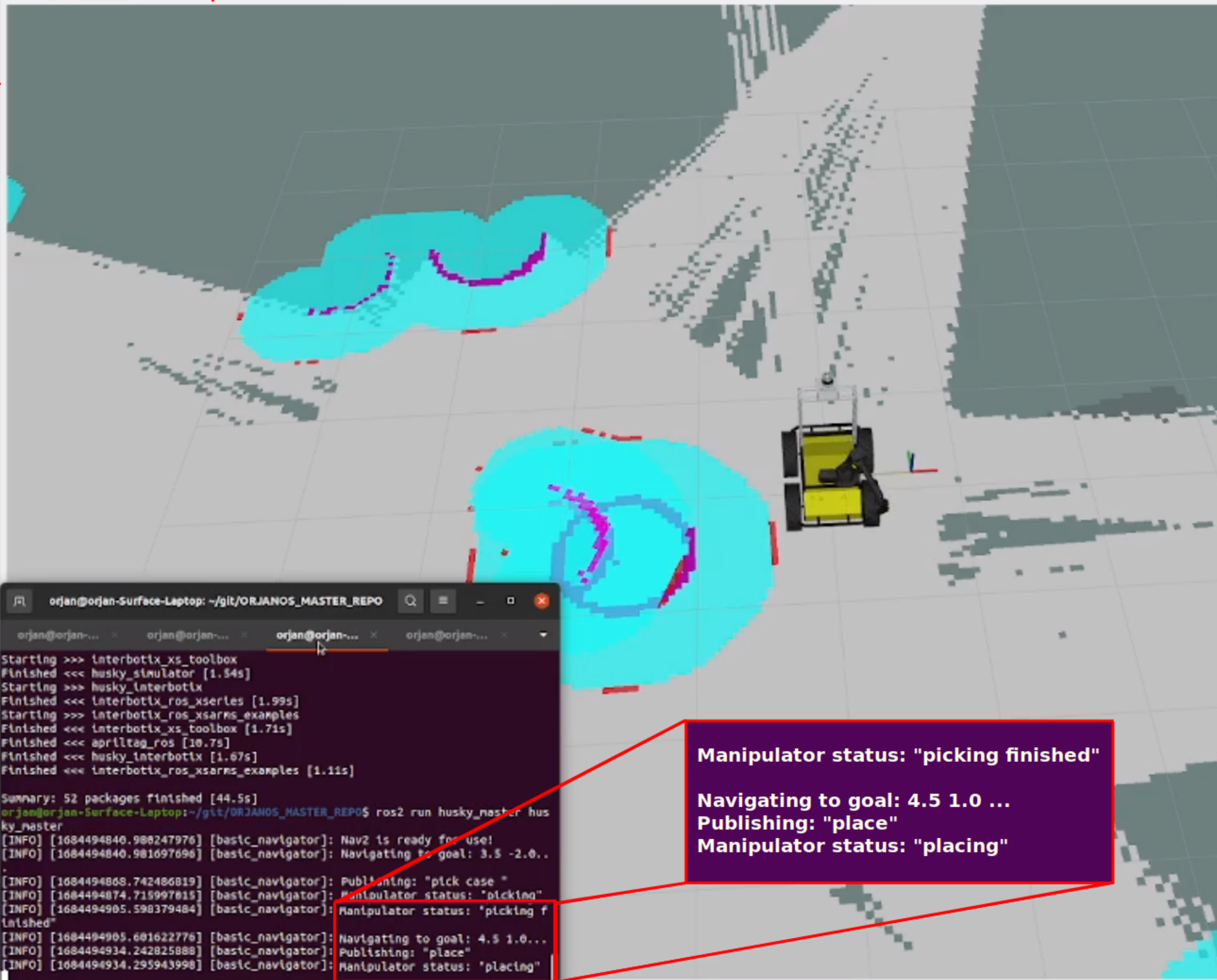
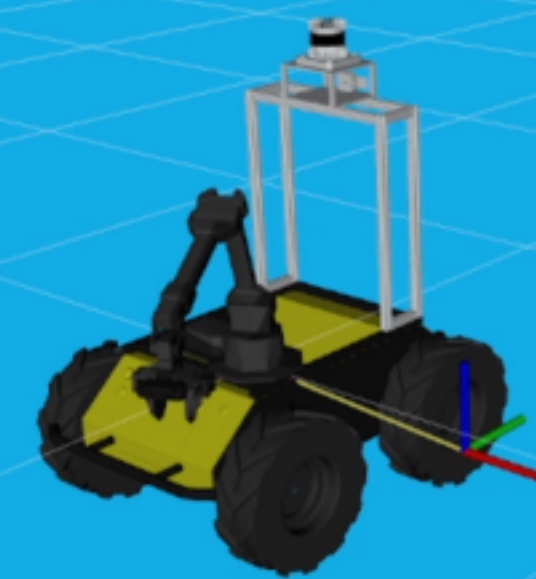


Digital Twin



Manipulator status: "picking finished"

Navigating to goal: 4.5 1.0 ...

Publishing: "place"

Manipulator status: "placing"

Gazebo Simulation

