```
Nodes = \{\};
Offst1 = 5.0;
Offst2 = 5.0;
shwNodes = {};
i = 1;
xst = 0;
yst = 0;
While[xst < 100.25,
  While[yst < 50.25,
   Nodes = Append[Nodes, {i, xst, yst}];
   shwNodes = Append[shwNodes, {xst, yst}];
   If [yst < 50, (*50-5*)
    yst = yst + Offst1,
    yst = 51.(*51-6*)
   ];
   i++
  ];
  xst = xst + Offst2;
  yst = 0;
 ];
PtNodes = ListPlot[shwNodes, AspectRatio → Automatic];
Show[PtNodes];
Elem3 = {};
i = 1;
j = 1;
Coln = 10; (*50*)
ColLst = Table[i * 11, {i, 1, 20}]; (*51*)
While [ i \le 400, (*2501*)
 Elem3 = Append[Elem3, \{i, j, j + Coln + 1, j + Coln + 2\}];
 Elem3 = Append[Elem3, \{i+1, j, j+Coln+2, j+1\}];
 j++;
 If[MemberQ[ColLst, j],
  j = j + 1
 ];
 i = i + 2;
];
nodes = {};
For [q = 1, q \le Length[Nodes], q++,
  AppendTo[nodes,
    {
     Nodes [[q]] [[2]],
     Nodes [ [q] ] [ [3] ]
    }
   ];
 ];
elements = {};
```

```
Vandermonde = ConstantArray[1, {Length[RTriangle], Length[RTriangle]}];
For [g = 1, g \le Length[Vandermonde], g++,
  Vandermonde[[g]][[2]] = RTriangle[[g]][[1]];
  Vandermonde[[g]][[3]] = RTriangle[[g]][[2]];
 ];
A = Vandermonde;
B = ConstantArray[0, Length[A]];
F = {};
K = ConstantArray[0, {Length[nodes], Length[nodes]}];
M = ConstantArray[0, {Length[nodes], Length[nodes]}];
For [i = 1, i \le Length[A], i++,
  B[[i]] = 1;
  AppendTo[F, LinearSolve[A, B].{1, x, y}];
  B[[i]] = 0;
 ];
a = \gamma - \alpha;
b = \delta - \beta;
\mathbf{c} = \mu - \alpha;
d = v - \beta;
T = \{\{a, c\}, \{b, d\}\};
{inverse1, inverse2} =
  For [k = 1, k \le Length[elements], k++,
  For [m = 1, m \le Length[F], m++,
     For [n = 1, n \le Length[F], n++,
       elementcounter = elements[[k]];
       columns = elementcounter[[n]];
       rows = elementcounter[[m]];
       \alpha = nodes[[elements[[k]]]][[1]][[1]];
       \beta = \text{nodes}[[elements[[k]]]][[1]][[2]];
       γ = nodes[[elements[[k]]]][[2]][[1]];
       \delta = \text{nodes}[[elements[[k]]]][[2]][[2]];
       \mu = nodes[[elements[[k]]]][[3]][[1]];
       v = nodes[[elements[[k]]]][[3]][[2]];
       F_{m}[x_{y}] = F[[m]];
       F_n[x_y] = F[[n]];
       P<sub>m</sub>[x_, y_] = Simplify[F<sub>m</sub>[inverse1, inverse2]];
       P<sub>n</sub>[x_, y_] = Simplify[F<sub>n</sub>[inverse1, inverse2]];
```

```
G_m = Grad[P_m[x, y], \{x, y\}];
        G_n = Grad[P_n[x, y], \{x, y\}];
        H_m = P_m[x, y];
        H_n = P_n[x, y];
        If [Mod[k, 2] \neq 0,
         K[[rows, columns]] = K[[rows, columns]] +
             Integrate [Dot [G<sub>m</sub>, G<sub>n</sub>], {x, \alpha, \gamma}, {y, \beta, ((\nu - \beta) / (\mu - \alpha)) (x - \alpha) + \beta}];
          M[[rows, columns]] = M[[rows, columns]] + NIntegrate[Times[H<sub>m</sub>, H<sub>n</sub>],
               \{x, \alpha, \gamma\}, \{y, \beta, ((\nu - \beta) / (\mu - \alpha)) (x - \alpha) + \beta\}];
        ];
        If[Mod[k, 2] = 0,
          K[[rows, columns]] = K[[rows, columns]] +
             Integrate[Dot[G_m, G_n], {x, \alpha, \gamma}, {y, ((\delta - \beta) / (\gamma - \alpha)) (x - \alpha) + \beta, \nu}];
         M[[rows, columns]] = M[[rows, columns]] + NIntegrate[Times[H<sub>m</sub>, H<sub>n</sub>],
               \{X, \alpha, \gamma\}, \{y, ((\delta - \beta) / (\gamma - \alpha)) (X - \alpha) + \beta, \gamma\}];
        ];
      ];
   ];
];
```

```
dirichlet = ConstantArray[0, Length[nodes]];
dirichlet[[1]] = 1;
K[[1]] = dirichlet;
M[[1]] = dirichlet;
evectors = Eigenvectors[{K, M}];
rise = ConstantArray[0, Length[elements]];
plots = ConstantArray[0, Length[nodes]];
For [\lambda = 1, \lambda \leq Length[nodes], \lambda++,
  For v = 1, v \le Length[elements], v + +,
    elementcounter = elements[[v]];
    \alpha = nodes[[elements[[v]]]][[1]][[1]];
    \beta = nodes[[elements[[v]]]][[1]][[2]];
    γ = nodes[[elements[[v]]]][[2]][[1]];
    \delta = \text{nodes}[[elements[[v]]]][[2]][[2]];
    \mu = nodes[[elements[[v]]]][[3]][[1]];
    v = nodes[[elements[[v]]]][[3]][[2]];
    centerx = (\alpha + \gamma) / 2;
    centery = (\beta + \gamma)/2;
    rise[[v]] = {centerx, centery, evectors[[\lambda]][[elementcounter[[1]]]] * P_1[x, y] +
         evectors[[\lambda]][[elementcounter[[2]]]] * P<sub>2</sub>[x, y] +
         evectors[[\lambda]][[elementcounter[[3]]]] * P_3[x, y] /. \{x \rightarrow centerx, y \rightarrow centery\}\};
  plots[[\lambda]] = ListPlot3D[rise, PlotRange \rightarrow All];
 ];
timestart = 1;
timefinish = Length[plots];
time = RandomInteger[{timestart, timefinish}];
time1 = RandomInteger[{time, timefinish}];
time2 = RandomInteger[{time1, timefinish}];
Print[plots[[time]], "3D Plot solution for randomly generated \lambda = ", time];
Print[plots[[time1]], "3D Plot solution for randomly generated \lambda = ", time1];
Print[plots[[time2]], "3D Plot solution for randomly generated \lambda = ", time2];
```

