```
Nodelist = Import["Desktop/ChnlNodes.Dat"];
Elementlist = Import["Desktop/ChnlElems.Dat"];
nodes = {};
elements = {};
elementpointer = {};
elementlines = {};
K = ConstantArray[0, {Length[Nodelist], Length[Nodelist]}];
For[i = 1, i ≤ Length[Nodelist], i++,
  AppendTo[nodes, {Nodelist[[i]][[2]], Nodelist[[i]][[3]]}
   ];
 ];
For[p = 1, p ≤ Length[Elementlist], p++,
  AppendTo[elementpointer,
     Elementlist[[p]][[2]],
     Elementlist[[p]][[3]],
     Elementlist[[p]][[4]],
     Elementlist[[p]][[5]]
    }
   ];
 ];
For[h = 1, h ≤ Length[Elementlist], h++,
  AppendTo[elementlines,
   Line[
     nodes[[Elementlist[[h]][[2]]]],
     nodes[[Elementlist[[h]][[3]]]],
     nodes[[Elementlist[[h]][[4]]]],
     nodes[[Elementlist[[h]][[5]]]],
     nodes[[Elementlist[[h]][[2]]]]
    }
   ]]];
For [k = 1, k \le Length[Elementlist], k++,
  AppendTo[elements,
   {
    nodes[[elementpointer[[k]][[1]]]],
    nodes[[elementpointer[[k]][[2]]]],
    nodes[[elementpointer[[k]][[3]]]],
    nodes[[elementpointer[[k]][[4]]]]
   }
  ]
 ];
```

```
N_1[\alpha_-, \beta_-, \gamma_-, \delta_-, x_-, y_-] := \frac{(\gamma - x)}{(\gamma - \alpha)} * \frac{(\delta - y)}{(\delta - \beta)};
N_2[\alpha_{-}, \beta_{-}, \gamma_{-}, \delta_{-}, x_{-}, y_{-}] := \frac{(x-\alpha)}{(y-\alpha)} * \frac{(\delta-y)}{(\delta-\beta)};

N_{3}[\alpha_{-}, \beta_{-}, \gamma_{-}, \delta_{-}, x_{-}, y_{-}] := \frac{(x-\alpha)}{(x-\alpha)} * \frac{(y-\beta)}{(\delta-\beta)}; 

N_{4}[\alpha_{-}, \beta_{-}, \gamma_{-}, \delta_{-}, x_{-}, y_{-}] := \frac{(\gamma-x)}{(\gamma-\alpha)} * \frac{(y-\beta)}{(\delta-\beta)};

Polyfuction = \{N_1, N_2, N_3, N_4\};
For [m = 1, m ≤ Length [elements], m++,
    For [n = 1, n ≤ Length [Polyfuction], n++,
       For[o = 1, o ≤ Length[Polyfuction], o++,
           elementcounter = elementpointer[[m]];
           columns = elementcounter[[0]];
           rows = elementcounter[[n]];
           \alpha = nodes[[elementcounter[[1]]]][[1]];
           \beta = nodes[[elementcounter[[1]]]][[2]];
           γ = nodes[[elementcounter[[3]]]][[1]];
           \delta = \text{nodes}[[elementcounter}[[3]]]][[2]];
           g_n = Grad[N_n[\alpha, \beta, \gamma, \delta, x, y], \{x, y\}];
           g_o = Grad[N_o[\alpha, \beta, \gamma, \delta, x, y], \{x, y\}];
           K[[rows, columns]] =
            K[[rows, columns]] + NIntegrate[Dot[g_0, g_n], \{x, \alpha, \gamma\}, \{y, \beta, \delta\}];
         ];
     ];
  ];
R = ConstantArray[0, Length[Nodelist]];
For [t = 1, t \le 9, t++,
  elementcounter = elementpointer[[t]];
  \alpha = nodes[[elementcounter[[1]]]][[1]];
  \beta = nodes[[elementcounter[[1]]]][[2]];
  γ = nodes[[elementcounter[[3]]]][[1]];
  \delta = \text{nodes}[[elementcounter}[[3]]]][[2]];
  R[[elementcounter[[1]]]] =
    R[[elementcounter[[1]]]] + NIntegrate[-N_1[\alpha, \beta, \gamma, \delta, \alpha, y], \{y, \beta, \delta\}];
  R[[elementcounter[[4]]]] = R[[elementcounter[[4]]]] +
     NIntegrate [-N_4[\alpha, \beta, \gamma, \delta, \alpha, y], \{y, \beta, \delta\}];
]
```

```
For[u = Length[elements] - 8, u ≤ Length[elements], u++,
  elementcounter = elementpointer[[u]];
  \alpha = nodes[[elementcounter[[1]]]][[1]];
  \beta = \text{nodes}[[elementcounter}[[1]]][[2]];
  γ = nodes[[elementcounter[[3]]]][[1]];
  \delta = \text{nodes}[[elementcounter}[[3]]]][[2]];
  R[[elementcounter[[2]]]] =
    R[[elementcounter[[2]]]] + NIntegrate[N_2[\alpha, \beta, \gamma, \delta, \gamma, y], {y, \beta, \delta}];
  R[[elementcounter[[3]]]] = R[[elementcounter[[3]]]] +
     NIntegrate [N_3[\alpha, \beta, \gamma, \delta, \gamma, y], {y, \beta, \delta}];
 ];
bound = ConstantArray[0, Length[R]];
bound[[61]] = 1;
K[[61]] = bound;
R[[61]] = 0;
alpha = LinearSolve[K, R];
arrows = ConstantArray[0, Length[elements]];
half = 0.5;
For v = 1, v \le Length[elements], v + +,
  elementcounter = elementpointer[[v]];
  \alpha = nodes[[elementcounter[[1]]]][[1]];
  \beta = nodes[[elementcounter[[1]]]][[2]];
  γ = nodes[[elementcounter[[3]]]][[1]];
  \delta = nodes[[elementcounter[[3]]]][[2]];
  centerx = (\alpha + \gamma) / 2;
  centery = (\beta + \delta) / 2;
  potential[x_, y_] := alpha[[elementcounter[[1]]]] * N_1[\alpha, \beta, \gamma, \delta, x, y] +
     alpha[[elementcounter[[2]]]] * N_2[\alpha, \beta, \gamma, \delta, x, y] + alpha[[elementcounter[[3]]]] *
      N_3[\alpha, \beta, \gamma, \delta, x, y] + alpha[[elementcounter[[4]]]] * <math>N_4[\alpha, \beta, \gamma, \delta, x, y];
  gradflow = Grad[potential[x, y], \{x, y\}] /. \{x \rightarrow centerx, y \rightarrow centery\};
  arrows[[v]] = Arrow[{{centerx, centery}, {centerx, centery} + gradflow * half}];
 ];
Show[Graphics[elementlines], ListPlot[nodes, PlotStyle → PointSize[0.005]],
 Graphics[{Arrowheads[0.01], Magenta, Dashed, arrows}]]
```

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