

Microcontroller Music Player

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Objectives

- Demonstrate fundamental knowledge of RC circuits
- Show utilization of RS-Flip Flops to denote choice
- Use of Oscilloscope and DMM to capture data
- Predicting and scaling expectations to be proper to goal
- Using correct units and format for graphs and tables



Introduction

- Project is culmination of learning so far
- Voted to create a Microcontroller Music Player
 - Expectation: proper challenge and complexity for us
 - Turned out to be great challenge and beyond course scope
- Focused on hardware aspect utilizing current amplifier
- Software aspect utilized tones and duration to create songs



Introduction - Utilized parts and Circuits

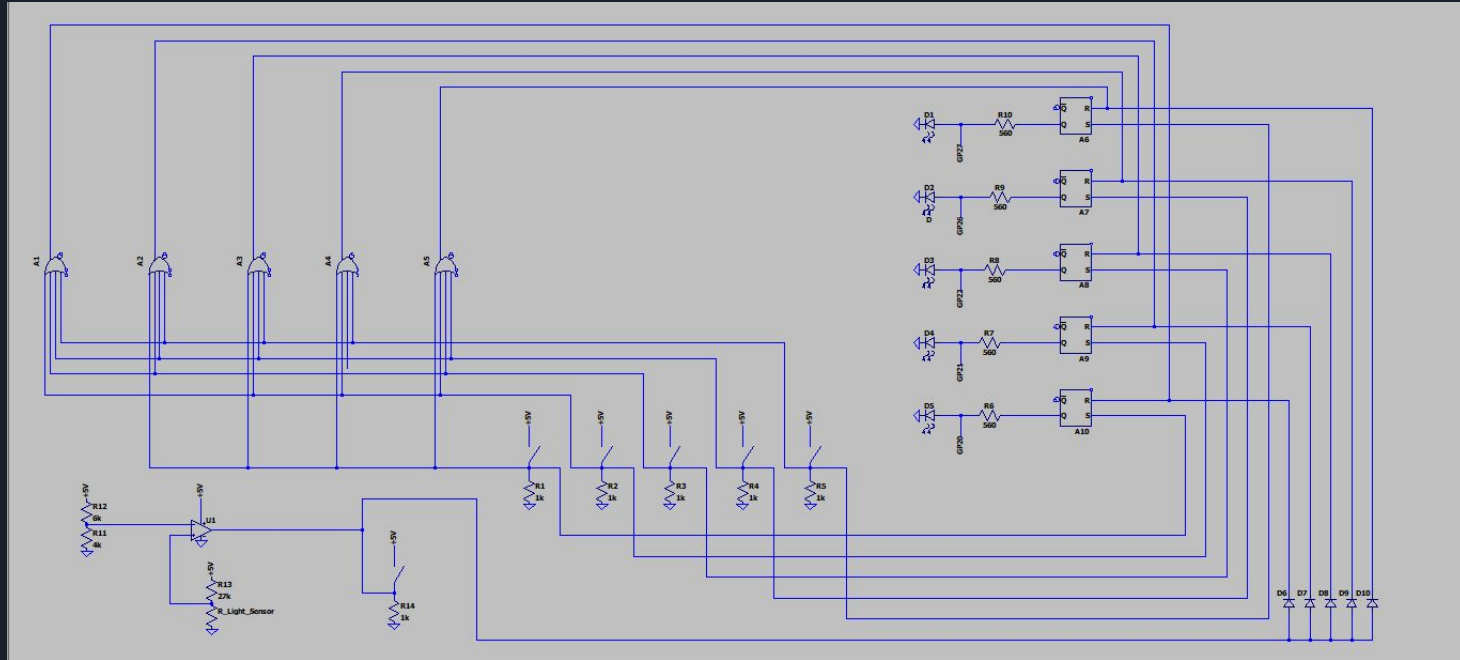
- Parts include:
 - 8 Buttons
 - 10 NOR-Gates
 - 5 LEDs
 - 25 Diodes
 - 1 LM386 Current Amplifier
 - Raspberry pi pico
 - 7-segment display
 - LDR
 - LM324
 - Various resistors
 - Various Capacitors



Requirements

- Requirements include:
 - Being battery powered (Objective: 3 days)
 - Storing several songs (in .wav format) (Objective: 9 songs)
 - Changing the volume based on gain
 - Play music through a speaker
 - Using a bandpass filter to filter background noise
 - Objective: -40 dB/decade

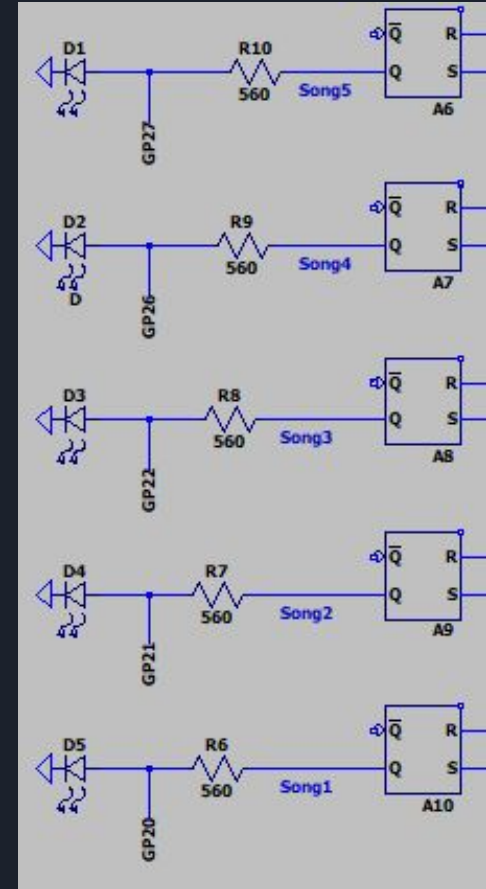
Circuit Operation - Song Selection System



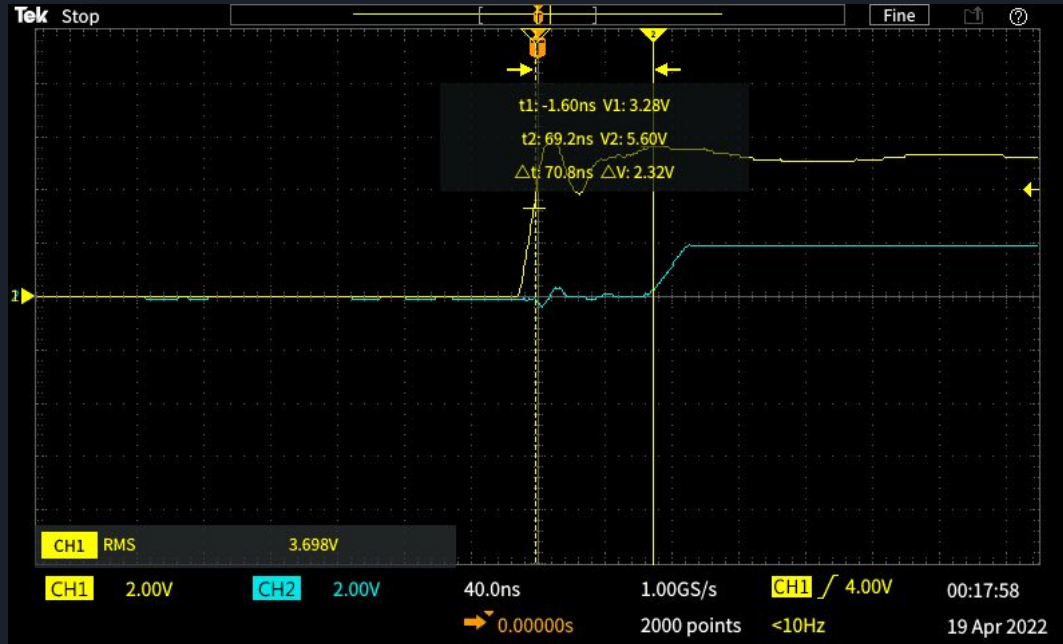
- SR Flip-Flops control various LEDs and interact with the microcontroller, which indicates what song should be playing
- Used CD4001 NOR gates to construct SR Flip-Flops
- Selection buttons used to set/reset various SR Flip-Flops
- OR gates constructed from multiple diodes
- Reset button implemented
- LDR reset implemented also

Microcontroller Inputs

- Each SR Flip-Flop used to “represent” a song
 - Song1: “Twinkle Twinkle Little Star”
 - Song2: “D*mned”
 - Song3: “Let It Be”
 - Song4: “Hedwig's Theme”
 - Song5: “Happy Birthday”
- 560 ohm resistors utilized to prevent LED burnout
- Voltage at a logic high microcontroller input measured to be approximately 2 Volts
- Zener diodes were considered

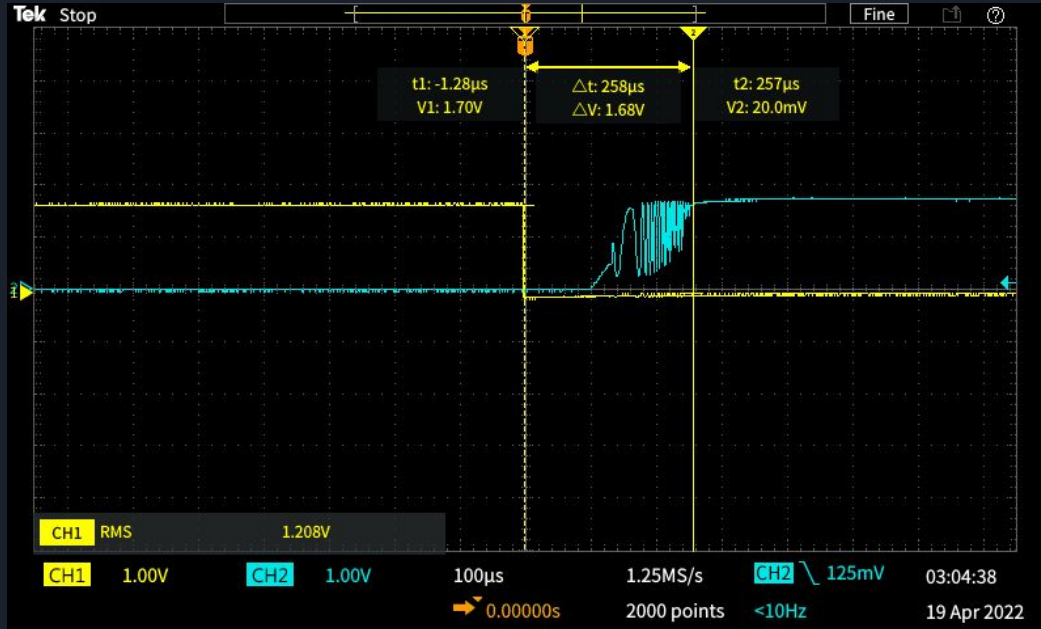


Propagation Delay



- Delay from button press to the microcontroller input turning logic high
 - CH1: button voltage
 - CH2: microcontroller input voltage
- Measured to be approximately 70.8 ns, which is a short period of time
- Time until the microcontroller reads the input voltage likely much longer

Push Button Bounce



- Delay from one LED turning off to another turning on
 - CH1: LED that is initially on
 - CH2: LED that is initially off
- Peculiar oscillation in CH2 voltage
 - Button bounce phenomenon?
- May have caused problems with the FDRM-KL25Z microcontroller

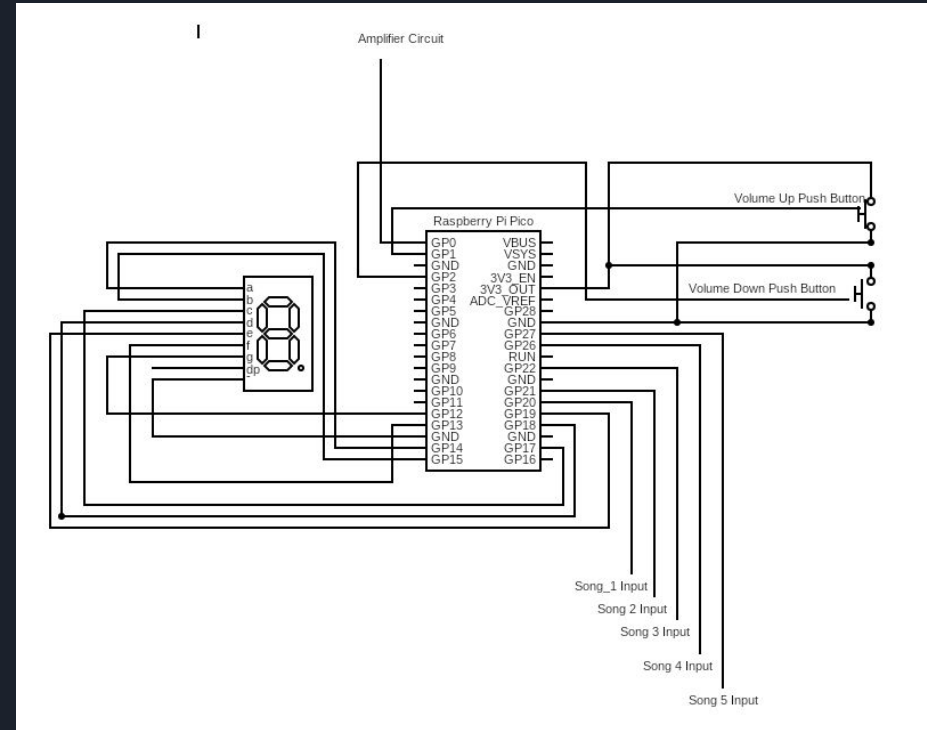


Circuit Operation - Microcontroller

- The microcontroller's code comes in two parts:
 - a. Main structure is based off of provided MBED example
 - b. Tone notes are based off of actual songs
- Microcontroller looks through a list of tones
 - a. Plays tones for a given interval
 - b. Sends output to PWM / Dout

Connections to MCU

- Song Input Signals
 - Signal is sent to sound Amplifier circuit based on song input.
- 7-Segment Display Connections
 - Uses PWM Out to control voltage
- Up and Down Volume Buttons
 - Button is in close circuit state



7 Segment Display Code

- Raspberry pi pico Pwm integer 16-bit output
 - Wanted_Vout = (3)/(0xFF)*value
 - Maximum 7-segment voltage limit: 2V
- toSegments function sets output voltage for all segments
- displaySegments function determines ON and OFF values for each segment based on wanted display value
 - Output in HEX(0-15)

```
125 def toSegments(a=LED_OFF,b=LED_OFF,c=LED_OFF,d=LED_OFF,e=LED_OFF,f=LED_OFF,g=LED_OFF):
126     seg_a.duty_u16(a)
127     seg_b.duty_u16(b)
128     seg_c.duty_u16(c)
129     seg_d.duty_u16(d)
130     seg_e.duty_u16(e)
131     seg_f.duty_u16(f)
132     seg_g.duty_u16(g)
133     displaySegments(1)
```

```
95 LED_ON = 35000
96 LED_OFF = 0
97 vol = 1000
```

```
99 def displaySegments(value):
100     a = LED_ON
101     b = LED_ON
102     c = LED_ON
103     d = LED_ON
104     e = LED_ON
105     f = LED_ON
106     g = LED_ON
107
108     value == 0 and toSegments(a=a,b=b,c=c,d=d,e=e,f=f)
109     value == 1 and toSegments(e=e,f=f)
110     value == 2 and toSegments(a=a,b=b,d=d,e=e,g=g)
111     value == 3 and toSegments(a=a,b=b,c=c,d=d,g=g)
112     value == 4 and toSegments(b=b,c=c,f=f,g=g)
113     value == 5 and toSegments(a=a,c=c,d=d,f=f,g=g)
114     value == 6 and toSegments(a=a,c=c,d=d,e=e,f=f,g=g)
115     value == 7 and toSegments(a=a,b=b,c=c)
116     value == 8 and toSegments(a=a,b=b,c=c,d=d,e=e,f=f,g=g)
117     value == 9 and toSegments(a=a,b=b,c=c,f=f,g=g)
118     value == 10 and toSegments(a=a,b=b,c=c,e=e,f=f,g=g)
119     value == 11 and toSegments(c=c,d=d,e=e,f=f,g=g)
120     value == 12 and toSegments(a=a,d=d,e=e,f=f)
121     value == 13 and toSegments(b=b,c=c,d=d,e=e,g=g)
122     value == 14 and toSegments(a=a,d=d,e=e,f=f,g=g)
123     value == 15 and toSegments(a=a,e=e,f=f,g=g)
```

Music Output

- Variables for note frequencies and durations were created for ease of translation.
- playsong function takes in duty cycle for output volume, the note array of frequencies, and notes_duration array for the length of the respective note.

```
65 # notes and durations for tones
66 twinkle_note= [C, C, G, G, A, A, G, F, F, E, E, D, D, C, G,
67                G, F, F, E, E, D, G, G, F, F, E, E, D, C, C,
68                G, G, A, A, G, F, F, E, E, D, D, C]
69 twinkle_duration= [Q, Q, Q, Q, Q, Q, H, Q, Q, Q, Q, Q, Q, H,
70                   Q, Q, Q, Q, Q, Q, H, Q, Q, Q, Q, Q, Q, H,
71                   Q, Q, Q, Q, Q, Q, H, Q, Q, Q, Q, Q, Q, H]
```

```
155 def playsong(timer):
156
157     global i
158     global playing
159     if i == limit:
160         speaker.duty_u16(0)
161         playing = False
162     else:
163         speaker.duty_u16(0)
164         utime.sleep(0.015)
165         speaker.duty_u16(int(vol))
166         speaker.freq(int(int(notes[i])))
167         i+=1
168         timer.init(freq=1/notes_duration[i], mode=Timer.ONE_SHOT, callback=playsong)
```

Volume Up And Down Code

```
165 # GPIO Pin for volume UP
166 volUP=Pin(1, Pin.IN, Pin.PULL_DOWN)
167 volUP.irq(trigger=Pin.IRQ_FALLING, handler=checkVolUpInput)
168 #GPIO Pin for volume down
169 volDown=Pin(2, Pin.IN, Pin.PULL_DOWN)
170 volDown.irq(trigger=Pin.IRQ_FALLING, handler=checkVolDownInput)
```

```
38 # Interrupt function for volume up button
39 def checkVolUpInput(t):
40     global vol
41     if vol<(15000+1000):
42         vol +=1000
43         displaySegments(0 if vol == 0 else (vol-1000)/1000)
44 # Interrupt function for volume down button
45 def checkVolDownInput(t):
46     global vol
47     if vol>(1000):
48         vol -=1000
49         displaySegments(0 if vol == 0 else (vol-1000)/1000)
```

Main Function

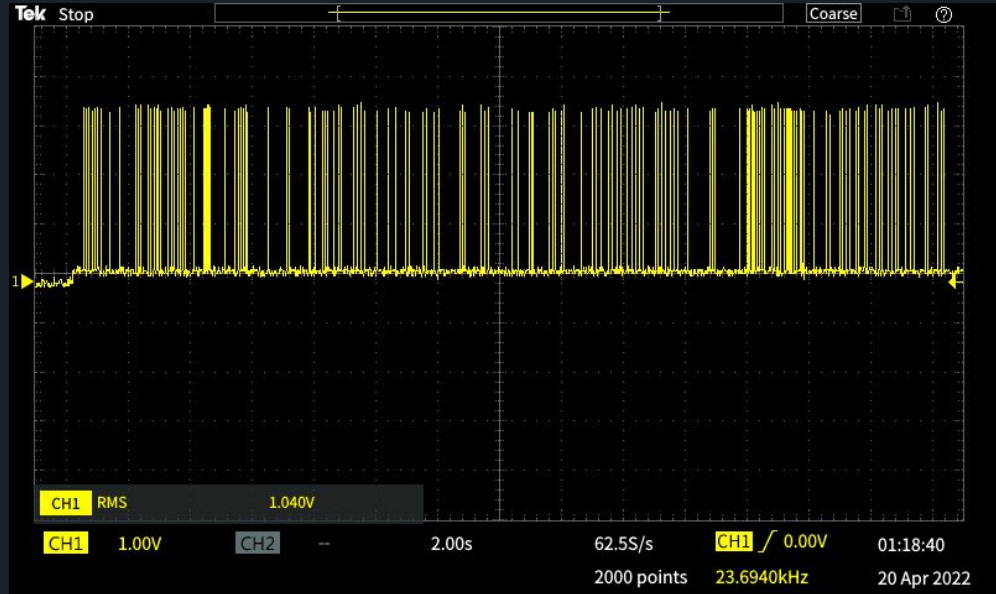
- Infinite while loop that allow user to select song based on input button

```
177 while 1:
178     if song1.value() and (not playing or not notes == twinkle_note) :
179         notes = twinkle_note
180         notes_duration = twinkle_duration
181         i = 0
182         limit = len(twinkle_note)-1
183         playing = True
184         timer.init(freq=1/notes_duration[i], mode=Timer.ONE_SHOT, callback=playsong)
185     elif song2.value() and (not playing or not notes == damned_note) :
186         notes = damned_note
187         notes_duration = damned_duration
188         i = 0
189         limit = len(damned_note)-1
190         playing = True
191         timer.init(freq=1/notes_duration[i], mode=Timer.ONE_SHOT, callback=playsong)
192     elif song3.value() and (not playing or not notes == letit_note) :
193         notes = letit_note
194         notes_duration = letit_duration
195         i = 0
196         limit = len(letit_duration)-1
197         playing = True
198         timer.init(freq=1/notes_duration[i], mode=Timer.ONE_SHOT, callback=playsong)
199     elif song4.value() and (not playing or not notes == hedwig_note) :
200         notes = hedwig_note
201         notes_duration = hedwig_duration
202         i = 0
203         limit = len(hedwig_note)-1
204         playing = True
205         timer.init(freq=1/notes_duration[i], mode=Timer.ONE_SHOT, callback=playsong)
206     elif song5.value() and (not playing or not notes == bday_note) :
207         notes = bday_note
208         notes_duration = bday_duration
209         i = 0
210         limit = len(bday_note)-1
211         playing = True
212         timer.init(freq=1/notes_duration[i], mode=Timer.ONE_SHOT, callback=playsong)
213
```

PWM Modulation

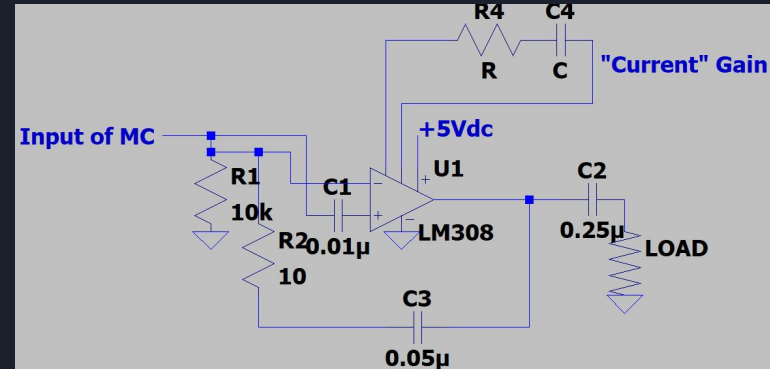
- The duty cycle of the pulses determines volumes.
More on time = higher volume.
- The frequency of the pulses changes the pitch that we hear

More oscillations = higher pitch



Circuit Operation - Amplifier

- According to LM386 Datasheet by Texas Instruments
 - Gain is fed into pins 1 and 8
 - Change gain by changing capacitor and resistor values
 - Inputs are fed into input pins (2 & 3)
 - Output (pin 5) current goes into speaker
- Circuit based off of MBED circuit diagram for audio amplifier





Notable Errors

- Overestimated our requirements
 - Circuit utilizes two distinct power sources (3.3V and 5V) to maximize volume potential
 - Bandpass Circuit unneeded because purity of sound
 - Propagation delay is huge given capacitors
 - .wav files generally do not work due to size and sampling rate from memory module



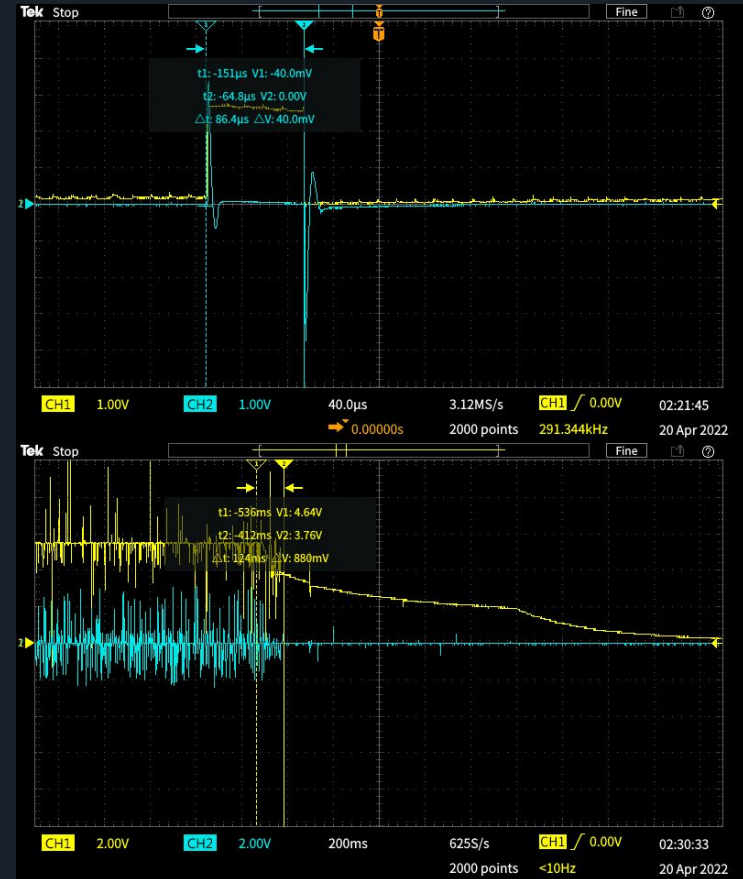
.WAV File Implementation

- Initially able to perform I/O on SD card using the KL25Z board
- The amount of memory that needed to be transferred in order to play songs exceeded our capabilities.

```
17 SDFFileSystem sd(p5, p6, p7, p8, "sd"); //SD card
18
19 AnalogOut DACout(p18);
20
21 wave_player waver(&DACout);
22
23 void play (string path) {
24     FILE *wave_file;
25     wave_file=fopen(path,"r");
26     if(wave_file==NULL) printf("file open error!\n\n\r");
27     waver.play(wave_file);
28     fclose(wave_file);
29 }
30
31 int main()
32 {
33     while(1) {
34         play(track1);
35         wait(0.5);
36         play(track2);
37         wait(0.5);
38         play(track3);
39         wait(0.5);
40     }
41 }
```

Observation of Square Wave

- Top picture shows PWM of a tone.
 - Example of how changing the duty cycle increases volume
- Bottom shows it takes 125 μs for the speaker to register sound turn off.





Conclusion

- Can firmly conclude that our project met the intended goals
 - Measured using Oscilloscope to confirm propagation delay and circuit function
 - Created digital logic to hold values as well as combine with software
- Although project was not a success, it was a learning experience
 - Learned how different tones are made via frequency and duty cycle
- Code can be found at the following github repo:
 - [Microcontroller-Audio-Project-/mainmain.py at main · orugantiv/Microcontroller-Audio-Project-\(github.com\)](https://github.com/orugantiv/Microcontroller-Audio-Project)



Works Cited

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Any Questions?