

Phase 4: Vacuum-to-FRW Consistency and Scale Sanity

A corridor-style test of the Phase 3 global-amplitude mechanism

Origin Axiom Program

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Abstract

Phase 4 tests whether the canonical global-amplitude mechanism defined in Phase 3 can be connected, in a structurally reasonable way, to FRW-style dynamics and vacuum-energy-like observables. The goal is to probe whether the non-cancellation floor that stabilises the toy vacuum can also support scale-sane behaviour when mapped into simple cosmological modules, without claiming a full cosmological fit or a theory of everything.

1 Introduction

Phase 4 sits between the mechanism-level vacuum work of Phase 3 and any future attempts to build a unified picture of vacuum, matter, and geometry. Its mission is narrow:

- take the canonical Phase 3 global-amplitude mechanism and non-cancellation floor as given;
- define simple, explicit mappings from the floor-enforced amplitude or residue into FRW-like dynamics and vacuum-energy-like observables; and
- study the resulting behaviour of the Origin-Axiom phase parameter θ in the corridor / ledger framework of Phase 0.

The guiding question is not whether we can reproduce the full Λ CDM model or fit precise cosmological parameters, but whether the Phase 3 mechanism can be made compatible with toy FRW modules in a way that is numerically stable, structurally sane, and expressible as a θ -filter in the sense of Phase 0.

Throughout this phase we distinguish carefully between:

- *binding* outputs, which may eventually define a Phase 4 θ -filter; and
- *non-binding* diagnostics and figures, which serve only as intuition and internal checks.

The present rung does not define any concrete mappings or filters. It only provides a minimal paper skeleton so that future rungs can add well-documented mechanisms and experiments without restructuring the front matter.

2 Mapping families: first pass (**F1**)

Phase 4 takes as input the Phase 3 global-amplitude mechanism: a toy vacuum with an unconstrained observable $A_0(\theta)$, a non-cancellation floor ε , and a floor-enforced amplitude $A(\theta) = \max(A_0(\theta), \varepsilon)$ defined on a grid $\theta \in [0, 2\pi]$. The present paper introduces a first, explicit mapping family, denoted **F1**, from this structure to a toy vacuum-energy-like scalar.

2.1 F1: direct scalar mapping from $A(\theta)$

The F1 family is intentionally simple. For a fixed Phase 3 vacuum configuration and floor ε (taken from the Phase 3 baseline diagnostics), we define a scalar

$$E_{\text{vac}}(\theta) = \alpha A(\theta)^\beta, \quad (1)$$

where $\alpha > 0$ and $\beta > 0$ are explicit, configurable parameters. At this rung we adopt a conservative default, $\alpha = 1$ and $\beta = 2$, and focus on structural behaviour rather than numerical normalisation.

Operationally, Phase 4 reuses the Phase 3 baseline configuration `baseline_v1` and the floor ε recorded in `phase3/outputs/tables/mech_baseline_scan_diagnostics.json`. We then evaluate $A(\theta)$ and $E_{\text{vac}}(\theta)$ on a uniform grid of $N_\theta = 2048$ points in $[0, 2\pi]$. The per-grid values and summary diagnostics are written to

```
phase4/outputs/tables/phase4_F1_sanity_curve.csv,
```

together with metadata describing the mapping parameters and the underlying Phase 3 diagnostics.

At this stage F1 is a *non-binding* mapping family: it does not yet define a θ -corridor or a Phase 4 θ -filter. Instead it serves as a concrete, auditable bridge between the Phase 3 mechanism and simple scalar observables that later rungs can connect to FRW-like toy modules and corridor construction.

3 Diagnostics and toy corridors (draft)

At this rung Phase 4 focuses on internal diagnostics of the scalar $E_{\text{vac}}(\theta) = \alpha A(\theta)^\beta$ produced by the F1 mapping family, together with simple, non-binding θ -corridors. No FRW module is yet implemented; instead we prepare the ground for later FRW-like tests.

3.1 Vacuum-curve sanity check

The first diagnostic is a direct sanity check of the F1 mapping. Using the Phase 3 baseline configuration and floor recorded in `phase3/outputs/tables/mech_baseline_scan_diagnostics.json`, we evaluate $A(\theta)$ and $E_{\text{vac}}(\theta)$ on a uniform grid of $N_\theta = 2048$ points in $[0, 2\pi]$. The script

```
phase4/src/phase4/run_f1_sanity.py
```

writes the per-grid values to

```
phase4/outputs/tables/phase4_F1_sanity_curve.csv,
```

together with mapping metadata and a summary of basic moments.

For the baseline configuration used here, $E_{\text{vac}}(\theta)$ is strictly positive and remains on a small, controlled scale, reflecting the scale of the underlying amplitude and the chosen (α, β) . This establishes that the F1 mapping is at least numerically well behaved and correctly wired to the Phase 3 mechanism.

3.2 Toy shape diagnostics and non-binding corridor

The second diagnostic probes the *shape* of $E_{\text{vac}}(\theta)$. The script

```
phase4/src/phase4/run_f1_shape_diagnostics.py
```

rebuids the same F1 curve and computes:

- global extrema and moments ($E_{\text{vac,min}}$, $E_{\text{vac,max}}$, mean, std);
- a toy, non-binding θ -corridor defined by

$$E_{\text{vac}}(\theta) \leq E_{\text{vac,min}} + k_\sigma \sigma, \quad k_\sigma = 1;$$

- the fraction of the grid lying inside this corridor and the induced θ -range.

The resulting summary is written to

`phase4/outputs/tables/phase4_F1_shape_diagnostics.json`,

while a per- θ mask, indicating membership in the toy corridor, is written to

`phase4/outputs/tables/phase4_F1_shape_mask.csv`.

This corridor is explicitly labelled as *exploratory and non-binding*. It does not define a canonical θ_* or a Phase 4 θ -filter; it is only a structured way of selecting a low- E_{vac} region that later rungs can reuse when designing FRW-like toy modules.

3.3 FRW-like toy diagnostics (design only)

To keep the Phase 4 narrative aligned with the Phase 0 contract, we separate the internal diagnostics above from any FRW-like behaviour tests. A separate design note

`phase4/FRW_TOY_DESIGN.md`

specifies a minimal FRW-inspired toy module in which the F1 scalar acts as a driving term for a dimensionless scale factor $a(\tau)$ and Hubble-like quantity $H(\tau)$.

At the present rung this module is *not* implemented, and no FRW-style diagnostics enter the claims table. The only purpose of the design work is to:

- define clear, auditable interfaces between $E_{\text{vac}}(\theta)$, the toy corridor mask, and FRW-like quantities; and
- constrain future work so that any FRW-like diagnostics remain simple, reproducible, and explicitly non-claiming unless promoted to a Phase 4 θ -filter.

Subsequent rungs may instantiate this toy module in code or, if it proves unhelpful, retire it in favour of alternative diagnostics. In either case, the Phase 4 paper will distinguish binding θ -filters from non-binding exploratory diagnostics in line with the Phase 0 corridor semantics.

4 Limitations and outlook

Phase 4 is intentionally narrow in scope. Even once the mappings and diagnostics are implemented, the phase will not claim:

- a full derivation of cosmological parameters;
- a proof that the Origin Axiom is realised in nature; or
- a unique mechanism for connecting vacuum structure to FRW dynamics.

Instead, the goal is to provide a clean yes-or-no style test for a specific question:

Can the Phase 3 global-amplitude mechanism support scale-sane FRW-like behaviour, in at least one simple mapping family, without producing a degenerate or empty θ -corridor?

If the answer is “no” for all tested mapping families, Phase 4 will record this as a structured negative result, signalling that either the Phase 3 mechanism or the mapping strategy needs revision before further unification attempts.

Appendix A: Phase 4 claims table (draft)

Table 1 summarises the intended Phase 4 claims. At this rung all entries are draft and non-binding.

Table 1: Draft Phase 4 claims. Binding status will be updated once the phase is complete and audited.

| ID | Binding? | Summary |
|------|----------|--|
| C4.1 | no | Existence of at least one explicit mapping from the Phase 3 global amplitude or residue into an FRW-like or vacuum-energy-like observable with numerically stable behaviour. |
| C4.2 | no | Existence of a non-empty, non-trivial θ -corridor for at least one such mapping. |
| C4.3 | no | Structured negative result if all tested mappings yield empty or pathological corridors. |

Appendix B: Reproducibility notes (draft)

This appendix will eventually document:

- the Phase 4 directory and workflow structure;
- the gate levels (paper-only vs. paper+artifacts);
- the commands required to rebuild the Phase 4 paper and any binding θ -filters; and
- the run manifests and configuration files that define the tested mapping families.

At this rung, Phase 4 only provides a minimal paper skeleton and no mapping implementations. Reproducibility therefore reduces to rebuilding the present PDF via the Phase 4 gate script.

References