

Ray tracing UV light disinfection of hospital rooms

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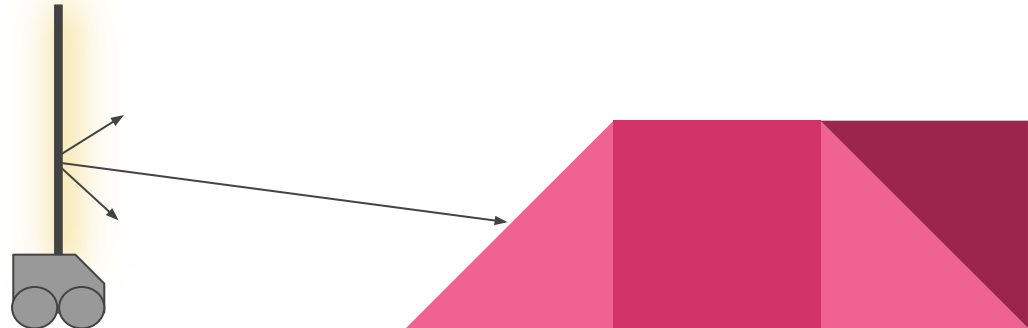
Content

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Concept

- UV lamp robot moves to points in a room
- Visualising UV radiation on the surfaces of this room
- Using ray tracing, an increasingly popular computer graphics technique



Approach

- Produce a heatmap
- Compute once a dose/color per triangle
- Cumulative dosage & maximum irradiance



3D model

- Obtained by using LiDAR technology in iPhones, via Polycam
- Slightly variable level of detail
- Not super robust, but decent, and is both cheaper and more efficient compared to the alternatives



Results

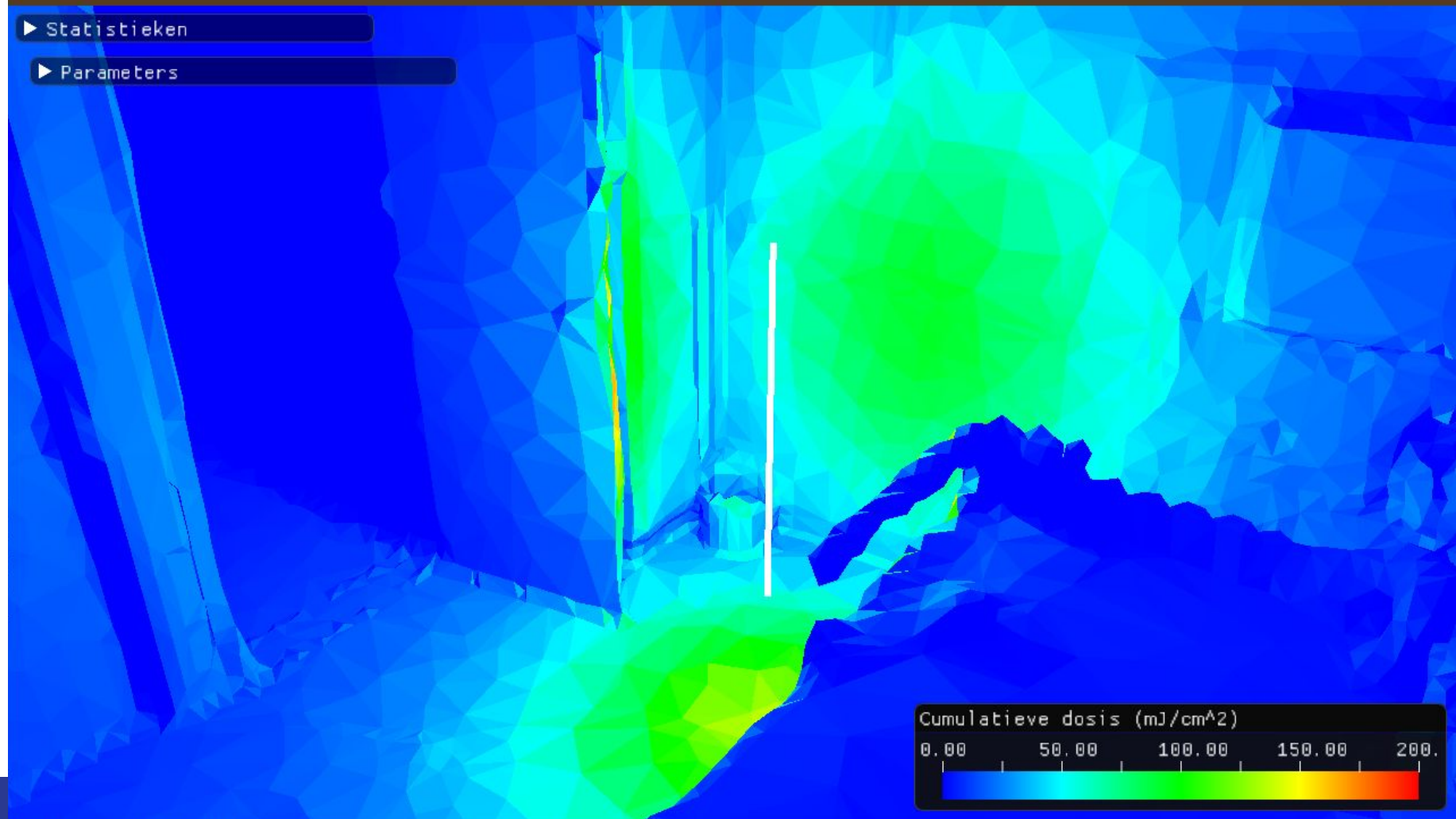
► Statistieken

► Parameters



► Statistieken

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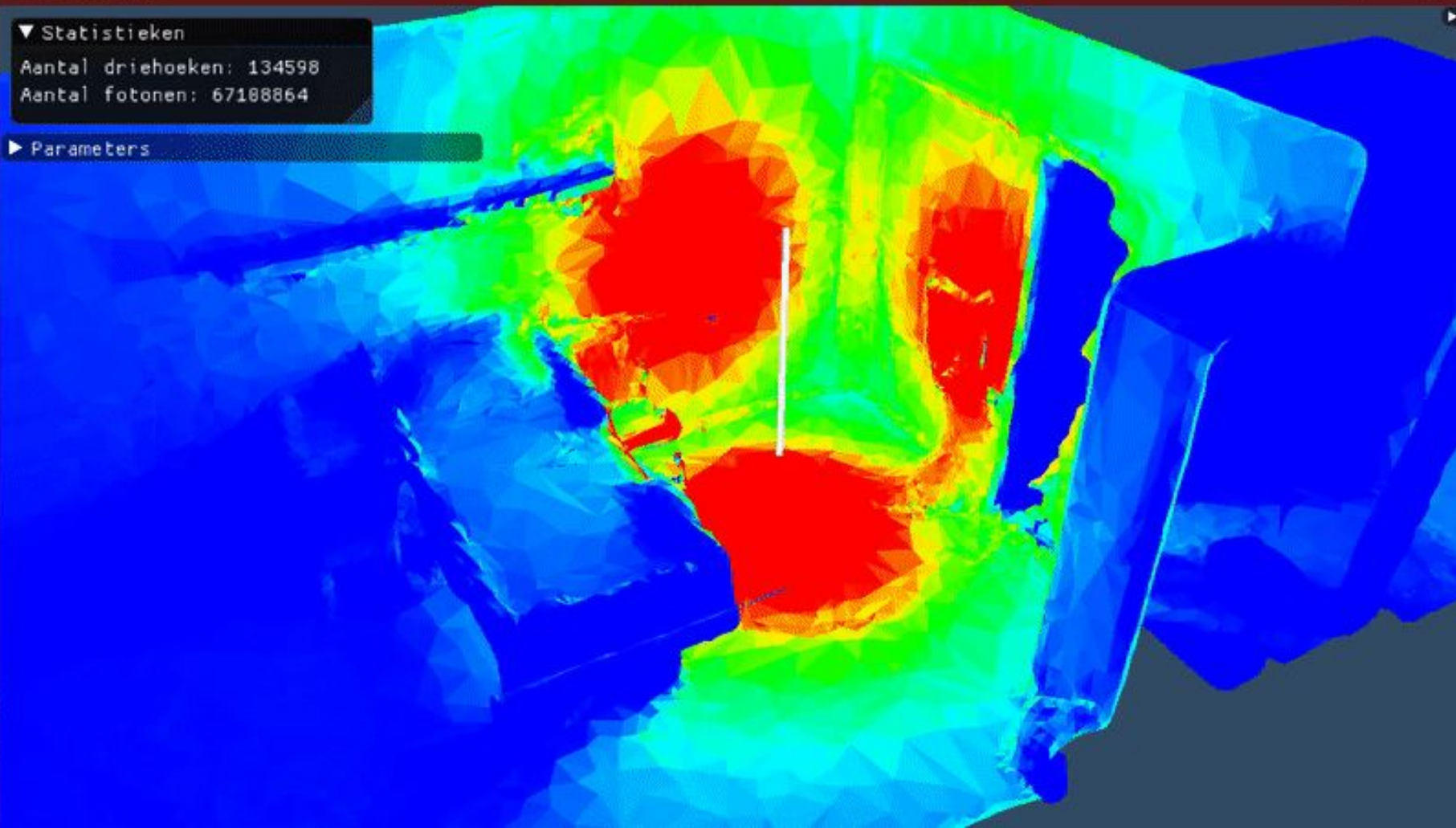


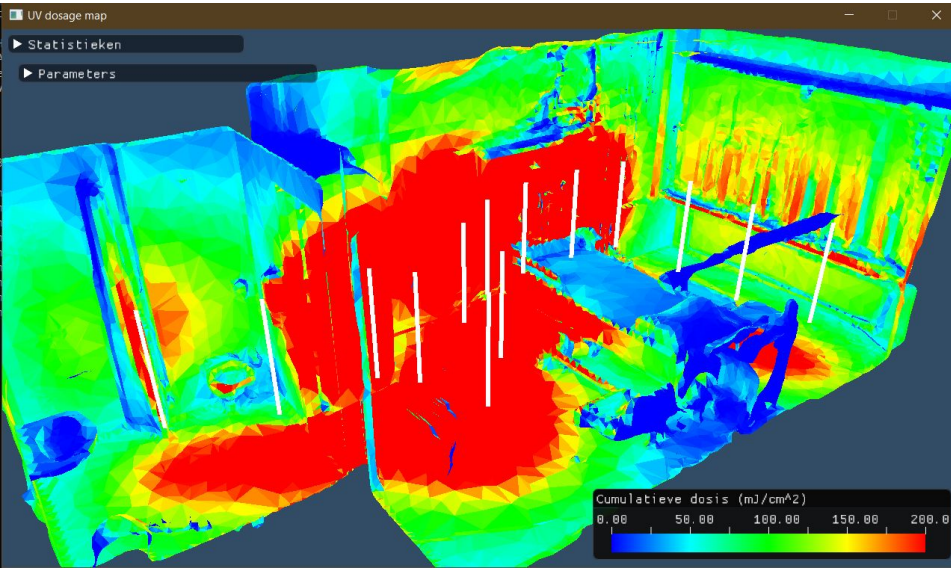
▼ Statistieken

Aantal driehoeken: 134598

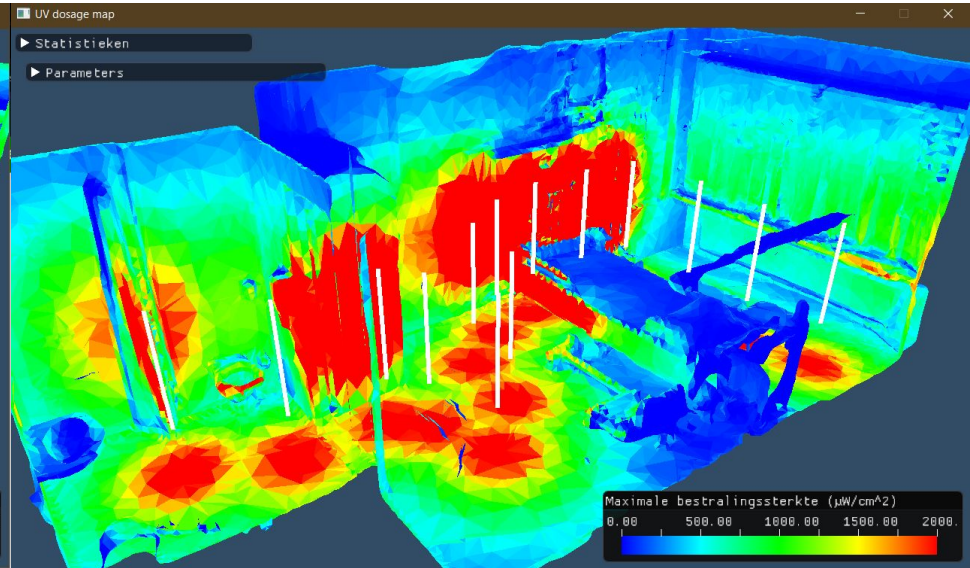
Aantal fotonen: 67188864

► Parameters





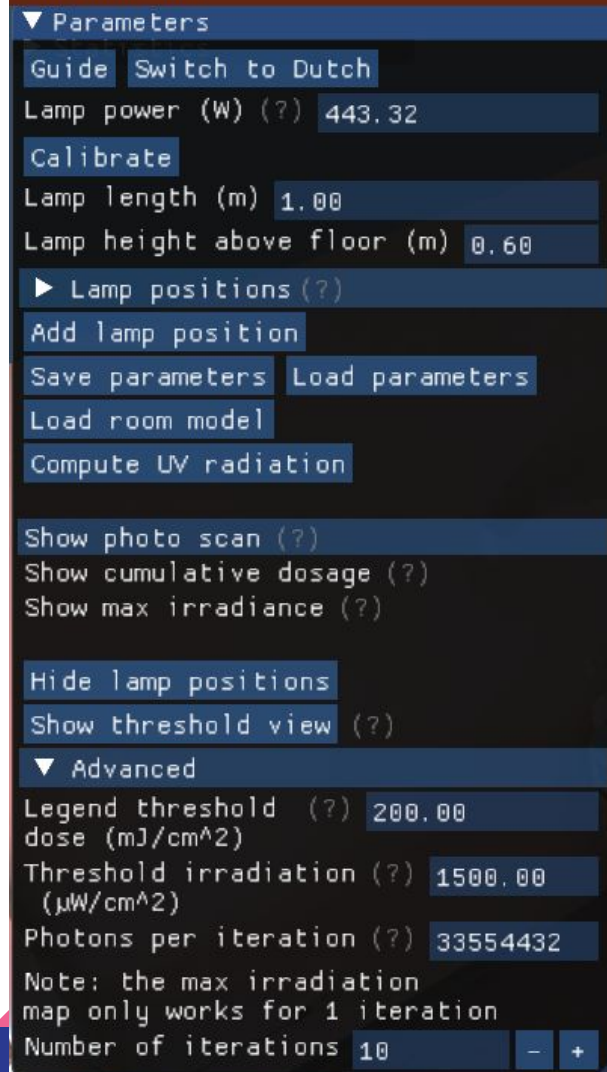
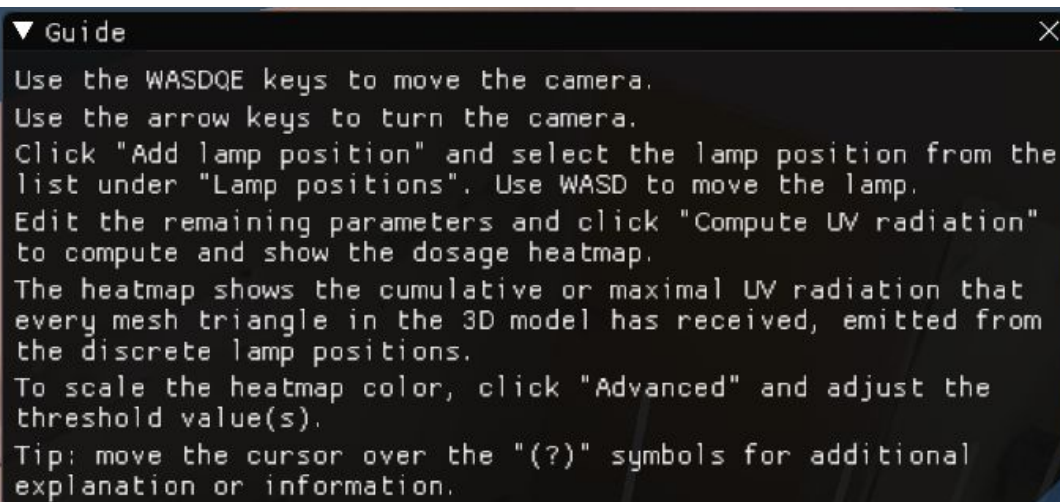
Cumulative dosage



Maximum irradiance

User Interface

- Lamp parameters
- Editable light positions



► Statistieken

▼ Parameters

Handleiding

Lamp sterkte (W) (?) 180.00

Lamp lengte (m) 1.00

Lamp hoogte (m) -0.90

► Lamp posities (?)

Lamp positie toevoegen

Parameters opslaan Parameters laden

Kamer model laden

Herbereken UV straling

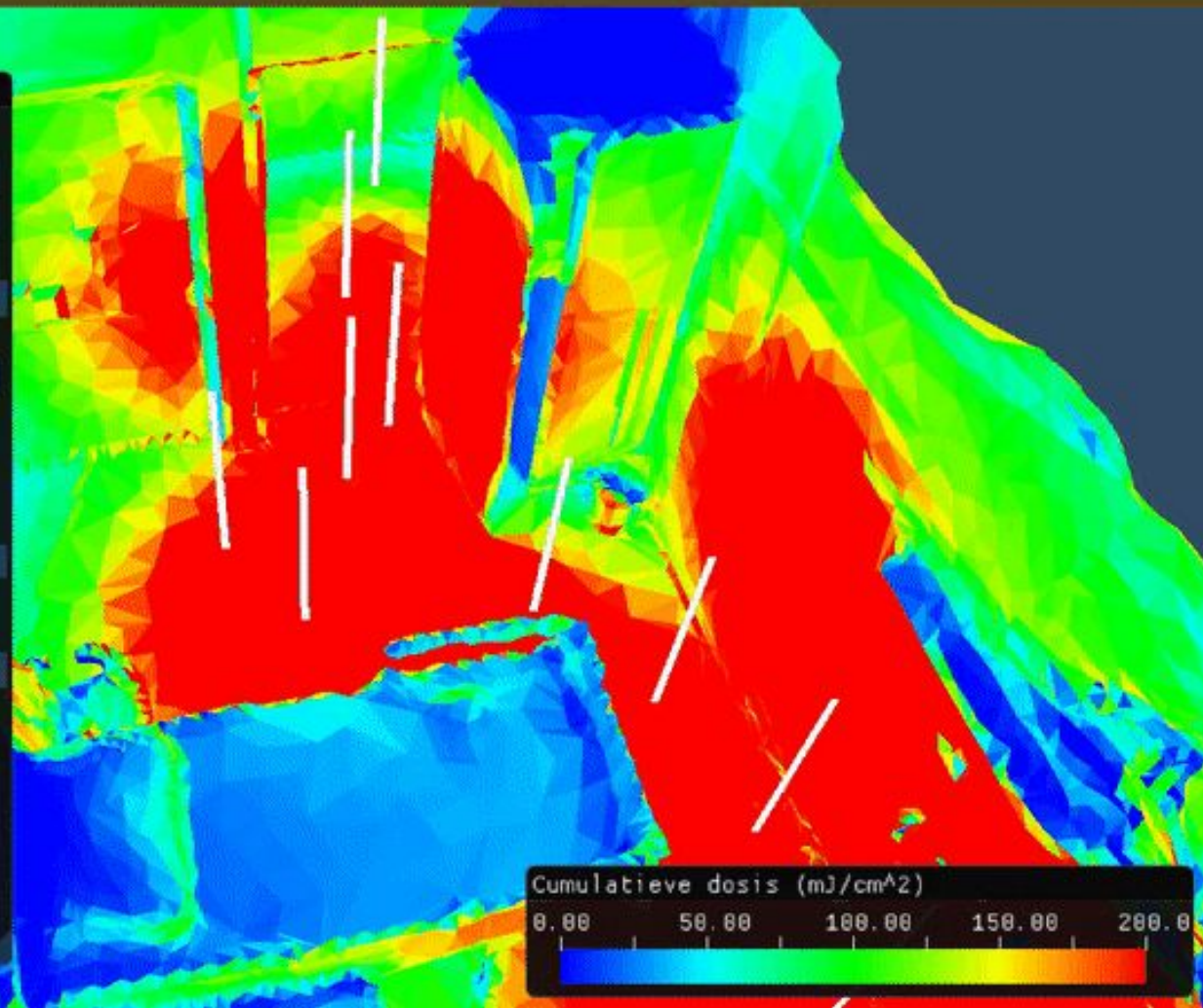
Toon fotoscan (?)

Toon totale dosis (?)

Toon max bestralingssterkte (?)

Verberg lamp posities

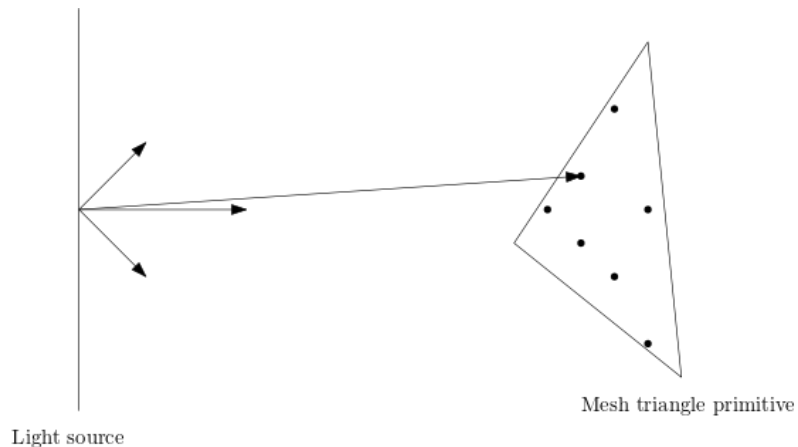
► Geavanceerd

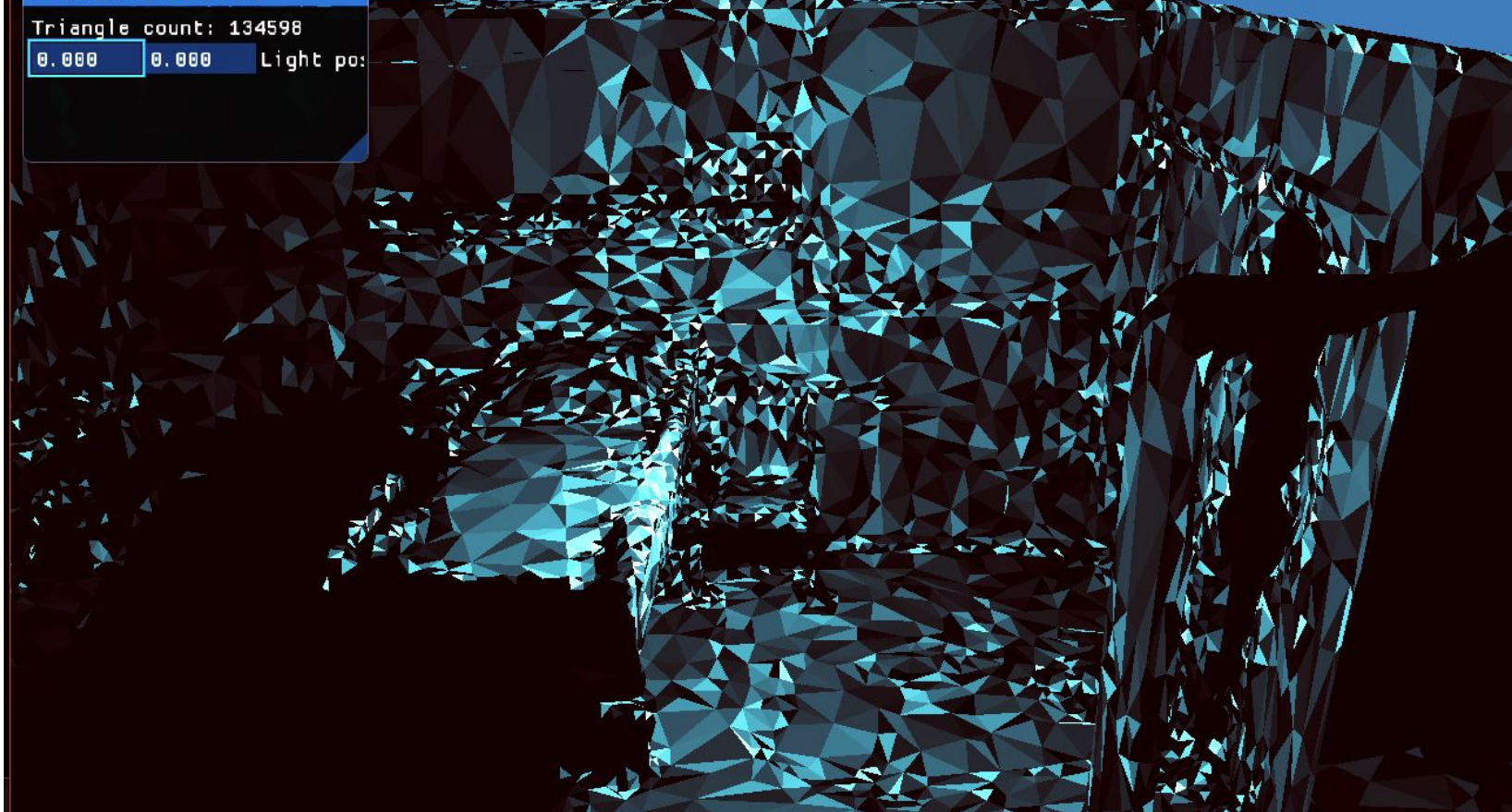


Implementation

Counting photons per triangle

- Rays/photons sent out from light source (vertical line) in all directions
- Count per triangle the number of hits
- Divide by area to get photon density
- Angle of light is automatically handled
- Same for inverse square law:
intensity decreases in proportion
to square distance
- Smaller triangles are more noisy





A low photon count results in inaccuracies at smaller triangles, luckily the use of a BVH acceleration structure allows for shooting a large enough number of photons

Implementation

- Computing irradiance & dose
- Within a few seconds on the GPU:
Generating rays, computing intersections,
then applying formula & mapping to colors

$$D = \frac{I * \sum_{l=0}^L (\Delta t_l * n_l)}{A * \frac{N}{L}} * 0.1$$

where I [W] is the intensity of the light source, L is the number of light positions, n_l is the number of photons received by the triangle from light position l , Δt_l is the time duration per light position, A [m²] is the surface area of the triangle, and N is the total number of photons. The fraction is multiplied by 0.1 to convert from Jm^{-2} to $mJcm^{-2}$.



Limitations / (Possible) Sources of Inaccuracy

- Mesh accuracy
- Number of photons
- Lamp is approximated as vertical line
- User entered parameters
- Lamp movement is ignored
- Air and surface conditions are (somewhat) ignored
- Reflections are ignored
- Lamp needs 2 minute warm up



Additional Future work

- More advanced calibration & validation
- Optimisation of disinfection strategy

