

HuskyMasterNode

```
+ action_: var = ""  
+ action_status_: var = ""  
+ dimensions: var = [0.0, 0.0, 0.0]  
- manipulator_model: var = ""  
+ object: var = ""  
+ pick_loc: var = [0.0, 0.0, 0.0]
```

```
+ __init__(, )  
+ action_callback(, )  
+ action_publisher()  
+ create_pose_stamped(, , , )  
+ run()  
+ set_action(, )
```