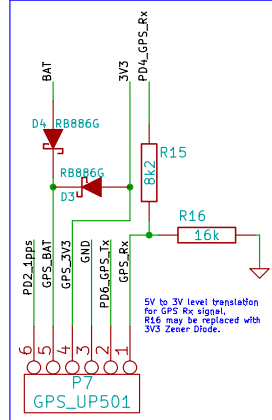
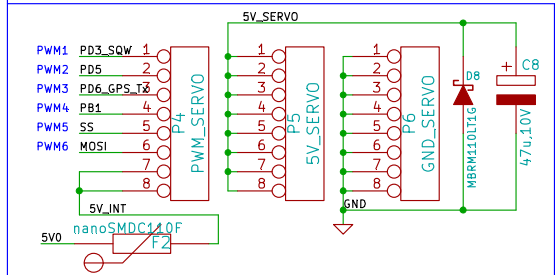


GPS Header

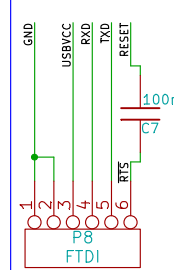


EXT Mode : Connect EXT Servo supply to 5V_SERVO and GND_SERVO Connectors Pins 7/8.
INT Mode : Use Jumper links to shunt Pins 7/8 of PWM_SERVO and 5V_SERVO connectors to run Servos using on board 5V.

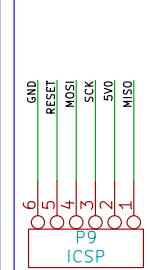
SERVO Header



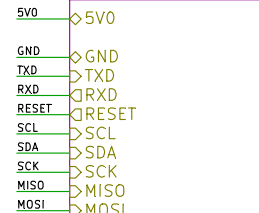
FTDI Header



ISP Header

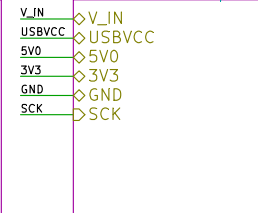


Sheet: RPi



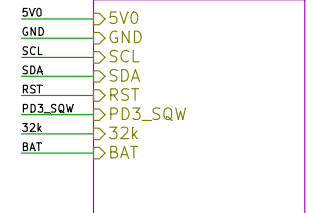
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Sheet: aLaMode_pwr



File: aLaMode_pwr.sch

Sheet: aLaMode_rtc



File: aLaMode_rtc.sch

WyoLum :: <http://wyolum.com/projects/alamode/>

File:

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Title: aLaMode_v3

Size: A4

Date: 14 jun 2013

Rev: 3

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Id: 1/4

TE - 1981568-1
 PR
 FCI - 10118193-0001LF

If using Barrel Socket,
DO NOT INSTALL :
P12, F1, D7, C15, R14

The diagram shows a circuit for a blink LED. It includes a 555 timer (U5B) configured as an astable multivibrator, with its timing network (R1, R2, C2) connected to a 5V0 supply. The output of the 555 timer (pin 7) is connected to the non-inverting input (pin 4) of an LM358N op-amp. The op-amp's other input (pin 6) is connected to ground (GND), and its output (pin 7) is connected to the anode of an LED (D13 BLINK) through a 4k resistor (R12). The LED's cathode is connected to GND. A 100nF capacitor (C2) is connected between the 5V0 supply and GND.



Id: 2/4



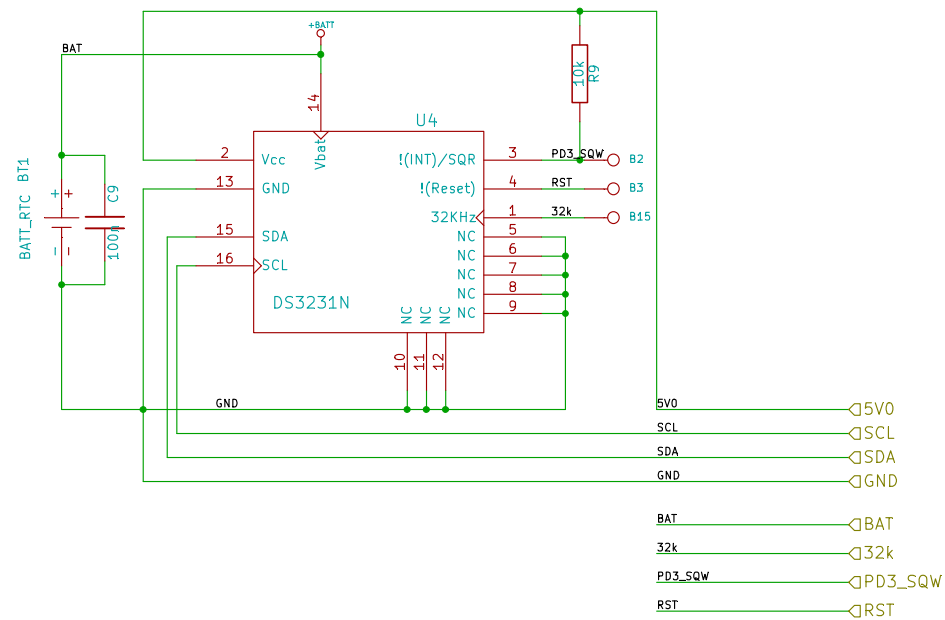
Logo_Wyolum

100

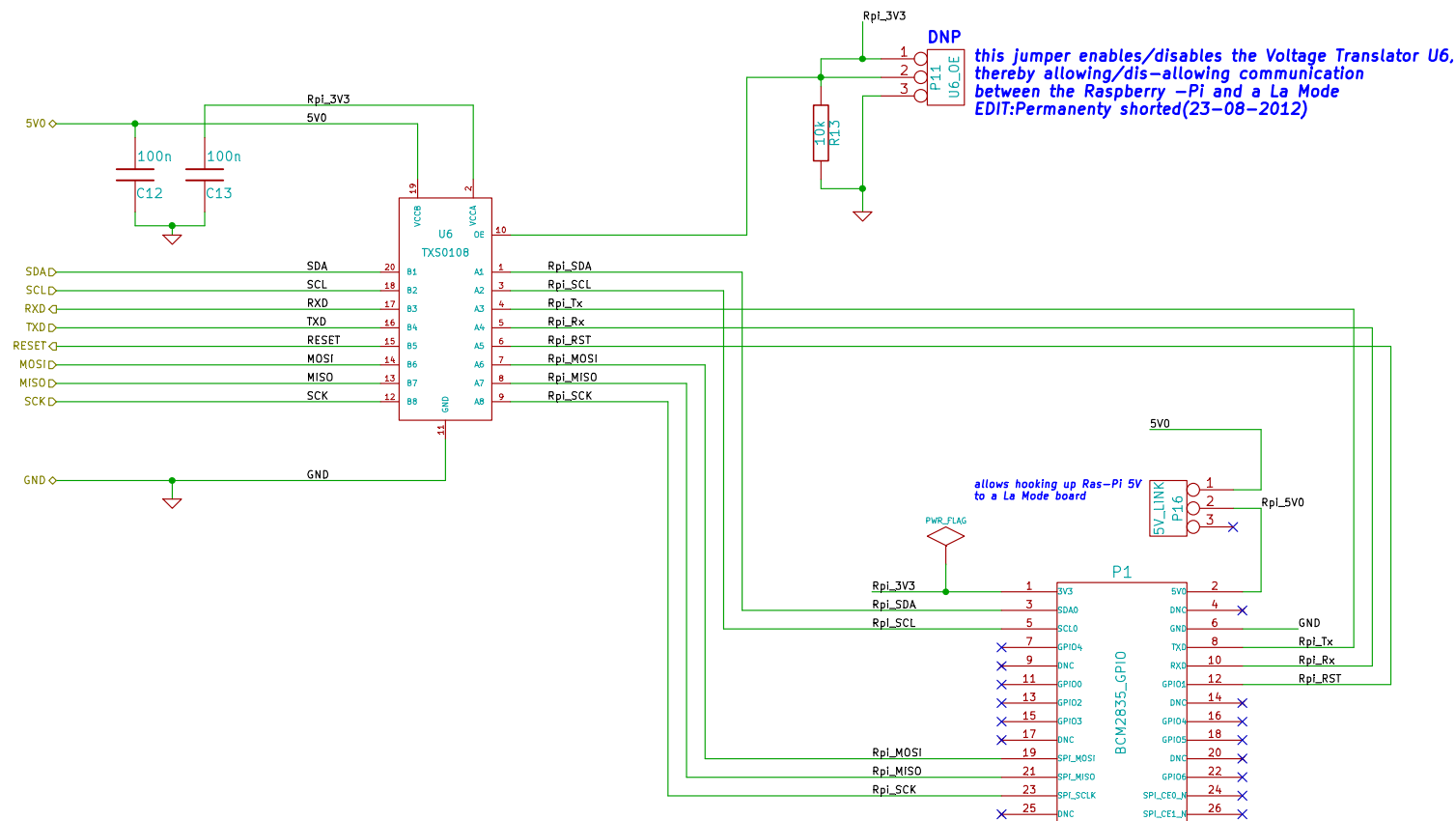


A diagram of a rectangular prism. The length of the base is labeled L , the width of the base is labeled W , and the height is labeled C .

PCB1



WyoLum :: http://wyolum.com/projects/alamode/		
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Sheet: /aLaMode_rtc/		
Title: aLaMode_v3		
Size: A4	Date: 14 jun 2013	Rev: 3
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NOTE : GPIO voltage levels are 3v3 and are not 5v tolerant.

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Sheet: /RPI/

Title: aLaMode_v3

Size: A4

Date: 14 jun 2013

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Id: 4/4