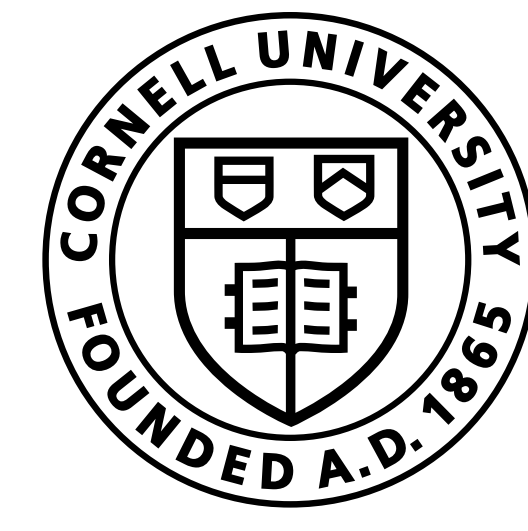


Aristos: Pipelining One-sided Communication in Distributed Mixture of Experts (MoE)

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Background

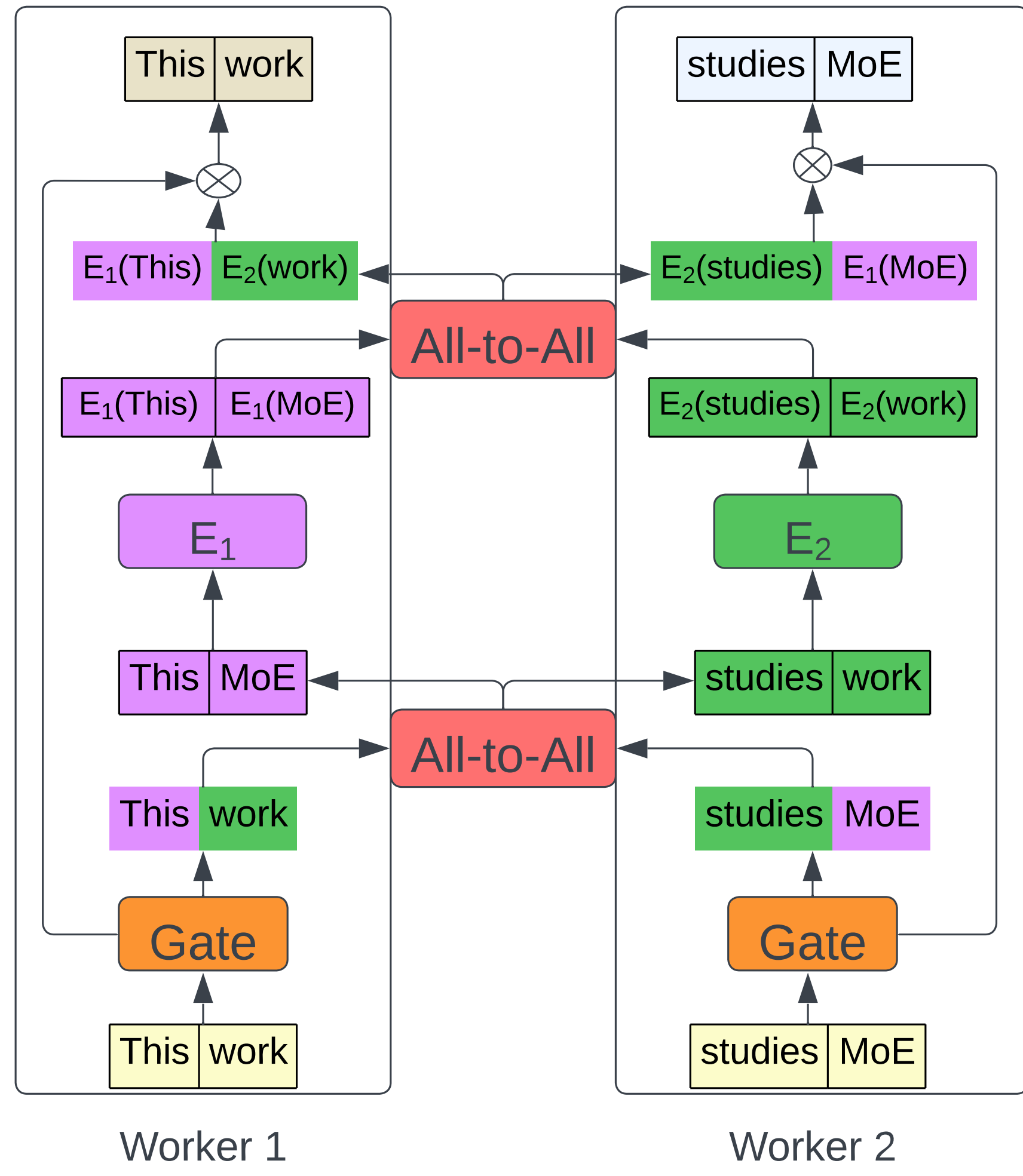
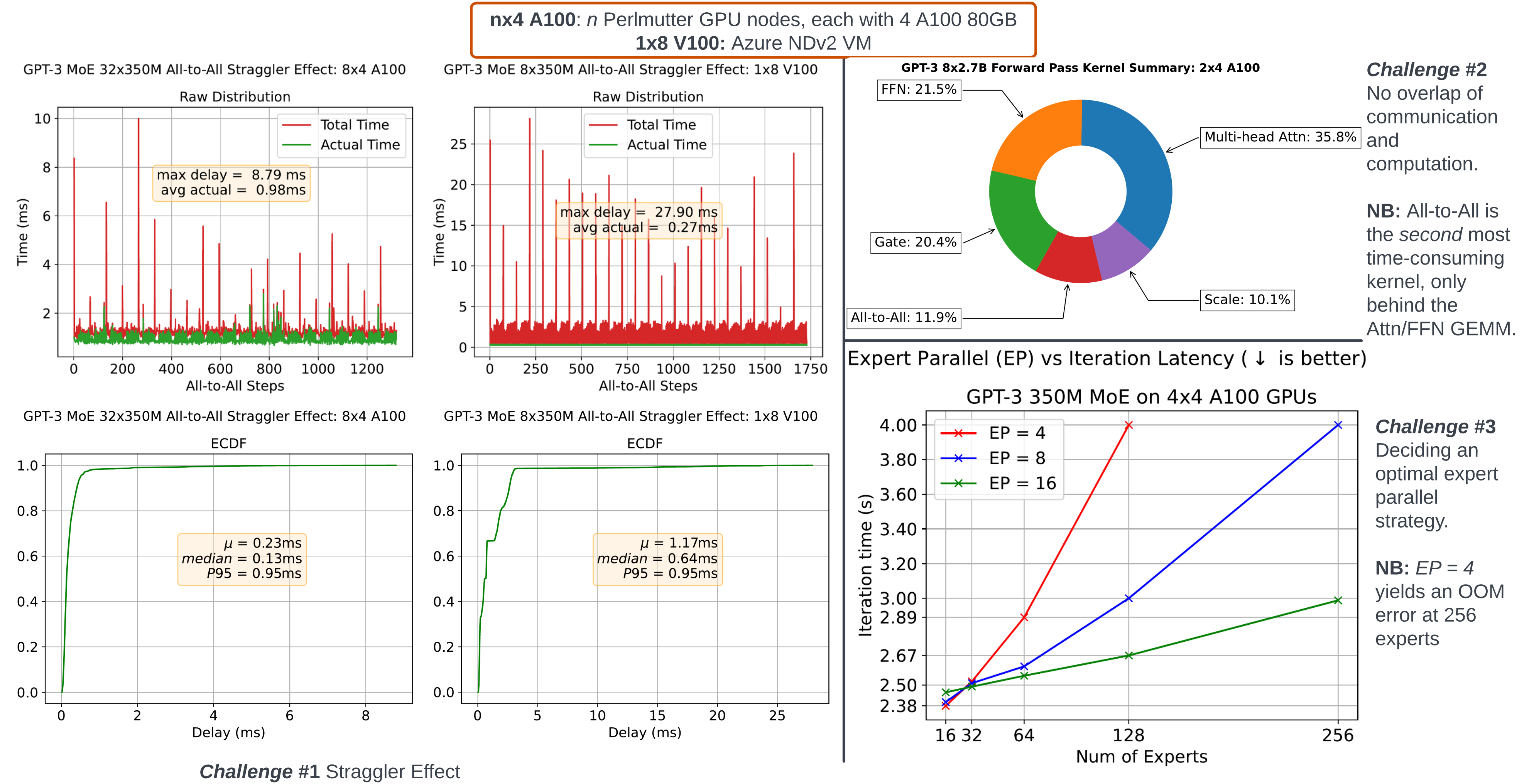


Figure 1: DMoE [4] with $W = EP = 2$. The **Gate** routes tokens to experts; **All-to-All** disseminates tokens; expert/FFN computation occurs; **All-to-All** reconstitutes tokens followed by the **Scale** computation.

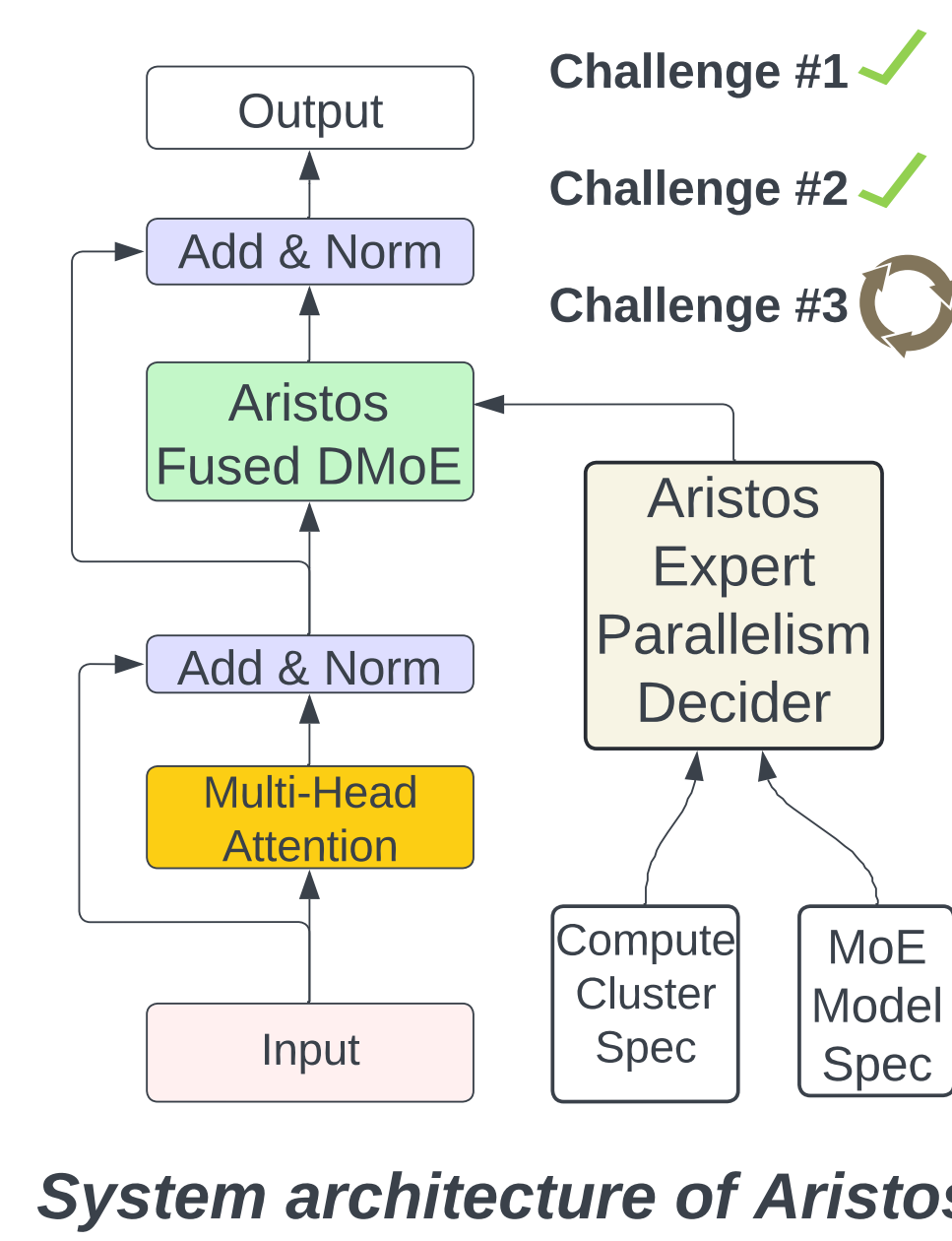
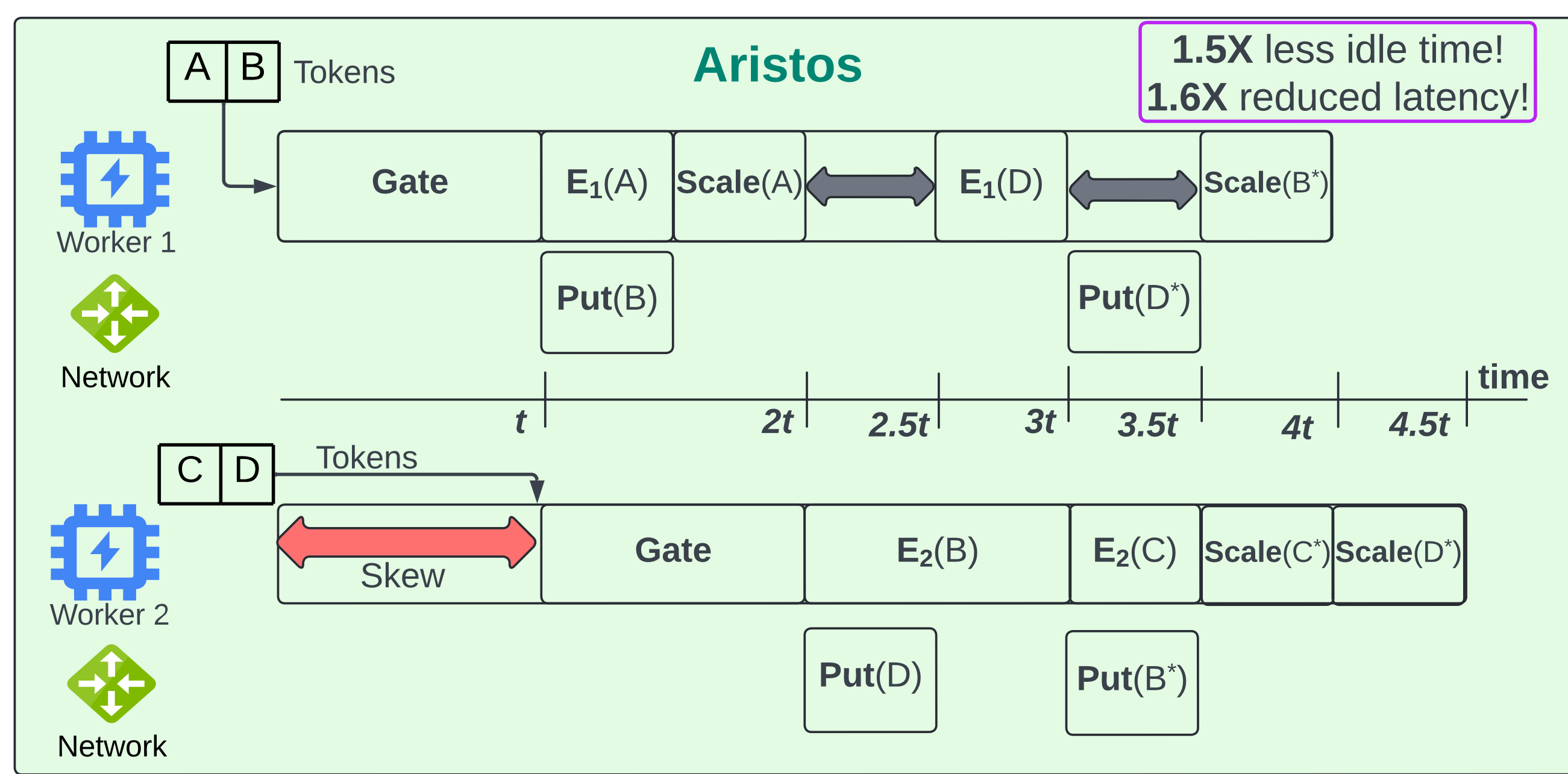
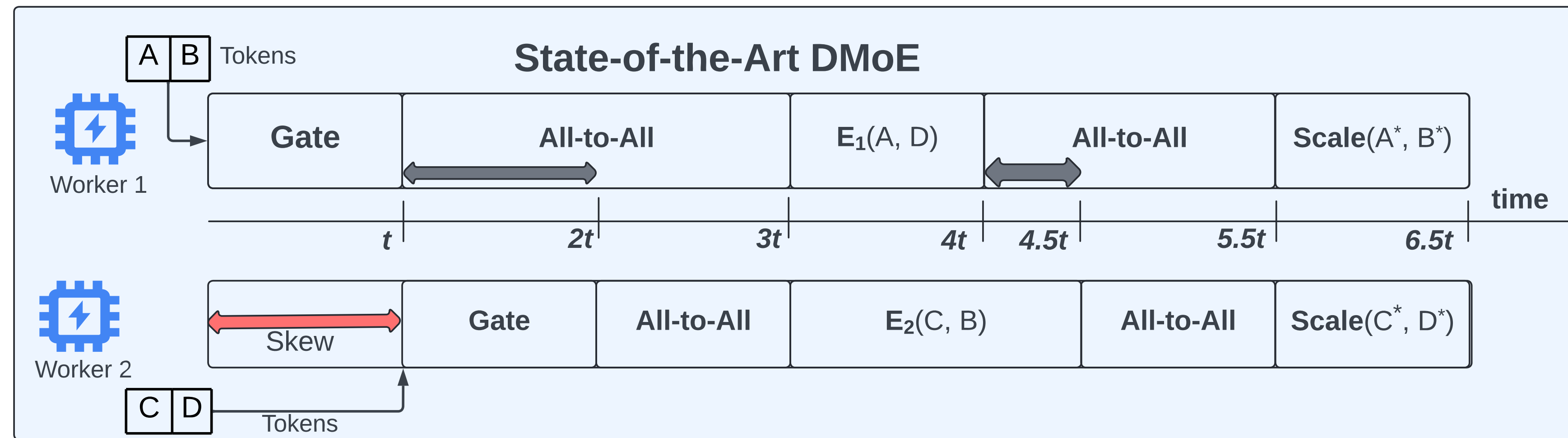
Challenges

The widely-adopted [3] MoE architecture, promising **5x** faster training and **9x** reduced inference costs [6], is currently plagued by three *open* challenges [2, 5, 1] in the distributed setting.



Method

Idle Time



Ongoing Work

Define $G = (V, E)$ as the cluster topology, where V denotes devices and E communication links. Equation 1 formulates the heart of challenge #3: finding $G^* = \{g = (V_g, E_g) \mid g \subseteq G\}$ the set of optimal expert parallel groups or the *topology-aware sharding specification*.

$$\min \max_{g \in G^*} \kappa \left(\pi(g) + \max_{i \in V_g} C_i \right) + T_\rho(|G^*|) \quad (1)$$

subject to,

$$\sum_{j \in V_g} m_j \geq |\mathcal{X}| \quad \forall g \in G^* \quad (2)$$

where, \mathcal{X} is the set of all experts and m_j is expert memory capacity for device j . Also, κ identifies the frequency of MoE computation, $\pi(g)$ is the compute cost of g , C_i denotes the communication cost of device i and $T_\rho(|G^*|)$ is the cost of inter-group all-reduce on MoE parameters due to data parallelism. We also note that CUDA development for Aristos Fused is underway.

Acknowledgements

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Microbenchmarks

