Cylindrical Coords
$$\frac{1}{2}$$

$$\hat{\Gamma} = \cos \hat{Q} \hat{X} + \sin \hat{Q} \hat{Y}$$

$$\hat{\theta} = -\sin \hat{Q} \hat{X} + \cos \hat{Q} \hat{Y}$$

$$\hat{Z} = \hat{Z}$$

$$2\hat{\Gamma} = \hat{\theta} \quad 2\hat{\theta} = -\hat{\Gamma}$$

$$7\hat{\theta} = \hat{\theta} = \hat{\theta} = -\hat{\theta} = -\hat{\Gamma}$$

$$7$$

and the state of t

$$\nabla^{2} \vec{A} = \nabla^{2} (A_{r} \hat{c} + A_{\theta} \hat{o} + A_{z} \hat{z})$$

$$= \nabla^{2} (A_{r} \hat{c}) + \nabla^{2} (A_{\theta} \hat{e}) + \nabla^{2} (A_{z} \hat{z})$$

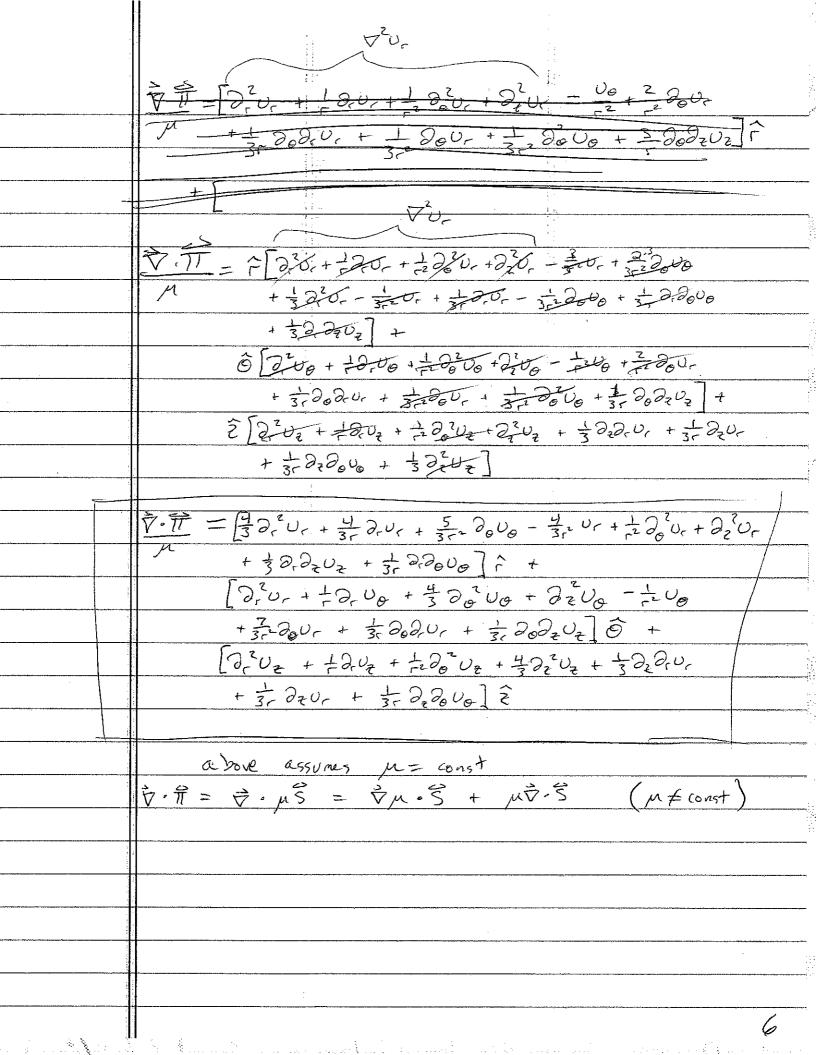
$$= \hat{c} \nabla^{2} A_{r} + 2 \hat{v} A_{r} \cdot \hat{v} \hat{a} \hat{c} + A_{r} \nabla^{2} \hat{c}$$

$$+ \hat{c} \nabla^{2} A_{z} + 2 \nabla A_{z} \cdot \nabla \hat{c} + A_{z} \nabla^{2} \hat{c}$$

$$+ \hat{c} \nabla^{2} A_{z} + 2 \nabla A_{z} \cdot \nabla \hat{c} + A_{z} \nabla^{2} \hat{c}$$

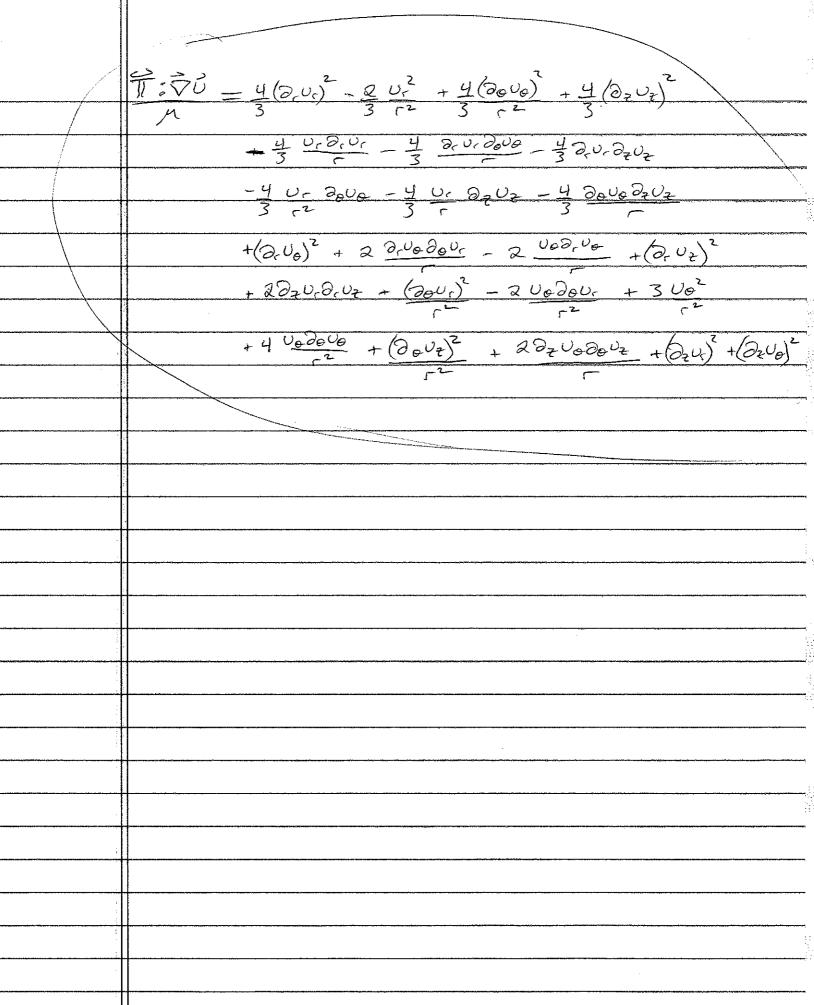
$$= \hat{c} \nabla^{2} A_{r} + 2 \left[\hat{c} \partial_{r} A_{r} + \frac{\hat{c} \partial_{r} A_{r}}{2} + A_{z} \nabla^{2} \hat{c} + \frac{\hat{c} \partial_{r} \hat{c}}{2} + \frac{\hat{c} \partial_{r} \hat{c}}$$

$$\begin{aligned}
&\vec{\Pi} = \mu \left(\nabla \vec{0} + (\nabla \vec{0})^T - \frac{2}{3} \vec{\Sigma}_{i_1} \nabla \cdot \vec{0} \right) \\
&\vec{\Pi}_{i_3} = \mu \left(\partial_1 U_{i_1} + \partial_2 U_{j_2} - \frac{2}{3} S_{i_3} \nabla \cdot \vec{0} \right) \\
&\vec{\nabla} \cdot \vec{\Pi} = \partial_1 \vec{\Pi}_{i_3} = \mu \left[\partial_1 \left(\partial_1 U_{i_1} \right) + \partial_1 \partial_1 U_{j_2} - \frac{2}{3} S_{i_3} \partial_1 \left(\nabla \vec{0} U_{j_2} \right) \right] \\
&= \mu \left[\partial_1 \partial_1 U_{i_2} + \nabla^2 U_{j_2} - \frac{2}{3} \partial_2 \left(\nabla \cdot \vec{0} \right) \right] \\
&= \mu \left[\vec{Q} \left(\nabla \cdot U_{j_2} + \nabla^2 U_{j_2} - \frac{2}{3} \partial_3 \left(\nabla \cdot \vec{0} \right) \right] \\
&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\nabla^2 \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \left(\vec{\nabla} \cdot \vec{0} \right) \right] \\
&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\nabla^2 \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \left(\vec{\nabla} \cdot \vec{0} \right) \right] \\
&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\nabla^2 \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \left(\vec{\nabla} \cdot \vec{0} \right) \right) \\
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&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\partial_1 \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \left(\vec{\nabla} \cdot \vec{0} \right) \right) \\
&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\partial_1 \vec{U}_{j_2} + \vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \vec{U}_{j_2} \right) \\
&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\partial_1 \vec{U}_{j_2} + \vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \vec{U}_{j_2} \right) \\
&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\partial_1 \vec{U}_{j_2} + \vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \vec{U}_{j_2} \right) \\
&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\partial_1 \vec{U}_{j_2} + \vec{U}_{j_2} + \vec{U}_{j_2} + \vec{U}_{j_2} \right) \\
&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \vec{U}_{j_2} \right) \\
&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \vec{U}_{j_2} \right) \\
&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \vec{U}_{j_2} \right) \\
&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{\nabla} \vec{U}_{j_2} \right) \\
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&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{U}_{j_2} \vec{U}_{j_2} \right) \\
&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{U}_{j_2} \vec{U}_{j_2} \right) \\
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&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\vec{\nabla} \vec{U}_{j_2} + \frac{1}{3} \vec{U}_{j_2} \vec{U}_{j_2} \right) \\
&\vec{\nabla} \cdot \vec{\Pi} = \hat{\mu} \left(\vec{\nabla} \vec{U}_{j_2} +$$



```
(\nabla u)_{ij} = \partial_i u_j
        T: VO where A:B = AisBis
         Ti (VU)2; = TI, VU, +TI, VU, + TI3 VU, +
                         1 72, VU4 + 1722 VU22 + 1723 V23 +
                         173, 757 + #32 VU32 +T33 VU33
        T_{ij} = \mu \left( \partial_i U_j + \partial_j U_i - \frac{2}{3} S_{ij} \partial_k U_k \right)
        (-38ij ORUR) DiUj = -30RUR DiUj Sij
                               = - = (0.0) 8,0;
                               = -\frac{2}{3}(\vec{\nabla} \cdot \vec{\sigma})^2
+ 2, 03 2, 03 + 23 0, 2, 03 +
                  + 22 03 22 03 + 23 6 203 +
                   734, 730, + 7,45 730, + 2302 7302 + 2203 7302
                   + 2,0,2,0,3 + 2,0, 2,0,3
        T superscript denotes it is from the DUT: DU term, not the DUT matrix
             i.e. \partial_3 v_z^T = \partial_3 v_z (based on the indices of \partial_i v_i + \partial_i v_i)
         so the transpose was taken when the indices were reversed so
        it still refers to elements of Ti matrix
```

Vuis Vuis + (Vut)is = Ti, Vuis 2 (F. 0)2 = [2:0: +2:0:]2:0; same matrix, different indices $\frac{2(\vec{\varphi}\cdot\vec{o})^2 + \vec{T}: \vec{\nabla}\vec{v} = 2(\partial_r \vec{v}_r)^2 + (\partial_r \vec{v}_\theta)^2 + (\partial_\theta \vec{v}_r - \underline{v}_\theta)(\partial_r \vec{v}_\theta)}{2(\vec{\varphi}\cdot\vec{o})^2 + (\partial_\theta \vec{v}_r - \underline{v}_\theta)(\partial_r \vec{v}_\theta)}$ + (2,02) + (2,02) + (200 - 00)2 $+\left(\partial_{c}v_{o}\right)\left(\partial_{o}v_{c}-v_{o}\right)+2\left(\partial_{o}v_{o}+v_{c}\right)^{2}$ + (2002)2 + (220)2002 + (220)2 + (2007) (200,) + (200) + (20 U) (200) +2(2=Uz)2 * $\frac{\hat{\Pi} \cdot \hat{\nabla} \hat{U} = -2(\hat{\nabla} \cdot \hat{U})^2 + 2(\partial_r u_r)^2 + (\partial_r u_e)^2 + 2(\partial_r u_e)(\partial_\theta u_r - u_e)}{2}$ + (2, 02)2 + 2 (20) (2, 02) + (200-00)2 + 2 (2000 + 00)2 + (2002) + 2 (2200) 2002 + (8 z vr)2 + (8 z vo) + 2 (8 z vz)2



Fluid Equations

MHD: M, k, 2 need not be const:

4)
$$g D \vec{v} = -\vec{\nabla} P + g \vec{g} + \vec{\nabla} \cdot \vec{T} + (\vec{\nabla} \times \vec{B}) \times \vec{B}$$

$$4\pi$$

Hydro:

$$\frac{\partial}{\partial t} = -g \dot{\nabla} \cdot \dot{\vec{v}}$$

Pressure Egn (derived on 1914)

THE STATE OF THE S

Derivation of
$$T \propto_{+} \frac{ds}{c_{p}} = \frac{1}{17} \frac{dP}{P} - \frac{ds}{s}$$

(1) $\frac{\partial a}{\partial b} = \frac{1}{2} \frac{(a)}{2} \frac{\partial c}{\partial b} = \frac{1}{2} \frac{\partial c}{\partial c} = \frac{1}{2} \frac{\partial$

$$g = h - Ts \Rightarrow dg = dh - Tds \Rightarrow SdT = \frac{1}{3}d\rho + SdT$$

$$\frac{\partial g}{\partial P|_{T}} = \frac{1}{3} \Rightarrow \frac{\partial^{2} g}{\partial P^{\partial T}} = \frac{1}{3}\frac{\partial g}{\partial P^{\partial T}}$$

$$\frac{\partial g}{\partial P|_{T}} = \frac{1}{3}\Rightarrow \frac{\partial^{2} g}{\partial P^{\partial T}} = \frac{1}{3}\frac{\partial g}{\partial P^{\partial T}}$$

$$\frac{\partial g}{\partial P|_{T}} = -S \Rightarrow -\frac{\partial S}{\partial P^{\partial T}} = \frac{1}{3}\frac{\partial g}{\partial P^{\partial T}}$$

$$\frac{\partial g}{\partial P|_{T}} = -S \Rightarrow -\frac{\partial S}{\partial P^{\partial T}} = \frac{1}{3}\frac{\partial g}{\partial P^{\partial T}}$$

$$\frac{\partial g}{\partial P^{\partial T}} = -\frac{1}{3}\frac{\partial g}{\partial P^{\partial T}} = \frac{1}{3}\frac{\partial g}{\partial P^{\partial T}}$$

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$$\frac{\partial g}{\partial P^{\partial T}} = -\frac{1}{3}\frac{\partial g}{\partial P^{\partial T}} = \frac{1}{3}\frac{\partial g}{\partial P^{\partial$$

Derivation of Pressure Egn

I deal gas => x = 1/T 17 = 8 P= 6-1) CrgT Cp = 8 Cr

 $\frac{1}{C_8} \frac{dS}{dP} = \frac{dP}{dP} = \frac{dP}{$

DS = 1 0-(kōT) + 1 T:00 + 1 7 (0x8)2 Dt ST 9T 4T

1 Dlap - Dlag = 1 To (RÝT) + 1 T. TO + 1 T (TXB) TO Dt ptcp gtcp gtcp gtcp ytch ytch

TDP = - 8 P. D + 8 P (OXB) + 8 P. DO + 2 (OXB)

DP = - 8 P や・ひ + (8-1) や・(kを) + (8-1) 前: やび + (8-1) 型 (学x B) 2 P ± 4 m

Ohnie Heating Term

$$\vec{\nabla} \times \vec{E} = -\frac{1}{C} \vec{\nabla} \times (\vec{o} \times \vec{B}) + \vec{\nabla} \times (\vec{c} \cdot \vec{J}) = -\frac{1}{C} \partial_t \vec{B}$$

$$\partial_{1}\vec{B} = \vec{\nabla} \times (\vec{O} \times \vec{B}) - \vec{C} \times \left[\vec{J} + \vec{G} \times \vec{B} \right] \qquad \vec{\nabla} \times \vec{B} = \frac{\vec{U} \cdot \vec{D}}{\vec{C}}$$

$$\partial_{+}\vec{B} = \vec{\nabla} \times (\vec{o} \times \vec{B}) - \vec{\nabla} \times \left(\frac{c^{2}}{4\pi\sigma} \vec{\nabla} \times \vec{B}\right) \qquad \mathcal{Z} = \frac{c^{2}}{4\pi\sigma}$$

$$\partial_{+}\vec{B} = \vec{\nabla} \times (\vec{o} \times \vec{b}) - \vec{\nabla} \times (\vec{q} \vec{o} \times \vec{b})$$

$$\frac{7 = const}{\partial_t \vec{B} = \vec{\nabla} \times (\vec{o} \times \vec{B}) + 2\vec{\nabla}^2 \vec{B}}$$

Ohmic Heating =
$$\vec{J} \cdot \vec{E} = \vec{J} \cdot \vec{J}/r = \vec{J}/c/4\pi\eta$$

$$= \frac{4\pi\eta}{c^2} \vec{J}^2 = \frac{4\pi\eta}{c^2} \frac{c^2}{(4\pi)^2} (\vec{\nabla} \times \vec{B})^2$$

$$= \frac{2}{4\pi} \left(\vec{\nabla} \times \vec{B} \right)^2$$

Dedalus Friendly (Hydro) Equations

$$\partial_{t}g_{i} + \frac{\sqrt{20}g_{i}}{\sqrt{20}} + \vec{\upsilon} \cdot \nabla g_{0} + g_{0}\vec{\nabla} \cdot \vec{\upsilon} + g_{1} + g_{0}\vec{\nabla} \cdot \vec{\upsilon} + g_{1} + g_{0}\vec{\nabla} \cdot \vec{\upsilon}$$

Continuity

2)
$$g \partial_t \hat{o} + g \hat{o} \cdot \vec{\nabla} \hat{o} = -\nabla P + g \hat{g} + \vec{\nabla} \cdot \vec{\Pi}$$

$$Q_t \hat{o} + \hat{o} \cdot \nabla \hat{o} = -\frac{1}{7} \nabla P + \hat{g} + \frac{1}{7} \nabla \cdot \vec{\Pi}$$

$$Q_t \hat{o} + \hat{o}_t \hat{o}_t + \hat{v} \hat{o}_t \nabla \hat{o}_t + \hat{o}_t \nabla \hat{o}_t + \hat{o}_t \nabla \hat{o}_t = -\frac{1}{7} \nabla P_t + \frac{1}{7} \frac{1}{7} \frac{1}{7} + \frac{1}{7} \hat{\nabla} \cdot \vec{\Pi}_t + \frac{1}{7} \hat{\nabla} \cdot \vec{\Pi}_t$$

$$= -\frac{1}{7} \nabla P_t - \frac{1}{7} \nabla P_t + \frac{1}{7} \frac{1}{7} + \frac{1}{7} \hat{\nabla} \cdot \vec{\Pi}_t + \frac{1}{7} \hat{\nabla} \cdot \vec{\Pi}_t$$

$$= -\frac{1}{7} \nabla P_t + \frac{1}{7} \frac{1}{7} + \frac{1}{7} \hat{\nabla} \cdot \vec{\Pi}_t$$

$$= -\frac{1}{7} \nabla P_t + \frac{1}{7} \frac{1}{7} + \frac{1}{7} \hat{\nabla} \cdot \vec{\Pi}_t$$

$$= -\frac{1}{7} \nabla P_t + \frac{1}{7} \frac{1}{7} + \frac{1}{7} \hat{\nabla} \cdot \vec{\Pi}_t$$

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$$= -\frac{1}{7} \nabla P_t + \frac{1}{7} \frac{1}{7} + \frac{1}{7} \frac{$$

Momentum Egn by Components godtur + OrP, + gov dour - govuo - govuo - gigir $-(\hat{\nabla}\cdot\hat{\pi}_i)\cdot\hat{r} = -g_0 \nu_r \partial_r \nu_r - g_0 \nu_0 \partial_0 \nu_r - g_0 \nu_2 \partial_2 \nu_r$ + 9000 - 9, 0, P, - 9, q. F 一等(合). 产 9.0700 + 100P, + 9.0 2000 + 9.0VU, +9.0-2, V-9, g. 6-(D. T.). 6 = -9.0.9.00 - 9.00 DOUG - 9.020200 - 9.000, - Si 20Pi - Si q, 6 - Si (中, 前, 6) godzvz + 2zP, + goV 2ouz -gig·ê-(√?)·ê = -gov, Dovz - govo Dovz - govz Dzvz - Si Dz P, - 9,3 g-2 - 8, (V-7)-2

3)
$$\frac{\partial P}{\partial t} = -\sqrt{P_{c}} \cdot \vec{\alpha} - \frac{1}{2} (x-1)} \vec{\nabla} \cdot \vec{Q} + (x-1) \vec{\Pi} \cdot \vec{\nabla} \vec{O}$$

$$\frac{\partial P}{\partial t} + \partial_{0} P_{1} = -\sqrt{P_{c}} + P_{1}) \vec{\nabla} \cdot \vec{Q}_{0} + \vec{Q}_{1} \cdot \vec{\nabla}_{1} \cdot \vec{\nabla}_{1}$$

$$\frac{\partial_{1} P_{1} + \sqrt{\partial_{0} P_{1} + \dot{U}_{1} \cdot \nabla P_{0} + \sqrt{P_{0} \partial_{1} (rU_{1}) + \sqrt{P_{0} \partial_{0} U_{0}} + \sqrt{P_{0} \partial_{2} U_{2}}}{+ \sqrt{P_{0} \nabla U_{0}} - (\sqrt{P_{0} - 1}) \nabla_{0} (\sqrt{P_{0} \nabla U_{1}}) - \sqrt{P_{0} \partial_{0} P_{1}} (\sqrt{P_{0} U_{0}}) + \sqrt{P_{0} \partial_{0} P_{$$

⇒ 竹。:マロ、= 竹;マロ。

0, P, +	Y20P, +0,·∇P, + 0 Po 2(rur) + 8Po 2000 + 8Po 22U2	T
	-(8-1) P. (KPT,) - 2(8-1) M D. VD. Up + D. VD. Up	
	- Ue 3/V - Y 300/ + VUe - V3,Ue]	
	$= -\frac{1}{2} \left[\frac{1}{2} \left(\frac{1}{2} \left(\frac{1}{2} \right) - \frac{1}{2} \left(\frac{1}{2} \right) - \frac{1}{2} \left($	
######################################	-U000, - U202P, +(8-1) 1,: VD,	

$$\begin{array}{ll} \overrightarrow{\Pi}_{1} : \overrightarrow{\nabla V_{0}} & \overrightarrow{U_{0}} = \overrightarrow{V(r)} \widehat{\Theta} \\ & \overrightarrow{\nabla U_{0}} = \overrightarrow{(0)} \widehat{r} + \overrightarrow{r} \in \mathscr{D}_{r} \lor + \widehat{r} \in \mathscr{D}_{r} \lor + \widehat{r} \in \mathscr{D}_{r} \lor \\ & + \widehat{\Theta} \widehat{r} \left(- \frac{\overrightarrow{V}}{r} \right) + \widehat{\Theta} \widehat{\Theta} \left(0 \right) + \widehat{\Theta} \widehat{\mathcal{C}} \left(0 \right) \\ & + \widehat{r} \widehat{r} \left(0 \right) + \widehat{r} \widehat{\Theta} \widehat{\Theta} \left(0 \right) + \widehat{r} \in \mathscr{D}_{r} \\ & + \widehat{r} \widehat{r} \left(0 \right) + \widehat{r} \widehat{\Theta} \widehat{\Theta} \left(0 \right) + \widehat{r} \widehat{\mathcal{C}} \widehat{V} \right) \\ & \Rightarrow \overrightarrow{\nabla U_{0}} = \widehat{r} \widehat{\theta} \widehat{\partial}_{r} \checkmark - \widehat{\Theta} \widehat{r} \checkmark \\ & \overrightarrow{\Pi}_{1} : \overrightarrow{\nabla U_{0}} = \widehat{r} \widehat{\theta} \widehat{\partial}_{r} \checkmark - \widehat{\Theta} \widehat{r} \checkmark \\ & = \mu \left(\frac{\mathbf{S}_{r}}{r} \nabla U_{r_{0}} + \nabla U_{r_{0}} - \frac{2}{3} (0) \nabla \cdot \widehat{U} \right) \left[- \frac{\overrightarrow{V}}{r} \right] \\ & = \mu \left(\partial_{r} U_{0} + \partial_{0} U_{r_{0}} - \frac{2}{3} (0) \nabla \cdot \widehat{U} \right) \left[- \frac{\overrightarrow{V}}{r} \right] \\ & = \mu \left(\partial_{r} U_{0} + \partial_{0} U_{r_{0}} - \frac{2}{3} (0) \nabla \cdot \widehat{U} \right) \left[- \frac{\overrightarrow{V}}{r} \right] \\ & + \mu \left(\partial_{0} U_{r_{0}} - U_{0} + \partial_{0} U_{r_{0}} - \frac{2}{3} (0) \nabla \cdot \widehat{U} \right) \left[- \frac{\overrightarrow{V}}{r} \right] \\ & = \mu \left(\partial_{r} U_{0} + \partial_{0} U_{r_{0}} - \frac{2}{3} (0) \nabla \cdot \widehat{U} \right) \left[- \frac{\overrightarrow{V}}{r} \right] \\ & + \mu \left(\partial_{0} U_{r_{0}} - U_{0} + \partial_{0} U_{r_{0}} - \frac{2}{3} (0) \nabla \cdot \widehat{U} \right) \left[- \frac{\overrightarrow{V}}{r} \right] \\ & = \mu \left(\partial_{r} U_{0} + \partial_{0} U_{r_{0}} - U_{0} + \partial_{0} U_{r_{0}} - \frac{2}{3} (0) \nabla \cdot \widehat{U} \right) \left[- \frac{\overrightarrow{V}}{r} \right] \\ & = \mu \left(\partial_{r} U_{0} - U_{0} + \partial_{0} U_{r_{0}} - U_{0} \right) \left(- \frac{\overrightarrow{V}}{r} \right) \\ & = \mu \left(\partial_{r} U_{0} - U_{0} - U_{0} - U_{0} - U_{0} \right) \left(- \frac{\overrightarrow{V}}{r} \right) \\ & = \mu \left(\partial_{r} U_{0} - U_{0} - U_{0} - U_{0} - U_{0} \right) \left(- \frac{\overrightarrow{V}}{r} \right) \\ & = \mu \left(\partial_{r} U_{0} - U_{0} - U_{0} - U_{0} - U_{0} - U_{0} \right) \left(- \frac{\overrightarrow{V}}{r} \right) \\ & = \mu \left(\partial_{r} U_{0} - U_{0} - U_{0} - U_{0} - U_{0} - U_{0} \right) \left(- \frac{\overrightarrow{V}}{r} \right) \\ & = \mu \left(\partial_{r} U_{0} - U_{0} - U_{0} - U_{0} - U_{0} - U_{0} \right) \left(- \frac{\overrightarrow{V}}{r} \right)$$

$$\overrightarrow{\Pi}_{o} : \overrightarrow{\nabla} \overrightarrow{U}_{i} \qquad \overrightarrow{U}_{o} = \forall (i) \widehat{\theta}$$

$$\overrightarrow{\Pi}_{o} : = \mu \left(\overrightarrow{\nabla} \overrightarrow{U}_{o} + \overrightarrow{\nabla} \overrightarrow{U}_{o}^{T} - \frac{1}{2} \overrightarrow{\mathbf{I}} (\cancel{\varphi} \overrightarrow{U}_{o}) \right)$$

$$= \mu \left(\widehat{i} \widehat{\theta} \widehat{\theta}_{i} \times - \widehat{\theta} \widehat{i} \xrightarrow{Y} \right) + \mu \left(- \underbrace{Y} \widehat{i} \widehat{\theta} + \widehat{\theta}_{i} \vee \widehat{\theta} \widehat{i} \right)$$

$$\overrightarrow{V}_{o} \qquad \qquad \forall U_{i}$$

$$\overrightarrow{V}_{o} \qquad \qquad \forall U_{i}$$

$$\overrightarrow{\Pi}_{o} : \overrightarrow{\nabla} \overrightarrow{U}_{i} = \Pi_{i, \varphi} \overrightarrow{\nabla} U_{i, \varphi} + \Pi_{e_{i}} \overrightarrow{\nabla} U_{e_{i}}$$

$$= \mu \left(\widehat{\theta}_{i} \times - \underbrace{Y} \right) \partial_{i} U_{i} + \mu \left(\partial_{i} \times - \underbrace{Y} \right) \left(\underbrace{\vartheta_{e_{i}}} - \underbrace{U_{e_{i}}} \right)$$

$$= \mu \left(\widehat{\theta}_{i} \times - \underbrace{Y} \right) \partial_{i} U_{i} + \mu \left(\partial_{i} \times - \underbrace{Y} \right) \left(\underbrace{\vartheta_{e_{i}}} - \underbrace{U_{e_{i}}} \right)$$

$$= \mu \left(\widehat{\theta}_{i} \times - \underbrace{Y} \right) \partial_{i} U_{e_{i}} + \underbrace{2 \times 2 \partial_{i} U_{e_{i}}} - \underbrace{2 \times 2 U_{e_{i}}} + \underbrace{2 \times 2 U_{e_{i}}} - \underbrace{Y} \partial_{i} U_{e_{i}} - \underbrace{Y} \partial_{i} U_{e_{i}} - \underbrace{Y} \partial_{i} U_{e_{i}}$$

$$= \mu \left(\widehat{\theta}_{i} \times - \underbrace{Y} \right) \partial_{i} U_{e_{i}} - \underbrace{Y} \partial_$$

4)
$$P = (x-1)CvgT$$
 $\nabla P_0 + \nabla P_1 = \nabla [(x-1)Cv] + (x-1)Cvg\nabla T + (x-1)CvT\nabla G$
 $\nabla P_0 + \nabla P_1 = gT\nabla [(x-1)Cv] + (x-1)Cvg\nabla T_1 + (x-1)Cvg\nabla T_2$
 $+(x-1)CvT\nabla G_0 + (x-1)CvT\nabla G_1$
 $+(x-1)CvT\nabla G_1 + (x-1)CvT\nabla G_2$
 $+(x-1)CvT\nabla G_2 + (x-1)CvT\nabla G_3$
 $+(x-1)CvT\nabla G_3 + (x-1)CvT\nabla G_3$