Orion Joyner

Professor Alvarez

CSC 461/ Final Report

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Final Report

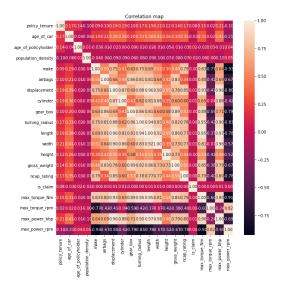
Introduction:

This project is a study of predicting car insurance claims in the next six months within machine learning algorithms. The dataset was taken from Kaggle.com and was used in a competition on the website. The name of the dataset is Car Insurance Claim Prediction The objective of using this dataset is to predict what factors contribute most to the policy holder's claim and if we are able to predict it ourselves. It is made up of a record of 10,302 observations and 27 variables. First, I had to analyze the dataset and become more familiar with it. This step involved looking at the various features, checking for null values, and performing some preprocessing. I constructed one base model and one model in order to compare accuracies. Finally, the model we use was submitted on kaggle in order to measure its best accuracy/precision.

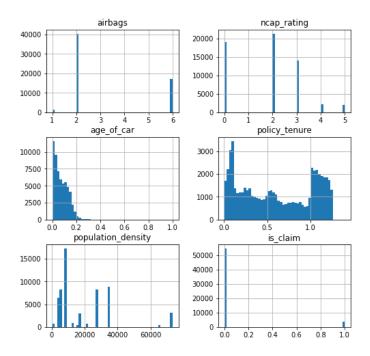
EDA:

As said before, in order to understand the data set completely, I need to use preprocessing and analyze different features. The training data was imported using the pandas library. The dataset has 15120 instances and 55 attributes. 54 of those attributes are features of the forest areas while the last attribute is the forest cover type or label. In order to analysis this more, a correlation matrix was made. Correlations between the non-categorical variables were

analyzed and plotted in the figure below. All of these strong correlations seem to be slightly higher than 0.75 in magnitude.



By also cleaning up the data, we were able to determine the six main contributing factors to the dataset itself. The figure is shown below for reference.



Source Code:

The following listed is the actual source code needed to represent our approach to this problem.

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import pandas as pd
import seaborn as sns
import numpy as np
import matplotlib.pyplot as plt
import io
from sklearn.ensemble import RandomForestClassifier
from sklearn.model selection import train test split, GridSearchCV
from sklearn.metrics import roc auc score, accuracy score, f1 score,
recall score, precision score
from sklearn.experimental import enable halving search cv
from sklearn.model selection import HalvingRandomSearchCV
from sklearn.dummy import DummyClassifier
from sklearn.metrics import accuracy score, ConfusionMatrixDisplay
from sklearn.linear model import LogisticRegression
from sklearn.tree import DecisionTreeClassifier
from sklearn.ensemble import RandomForestClassifier,
GradientBoostingClassifier
from sklearn.pipeline import make pipeline
from google.colab import files
from imblearn.over sampling import RandomOverSampler
from scipy.stats import randint
```

Gathering the Data

data = files.upload()

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Saving test.csv.zip to test.csv (1).zip

Saving train.csv.zip to train.csv (1).zip

In [69]:

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train=pd.read_csv("train.csv.zip")
test=pd.read csv("test.csv.zip")
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In [70]

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pd.set_option('display.max_rows',100)
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train.info()

RangeIndex: 58592 entries, 0 to 58591

Data columns (total 44 columns):

#	Column	Non-Null Count Dtype
0	policy_id	58592 non-null object
1	policy_tenure	58592 non-null float64
2	age_of_car	58592 non-null float64
3	age_of_policyholder	58592 non-null float64
4	area_cluster	58592 non-null object
5	population_density	58592 non-null int64
6	make	58592 non-null int64
7	segment	58592 non-null object
8	model	58592 non-null object
9	fuel_type	58592 non-null object
10	max_torque	58592 non-null object
11	max_power	58592 non-null object
12	engine_type	58592 non-null object

13	airbags	58592 non-null int64
14	is_esc	58592 non-null object
15	is_adjustable_steering	58592 non-null object
16	is_tpms	58592 non-null object
17	is_parking_sensors	58592 non-null object
18	is_parking_camera	58592 non-null object
19	rear_brakes_type	58592 non-null object
20	displacement	58592 non-null int64
21	cylinder	58592 non-null int64
22	transmission_type	58592 non-null object
23	gear_box	58592 non-null int64
24	steering_type	58592 non-null object
25	turning_radius	58592 non-null float64
26	length	58592 non-null int64
27	width	58592 non-null int64
28	height	58592 non-null int64
29	gross_weight	58592 non-null int64
30	is_front_fog_lights	58592 non-null object
31	is_rear_window_wiper	58592 non-null object
32	is_rear_window_washe	r 58592 non-null object
33	is_rear_window_defogo	ger 58592 non-null object
34	is_brake_assist	58592 non-null object
35	is_power_door_locks	58592 non-null object
36	is_central_locking	58592 non-null object
37	is_power_steering	58592 non-null object

38 is_driver_seat_height_adjustable 58592 non-null object

39 is_day_night_rear_view_mirror 58592 non-null object

40 is_ecw 58592 non-null object

41 is_speed_alert 58592 non-null object

42 ncap_rating 58592 non-null int64

43 is_claim 58592 non-null int64

dtypes: float64(4), int64(12), object(28)

memory usage: 19.7+ MB

In [76]

test.info()

RangeIndex: 39063 entries, 0 to 39062

Data columns (total 43 columns):

Column Non-Null Count Dtype

--- ----- -----

0 policy_id 39063 non-null object

1 policy_tenure 39063 non-null float64

2 age_of_car 39063 non-null float64

3 age_of_policyholder 39063 non-null float64

4 area_cluster 39063 non-null object

5 population_density 39063 non-null int64

6 make 39063 non-null int64

7 segment 39063 non-null object

8 model 39063 non-null object

9 fuel_type 39063 non-null object

10 max_torque 39063 non-null object

11 max power 39063 non-null object

12	engine_type	39063 non-null object
13	airbags	39063 non-null int64
14	is_esc	39063 non-null object
15	is_adjustable_steering	39063 non-null object
16	is_tpms	39063 non-null object
17	is_parking_sensors	39063 non-null object
18	is_parking_camera	39063 non-null object
19	rear_brakes_type	39063 non-null object
20	displacement	39063 non-null int64
21	cylinder	39063 non-null int64
22	transmission_type	39063 non-null object
23	gear_box	39063 non-null int64
24	steering_type	39063 non-null object
25	turning_radius	39063 non-null float64
26	length	39063 non-null int64
27	width	39063 non-null int64
28	height	39063 non-null int64
29	gross_weight	39063 non-null int64
30	is_front_fog_lights	39063 non-null object
31	is_rear_window_wiper	39063 non-null object
32	is_rear_window_washe	er 39063 non-null object
33	is_rear_window_defogo	ger 39063 non-null object
34	is_brake_assist	39063 non-null object
35	is_power_door_locks	39063 non-null object
36	is_central_locking	39063 non-null object
37	is_power_steering	39063 non-null object

38 is_driver_seat_height_adjustable 39063 non-null object

```
39 is_day_night_rear_view_mirror 39063 non-null object
40 is_ecw 39063 non-null object
41 is_speed_alert 39063 non-null object
42 ncap_rating 39063 non-null int64
dtypes: float64(4), int64(11), object(28)
memory usage: 12.8+ MB
#This shows the data set is heavily imbalanced
train['is_claim'].value_counts()/train.shape[0] * 100
0 93.603222
1 6.396778
sns.barplot(x = [0, 1], y = [54844, 3784])
```



train["policy_id"].duplicated().sum()

```
Out[79]:
0
In [81]:
```

data = train.set_index("policy_id")

```
In [82]:
```

```
def data_solver_strings(data):
```

```
data["max_torque_Nm"] =
data["max_torque"].str.extract(r"([-+]?[0-9]*\.?[0-9]+)(?=\s*Nm)").astype(
'float64')
```

```
data["max_torque_rpm"] =
data["max_torque"].str.extract(r"([-+]?[0-9]*\.?[0-9]+)(?=\s*rpm)").astype
('float64')
    data["max_power_bhp"] =
data["max power"].str.extract(r"([-+]?[0-9]*\.?[0-9]+)(?=\s*bhp)").astype(
'float64')
    data["max_power_rpm"] =
data["max_power"].str.extract(r"([-+]?[0-9]*\.?[0-9]+)(?=\s*rpm)").astype(
'float64')
    data.drop(["max_torque","max_power"], axis=1, inplace=True)
data_solver_strings(data)
fig, ax = plt.subplots(figsize=(10,10))
sns.heatmap(data.corr(), annot=True, fmt=".2f", ax=ax )
plt.title("Correlation map")
plt.show()
```

```
1.00 0.170.140.100.090.100.190.190.100.170.190.210.120.140.170.080.150.020.21-0.10
             0.17<mark>1.00</mark>-0.040.060.190.210.390.380.200.330.380.410.260.300.350.030.310.020.41<mark>-0.21</mark>
            0.14-0.04<mark>1.00</mark>0.01-0.030.010.020.000.000.020.020.010.050.010.030.02-0.020.03-0.010.04
            -0.100.060.01<mark>1.00</mark>-0.040.060.090.090.060.080.090.100.07-0.080.070.02-0.080.000.100.05
            0.09 0.19-0.030.04<mark>1.00</mark> 0.50 0.75 0.41 0.63 0.75 0.69 0.51 0.30 0.48 0.79-0.00 0.83<mark>-0.77</mark>0.64<mark>-0.93</mark>
            0.10 0.21-0.010.060.50 1.00 0.66 0.48 0.86 0.81 0.81 0.64 0.42 0.83 0.34 0.00 0.80 0.42 0.69 0.67
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      0.10 0.20-0.000.06 0.63 0.86 0.69 0.41 1.00 0.86 0.81 0.60 0.58 0.89 0.53-0.00 0.89 0.59 0.71 0.79
 no radius 0.17 0.33-0.020.08 0.75 0.81 0.88 0.62 0.86 1.00 0.94 0.83 0.46 0.82 0.78 0.00 0.95 0.42 0.90 0.83
            0.19 0.38 0.020.09 0.69 0.81 0.96 0.81 0.81 0.941.00 0.92 0.55 0.86 0.77 <mark>0.01 0.95 0.37</mark>0.97 0.78
            0.21 0.41 0.010.10 0.51 0.64 0.90 0.86 0.60 0.83 0.921.00 0.39 0.73 0.77 <mark>0.01 0.81 0.07</mark> 0.96 0.57
            0.12 0.26 0.05 0.07 0.3 0 0.4 2 0.5 5 0.3 5 0.5 8 0.4 6 0.5 5 0.3 9 1.0 0.7 3 0.4 4 0.0 0 0.5 4 0.4 2 0.4 8 0.5 2
            0.14 0.30 0.010.080.48 0.83 0.78 0.60 0.89 0.82 0.86 0.73 0.73 1.00 0.56 0.00 0.85 0.38 0.79 0.67
            0.17 0.35-0.030.07 0.79 0.34 0.85 0.60 0.53 0.78 0.77 0.77 0.44 0.56 1.00 0.00 0.79 0.40 0.80 0.78
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orque rom <mark>0.02 0.02 0.03-0.00</mark>0.770.420.41<mark>-0.04</mark>0.590.42-0.370.070.42-0.380,400.00-0.60<mark>1.00-</mark>0.24 0.82
 ower blog -0.21 0.41-0.010.10 0.640.69 0.96 0.88 0.71 0.90 0.970.96 <mark>0.48 0.79 0.80 0.01 0.90 0.24</mark>1.00 0.69
    er rom -<mark>0.100.210.040.05-</mark>0.930.670.800.420.790.830.780.570.520.670.78<mark>0.00-</mark>0.91<mark>0.82</mark>-0.691.00
```

```
# TARGET BALANCE

train["is_claim"].value_counts(normalize=True).plot(kind="bar")

plt.ylabel("Relative Frequency")

plt.xlabel("Target")
```

plt.title("Target Balance");

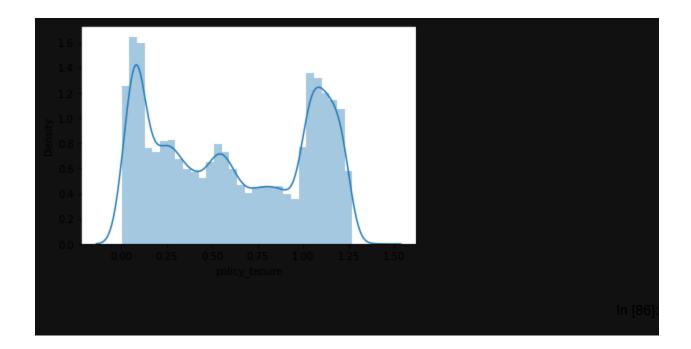


checking for outliers

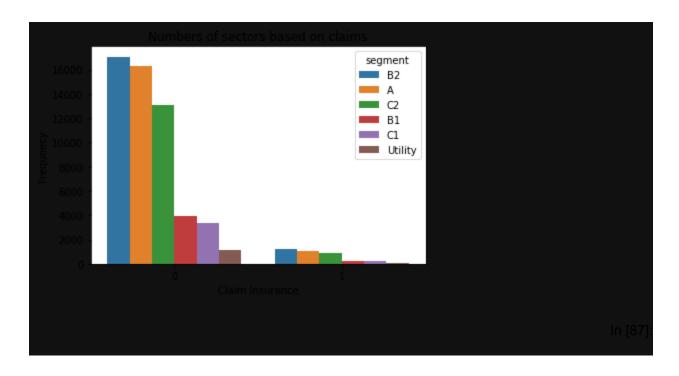
sns.distplot(train["policy tenure"]);

/usr/local/lib/python3.8/dist-packages/seaborn/distributions.py:2619: FutureWarning: `distplot` is a deprecated function and will be removed in a future version. Please adapt your code to use either `displot` (a figure-level function with similar flexibility) or `histplot` (an axes-level function for histograms).

warnings.warn(msg, FutureWarning)



Numbers of segments based on cliams



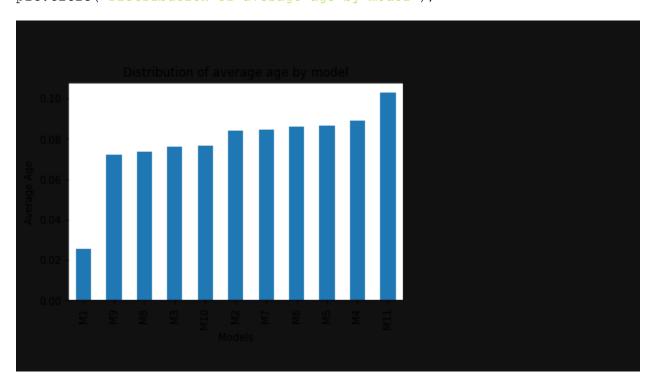
```
## distribution of average age by model

train.groupby("model")["age_of_car"].mean().sort_values().plot(kind="bar")

plt.xlabel("Models")

plt.ylabel("Average Age")

plt.title("Distribution of average age by model");
```



```
ln [88
```

```
target = "is_claim"
X = train.drop(target, axis=1)
y = train[target]
print(X.shape, y.shape)
(58592, 43) (58592,)
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2,
random_state=1)
from imblearn.over_sampling import RandomOverSampler
sampler = RandomOverSampler(random_state=1)
X_train_over, y_train_over = sampler.fit_resample(X_train,y_train)
print(X_train_over.shape, y_train_over.shape)
(87764, 43) (87764,)
model_baseline = y_train.value_counts(normalize=True).max()
model_baseline
```

```
Out[91
.9361892774091695
In [92
```

```
def vif check(data check):
   vif_data = pd.DataFrame()
   vif data["feature"] = data check.columns
    # calculating VIF for each feature
    vif data["VIF"] = [variance inflation factor(data check.values, i)
                          for i in range(len(data check.columns))]
    return vif_data.sort_values("VIF", ascending=False).reset_index()
data check = data.select dtypes(exclude=["object"]).drop("is_claim",
axis=1)
#cycle which returns features having VIF < 5, or Featues with low
correlation
while vif check(data check)["VIF"][0] > 5:
    data check.drop(vif check(data check)["feature"][0], axis=1,
inplace=True)
feature_vif_table = vif_check(data_check)
feature vif table
```

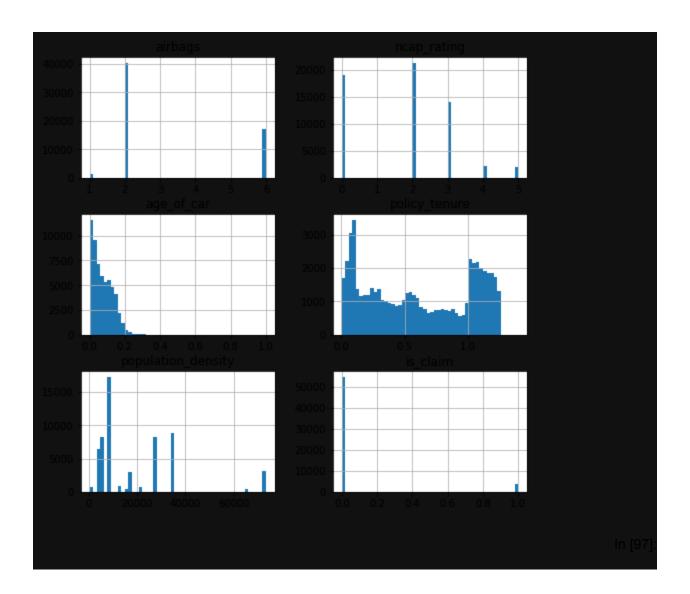
/usr/local/lib/python3.8/dist-packages/statsmodels/stats/outliers_influence.py:193: RuntimeWarning: divide by zero encountered in double_scalars

	inde x	feature	VIF
0	3	airbags	3.58732 6
1	4	ncap_rating	3.22181 5
2	1	age_of_car	2.77937 1
3	0	policy_tenure	2.69811 1
4	2	population_densit y	1.68483 4

In [9

						Out[95]:
	airbags	ncap_rating	age_of_car	policy_tenur e	population_densit y	is_claim
coun t	58592.00000 0	58592.00000 0	58592.00000 0	58592.00000 0	58592.000000	58592.00000 0
mea n	3.137066	1.759950	0.069424	0.611246	18826.858667	0.063968
std	1.832641	1.389576	0.056721	0.414156	17660.174792	0.244698
min	1.000000	0.000000	0.000000	0.002735	290.000000	0.000000
25%	2.000000	0.000000	0.020000	0.210250	6112.000000	0.000000
50%	2.000000	2.000000	0.060000	0.573792	8794.000000	0.000000
75%	6.000000	3.000000	0.110000	1.039104	27003.000000	0.000000
max	6.000000	5.000000	1.000000	1.396641	73430.000000	1.000000
						In [96]:

data_clean.hist(bins=50, figsize=(8,8))
plt.show()



data_clean = data_clean[data_clean["age_of_car"] < 0.25]</pre>

```
Preprocessing
```

```
X = data_clean.drop("is_claim", axis=1)
y = data_clean["is_claim"]
```

```
X_train, X_valid, y_train, y_valid = train_test_split(X, y,
random_state=737, test_size=0.2, stratify=y)
X_train = pd.get_dummies(X_train, drop_first=True)
X_valid = pd.get_dummies(X_valid, drop_first=True)
sampler = RandomOverSampler(random_state=737)
X_train_over, y_train_over = sampler.fit_resample(X_train,y_train)
y_train_over.hist(figsize=(15,3))
plt.title("Spread of zeroes and ones")
plt.show()
```



Base Model

Base Model

In [102

```
dummy = DummyClassifier(strategy="stratified", random_state=737)
dummy.fit(X_train_over, y_train_over)
predicted_valid = dummy.predict(X_valid)
accuracy = accuracy_score(y_valid, predicted_valid)
ras = roc_auc_score(y_valid, dummy.predict_proba(X_valid)[:, 1])
f1 = f1_score(y_valid, predicted_valid)
recall = recall_score(y_valid, predicted_valid)
precision = precision_score(y_valid, predicted_valid)
print("Accuracy score = ", accuracy)
print("AUC-ROC score = ", ras)
print("F1 score = ", f1)
print("Recall score = ", recall)
print("Precision score = ", precision)
```

Accuracy score = 0.4964423489069867

AUC-ROC score = 0.4974766456084045

F1 score = 0.11268882175226586

Recall score = 0.49866310160427807

Precision score = 0.06352179836512262

```
Model
In [103]
```

```
model = RandomForestClassifier(random_state=737)
np.random.seed(737)
param_distributions = {"max_depth": randint(3,10),
                        "min_samples_split": randint(2, 9),
                        "min samples leaf": randint(2, 9)
search = HalvingRandomSearchCV(model, param_distributions,
resource="n estimators",
                                max resources=50,
                                random state=737,
                                scoring="f1",
                                cv=5).fit(X train over, y train over)
search.best params
{'max_depth': 9,
'min_samples_leaf': 8,
'min_samples_split': 8,
```

model = RandomForestClassifier(random_state=737, **search.best_params_)

```
model.fit(X_train_over, y_train_over)
predicted_valid = model.predict(X_valid)
accuracy = accuracy_score(y_valid, predicted_valid)

ras = roc_auc_score(y_valid, model.predict_proba(X_valid)[:, 1])

f1 = f1_score(y_valid, predicted_valid)

recall = recall_score(y_valid, predicted_valid)

precision = precision_score(y_valid, predicted_valid)

print("Accuracy score = ", accuracy)

print("AUC-ROC score = ", ras)

print("F1 score = ", f1)

print("Recall score = ", precision)
```

```
Accuracy score = 0.5873124732104587
```

AUC-ROC score = 0.6416906566268867

F1 score = 0.16481609993060375

Recall score = 0.6350267379679144

Precision score = 0.0946969696969697

Conclusion:

The classifier we performed the best with an accuracy of 63%. This was a very disappointing result and was simply not expected. It is possible that if we had included more methods and algorithms into our data, we would've created a better model. It is possible that overfitting occurred even though cross-validation was used. The results obtained were not good enough to place well on the leaderboard. While the results were not as satisfactory as expected,

this project was a great introduction to using different types of machine learning methods on a real world dataset. This project significantly improved their understanding of the classifiers used and their competence of implementing these models in Python. Further work could be done to better fit the data and possibly achieve better performance results. It is possible that other algorithms and methods would be better suited to this dataset than the ones used in this study. In conclusion, much was learned from performing this study but further work would have to be done in order to improve the results obtained.

References:

[1] Kaggle. (2014). Car Insurance Prediction. Available at:

https://www.kaggle.com/datasets/ifteshanajnin/carinsuranceclaimprediction-classification

[2] Kaggle. (2014). Car Insurance Prediction. Available at:

https://www.kaggle.com/code/gautamchettiar/claim-predictions-encoding-classifiers-eda

[3] RandomForestClassifer. Available

at: https://scikit-learn.org/stable/modules/generated/sklearn.ensemble.RandomForest
Classifier.html

[4] Model Classification Accuracy

https://developers.google.com/machine-learning/crash-course/classification/accuracy