

# Filters Sheet - Omar Rashad Salem

## Task 1

answers :

- a ) blurs the image
- b ) sharpens the image
- c ) detects edges

```
In [1]: import cv2 ; import numpy as np ; import matplotlib.pyplot as plt
org = cv2.imread( "man.png" , cv2.IMREAD_GRAYSCALE)

# a) box blur kernel 3x3
a_image = org.copy()
a_kernel = np.full((3,3) , 1/9 , dtype= float )

a_image = cv2.filter2D ( a_image , -1 , a_kernel ) # -1 is to ouput same source image pixel depth

# b) sharpen kernel 3x3
b_image = org.copy()
b_kernel = np.array([[0 , -1 , 0],
                     [-1 , 5 , -1],
                     [0 , -1 , 0]])
b_image = cv2.filter2D( b_image , -1 , b_kernel)

#c) edge detection kernel 3x3
c_image = org.copy()
c_kernel = np.array([[-1 , -1 , -1],
                     [-1 , 8 , -1],
                     [-1 , -1 , -1]])
c_image = cv2.filter2D ( c_image , -1 , c_kernel )

show all images
titles = ['original','a) box blur ','b) sharpen ' , 'c) edge detection ' ]
images = [org , a_image , b_image , c_image]
for i in range(4) :
    plt.subplot(4,4,i+1) # row columns index
    plt.imshow(images[i],"gray",vmin = 0, vmax = 255)
    plt.title(titles[i])
    plt.xticks([])
    plt.yticks([])

plt.xticks([])
plt.yticks([])

# cv2.waitKey(0)
# cv2.destroyAllWindows
```

Out[1]: ([], [])



## Task 2

answers :

- a ) it's a Difference filter

b ) min = (-255 -(2255) - (2 255)) = -1275 => ( 0 intensity pure black ) max = 1275 => ( 255 intensity pure white pixel)

c ) corelation result will be the kernel values in center but fliped 180 degrees (anti c.w) and serrounded with black pixels (zero intensity)

**EXTRA : if convolution was done between impulse and the kernel, result will be exact same kernel in center.**

d) yes : because convolving flips the kernel before applying the summation formula. so the difference filter result will be sharpened and inverted.

- e) not an isotropic filter

```
In [2]: #TASK 2 : a

import cv2 ; import numpy as np ; import matplotlib.pyplot as plt
from scipy.ndimage import rotate
```

```
org = cv2.imread( "man.png" , cv2.IMREAD_GRAYSCALE)
# cv2.imshow("original" , org )
```

```
cpy = org.copy()
```

```
kernel = np.array ([[ -1 , -2 , 0] , [-2 , 0 , 2], [0 , 2 , 1]])
```

```
cpy = cv2.filter2D(cpy , -1 , kernel)
```

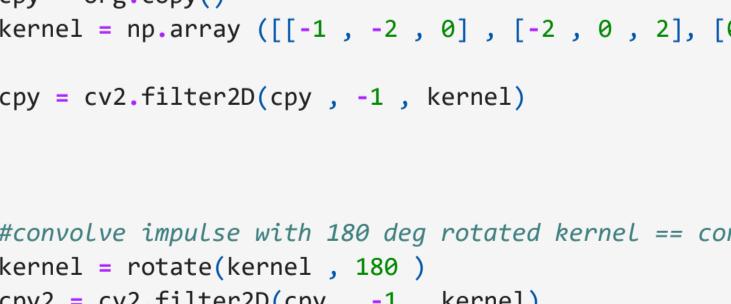
```
plt.imshow(cpy,"gray")
```

```
plt.xticks([])
```

```
plt.yticks([])
```

```
# cv2.waitKey(0)
```

Out[2]: ([], [])



```
In [3]: # TASK 2 : C
```

```
import cv2 ; import numpy as np ; import matplotlib.pyplot as plt
from scipy.ndimage import rotate
```

```
#make impulse signal
```

```
org = np.zeros((510,510) , dtype = np.uint8)
```

```
org[255 , 255] = 255
```

```
cv2.imshow("original" , org )
```

```
cpy = org.copy()
```

```
kernel = np.array ([[ -1 , -2 , 0] , [-2 , 0 , 2], [0 , 2 , 1]])
```

```
#convolve impulse with 180 deg rotated kernel == correlation
```

```
kernel = rotate(kernel , 180 )
```

```
cpy = cv2.filter2D(cpy , -1 , kernel)
```

```
cv2.imshow( "Task 2 - c " , cpy )
```

```
cv2.waitKey(0)
```

Out[3]: -1

```
In [1]: #TASK 2 : d
```

```
import cv2 ; import numpy as np ; import matplotlib.pyplot as plt
from scipy.ndimage import rotate
```

```
org = cv2.imread( "man.png" , cv2.IMREAD_GRAYSCALE)
```

```
cpy = org.copy()
```

```
kernel = np.array ([[ -1 , -2 , 0] , [-2 , 0 , 2], [0 , 2 , 1]])
```

```
cpy = cv2.filter2D(cpy , -1 , kernel)
```

```
#convolve impulse with 180 deg rotated kernel == correlation
```

```
kernel = rotate(kernel , 180 )
```

```
cpy2 = cv2.filter2D(cpy , -1 , kernel)
```

```
cv2.imshow("conv" , cpy)
```

```
cv2.imshow( 'core' , cpy2)
```

```
# titles = ['original',' convolve' , 'correlate ']
```

```
# images = [org , cpy , cpy2]
```

```
# for i in range(3) :
```

```
# plt.subplot(4,4,i+1) # row columns index
```

```
# plt.imshow(images[i] , 'gray')
```

```
# plt.title(titles[i])
```

```
# plt.xticks([])
```

```
# plt.yticks([])
```

The Kernel crashed while executing code in the the current cell or a previous cell. Please review the code in the cell(s) to identify a possible cause of the failure. Click [here](https://aka.ms/vscodeJupyterKernelCrash) for more info. View Jupyter [log](command:jupyter.viewOutput) for further detail.

## Task 3

answer : the box filter ( uniform weight smoothing filter)

## Task 4

answer : because it removes the intensity spikes in pixels.

**END OF SHEET 4**