



```
orjan@orjan-Surface-Book-2: ~  
orjan@orjan-... x orjan@orjan-... x orjan@orjan-... x orjan@orjan-... x orjan@orjan-... x  
orjan@orjan-Surface-Book-2:~$ ros2 run husky_master husky_master  
[INFO] [1681198723.798447857] [basic_navigator]: Nav2 is ready for use!  
[INFO] [1681198723.804046285] [basic_navigator]: Navigating to goal: 2.0 0.0...  
[INFO] [1681198772.415497980] [basic_navigator]: Publishing: "pick case "  
[INFO] [1681198778.113696617] [basic_navigator]: Manipulator status: "picking"
```