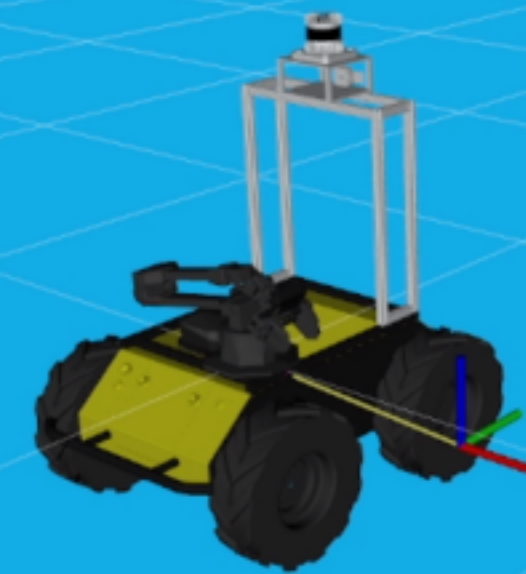
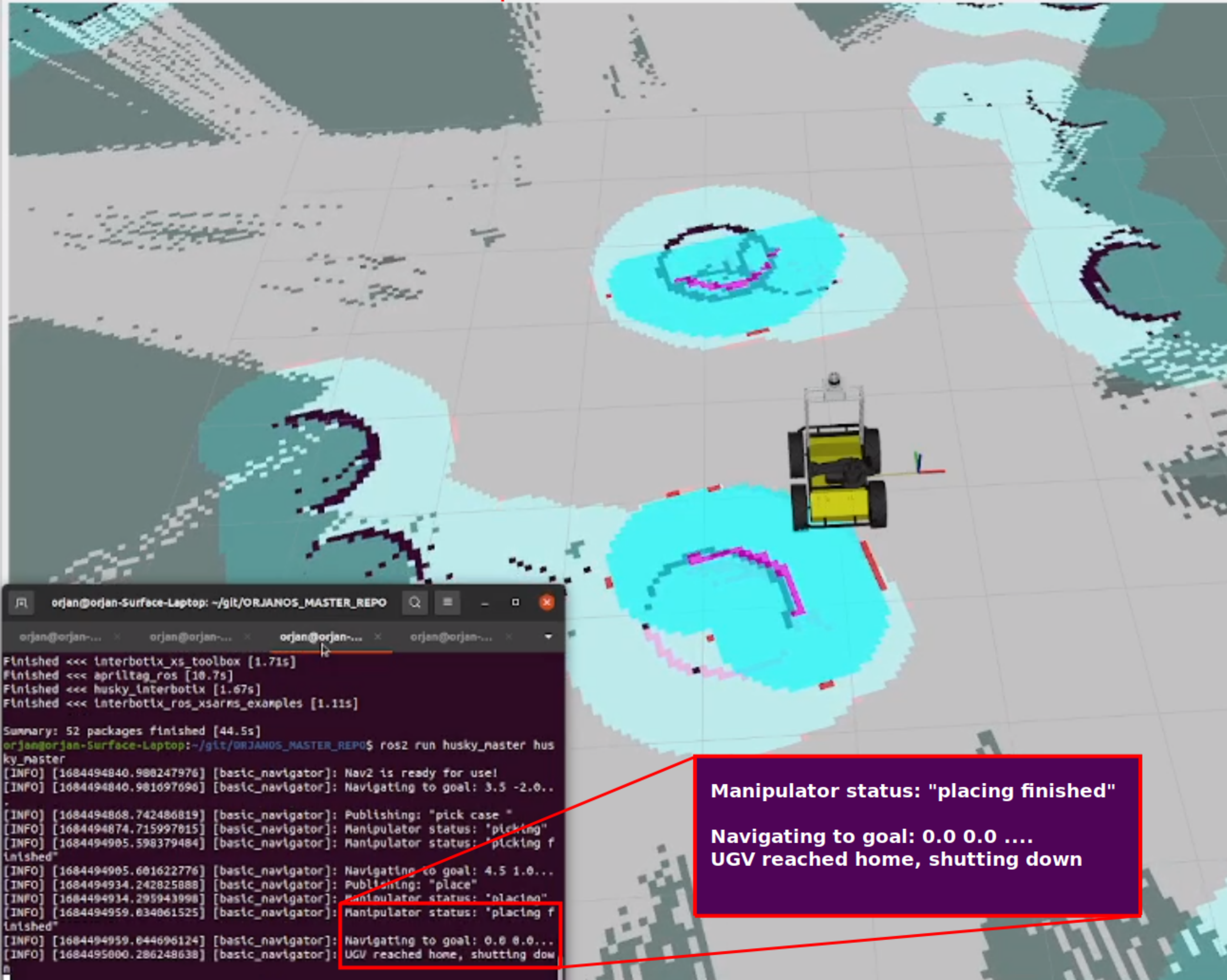
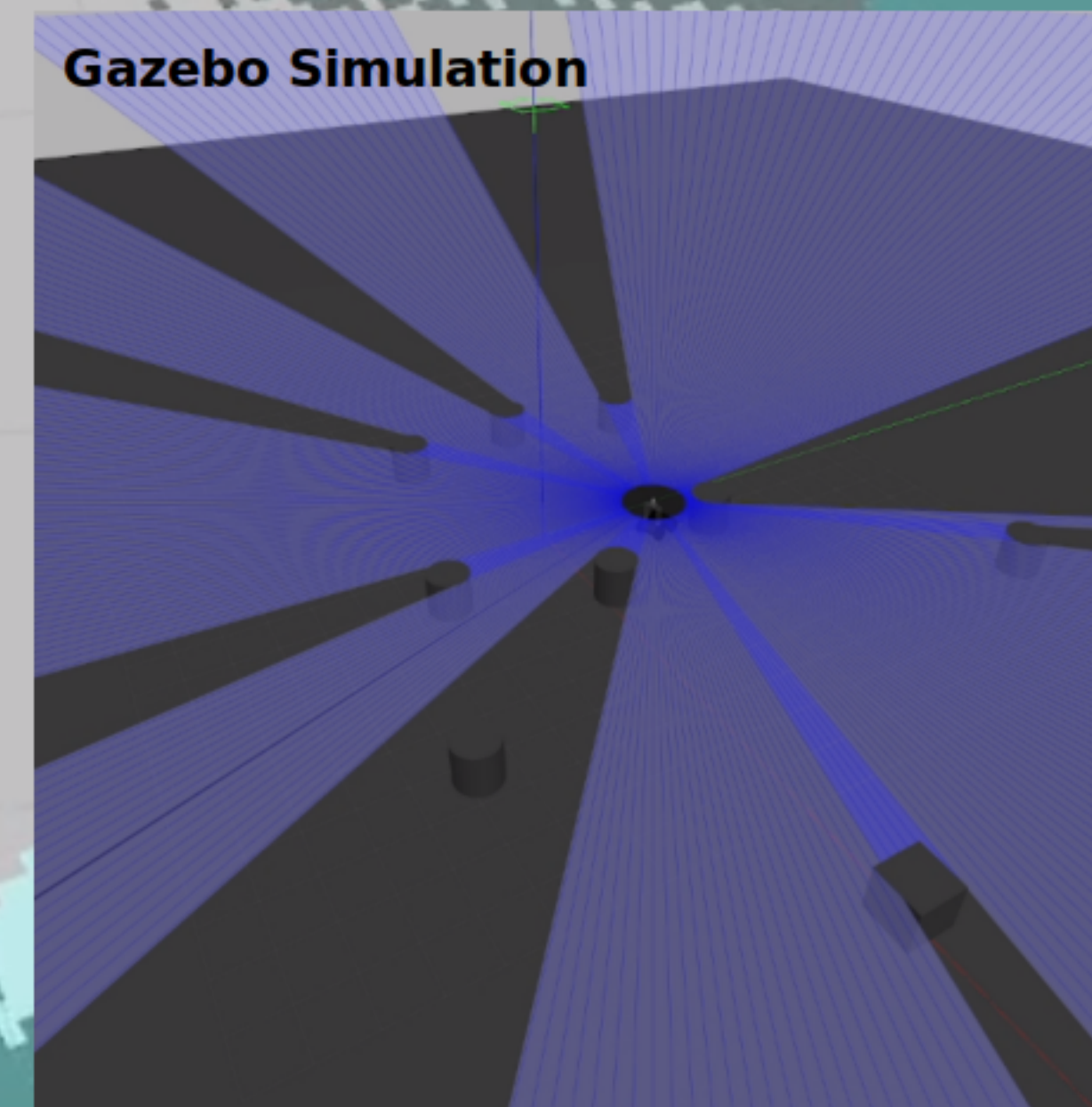


Digital Twin



Gazebo Simulation



Manipulator status: "placing finished"

Navigating to goal: 0.0 0.0 ....  
UGV reached home, shutting down