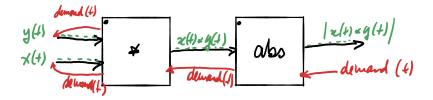
# Compiling Faust with Ondemand (https://github.com/orlarey/ondemand-ifc22-slides/blob/master/slides.pdf)

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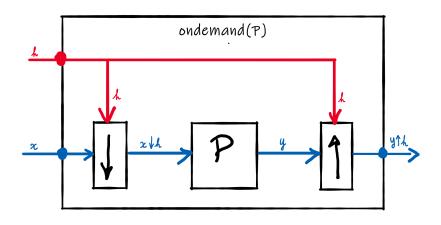


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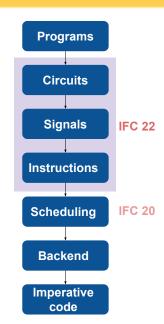
# Ondemand: Traditional Approach



# Ondemand: Faust Approach



### The Faust Compiler



### Faust Circuits as Formal Expressions

Faust circuits (evaluated Faust programs) are defined recursively by the following grammar:

#### Circuits Definition

```
\begin{split} C \in \mathbb{C} ::= & k \mid u \mid \star \mid @ \mid ! \mid \bot \\ & \mid C_1 : C_2 \mid C_1, C_2 \\ & \mid C_1 <: C_2 \mid C_1 :> C_2 \\ & \mid C_1 \sim C_2 \mid \mathrm{od}(C) \end{split}
```

#### **Primitives**

- k numbers (integer or real);
- *u* user interface elements (sliders, buttons, etc.);
- ★ any numerical operation;
- @ the delay operation;
- \_ underscore, the identity circuit (a perfect cable);
- ! cut, the termination circuit.

### Faust Circuits as Formal Expressions

#### Circuits Composition

- $C_1 <: C_2$  split composition, the outputs of  $C_1$  are distributed over the inputs of  $C_2$ ;
- ullet  $C_1:>C_2$  merge composition, the outputs of  $C_1$  are summed to form the inputs of  $C_2$ ;
- $C_1: C_2$  sequential composition, the outputs of  $C_1$  are propagated to the inputs of  $C_2$ ;
- $C_1, C_2$  parallel composition, the inputs are those of  $C_1$  and  $C_2$  and so are the outputs;
- $C_1 \sim C_2$  recursive composition, the outputs of  $C_1$  are fed back to the inputs of  $C_2$  and vice versa;
- $\bullet$  od(C) ondemand version of C.

### Well Formed Circuits

#### Number of Inputs and Outputs

$$(\operatorname{seq}) \cfrac{\operatorname{io} \llbracket C_1 \rrbracket : m \to n \quad \operatorname{io} \llbracket C_2 \rrbracket : n \to p}{\operatorname{io} \llbracket C_1 \rrbracket : m \to n \quad \operatorname{io} \llbracket C_2 \rrbracket : p \to q}$$
 
$$(\operatorname{par}) \cfrac{\operatorname{io} \llbracket C_1 \rrbracket : m \to n \quad \operatorname{io} \llbracket C_2 \rrbracket : p \to q}{\operatorname{io} \llbracket C_1 \rrbracket : m \to n \quad \operatorname{io} \llbracket C_2 \rrbracket : n.k \to p}$$
 
$$(\operatorname{split}) \cfrac{\operatorname{io} \llbracket C_1 \rrbracket : m \to n \quad \operatorname{io} \llbracket C_2 \rrbracket : n.k \to p}{\operatorname{io} \llbracket C_1 \rrbracket : m \to k.n \quad \operatorname{io} \llbracket C_2 \rrbracket : n \to p}$$
 
$$(\operatorname{merge}) \cfrac{\operatorname{io} \llbracket C_1 \rrbracket : m \to k.n \quad \operatorname{io} \llbracket C_2 \rrbracket : n \to p}{\operatorname{io} \llbracket C_1 \rrbracket : r + n \to q + m \quad \operatorname{io} \llbracket C_2 \rrbracket : q \to r}$$
 
$$(\operatorname{rec}) \cfrac{\operatorname{io} \llbracket C_1 \rrbracket : r + n \to q + m \quad \operatorname{io} \llbracket C_2 \rrbracket : n \to q + m}{\operatorname{io} \llbracket C_1 \rrbracket : m \to n}$$
 
$$(\operatorname{od}) \cfrac{\operatorname{io} \llbracket C \rrbracket : m \to n}{\operatorname{io} \llbracket \operatorname{od} (C) \rrbracket : m \to n}$$

### Semantics of Well Formed Circuits

### Signal Processor Semantics

An audio circuit  $C\in\mathbb{C}$  denotes to a signal processor  $[\![C]\!]\in\mathbb{P}=\mathbb{S}^n\to\mathbb{S}^m$  that takes input signals and produces output signals.

#### Notation

- $(S_1,...,S_n)$  a tuple of signals,
- () the empty tuple and
- $(S_1,...,S_n,**k)$  an n\*k tuple  $(S_1,...,S_n,S_1,...,S_n,...)$  obtained by concatenating k times the tuple  $(S_1,...,S_n)$ .

# Primitives Semantics (1)

#### Constant

A number k denotes an elementary circuit with no input, that produces a constant signal k.

$$(\mathsf{num}) \overline{\hspace{0.1cm} [\![ k ]\!] () = (k)}$$

#### Control

A user interface element u denotes an elementary circuit with no input and one output, the signal u produced by the user interface element.

$$(\mathsf{ctrl}) \overline{\hspace{0.1in} [\![ u ]\!]() = (u)}$$

# Primitives Semantics (2)

#### Numeric operation

The  $\star$  symbol denotes a *generic* numerical operation on signals. It represents a circuit with n inputs (typically 1 or 2 depending on the nature of the operation) and one output.

$$(\mathsf{nop}) \overline{\hspace{0.2in} \llbracket \star \rrbracket (S_1, S_2, \ldots) = (\star (S_1, S_2, \ldots))}$$

#### Delay

A delay primitive @ denotes a circuit with two inputs and one output.

# Primitives Semantics (3)

#### Cable

The cable has one input and one output.

$$\begin{array}{c} \text{(cable)} \\ \hline & \text{[\![\_]\!]}(S) = (S) \end{array}$$

#### Cut

The cut has one input and no output.

$$(\operatorname{cut}) \overline{\quad [\![!]\!](S) = ()}$$

# Circuit Compositions Semantics (1)

#### Sequential Composition Semantics

$$\begin{split} & & & \mathbb{ [ } [C_1] \mathbb{ [ } (S_1,...,S_n) = (Y_1,...,Y_m) \\ & & & \mathbb{ [ } [C_2] \mathbb{ [ } (Y_1,...,Y_m) = (Z_1,...,Z_p) \\ & & & \mathbb{ [ } [C_1:C_2] \mathbb{ [ } (S_1,...,S_n) = (Z_1,...,Z_p) \end{split}$$

#### Parallel Composition Semantics

$$\begin{split} & & & \mathbb{[\![}C_1\mathbb{]\!]}(S_1,...,S_n) = (U_1,...,U_m) \\ & & & & \mathbb{[\![}C_2\mathbb{]\!]}(Y_1,...,Y_p) = (V_1,...,V_q) \\ & & & & \mathbb{[\![}C_1,C_2\mathbb{]\!]}(S_1,...,S_n,Y_1,...,Y_p) = (U_1,...,U_m,V_1,...,V_q) \end{split}$$

# Circuit Compositions Semantics (2)

#### Split Composition Semantics

$$\begin{split} & & [\![C_1]\!](S_1,...,S_n) = (Y_1,...,Y_m) \\ & & [\![C_2]\!](Y_1,...,Y_m,**k) = (Z_1,...,Z_p) \\ & & & [\![C_1]\!](S_1,...,S_n) = (Z_1,...,Z_p) \end{split}$$

#### Merge Composition Semantics

$$\text{(merge)} \frac{ \begin{bmatrix} \mathbb{C}_1 \end{bmatrix} (S_1,...,S_n) = (Y_{1,1},...,Y_{1,m},...,Y_{k,1,},...,Y_{k,m}) \\ & \mathbb{[}C_2 \end{bmatrix} (Y_{1,1}+...+Y_{k,1},...,Y_{1,m}+...+Y_{k,m}) = (Z_1,...,Z_p) \\ & \mathbb{[}C_1 :> C_2 \end{bmatrix} (S_1,...,S_n) = (Z_1,...,Z_p)$$

# Circuit Compositions Semantics (3)

#### Recursive Composition Semantics

$$W = \text{fresh recursive symbol} \\ [\![C_2]\!](W_1@1,...,W_q@1) = (Z_1,...,Z_r) \\ (\text{rec}) \\ \hline [\![C_1]\!](Z_1,...,Z_r,S_1,...,S_n) = (Y_1,...,Y_q,Y_{q+1},...,Y_{q+m}) \\ \hline [\![C_1\sim C_2]\!](S_1,...,S_n) = (Y_1,...,Y_q,Y_{q+1},...,Y_{q+m}) \\ \text{with def}[\![W]\!] = (Y_1,...,Y_q).$$

### **Ondemand Semantics**

#### Ondemand

$$(\operatorname{od}) \frac{[\![C]\!](S_1 \!\downarrow\! H, ..., S_n \!\downarrow\! H) = (Y_1, ..., Y_m)}{[\![\operatorname{od}(C)]\!](H, S_1, ..., S_n) = (Y_1 \!\uparrow\! H, ..., Y_m \!\uparrow\! H)}$$

### Faust Signals as Formal Expressions

Faust signals are defined by the following grammar:

$$S \in \mathbb{S} ::= k \mid u \mid \mathbf{I}_c \mid X_i \mid \star(S_1, S_2, ...) \mid S_1 @ S_2 \mid S_1 \downarrow S_2 \mid S_1 \uparrow S_2$$

- k is a number (integer or real)
- ullet u is a user interface element (slider, button, etc.)
- ullet I is the input channel c
- $\star(S_1, S_2, ...)$  is a numerical operation on signals
- $ullet X_i$ : is the i-th signal of a group of mutually recursive signals associated to symbol X
- ullet  $S_1@S_2$  is  $S_1$  delayed by  $S_2$
- $S_1 \downarrow S_2$  is  $S_1$  downsampled by  $S_2$
- $S_1 \uparrow S_2$  is  $S_1$  up-sampled by  $S_2$ .

### The semantics of Faust Signals as a function of time

A Faust signal  $S \in \mathbb{S}$  denotes a function of time, notated  $[S]: \mathbb{Z} \to \mathbb{R}$ . The value of this function at time t is notated [S](t).

By definition in Faust, the value of any signal before time 0 is always 0. Therefore we have:

$$\forall S \in \mathbb{S}, \forall t < 0, [S](t) = 0$$

# The semantics of Faust Signals as a function of time

#### For $t \ge 0$ we have:

- $\bullet \ \llbracket k \rrbracket(t) = k$
- $[\![u]\!](t) = \text{value of the user interface controller } u$  at time t
- $[\![\mathbf{I}_c]\!](t) = \text{value of the audio input channel } c \text{ at time } t$
- $[\![X_i]\!](t) = [\![S_i]\!](t)$  with definitions  $\mathsf{def}[\![X]\!] = (S_1,..,S_i,..,S_n)$
- $[\![\star(S_1, S_2, \dots)]\!](t) = \star([\![S_1]\!](t), [\![S_2]\!](t), \dots)$
- $\bullet \ [S_1@S_2](t) = [S_1](t [S_2](t))$
- $[S_1 \downarrow S_2](t) = [S_1](\text{down}[S_2](t))$
- $\bullet \ [\![S_1 \!\uparrow\! S_2]\!](t) = [\![S_1]\!](\mathsf{up}[\![S_2]\!](t))$

# Signal Downsampling

 $S_1 \downarrow S_2$  is the downsampling of  $S_1$ , based on the clock signal  $S_2$ .

$S_1$	$S_2$	$S_1 \downarrow S_2$	$down \llbracket S_2 \rrbracket$
a	1	а	0
b	0		
С	0		
d	1	d	3
f	1	f	4
g	0		

Table 1: Example of downsampling

$$(\mathsf{down}) \quad \frac{\mathsf{down}[\![S_2]\!] = \{n \in \mathbb{N} \mid [\![S_2]\!](n) = 1\}}{[\![S_1\rfloor\!] \cup S_2]\!](t) = [\![S_1]\!](\mathsf{down}[\![S_2]\!](t))}$$

# Signal Upsampling

 $S_1 \uparrow S_2$  is the upsampling of  $S_1$  according to clock signal  $S_2$ .

$\overline{S_1}$	$S_2$	$S_1 \uparrow S_2$	$up\llbracket S_2  rbracket$
a	1	a	0
d	0	a	0
f	0	a	0
	1	d	1
	1	f	2
	0	f	2

Table 2: Example of upsampling

$$(\operatorname{up}) - \frac{\operatorname{up}[\![S_2]\!](t) = \sum_{i=0}^t [\![S_2]\!](i) - 1}{[\![S_1 \!\uparrow\! S_2]\!](t) = [\![S_1]\!](\operatorname{up}[\![S_2]\!](t))}$$

# Memory Signals

Memory signals are like signals seen before, but using *memory references* to implement delay lines, recursions, and sharing of common subexpressions. During the compilation signals are translated to *memory signals*.

#### Definition

$$M \in \mathbb{M} ::= k \mid u \mid I_c \mid \star(M_1, M_2, ...) \mid t \mid m \mid v[M_1, M_2]$$

#### Where

- k is a number (integer or real)
- u is a user interface element (slider, button, etc.)
- I<sub>c</sub> is the input channel c
- $\star(M_1, M_2, ...)$  is a numerical operation on signals
- t: is a scalar memory reference corresponding to the current time
- m: is a scalar memory reference corresponding to a signal
- $v[M_1, M_2]$  is a vector memory reference where  $M_1$  is the time and  $M_2$  the delay.

### Instructions

An *instruction* is an intermediate representation, of type SSA, for signals.

#### Definition

$$\begin{split} I \in \mathbb{I} ::= & T \vdash d {:=} M \\ & \mid T \vdash v[M_1, M_2] {:=} M_3 \\ & \mid T \vdash t {:=} t + 1 \end{split}$$

#### Where

- T is a time reference indicates when this instruction must be executed;
- ullet d and v are memory references;
- M is a signal in memory that is computed;
- ullet is a memory reference for the current value of the time reference.

### Time reference

A *time reference* is a non empty list of clock signals that indicates when an instruction should be executed.

#### Definition

$$T \in \mathbb{T} ::= 1 \mid S.T$$

#### Where

- $S \in \mathbb{M}$  is a clock signal  $S : \mathbb{Z} \to \{0, 1\}$
- 1 is the top level clock signal (execution every sample)

### Memory Destinations

A memory destination indicates where the writing of the result should take place. This can be an output buffer, a scalar variable, or a vector in the case of delay lines for example.

#### **Definition**

$$D \in \mathbb{D} ::= \mathbf{0}_n \mid t \mid m \mid v[M, M]$$

where  $\mathbf{O}_n$  represents the audio buffer of the nth output channel, t, m and v are identifiers allocated at compile time.

### Identifiers and Marking

#### Fresh identifier representing memory locations

- $id_s[S.T] = m$  unique scalar identifier for S in time context T;
- $\bullet$  id<sub>v</sub>[[S.T]] = v unique vector identifier for S in time context T ;
- $id_t[T] = t$  unique scalar identifier representing the current time in time context T.

### Marking recursive definitions

- $mark[Xi.T] = \varnothing$ : not yet marked;
- $\max \|Xi.T\| \leftarrow v$ : mark it with identifier v;
- ullet mark $[\![Xi.T]\!]=v$ : already marked with v.

Function cs[[.]] :  $\mathbb{S} \times \mathbb{T} \to \mathbb{M} \times \mathcal{P}(\mathbb{I})$ 

Number

$$(\text{num}) \overline{ \quad \text{cs} \llbracket k.T \rrbracket = k \times \varnothing }$$

User interface

$$(\mathsf{ctrl}) \overline{\hspace{0.2cm}} \mathsf{cs} \llbracket u.T \rrbracket = u \times \varnothing$$

Inputs

$$\begin{array}{c} \text{(input)} \\ \hline \quad \text{cs} \llbracket \mathbf{I}_c.T \rrbracket = \mathbf{I}_c \times \varnothing \end{array}$$

### **Numerical Operation**

$$\begin{split} \operatorname{cs}[\![S_1.T]\!] &= M_1 \times J_1 \\ \operatorname{cs}[\![S_2.T]\!] &= M_1 \times J_2 \\ &\vdots \\ \operatorname{id}_{\mathsf{V}}[\![\star(M_1,M_2,\ldots)]\!] &= m \\ \\ (\operatorname{nop}) & \overline{ \text{ cs}[\![\star(S_1,S_2,\ldots).T]\!] = m \times \{T \vdash m := \star (M_1,M_2,\ldots)\} \bigcup_i J_i } \end{split}$$

#### Downsampling

The downsampling  $S_1 \downarrow S_2$  appears at the entrance of an ondemand. This means that compiling  $S_1 \downarrow S_2$  into the  $M_2.T$  time environment (where  $M_2$  is the compiled version of  $S_2$ ) is like compiling  $S_1$  into the T time environment and using a variable to do the downsampling.

$$\begin{split} \operatorname{cs}[\![S_1.T]\!] &= M_1 \times J_1 \\ \operatorname{cs}[\![S_2.T]\!] &= M_2 \times J_2 \\ \operatorname{id}_{\operatorname{s}}[\![M_1.T]\!] &= m \\ J_3 &= \{T \vdash m {:=} M_1\} \\ \hline \operatorname{cs}[\![(S_1 {\downarrow} S_2).M_2.T]\!] &= m \times J_3 \cup J_1 \cup J_2 \end{split}$$

### Upsampling

The  $S_1 \uparrow S_2$  upsampling appears at the output of an ondemand. It is necessary to compile  $S_1$  into the clock time reference  $S_2$  (which is added to the current time reference). The signal  $S_1$  must also be stored in a variable to do the upsampling.

$$\begin{split} \cos[\![S_2.T]\!] &= M_2 \times J_2 \\ \cos[\![S_1.M_2.T]\!] &= M_1 \times J_1 \\ \operatorname{id}_{\mathbf{S}}[\![M_1.M_2.T]\!] &= m \\ J_3 &= \{M_2.T \vdash m {:=} M_1\} \\ \hline \cos[\![(S_1 {\uparrow} S_2).T]\!] &= m \times J_1 \cup J_1 \cup J_2 \\ \end{split}$$

#### Delay

### Signal Compilation: recursion

#### First visit

If it is the first visit, we have  $\max[X_i.T] = 0$ :

```
\begin{split} \operatorname{id_v}[\![X_i.T]\!] &= v \\ \operatorname{mark}[\![X_i.T]\!] &\leftarrow v \\ \operatorname{def}[\![X]\!] &= (...,S_i,...) \\ \operatorname{cs}[\![S_i.T]\!] &= M_i \times J_i \\ \operatorname{cs}[\![S_d.T]\!] &= M_d \times J_d \\ \operatorname{id_t}[\![T]\!] &= t \\ (\operatorname{r1}) &\frac{J_3 = \{T \vdash v[t,0] {:=} M_i\} \cup \{T \vdash t {:=} t+1\}}{\operatorname{cs}[\![(X_i@S_d).T]\!] &= v[t,M_d] \times J_3 \cup J_i \cup J_d} \end{split}
```

# Signal Compilation: recursion

#### Next visits

If it is not the first visit, we have  $mark[X_i.T] = v$ :

$$\begin{split} \operatorname{cs}[\![S_d.T]\!] &= M_d \times J_d \\ \operatorname{id_t}[\![T]\!] &= t \\ \hline \operatorname{cs}[\![(X_i@S_d).T]\!] &= v[t,M_d] \times J_d \end{split}$$

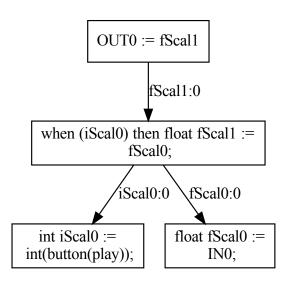
### Global compilation

```
\begin{split} \mathsf{Global} & \mathsf{comp}[\![.]\!] : \mathbb{S}^n \to \mathcal{P}(\mathbb{I}) \\ & \qquad \qquad \vdots \\ & \qquad \qquad \mathsf{cs}[\![S_i.1]\!] = M_i \times J_i \\ & \qquad \qquad J_i' = \{1 \vdash \mathsf{0}_i := M_i\} \cup J_i \\ & \qquad \qquad \vdots \\ & \qquad \qquad (\mathsf{comp}) \overline{\qquad \qquad } \vdots \\ & \qquad \qquad (\mathsf{comp}) \overline{\qquad \qquad } = \ldots \cup J_i' \cup \ldots \end{split}
```

# Example 1, block-diagram

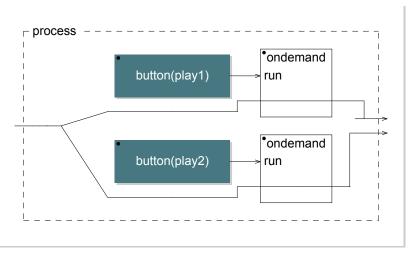
```
process = button("play"), _ : ondemand(_);
     process
                               ondemand
             button(play)
                              → run
```

### Example 1, instruction graph

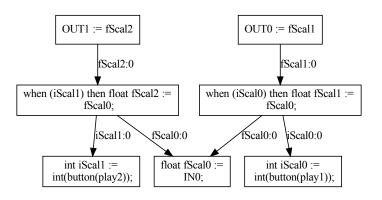


# Example 2, block-diagram

```
process = _ <: ondemand(_)(button("play1")), ondemand(_)(button(</pre>
```

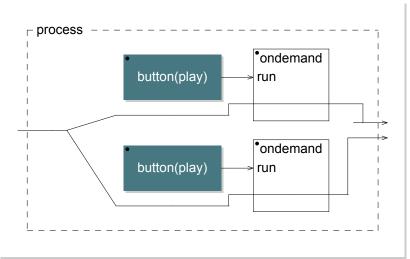


### Example 2, instruction graph

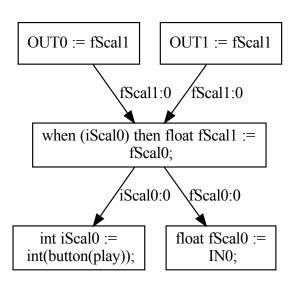


### Example 3, block-diagram

```
process = _ <: ondemand(_)(button("play")), ondemand(_)(button(")</pre>
```

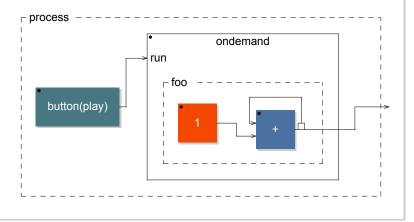


### Example 3, instruction graph

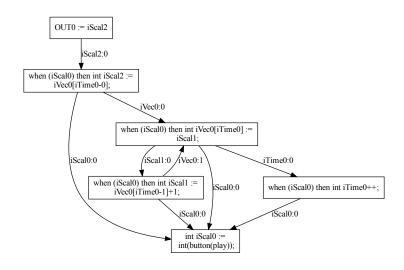


#### Example 4, block-diagram

```
foo = 1:+~_;
process = ondemand(foo)(button("play"));
```

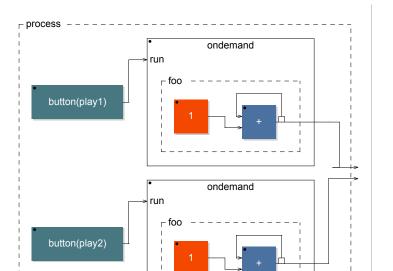


#### Example 4, instruction graph

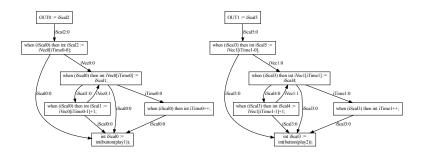


# Example 5, block-diagram

```
foo = 1:+~_;
process = ondemand(foo)(button("play1")), ondemand(foo)(button(")
```

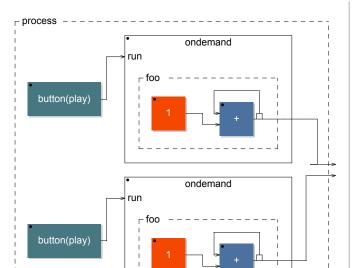


## Example 5, instruction graph

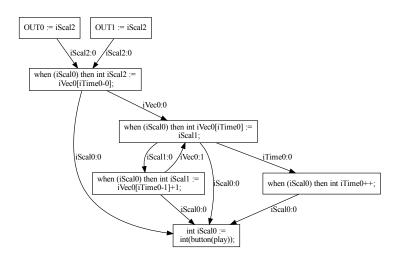


# Example 6, block-diagram

```
foo = 1:+~_;
process = ondemand(foo)(button("play")), ondemand(foo)(button("play"))
```

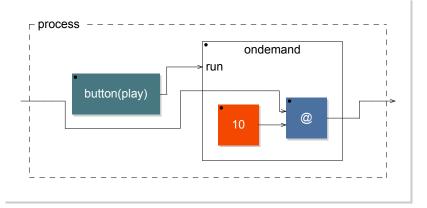


## Example 6, instruction graph

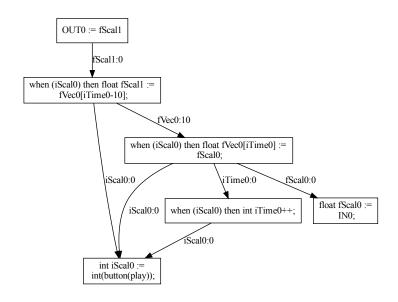


## Example 7, block-diagram

```
process = ondemand(@(10))(button("play"));
```

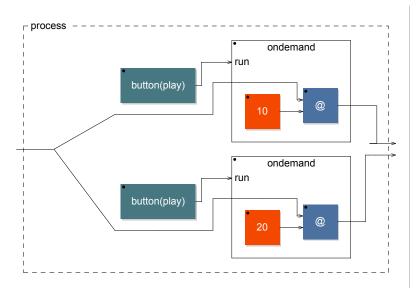


#### Example 7, instruction graph

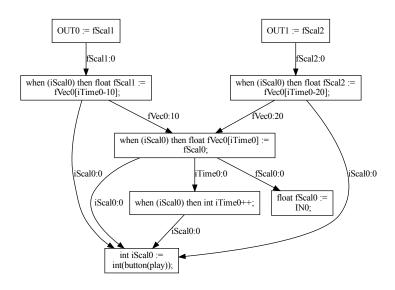


# Example 8, block-diagram

```
process = _ <: ondemand(@(10))(button("play")), ondemand(@(20))(</pre>
```



#### Example 8, instruction graph



#### Conclusion

#### What's missing?

- Several primitives like tables, waveforms, etc. are missing
- Replace current interval computation
- Proper C++ code generation
- Merge with dev branch
- Future extensions:
  - interleave(P)
  - upsample(N,P)
  - downsample(N,P)
  - modulation
- Code génération improvements:
  - Data Parallelism