

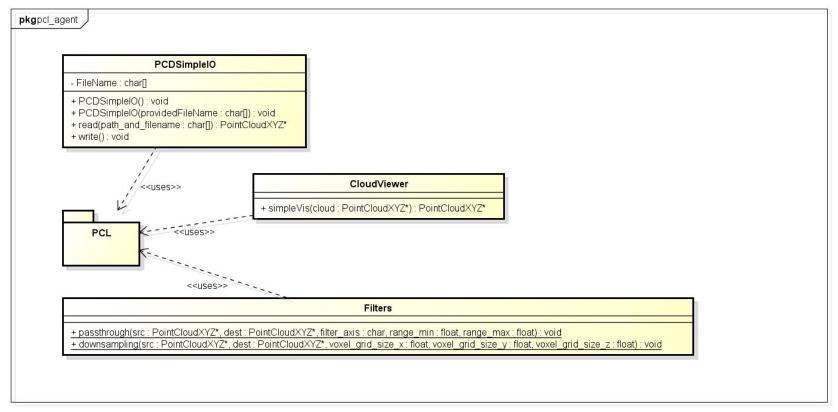
PRESENTATION CONTENT

- Current Progress
- Software Demo
- Objective for the next sprint

CURRENT PROGRESS

- Utilizing Point Cloud Library components
 - Data or Input sources
 - Point cloud file reader
 - Kinect Camera
 - Output sources
 - Point cloud file writer
 - Point cloud Viewer
 - Filter components
 - Pass through filter
 - Downsampling filter
 - Statiscal outliar removal
 - Radius outliar removal

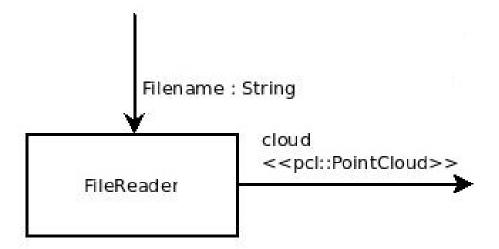
SOFTWARE DEMO

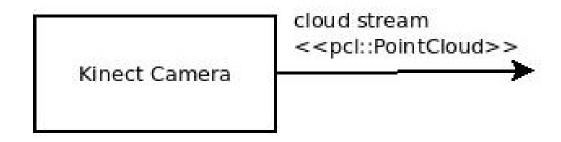


OBJECTIVE FOR THE NEXT SPRINT

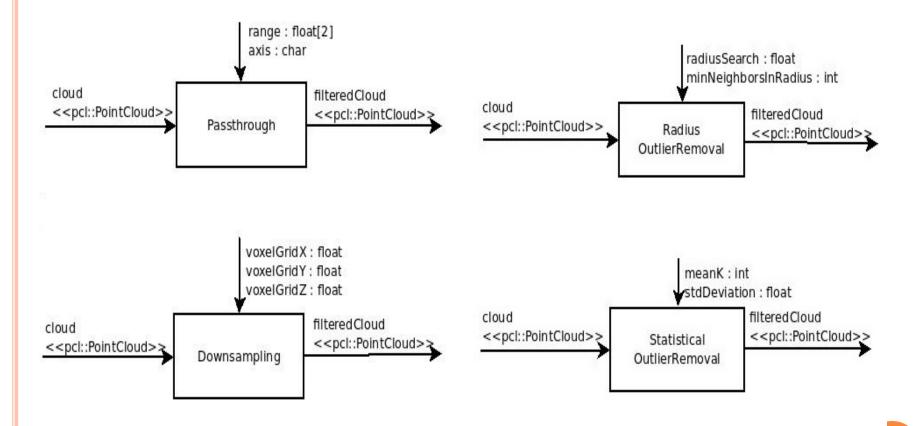
- Implement the functionalities as agents
 - Input
 - Configuration
 - Output
- Integrate agents in ROS
 - Wrap each agent with a ROS node
 - o Input => Subscriber
 - Parameter Configurations
 - o Output => Publisher
 - Create a Dynamic reconfigure node
 - Runtime configuration of agent parameters

AGENTS DIAGRAM





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