

Faculty of Engineering & Technology Department of Electrical and Computer Engineering

First Semester, 2023/2024

ENC3310- Advanced Digital Design Course Project

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Overview

In this project you will build a simple part of a microprocessor. Firstly, you will build two main blocks: the ALU and the register file, then you will connect them together and run a simple machine code program on them.

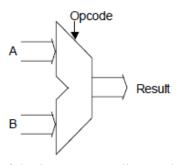
In order to ensure that your design is related to yourself, various aspects of the design will be dictated by your student ID number. These include the machine code used by your design, the contents of the register file. This means that every student should have a unique design.

You have to work individually in this project and submit a report about your design and implementation of this project.

Part 1

The ALU

Write a VERILOG description of an ALU with two 32-bit inputs, A and B, and a 32-bit output Result (module alu).



The result is derived from one or both of the inputs according to the value of a 6-bit opcode. The operations that the ALU can perform are listed below:

- \bullet a + b
- a b
- |a| (i.e. the absolute value of a)
- max (a, b) (i.e. the maximum of a and b)
- min (a, b) (i.e. the minimum of a and b)
- avg(a,b) (i.e. the average of a and b the integer part only and remainder is ignored)
- not a
- a or b
- a and b
- a xor b

The opcode that will be used to represent each of these operations is determined by the last digit of your students ID number. The table below shows which opcode you should use in your design for each instruction.

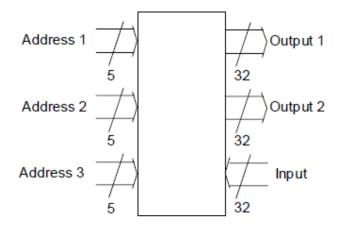
Digit of	0	1	2	3	4	5	6	7	8	9
	U	1	2	3	7)	U	/	O	9
ID no.										
a + b	8	6	6	4	6	3	4	4	1	5
a - b	9	8	9	11	2	15	10	14	6	8
a	2	10	1	8	5	13	3	8	13	13
-a	10	12	5	6	4	12	12	11	8	7
max(a,b)	12	14	7	13	7	7	7	10	7	3
min (a,b)	1	11	8	14	10	1	2	1	4	6
avg(a,b)	13	13	11	7	9	9	6	13	11	10
not a	5	15	14	9	13	10	13	6	15	2
a or b	4	2	13	12	8	14	14	9	3	15
a and b	11	3	12	10	1	11	11	5	5	4
a xor b	15	9	4	5	3	5	8	7	2	12

So, for example if your ID is 1221438 then the last digit is 8.

Then a+b is to be represented by opcode 1, a-b is to be represented by opcode 6, |a| is to be represented by opcode 13 and so on. (These are shown as denary (base 10) values; your design may use binary or hexadecimal values.)

The register file

Inside a modern processor there is a very small amount of memory that is used to hold the operands that it is presently working on. This is called the *register file*, and normally has the following appearance (module reg_file).



This is a very small fast RAM, typically holding 32 x 32-bit words, and therefore requiring a 5-bit address to select out one of the 32-bit words. It is unlike normal RAM in that it can process three addresses at the same time, two of which are always read operations, and one of which is always written to.

Output 1 produces the item within the register file that is address by Address 1. Similarly Output 2 produces the item within the register file that is address by Address 2. Input is used to supply a value that is written into the location addressed by Address 3.

The initial values stored in the register file are determined by the second-from-last digit of your student ID, and are shown in the table below:

ID/	0	1	2		4	-	(0	0
ID/	0	1	2	3	4	5	6	7	8	9
Location	•	0	0	0	0	_	0		_	0
0	0	0	0	0	0	0	0	0	0	0
1	7942	11662	12642	12996	4198	11930	4616	15034	5986	16302
2	13224	11562	10592	11490	5596	5348	11640	8854	12250	2994
3	15462	15330	6230	7070	14426	7308	11254	170	482	1658
4	8026	9594	8940	6026	7612	15684	6786	7226	14246	5474
5	3692	14746	8776	3322	6638	12346	6784	4480	5124	6784
6	9882	3288	9436	10344	10040	9716	12432	8928	1848	10836
7	8248	5932	3056	6734	3930	7820	13548	7302	5260	4648
8	3432	1978	4850	15834	4150	5190	13462	8922	16170	524
9	178	4912	3406	15314	6406	14702	13454	1044	4766	12200
10	2378	2380	12380	6000	5400	5630	11780	6706	4298	3286
11	8302	1926	548	12196	8572	2352	13170	258	610	14734
12	592	12726	13054	11290	16324	15424	2982	7354	1510	10998
13	7430	176	2800	13350	8840	2670	8096	3294	9794	4420
14	10572	8408	12988	2086	8258	4172	514	14740	7456	8754
15	7676	8394	956	6734	11228	4300	3600	6532	5580	3246
16	1238	13604	2194	7430	8462	4744	10870	10436	9300	9040
17	16008	10222	11914	14102	13284	1286	12528	11900	12314	8714
18	2426	7262	15864	13200	4676	8122	9860	14694	12806	12008
19	11930	10190	11832	3264	3980	4558	6166	8830	10478	1006
20	6724	8734	12346	2368	5634	8534	4520	8712	11556	6724
21	12790	12432	2192	15846	7632	13340	14436	4532	6778	12746
22	4842	8724	1840	11710	9846	6918	12136	9084	8430	5462
23	7108	5412	13996	14736	5442	11700	5134	13838	5700	11810
24	6296	11082	12054	5338	12488	10722	11958	10018	13422	7590
25	3322	2212	4434	5544	6656	3346	7688	1280	11224	4368
26	10848	6188	12152	1852	832	3300	5258	5814	1990	10358
27	14698	7056	9876	3898	4664	2386	12420	670	922	15252
28	16378	3744	8734	16252	6798	11212	3560	8832	6020	11954
29	15456	5766	8308	1048	14166	3504	1248	15186	15768	13704
30	1260	3412	3422	5642	3246	8712	8724	4512	5624	1478
31	0	0	0	0	0	0	0	0	0	0

So, for example, if your students ID is 1225<u>6</u>7 then the second-from-last digit of your ID number is <u>6</u>. so item 0 should be 0, item 1 should be 4616, item 2 should be 11640, and so on. (N.B. these values are in *denary (i.e. base 10)*. You may need to convert them to binary or hexadecimal.)

Part 2 In this part you will connect the ALU with the RAM to form a simple microprocessor.

Clocking the register file

The register file that you created in the first part was a combinational circuit. This causes some serious problems if, for example, address 2 and address 3 are the same. The circuit would read output 2 from the location referenced by address 2, at the same time that the input is over-writing that location.

These problems can be solved by synchronising the register file to a clock. You will need to add an extra input named *clock*, and give the register file the following behaviour:

On the rising edge of the clock:

- Output 1 produces the item within the register file that is address by Address 1.
- Output 2 produces the item within the register file that is address by Address 2.
- Input is used to supply a value that is written into the location addressed by Address 3.

Under all other circumstances:

• the outputs are held constant at the values they assumed during the last rising edge of the clock.

You should check your design thoroughly, and in particular make sure that it behaves sensibly when the address for the input is the same as the address of one of the outputs.

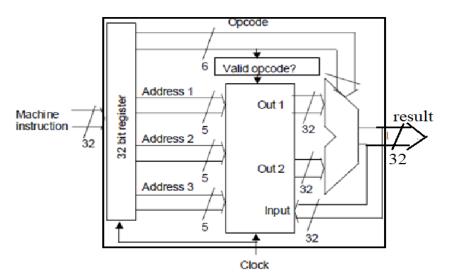
Enabling the register file

The register file that you created is always sensitive to its inputs, even when the inputs have garbage values. This can cause problems because when the simulation initializes (which corresponds to the real hardware being switched on) all the values of the logic signals initializes to some random garbage value.

Give the register file an enable input. When the enable input=1 the register file will operate normally. Otherwise the register file will ignore its inputs, and will not update its outputs.

Creating the core of the microprocessor

Now create a testbench that contains an instance of the register file and an instance of the ALU connected like this (module mp top):



Machine instructions are supplied to this arrangement in the form of 32-bit numbers. The format of these instructions is as follows:

- The first 6 bits identify the opcode
- The next 5 bits identify first source register
- The next 5 bits identify second source register
- The next 5 bits identify destination register
- The final 11 bits are unused

So, for example, if you want to add the contents of register 1 and register 2 and put the result into register 3, then the machine instruction would be as follows:

- The first 6 bits supply the opcode for the *add* instruction
- The next 5 bits would address register 1, and the next 5 would address register 2
- The next 5 bits address register 3.
- The remaining bits are unused, and should be set to zero.

The *enable* signal to the register should go high when the *opcode* contains a valid value, and should be low otherwise.

Test out your design by supplying machine instructions to it, and check that the operation performed is correct. Make sure you understand the timing of instructions, and in particular the relationship between the clock cycle on which the instruction occurs, and the clock cycle on which the appropriate result is written to register.

Main Modules templates

In order to ease the ability to test your design, you need to stick the following modules definition. If you don't stick to the modules definition, then testing your design by the instructor testbench will not be possible and hence you will loose part of the evaluation

```
module alu (opcode, a, b, result );
  input [5:0]
                  opcode;
  input [31:0] a, b;
  output reg [31:0] result;
endmodule
module reg file (clk, valid opcode, addr1, addr2, addr3, in , out1, out2);
                     clk;
  input
                    valid opcode;
  input
  input
       [4:0]
                    addr1, addr2, addr3;
  input [31:0]
                    in:
  output reg [31:0] out1, out2;
endmodule
module mp top (clk, instruction, result);
  input
                     clk;
  input [31:0]
                   instruction;
  output reg [31:0] result;
endmodule
```

Running a program (Testing your design)

Now create a stream of machine instructions that will act as a small program. The program must act as follows:

- 1- Create an array of instructions.
- 2- Include at least one instruction for each of the provided opcodes.
- 3- Print the input instruction and result (output)

- 4- For each instruction calculate the expected result, then compare the expected value with your output result.
- 5- If any instruction fails, then test fails, else test passes

Synchronising the data

All parts of the design that are synchronized to the clock should use *only the rising edge* of the clock. If you use both the rising edge and the falling edge, then it's much easier to do the design in simulation, but the real life hardware would be very expensive and complicated to manufacture. You will therefore lose a substantial number of marks if you use both edges of the clock.

No ops or buffering of opcode

You may find it useful to create a no-op instruction, i.e. an instruction that instructs the microprocessor to "do nothing" for the next clock cycle, and allocate one of your un-used opcodes to this instruction. Also, in the first clock, the opcode may arrive before the register values, thus you may need to add buffer (reg) (with one clock cycle delay) for the opcode.

If you don't manage to finish

Don't panic. Obviously you will lose marks for having an incomplete design, but you can still achieve a reasonable mark provided that you do a good write up of the parts that you have finished.

Writing up the assignment

Format of write up

The assignment should be written up as a brief report, which should explain (in about 6-8 pages)

- The ideas behind your design and how it works (in particular what happens on what clock cycle and why);
- How you tested it and how you interpreted the results of your tests;
- Which parts work correctly.

Your Report should be submitted as pdf file while Verilog code should be submitted as .v file (one file for report and one file for the code).

Print outs (screen shots) of your simulation results should be included as appendix 1 (not more than 5 pages; if you have a large number of results, then you should choose only the most meaningful results, and explain in the text what their significance is)

Deadline and hand-in procedure

The deadline for submission is Wednesday 17/01/2024 till midnight (more than 4 weeks from now). You will lose 10% of your mark for each late day (Late submission is allowed until Thursday 25/01/2024).

Mark scheme	
Style, structure and presentation of report	10%
Description of design and testing process	20%
Technical achievements in design, implementation and evaluation	50%
Quality of code (good comments, clear layout, good coding style,	
meaningful signal and entity names)	10%
Judgment and creativity	10%



Electrical and Computer Engineering Department

Project Feedback Course Project (ENCS 3310)

Instructors: Abdellatif Abu-Issa & Elias Khalil

Student Name: Student ID:	
	Marks
Report Presentation (10%) Language (Spelling and Grammar), style of the report, caption of figures, page numberingetc.	
 Design Process and Outcome (80%) Description of the design and test process (20%) Technical Achievement in System Design and implementation (50%) Quality of code (10%) 	
Judgment and Creativity (`10%) Demonstration of good judgment, imagination and creativity in selecting and applying design methods. Good discussion and analysing of the system and suggested improvements.	
Total Mark (Out of 100)	
Deducted Marks: late days * 10% per day	
FINAL ALLOCATED MARK (Out of 100) Any evidence for any type of cheating: pyes pro	