

Digital Twin



ros2 run husky_master husky_master

```
orjan@orjan-Surface-Laptop: ~/git/ORJANOS_MASTER_REPO
orjan@orjan-... orjan@orjan-... orjan@orjan-... orjan@orjan-...
Starting >>> vision_opencv
Finished <<< realsense2_camera [3.34s]
Starting >>> husky_desktop
Finished <<< vision_opencv [1.54s]
Starting >>> husky_robot
Finished <<< husky_desktop [1.32s]
Starting >>> husky_simulator
Finished <<< opencv_tests [6.84s]
Starting >>> interbotix_ros_xseries
Finished <<< husky_robot [1.48s]
Starting >>> interbotix_xs_toolbox
Finished <<< husky_simulator [1.54s]
Starting >>> husky_interbotix
Finished <<< interbotix_ros_xseries [1.99s]
Starting >>> interbotix_ros_xsarms_examples
Finished <<< interbotix_xs_toolbox [1.71s]
Finished <<< apriltag_ros [10.7s]
Finished <<< husky_interbotix [1.67s]
Finished <<< interbotix_ros_xsarms_examples [1.11s]

Summary: 52 packages finished [44.5s]
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```

Gazebo Simulation

