```
Ch.2 Part 2
     Is global temp data from Example 1.2
     Stationary or non-stationary?
     While there are derications from a general
     upward thend of both land and sea temps
      from 1880 to 2017, the upward trend
     itself would indicate stationarity, but separate chunks of the timeline change, and especially the drastic uptick in
     the last 40 years would indicate a
     changing thend, indicating non-stationanty
     (or thend stationarity).
2.7 Periodic time series:
            Xt = Uisin(2πωοt) + Uz cos(2πωοτ)
       where U, II U2, rv's, means 0 & E(U,2) = E(U2) = 02
      constant as determines period of time to complete
      a cycle. Show that X+ is weakly stationary
     with acr function
             \gamma(h) = \sigma^2 \cos(2\pi\omega_0 h)
      Say \lambda = 2\pi\omega_0
    Y(h) = Y(h,h) = var(xh)
      by Y(h) = var (Uisin (2t) + Uzcos (2t))
            = cov [(U, sin (2h) + U2cos(2h)), (U, sin(2h) + U2cos(2h))]
       = cov [Uisin()th), Uisin()th)] + cov [Uisin()th), Uzcos (2th)]
           + cov [U2cos (2+), U1 sin (2+)] + cov [U2 cos(2+), U2cos (2+)]
       = \sigma^2 \sin^2(\chi h) + 0 + 0 + \sigma^2 \cos^2(\chi h)
        = \sigma^2 \left[ \sin^2(\lambda t_0) + \cos^2(\lambda t_0) \right]
        = \sigma^2 \cos(2\pi\omega_0 + \frac{1}{2})
     The series is weakly stationary because
       the ACV depends not on time to but on
      time difference Clag) h, making it
      thend, or weakly, stationary.
```

2.8 Consider 4t = Wt - OW+1 + Ut Wt, Ut are independent white hoise of \$000 and 0 is a constant @ Express ACF fy(h) for h=0, ±1, ±2, ... of y+ as a function of our, our, and o Py (h) = (7/0) $\hat{\chi}(h) = \frac{1}{2}(y_{t+h}, y_t) = cov(y_{t+h}, y_t)$ = cov & (Wt+n- Owt+n-1 + M++n), (W+ - OW+-1 + M+) } by (0) = cov & (w+ - Ow+ 1 + U+), (w+ - Ow+ 1 + U+)} = var (w+) + 8 2 var (w+-1) + var (u+) $= \sigma_{\alpha}^{2} + \theta^{2} \sigma_{\alpha}^{2} + \sigma_{\alpha}^{2} = \sigma_{\alpha}^{2} \left(1 + \theta^{2}\right) + \sigma_{\alpha}^{2}$ Ty(1) = Ty(-1) = COV {(W++1 - OW+ + U++1), (W+ - OW+-1 + U+)} =- 9 var(wt) = - 9 0 2 Jy(z) = Jy(-2) = COV { (We+z - DWE+1 + U++2), (WE-BUE-1 + 4+)} Ty(h) = (02(1+02)+02, h=0 1-00th, h= ±1 Py(h) = 7(h) Py(0)=1 Py (2) =0 $\rho_y(h) = \begin{cases} 1, & h=0 \\ \frac{-\theta\sigma_w^2}{\sigma_w^2(1+\theta^2)} + \sigma_w^2, & h=\pm 1 \end{cases}$

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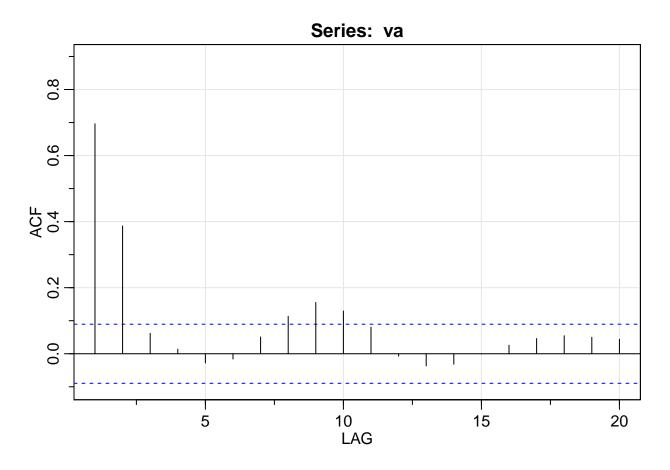
```
(2.8, continued)
OCF pxy (h) relating to Xt & yt
Xt= Wt
yt = \omega t - \theta \omega t + Ut
 f_{xy}(h) = f_{xy}(h) 
 f_{xy}(0) 
 Txy (h) = cov (Xt, yt) = cov { wt, wt - Owt + 4+3
 Txy (0) = cov { Wt, Wt - BW+1 + Ut }
         = Var(w_t) = \sigma_w^2
 Txy (1) = (0V {w+1, w+ - Ow+-1 + 4+3
        = -\theta \text{ var} (\omega_{t-1}) = -\theta \sigma_{t}^2
 Txy (2) = cov & Wt-2, Wt- But-1 + Ut3 = 0
     fxy(h)= \ oz, h=0
                \begin{cases} -0 \, \sigma_{\alpha}^{2}, & h = -1 \\ 0, & |h| > 1 \end{cases}
                   o_ , |h| >1
 Pry (h) = bxy(h) Notrostylos
 0, 14/>1
@ Show that xt and yt are jointly stationary
  Xt and yt are stationary if

fxy(h) = roxiosticy) is a function of honly
we have try(h) from 10, and see that
 it satisfies the negimenents of joint
Stationarity, Both of their fx, fx are
 stationary (no dependence on time),
and is only a function of lag h.
```

2.11

(a) Simulate a series of n=500 Gaussian white noise observations as in Example 1.7 and compute the sample ACF, p(h), to lag 20. Compare the sample ACF you obtain to the actual ACF, p(h). [Recall Example 2.17.]

```
wa = rnorm(500)
va = filter(wa, side = 2, filter = rep(1/3, 3))
acf1(va, 20)
```

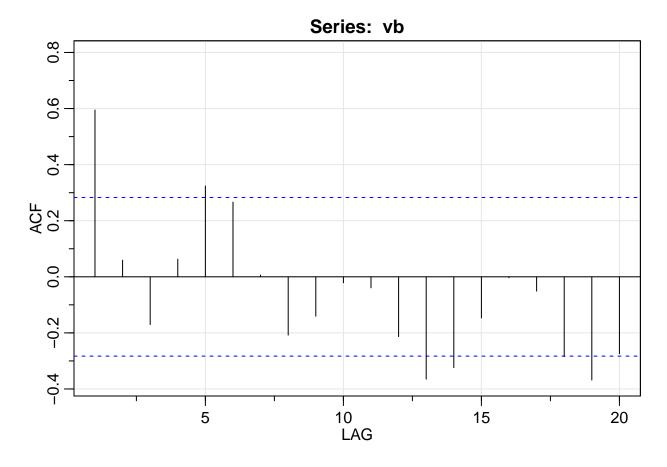


```
## [1] 0.70 0.39 0.06 0.01 -0.03 -0.02 0.05 0.11 0.16 0.13 0.08 -0.01 ## [13] -0.04 -0.03 0.00 0.03 0.05 0.05 0.04
```

Compare sample ACF and true ACF: Theoretically should be zero (actual ACF, calculated in the book), but some fluctuation around 0. Plotted, there are some residual values. Almost all spikes are within bounds so we can consider them white noise.

(b) Repeat part (a) using only n = 50. How does changing n affect the results?

```
wb = rnorm(50)
vb = filter(wb, side = 2, filter = rep(1/3, 3))
acf1(vb, 20)
```



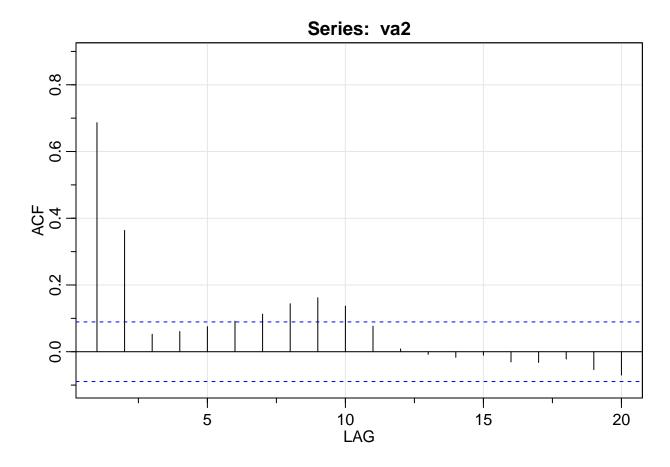
```
## [1] 0.59 0.06 -0.17 0.06 0.32 0.27 0.01 -0.21 -0.14 -0.02 -0.04 -0.21 ## [13] -0.37 -0.32 -0.15 0.00 -0.05 -0.28 -0.37 -0.27
```

This changes results: There is more variability because we have fewer observations, and we see a few more spikes beyond the bounds. We expect about 95% of observations to remain within the bounds.

2.12

(a) Simulate a series of n=500 moving average observations as in Example 1.8 and compute the sample ACF, p(h), to lag 20. Compare the sample ACF you obtain to the actual ACF, p(h). [Recall Example 2.18.]

```
wa2 = rnorm(502, 0, 1)
va2 = filter(wa2, rep(1/3, 3))
acf1(va2, 20)
```



```
## [1] 0.69 0.36 0.05 0.06 0.08 0.09 0.11 0.14 0.16 0.14 0.08 0.01 ## [13] -0.01 -0.02 -0.01 -0.03 -0.03 -0.02 -0.05 -0.07
```

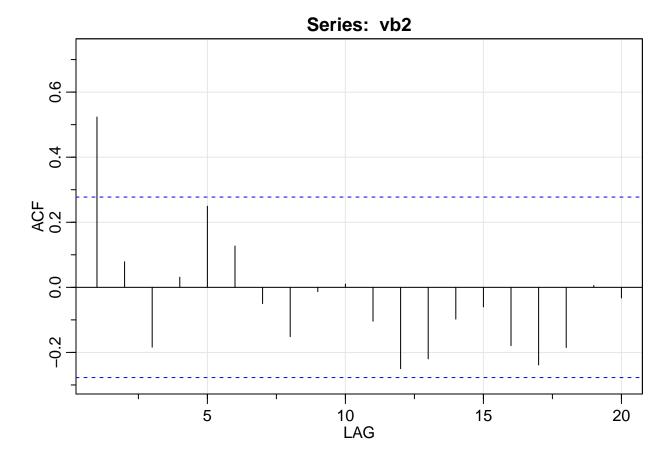
There are only two spikes beyond the bounds, at 1 and 2, otherwise they are within the bounds, whereas our actual ACF will be zero.

(b) Repeat part (a) using only n = 50. How does changing n affect the results?

```
wb2 = rnorm(52, 0, 1)

vb2 = filter(wb2, rep(1/3, 3))

acf1(vb2, 20)
```



```
## [1] 0.52 0.08 -0.18 0.03 0.25 0.13 -0.05 -0.15 -0.01 0.01 -0.10 -0.25 ## [13] -0.22 -0.10 -0.06 -0.18 -0.24 -0.18 0.01 -0.03
```

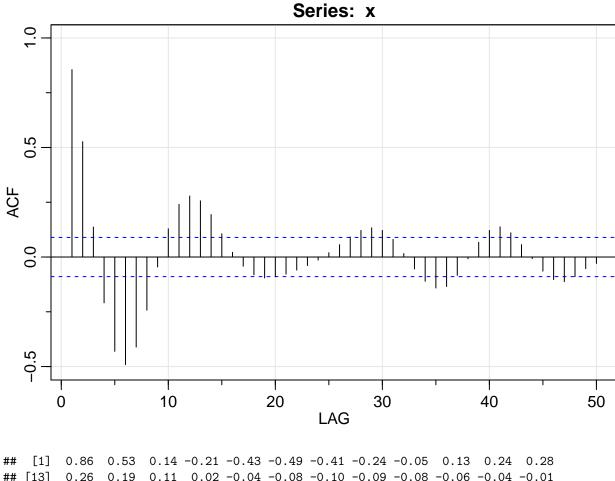
This changes the results: There is less variability with fewer observations generated, but we still have most observations within bounds leading our sample ACF to be approximately equal to the actual ACF.

2.13

Simulate 500 observations from the AR model specified in Example 1.9 and then plot the sample ACF to lag 50. What does the sample ACF tell you about the approximate cyclic behavior of the data? Hint: Recall Example 2.32.

```
xt = 1.5xt-1 - .75-x2 + wt
```

```
set.seed(90210)
w = rnorm(500 + 50)
x = filter(w, filter = c(1.5, -.75), method = "recursive")[-(1:50)]
acf1(x, 50)
```



```
## [1] 0.86 0.53 0.14 -0.21 -0.43 -0.49 -0.41 -0.24 -0.05 0.13 0.24 0.28

## [13] 0.26 0.19 0.11 0.02 -0.04 -0.08 -0.10 -0.09 -0.08 -0.06 -0.04 -0.01

## [25] 0.02 0.06 0.09 0.12 0.13 0.12 0.08 0.02 -0.05 -0.11 -0.14 -0.13

## [37] -0.08 -0.01 0.07 0.12 0.14 0.11 0.06 -0.01 -0.06 -0.10 -0.11 -0.09

## [49] -0.05 -0.03
```

The sample ACF of the generated data with lag 50 shows cyclical behavior about every 10 units, with a positive autocorrelation exhibited on 5 units and negative autocorrelation every 5 units in a cyclical manner.

```
2.15 For ye in Ey 2.29 (y_{t} = 5 + \chi_{t} - .5\chi_{t-1})

verify stated result that
f_{y(1)} = .4
and f_{y(h)} = 0 for h > 1
f_{y(h)} = \frac{f_{y(0)}}{f_{y(0)}}
f_{y(h)} = \frac{f_{y(0)}}{f_{y(0)}}
f_{y(h)} = \frac{f_{y(0)}}{f_{y(0)}}
f(0) = cov(y_{t}, y_{t}) = var(y_{t})
= var(x_{t}) + .25 var(x_{t-1})
= (1 + .25) \sigma^{2}
f(1) = cov(y_{t+1}, y_{t}) = cov_{x}^{2}(x_{t+1} - .5x_{t}), (x_{t} - .5x_{t-1})_{x}^{2}
= -.5 var(x_{t}) = -.5\sigma^{2}
f(2) = cov_{x}^{2}(x_{t+2} - .5x_{t+1}), (x_{t} - .5x_{t-1})_{x}^{2} = 0
50 \quad f_{y(1)} = -.5(1 + .25) = -.4
and f_{y(h)} = 0 for h > 1
```