Matrix Calculator

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Chapter 1

File Index

1.1 File List

Here is a list of all files with brief descriptions:

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2 File Index

Chapter 2

File Documentation

2.1 main.cpp File Reference

```
#include <iostream>
#include <fstream>
#include <sstream>
#include <cmath>
#include <stdio.h>
#include <stdlib.h>
#include <time.h>
#include "matrix.h"
```

Enumerations

```
    enum class operation {
    add = 0 , subtract , multiply , determinant ,
    inverse , cofactor , transpose , random }
```

Functions

- void debugMatrix (const std::vector< std::vector< int > > vect)
- const std::vector< std::vector< int > > read_matrix (std::string file_name)
- void save_solution (const std::vector< std::vector< int > > solution, std::string &outputFile)
- void save_solution (int solution, std::string &outputFile)
- void save_solution (std::string input, std::string &outputFile)
- int Determinant (std::vector< std::vector< int > > A)
- void Add (const std::vector< std::vector< int > > A, const std::vector< std::vector< int > > B, std::string &outputFile)
- void Subtract (const std::vector< std::vector< int > > A, const std::vector< std::vector< int > > B, std::string &outputFile)
- void Multiply (const std::vector< std::vector< int > > A, const std::vector< std::vector< int > > B, std::string &outputFile)
- std::vector< std::vector< int > > Transpose (const std::vector< std::vector< int > > A)
- std::vector< std::vector< int > > Cofactor (const std::vector< std::vector< int > > A)
- void Inverse (const std::vector< std::vector< int > > A, std::string &outputFile)
- operation convert (std::string &perform)
- int main (int argc, char *argv[])

2.1.1 Enumeration Type Documentation

2.1.1.1 operation

```
enum class operation [strong]
```

An Enum class of operations

Parameters

add	
subtract	
multiply	
determinant	
inverse	
cofactor	
transpose	
random	

Enumerator

add	
subtract	
multiply	
determinant	
inverse	
cofactor	
transpose	
random	

2.1.2 Function Documentation

2.1.2.1 Add()

The function calculates the addition of two matrix and returns a solution to the file

Parameters

const	std::vector <std::vector<int>>A first matrix from file</std::vector<int>
const	std::vector <std::vector<int>> B second matrix from file</std::vector<int>

Returns

std::vector<std::vector<int>> solution solution from the add operation

2.1.2.2 Cofactor()

```
std::vector< std::vector< int >> Cofactor ( const std::vector< std::vector< int >> A )
```

The function takes a matrix and returns the cofactor of the matrix

Parameters

const	std::vector <std::vector<int>> matrix The input matrix to be transposed</std::vector<int>
-------	--

Returns

std::vector<std::vector<int>> solution returns the cofactor matrix

2.1.2.3 convert()

```
operation convert (
          std::string & perform )
```

The function takes a string input and compares with default parameters to get the operation type

Parameters

std::string& perform pointer with	th the string function
-----------------------------------	------------------------

Returns

operation convert

2.1.2.4 debugMatrix()

```
void debugMatrix ( {\tt const \ std::vector} < {\tt std::vector} < {\tt int} \ > \ {\tt vect} \ )
```

The function prints a matrix on console

Parameters

const std::vector<std::vector<double>> vect vector of vector double printed to the output

2.1.2.5 Determinant()

```
int Determinant ( {\tt std::vector} < {\tt std::vector} < {\tt int} \ > \ {\tt A} \ )
```

The function calculates the determinate of a matrix and returns a solution

Parameters

std::vector <std::vector<double>></std::vector<double>	A a vector of vector matrix containing the values read from file
---	--

Returns

int Determinant returns the value of the determinant

2.1.2.6 Inverse()

The function calculates the inverse of a matrix and returns a matrix of vector containing the solution

Parameters

const	std::vector <std::vector<int>>> matrix The input matrix</std::vector<int>
std::string&	outputFile pointer to the file where output solution from the operation is saved

2.1.2.7 main()

```
int main (
                      int argc,
                      char * argv[] )
```

2.1.2.8 Multiply()

The function multiplies two matrix and returns a matrix of vector containing the solution to the file

Parameters

const	std::vector <std::vector<int>>> A first Vector of matrix to be multiplied</std::vector<int>
const	std::vector <std::vector<int>>> B second vector of matrix to be multiplied</std::vector<int>
std::string&	outputFile pointer to the file where output solution from the operation is saved

2.1.2.9 read_matrix()

The function reads a matrix of random number from a file

Parameters

const	std::string& file_name pointer to the file been read from
-------	---

Returns

std::vector< std::vector<double>> read_matrix returns a vector of vector matrix containing the read matrix

Extract numbers from text

2.1.2.10 save_solution() [1/3]

The function saves the solution form a matrix operation to a file

Parameters

const	std::string& file_name pointer to the file been saved to
const	std::vector< std::vector <double>> solution vector of vector matrix containing the matrix to be saved to file</double>

2.1.2.11 save_solution() [2/3]

The function saves the solution form a matrix operation to a file

Parameters

double	solution double with value to the printed to file
std::string&	outputFile pointer to the file been saved to

2.1.2.12 save_solution() [3/3]

The function saves the solution form a matrix operation to a file

Parameters

std::string	file_name string with error message to the printed to file
std::string	&outputFile pointer to the file been saved to

2.1.2.13 Subtract()

The function calculates the difference of two matrix and returns a solution to the file

Parameters

const	std::vector <std::vector<int>> matrix1 first matrix from file</std::vector<int>	
const	std::vector <std::vector<int>>> matrix2 second matrix from file</std::vector<int>	
std::string& outputFile pointer to the file where output solution from the operation is save		

2.2 Matrix.h File Reference 9

2.1.2.14 Transpose()

```
std::vector< std::vector< int >> Transpose ( const std::vector< std::vector< int >> A )
```

The function takes a matrix and returns the matrix transpose to the file

Parameters

```
const std::vector<std::vector<int>> matrix The input matrix to be transposed
```

Returns

std::vector<std::vector<int>> solution returns the matrix transpose

2.2 Matrix.h File Reference

```
#include <vector>
```

Functions

- const std::vector< std::vector< int > > read_matrix (std::string file_name)
- void debugMatrix (const std::vector< std::vector< int > > vect)
- void save_solution (const std::vector< std::vector< int > > solution, std::string &outputFile)
- void save solution (int solution, std::string &outputFile)
- void save_solution (std::string input, std::string &outputFile)
- int Determinant (std::vector< std::vector< int > > A)
- void Add (const std::vector< std::vector< int > > A, const std::vector< std::vector< int > > B, std::string &outputFile)
- void Subtract (const std::vector< std::vector< int > > A, const std::vector< std::vector< int > > B, std::string &outputFile)
- void Multiply (const std::vector< std::vector< int > > A, const std::vector< std::vector< int > > B, std::string &outputFile)
- std::vector< std::vector< int > > Transpose (const std::vector< std::vector< int > >A)
- std::vector< std::vector< int > > Cofactor (const std::vector< std::vector< int > > A)
- void Inverse (const std::vector< std::vector< int > > A, std::string &outputFile)

2.2.1 Function Documentation

2.2.1.1 Add()

The function calculates the addition of two matrix and returns a solution to the file

Parameters

const	std::vector <std::vector<int>>A first matrix from file</std::vector<int>
const std::vector <std::vector<int>> B second matrix from f</std::vector<int>	

Returns

std::vector<std::vector<int>> solution solution from the add operation

2.2.1.2 Cofactor()

```
std::vector< std::vector< int >> Cofactor ( const std::vector< std::vector< int >> A )
```

The function takes a matrix and returns the cofactor of the matrix

Parameters

Returns

std::vector<std::vector<int>> solution returns the cofactor matrix

2.2.1.3 debugMatrix()

```
void debugMatrix ( {\tt const \ std::vector< \ std::vector< \ int \ > \ \it vect} \ )
```

The function prints a matrix on console

Parameters

const std::vector<std::vector<double>> vect vector of vector double printed to the output

2.2.1.4 Determinant()

```
int Determinant ( {\tt std::vector} < \; {\tt std::vector} < \; {\tt int} \; > \; {\tt A} \; {\tt )}
```

The function calculates the determinate of a matrix and returns a solution

2.2 Matrix.h File Reference

Parameters

std::vector <std::vector<double>></std::vector<double>	A a vector of vector matrix containing the values read from file
---	--

Returns

int Determinant returns the value of the determinant

2.2.1.5 Inverse()

The function calculates the inverse of a matrix and returns a matrix of vector containing the solution

Parameters

const	std::vector <std::vector<int>> matrix The input matrix</std::vector<int>	
std::string&	outputFile pointer to the file where output solution from the operation is saved	

2.2.1.6 Multiply()

The function multiplies two matrix and returns a matrix of vector containing the solution to the file

Parameters

const	std::vector <std::vector<int>>> A first Vector of matrix to be multiplied</std::vector<int>
const	std::vector <std::vector<int>>> B second vector of matrix to be multiplied</std::vector<int>
std::string&	outputFile pointer to the file where output solution from the operation is saved

2.2.1.7 read_matrix()

The function reads a matrix of random number from a file

Parameters

const std::string& file_name pointer to the file been read from

Returns

std::vector< std::vector<double>> read_matrix returns a vector of vector matrix containing the read matrix

Extract numbers from text

2.2.1.8 save_solution() [1/3]

The function saves the solution form a matrix operation to a file

Parameters

const	std::string& file_name pointer to the file been saved to
const	std::vector< std::vector <double>> solution vector of vector matrix containing the matrix to be saved</double>
	to file

2.2.1.9 save_solution() [2/3]

The function saves the solution form a matrix operation to a file

Parameters

double	solution double with value to the printed to file
std::string&	outputFile pointer to the file been saved to

2.2.1.10 save_solution() [3/3]

The function saves the solution form a matrix operation to a file

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Parameters

std::string	file_name string with error message to the printed to file
std::string &outputFile pointer to the file been saved to	

2.2.1.11 Subtract()

The function calculates the difference of two matrix and returns a solution to the file

Parameters

const	std::vector <std::vector<int>> matrix1 first matrix from file</std::vector<int>
const	std::vector <std::vector<int>> matrix2 second matrix from file</std::vector<int>
std::string&	outputFile pointer to the file where output solution from the operation is saved

2.2.1.12 Transpose()

```
\label{eq:std::vector} $$ std::vector< int >> Transpose ($$ const std::vector< std::vector< int >> A )
```

The function takes a matrix and returns the matrix transpose to the file

Parameters

```
const std::vector<std::vector<int>> matrix The input matrix to be transposed
```

Returns

std::vector<std::vector<int>> solution returns the matrix transpose

2.3 Matrix.h

Go to the documentation of this file.

```
1 #ifndef MATRIX_H
2 #define MATRIX_H
3 #include <vector>
4
10 const std::vector<std::vector<int> read_matrix(std::string file_name);
11
16 void debugMatrix(const std::vector<std::vector<int> vect);
17
```

```
23 void save_solution(const std::vector< std::vector<int> solution, std::string& outputFile);
30 void save_solution(int solution, std::string& outputFile);
31
37 void save_solution(std::string input, std::string& outputFile);
38
39
44 int Determinant(std::vector<std::vector<int» A);
45
51 void Add(const std::vector<std::vector<int» A, const std::vector<std::vector<int» B, std::string&
       outputFile);
52
58 void Subtract(const std::vector<std::vector<int> A, const std::vector<std::vector<int> B, std::string&
59
65 void Multiply(const std::vector<std::vector<int» A, const std::vector<std::vector<int» B, std::string&
      outputFile);
66
72 std::vector<std::vector<int> Transpose(const std::vector<std::vector<int>A);
79 std::vector<std::vector<int> Cofactor(const std::vector<std::vector<int> A);
80
81
87 void Inverse(const std::vector<std::vector<int» A, std::string& outputFile);
88 #endif
```

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