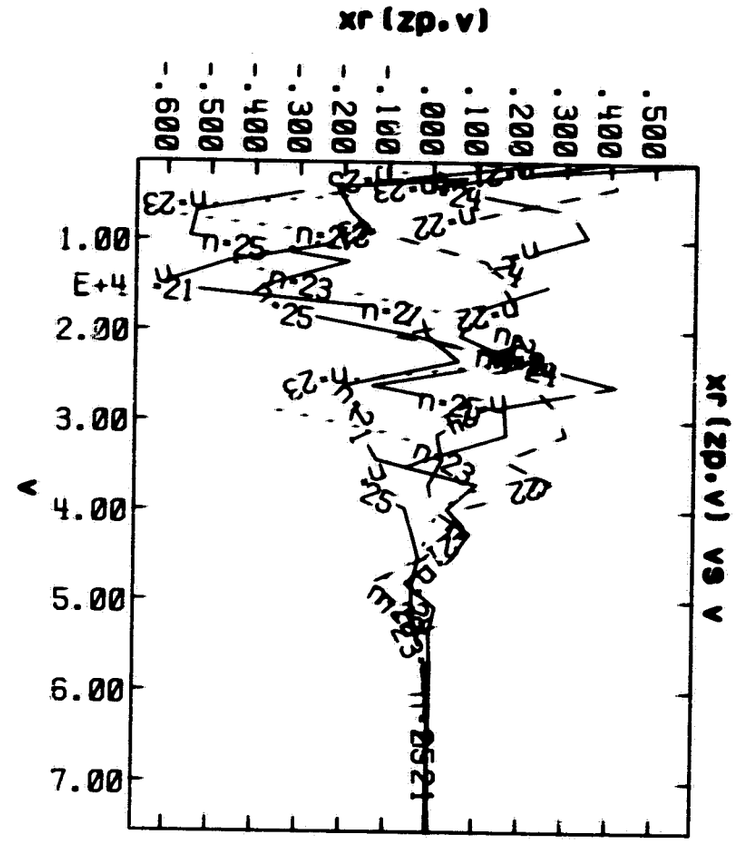

xr(zp.psi) vs psi
xr(zp.psi)
.600
.500
.400
.300
.200
.100
.000
-.100
-.200
-.300
-.400
-.500
-.600
.00
E+4
1.00
2.00
3.00
4.00
5.00
6.00
psi

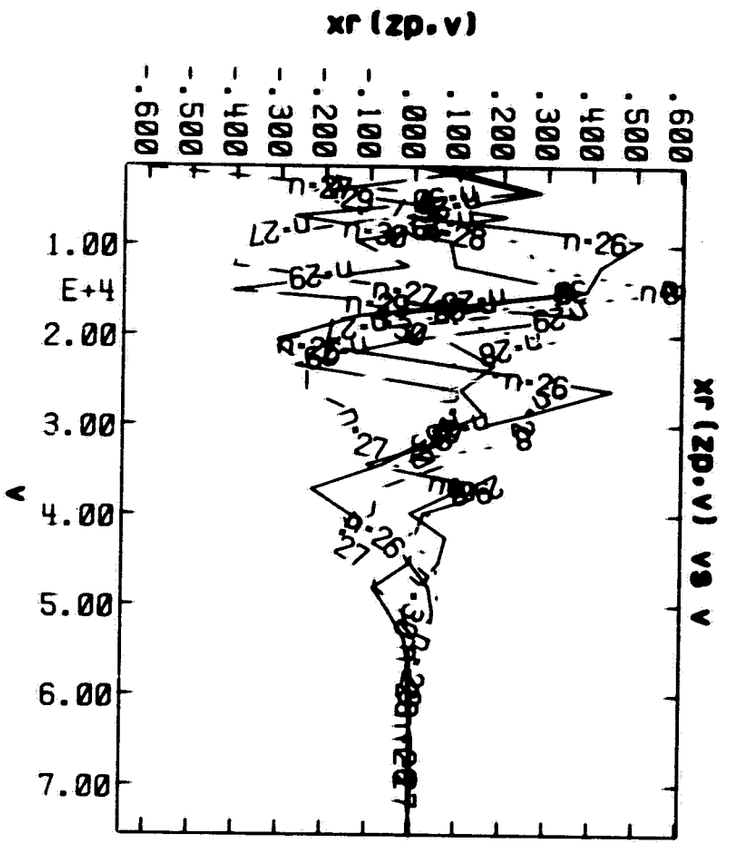

xr (zp.v)
1.00
E+4
2.00
3.00
4.00
5.00
6.00
7.00
A
xr (zp.v) VS A

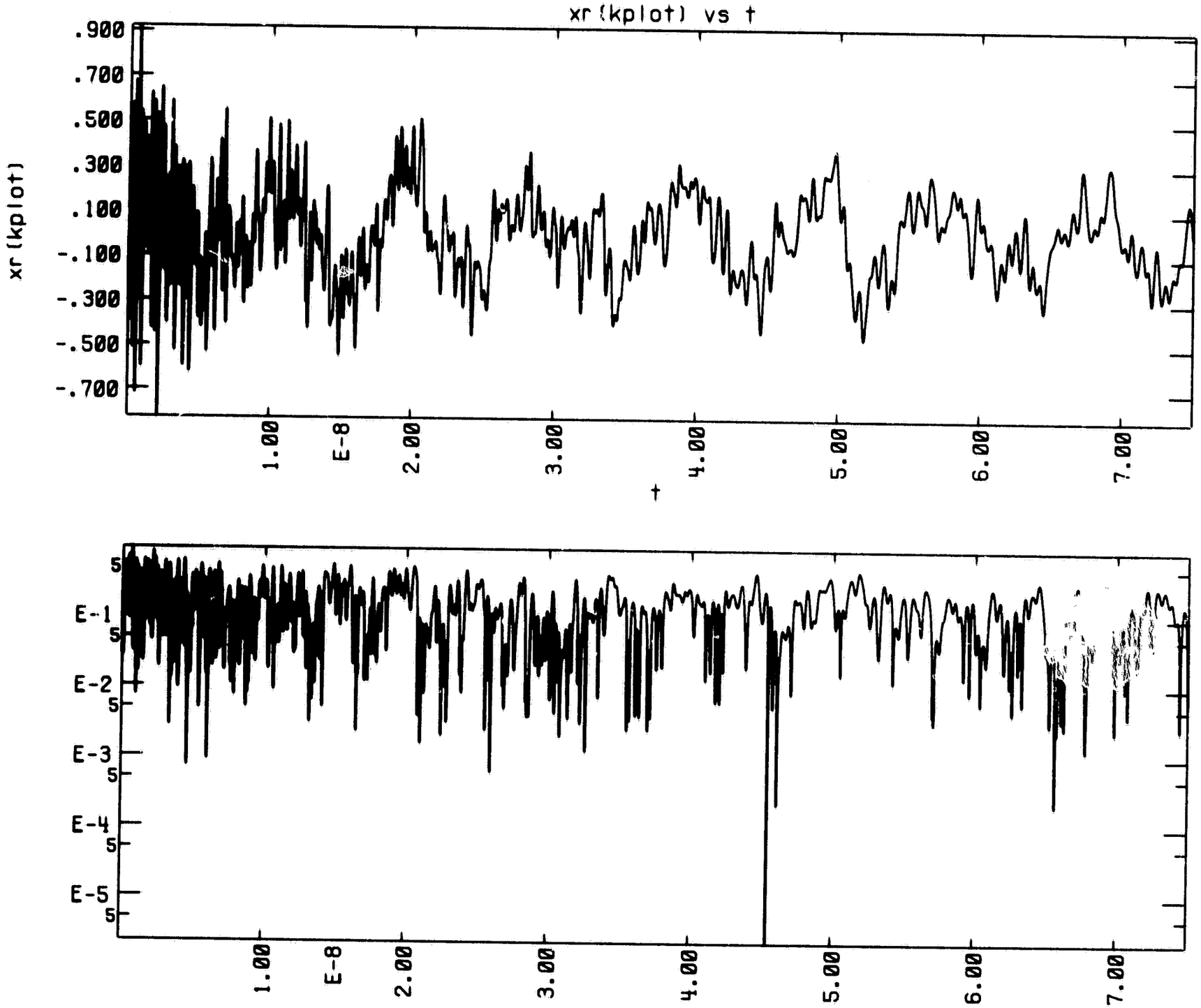

xr (zp.v)
1.00
E+4
2.00
3.00
4.00
5.00
6.00
7.00
A
xr (zp.v) VS A


xr (zp.v)
1.00
E+4
2.00
3.00
4.00
5.00
6.00
7.00
A
xr (zp.v) VS A


xr (zp.v)
1.00
E+4
2.00
3.00
4.00
5.00
6.00
7.00
A
xr (zp.v) VS A


xr(zp,v)
-.600
-.500
-.400
-.300
-.200
-.100
.000
.100
.200
.300
.400
.500
1.00
E+4
2.00
3.00
4.00
5.00
6.00
7.00
v
xr(zp,v) vs v


xr(zp,v)
-.600
-.500
-.400
-.300
-.200
-.100
.000
.100
.200
.300
.400
.500
.600
1.00
E+4
2.00
3.00
4.00
5.00
6.00
7.00
v
xr(zp,v) vs v


xr(kplot) vs t
xr(kplot)
.900
.700
.500
.300
.100
-.100
-.300
-.500
-.700
1.00
E-8
2.00
3.00
4.00
5.00
6.00
7.00
t
5
E-1
5
E-2
5
E-3
5
E-4
5
E-5
5
1.00
E-8
2.00
3.00
4.00
5.00
6.00
7.00

box u21$

graflib:gcs02042kcs02042
11 frames

10:42:0308/06/82 c