Some calculations about the mirror descent (MD) algorithm.

The setting and notations...

- The potential  $R: \mathbb{R}^d \to \mathbb{R}$ , a Legendre function.
- Its convex conjugate:  $R^*(u) = \sup_x \{ \langle u, x \rangle R(x) \}.$
- The "mirror maps"  $\nabla R : \mathbb{R}^d \to \mathbb{R}^d$  and  $\nabla R^* : \mathbb{R}^d \to \mathbb{R}^d$ .
- The loss functions  $(\ell_t)$ , each  $\ell_t : \mathbb{R}^d \to \mathbb{R}$ .
- Time index  $t \in \{0, 1, 2, ...\}$  for discrete time,  $t \in [0, \infty)$  for continuous time.
- $x, x_t$  (discrete time), x(t) (continuous time) elements of the primal space.
- $u, u_t$  (discrete time), u(t) (continuous time) elements of the dual space.

The MD algorithm (discrete time) uses the initialization and updates

$$x_1 = \arg\min R(x),$$
  

$$x_{t+1} = \arg\min_{x \in \mathbb{R}^d} \left\{ \langle \nabla \ell_t(x_t), x \rangle + \eta D_R(x, x_t) \right\}.$$

Here  $D_R(x, y)$  stands for the Bregman divergence, whose definition is recalled now:

$$D_R(a_1, a_2) = R(a_1) - R(a_2) - \langle \nabla R(a_2), a_1 - a_2 \rangle$$
.

The order of the arguments matters. Let's say  $D_R(a_1, a_2)$  is "supported at  $a_2$ " (its definition uses a tangent supported at  $a_2$ ). To minimize clutter let's denote by  $\partial_i$  the partial derivative (operator) with respect to the *i*-th argument. So for instance:

$$\partial_1 D_R(a_1, a_2) = \nabla R(a_1) - \nabla R(a_2),$$
  
 $\partial_2 D_R(a_1, a_2) = -\nabla^2 R(a_2)(a_1 - a_2).$ 

A couple of equations in discrete time:

$$u_{t+1} = u_t - \eta \nabla \ell_t(x_t) \tag{1dt}$$

$$x_t = \nabla R^*(u_t). \tag{2dt}$$

Analogous equations in continuous time:

$$u'(t) = -\eta \nabla \ell_t(x(t)) \tag{1ct}$$

$$x(t) = \nabla R^*(u(t)). \tag{2ct}$$

For fixed  $x^* \in \mathbb{R}^d$ ,  $u^* = \nabla R(x^*)$ ,

$$\ell_t(x^*) \ge \ell_t(x(t)) + \langle \nabla \ell_t(x(t)), x^* - x(t) \rangle \tag{3}$$

From (1ct) we get  $\nabla \ell_t(x(t)) = -u'(t)/\eta$ , and plugging this in (3) we get:

$$\ell_t(x^*) \ge \ell_t(x(t)) - \frac{1}{\eta} \langle u'(t), x^* - x(t) \rangle.$$

Rearranging:

$$\ell_t(x(t)) - \ell_t(x^*) \le \frac{1}{\eta} \langle u'(t), x^* - x(t) \rangle, \qquad (4)$$

and the claim is that the RHS is the derivative of a Bregman divergence.

On one hand, by the chain rule and the symmetry of the Hessian:

$$\frac{d}{dt}D_{R^*}(u^*, u(t)) = \langle \partial_2 D_{R^*}(u^*, u(t)), u'(t) \rangle$$

$$= -\langle \nabla^2 R^*(u(t))(u^* - u(t)), u'(t) \rangle$$

$$= -\langle u^* - u(t), \nabla^2 R^*(u(t))u'(t) \rangle$$

$$= -\langle u^* - u(t), x'(t) \rangle.$$

On the other hand,

$$\frac{d}{dt}\langle u^* - u(t), x^* - x(t) \rangle = -\langle u'(t), x^* - x(t) \rangle - \langle u^* - u(t), x'(t) \rangle.$$

Combining the two:

$$\langle u'(t), x^* - x(t) \rangle = -\langle u^* - u(t), x'(t) \rangle - \frac{d}{dt} \langle u^* - u(t), x^* - x(t) \rangle$$
$$= \frac{d}{dt} D_{R^*}(u^*, u(t)) - \frac{d}{dt} \langle u^* - u(t), x^* - x(t) \rangle.$$

Then (4) can be written as

$$\ell_t(x(t)) - \ell_t(x^*) \le \frac{1}{\eta} \frac{d}{dt} \Big( D_{R^*}(u^*, u(t)) - \langle u^* - u(t), x^* - x(t) \rangle \Big)$$

After integrating (???)

$$\int_0^T [\ell_t(x(t)) - \ell_t(x^*)] dt \le \frac{1}{\eta} [D_{R^*}(u^*, u(T)) - D_{R^*}(u^*, u(0))]$$

Note: the term  $\langle u^* - u(t), x^* - x(t) \rangle = \langle \nabla R(x^*) - \nabla R(x(t)), x^* - x(t) \rangle$  is the sum of  $D_R(x^*, x(t))$  and  $D_R(x(t), x^*)$ , so it is non-negative.