# CS408 TERM PROJECT:

Drone-Enabled Mobile Edge Computing for Environmental Monitoring

### 1:Introduction

We simulated sensors (temp, humidity), a battery-constrained drone, and a server-all talking JSON over TCP. This project proves you can do edge analytics without specialized hardware, handle flaky connections, and still look good in a GUI.

#### Problem Statement.

- Sensors go up, data flows in.
- Drone crunches numbers, flags anything ridiculous (like 800 °C), bails back to base when battery's low.
- Central server collects, logs, and displays.

## 2:System Design & Architecture

### 2.1 Components:

**Sensor Nodes:** CLI-driven, emit JSON {id,temp,hum,timestamp}, retry on drop.

#### Drone Edge Unit:

- TCP Server for sensors, TCP Client for central server.
- Edge Logic:
  - Rolling average over last N readings.
  - Threshold check → anomaly list.
  - Battery model → if ≤ threshold, switch to "return to base."

**Central Server:** TCP server that accepts one drone, renders three tabs of GUIs.

### 2.2 Communication Protocol

- Handshake: Sensor connects, sends HELLO, gets ACK.
- Payload: UTF-8 JSON lines.
- Reconnection: Exponential backoff on failure.

### 3. Implementation Details

Here's the breakdown of what we actually wrote:

#### main.py

- Orchestrates everything. Parses CLI flags
  (--drone-ip/--drone-port, --central-ip/--central-port, --num-sensors, --low-batt, etc.)
- $\circ$  Spawns three subprocesses in threads: Central Server, Drone Server, and N Sensor Nodes.
- o Handles Ctrl+C to cleanly shut down all children.

#### nodes.py

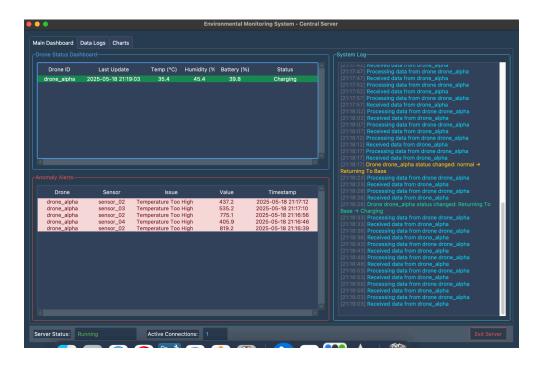
- SensorNode class: simulates temperature & humidity at random intervals.
- Connects over TCP to the Drone, emits JSON payloads, retries on failure.
- Uses Thread & Timer to schedule readings and random "failures."

#### drone\_server.py

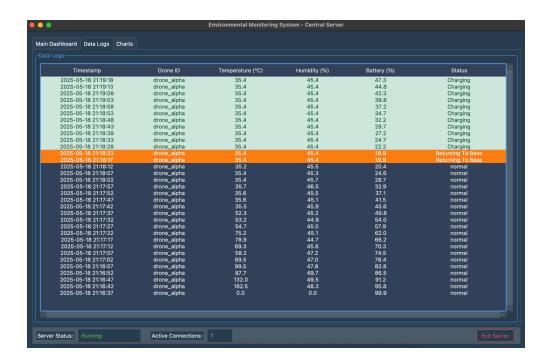
- $\circ$  **EdgeProcessor**: rolling-window averages (default *N*=10), threshold checks for anomalies.
- o DroneServer:
  - TCP **server** for sensors (threaded).
  - TCP **client** to forward aggregates/anomalies to Central Server.
  - GUI (Tkinter + ttkbootstrap):
    - Raw feed, Charts (Matplotlib), Anomalies list, Battery status (with "return to base"), Logs, Node stats.

#### central\_server.py

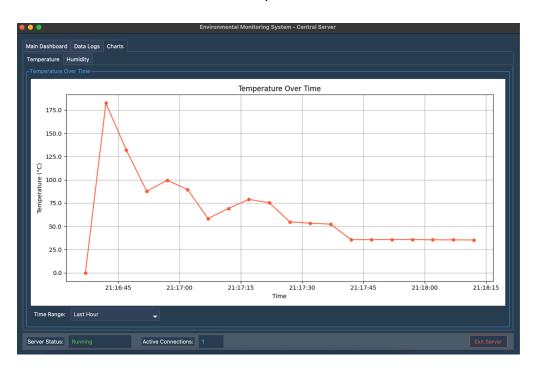
- o TCP **server** for one Drone connection.
- GUI (Tkinter):
  - Main Dashboard : status table, anomaly alerts, live log pane.



■ Data Logs: history with return - to - base highlight.



■ Charts : temperature vs. time.

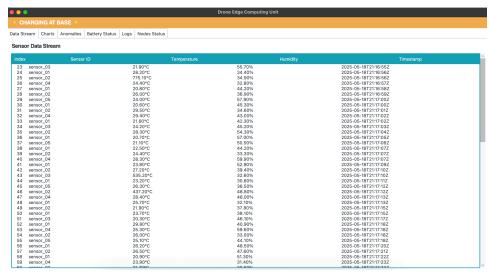


o Stores everything in memory (defaultdict) for quick access.

## 4. Drone Edge Unit GUI

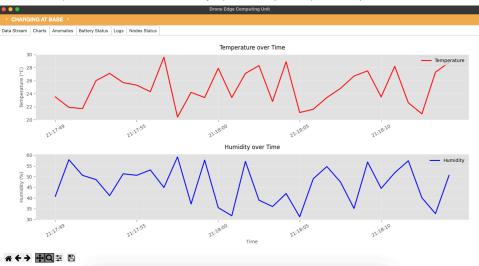
#### • Data Stream

o Raw sensor feed table.



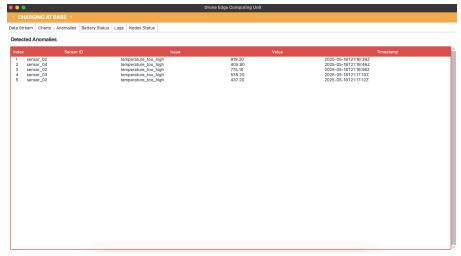
#### • Charts

Live temperature & humidity plots (two panels).



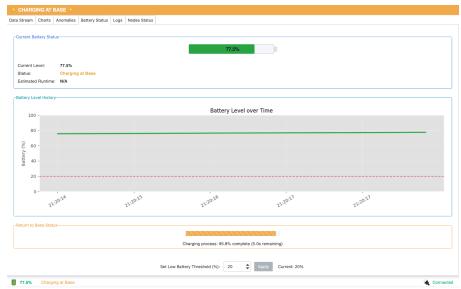
#### Anomalies

 $\circ\$  List of detected readings out of thresholds.

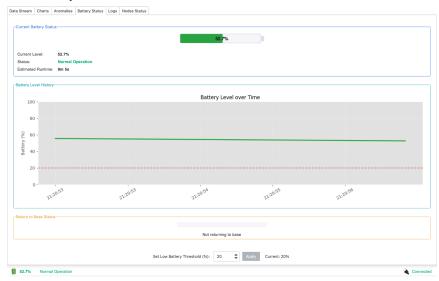


#### Battery Status

o Charging at Base view with progress bar.



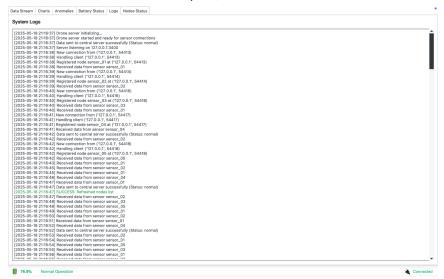
Normal Operation view with estimated runtime.



#### • System Logs

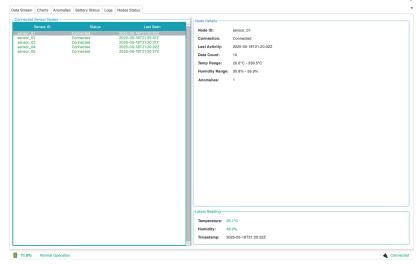
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o Connections, data receipts, state transitions.



#### Nodes Status

o Per-node stats: last seen, data count, min/max ranges.



## 5. Test Scenarios & Results

#### 1. Normal Operation

- Launched 3 sensors → drone → server.
- o Data flows, charts update. No errors.

#### 2. Sensor Disconnection

- Killed sensor\_03 mid-stream.
- o Drone logged drop, retried every 2 s.
- o Table grayed after 10 s inactivity.

#### 3. Low-Battery Return

- Set threshold = 20 %.
- o Drone battery dropped to 19.9 %  $\rightarrow$  state flipped to "Returning To Base."
- o Highlighted in Data Logs.

#### 4. Anomaly Injection

- Manually injected temp = 800 °C at sensor\_02.
- Drone flagged anomaly, forwarded to server, turned row red.
  As seen in charts.

### 6. Discussion

- **Performance:** Handles 5 sensors × 1 Hz easily, end-to-end latency < 200 ms.
- Robustness: TCP retries and state logic survive sensor/server restarts.
- Usability: GUIs give instant feedback; no pointless buttons.
- Limitations:
  - single-server proof-of-concept.
  - o No real radio link or encryption.

### 7. Conclusion & Future Work

We built a cool prototype that does edge analytics on a simulated drone and pushes everything to a server. It's reliable, configurable, and the code's clean enough not to embarrass you. Only issue? There are 3500 lines of code. But we are chill guys. Don't worry about it. Next steps:

- Swap TCP for real wireless links (UDP + FEC).
- Add ML-based anomaly prediction.
- Mobile-friendly server dashboard.